# Quad ISLAC™

Quad Intelligent Subscriber Line Audio-processing Circuit (Quad ISLAC™)
Am79Q2241/2242/2243 Device

### **APPLICATIONS**

- Voice over IP/DSL Integrated Access Devices (IAD), Smart Residential Gateways (SRG), Home Gateway/ Router
- Cable Telephony NIU, Set-Top Box, Home Side Box, Cable Modem, Cable PC
- Fiber Fiber in the Loop (FITL), Fiber to the Home (FTTH)
- Wireless Local Loop, Intelligent PBX
- **■** DLC-MUX
- CO

### **FEATURES**

- High performance digital signal processor provides programmable control of all major linecard functions
  - A-law/µ-law and linear codec
    - Transmit and receive gain
    - Two-wire AC impedance
    - Transhybrid balance
    - Equalization
  - DC loop feeding
    - Smooth or abrupt polarity reversal
  - Loop supervision
    - Off-hook debounce circuit
    - Ground-key and ring-trip filters
  - Ringing generation and control
  - Adaptive hybrid balance
  - Line and circuit testing
  - Tone generation
  - Metering generation at 12 kHz and 16 kHz
    - Envelope shaping and level control
- Selectable PCM/MPI or GCI digital interfaces
  - Supports most available master clock frequencies from 512 kHz to 8.192 MHz
- General purpose I/O pins
- **■** +3.3 V DC operation
- Exceeds LSSGR and ITU requirements
- Supports external ringing with on-chip ring-trip circuit
  - Automatic or manual ring-trip modes

### ORDERING INFORMATION



Device	Package
Am79Q2241 VC	64-pin TQFP
Am79Q2242 JC	68-pin PLCC
Am79Q2243 VC	80-pin TQFP

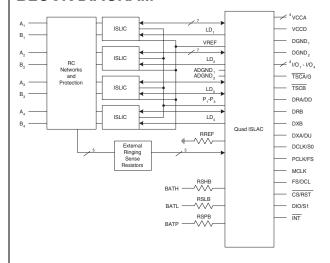
### DESCRIPTION

The Quad ISLAC™ device, in combination with an ISLIC™ device, implements a four channel universal telephone line interface. This enables the design of a single, low cost, high performance, fully software programmable line interface for multiple country applications. All AC, DC, and signaling parameters are fully programmable via microprocessor or GCI interfaces. Additionally, the Quad ISLAC device has integrated self-test and line-test capabilities to resolve faults to the line or line circuit. The integrated test capability is crucial for remote applications where dedicated test hardware is not cost effective.

### RELATED LITERATURE

- 080274 Am79D2251 Dual ISLAC Data Sheet
- 080248 Am79231 ISLIC Data Sheet
- 080693 Am79240 ISLIC Data Sheet
- 080249 Am79241 ISLIC Data Sheet
- 080253 Am79251 ISLIC Data Sheet
- 080344 Am79R2xx/Am79Q224x Technical Reference
- 080345 Am79R240/Am79D2251 Technical Reference

### **BLOCK DIAGRAM**



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### PRODUCT DESCRIPTION

The Intelligent Access™ voice chipsets integrate all functions of the subscriber line for four subscriber lines. One or more of two chip types are used to implement the linecard; an ISLIC device and a Quad ISLAC device. These provide the following basic functions:

- 1. The ISLIC device: A high voltage, bipolar IC that drives the subscriber line, maintains longitudinal balance and senses line conditions.
- 2. The Quad ISLAC device: A low voltage CMOS IC that provides conversion and DSP functions for all 4 channels.

Complete schematics of linecards using the Intelligent Access voice chipsets for internal and external ringing are shown in "Application Circuits" on page 26.

The ISLIC device uses reliable, bipolar technology to provide the power necessary to drive a wide variety of subscriber lines. It can be programmed by the ISLAC device to operate in eight different modes that control power consumption and signaling modes. This enables it to have full control over the subscriber loop. The ISLIC device is designed to be used exclusively with the ISLAC device as part of a multiple-line chipset. The ISLIC device requires only +5 V power and the battery supplies for its operation.

