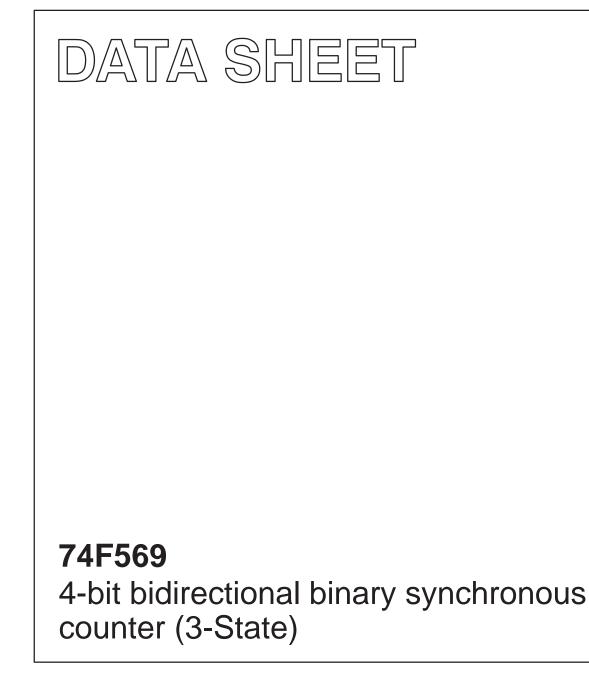
# INTEGRATED CIRCUITS



Product specification

1996 Jan 05

IC15 Data Handbook



74F569

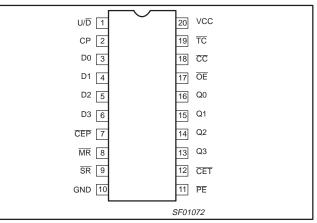
#### **FEATURES**

- 4-bit bidirectional counting binary counter
- Synchronous counting and loading
- Look ahead carry capability for easy cascading
- Preset capability for programmable operation
- Master Reset (MR) overrides all other inputs
- Synchronous Reset (SR) overrides counting and parallel loading
- Clock Carry (CC) output to be used as a clock for flip-flops, register and counters
- 3-State outputs for bus organized systems

#### DESCRIPTION

The 74F569 is a fully synchronous Up/Down binary counter. It features preset capabilities for programmable operation, carry look ahead for programmable operation, carry look ahead for easy cascading, and  $U/\overline{D}$  input to control the direction of counting. For maximum flexibility there are both Synchronous and Master Reset inputs as well as both Clocked Carry (CC) and Terminal Count (TC) outputs. All state changes except Master Reset are initiated by rising edge of the clock. A High signal on the Output Enable ( $\overline{OE}$ ) input forces the output buffers into the high impedance state but does not prevent counting, resetting or parallel loading.

#### **PIN CONFIGURATION**

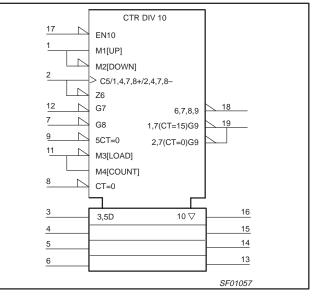


ТҮРЕ	TYPICAL f <sub>MAX</sub>	TYPICAL SUPPLY CURRENT (TOTAL)
74F569	115MHz	40mA

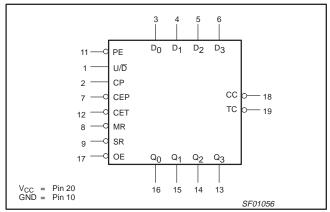
#### **ORDERING INFORMATION**

	ORDER CODE			
DESCRIPTION	COMMERCIAL RANGE V <sub>CC</sub> = 5V ±10%, T <sub>amb</sub> = 0°C to +70°C	PKG. DWG. #		
20-pin plastic DIP	N74F569N	SOT146-1		
20-pin plastic SO	N74F569D	SOT163-1		

