

LMP7731

2.9 nV/sqrt(Hz) Low Noise, Precision, RRIO Amplifier

General Description

The LMP7731 is a single, low noise, rail-to-rail input and output, low voltage amplifier. The LMP7731 is part of the LMP® precision amplifier family and is ideal for precision and low noise applications with low voltage requirements.

This operational amplifier offers low voltage noise of 2.9 nV/√Hz with a 1/f corner of only 3 Hz. The LMP7731 has bipolar input stages with a bias current of only 1.5 nA. This low input bias current, complemented by the very low level of voltage noise, makes the LMP7731 an excellent choice for photometry applications.

The LMP7731 provides a wide GBW of 22 MHz while consuming only 2 mA of current. This high gain bandwidth along with the high open loop gain of 130 dB enables accurate signal conditioning in applications with high closed loop gain requirements.

The LMP7731 has a supply voltage range of 1.8V to 5.5V, making it an ideal choice for battery operated portable applications.

The LMP7731 is offered in the space saving 5-Pin SOT-23 and 8-Pin SOIC packages.

Features

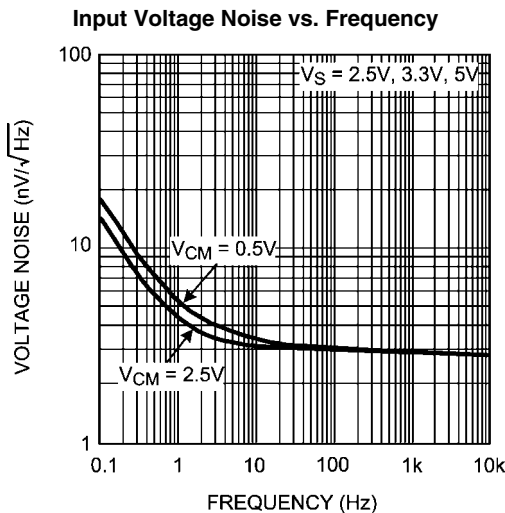
(Typical values, $T_A = 25^\circ\text{C}$, $V_S = 5\text{V}$)

■ Input voltage noise	
— $f = 3\text{ Hz}$	3.3 nV/√Hz
— $f = 1\text{ kHz}$	2.9 nV/√Hz
■ CMRR	130 dB
■ Open loop gain	130 dB
■ GBW	22 MHz
■ Slew rate	2.4 V/μs
■ THD @ $f = 10\text{ kHz}$, $A_V = +1$, $R_L = 2\text{ k}\Omega$	0.001%
■ Supply current per channel	2.2 mA
■ Supply voltage range	1.8V to 5.5V
■ Operating temperature range	-40°C to 125°C
■ Input bias current	±1.5 nA
■ RRIO	

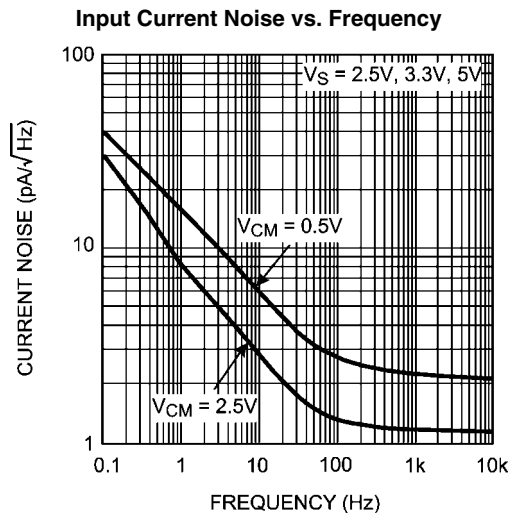
Applications

- Gas analysis instruments
- Photometric instrumentation
- Medical instrumentation

Typical Performance Characteristics



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Absolute Maximum Ratings (Note 1)

If Military/Aerospace specified devices are required, please contact the National Semiconductor Sales Office/ Distributors for availability and specifications.

ESD Tolerance (Note 2)

Human Body Model	
Inputs pins only	2000V
All other pins	2000V
Machine Model	200V
Charge Device Model	1000V
V_{IN} Differential	$\pm 2V$
Supply Voltage ($V_S = V^+ - V^-$)	6.0V

Storage Temperature Range	-65°C to 150°C
Junction Temperature (Note 3)	+150°C max
Soldering Information	
Infrared or Convection (20 sec)	235°C
Wave Soldering Lead Temp. (10 sec)	260°C

Operating Ratings (Note 1)

Temperature Range	-40°C to 125°C
Supply Voltage ($V_S = V^+ - V^-$)	1.8V to 5.5V
Package Thermal Resistance (θ_{JA})	
5-Pin SOT-23	265°C/W
8-Pin SOIC	190°C/W

2.5V Electrical Characteristics (Note 4)

Unless otherwise specified, all limits are guaranteed for $T_A = 25^\circ\text{C}$, $V^+ = 2.5\text{V}$, $V^- = 0\text{V}$, $V_{CM} = V^+/2$, $R_L > 10\text{ k}\Omega$ to $V^+/2$. **Bold-face** limits apply at the temperature extremes.

Symbol	Parameter	Conditions	Min (Note 6)	Typ (Note 5)	Max (Note 6)	Units
V_{OS}	Input Offset Voltage (Note 7)	$V_{CM} = 2.0\text{V}$		± 9	± 500 ± 600	μV
		$V_{CM} = 0.5\text{V}$		± 9	± 500 ± 600	
TCV_{OS}	Input Offset Voltage Temperature Drift	$V_{CM} = 2.0\text{V}$		± 0.5	± 5.5	$\mu\text{V}/^\circ\text{C}$
		$V_{CM} = 0.5\text{V}$		± 0.2	± 5.5	
I_B	Input Bias Current	$V_{CM} = 2.0\text{V}$		± 1	± 30 ± 45	nA
		$V_{CM} = 0.5\text{V}$		± 12	± 50 ± 75	
I_{OS}	Input Offset Current	$V_{CM} = 2.0\text{V}$		± 1	± 50 ± 75	nA
		$V_{CM} = 0.5\text{V}$		± 11	± 60 ± 80	
TCI_{OS}	Input Offset Current Drift	$V_{CM} = 0.5\text{V}$ and $V_{CM} = 2.0\text{V}$		0.0474		$\text{nA}/^\circ\text{C}$
CMRR	Common Mode Rejection Ratio	$0.15\text{V} \leq V_{CM} \leq 0.7\text{V}$	101	120		dB
		$0.23\text{V} \leq V_{CM} \leq 0.7\text{V}$	89			
		$1.5\text{V} \leq V_{CM} \leq 2.35\text{V}$	105	129		
		$1.5\text{V} \leq V_{CM} \leq 2.27\text{V}$	99			
PSRR	Power Supply Rejection Ratio	$2.5\text{V} \leq V^+ \leq 5\text{V}$	111 105	129		dB
		$1.8\text{V} \leq V^+ \leq 5.5\text{V}$		117		
CMVR	Common Mode Voltage Range	Large Signal CMRR $\geq 80\text{ dB}$	0		2.5	V
A_{VOL}	Open Loop Voltage Gain	$R_L = 10\text{ k}\Omega$ to $V^+/2$ $V_{OUT} = 0.5\text{V}$ to 2.0V	112 104	130		dB
		$R_L = 2\text{ k}\Omega$ to $V^+/2$ $V_{OUT} = 0.5\text{V}$ to 2.0V	109 90	119		

