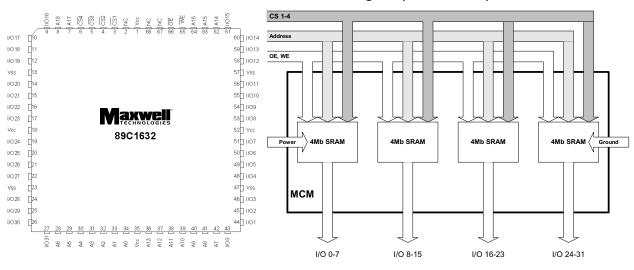


# 89C1632 16 Megabit (512K x 32-Bit) MCM SRAM

#### 16 Megabit (512k x 32-bit) SRAM MCM

Logic Diagram



## **FEATURES:**

- Four 512k x 8 SRAM architecture
- Rad-Pak® technology hardens against natural space radiation technology
- Total dose hardness:
  - > 100 krad (Si), depending upon space mission
- Excellent Single Event Effects:
  - SEL > 101MeV-cm<sup>2</sup>/mg
  - SEU threshold = 3 MeV-cm<sup>2</sup>/mg
  - SEU saturated cross section: 6E-9 cm<sup>2</sup>/bit
- · Package: 68-pin quad flat package
- · Fast access time: 20, 25 and 30 ns
- Completely static memory no clock or timing strobe required
- Internal bypass capacitor
- High-speed silicon-gate CMOS technology
- 5V or 3V  $\pm$  10% power supply
- Equal address and chip enable access times
- Three-state outputs
- · All inputs and outputs are TTL compatible

#### **DESCRIPTION:**

Maxwell Technologies' 89C1632 high-performance 16 Megabit Multi-Chip Module (MCM) Static Random Access Memory features a greater than 100 krad (Si) total dose tolerance, depending upon space mission. The four 4-Megabit SRAM die and bypass capacitors are incorporated into a high-reliable hermetic quad flat-pack ceramic package. With high-performance silicon-gate CMOS technology, the 89C1632 reduces power consumption and eliminates the need for external clocks or timing strobes. It is equipped with output enable (OE) and four byte enable (CS1 - CS4) inputs to allow greater system flexibility. When OE input is high, the output is forced to high impedance.

Maxwell Technologies' patented Rad-Pak® packaging technology incorporates radiation shielding in the microcircuit package. In a GEO orbit, Rad-Pak provides true greater than 100 krad (Si) total radiation dose tolerance, dependent upon space mission. It eliminates the need for box shielding while providing the required radiation shielding for a lifetime in orbit or a space mission. This product is available with screening up to Maxwell Technologies self-defined Class K.

TABLE 1. PINOUT DESCRIPTION

Pin	Symbol	Description
34-28, 42-36, 62-64, 7, 8	A0-A18	Address Enable
65	WE	WriteEnable
66	ŌĒ	Output Enable
3-6	CS1 - CS4	Chip Enable
43-46, 48-56, 58-61, 9-12, 14-17, 19-22, 24-27	1/00-1/031	Data Input/Output
2, 67, 68	NC	No Connection
1, 18, 35, 52	V <sub>CC</sub>	+5V Power Supply
13, 23, 47, 57	$V_{SS}$	Ground

Table 2. 89C1632 Absolute Maximum Ratings

(Voltage referenced to  $V_{SS} = 0V$ )

PARAMETER	Symbol	Min	Max	Units
Power Supply Voltage Relative to V <sub>SS</sub>	V <sub>CC</sub>	-0.5	+7.0	V
Voltage Relative to V <sub>SS</sub> for Any Pin Except V <sub>CC</sub>	V <sub>IN</sub> , V <sub>OUT</sub>	-0.5	V <sub>CC</sub> +0.5	V
Power Dissipation	$P_{D}$		4.0	W
Operating Temperature	T <sub>A</sub>	-55	+125	°C
Storage Temperature	T <sub>S</sub>	-65	+150	°C

#### TABLE 3. 89C1632 RECOMMENDED OPERATING CONDITIONS

Parameter	Symbol	Min	Max	Units
Supply Voltage, (Operating Voltage Range)	V <sub>CC</sub>	4.5	5.5	V
Input High Voltage	V <sub>IH</sub>	2.2	$V_{\rm CC}$ + 0.5 <sup>(1)</sup>	V
Input Low Voltage	V <sub>IL</sub>	-0.5 <sup>(2)</sup>	0.8	V

<sup>1.</sup>  $V_{IH}$  (max) =  $V_{CC}$  + 2V ac (pulse width  $\leq$  10ns) for I  $\leq$  80 mA.