#### LOGIC SYMBOL (IEEE/IEC)



#### LOGIC SYMBOL



74F569

20µA/0.6mA

20µA/0.6mA

20µA/0.6mA

1.0mA/20mA

1.0mA/20mA

3.0mA/24mA

Product specification

INPUT AND OU	TPUT LOADING AND FAN-OUT TABLE			
PINS	DESCRIPTION	74F(U.L.) HIGH/LOW	LOAD VALUE HIGH/LOW	
D0 - D3	Parallel data inputs	1.0/1.0	20µA/0.6mA	
CEP	Count Enable parallel input (active Low)	1.0/1.0	20µA/0.6mA	
CET	Count Enable Trickle input (active Low)	1.0/2.0	20µA/1.2mA	
СР	Clock input (active rising edge)	1.0/1.0	20µA/0.6mA	
PE	Parallel Enable input (active Low)	1.0/2.0	20µA/1.2mA	
U/D	Up/Down count control input	1.0/1.0	20µA/0.6mA	

NOTE: One (1.0) FAST Unit Load (U.L.) is defined as: 20µA in the High state and 0.6mA in the Low state.

#### FUNCTIONAL DESCRIPTION

Philips Semiconductors

OE

MR

SR

TC

CC

Q0 - Q3

The 74F569 counts in the modulo-16 binary sequence. From state 0 (LLLL) it will increment to 15 in the up mode; in the down mode it will decrement from 15 to 0. The clock inputs of all flip-flops are driven parallel through a clock buffer. All state changes (except due to Master Reset) occur synchronously with the Low-to-High transition of the Clock Pulse ( $\overline{CP}$ ) input.

Data outputs

**Output Enable input** 

Master Reset input (active Low)

Synchronous Reset (active Low)

Terminal count output (active Low)

Clocked carry output (active Low)

The circuit has five fundamental modes of operation, in order of precedence: asynchronous reset, synchronous reset, parallel load, count and hold. Six control inputs–Master Reset ( $\overline{MR}$ ), Synchronous Reset ( $\overline{SR}$ ), Count Enable Trickle ( $\overline{CET}$ ), Parallel Enable ( $\overline{PE}$ ), Count Enable Parallel ( $\overline{CEP}$ ), and the Up/Down (U/ $\overline{D}$ ) input – determine the mode of operation, as shown in the Function Table.

A Low signal on  $\overline{\text{MR}}$  overrides all other inputs and asynchronously forces the flip-flop Q outputs Low. A Low signal on  $\overline{\text{SR}}$  overrides counting and parallel loading and allows the Q output to go Low on the next rising edge of CP. A Low signal on  $\overline{\text{PE}}$  overrides counting and allows information on the parallel data (Dn) inputs to be loaded into the flip-flops on the next rising edge of CP. With  $\overline{\text{MR}}$ ,  $\overline{\text{SR}}$ , and  $\overline{\text{PE}}$  High,  $\overline{\text{CEP}}$  and  $\overline{\text{CET}}$  permit counting when both are Low. Conversely, a High signal on either  $\overline{\text{CEP}}$  and  $\overline{\text{CET}}$  inhibits counting.

The 74F569 uses edge-triggered flip-flops and changing the  $\overline{SR}$ ,  $\overline{PE}$ ,  $\overline{CEP}$ ,  $\overline{CET}$  or U/D inputs when the CP is in either state does not cause errors, provided that the recommended setup and hold times, with respect to the rising edge of CP, are observed. Two types of outputs are provided as overflow/underflow indicators. The Terminal Count (TC) output is normally High and goes Low provided  $\overline{CET}$  is Low, when the counter reaches zero in the down mode, or reaches maximum 15 in the up mode

 $\overline{TC}$  will then remain Low until a state change occurs by counting or presetting, or until U/D or  $\overline{CET}$  is changed.

To implement synchronous multistage counters, the connections between the TC output and the CEP and CET inputs can provide either slow or fast carry propagation. Figure 1 shows the connections for a simple ripple carry, in which the clock period must be longer than the CP to TC delay of the first stage, plus the cumulative CET to TC delays of the intermediate stages, plus the CET to CP setup time of the last stage. This total delay plus setup time sets the upper limit on clock frequency. For faster clock rates, the carry look ahead connections in Figure 2 are recommended. In this scheme the ripple delay through the intermediate stages commences with the same clock that causes the first stage to tick over from Max to Min in the up mode, or Min to Max in the down mode, to start its final cycle. Since this takes 16 clocks to complete, there is plenty of time for the ripple to progress through the intermediate stages. The critical timing that limits the clock period is the CP to TC delay of the first stage plus the CEP to CP setup time of the last stage. The TC output is subject to decoding spikes due to internal race conditions and is therefore not recommended for use as a clock or asynchronous reset for flip-flops, register or counters.