Symbol	Parameter	Conditions	Min (Note 6)	Typ (Note 5)	Max (Note 6)	Units
V_{OUT}	Output Voltage Swing High	$R_L = 10\text{ k}\Omega$ to $V^+/2$		4	50 75	mV from either rail
		$R_L = 2\text{ k}\Omega$ to $V^+/2$		13	50 75	
	Output Voltage Swing Low	$R_L = 10\text{ k}\Omega$ to $V^+/2$		6	50 75	
		$R_L = 2\text{ k}\Omega$ to $V^+/2$		9	50 75	
I_{OUT}	Output Current	Sourcing, $V_{OUT} = V^+/2$ $V_{IN}(\text{diff}) = 100\text{ mV}$	22 12	31		mA
		Sinking, $V_{OUT} = V^+/2$ $V_{IN}(\text{diff}) = -100\text{ mV}$	15 10	44		
I_S	Supply Current (Per Channel)	$V_{CM} = 2.0\text{V}$		2.0	2.7 3.4	mA
		$V_{CM} = 0.5\text{V}$		2.3	3.1 3.9	
SR	Slew Rate	$A_V = +1$, $C_L = 10\text{ pF}$, $R_L = 10\text{ k}\Omega$ to $V^+/2$, $V_O = 2 V_{PP}$		2.4		V/ μs
GBW	Gain Bandwidth	$C_L = 20\text{ pF}$, $R_L = 10\text{ k}\Omega$ to $V^+/2$		21		MHz
G_M	Gain Margin	$C_L = 20\text{ pF}$, $R_L = 10\text{ k}\Omega$ to $V^+/2$		14		dB
Φ_M	Phase Margin	$C_L = 20\text{ pF}$, $R_L = 10\text{ k}\Omega$ to $V^+/2$		60		deg
R_{IN}	Input Resistance	Differential Mode		38		k Ω
		Common Mode		151		M Ω
THD+N	Total Harmonic Distortion + Noise	$A_V = 1$, $f = 1\text{ kHz}$, Amplitude = 1V		0.002		%
e_n	Input Referred Voltage Noise Density	$f = 1\text{ kHz}$, $V_{CM} = 2.0\text{V}$		3		nV/ $\sqrt{\text{Hz}}$
		$f = 1\text{ kHz}$, $V_{CM} = 0.5\text{V}$		3		
	Input Voltage Noise	0.1 Hz to 10 Hz		75		nV _{PP}
i_n	Input Referred Current Noise Density	$f = 1\text{ kHz}$, $V_{CM} = 2.0\text{V}$		1.1		pA/ $\sqrt{\text{Hz}}$
		$f = 1\text{ kHz}$, $V_{CM} = 0.5\text{V}$		2.3		

3.3V Electrical Characteristics (Note 4)

Unless otherwise specified, all limits are guaranteed for $T_A = 25^\circ\text{C}$, $V^+ = 3.3\text{V}$, $V^- = 0\text{V}$, $V_{CM} = V^+/2$, $R_L > 10\text{ k}\Omega$ to $V^+/2$. **Bold-face** limits apply at the temperature extremes.

Symbol	Parameter	Conditions	Min (Note 6)	Typ (Note 5)	Max (Note 6)	Units
V_{OS}	Input Offset Voltage (Note 7)	$V_{CM} = 2.5\text{V}$		± 6	± 500 ± 600	μV
		$V_{CM} = 0.5\text{V}$		± 6	± 500 ± 600	
TCV_{OS}	Input Offset Voltage Temperature Drift	$V_{CM} = 2.5\text{V}$		± 0.5	± 5.5	$\mu\text{V}/^\circ\text{C}$
		$V_{CM} = 0.5\text{V}$		± 0.2	± 5.5	
I_B	Input Bias Current	$V_{CM} = 2.5\text{V}$		± 1.5	± 30 ± 45	nA
		$V_{CM} = 0.5\text{V}$		± 13	± 50 ± 77	
I_{OS}	Input Offset Current	$V_{CM} = 2.5\text{V}$		± 1	± 50 ± 70	nA
		$V_{CM} = 0.5\text{V}$		± 11	± 60 ± 80	

Symbol	Parameter	Conditions	Min (Note 6)	Typ (Note 5)	Max (Note 6)	Units
$TC_{I_{OS}}$	Input Offset Current Drift	$V_{CM} = 0.5V$ and $V_{CM} = 2.5V$		0.048		nA/°C
CMRR	Common Mode Rejection Ratio	$0.15V \leq V_{CM} \leq 0.7V$	101	120		dB
		$0.23V \leq V_{CM} \leq 0.7V$	89			
		$1.5V \leq V_{CM} \leq 3.15V$	105	130		
		$1.5V \leq V_{CM} \leq 3.07V$	99			
PSRR	Power Supply Rejection Ratio	$2.5V \leq V^+ \leq 5.0V$	111	129		dB
		$1.8V \leq V^+ \leq 5.5V$	105	117		
CMVR	Common Mode Voltage Range	Large Signal CMRR ≥ 80 dB	0		3.3	V
A_{VOL}	Open Loop Voltage Gain	$R_L = 10\text{ k}\Omega$ to $V^+/2$	112	130		dB
		$V_{OUT} = 0.5V$ to $2.8V$	104			
		$R_L = 2\text{ k}\Omega$ to $V^+/2$	110	119		
V_{OUT}	Output Voltage Swing High	$R_L = 10\text{ k}\Omega$ to $V^+/2$		5	50	mV from either rail
		$R_L = 2\text{ k}\Omega$ to $V^+/2$		14	75	
	Output Voltage Swing Low	$R_L = 10\text{ k}\Omega$ to $V^+/2$		9	50	
		$R_L = 2\text{ k}\Omega$ to $V^+/2$		13	75	
I_{OUT}	Output Current	Sourcing, $V_{OUT} = V^+/2$	28	45		mA
		$V_{IN}(\text{diff}) = 100\text{ mV}$	22			
		Sinking, $V_{OUT} = V^+/2$	25	48		
I_S	Supply Current (Per Channel)	$V_{CM} = 2.5V$		2.1	2.8	mA
		$V_{CM} = 0.5V$		2.4	3.2	
				4.0		
SR	Slew Rate	$A_V = +1$, $C_L = 10\text{ pF}$, $R_L = 10\text{ k}\Omega$ to $V^+/2$, $V_{OUT} = 2 V_{PP}$		2.4		V/ μ s
GBW	Gain Bandwidth	$C_L = 20\text{ pF}$, $R_L = 10\text{ k}\Omega$ to $V^+/2$		22		MHz
G_M	Gain Margin	$C_L = 20\text{ pF}$, $R_L = 10\text{ k}\Omega$ to $V^+/2$		14		dB
Φ_M	Phase Margin	$C_L = 20\text{ pF}$, $R_L = 10\text{ k}\Omega$ to $V^+/2$		62		deg
R_{IN}	Input Resistance	Differential Mode		38		k Ω
		Common Mode		151		M Ω
THD+N	Total Harmonic Distortion + Noise	$A_V = 1$, $f = 1\text{ kHz}$, Amplitude = 1V,		0.002		%
e_n	Input Referred Voltage Noise Density	$f = 1\text{ kHz}$, $V_{CM} = 2.5V$		2.9		nV/ $\sqrt{\text{Hz}}$
		$f = 1\text{ kHz}$, $V_{CM} = 0.5V$		2.9		
	Input Voltage Noise	0.1 Hz to 10 Hz		65		nV $_{PP}$
i_n	Input Referred Current Noise Density	$f = 1\text{ kHz}$, $V_{CM} = 2.5V$		1.1		pA/ $\sqrt{\text{Hz}}$
		$f = 1\text{ kHz}$, $V_{CM} = 0.5V$		2.1		

5V Electrical Characteristics (Note 4)

Unless otherwise specified, all limits are guaranteed for $T_A = 25^\circ\text{C}$, $V^+ = 5\text{V}$, $V^- = 0\text{V}$, $V_{CM} = V^+/2$, $R_L > 10\text{ k}\Omega$ to $V^+/2$. **Boldface** limits apply at the temperature extremes.