The ISLIC device implements a linear loop-current feeding method with the enhancement of intelligent thermal management in a controlled manner. This limits the amount of power dissipated on the ISLIC chip by dissipating excess power in external resistors.

Each ISLAC device contains high-performance codec circuits that provide A/D and D/A conversion for voice (codec), DC-feed and supervision signals for four subscriber channels. The ISLAC device contains a DSP core that handles signaling, DC-feed, supervision and line diagnostics for all four channels.

The DSP core selectively interfaces with three types of backplanes:

- Standard PCM/MPI
- Standard GCI
- Modified GCI with a single analog line per GCI channel

The Intelligent Access voice chipset provides a complete software configurable solution to the BORSCHT functions as well as complete programmable control over subscriber line DC-feed characteristics, such as current limit and feed resistance. In addition, these chipsets provide system level solutions for the loop supervisory functions and metering. In total, they provide a programmable solution that can satisfy worldwide linecard requirements by software configuration.

Software programmed filter coefficients, DC-feed data and supervision data are easily calculated with the WinSLAC™ software. This PC software is provided free of charge. It allows the designer to enter a description of system requirements. WinSLAC then computes the necessary coefficients and plots the predicted system results.

The ISLIC interface unit inside the ISLAC device processes information regarding the line voltages, loop currents and battery voltage levels. These inputs allow the ISLAC device to place several key ISLIC performance parameters under software control.

The main functions that can be observed and/or controlled through the ISLAC backplane interface are:

- · DC-feed characteristics
- Ground-key detection
- Off-hook detection
- Metering signal
- · Longitudinal operating point
- · Subscriber line voltage and currents
- Ring-trip detection
- Abrupt and smooth battery reversal
- Subscriber line matching
- Ringing generation
- · Sophisticated line and circuit tests

To accomplish these functions, the ISLIC device collects the following information and feeds it, in analog form, to the ISLAC device:

- The metallic (IMT) and longitudinal (ILG) loop currents
- The AC (VTX) and DC (VSAB) loop voltages
- The outputs supplied by the ISLAC device to the ISLIC device are then:
- A voltage (VHLi) that provides control for the following high-level ISLIC device outputs:
- DC loop current
- · Internal ringing signal
- 12 or 16 kHz metering signal



- A low-level voltage proportional to the voice signal (VOUTi)
- A voltage that controls longitudinal offset for test purposes (VLBi)

The ISLAC device performs the codec and filter functions associated with the four-wire section of the subscriber line circuitry in a digital switch. These functions involve converting an analog voice signal into digital PCM samples and converting digital PCM samples back into an analog signal. During conversion, digital filters are used to band-limit the voice signals.

The user-programmable filters set the receive and transmit gain, perform the transhybrid balancing function, permit adjustment of the two-wire termination impedance and provide frequency attenuation adjustment (equalization) of the receive and transmit paths. Adaptive transhybrid balancing is also included. All programmable digital filter coefficients can be calculated using WinSLAC software. The PCM codes can be either 16-bit linear two's-complement or 8-bit companded A-law or µ-law.

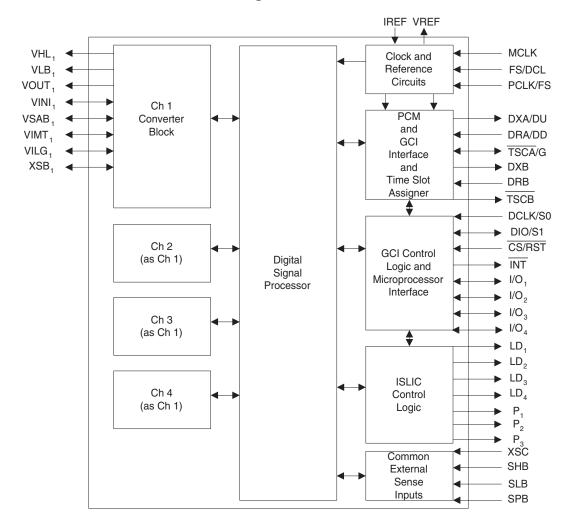
Besides the codec functions, the Intelligent Access voice chipset provides all the sensing, feedback, and clocking necessary to completely control ISLIC device functions with programmable parameters. System-level parameters under programmable control include active loop current limits, feed resistance, and feed mode voltages.