TABLE 4. 89C1632 DELTA LIMITS

Parameter	Variationl
I <sub>cc</sub>	±10% of stated value in table 5

<sup>2.</sup>  $V_{IL}$  (min) = -2.0V ac; (pulse width  $\leq$  20 ns) for I  $\leq$  80 mA.

TABLE 4. 89C1632 DELTA LIMITS

Parameter	Variationl
I <sub>SB</sub>	±10% of stated value in table 5
I <sub>SB1</sub>	±10% of stated value in table 5
ILI	±10% of stated value in table 5

## TABLE 5. 89C1632 DC ELECTRICAL CHARACTERISTICS

( $V_{CC}$  = 5.0  $\pm$  10%,  $T_A$  = -55 to +125  $^{\circ}C$ , unless otherwise noted)

Parameter	Symbol	TEST CONDITIONS	Subgroups	Min	Түр	Max	Units
Input Leakage Current	ILI	$V_{IN} = 0$ to $V_{CC}$	1, 2, 3	-8.0		+8.0	uA
Output Leakage Current	I <sub>LO</sub>	$\overline{\text{CS}} = V_{\text{IH}}, V_{\text{OUT}} = V_{\text{SS}} \text{ to } V_{\text{CC}}$	1, 2, 3	-8.0		+8.0	uA
Average Operating Current Cycle Time: 20 ns 25 ns 30 ns	I <sub>cc</sub>	Min. Cycle, 100% Duty, $\overline{CS} = V_{IL}$ , $I_{OUT} = 0$ mA $V_{IN} = V_{IH}$ or $V_{IL}$	1, 2, 3	 		800 760 720	mA
Standby Power Supply Current	I <sub>SB</sub>	CS= V <sub>IH</sub> , cycle time <u>&gt;</u> 25ns	1, 2, 3			240	mA
CMOS Standby Power Supply Current	I <sub>SB1</sub>	$\overline{\text{CS}} \ge \text{V}_{\text{CC}} - 0.2\text{V}, \text{ f} = 0 \text{ MHz}, \text{V}_{\text{IN}} \ge \text{V}_{\text{CC}} - 0.2\text{V or} \text{V}_{\text{IN}} < 0.2\text{V}$	1, 2, 3			60	mA
Output Low Voltage	V <sub>OL</sub>	$I_{OL} = + 8.0 \text{ mA}$	1, 2, 3			0.4	V
Output High Voltage	V <sub>OH</sub>	I <sub>OH</sub> = -4.0 mA	1, 2, 3	2.4			V
Input Capacitance <sup>1</sup> CS1 - CS4, OE, WE I/O0-7, I/O8-15, I/O16-23, I/O24-31	C <sub>IN</sub>	V <sub>IN</sub> = 0 V	1, 2, 3			7 28 7	pF
Input / Output Capacitance <sup>1</sup>	C <sub>OUT</sub>	V <sub>I/O</sub> = 0 V	4, 5, 6			8	pF

<sup>1.</sup> Guaranteed by design.

Table 6. 89C1632 AC Operating Conditions and Characteristics

Parameter	Min	Түр	Max	Units
Input Pulse Level	0.0		3.0	V
Output Timing Measurement Reference Level			1.5	V
Input Rise/Fall Time			3.0	ns

## TABLE 6. 89C1632 AC OPERATING CONDITIONS AND CHARACTERISTICS

( $V_{CC}$  = 5.0  $\pm$  10%,  $T_A$  = -55 to +125  $^{\circ}C$ , unless otherwise noted)

Parameter	Min	Түр	Max	Units
Input Timing Measurement Reference Level			1.5	V

## TABLE 7. 89C1632 READ CYCLE

Parameter	Symbol	Subgroups	Min	Түр	Max	Units
Read Cycle Time	t <sub>RC</sub>	9, 10, 11				ns
-20	, KC		20			
-25			25			
-30			30			
Address Access Time	t <sub>AA</sub>	9, 10, 11				ns
-20					20	
-25					25	
-30					30	
Chip Select to Output	t <sub>co</sub>	9, 10, 11				ns
-20					20	
-25					25	
-30					30	
Output Enable to Output	t <sub>OE</sub>	9, 10, 11				ns
-20					10	
-25					12	
-30					14	
Output Enable to Low-Z Output	t <sub>OLZ</sub>	9, 10, 11				ns
-20				0		
-25				0		
-30				0		
Chip Enable to Low-Z Output	t <sub>LZ</sub>	9, 10, 11				ns
-20				3		
-25				3		
-30				3		
Output Disable to High-Z Output	t <sub>OHZ</sub>	9, 10, 11				ns
-20				5		
-25				6		
-30				8		
Chip Disable to High-Z Output	t <sub>HZ</sub>	9, 10, 11				ns
-20				5		
-25				6		
-30				8		
Output Hold from Address Change	t <sub>OH</sub>	9, 10, 11				ns
-20			3			
-25			3			
-30			3			