Symbol	Parameter	Conditions	Min (Note 6)	Typ (Note 5)	Max (Note 6)	Units
V_{OS}	Input Offset Voltage (Note 7)	$V_{CM} = 4.5\text{V}$		± 6	± 500 ± 600	μV
		$V_{CM} = 0.5\text{V}$		± 6	± 500 ± 600	
TCV_{OS}	Input Offset Voltage Temperature Drift	$V_{CM} = 4.5\text{V}$		± 0.5	± 5.5	$\mu\text{V}/^\circ\text{C}$
		$V_{CM} = 0.5\text{V}$		± 0.2	± 5.5	
I_B	Input Bias Current	$V_{CM} = 4.5\text{V}$		± 1.5	± 30 ± 50	nA
		$V_{CM} = 0.5\text{V}$		± 14	± 50 ± 85	
I_{OS}	Input Offset Current	$V_{CM} = 4.5\text{V}$		± 1	± 50 ± 70	nA
		$V_{CM} = 0.5\text{V}$		± 11	± 65 ± 80	
TCI_{OS}	Input Offset Current Drift	$V_{CM} = 0.5\text{V}$ and $V_{CM} = 4.5\text{V}$		0.0482		nA/ $^\circ\text{C}$
CMRR	Common Mode Rejection Ratio	$0.15\text{V} \leq V_{CM} \leq 0.7\text{V}$	101	120		dB
		$0.23\text{V} \leq V_{CM} \leq 0.7\text{V}$	89			
		$1.5\text{V} \leq V_{CM} \leq 4.85\text{V}$	105	130		
		$1.5\text{V} \leq V_{CM} \leq 4.77\text{V}$	99			
PSRR	Power Supply Rejection Ratio	$2.5\text{V} \leq V^+ \leq 5\text{V}$	111 105	129		dB
		$1.8\text{V} \leq V^+ \leq 5.5\text{V}$		117		
CMVR	Common Mode Voltage Range	Large Signal CMRR $\geq 80\text{ dB}$	0		5	V
A_{VOL}	Open Loop Voltage Gain	$R_L = 10\text{ k}\Omega$ to $V^+/2$	112	130		dB
		$V_{OUT} = 0.5\text{V}$ to 4.5V	104			
		$R_L = 2\text{ k}\Omega$ to $V^+/2$	110	119		
		$V_{OUT} = 0.5\text{V}$ to 4.5V	94			
V_{OUT}	Output Voltage Swing High	$R_L = 10\text{ k}\Omega$ to $V^+/2$		8	50 75	mV from either rail
		$R_L = 2\text{ k}\Omega$ to $V^+/2$		24	50 75	
	Output Voltage Swing Low	$R_L = 10\text{ k}\Omega$ to $V^+/2$		9	50 75	
		$R_L = 2\text{ k}\Omega$ to $V^+/2$		23	50 75	
I_{OUT}	Output Current	Sourcing, $V_{OUT} = V^+/2$	33	47		mA
		$V_{IN}(\text{diff}) = 100\text{ mV}$	27			
		Sinking, $V_{OUT} = V^+/2$	30	49		
		$V_{IN}(\text{diff}) = -100\text{ mV}$	25			
I_S	Supply Current (Per Channel)	$V_{CM} = 4.5\text{V}$		2.2	3.0 3.7	mA
		$V_{CM} = 0.5\text{V}$		2.5	3.4 4.2	
SR	Slew Rate	$A_V = +1$, $C_L = 10\text{ pF}$, $R_L = 10\text{ k}\Omega$ to $V^+/2$, $V_{OUT} = 2 V_{PP}$		2.4		V/ μs
GBW	Gain Bandwidth	$C_L = 20\text{ pF}$, $R_L = 10\text{ k}\Omega$ to $V^+/2$		22		MHz

Symbol	Parameter	Conditions	Min (Note 6)	Typ (Note 5)	Max (Note 6)	Units
G_M	Gain Margin	$C_L = 20 \text{ pF}$, $R_L = 10 \text{ k}\Omega$ to $V^+/2$		12		dB
Φ_M	Phase Margin	$C_L = 20 \text{ pF}$, $R_L = 10 \text{ k}\Omega$ to $V^+/2$		65		deg
R_{IN}	Input Resistance	Differential Mode		38		$\text{k}\Omega$
		Common Mode		151		$\text{M}\Omega$
THD+N	Total Harmonic Distortion + Noise	$A_V = 1$, $f = 1 \text{ kHz}$, Amplitude = 1V		0.001		%
e_n	Input Referred Voltage Noise Density	$f = 1 \text{ kHz}$, $V_{CM} = 4.5\text{V}$		2.9		$\text{nV}/\sqrt{\text{Hz}}$
		$f = 1 \text{ kHz}$, $V_{CM} = 0.5\text{V}$		2.9		
	Input Voltage Noise	0.1 Hz to 10 Hz		78		nV_{PP}
i_n	Input Referred Current Noise Density	$f = 1 \text{ kHz}$, $V_{CM} = 4.5\text{V}$		1.1		$\text{pA}/\sqrt{\text{Hz}}$
		$f = 1 \text{ kHz}$, $V_{CM} = 0.5\text{V}$		2.2		

Note 1: Absolute Maximum Ratings indicate limits beyond which damage to the device may occur. Operating Ratings indicate conditions for which the device is intended to be functional, but specific performance is not guaranteed. For guaranteed specifications and the test conditions, see the Electrical Characteristics Tables.

Note 2: Human Body Model, applicable std. MIL-STD-883, Method 3015.7. Machine Model, applicable std. JESD22-A115-A (ESD MM std. of JEDEC). Field-Induced Charge-Device Model, applicable std. JESD22-C101-C (ESD FICDM std. of JEDEC).

Note 3: The maximum power dissipation is a function of $T_{J(MAX)}$, θ_{JA} . The maximum allowable power dissipation at any ambient temperature is $P_D = (T_{J(MAX)} - T_A) / \theta_{JA}$. All numbers apply for packages soldered directly onto a PC Board.

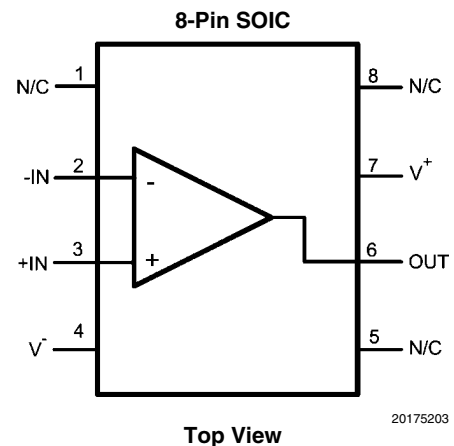
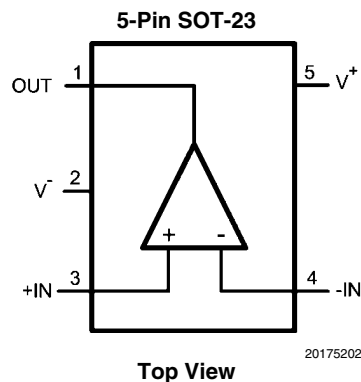
Note 4: Electrical Table values apply only for factory testing conditions at the temperature indicated. Factory testing conditions result in very limited self-heating of the device such that $T_J = T_A$. No guarantee of parametric performance is indicated in the electrical tables under conditions of internal self-heating where $T_J > T_A$. Absolute maximum Ratings indicate junction temperature limits beyond which the device maybe permanently degraded, either mechanically or electrically.

Note 5: Typical values represent the most likely parametric norm as determined at the time of characterization. Actual typical values may vary over time and will also depend on the application and configuration. The typical values are not tested and are not guaranteed on shipped production material.

Note 6: All limits are guaranteed by testing, statistical analysis or design.

Note 7: Ambient production test is performed at 25°C with a variance of $\pm 3^\circ\text{C}$.

Connection Diagrams

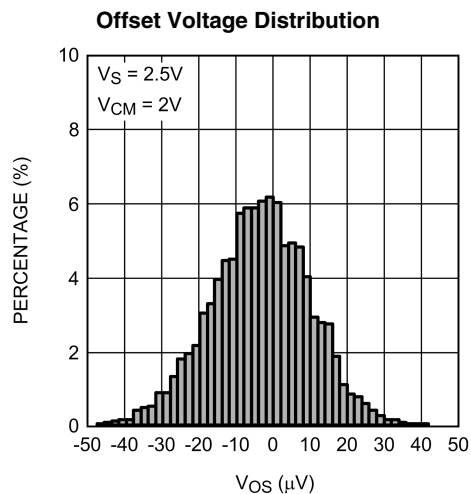


Ordering Information

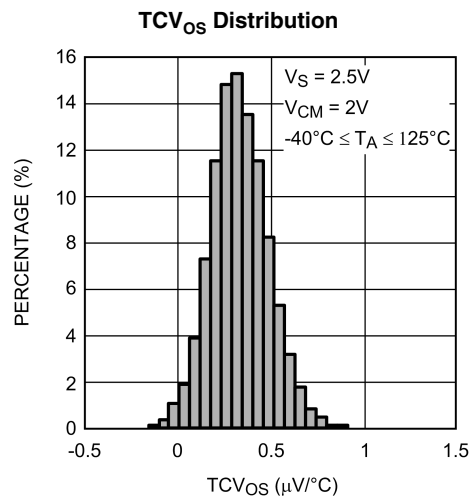
Package	Part Number	Package Marking	Transport Media	NSC Drawing
5-Pin SOT-23	LMP7731MF	AY3A	1k Units Tape and Reel	MF05A
	LMP7731MFE		250 Units Tape and Reel	
	LMP7731MFX		3k Units Tape and Reel	
8-Pin SOIC	LMP7731MA	LMP7731MA	95 Units/Rail	M08A
	LMP7731MAX		2.5k Tape and Reel	

Typical Performance Characteristics

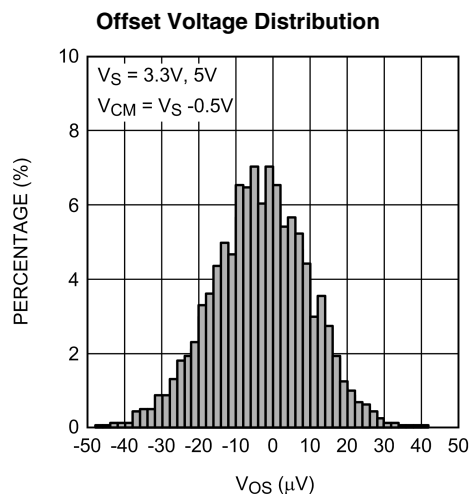
Unless otherwise noted: $T_A = 25^\circ\text{C}$, $R_L > 10\text{ k}\Omega$, $V_{CM} = V_S/2$.



