## Features

- Logic voltage: 5V
- High-voltage output: $\mathrm{V}_{\mathrm{DD}}-35 \mathrm{~V}$ max.
- Multiple display
(12-segment \& 16-digit to 20 -segment \& 8-digit)
- $12 \times 4$ matrix key scanning
- 8 steps dimmer circuit
- 5 LED output ports (20mA max.)


## Applications

- Consumer products panel function control
- Industrial measuring instrument panel function control


## General Description

HT16511 is a VFD (Vacuum Fluorescent Display) controller/driver that is driven on a $1 / 8$ to $1 / 16$ duty factor. It consists of 12 segment output lines, 8 grid output lines, 8 segment/grid output drive lines, 5 LED output ports, a control circuit, a display memory, and a key scan circuit.

- 4-bit general purpose input port
- No external resistors necessary for driver output (provides PMOS open-drain and pull-low resistor output)
- Serial interface with MCU (CLK, $\overline{\mathrm{CS}}, \mathrm{DI}, \mathrm{DO})$
- 52-pin QFP package
- Other similar application panel function control

Serial data inputs to the HT16511 through a three-line serial interface. This VFD controller/driver is ideal as a peripheral device for an MCU.

Block Diagram


## Pin Assignment



## Pad Assignment



Chip Size: $103.5 \times 70.5(\text { mil })^{2}$

* The IC substrate should be connected to VSS in the PCB layout artwork.

HT16511

Pad Coordinates
Unit: $\mu \mathrm{m}$

| Pad No. | $\mathbf{X}$ | $\mathbf{Y}$ | Pad No. | $\mathbf{X}$ | $\mathbf{Y}$ |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 1 | -1110.000 | 555.300 | 27 | 977.250 | -720.000 |
| 2 | -1110.000 | 450.300 | 28 | 977.250 | -612.000 |
| 3 | -1110.000 | 345.300 | 29 | 977.250 | -504.000 |
| 4 | -1110.000 | 240.300 | 30 | 977.250 | -396.000 |
| 5 | -1110.000 | 135.300 | 31 | 977.250 | -288.000 |
| 6 | -1165.900 | 9.800 | 32 | 977.250 | -180.000 |
| 7 | -1110.000 | -125.500 | 33 | 977.250 | -55.150 |
| 8 | -1110.000 | -230.500 | 34 | 977.250 | 49.850 |
| 9 | -1110.000 | -335.500 | 35 | 977.250 | 173.350 |
| 10 | -1110.000 | -440.500 | 36 | 977.250 | 281.350 |
| 11 | -1110.000 | -545.500 | 37 | 977.250 | 389.350 |
| 12 | -1110.000 | -650.500 | 38 | 977.250 | 497.350 |
| 13 | -1110.000 | -755.500 | 39 | 977.250 | 605.350 |
| 14 | -897.200 | -560.300 | 40 | 977.250 | 713.350 |
| 15 | -782.500 | -560.300 | 41 | 405.500 | 545.400 |
| 16 | -674.500 | -560.300 | 42 | 297.500 | 545.400 |
| 17 | -566.500 | -560.300 | 43 | 189.500 | 545.400 |
| 18 | -458.500 | -560.300 | 44 | 81.500 | 545.400 |
| 19 | -350.500 | -560.300 | -34.700 | 545.400 |  |
| 20 | -242.500 | -560.300 | -56 | 68.950 | 684.850 |
| 21 | -134.500 | -560.300 | 46 | -285.150 | 684.850 |
| 22 | -26.500 | -560.300 | 47 | -390.150 | 684.850 |
| 23 | 81.500 | -560.300 | 48 | -501.350 | 684.850 |
| 24 | 189.500 | -560.300 | -606.350 | 684.850 |  |
| 25 | 297.500 | -560.300 | 59 | -765.200 | 726.350 |
| 26 | 405.500 | -560.300 | 51 |  |  |

