

1.2A Step-Down Converter with 1.4MHz Switching Frequency

Features

- V_{IN} 4.75V to 24V
- Load current of up to 1.2A
- Internal Power MOSFET
- Stable with Low ESR Ceramic Output Capacitors
- Up to 90% Efficiency
- 0.1 μ A Shutdown Mode
- Fixed 1.4MHz Frequency
- Thermal Shutdown
- Cycle-by-Cycle Over Current Protection
- Resistor divider adjustable Output: 0.81V to 15V
- SOT26: Available in "Green" Molding Compound (no Br, Sb)
- Lead Free Finish/RoHS Compliant (Note 1)

General Description

The AP5100 is a current mode step-down converter with a built-in power MOSFET to enable smallest solution size power conversion.

With the low series resistance power switch it enables a constant output current of up to 1.2A over a wide input supply range. The load and line regulation has excellent response time over the operating input voltage and temperature range.

The AP5100 is self protected, through a cycle-by-cycle current limiting algorithm and an on chip thermal protection.

The AP5100 will provide the voltage conversion with a low count of widely available standard external components.

The AP5100 is available in SOT26 package.

Applications

- Distributed Power Systems
- Battery Charger
- Pre-Regulator for Linear Regulators
- WLED Drivers

Typical Applications

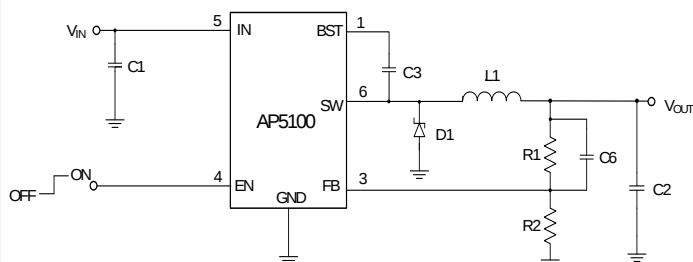
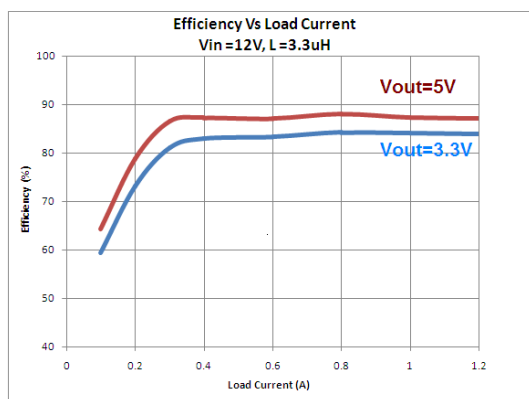


Figure 1. Typical Application Circuit

Typical Applications (Continued)