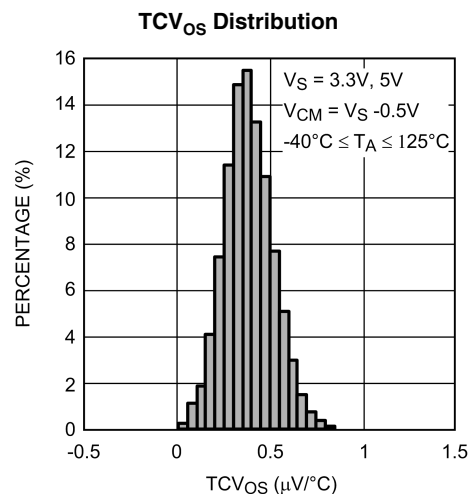
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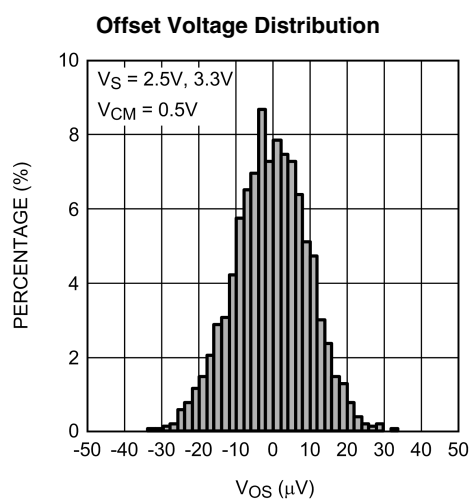
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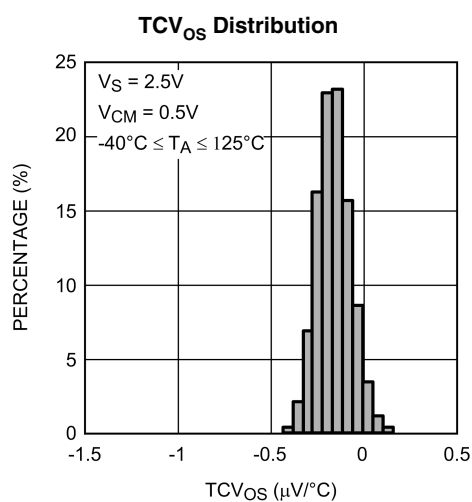
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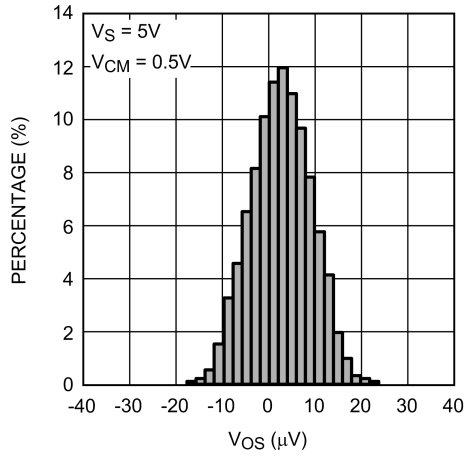


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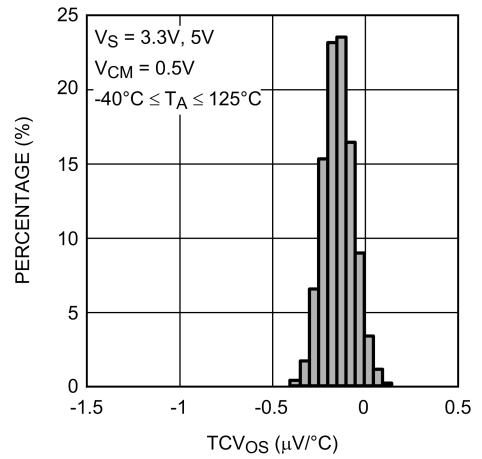


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Offset Voltage Distribution

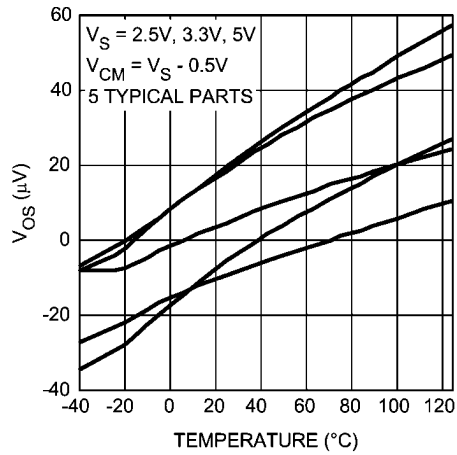


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TCV_{OS} Distribution

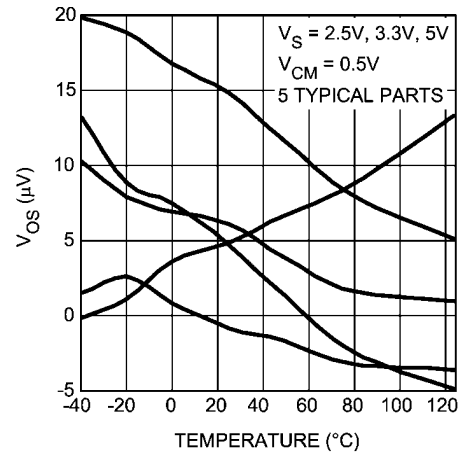
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Offset Voltage vs. Temperature



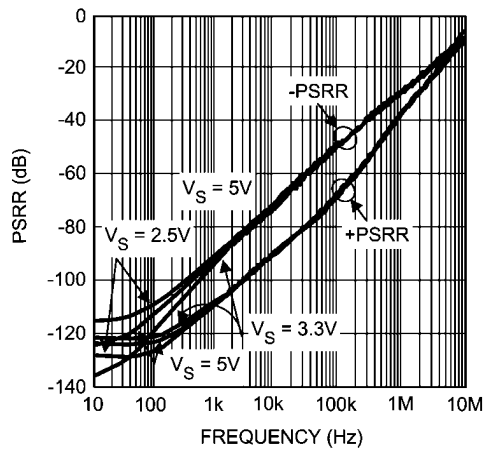
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Offset Voltage vs. Temperature



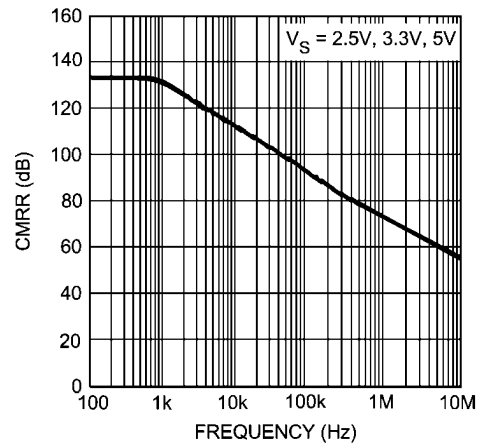
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PSRR vs. Frequency



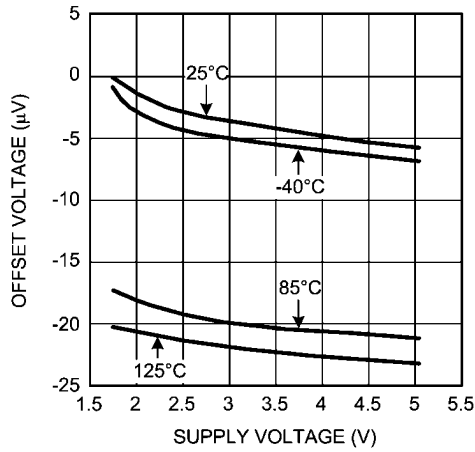
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CMRR vs. Frequency



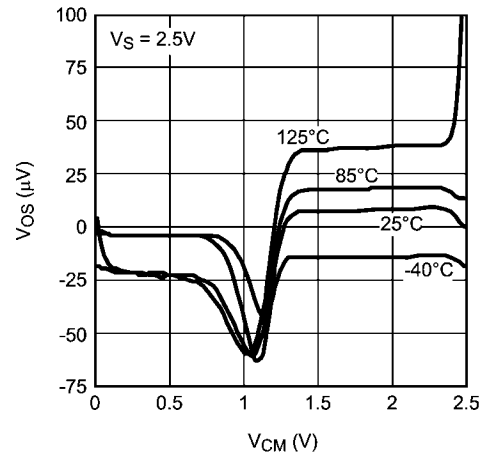
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Offset Voltage vs. Supply Voltage



