

MITSUBISHI (DGTL LOGIC)

M54542L

BI-DIRECTIONAL MOTOR DRIVER

DESCRIPTION

The M54542L, BI-DIRECTIONAL MOTOR DRIVER, consists of a full bridge power driver designed for D-C motor control.

FEATURES

- 9-pin single inline package with heat sink
- Integral diodes for transient suppression
- 1.2A output current
- PMOS compatible input

APPLICATION

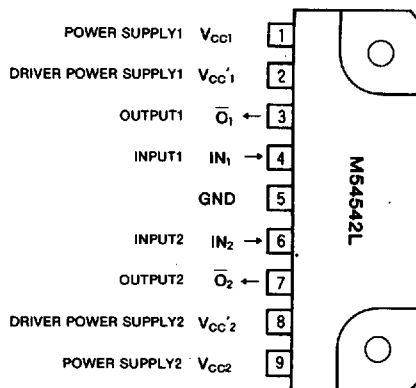
Audio, video cassette recorders, Floppy disk driver

FUNCTION

The M54542L, full bridge motor driver, has the logic circuitry and darlington-pair power drivers for bidirectional control of D-C motors operating at currents up to 1.2A.

The power supplies for the logic circuitry and the drivers are separated so that the applied voltage to the motor can be controlled by the V_{CC} of the driver power supply voltage.

PIN CONFIGURATION (TOP VIEW)

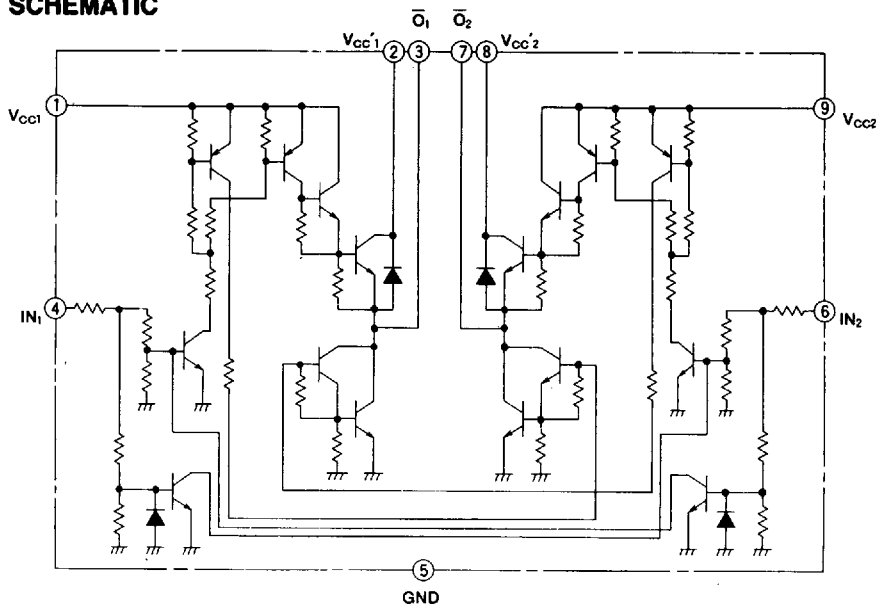


Outline 9P9

LOGIC TRUTH TABLE

INPUT		OUTPUT		NOTE
IN ₁	IN ₂	$\bar{O}_1$	$\bar{O}_2$	
L	L	"OFF" state	"OFF" state	Open
H	L	H	L	○
L	H	L	H	○
H	H	"OFF" state	"OFF" state	Open

CIRCUIT SCHEMATIC



BI-DIRECTIONAL MOTOR DRIVER

ABSOLUTE MAXIMUM RATINGS ($T_a=25^\circ\text{C}$, unless otherwise noted)

Symbol	Parameter	Conditions	Ratings	Unit
V_{CC}	Supply voltage		$-0.5 \sim +16$	V
$V_{CC'}$	Driver voltage		$-0.5 \sim V_{CC}$	V
V_i	Input voltage		$-0.5 \sim V_{CC}$	V
V_o	Output voltage		$-0.5 \sim V_{CC} + 2.5$	V
$I_{O(max)}$	Peak output current	$t_{op}=10\text{ms}$ Repetitive cycle 0.2Hz max	± 1200	mA
I_o	Continuous output current		± 330	mA
P_d	Power dissipation	$T_a=60^\circ\text{C}$	1000	mW
T_{opr}	Operating temperature		$-10 \sim +60$	$^\circ\text{C}$
T_{stg}	Storage temperature		$-55 \sim +125$	$^\circ\text{C}$

