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SIEMENS

T-75-11-21

# Memory Time Switch Small (MTSS)

PEB 2046 PEF 2046

#### **Preliminary Data**

CMOS IC

Туре	Ordering Code	Package
PEB 2046 C	Q67100-H6103	C-DIP-40
PEB 2046 N	Q67100-H6104	PL-CC-44 (SMD)
PEB 2046 P PEF 2046 C	Q67100-H6105	P-DIP-40
PEF 2046 N	Q67100-H6106 Q67100-H6107	C-DIP-40
PEF 2046 P	Q67100-H6108	P-DIP-40

The Siemens memory time switch PEx 2046 is a monolithic CMOS circuit connecting any of 256 incoming PCM channels to any of 256 outgoing PCM channels. The on-chip connection memory is accessed via the 8 bit  $\mu P$  interface.

The PEx 2046 is fabricated using the advanced CMOS technology from Siemens and is mounted in a C-DIP-40, P-DIP-40 or a PL-CC-44 package. Inputs and outputs are TTL-compatible.

The PEB 2046 works with either a 8192 kHz clock or a 4096 kHz clock. Henceforth, the respective clock periods are referred to as  $t_{\rm CP8}$  and  $t_{\rm CP4}$ .

The bits of a time slot are numbered 0 through 7. Bit 0 of a time slot is the first bit to be received or transmitted by the MTSC, bit 7 the last.

The components PEB 2046 and PEF 2046 are functionally identical. The difference between the two types lies in the temperature range. The PEB 2046 operates in the temperature range 0 to  $70\,^{\circ}$ C, the PEF 2046 in the range -40 to  $+85\,^{\circ}$ C.

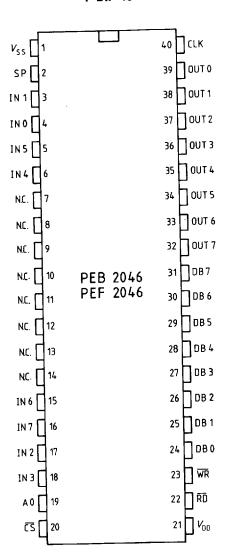
#### **Features**

- Time/space switch for 2048 kbit/s PCM systems
- Switching of up to 256 incoming PCM channels to up to 256 outgoing PCM channels
- 8 input and 8 output PCM lines
- Configurable for a 4096 and 8192 kHz device clock
- Tristate function for further expansion and tandem operation
- 8 bit μP interface
- Single +5 V power supply
- Advanced low power CMOS technology

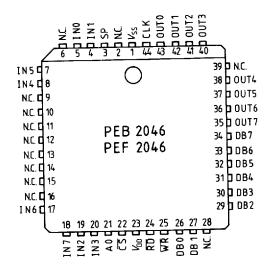
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Pin Configuration (top view)

**P-DIP-40** 



PL-CC-44



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# Pin Definitions and Functions

P-DIP Pin No.	PL-CC Pin No.	Symbol	Input (I) Output (O)	Function
1	1	V <sub>ss</sub>	1	Ground (OV)
2	3	SP	ı	Synchronization Pulse: The PEx 2046 is synchronized relative to the PCM system via this line.
3 4 5 6 15 16 17	4 5 7 8 17 18 19 20	IN1 IN0 IN5 IN4 IN6 IN7 IN2 IN3	 	PCM Input Ports: Serial data is received at these lines at standard TTL levels.
19	21	AO	I	Address 0: When high, the indirect register access mechanism is enabled. If A0 is logical 0 the mode and status registers can be written to and read respectively.
20	22	CS	1	Chip Select: A low level selects the PEx 2046 for a register access operation.
21	23	$V_{\scriptscriptstyle  m DD}$	ļ	Supply Voltage: 5 V ± 5%.
22	24	RD		<b>Read:</b> This signal indicates a read operation and is internally sampled only if $\overline{CS}$ is active. The MTSC puts data from the selected internal register on the data bus with the falling edge of $\overline{RD}$ . $\overline{RD}$ is active low.
23	25	WR		Write: This signal initiates a write operation. The WR input is internally sampled only if CS is active. In this case the MTSC loads an internal register with data from the data bus at the rising edge of WR. WR is active low.
24 25 26 27 28 29 30 31	26 27 29 30 31 32 33 34	DB0 DB1 DB2 DB3 DB4 DB5 DB6 DB7	1/O 1/O 1/O 1/O 1/O 1/O 1/O 1/O	<b>Data Bus:</b> The data bus is used for communication between the MTSC and a processor.