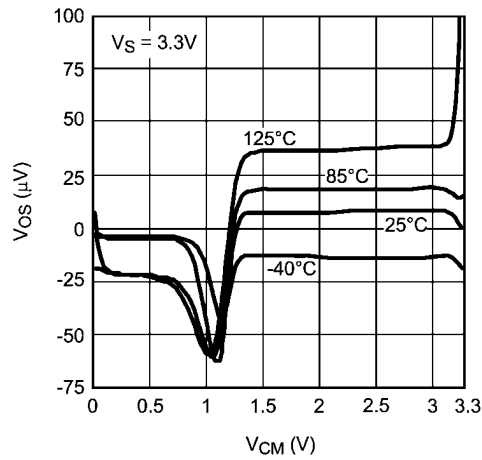
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Offset Voltage vs. V_{CM}



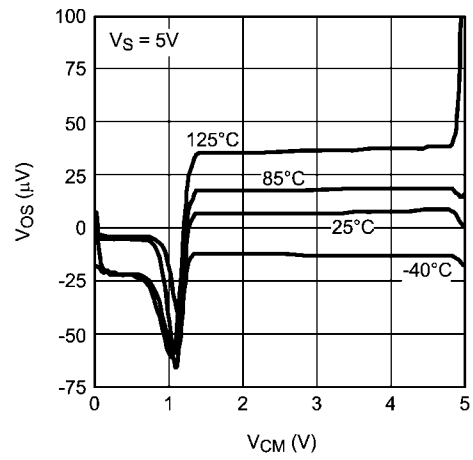
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Offset Voltage vs. V_{CM}



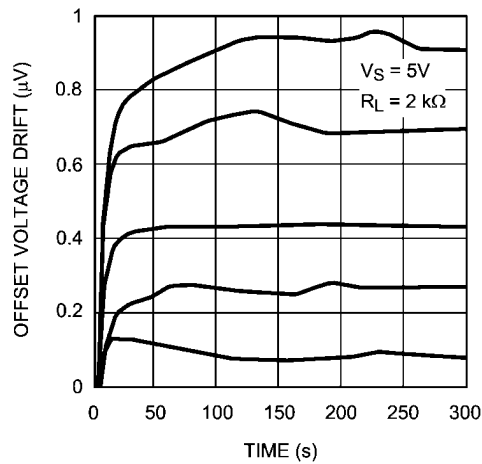
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Offset Voltage vs. V_{CM}



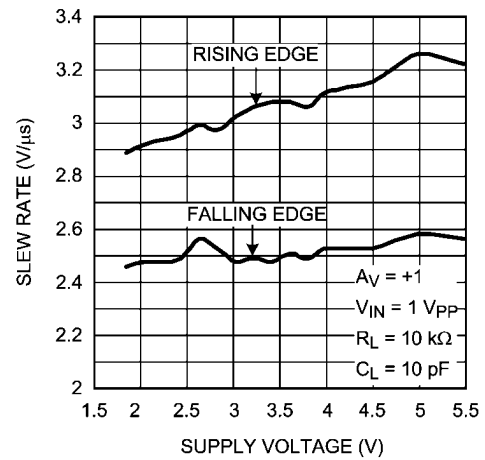
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Input Offset Voltage Time Drift



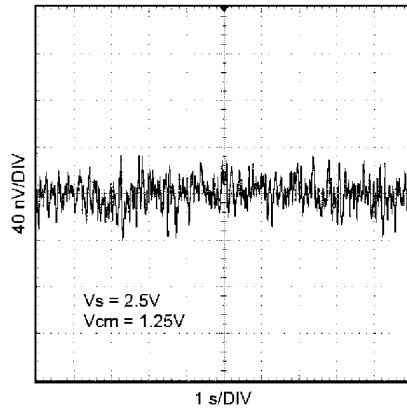
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Slew Rate vs. Supply Voltage



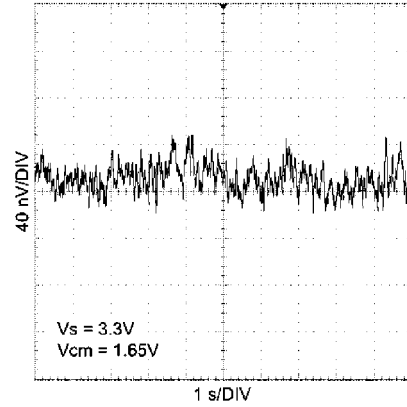
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Time Domain Voltage Noise



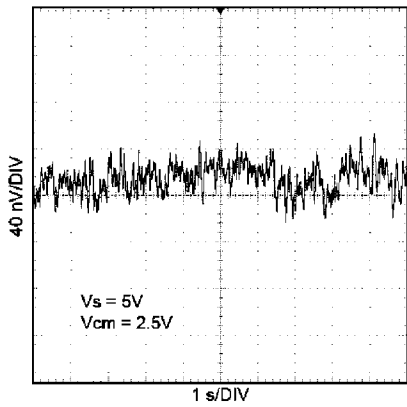
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Time Domain Voltage Noise



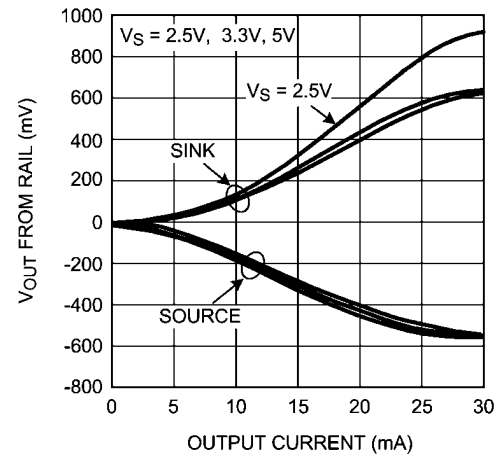
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Time Domain Voltage Noise

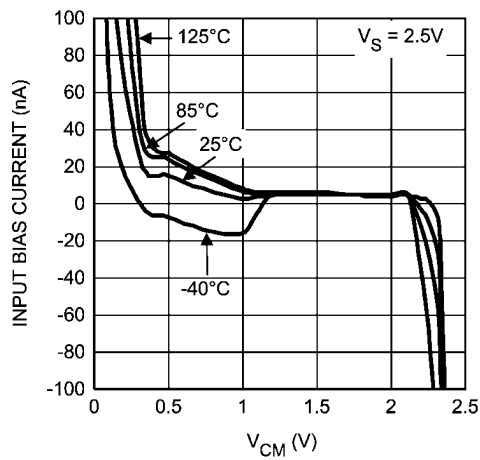


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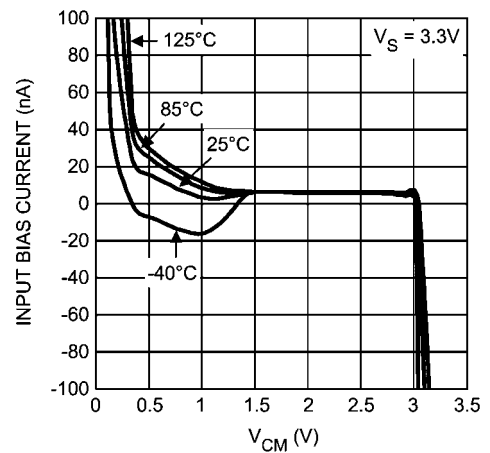
Output Voltage vs. Output Current



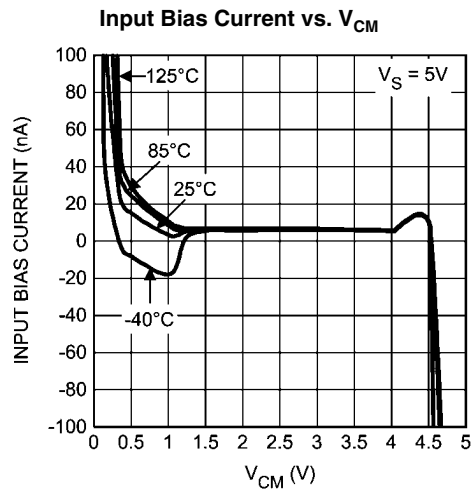
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Input Bias Current vs. V_{CM} 