1.0/1.0

1.0/1.0

1.0/1.0

50/33

50/33

150/40

For such applications, the Clocked Carry ( $\overline{CC}$ ) output is provided. The  $\overline{CC}$  output is normally High. When  $\overline{CEP}$ ,  $\overline{CET}$ , and  $\overline{TC}$  are Low, the  $\overline{CC}$  output will go Low, when the clock next goes Low and will stay Low until the clock goes High again; as shown in the  $\overline{CC}$  Function Table. When the Output Enable ( $\overline{OE}$ ) is Low, the parallel data outputs Q0–Q3 are active and follow the flip-flop Q outputs. A High signal on  $\overline{OE}$  forces Q0–Q3 to the High impedance state but does not prevent counting, loading or resetting.

 $\begin{array}{l} \mbox{LOGIC EQUATIONS:} \\ \mbox{Count Enable=CEP}{\times} \hline \mbox{CET} {\times} \hline \mbox{PE} \\ \mbox{Up: } TC=Q0{\times}Q1{\times}Q2{\times}Q3{\times} (Up){\times} \hline \mbox{CET} \\ \mbox{Down: } TC=Q0{\times}Q1{\times}Q2{\times}Q3{\times} (Down){\times} \hline \mbox{CET} \\ \end{array}$ 

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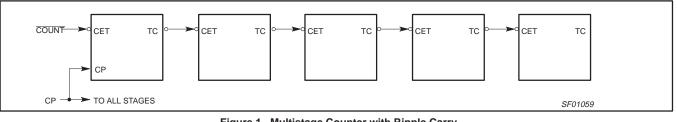


Figure 1. Multistage Counter with Ripple Carry

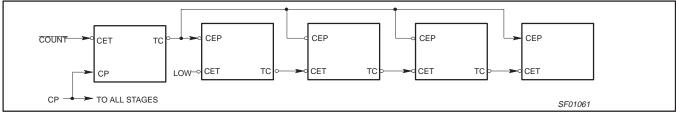
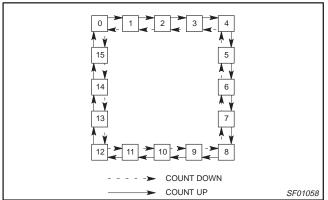


Figure 2. Multistage Counter with Look-Ahead Carry

#### STATE DIAGRAM



#### **CC** FUNCTION TABLE

		INP	UTS			OUTPUT	
SR	PE						
L	Х	Х	Х	Х	Х	Н	
Х	L	Х	Х	Х	Х	Н	
Х	Х	Н	Х	Х	Х	Н	
Х	Х	Х	Н	Х	Х	Н	
Х	Х	Х	Х	Н	Х	Н	
Н	Н	L	L	L	Ъ	U	

TC is generated internally =

= High voltage level Н

L X Low voltage level =

Don't care = l

= Low Pulse

#### **FUNCTION TABLE**

			INPUTS				OPERATING MODE		
MR	SR	PE	CEP	CET	U/D	СР			
L	Х	Х	Х	Х	Х	Х	Asynchronous reset		
h	Ι	Х	Х	Х	Х	↑	Synchronous reset		
h	h	I	Х	Х	Х	Ŷ	Parallel load		
h	h	h	I	I	h	Ŷ	Count Up (increment)		
h	h	h	I	I	I	Ŷ	Count Down (decrement)		
h	Н	Н	Н	Х	Х	Х	Hold (do nothing)		
h	Н	Н	Х	Н	Х	Х			