RECOMMENDED OPERATING CONDITIONS ($T_a=25^\circ\text{C}$, unless otherwise noted)

Symbol	Parameter	Conditions	Limits			Unit
			Min	Typ	Max	
V_{CC}	Supply voltage		6	14	15	V
I_o	Continuous output current				± 300	mA
V_{IH}	"H" Input voltage		3	5	V_{CC}	V
V_{IL}	"L" Input voltage			0	0.4	V
T_{OFF}	Input switching interval	It is prohibited to switch the inputs at the same time.	10	300		ms

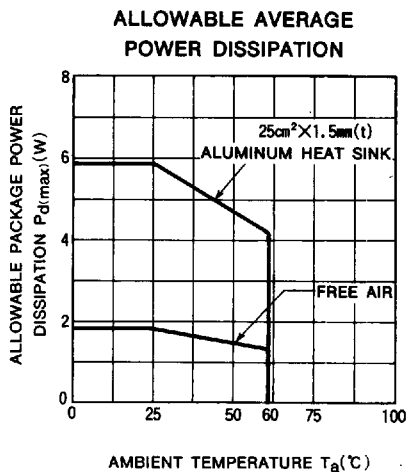
ELECTRICAL CHARACTERISTICS ($T_a=25^\circ\text{C}$, unless otherwise noted)

Symbol	Parameter	Test conditions		Limits			Unit
				Min	Typ*	Max	
$I_{O(leak)}$	Output leakage current	$V_{CC}=V_{CC'}=20\text{V}$ $V_{i1}=V_{i2}=3\text{V}$	$V_o=20\text{V}$ $V_o=0\text{V}$			100 -100	μA
V_{OH}	"H" Output saturation voltage	$V_{CC}=V_{CC'}=12\text{V}$ $I_{OH}=-300\text{mA}$	$V_{i1}=3\text{V}, V_{i2}=0\text{V}$ $V_{i1}=0\text{V}, V_{i2}=3\text{V}$	9.7	10.2		V
V_{OL}	"L" Output saturation voltage	$V_{CC}=V_{CC'}=12\text{V}$ $I_{OL}=300\text{mA}$	$V_{i1}=3\text{V}, V_{i2}=0\text{V}$ $V_{i1}=0\text{V}, V_{i2}=3\text{V}$		0.9	1.4	V
I_{IH}	"H" Input current	$V_{CC}=V_{CC'}=12\text{V}$	$V_{i1}=3\text{V}$ $V_{i2}=3\text{V}$			500	μA
I_{CC}	Supply current	$V_{CC}=V_{CC'}=16\text{V}$	$V_{i1}=3\text{V}, V_{i2}=0\text{V}$ $V_{i1}=0\text{V}, V_{i2}=3\text{V}$ $V_{i1}=0\text{V}, V_{i2}=0\text{V}$ $V_{i1}=3\text{V}, V_{i2}=3\text{V}$		7 0	10	mA

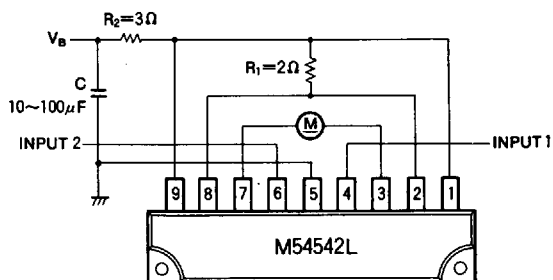
* : A typical value at $T_a=25^\circ\text{C}$.

BI-DIRECTIONAL MOTOR DRIVER

TYPICAL CHARACTERISTICS



APPLICATION EXAMPLE



Note

1. It is prohibited to switch the both inputs simultaneously. The inputs should be driven separately to avoid high crossover current.
2. The pins 1, 9 and 2, 8 are separated and shall be connected externally.