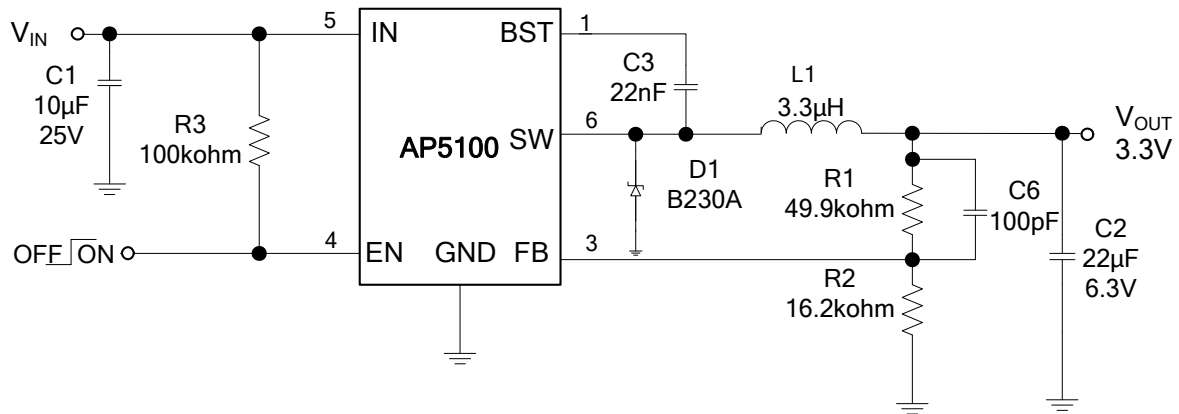


Figure 2. 1.4MHz, 3.3V Output at 1A Step-Down Converter

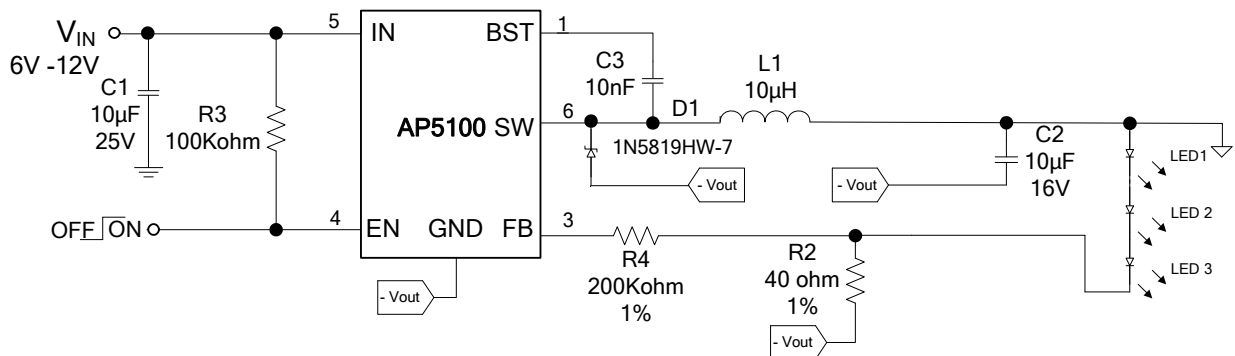
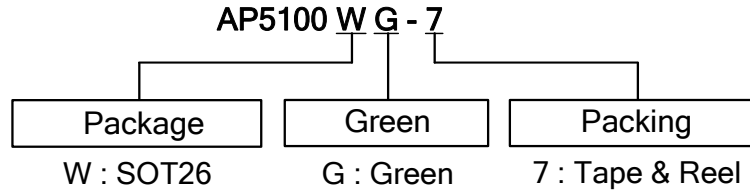


Figure 3. White LED Driver Application

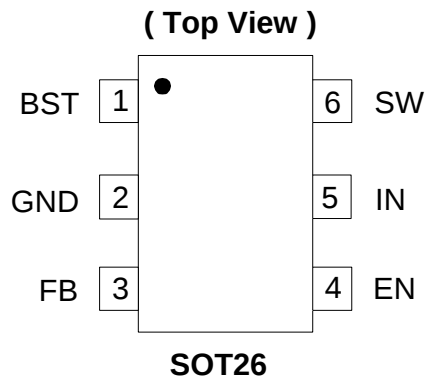
Ordering Information



Device	Package Code	Packaging (Note 2)	7" Tape and Reel	
			Quantity	Part Number Suffix
AP5100WG-7	W	SOT26	3000/Tape & Reel	-7

Notes: 1. EU Directive 2002/95/EC (RoHS). All applicable RoHS exemptions applied. Please visit our website at http://www.diodes.com/products/lead_free.html.
2. Pad layout as shown on Diodes Inc. suggested pad layout document AP02001, which can be found on our website at <http://www.diodes.com/datasheets/ap02001.pdf>.