## Pin Description

| Pin No. | Pin Name | I/O | Description |
| :--- | :--- | :---: | :--- | :--- |
| $1 \sim 4$ | SW1~SW4 | I | 4-bit general purpose input port |
| 5 | DO | O | Output serial data at the falling edge of the shift clock, starting from low order <br> bit. This is an NMOS open-drain output pin. |
| 6 | DI | I | Input serial data at the rising edge of the shift clock, starting from the low order <br> bit. |
| 7 | NC | - | No connection |
| 8 | CLK | I | Reads serial data at the rising edge, and outputs data at the falling edge. |
| 9 | CS | Initializes serial interface at the rising or falling edge of the HT16511. Then it <br> waits to receive a command. Data input after CS has fallen is processed as a <br> command. While command data is processed, current processing is stopped, <br> and the serial interface is initialized. While CS is high, CLK is ignored. |  |
| $10 \sim 13$ | K0~K3 | I | Keying data input to these pins is latched at the end of the display cycle. |
| $14,33,45$ | VDD | - | Posistive power supply |
| $15 \sim 26$ | S1/K1~S12/K12 | O | Segment or key source output pins (dual function). This is PMOS open-drain <br> and pull-low resistor output. |
| $27 \sim 32$, | S13/G16~S20/G9 | O | Segment or Grid driver output pins. These pins are selectable for segment or <br> grid driving. This is PMOS open-drain and pull-low resistor output. |
| $35 \sim 36$ | VEE | - | VFD power supply |
| 34 | G8~G1 | O | Grid driver output pins (Grid only). This is PMOS open-drain and pull-low re- <br> sistor output. |
| $37 \sim 44$ | O | LED driver output ports. This is a CMOS output pin. |  |
| $46 \sim 50$ | LED4~LED0 | - | Negative power supply, ground |
| 51 | VSS | I | Connected to an external resistor or an RC oscillator circuit. |
| 52 | OSC |  |  |

## Approximate Internal Connections

| NMOS OUT | PMOS OUT | CMOS OUT |
| :---: | :---: | :---: |
| OVDD |  |  |

## Absolute Maximum Ratings

| Supply Voltage | . $\mathrm{V}_{\mathrm{SS}}-0.3 \mathrm{~V}$ to $\mathrm{V}_{\mathrm{SS}}+6.0 \mathrm{~V}$ | Operating Temperature........................ $25^{\circ} \mathrm{C}$ to $75^{\circ} \mathrm{C}$ |
| :---: | :---: | :---: |
| Input Voltage. | . $\mathrm{V}_{\mathrm{SS}}-0.3 \mathrm{~V}$ to $\mathrm{V}_{\mathrm{DD}}+0.3 \mathrm{~V}$ | Storage Temperature ........................ $-50^{\circ} \mathrm{C}$ to $125^{\circ} \mathrm{C}$ |

Note: These are stress ratings only. Stresses exceeding the range specified under "Absolute Maximum Ratings" may cause substantial damage to the device. Functional operation of this device at other conditions beyond those listed in the specification is not implied and prolonged exposure to extreme conditions may affect device reliability.
D.C. Characteristics
$\mathrm{Ta}=25^{\circ} \mathrm{C}$