The ISLAC device supplies complete mode control to the ISLIC device using the control bus and (P1-P3) tri-level load signal (LDi).

The Intelligent Access voice chipset provides extensive loop supervision capability including off-hook, ring-trip and ground-key detection. Detection thresholds for these functions are programmable. A programmable debounce timer is available that eliminates false detection due to contact bounce.

For subscriber line diagnostics, AC and DC line conditions can be monitored using built in test tools. Measured parameters can be compared to programmed threshold levels to set a pass/fail bit. The user can choose to send the actual PCM measurement data directly to a higher level processor by way of the voice channel. Both longitudinal and metallic resistance and capacitance can be measured, which allows leakage resistance, line capacitance, and telephones to be identified.

### Quad ISLAC™ Device Internal Block Diagram





## Features of the Intelligent Access™ Chipset

- Performs all battery feed, ringing, signaling, hybrid and test (BORSCHT) functions
- Two chip solution supports high density, multi-channel architecture
- Single hardware design meets multiple country requirements through software programming of:
  - Ringing waveform and frequency
  - DC loop-feed characteristics and current-limit
  - Loop-supervision detection thresholds
    - Off-hook debounce circuit
    - Ground-key and ring-trip filters
  - Off-hook detect de-bounce interval
  - Two-wire AC impedance
  - Transhybrid balance
  - Transmit and receive gains
  - Equalization
  - Digital I/O pins
  - A-law/µ-law and linear selection
- Supports internal and external battery-backed ringing
  - Self-contained ringing generation and control
  - Supports external ringing generator and ring relay
  - Ring relay operation synchronized to zero crossings of ringing voltage and current
  - Integrated ring-trip filter and software enabled manual or automatic ring-trip mode
- · Supports metering generation with envelope shaping
- Smooth or abrupt polarity reversal
- Adaptive transhybrid balance
  - Continuous or adapt and freeze

- Supports both loop-start and ground-start signaling
- Exceeds LSSGR and CCITT central office requirements
- Selectable PCM or GCI interface
  - Supports most available master clock frequencies from 512 kHz to 8.192 MHz
- On-hook transmission
- · Power/service denial mode
- Line-feed characteristics independent of battery voltage
- Only 5 V, 3.3 V and battery supplies needed
- Low idle-power per line
- Linear power-feed with intelligent power-management feature
- Compatible with inexpensive protection networks;
   Accommodates low-tolerance fuse resistors while maintaining longitudinal balance
- Monitors two-wire interface voltages and currents for subscriber line diagnostics
- · Built-in voice-path test modes
- Power-cross, fault, and foreign voltage detection
- · Integrated line-test features
  - Leakage
  - Line and ringer capacitance
  - Loop resistance
- Integrated self-test features
  - Echo gain, distortion, and noise
- · Small physical size
- Up to three relay drivers per ISLIC<sup>™</sup> device
  - Configurable as test load switches