H = High voltage level

h = High voltage level one setup time prior to the Low-to-High clock transition

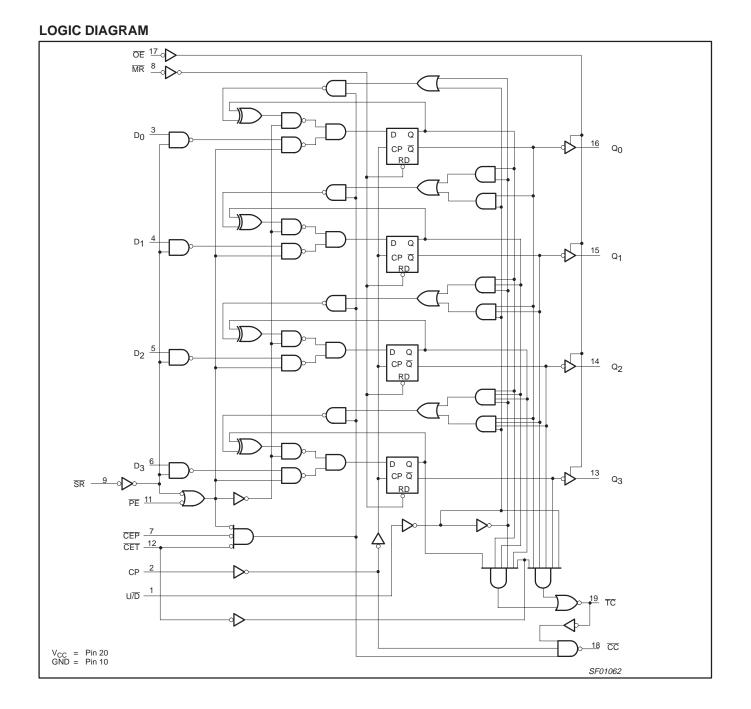
L = Low voltage level

= Low voltage level one setup time prior to the Low-to-High clock transition 1

X = Don't care

 $\uparrow$  = Low-to-High clock transition

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#### **ABSOLUTE MAXIMUM RATINGS**

(Operation beyond the limits set forth in this table may impair the useful life of the device.

Unless otherwise noted these limits are over the operating free-air temperature range.)

SYMBOL	PARAMETER		RATING	UNIT
V <sub>CC</sub>	Supply voltage		-0.5 to +7.0	V
V <sub>IN</sub>	Input voltage		-0.5 to +7.0	V
I <sub>IN</sub>	Input current	-30 to +5	mA	
V <sub>OUT</sub>	Voltage applied to output in High output state	-0.5 to +V <sub>CC</sub>	V	
laum.	Current applied to output in Low output state	TC, CC	40	mA
IOUT	Current applied to output in Low output state	48	mA	
T <sub>amb</sub>	Operating free-air temperature range		0 to +70	°C
T <sub>stg</sub>	Storage temperature	–65 to +150	°C	

#### **RECOMMENDED OPERATING CONDITIONS**

SYMBOL	PARAMETER		UNIT				
STWIDOL		MIN	NOM	MAX			
V <sub>CC</sub>	Supply voltage		4.5	5.0	5.5	V	
V <sub>IH</sub>	High-level input voltage	High-level input voltage					
V <sub>IL</sub>	Low-level input voltage			0.8	V		
I <sub>IK</sub>	Input clamp current			-18	mA		
1	High lovel output ourrent	TC, CC			-1	mA	
ЮН	High-level output current	Qn			-3	mA	
1	Low lovel output ourrent	TC, CC			20	mA	
IOL	Low-level output current			24	mA		
T <sub>amb</sub>	Operating free-air temperature range	0		70	°C		

#### DC ELECTRICAL CHARACTERISTICS

(Over recommended operating free-air temperature range unless otherwise noted.)