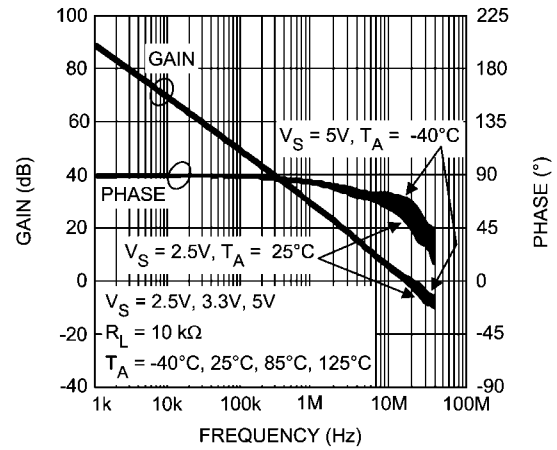
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Input Bias Current vs. V_{CM} 

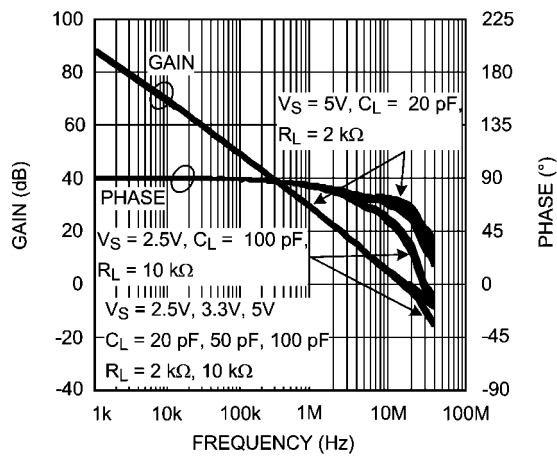
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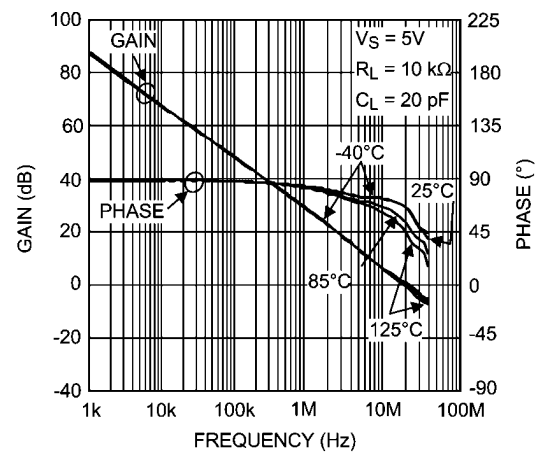
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Open Loop Frequency Response Over Temperature

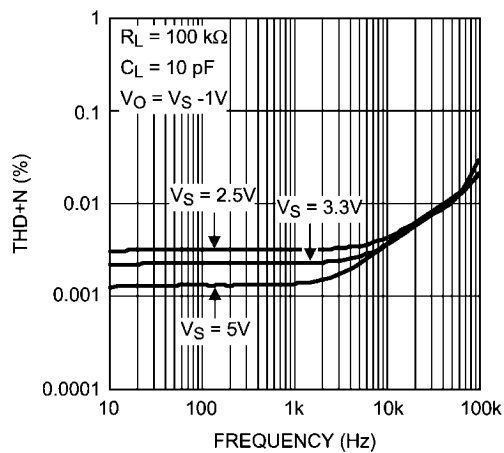
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Open Loop Frequency Response

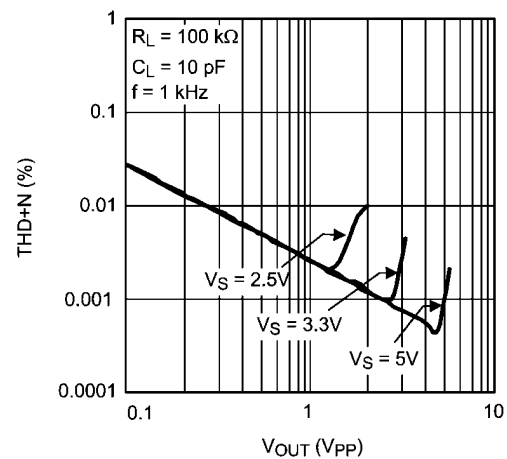
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Open Loop Frequency Response

20175228

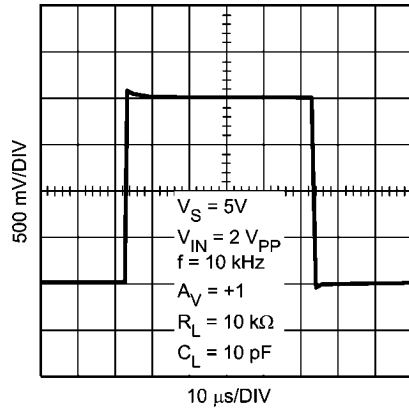
THD+N vs. Frequency

20175257

THD+N vs. Output Voltage

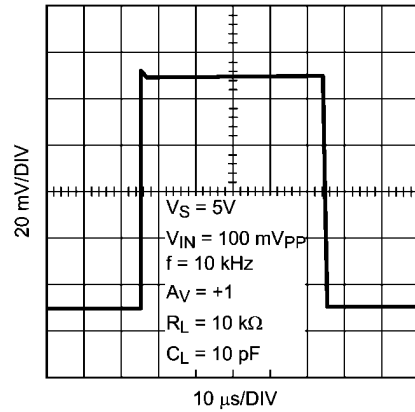
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Large Signal Step Response



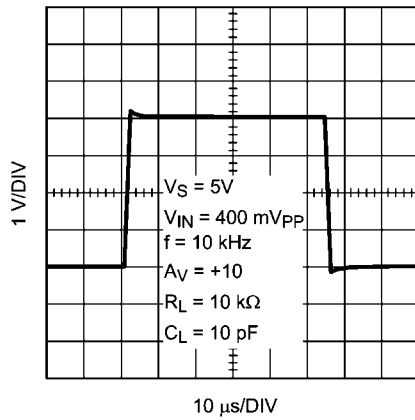
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Small Signal Step Response



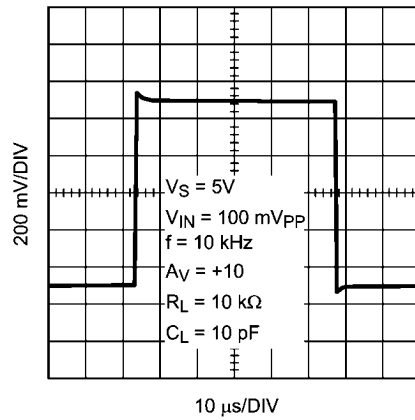
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Large Signal Step Response



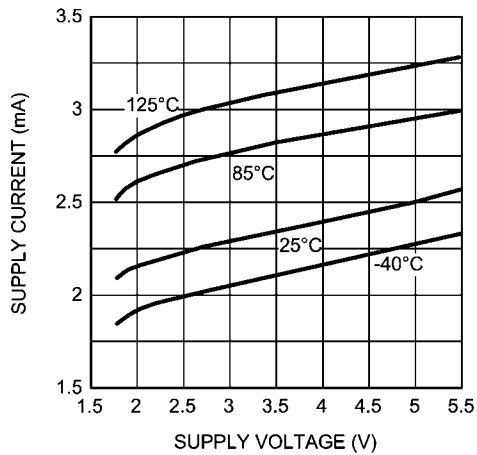
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Small Signal Step Response



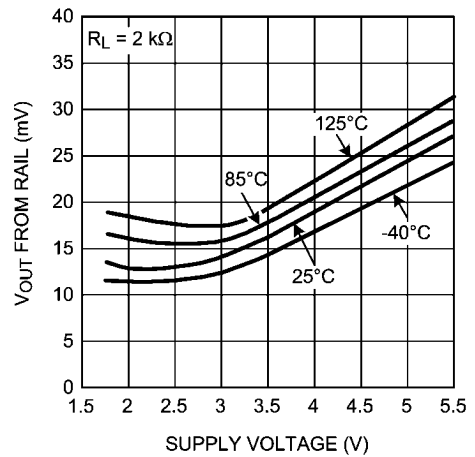
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Supply Current vs. Supply Voltage

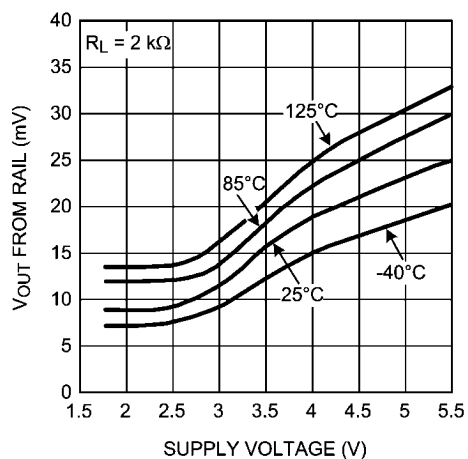


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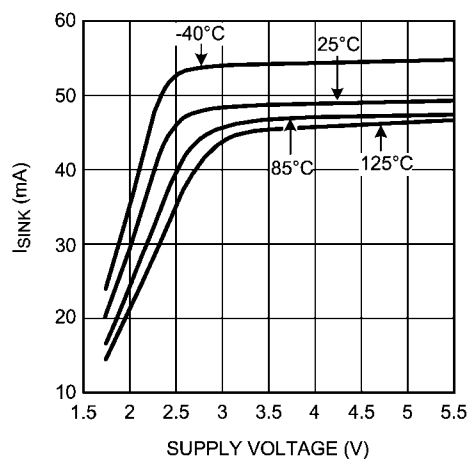
Output Swing High vs. Supply Voltage