### CONNECTION DIAGRAMS

Figure 1. 68-Pin PLCC Connection Diagram

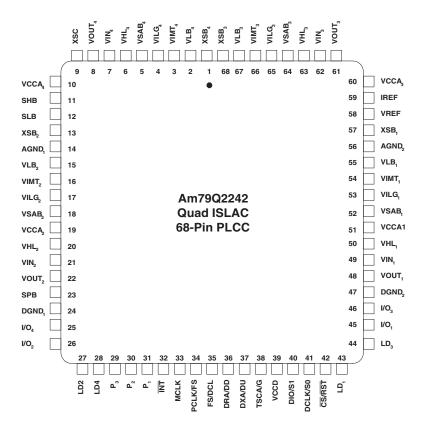


Figure 2. 64-Pin TQFP Connection Diagram

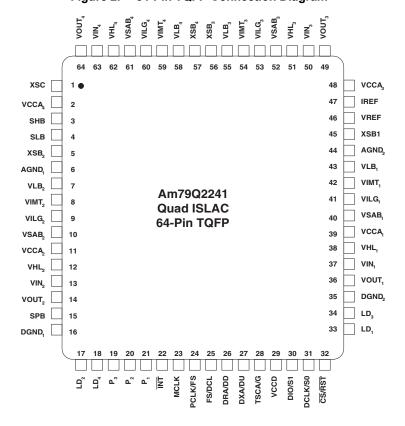
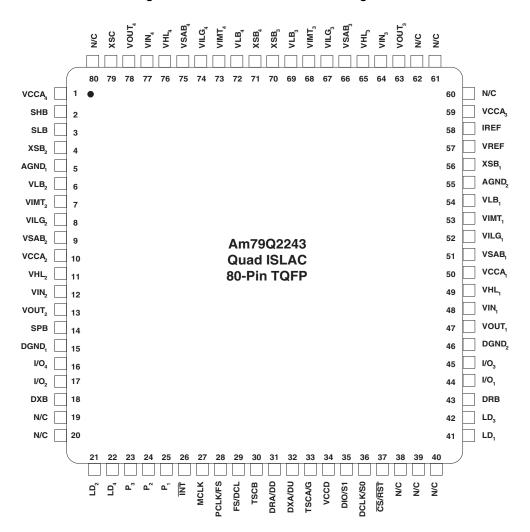




Figure 3. 80-Pin TQFP Connection Diagram





## **PIN DESCRIPTIONS**

Pin	Pin Name	I/O	Description
AGND <sub>1</sub> , AGND <sub>2</sub>	Analog Ground		Analog circuitry ground returns
DCLK/S0	Data Clock/GCI Address Strap 0	I	Provides data control for MPI interface control. For GCI operation, this pin is device address bit 0.5 V tolerant.
DGND <sub>1</sub> , DGND <sub>2</sub>	Digital Ground		Digital ground returns
DIO/S1	Data I/O/GCI Address Strap 1	I/O	For PCM backplane operation, control data is serially written into and read out of the ISLAC device via the DIO pin with the MSB first. The data clock (DCLK) determines the data rate. DIO is high impedance except when data is being transmitted from the ISLAC device under control of CS/RST. For GCI operation, this pin is device address bit 1. 5 V tolerant.
DRA/DD, DRB	RX Path A Backplane Data/ GCI data Downstream, Receive Path B backplane data	ı	For the PCM highway, the receive PCM data is input serially through the DRA or DRB ports. The data input is received every 125 µs and is shifted in, MSB first, in 8-bit PCM or 16-bit linear bursts at the PCLK rate. The receive port can receive information for direct control of the ISLIC device. This mode is selected in Device Configuration Register 2 (RTSEN=1, RTSMD=1). When selected, this data is received in an independently programmable timeslot from the PCM data. For the GCI mode, downstream receive and control data is accepted on this pin. The DRB pin is available only on the 80-pin TQFP package. 5 V tolerant.
DXA/DU, DXB	TX Path A Backplane Data/ GCI Data Upstream, TX Path B Backplane Data	0	For the PCM highway, the transmit PCM data is transmitted serially through the DXA or DXB ports. The transmission data output is available every 125 µs and is shifted out, MSB first, in 8-bit PCM or 16-bit linear bursts at the PCLK rate. DXA and DXB are high impedance between bursts and while the device is in the inactive mode. Can also select a mode (RTSEN= 1, RTSMD=1 or 0 in Device Configuration Register 2) that transmits the Signaling Register MSB contents first, in an independently programmable timeslot from the PCM data. This data is transmitted in all modes except disconnect. For the GCI mode, upstream transmit and signaling data is transferred on this pin. The DXB pin is available only on the 80-pin TQFP package. 5 V tolerant.
FS/DCL	Frame sync/GCI Downstream Clock	ı	For PCM operation, pin is Frame Sync. PCM operation is selected by the presence of an 8 kHz Frame Sync signal on this pin in conjunction with the PCLK on the PCLK/FS pin (see below). This 8 kHz pulse identifies the beginning of a frame. The ISLAC device references individual timeslots with respect to this input, which must be synchronized to PCLK. GCI operation is selected by the presence of the downstream clock DCL, on this pin in conjunction with the presence of a FS on the PCLK/FS pin. In GCI mode, the data rate is 2 MHz and DCL must be either 2 or 4 MHz. 5 V tolerant.
INT	Interrupt	0	For PCM operation, when a subscriber line requires service, this pin goes to a logic 0 to interrupt a higher level processor. Several registers work together to control operation of the interrupt: Signaling and Global Interrupt Registers with their associated Mask Registers, and the Interrupt Register. See the description at channel configuration register 6 (Mask) for operation. Logic drive is selectable between open drain and TTL-compatible outputs.
I/O <sub>1</sub> –I/O <sub>4</sub>	Control Ports	I/O	General purpose, TTL-compatible, logic input/output connection for each of 4 channels. These control lines are TTL-compatible and each can be programmed as an input or output in the Global I/O Direction Register. When programmed as outputs, they can control an external logic device. When programmed as inputs, they can monitor external, TTL-compatible logic circuits. Data for these pins can be written or read individually (from the channel specific I/O Register) or as a group (from the Global I/O Data Register). Not available on the 64-pin package.
IREF	Current Reference	I	External resistor (RREF) connected between this pin and analog ground generates an accurate, on-chip reference current for the A/D's and D/A's on the ISLAC chip.
LD <sub>1</sub> –LD <sub>4</sub>	Register Load	0	The LD pins output 3-level voltages. When LD <sub>n</sub> is a logic 0 (< 0.4 V), the destination of the code on $P_1$ – $P_3$ is the relay control latches in the ISLIC control register. When LD <sub>n</sub> is a logic 1 (>V <sub>CC</sub> –0.4 V), the destination of $P_1$ – $P_3$ is the mode control latches. LD <sub>n</sub> is driven to VREF when the contents of the ISLIC control register must not change.