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# Pin Definitions and Functions (cont'd)

P-DIP Pin No.	PL-CC Pin No.	Symbol	Input (I) Output (O)	Function
32 33 34 35 36 37 38 39	35 36 37 38 40 41 42 43	OUT7 OUT6 OUT5 OUT4 OUT3 OUT2 OUT1	0 0 0 0 0 0	PCM Output Port: Serial data is sent by these lines at standard CMOS or TTL levels. These pins can be tristated.
40	44	CLK	1	Clock: 4096 or 8192 kHz device clock

#### **Functional Description**

The PEx 2046 is a memory time switch device. It can connect any of 256 PCM input channels to any of 256 output channels.

The input information of a complete frame is stored in the on-chip 2 kbit speech memory SM. (see figure 1). The incoming 256 channels of 8 bits each are written in sequence into fixed positions in the SM. This is controlled by the input counter in the timing control block with a 8 kHz repetition rate.

For outputting, the connection memory (CM) is read in sequence. Each location in CM points to a location in the speech memory. The byte in this speech memory location is read into the current output time slot. The read access of the CM is controlled by the output counter which also resides in the timing control block.

Hence the CM needs to be programmed beforehand for the desired connection. The CM address corresponds to one particular output time slot and line number. The contents of this CM address points to a particular input time slot and line number (now resident in the SM).

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Figure 1
Block Diagram of the PEx 2046

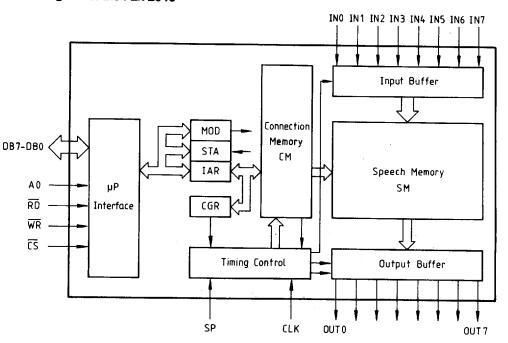
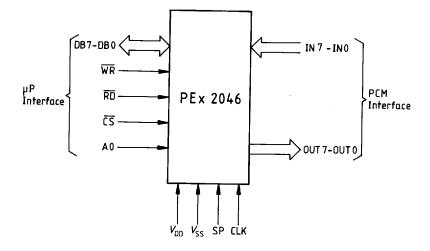


Figure 2
Functional Symbol for the Standard Configuration



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# **Operational Description**

#### **Power Up**

Upon power up the PEx 2046 is set to its initial state. The mode and configuration register bits are all set to logical 1. The status register **B**-bit is undefined, the **Z**-bit contains logical 0, the **R**-bit is undefined.

This state is also reached by pulling the  $\overline{\text{WR}}$  and  $\overline{\text{RD}}$  signals to logical 0 at the same time, (software reset). For the software the state of  $\overline{\text{CS}}$  is of no significance.

## **Initialization Procedure**

After power up a few internal signal and clocks need to be initialized. This is done with the initialization sequence. To give all signals and clocks a defined value the MTSC must encounter three falling and two rising edges of the SP signal. The resulting SP pulses may be of any length allowed in normal operation, the time interval between the two SP pulses may be of any length down to 250 nsec.

With all signals being defined, the CM needs to be reset. To do that a logical 0 is written into MOD:RC. STA:B is set. The resulting CM reset is finished after at most 250  $\mu$ sec and is indicated by the status register B-bit being logical 0. Changing the pulse shaping factor N during CM reset may result in a CM reset time longer than 250  $\mu$ s.

To prepare the PEx 2046 for programming the CM, the RI-bit in the mode register must be reset. Note that one mode register access can serve to reset both RC and RI bits as well as configuring to chip (i.e. selecting operating mode etc.).

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Figure 3 Initializing the PEx 2046 for a 8192-kHz-Device Clock

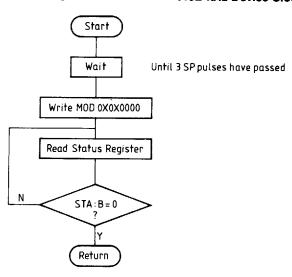
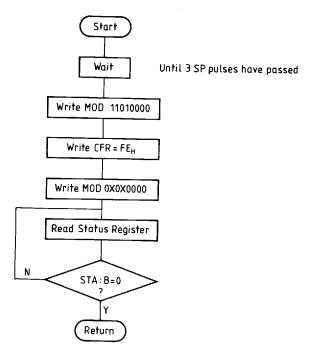