| Symbol | Parameter | Test Conditions |  | Min. | Typ. | Max. | Unit |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | $V_{\text {D }}$ | Conditions |  |  |  |  |
| $V_{D D}$ | Logic Supply Voltage | - | - | 4.5 | 5 | 5.5 | V |
| $\mathrm{V}_{\text {EE }}$ | VFD Supply Voltage | - | - | 0 | - | $\mathrm{V}_{\mathrm{DD}}-35$ | V |
| fosc | Oscillation Frequency | 5 V | $\mathrm{R}_{\text {OSc }}=51 \mathrm{k} \Omega$ | 350 | 500 | 650 | kHz |
| $\mathrm{R}_{\mathrm{PL}}$ | Output Pull-low Resistor | 5 V | Driver output | 50 | 100 | 150 | k $\Omega$ |
| $\mathrm{I}_{\mathrm{DD}}$ | Operating Current | 5 V | No load, VFD display off | - | - | 5 | mA |
| lol | Driver Leakage Current | 5 V | $\mathrm{V}_{\mathrm{O}}=\mathrm{V}_{\text {DD }}-30 \mathrm{~V}$, VFD driver off | - | - | -10 | $\mu \mathrm{A}$ |
| lol1 | LED Sink Current | 5 V | $V_{\text {OL }}=1 \mathrm{~V}$, LED0~LED4 | 20 | - | - | mA |
| $\mathrm{I}_{\mathrm{OH} 1}$ | LED Source Current | 5 V | $\mathrm{V}_{\mathrm{OH}}=0.9 \mathrm{~V}_{\mathrm{DD}}$, LED0~LED4 | -1 | - | - | mA |
| $\mathrm{I}_{\mathrm{OH} 21}$ | Segment/Key Source Current | 5 V | $\mathrm{V}_{\text {OH }}=\mathrm{V}_{\mathrm{DD}}-2 \mathrm{~V}, \mathrm{~S} 1 / \mathrm{K} 1 \sim \mathrm{~S} 12 / \mathrm{K} 12$ | -3 | - | - | mA |
| $\mathrm{I}_{\mathrm{OH} 22}$ | Segment/Grid Source Current | 5 V | $\mathrm{V}_{\mathrm{OH}}=\mathrm{V}_{\mathrm{DD}}-2 \mathrm{~V}$ | -15 | - | - | mA |
| IoL3 | DO Sink Current | 5 V | $\mathrm{V}_{\mathrm{OL}}=0.4 \mathrm{~V}$ | 4 | - | - | mA |
| $\mathrm{V}_{\mathrm{IH}}$ | " H " Input Voltage | - | - | $0.7 \mathrm{~V}_{\mathrm{DD}}$ | - | $V_{D D}$ | V |
| $\mathrm{V}_{\text {IL }}$ | "L" Input Voltage | - | - | 0 | - | $0.3 \mathrm{~V}_{\mathrm{DD}}$ | V |
| $\mathrm{V}_{\mathrm{OH} 1}$ | High-level Output Voltage | 5 V | LED0~LED4, $\mathrm{I}_{\mathrm{OH} 1}=-1 \mathrm{~mA}$ | $0.9 \mathrm{~V}_{\mathrm{DD}}$ | - | $V_{D D}$ | V |
| $\mathrm{V}_{\text {OL1 }}$ | Low-level Output Voltage | 5 V | LED0~LED4, $\mathrm{l}_{\mathrm{OL} 1}=20 \mathrm{~mA}$ | 0 | - | 1 | V |
| Vol2 | Low-level Output Voltage | 5 V | $\mathrm{DO}, \mathrm{I}_{\mathrm{OL2}}=4 \mathrm{~mA}$ | 0 | - | 0.4 | V |

A.C. Characteristics
$\mathrm{Ta}=25^{\circ} \mathrm{C}$

| Symbol | Parameter | Test Conditions |  | Min. | Typ. | Max. | Unit |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | $\mathrm{V}_{\mathrm{DD}}$ | Conditions |  |  |  |  |
| $\mathrm{t}_{\text {PHL }}$ | Propagation Delay Time | 5 V | $\begin{aligned} & \mathrm{CLK} \rightarrow \mathrm{DO} \\ & \mathrm{C}_{\mathrm{L}}=15 \mathrm{pF}, \mathrm{R}_{\mathrm{L}}=10 \mathrm{k} \Omega \end{aligned}$ | - | - | 300 | ns |
| $\mathrm{t}_{\text {PLH }}$ |  | 5V |  | - | - | 100 | ns |
| $\mathrm{tr}_{\text {r }}$ | Rise Time | 5 V | $\mathrm{C}_{\mathrm{L}}=300 \mathrm{pF}, \mathrm{S} 0 \sim \mathrm{~S} 12$ | - | - | 2 | $\mu \mathrm{S}$ |
| $\mathrm{t}_{\mathrm{r} 2}$ |  | 5 V | $\mathrm{C}_{\mathrm{L}}=300 \mathrm{pF}$, G1~G16 | - | - | 0.5 | $\mu \mathrm{S}$ |
| $\mathrm{t}_{\mathrm{f}}$ | Fall Time | 5 V | $\mathrm{C}_{\mathrm{L}}=300 \mathrm{pF}, \mathrm{Sn}, \mathrm{Gn}$ | - | - | 120 | $\mu \mathrm{S}$ |
| $\mathrm{t}_{\text {max }}$ | Maximum Clock Frequency | 5 V | Duty=50\% | 1 | - | - | MHz |
| Ci | Input Capacitance | 5 V | - | - | - | 15 | pF |
| $\mathrm{t}_{\text {CW }}$ | Clock Pulse Width | 5 V | - | 400 | - | - | ns |
| $t_{\text {SW }}$ | Strobe Pulse Width | 5 V | - | 1 | - | - | us |
| $t_{\text {SU }}$ | Data Setup Time | 5 V | - | 100 | - | - | ns |
| $t_{h}$ | Data Hold Time | 5 V | - | 100 | - | - | ns |
| $\mathrm{t}_{\mathrm{CS}}$ | Clock-Strobe Time | 5 V | CLK rising edge to CS rising edge | 1 | - | - | $\mu \mathrm{S}$ |
| $t_{\text {w }}$ | Wait Time | 5V | CLK rising edge to CLK falling edge | 1 | - | - | $\mu \mathrm{S}$ |