Pin Assignments



Pin Descriptions

Pin Name	Pin #	Description
BST	1	Bootstrap. To form a boost circuit, a capacitor is connected between SW and BST pins to form a floating supply across the power switch driver. This capacitor is needed to drive the power switch's gate above the supply voltage. Typical values for C_{BST} range from 0.1uF to 1uF.
GND	2	Ground. This pin is the voltage reference for the regulated output voltage. All control circuits are referenced to this pin. For this reason care must be taken in its layout.
FB	3	Feedback. To set the output voltage, connect this pin to the output resistor divider or directly to V_{OUT} . To prevent current limit run away during a current limit condition, the frequency foldback comparator lowers the oscillator frequency when the FB voltage is below 400mV.
EN	4	On/Off Control Input. Do not leave this pin floating. To turn the device ON, pull EN above 1.2V and to turn it off pull below 0.4V. If enable/disable is not used, connect a 100kOhm resistor between EN to V_{IN} .
IN	5	Supply Voltage. The AP5100 operates from a +4.75V to +24V unregulated input. A decoupling capacitor C1 is required to prevent large voltage spikes from appearing at the input. Place this capacitor near the IC.
SW	6	Switch Output. This is the reference for the floating top gate driver.

Absolute Maximum Ratings (Note 3)

Symbol	Description	Rating	Unit
ESD HBM	Human Body Model ESD Protection	3	KV
ESD MM	Machine Model ESD Protection	300	V
V_{IN}	Supply Voltage	26	V
V_{SW}	Switch Voltage	-0.3 to $V_{IN} + 0.3$	V
V_{BST}	Boost Voltage	$V_{SW} + 6$	V
	All Other Pins	-0.3 to +6	V
T_{ST}	Storage Temperature	-65 to +150	°C
T_J	Junction Temperature	+150	°C
T_L	Lead Temperature	+260	°C
θ_{JA}	Junction to Ambient Thermal Resistance (Note 4)	140	°C/W
θ_{JC}	Junction to Case Thermal Resistance (Note 4)	35	°C/W

Notes: 3. Exceeding these ratings may damage the device.
4. Test condition for SOT26: Measured on approximately 1" square of 1 oz copper.

Recommended Operating Ratings (Note 5)

Symbol	Description	Rating	Unit
V_{IN}	Supply Voltage	4.75 to 24	°C
T_A	Operating Ambient Temperature Range	-25 to +85	°C
V_{OUT}	Output Voltage	0.81 to 15	V

Notes: 5. The device function is not guaranteed outside of the recommended operating conditions.

Electrical Characteristics ($V_{IN} = 12V$, $T_A = +25^{\circ}C$, unless otherwise noted)

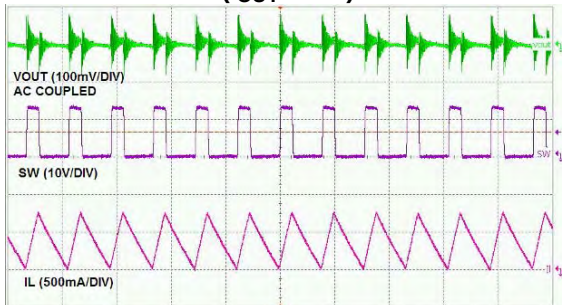
Symbol	Parameter	Test Conditions	Min	Typ.	Max	Unit
V_{FB}	Feedback Voltage	$4.75V \leq V_{IN} \leq 24V$	0.790	0.810	0.830	V
I_{FB}	Feedback Current	$V_{FB} = 0.8V$		0.1		μA
$R_{DS(ON)}$	Switch-On Resistance (Note 6)			0.35		Ω
	Switch Leakage	$V_{EN} = 0V$, $V_{SW} = 0V$			10	μA
	Current Limit (Note 6)			2.4		A
f_{SW}	Oscillator Frequency	$V_{FB} = 0.6V$	1.1	1.4	1.7	MHz
	Fold-back Frequency	$V_{FB} = 0V$		480		kHz
	Maximum Duty Cycle	$V_{FB} = 0.6V$		87		%
t_{ON}	Minimum On-Time (Note 6)			100		ns
	Under Voltage Lockout Threshold Rising		3.8	4.0	4.2	V
	Under Voltage Lockout Threshold Hysteresis			150		mV
	EN Input Low Voltage				0.4	V
	EN Input High Voltage		1.2			V
	EN Input Current	$V_{EN} = 2V$		0.3		μA
		$V_{EN} = 0V$		0.1		
I_S	Supply Current (Shutdown)	$V_{EN} = 0V$		0.1	1.0	μA
I_Q	Supply Current (Quiescent)	$V_{EN} = 2V$, $V_{FB} = 1V$		0.4	1.0	mA
	Thermal Shutdown (Note 6)			140		°C

Notes: 6. Guaranteed by design.