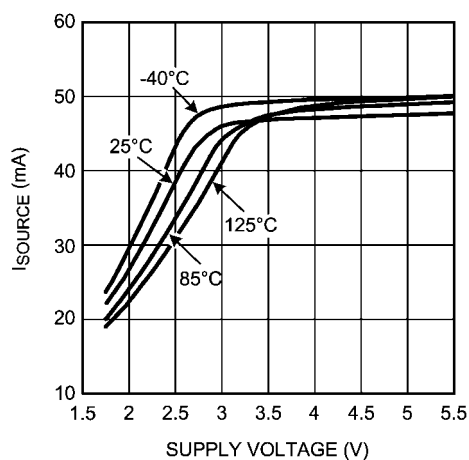
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Output Swing Low vs. Supply Voltage

20175249

Sinking Current vs. Supply Voltage

20175247

Sourcing Current vs. Supply Voltage

20175248

Application Information

LMP7731

The LMP7731 is a single, low noise, rail-to-rail input and output, and low voltage amplifier.

The low input voltage noise of only 2.9 nV/ $\sqrt{\text{Hz}}$ with a 1/f corner at 3 Hz makes the LMP7731 ideal for sensor applications where DC accuracy is of importance.

The LMP7731 has a high gain bandwidth of 22 MHz. This wide bandwidth enables use of the amplifier at higher gain settings while retaining usable bandwidth for the application. This is particularly beneficial when system designers need to use sensors with very limited output voltage range as it allows larger gains in one stage which in turn increases the signal to noise ratio.

The LMP7731 has proprietary input bias cancellation circuitry on the input stages. This allows the LMP7731 to have only about 1.5 nA bias current with a bipolar input stage. This low input bias current, paired with the inherent lower input voltage noise of bipolar input stages makes the LMP7731 an excellent choice for precision applications. The combination of low input bias current, and low input voltage noise enables the user to achieve unprecedented accuracy and higher signal integrity.

National Semiconductor is heavily committed to precision amplifiers and the market segment they serve. Technical support and extensive characterization data are available for sensitive applications or applications with a constrained error budget.

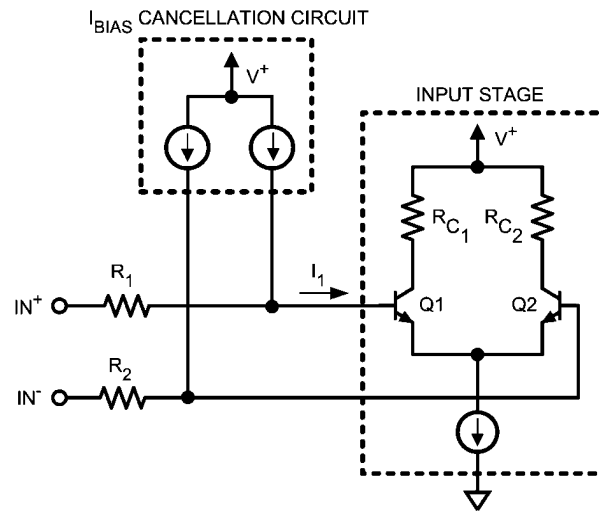
The LMP7731 is offered in the space saving 5-Pin SOT-23 and 8-Pin SOIC packages. These small packages are ideal solutions for area constrained PC boards and portable electronics.

INPUT BIAS CURRENT CANCELLATION

The LMP7731 has proprietary input bias current cancellation circuitry on their input stages.

The LMP7731 has rail-to-rail input. This is achieved by having two input stages in parallel. *Figure 1* shows only one of the input stages as the circuitry is symmetrical for both stages.

Figure 1 shows that as the common mode voltage gets closer to one of the extreme ends, current I_1 significantly increases. This increased current shows as an increase in voltage drop across resistor R_1 equal to $I_1 \cdot R_1$ on IN^+ of the amplifier. This voltage contributes to the offset voltage of the amplifier. When common mode voltage is in the mid-range, the transistors are operating in the linear region and I_1 is significantly small. The voltage drop due to I_1 across R_1 can be ignored as it is orders of magnitude smaller than the amplifier's input offset voltage. As the common mode voltage gets closer to one of the rails, the offset voltage generated due to I_1 increases and becomes comparable to the amplifiers offset voltage.

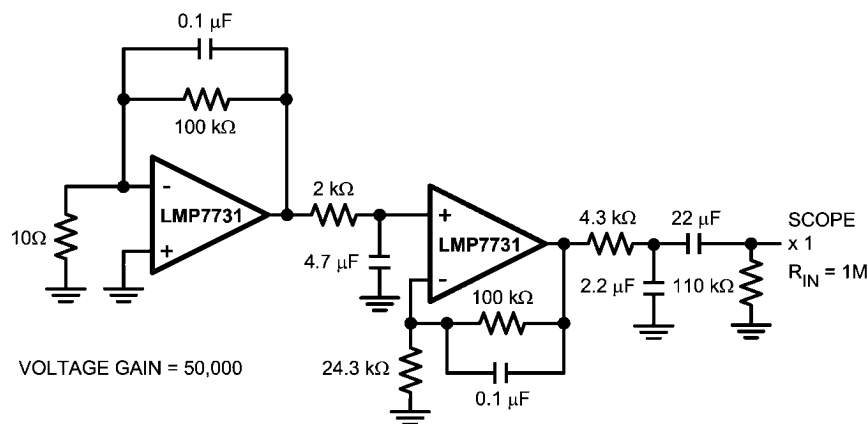


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FIGURE 1. Input Bias Current Cancellation

INPUT VOLTAGE NOISE MEASUREMENT

The LMP7731 has very low input voltage noise. The peak-to-peak input voltage noise of the LMP7731 can be measured using the test circuit shown in *Figure 2*



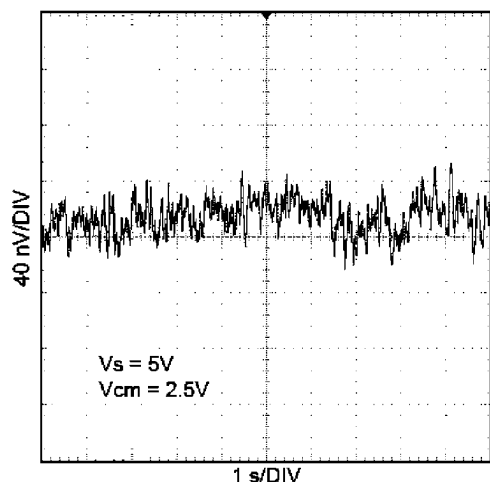
20175255

FIGURE 2. 0.1 Hz to 10 Hz Noise Test Circuit

The frequency response of this noise test circuit at the 0.1 Hz corner is defined by only one zero. The test time for the 0.1 Hz to 10 Hz noise measurement using this configuration should not exceed 10 seconds, as this time limit acts as an

additional zero to reduce or eliminate the noise contributions of noise from frequencies below 0.1 Hz.

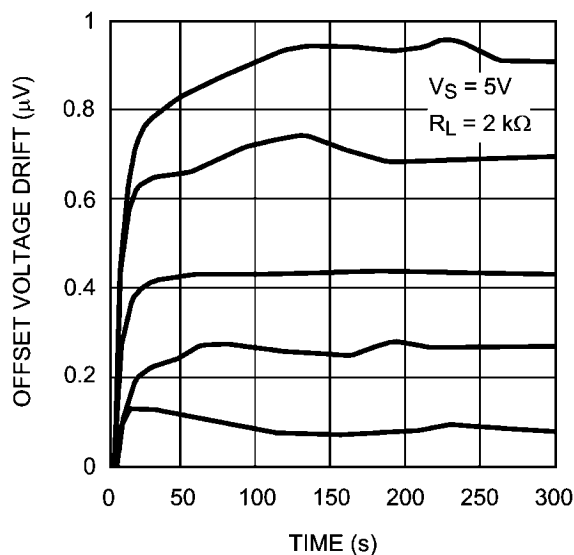
Figure 3 shows typical peak-to-peak noise for the LMP7731 measured with the circuit in *Figure 2* for the LMP7731.