Table 8. 89C1632 Functional Description

CS	WE	ŌĒ	Mode	I/O Pin	SUPPLY CURRENT
Н	X <sup>1</sup>	X <sup>1</sup>	Not Select	High-Z	I <sub>SB</sub> , I <sub>SB1</sub>
L	Н	Н	Output Disable	High-Z	I <sub>cc</sub>
L	Н	L	Read	D <sub>OUT</sub>	I <sub>cc</sub>
L	L	X <sup>1</sup>	Write	D <sub>IN</sub>	I <sub>cc</sub>

<sup>1.</sup> X = don't care.

Table 9. 89C1632 Write Cycle

Parameter	Symbol	Subgroups	Min	Түр	Max	Units
Write Cycle Time -20 -25 -30	t <sub>WC</sub>	9, 10, 11	20 25 30			ns
Chip Select to End of Write -20 -25 -30	t <sub>CW</sub>	9, 10, 11	14 17 20			ns
Address Set-up Time -20 -25 -30	t <sub>AS</sub>	9, 10, 11	0 0 0		  	ns
Address Valid to End of Write -20 -25 -30	t <sub>AW</sub>	9, 10, 11	14 17 20			ns
Write Pulse Width (OE High) -20 -25 -30	t <sub>WP</sub>	9, 10, 11	14 17 20			ns
Write Pulse Width (OE Low) -20 -25 -30	t <sub>WP1</sub>	9, 10, 11	20 25 30			ns
Write Recovery Time -20 -25 -30	t <sub>WR</sub>	9, 10, 11	0 0 0		  	ns

## TABLE 9. 89C1632 WRITE CYCLE

(V<sub>CC</sub> =  $5.0 \pm 10\%$ , T<sub>A</sub> = -55 to +125 °C, unless otherwise noted)

PARAMETER	Symbol	Subgroups	Мім	Түр	Max	Units
Write to Output High-Z	t <sub>whz</sub>	9, 10, 11				ns
-20				5		
-25				7		
-30				9		
Data to Write Time Overlap	t <sub>DW</sub>	9, 10, 11				ns
-25			10			
-30			12			
			14			
Data Hold from Write Time	t <sub>DH</sub>	9, 10, 11				ns
-20			0			
-25			0			
-30			0			
End Write to Output Low-Z	t <sub>ow</sub>	9, 10, 11				ns
-20				3		
-25				3		
-30				3		

FIGURE 1. AC TEST LOADS

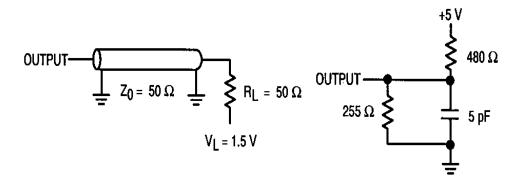


Figure 1A

Figure 1B

FIGURE 2. TIMING WAVEFORM OF READ CYCLE (1) (ADDRESS CONTROLLED)

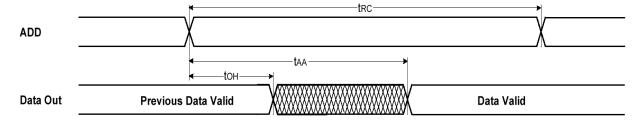
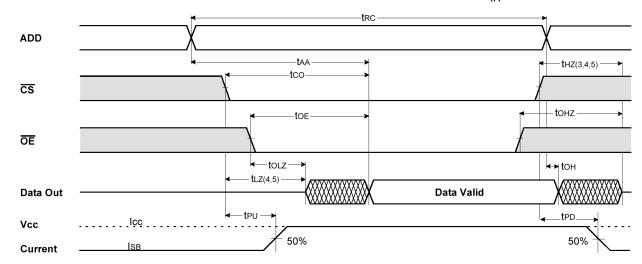


Figure 3. Timing Waveform of Read Cycle (2) ( $\overline{WE} = V_{IH}$ )



- 1.  $\overline{\text{WE}}$  is high for read cycle.
- 2. All read cycle timing is referenced from the last valid address to the first transition address.