Typical Performance Characteristics

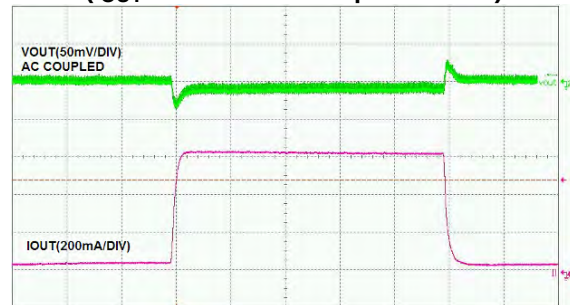
$V_{IN}=12V$, $V_{OUT}=3.3V$, $L=3.3\mu H$, $C1=10\mu F$, $C2=22\mu F$, $T_A=+25^{\circ}C$, unless otherwise noted.

Steady State Test
($I_{OUT}=0.5A$)



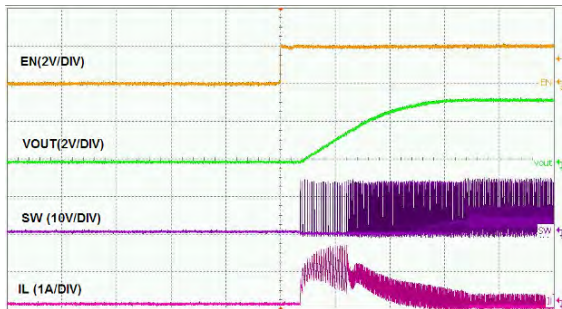
Time- 1 μs /div

Load Transient Test
($I_{OUT}=0.2A$ to $0.8A$. Step at $0.8A/\mu s$)



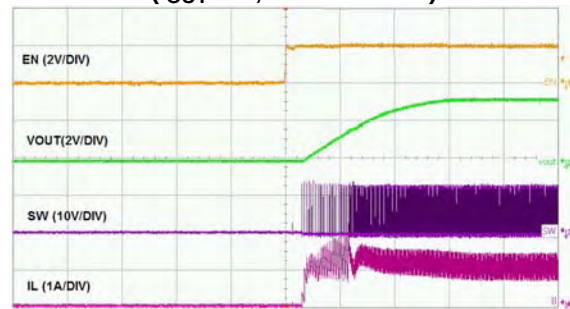
Time- 100 μs /div

Start-up Through Enable
(No Load)



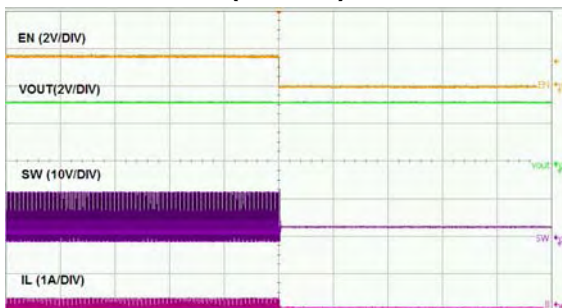
Time- 50 μs /div

Start-up through Enable
($I_{OUT}=1A$, resistive load)



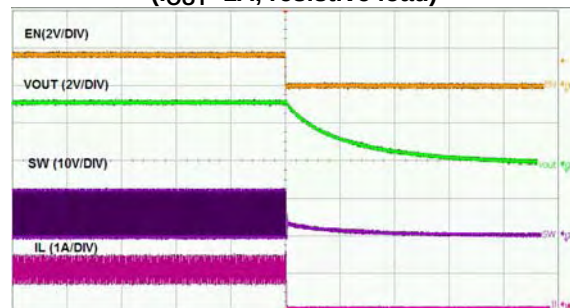
Time- 50 μs /div

Shutdown Through Enable
(No Load)