Pin	Pin Name	I/O	Description		
MCLK	Master Clock	ı	For PCM backplane operation, the DSP master clock connects here. A signal is required only for PCM backplane operation when PCLK is not used as the master clock. MCLK can be a wide variety of frequencies. Upon initialization the MCLK input is disabled, and relevant circuitry is driven by a connection to PCLK. 5 V tolerant.		
PCLK/FS	PCM Clock/ Frame Sync	I	For PCM operation, this is PCM Clock. PCM operation is selected by the presence of a PCLK signal on this pin in conjunction with the FS on the FS/DCL pin (see below). For PCM backplane operation, connect a data clock, which determines the rate at which PCM data is serially shifted into or out of the PCM ports. PCLK can be any multiple of the FS frequency. The minimum clock frequency for linear/ companded data plus signaling data is 256 kHz. For GCI operation, this pin is Frame Sync. The FS signal is an 8 kHz pulse that identifies the beginning of a frame. The ISLAC device references individual timeslots with respect to this input, which must be synchronized to DCL. 5 V tolerant.		
P <sub>1</sub> –P <sub>3</sub>	ISLIC Control	0	Control the operating modes of the four ISLIC devices connected to the Quad ISLAC device.		
CS/RST	Chip Select/ Reset	ı	For PCM backplane operation, a logic low on this pin for 16 or more DCLK cycles resets the sequential logic in the ISLAC device into a known mode. A logic low placed on this pin for less than 15 DCLK cycles is a chip select and enables serial data transmission into or out of the DIO port. For GCI operation, a logic low on this pin for 1 ms or longer resets the sequential logic into a known mode. See Table 2-4 in the Technical Reference for details. 5 V tolerant.		
SHB, SLB, SPB	Battery Sense	I	Resistors that sense the high, low and positive battery voltages connect here. If only one negative battery is used, connect both resistors at the supply. If the positive battery is not used, leave the pin unconnected. These pins are current inputs whose voltage is held at VREF.		
TSCA/G	Timeslot Control A/GCI Mode	O (PCM) I (GCI)	For PCM backplane operation, TSCA or TSCB is active low when PCM da output on the DXA or DXB pins. The outputs are open-drain and are normalization (high importance). Bull up leads should be connected to VCCD.		
TSCB	Time Slot Control B	0	inactive (high impedance). Pull-up loads should be connected to VCCD. TSCB is only available on the 80 pin TQFP package. When GCI mode is selected, one of two GCI modes may be selected by connecting TSCA/G to DGND or VCCD.		
VSAB <sub>1</sub> - VSAB <sub>4</sub>	Loop voltage sense	I	Connect to the VSAB pins of four ISLIC devices.		
VCCA <sub>1</sub> - VCCA <sub>4</sub>	Power Supply		+3.3 VDC supplies to the analog sections in each of the four channels.		
VCCD	Power Supply		+3.3 VDC supply to all digital sections.		
VREF	Analog Reference	0	This pin provides a 1.4 V, single-ended reference to the four ISLIC devices to which the ISLAC device is connected.		
VHL <sub>1</sub> - VHL <sub>4</sub>	High Level D/A	0	High-level loop control voltages on these pins are used to control DC-feed, internal ringing, metering and polarity reversal for each ISLIC device.		
VIN <sub>1</sub> - VIN <sub>4</sub>	TX Analog	I	Analog transmit signals (VTX) from each ISLIC device connect to these pins. The ISLAC device converts these signals to digital words and processes them. After processing, they are multiplexed into serial time slots and sent out of the DXA/DU pin.		
VLB <sub>1</sub> - VLB <sub>4</sub>	Longitudinal Reference	0	Normally connected to VCCA internally. They supply longitudinal reference voltages to the ISLIC devices during certain test procedures. These outputs are connected internally to VCCA during ISLIC Active, Standby, Ringing, and Disconnect modes. During test modes, it can be connected to the receive D/A.		