- 3.  $t_{HZ}$  and  $t_{OHZ}$  are defined as the time at which the outputs achieve the open circuit condition and are not referenced to  $V_{OH}$  or  $V_{OI}$  levels.
- At any given temperature and voltage conditions, t<sub>HZ</sub> (max) is less than t<sub>LZ</sub> (min) both for a given device and from device to device.
- 5. Transition is measured ±200mV from steady state voltage with Load(B). This parameter is sampled and not 100% tested.
- 6. Device is continuously selected with  $\overline{CS} = V_{II}$ .
- 7. Address valid prior to coincident with  $\overline{CS}$  transition low.
- 8. For common I/O applications, minimization or elimination of bus contention conditions is necessary during read and write cycle.

FIGURE 4. TIMING WAVEFORM OF WRITE CYCLE (1) (OE CLOCK)

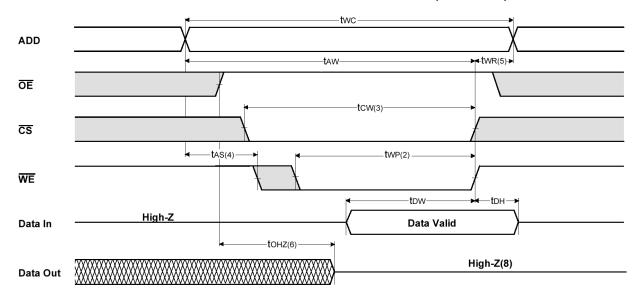


FIGURE 5. TIMING WAVEFORM OF WRITE CYCLE (2) (OE LOW FIIXED)

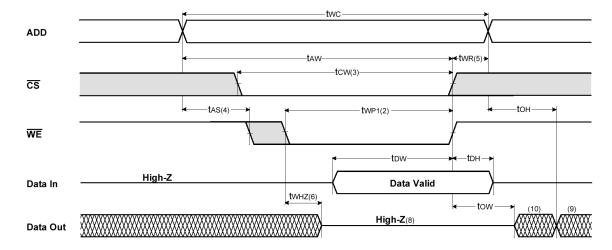
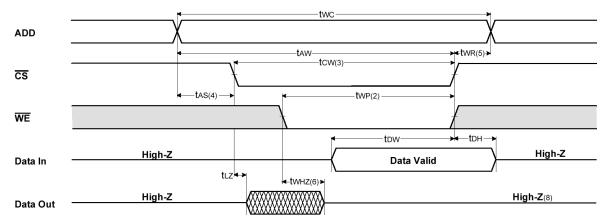


FIGURE 6. TIMING WAVEFORM OF WRITE CYCLE (3) (CS CONTROLLED)



- 1. All write cycle timing is referenced from the last valid address to the first transition address.
- 2. A write occurs during the overlap of a low  $\overline{CS}$  and  $\overline{WE}$ . A write begins at the latest transition  $\overline{CS}$  going low and  $\overline{WE}$  going low. A write ends at the earliest transition  $\overline{CS}$  going high or  $\overline{WE}$  going high.  $t_{WP}$  is measured from the beginning of write to the end of write.
- 3.  $t_{CW}$  is measured from the later of  $\overline{CS}$  going low to end of write.
- 4.  $t_{\rm AS}$  is measured from the address valid to the beginning of write.
- 5.  $t_{WR}$  is measured from the end of write to the address change.  $t_{WR}$  applied in case a write ends as  $\overline{CS}$  or  $\overline{WE}$  going high.
- 6. If  $\overline{OE}$ ,  $\overline{CS}$  and  $\overline{WE}$  are in the Read Mode during this period, the I/O pins are in the output low-Z state. Inputs of opposite phase of the output must not be applied because bus contention can occur.
- 7. For common I/O applications, minimization of elimination of bus contention conditions is necessary during read and write cycle.
- 8. If  $\overline{\text{CS}}$  foes low simultaneously with  $\overline{\text{WE}}$  going or after  $\overline{\text{WE}}$  going low, the outputs remain high impedance state.
- 9.  $D_{\text{OUT}}$  is the read data of the new address.
- 10. When CS is low, I/O pins are in the output state. The input signals in the opposite phase leading to the output should not be applied.