Figure 4
Initializing the PEx 2046 for a 4096-kHz-Device Clock



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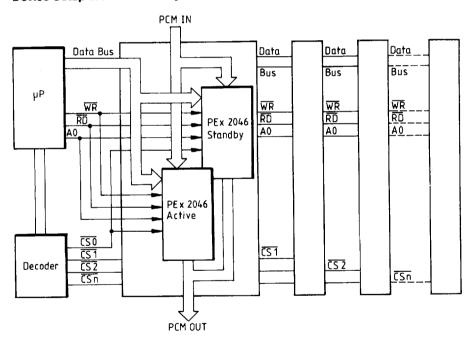
# Operation with a 4096-kHz-Device Clock

In order for the MTSC to operate with a 4096-kHz-device clock the CPS-bit in the CFR register needs to be reset. This has to be done before the CM reset and needs up to 1.8 μs. Please keep in mind, MOD:RI has to be reset prior to performing an indirect register access. For a flow chart of this process refer to figure 4.

#### Standby Mode

With MOD:SB being logical 1 the PEx 2046 works as a backup device in redundant systems. It can be accessed via the  $\mu P$  interface and works internally like an active device. However, the outputs are high impedance. If the SB-bit is reset the outputs are switched to low impedance for the programmed active channels and this MTSC can take over from another device which has been recognized as being faulty. See figure 5.

Figure 5 **Device Setup in Redundant Systems** 



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# **Detailed Register Description**

The following registers may be accessed:

#### Table 1

# **Addressing the Direct Registers**

Address A0	Write Operation	Read Operation		
0	MOD	STA		
11	IAR	IAR		

The chapters in this section cover the registers in detail.

# Mode Register (MOD)

DD 7

Access: write on address 0

		T	·	<del></del>			DB 0
RC	TE	RI	SB	MI1	MIO	MO1	MO0

Value after power up: FF<sub>H</sub>

Reset Connection memory; writing a zero to this bit causes the complete connection memory to be overwritten with 200<sub>H</sub> (tristate). During this time STA:B is set. The maximum time for resetting the connection memory is 250 µs.

TE: Tristate Enable; this bit determines which tristating scheme is activated.

TE = 1: If the speech memory address written into the connection memory is S8 - S0 = 0, the output channel is tristated.

TE = 0: The S9 bit written into the connection memory is interpreted as a validity bit: S9 = 0 enables the programmed connection, S9 = 1 tristates the output.

Note: If TE = 1, time slot 0 of the logical input line 0 cannot be used for switching.

RI: Reset Indirect access mechanism; setting this bit resets the indirect access mechanism. RI has to be cleared before writing/reading IAR after reset.

**SB:** Stand By; by selecting SB = 1 all outputs are tristated. The connection memory works normally. The PEx 2045 can be activated immediately by resetting SB.

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Table 2
Input and Output Pin Arrangement

### **Input Pin Arrangement**

Pin	-No.	8x2 Mbit/s
P-DIP	PL-CC	
3	4	IN 1
4	5	IN 0
5	7	IN 5
6	8	IN 4
15	17	IN 6
16	17	IN 7
17	19	IN 2
18	20	IN 3

# **Output Pin Arrangement**

-No. PL-CC	8x2 Mbit/s
35	OUT 7
36	OUT 6
37	OUT 5
38	OUT 4
40	OUT 3
41	OUT 2
42	OUT 1
43	OUT 0
	35 36 37 38 40 41 42

# Status Register (STA)

Access: read at address 0

DB 7							DB 0	
В	Z	R	0	0	0	0	0	

**B** usy: the chip is busy resetting the connection memory (B = 1). B is undefined after power up and logical 0 after the device initialization.

Note: The maximum time for resetting the connection memory is 250  $\mu s$ .

**Z** incomplete instruction; a three byte indirect instruction is not completed (Z = 1). Z is 0 after power up.

Note: Z is reset and the indirect access is cancelled by setting  $\mathbf{MOD}:\mathbf{RI}$  or resetting  $\mathbf{MOD}:\mathbf{RC}$ 

initialization Request. The connection memory has to be reset due to loss of data (R=1). The R bit is set after power failure or inappropriate clocking and reset when the connection memory reset is finished. R is undefined after power up and logical 0 after the device initialization.

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# **Indirect Access Register (IAR)**

(Read or Write Operation with Address A0 = 1)

An indirect access is performed by reading/writing three consecutive bytes (first byte = control byte, second byte = data byte, third byte = address byte) to/from IAR. The structure is shown in **table 3**.