## Functional Description

## Display RAM and Display Mode

The static display RAM is organized into $40 \times 8$ bits and stores the data transmitted from an external device to the HT16511 through a serial interface. The contents of the RAM are directly mapped to the contents of the VFD driver. Data in the RAM can be accessed through the data setting, address setting and display control commands. It is assigned addresses in 8-bit unit as follows:

| SEG4 |  | SEG8 | SEG12 SEG16 SEG20 |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 00 HL | 00Hu | 01HL | 01Hu | 02HL | DIG1 |
| 03 HL | 03 Hu | 04HL | 04Hu | $05 \mathrm{HL}^{2}$ | DIG2 |
| 06 HL | 06 Hu | 07HL | 07Hu | 08 HL | DIG3 |
| 09 HL | 09 Hu | 0AHL | 0AHu | 0BHL | DIG4 |
| 0 CHL | 0CHu | ODHL | ODHu | 0EHL | DIG5 |
| 0FHL | 0FHu | 10HL | 10Hu | 11 HL | DIG6 |
| 12HL | 12 Hu | 13 HL | 13 Hu | 14 HL | DIG7 |
| 15 HL | 15 Hu | 16 HL | 16 Hu | 17HL | DIG8 |
| 18 HL | 18 Hu | 19HL | 19Hu | 1 AHL | DIG9 |
| 1 BHL | 1 BHu | 1 CHL | 1 CHu | 1DHL | DIG10 |
| 1EHL | $1 \mathrm{EH} u$ | 1 FHL | 1 FHu | 20 HL | DIG11 |
| 21 HL | 21 Hu | 22 HL | 22 Hu | 23 HL | DIG12 |
| 24 HL | 24 Hu | 25 HL | 25 Hu | 26 HL | DIG13 |
| 27 HL | 27 Hu | 28 HL | 28 Hu | 29 HL | DIG14 |
| 2 AHL | 2 AHu | 2 BHL | 2 BHu | 2 CHL | DIG15 |
| 2DHL | 2DHu | 2 EHL | 2 EHu | 2 FHL | DIG16 |


| b0 | b3b4 |
| :--- | :--- |
| XXHL | XXHU |
| Lower | Higher |
| 4 bits | 4 bits |

Note: Only the lower 4 bits of the addresses assigned to SEG17 through SEG20 are valid, the higher 4 bits are ignored.

## Dimming Control

HT16511 provides 8-step dimmer function on display by controlling the 3 -bit binary command code. The full pulse width of grid signal is divides into 16 uniform sections by PWM (pulse width modulation) technology.
The 16 uniform sections available form 8 steps dimmer via 3-bit binary code. The 8-step dimmer includes $1 / 16$, $2 / 16,4 / 16,10 / 16,11 / 16,12 / 16,13 / 16$ and $14 / 16$. The $1 / 16$ pulse width indicates minimum lightness. The 14/16 pulse width represents maximum lightness (Refer to the display control command).

## Key Matrix and Key-Input Data Storage RAM

The key matrix scans the series key states at each level of the key strobe signal (S1/K1~S12/K12) output of the HT16511. The key strobe signal outputs are time-multiplexed signals from S1/K1~S12/K12. The states of inputs K0~K3 are sampled by strobe signal $\mathrm{S} 1 / \mathrm{K} 1 \sim \mathrm{~S} 12 / \mathrm{K} 12$ and latched into the register.