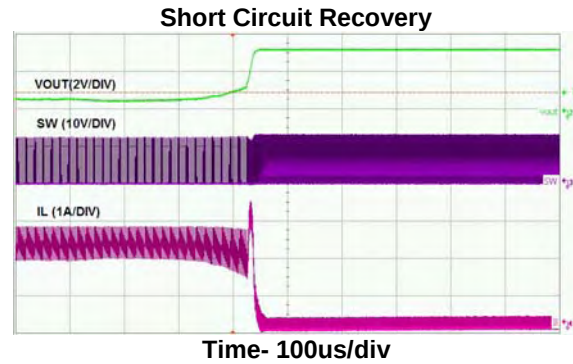
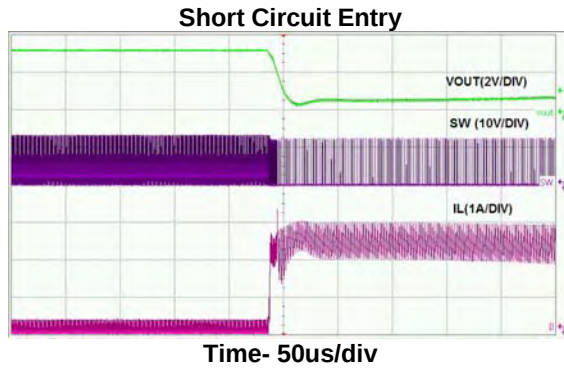
Time- 50 μs /div

Shutdown Through Enable
($I_{OUT}=1A$, resistive load)



Time- 50 μs /div

Typical Performance Characteristics (Continued)



Application Information

OPERATION

The AP5100 is a current mode control, asynchronous buck regulator. Current mode control assures excellent line and load regulation and a wide loop bandwidth for fast response to load transients. Figure. 4 depicts the functional block diagram of AP5100.

The operation of one switching cycle can be explained as follows. At the beginning of each cycle, HS (high-side) MOSFET is off. The EA output voltage is higher than the current sense amplifier output, and the current comparator's output is low. The rising edge of the 1.4MHz oscillator clock signal sets the RS Flip-Flop. Its output turns on HS MOSFET.

When the HS MOSFET is on, inductor current starts to increase. The Current Sense Amplifier senses and amplifies the inductor current. Since the current mode control is subject to sub-harmonic oscillations that peak

at half the switching frequency, Ramp slope compensation is utilized. This will help to stabilize the power supply. This Ramp compensation is summed to the Current Sense Amplifier output and compared to the Error Amplifier output by the PWM Comparator. When the sum of the Current Sense Amplifier output and the Slope Compensation signal exceeds the EA output voltage, the RS Flip-Flop is reset and HS MOSFET is turned off. The external Schottky rectifier diode (D1) conducts the inductor current.

For one whole cycle, if the sum of the Current Sense Amplifier output and the Slope Compensation signal does not exceed the EA output, then the falling edge of the oscillator clock resets the Flip-Flop. The output of the Error Amplifier increases when feedback voltage (VFB) is lower than the reference voltage of 0.81V. This also increases the inductor current as it is proportional to the EA voltage.