Table 3
The 3 Bytes of the Indirect Access

Bit 7					Bit 0			
0	0	K1	K0	0	0	C1	CO	Control Byte
D7	D6	D5	D4	D3	D2	D1	D0	Data Byte
IA7	IA7 IA6		IA4	IA3	IA2	IA1	IA0	Address Byte

The control byte bits K1, K0, C1 and C0 together with the address byte determine the type of access being performed according to **table 4**.

Table 4
Encoding the Different Types of Indirect Accesses

K1	КО	C1	C0	Address Byte	Туре	of Access
0 1 0	0 D9 0 D9 1 D9	D8 D8 D8	CM-Address CM-Address CM-Address	Read Write Write	CM CM CM	
1	1	0 0	0	FE <sub>H</sub>	Write Read	CFR CFR

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# **Connection Memory Access**

For a connection memory access the control byte bits C1 and C0 contain the data bits D9 and D8, respectively. D9 is the validity bit which together with D8 and the data byte D7-D0 is written to the CM address IA7-IA0.

The function of the validity bit is controlled by **STA:TE**. D8-D0 and IA7-IA0 contain the information for the logical line and time-slot numbers of the programmed connection, D8-D0 for the inputs, IA7-IA0 for the outputs. **Table 5** shows the programming of these bits.

#### Standard Configuration

Table 5
Time Slot and Line Programming

2 Mbit/s input lines	Bit Bit Bit	D3 D8 D9	to to	D0 D4	Logical line number Time slot number Valididy bit
2 Mbit/s output lines	Bit	IA2	to	IAO	Line number
	Bit	IA7	to	IAO	Time slot number

# Configuration Register Access (CFR)

Access: read or write at indirect address FEH

For a read access the bit 0 of the control byte must be set to logical 1 and for a write access to logical 0.

Value after power up or software reset: FF<sub>H</sub>

DB 7					_		DB 0
1	1	1	1	1	1	1	CPS

CPS.. Clock Period Select: device clock is set to 8192 kHz (logical 1) or 4096 kHz (logical 0)

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# **Absolute Maximum Ratings**

Parameter	Symbol	Limit Values	Unit
Ambient temperature under bias PEB 2046	T <sub>A</sub>	0 to 70	°C
Storage temperature PEB 2046	T <sub>stg</sub>	-65 to 125	°C
Ambient temperature under bias PEF 2046	T <sub>A</sub>	-40 to 85	°C
Storage temperature PEF 2046	T <sub>stg</sub>	-65 to 125	°C
Voltage on any pin with respect to ground	V <sub>s</sub>	-0.4 to V <sub>DD</sub> +0.4	V

# **DC Characteristics**

Ambient temperature under bias range;  $V_{\rm DD} = 5~{\rm V} \pm 5\%$ ,  $V_{\rm SS} = 0~{\rm V}$ .

		Limit Values				
Parameter	Symbol	min.	max.	Unit	Test Conditions	
L-input voltage	V <sub>IL</sub>	-0.4	0.8	V		
H-input voltage	V <sub>IH</sub>	2.0	V <sub>DD</sub> +0.4	V		
L-output voltage	$V_{OL}$		0.45	٧	$I_{\rm OL} = 2 \; {\rm mA}$	
H-output voltage H-output voltage	V <sub>OH</sub> V <sub>OH</sub>	2.4 V <sub>DD</sub> -0.5		V V	$I_{\text{OH}} = -400 \mu\text{A}$ $I_{\text{OH}} = -100 \mu\text{A}$	
Operational power supply current	$I_{CC}$		10	mA	$V_{\rm DD} = 5$ V, inputs at 0 V or $V_{\rm DD}$ , no output loads.	
Input leakage current Output leakage current	$I_{LI}$ $I_{LO}$		10	μА	0 V < V <sub>IN</sub> < V <sub>DD</sub> to 0 V 0 V < V <sub>OUT</sub> < V <sub>DD</sub> to 0 V	

Capacitances  $T_{\rm A} = 25\,^{\rm o}{\rm C},\ V_{\rm DD} = 5\ {\rm V} \pm 5\%,\ V_{\rm SS} = 0\ {\rm V}.$ 

			imit Values	
Parameter	Symbol	min.	max.	Unit
nput capacitance	C <sub>IN</sub>		10	pF
I/O capacitance	C <sub>IO</sub>		20	pF
Output capacitance	C <sub>OUT</sub>		15	pF

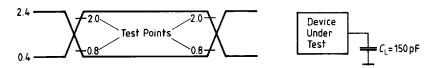
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### **AC Characteristics**

Ambient temperature under bias range,  $V_{DD} = 5 \text{ V} \pm 5\%$ 

Inputs are driven at 2.4 V for a logical 1 and at 0.4 V for a logical 0. Timing measurements are made at 2.0 V for a logical 1 and at 0.8 V for a logical 0. The AC testing input/output waveforms are shown below.