The key matrix is made up of a $12 \times 4$ matrix, as shown below.


Detail


The data of each key is stored as illustrated below, and is read with the read command, starting from the least significant bit.


## LED Port

The LED port belongs to the CMOS output configuration.
Data is written to the LED port with the write command, starting from the least port's least significant bit. In our application (see application circuits), the user adopts an internal NMOS device to a driver LED component by connecting VDD. When a bit of this port is 0 , the corresponding LED lights; when the bit is 1 , the LED turns off. The data of bits 6 through 8 are ignored.


## SW Data

The HT16511 provides an extra 4-bit general input port. The SW data is provided with available binary code. The SW data is read with the read command, starting from the least significant bit. Bits 5 through 8 of the SW data are 0 .


## Commands

Commands set the display mode and status of the VFD driver.
The first 1 byte input to the HT16511 through the DI pin after the $\overline{\mathrm{CS}}$ pin has fallen, is regarded as a command. If $\overline{\mathrm{CS}}$ is set high while commands/data are transmitted, serial communication is initialized, and the commands/ data being transmitted are not valid (however, the commands/data previously transmitted remains valid).

- Display mode setting commands

These commands initialize the HT16511 and select the number of segments and the number of grids (1/8~1/16 duty, 12 segments to 20 segments).
When these commands are executed, the display is forcibly turned off, and key scanning is also stopped. To resume display, the display command "ON" must be executed. If the same mode is selected, nothing happens.


Note: Power-on status: 16 -digit, 12 segment mode is selected.

- Data setting commands

These commands set the data write and data read modes.


Note: power-on status: normal mode operation and address increment mode are set.

- Address setting commands

These commands set the address of the display memory.


If address 30 H or higher is set, data is ignored until a valid address is set. Note: power-on status: the address is set to 00 H .

- Display control commands

| MSB |  |  |  |  |  |  |  |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| 1 | 0 | - | - | b3 | b2 | b1 | b0 |

Note: power-on status: 1-16 pulse width is set and the display is turned off. Key scanning will be stopped during power

## Timing Diagrams



## Key Scanning and Display Timing



Note: One cycle of key scan consists of two frames, and data of $12 \times 4$ matrixes is stored in RAM.

## Serial Communication Format

- Reception (command/data write)

- Transmission (data read)


DO must be sure to connect an external pull-high resistor to this pin ( $1 \mathrm{k} \Omega$ to $10 \mathrm{k} \Omega$ ).
Note: When data is read, a wait time " $\mathrm{t} \mathrm{w}^{\prime}$ " of $1 \mu \mathrm{~s}$ is necessary.

- Updating display memory by incrementing address


Note: Command 1: sets display mode
Command 2: sets data
Command 3: sets address
Data 1 to n : transfers display data ( 48 bytes max.)
Command 4: controls display

- Updating specific addresses


Note: Command 1: sets data
Command 2: sets address
Data: display data

## Application Circuits



Note: $\quad$ Rosc $=51 \mathrm{k} \Omega$ for oscillator resistor
R1=1~10k $\Omega$ for external pull-high resistor
R2~R6=750 $\Omega \sim 1.2 \mathrm{k} \Omega$
R7~R10=10k $\Omega$ for external pull-low resistor
D1~D12=1N4001
Ef=Filament voltage for VFD

## Package Information

## 52-pin QFP (14×14) Outline Dimensions



| Symbol | Dimensions in mm |  |  |
| :---: | :---: | :---: | :---: |
|  | Min. | Nom. | Max. |
| A | 18.80 | - | 19.20 |
| B | 13.90 | - | 14.10 |
| C | 18.80 | - | 19.20 |
| D | 13.90 | - | 14.10 |
| E | - | 0.65 | - |
| F | - | 0.40 | - |
| G | 2.50 | - | 3.10 |
| H | - | - | 3.40 |
| J | - | 0.10 | - |
| K | 0.73 | - | 1.03 |
| $\alpha$ | 0.10 | - | 0.20 |
| $0^{\circ}$ | - | $7^{\circ}$ |  |

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