						UNIT		
SYMBOL	PARAMETER	R	TEST CONDITIONS	TEST CONDITIONS <sup>NO TAG</sup>			MAX	
\/	High-level output voltage		$V_{CC} = MIN, V_{IL} = MAX,$	$V_{CC} = MIN, V_{II} = MAX, \pm 10\% V_{CC}$				V
V <sub>OH</sub>	nightevel output voltage		$V_{IH} = MIN, I_{OH} = MAX$	$\pm 5\% V_{CC}$	2.7	3.3		V
M			$V_{CC} = MIN, V_{IL} = MAX,$	±10%V <sub>CC</sub>		0.35	0.50	V
V <sub>OL</sub>	Low-level output voltage		$V_{IH} = MIN, I_{OL} = MAX$	±5%V <sub>CC</sub>		0.35	0.50	V
V <sub>IK</sub>	Input clamp voltage		$V_{CC} = MIN, I_I = I_{IK}$			-0.73	-1.2	V
l <sub>l</sub>	Input current at maximum ir	nput voltage	V <sub>CC</sub> = MAX, V <sub>I</sub> = 7.0V			100	μA	
I <sub>IH</sub>	High-level input current		$V_{CC} = MAX, V_I = 2.7V$				20	μA
I.,	Low lovel input ourrest	Others	$V_{CC} = MAX, V_1 = 0.5V$				-0.6	mA
ΙL	Low-level input current	CET, PE	$v_{\rm CC} =  v AX, v  = 0.5v$			-1.2	mA	
I <sub>OZH</sub>	Off-state output current, High-level voltage applied		$V_{CC} = MAX, V_O = 2.7V$				50	μΑ
I <sub>OZL</sub>	Off-state output current, High-level voltage applied		$V_{CC} = MAX, V_O = 0.5V$				-50	μΑ
los	Short-circuit output current <sup>N</sup>	IO TAG	V <sub>CC</sub> = MAX		-60		-150	mA
		I <sub>ССН</sub>				38	60	mA
I <sub>CC</sub>	Supply current (total)	I <sub>CCL</sub>	V <sub>CC</sub> = MAX			43	62	mA
		I <sub>CCZ</sub>	1			40	60	mA

NOTES:

1. For conditions shown as MIN or MAX, use the appropriate value specified under recommended operating conditions for the applicable type.

2. All typical values are at V<sub>CC</sub> = 5V,  $T_{amb}$  = 25°C.

3. Not more than one output should be shorted at a time. For testing I<sub>OS</sub>, the use of high-speed test apparatus and/or sample-and-hold techniques are preferable in order to minimize internal heating and more accurately reflect operational values. Otherwise, prolonged shorting of a High output may raise the chip temperature well above normal and thereby cause invalid readings in other parameter tests. In any sequence of parameter tests, I<sub>OS</sub> tests should be performed last.

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### AC ELECTRICAL CHARACTERISTICS

						LIMIT	ſS		
SYMBOL	PARAMETER	2	TEST CONDITIONS		<sub>amb</sub> = +25 <sup>°</sup> / <sub>CC</sub> = +5.\		T <sub>amb</sub> = 0°C V <sub>CC</sub> = +5		UNIT
		•			60pF, R <sub>L</sub> =		$C_{L} = 50 \text{ pF},$		
				MIN	ТҮР	MAX	MIN	MAX	
f <sub>MAX</sub>	Maximum clock Qn		Waveform 1	100	115		90		MHz
'MAX	frequency	CC, TC	Waveform 2	50	65		45		MHz
t <sub>PLH</sub> t <sub>PHL</sub>	Propagation delay CP to $Q_n$ ( $\overline{PE}$ , High or	Low)	Waveform 1	3.0 4.0	6.0 7.5	9.5 11.0	3.0 4.0	10.0 12.0	ns ns
t <sub>PLH</sub> t <sub>PHL</sub>	Propagation delay CP to TC		Waveform 2	5.5 4.0	10.0 7.5	15.0 11.0	5.5 4.0	16.0 12.0	ns ns
t <sub>PLH</sub> t <sub>PHL</sub>	Propagation delay CET to TC		Waveform 3	1.5 2.5	3.0 5.0	6.0 8.0	1.0 2.5	7.0 9.0	ns ns
t <sub>PLH</sub> t <sub>PHL</sub>	Propagation delay U/D to TC		Waveform 4	4.0 4.0	7.5 6.5	11.0 11.0	4.0 4.0	12.0 12.0	ns ns
t <sub>PLH</sub> t <sub>PHL</sub>	Propagation delay CP to CC		Waveform 2	2.5 2.0	4.5 4.0	7.5 6.6	2.0 2.0	6.0 7.0	ns ns
t <sub>PLH</sub> t <sub>PHL</sub>	Propagation delay CEP, CET to CC		Waveform 2	2.0 3.5	4.0 5.5	7.0 9.0	1.5 3.0	7.5 10.0	ns ns
t <sub>PHL</sub>	Propagation delay MR to Qn		Waveform 5	6.0	8.0	11.0	5.5	12.0	ns
t <sub>PLH</sub> t <sub>PHL</sub>	Propagation delay U/D to CC		Waveform 4	4.5 5.0	9.0 11.0	12.0 16.0	4.0 5.0	13.5 17.0	ns ns
t <sub>PHL</sub>	Propagation delay MR to TC, CC		Waveform 5	8.0	11.0	15.0	7.5	16.0	ns ns
t <sub>PLH</sub> t <sub>PHL</sub>	Propagation delay SR to CC		Waveform 3	5.5 7.5	8.0 9.5	11.0 12.0	5.0 7.0	12.0 13.0	ns ns
t <sub>PLH</sub> t <sub>PHL</sub>	Propagation delay PE to CC		Waveform 3	3.0 4.0	5.0 6.0	8.0 8.5	2.5 4.0	8.5 9.5	ns ns
t <sub>PZH</sub> t <sub>PZL</sub>	Output Enable time to High or Low level OE t	o Qn	Waveform 10 Waveform 11	2.0 4.5	4.0 6.5	7.0 9.5	2.0 4.0	7.5 10.0	ns ns
t <sub>PHZ</sub> t <sub>PLZ</sub>	Output Disable time to High or Low level OE t	o Qn	Waveform 10 Waveform 11	1.5 1.5	3.5 3.5	6.5 6.0	1.5 1.5	7.5 6.5	ns ns