FIGURE 7. SRAM HEAVY ION CROSS SECTION

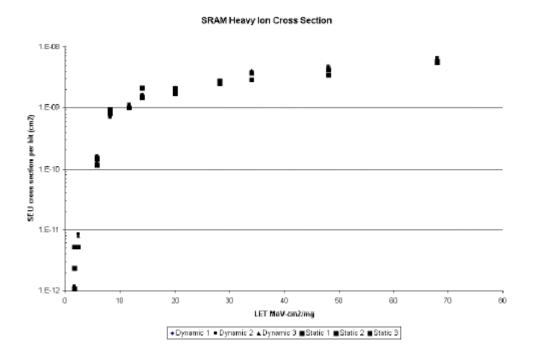
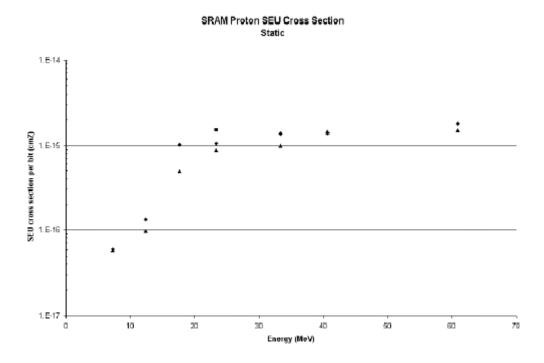
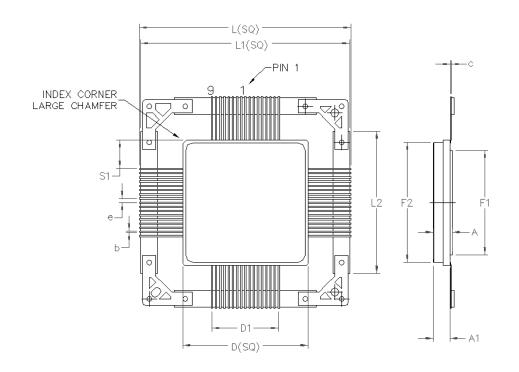


FIGURE 8. SRAM PROTON SEU CROSS SECTION STATIC





68 PIN RAD-PAK® QUAD FLAT PACKAGE

Symbol	DIMENSION		
	Min	Nом	Max
А	0.206	0.225	0.244
b	0.015	0.017	0.018
С	0.008	0.009	0.12
D	1.479	1.494	1.509
D1	0.800		
е	0.050 BSC		
S1		0.339	
F1	1.239	1.244	1.249
F2	1.429	1.434	1.439
L	2.485	2.510	2.545
L1	2.485	2.500	2.505
L2	1.690	1.700	1.710
A1	0.180	0.195	0.210
N	68		

Q68-04 Note: All dimensions in inches

# 16 Megabit (512K x 32-Bit) MCM SRAM

#### Important Notice:

These data sheets are created using the chip manufacturers published specifications. Maxwell Technologies verifies functionality by testing key parameters either by 100% testing, sample testing or characterization.

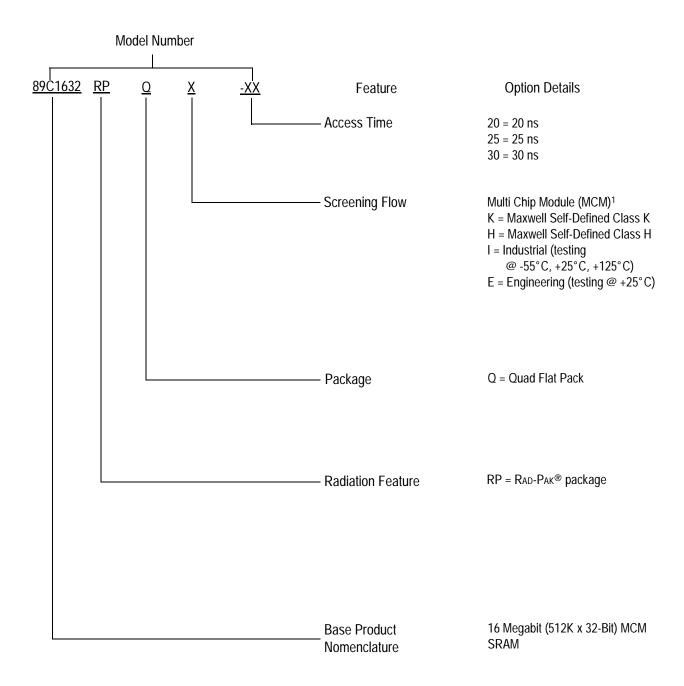
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# 16 Megabit (512K x 32-Bit) MCM SRAM

## **Product Ordering Options**



<sup>1)</sup> Products are manufactured and screened to Maxwell Technologies self-defined Class H and Class K.