20175268

FIGURE 3. 0.1 Hz to 10 Hz Input Voltage Noise

Measuring the very low peak-to-peak noise performance of the LMP7731, requires special testing attention. In order to achieve accurate results, the device should be warmed up for at least five minutes. This is so that the input offset voltage of the op amp settles to a value. During this warm up period, the offset can typically change by a few μV because the chip temperature increases by about 30°C . If the 10 seconds of the measurement is selected to include this warm up time, some of this temperature change might show up as the measured noise. Figure 4 shows the start-up drift of five typical LMP7731 units.



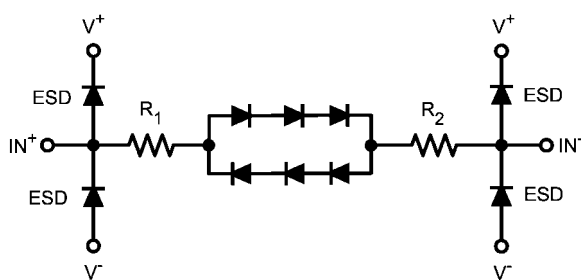
20175230

FIGURE 4. Start-Up Input Offset Voltage Drift

During the peak-to-peak noise measurement, the LMP7731 must be shielded. This prevents offset variations due to air-flow. Offset can vary by a few nV due to this airflow and that can invalidate measurements of input voltage noise with a magnitude which is in the same range. For similar reasons, sudden motions must also be restricted in the vicinity of the test area. The feed-through which results from this motion could increase the observed noise value which in turn would invalidate the measurement.

DIODES BETWEEN THE INPUTS

The LMP7731 has a set of anti-parallel diodes between the input pins as shown in Figure 5. These diodes are present to protect the input stage of the amplifier. At the same time, they limit the amount of differential input voltage that is allowed on the input pins. A differential signal larger than the voltage needed to turn on the diodes might cause damage to the diodes. The differential voltage between the input pins should be limited to ± 3 diode drops or the input current needs to be limited to ± 20 mA.



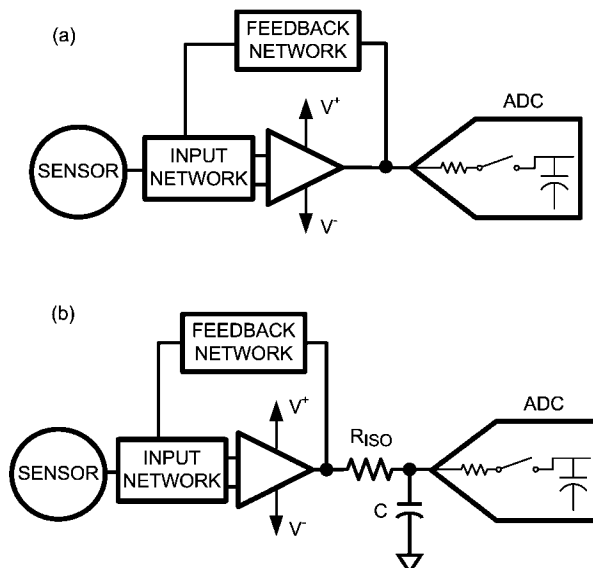
20175204

FIGURE 5. Anti-Parallel Diodes between Inputs

DRIVING AN ADC

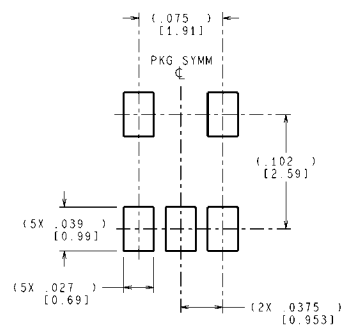
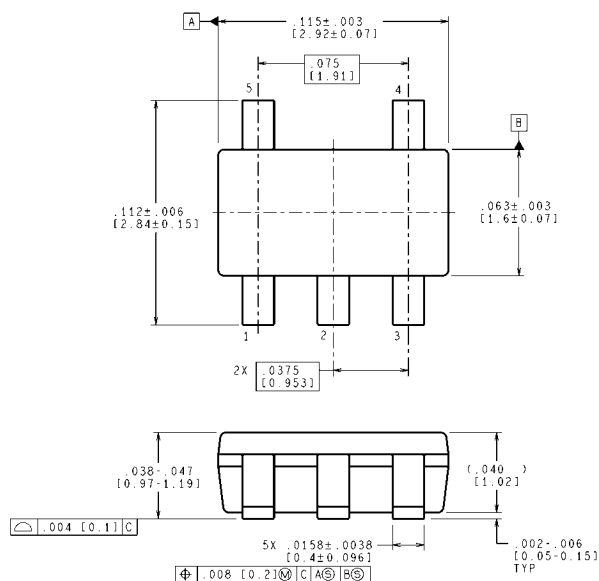
Analog to Digital Converters, ADCs, usually have a sampling capacitor on their input. When the ADC's input is directly connected to the output of the amplifier a charging current flows from the amplifier to the ADC. This charging current causes a momentary glitch that can take some time to settle. There are different ways to minimize this effect. One way is to slow down the sampling rate. This method gives the amplifier sufficient time to stabilize its output. Another way to minimize the glitch caused by the switch capacitor is to have an external capacitor connected to the input of the ADC. This capacitor is chosen so that its value is much larger than the internal switching capacitor and it will hence provide the voltage needed to quickly and smoothly charge the ADC's sampling capacitor. Since this large capacitor will be loading the output of the amplifier as well, an isolation resistor is needed between the output of the amplifier and this capacitor. The isolation resistor, R_{ISO} , separates the additional load capacitance from the output of the amplifier and will also form a low-pass filter and can be designed to provide noise reduction as well as anti-aliasing. The drawback to having R_{ISO} is that it reduces signal swing since there is some voltage drop across it.

Figure 6 (a) shows the ADC directly connected to the amplifier. To minimize the glitch in this setting, a slower sample rate needs to be used. Figure 6 (b) shows R_{ISO} and an external capacitor used to minimize the glitch.

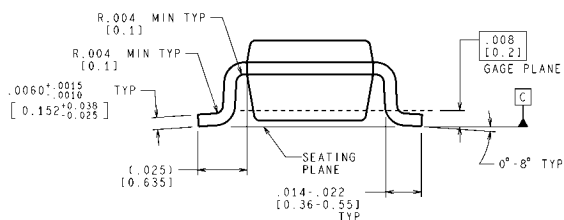


20175205

FIGURE 6. Driving an ADC

Physical Dimensions inches (millimeters) unless otherwise noted

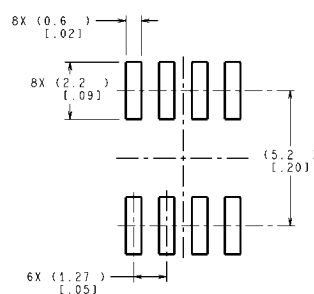
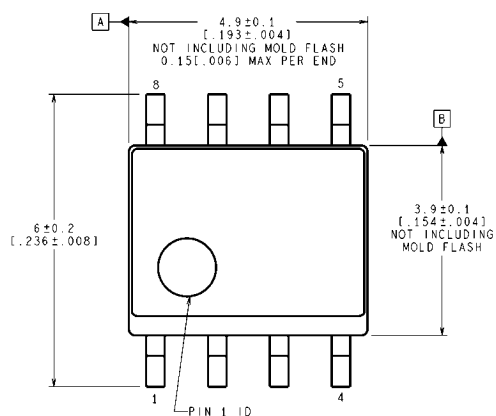
LAND PATTERN RECOMMENDATION



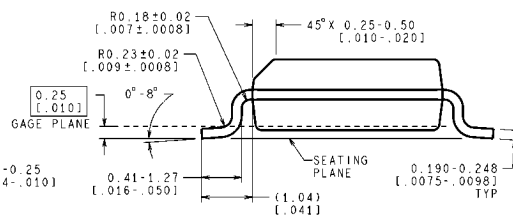
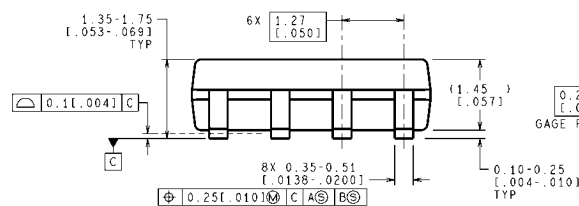
CONTROLLING DIMENSION IS INCH
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MF05A (Rev D)

5-Pin SOT-23
NS Package Number MF05A



RECOMMENDED LAND PATTERN



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M08A (Rev L)

8-Pin SOIC
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