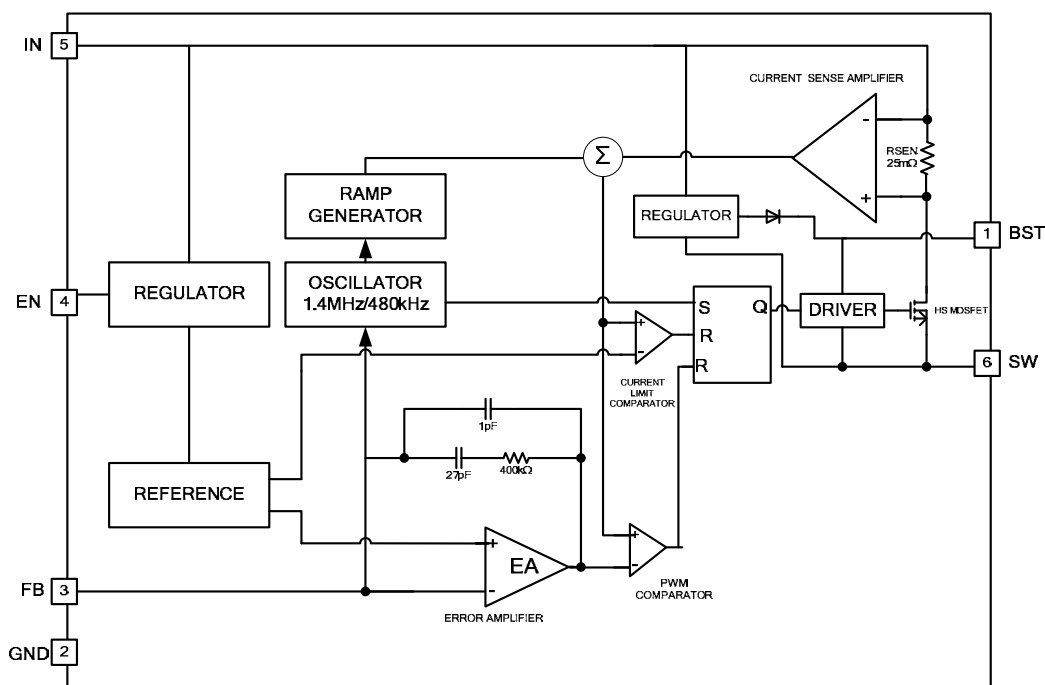


Figure 4. Functional Block Diagram

Application Information (Continued)

Setting the Output Voltage

The output voltage can be adjusted from 0.81V to 15V using an external resistor divider. Table 1 shows a list of resistor selection for common output voltages. Resistor R1 is selected based on a design tradeoff between efficiency and output voltage accuracy. For high values of R1 there is less current consumption in the feedback network. However the trade off is output voltage accuracy due to the bias current in the error amplifier. R2 can be determined by the following equation:

$$R_1 = R_2 \times \left(\frac{V_{OUT}}{0.81} - 1 \right)$$

V _{OUT} (V)	R ₁ (kΩ)	R ₂ (kΩ)
1.8	80.6 (1%)	64.9 (1%)
2.5	49.9 (1%)	23.7 (1%)
3.3	49.9 (1%)	16.2 (1%)
5	49.9 (1%)	9.53 (1%)

Table 1. Resistor Selection for Common Output Voltages

Inductor

Calculating the inductor value is a critical factor in designing a buck converter. For most designs, the following equation can be used to calculate the inductor value;

$$L = \frac{V_{OUT} \times (V_{IN} - V_{OUT})}{V_{IN} \times \Delta I_L \times f_{SW}}$$

Where ΔI_L is the inductor ripple current.

And f_{SW} is the buck converter switching frequency.

Choose the inductor ripple current to be 30% of the maximum load current. The maximum inductor peak current is calculated from:

$$I_L(MAX) = I_{LOAD} + \frac{\Delta I_L}{2}$$

Peak current determines the required saturation current rating, which influences the size of the inductor. Saturating the inductor decreases the converter efficiency while increasing the temperatures of the inductor, the MOSFET and the diode. Hence choosing an inductor with appropriate saturation current rating is important.

A 1μH to 10μH inductor with a DC current rating of at least 25% percent higher than the maximum load current is recommended for most applications.

For highest efficiency, the inductor's DC resistance should be less than 200mΩ. Use a larger inductance for improved efficiency under light load conditions.

Input Capacitor

The input capacitor reduces the surge current drawn from the input supply and the switching noise from the device. The input capacitor has to sustain the ripple current produced during the on time on the upper MOSFET. It must hence have a low ESR to minimize the losses.

Due to large dI/dt through the input capacitors, electrolytic or ceramics should be used. If a tantalum must be used, it must be surge protected. Otherwise, capacitor failure could occur. For most applications, a 4.7μF ceramic capacitor is sufficient.

Output Capacitor

The output capacitor keeps the output voltage ripple small, ensures feedback loop stability and reduces the overshoot of the output voltage. The output capacitor is a basic component for the fast response of the power supply. In fact, during load transient, for the first few microseconds it supplies the current to the load. The converter recognizes the load transient and sets the duty cycle to maximum, but the current slope is limited by the inductor value.