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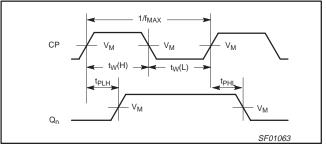
#### AC SETUP REQUIREMENTS

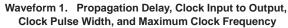
				LIM	ITS		
SYMBOL	PARAMETER	TEST CONDITIONS	T <sub>amb</sub> = V <sub>CC</sub> =		T <sub>amb</sub> = 0°C V <sub>CC</sub> = +5.		UNIT
			C <sub>L</sub> = 50pF,		C <sub>L</sub> = 50pF,		
			MIN	TYP	MIN	MAX	
t <sub>s</sub> (H) t <sub>s</sub> (L)	Setup time, High or Low D <sub>n</sub> to CP	Waveform 6	4.0 4.0		4.5 4.5		ns ns
t <sub>h</sub> (H) t <sub>h</sub> (L)	Hold time, High or Low D <sub>n</sub> to CP	Waveform 6	2.0 2.0		2.5 2.5		ns ns
t <sub>s</sub> (H) t <sub>s</sub> (L)	Setup time, High or Low CEP or CET to CP	Waveform 7	5.0 5.0		6.0 6.0		ns ns
t <sub>h</sub> (H) t <sub>h</sub> (L)	Hold time, High or Low CEP or CET to CP	Waveform 7	0 0		0 0		ns ns
t <sub>s</sub> (H) t <sub>s</sub> (L)	Setup time, High or Low PE to CP	Waveform 6	8.0 8.0		9.0 9.0		ns ns
t <sub>h</sub> (H) t <sub>h</sub> (L)	Hold time, High or Low PE to CP	Waveform 6	0 0		0 0		ns ns
t <sub>s</sub> (H) t <sub>s</sub> (L)	Setup time, High or Low $U/\overline{D}$ to CP	Waveform 8	10.0 8.0		12.5 8.0		ns ns
t <sub>h</sub> (H) t <sub>h</sub> (L)	Hold time, High or Low U/D to CP	Waveform 8	0 0		0 0		ns ns
t <sub>s</sub> (H) t <sub>s</sub> (L)	Setup time, High or Low SR to CP	Waveform 9	8.0 8.0		9.0 9.0		ns ns
t <sub>h</sub> (H) t <sub>h</sub> (L)	Hold time, High or Low SR to CP	Waveform 9	0 0		0 0		ns ns
t <sub>w</sub> (H) t <sub>w</sub> (L)	CP Pulse width, High or Low	Waveform 1	7.0 5.0		8.0 6.0		ns ns
t <sub>w</sub> (H)	MR Pulse width, Low	Waveform 5	4.5		5.0		ns
t <sub>REC</sub>	Recovery time, MR to CP	Waveform 5	6.0		7.0		ns

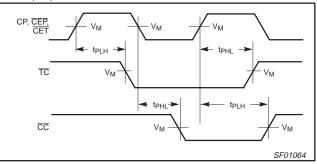
#### AC WAVEFORMS

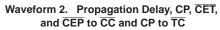
For all waveforms,  $V_M = 1.5V$ 

The shaded areas indicate when the input is permitted to change for predictable output performance.