Figure 5 I/O Waveform for AC Tests



# μP Interface Timing

		Limit Values		
Parameter	Symbol	min.	max.	Unit
Address stable before RD	t <sub>AR</sub>	0		ns
Address hold after RD	t <sub>RA</sub>	0		ns
RD width	t <sub>RR</sub>	90		ns
RD to data valid	t <sub>RD</sub>		90	ns
Address stable to data valid	t <sub>AD</sub>		90	ns
Data float after RD	t <sub>DF</sub>	5	25	ns
Read cycle time	t <sub>RCY</sub>	160		ns
Address stable before WR	t <sub>AW</sub>	0		ns
Address hold time	t <sub>WA</sub>	0		ns
WR width	tww	60		ns
Data setup time	t <sub>DW</sub>	5		ns
Data hold time	t <sub>WD</sub>	15		ns
Write cycle time	twcy	160		ns

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Figure 6 μP Read Cycle

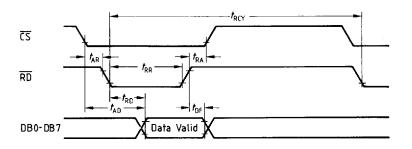
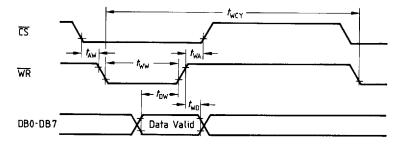


Figure 7 μP Write Cycle



# **PCM Interface Timing**

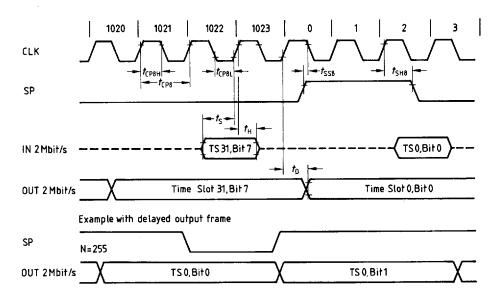
		L	imit Values	
Parameter	Symbol	min.	max.	Unit
PCM input setup	ts	0		ns
PCM input hold	t <sub>H</sub>	30		ns
PEB 2046 output delay	t <sub>D</sub>		45	ns
PEF 2046 output delay	$t_{D}$		50	ns

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**Clock and Synchronization Timing** 

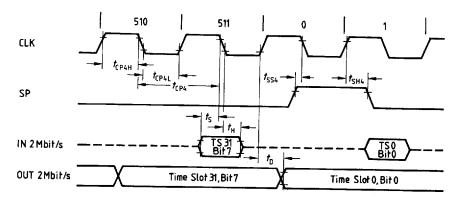
		L	imit Values	
Parameter	Symbol	min.	max.	Unit
Clock period 8 MHz high	t <sub>CP8 H</sub>	40		ns
Clock period 8 MHz low	t <sub>CP8.L</sub>	48		ns
Clock period 8 MHz	t <sub>CP8</sub>	120		ns
Synchronization pulse setup 8 MHz	t <sub>SS8</sub>	10	t <sub>CP8</sub> -20	ns
Synchronization pulse delay 8 MHz	t <sub>SH8</sub>	0	t <sub>CP8</sub> -20	ns
Clock period 4 MHz high	t <sub>CP4'H</sub>	90		ns
Clock period 4 MHz low	t <sub>CP4</sub> L	90		ns
Clock period 4 MHz	t <sub>CP4</sub>	240		ns
Synchronization pulse setup 4 MHz	t <sub>SS4</sub>	10	t <sub>CP4</sub> -30	ns
Synchronization pulse delay 4 MHz	t <sub>SH4</sub>	30	t <sub>CP4</sub> -10	ns

Figure 8
PCM Line Timing with a 8-MHz-Device Clock



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Figure 9
PCM Line Timing with a 4-MHz Device Clock



# **Busy Time**

Table 6 Busy Time

Operation	Max. Values	Unit
Indirect register access	900	ns
Connection memory reset	250	μs