Maximum capacitance required can be calculated from the following equation:

Application Information (Continued)

$$C_o = \frac{L(I_{OUT} + \frac{\Delta I_{inductor}}{2})^2}{(\Delta V + V_{OUT})^2 - V_{OUT}^2}$$

Where ΔV is the maximum output voltage overshoot.

ESR of the output capacitor dominates the output voltage ripple. The amount of ripple can be calculated from the equation below:

$$V_{out\text{capacitor}} = \Delta I_{inductor} \times ESR$$

An output capacitor with ample capacitance and low ESR is the best option. For most applications, a 22 μ F ceramic capacitor will be sufficient.

External Diode

The external diode's forward current must not exceed the maximum output current. Since power dissipation is a critical factor when choosing a diode, it can be calculated from the equation below:

$$P_{diode} = (1 - \frac{V_{OUT}}{V_{IN}}) \times I_{out} \times 0.3V$$

Note: 0.3V is the voltage drop across the schottky diode. A diode that can withstand this power dissipation must be chosen.

PC Board Layout

This is a high switching frequency converter. Hence attention must be paid to the switching currents interference in the layout. Switching current from one power device to another can generate voltage transients across the impedances of the interconnecting bond wires and circuit traces. These interconnecting impedances should be minimized by using wide, short printed circuit traces. The input capacitor needs to be as close as possible to the IN and GND pins. The external feedback resistors should be placed next to the FB pin.

External Bootstrap Diode

It is recommended that an external bootstrap diode be added when the input voltage is no greater than 5V or the 5V rail is available in the system. This helps improve the efficiency of the regulator. The bootstrap diode can be a low cost one such as IN4148 or BAT54.

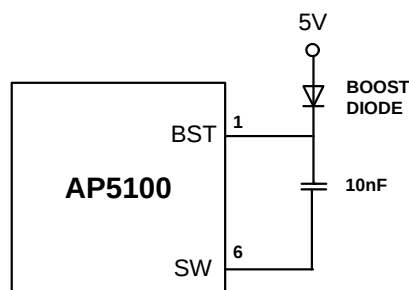
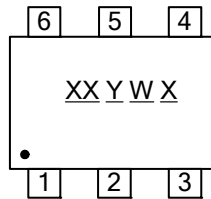


Figure 5. External Bootstrap Diode

Marking Information

(1) SOT26

(Top View)

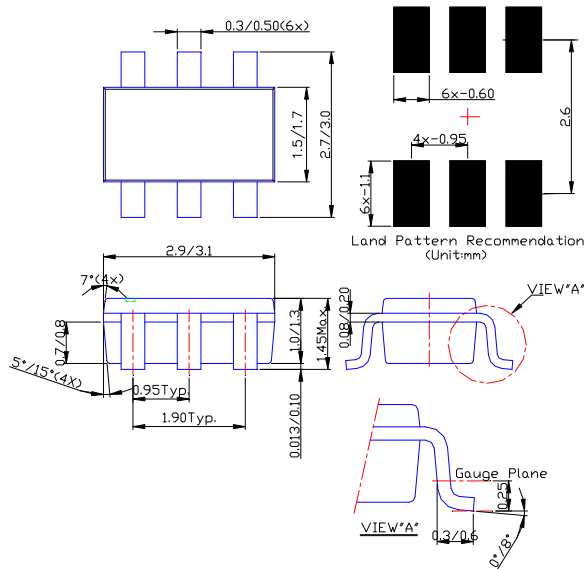


XX : Identification Code
Y : Year 0~9
W : Week : A~Z : 1~26 week;
a~z : 27~52 week; z represents
52 and 53 week
X : A~Z : Green

Part Number	Package	Identification Code
AP5100W	SOT26	AJ

Package Information (All Dimensions in mm)

(1) Package type: SOT26



1.2A Step-Down Converter with 1.4MHz Switching Frequency**IMPORTANT NOTICE**

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