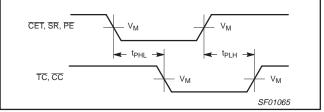




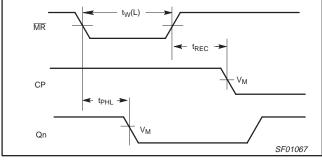
#### AC WAVEFORMS (Continued)

For all waveforms,  $V_{M}$  = 1.5V

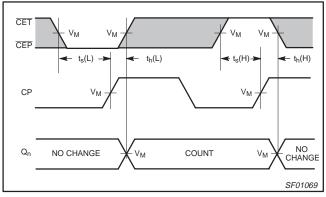
The shaded areas indicate when the input is permitted to change for predictable output performance.



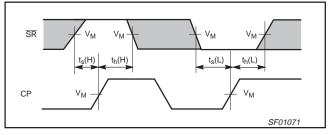
Waveform 3. Propagation Delays CET to TC and SR or PE to CC



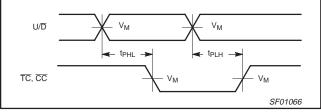
Waveform 5. Master Reset Pulse Width, Master Reset to Output Delay and Master Reset to Clock Recovery Time



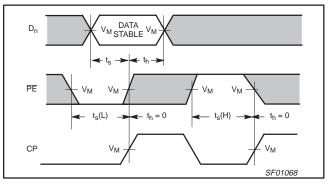
Waveform 7. Count Enable Data Setup and Hold Times



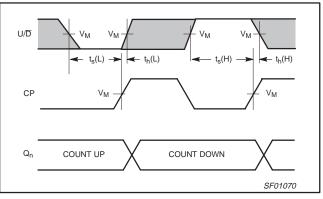
Waveform 9. Synchronous Reset Setup and Hold Times



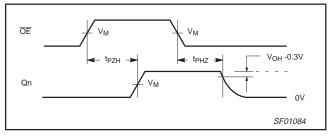




Waveform 6. Parallel Data and Parallel Enable Setup and Hold Times



Waveform 8. Up/Down Control Setup and Hold Times

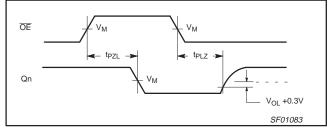


Waveform 10. 3-State Output Enable Time to High Level and Output Disable Time from High Level

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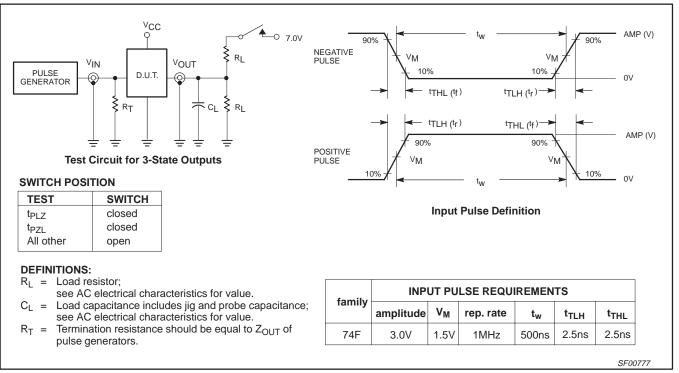
#### AC WAVEFORMS (Continued)

For all waveforms,  $V_M = 1.5V$ The shaded areas indicate when the input is permitted to change for predictable output performance.



Waveform 11. 3-State Output Enable Time to Low Level and Output Disable Time from Low Level

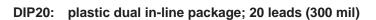
#### **TEST CIRCUIT AND WAVEFORM**

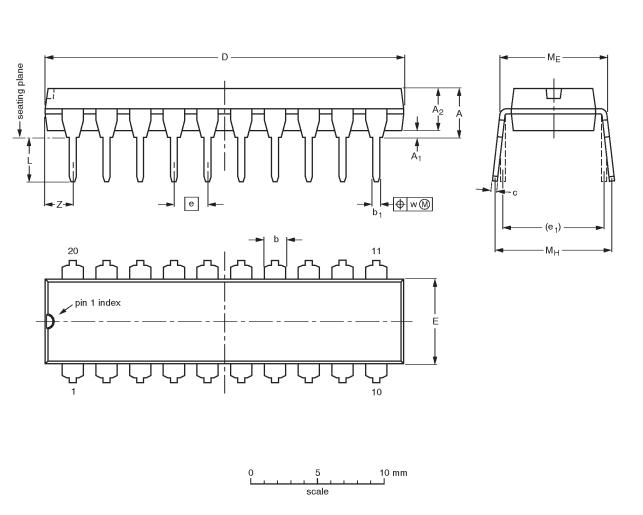


### 74F569

#### 1996 Jan 05

# 4-bit bidirectional binary synchronous counter (3-State)





#### DIMENSIONS (inch dimensions are derived from the original mm dimensions)

UNIT	A max.	A <sub>1</sub> min.	A <sub>2</sub> max.	b	b <sub>1</sub>	с	D <sup>(1)</sup>	E <sup>(1)</sup>	e	e <sub>1</sub>	L	M <sub>E</sub>	M <sub>H</sub>	w	Z <sup>(1)</sup> max.
mm	4.2	0.51	3.2	1.73 1.30	0.53 0.38	0.36 0.23	26.92 26.54	6.40 6.22	2.54	7.62	3.60 3.05	8.25 7.80	10.0 8.3	0.254	2.0
inches	0.17	0.020	0.13	0.068 0.051	0.021 0.015	0.014 0.009	1.060 1.045	0.25 0.24	0.10	0.30	0.14 0.12	0.32 0.31	0.39 0.33	0.01	0.078

#### Note

1. Plastic or metal protrusions of 0.25 mm maximum per side are not included.

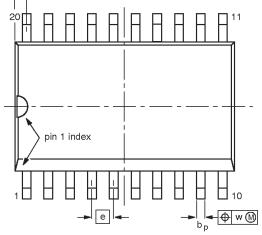
OUTLINE		REFER	EUROPEAN	ISSUE DATE		
VERSION	IEC	JEDEC	EIAJ		PROJECTION	ISSUE DATE
SOT146-1			SC603			<del>-92-11-17-</del> 95-05-24

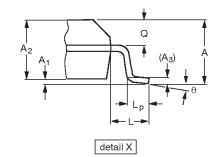
# 74F569

SOT146-1

Product specification

# SO20: plastic small outline package; 20 leads; body width 7.5 mm SOT163-1 А D Х Ду = v 🕅 A He







0.394

0.016

0.039

#### DIMENSIONS (inch dimensions are derived from the original mm dimensions) Α D<sup>(1)</sup> z <sup>(1)</sup> E <sup>(1)</sup> $A_1$ bp UNIT $A_2$ $A_3$ с е $H_{\rm E}$ L Lp Q v w у max. 0.30 2.45 0.49 0.32 13.0 7.6 10.65 0.9 1.1 1.1 2.65 mm 0.25 1.27 0.25 0.25 0.1 1.4 0.10 2.25 0.36 0.23 12.6 7.4 10.00 0.4 1.0 0.4 0.035 0.012 0.019 0.013 0.51 0.043 0.043 0.096 0.30 0.419 0.10 inches 0.050 0.055 0.004 0.01 0.01 0.01

0.29

#### Note

0.004

0.089

1. Plastic or metal protrusions of 0.15 mm maximum per side are not included.

0.014

0.009

0.49

OUTLINE VERSION	REFERENCES				EUROPEAN	ISSUE DATE
	IEC	JEDEC	EIAJ		PROJECTION	ISSUE DATE
SOT163-1	075E04	MS-013AC				<del>-95-01-24</del> 97-05-22



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8<sup>0</sup>

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0.016

#### Product specification

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NOTES

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DEFINITIONS					
Data Sheet Identification	Product Status	Definition			
Objective Specification	Formative or in Design	This data sheet contains the design target or goal specifications for product development. Specifications may change in any manner without notice.			
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