	Package Type					
Pin Options	80 pin	68 pin	64 pin			
DRB	ý	х	X			
DXB	V	Х	Х			
TSCB	V	x	Х			
I/O <sub>1</sub> –I/O <sub>4</sub>	V	V	Х			



### **ELECTRICAL CHARACTERISTICS**

### **Absolute Maximum Ratings**

Stresses greater than those listed under Absolute Maximum Ratings can cause permanent device failure. Functionality at or above these limits is not implied. Exposure to absolute maximum ratings for extended periods can affect device reliability

Storage Temperature	-60° C ≤ T <sub>A</sub> ≤ +125° C
Ambient Temperature, under Bias	-40° C ≤ T <sub>A</sub> ≤ +85° C
Ambient relative humidity (non condensing)	5 to 100%
V <sub>CCA</sub> with respect to DGND	-0.4 to + 3.6 V
V <sub>CCD</sub> with respect to DGND	-0.4 to + 3.6 V
V <sub>IN</sub> with respect to DGND	-0.4 to VCCA + 0.4 V
5 V tolerant pins	-0.4 to Vcc + 2.25 or 5.25 V, whichever is less
AGND	DGND ± 0.4 V
Latch up immunity (any pin)	±100 mA
Any other pin with respect to DGND	-0.4 V to V <sub>CC</sub>

## **Operating Ranges**

Operating ranges define those limits between which device functionality is guaranteed. Functionality of the device from 0 to 70° C is guaranteed by production testing. Performance from –40 to 85°C is guaranteed by characterization and periodic sampling of production units.

## **Environmental Ranges**

Ambient Temperature	-40 to +85° C
Ambient Relative Humidity	15 to 85%

### **Electrical Ranges**

Analog Supply V <sub>CCA</sub>	+3.3 V ± 5%
Digital Supply V <sub>CCD</sub>	+3.3 V ± 5%
DGND	0 V
AGND	DGND ±50 mV

### **SPECIFICATIONS**

The performance targets defined in this section are for the entire linecard comprised of both chips in the Intelligent Access voice chipsets unless otherwise noted. Specifications for the individual chips in the set will be published separately (see note 1).  $T_A = 0$  to  $70^{\circ}$  C unless otherwise noted.

## Intelligent Access Voice Chipsets System Target Specifications

Item	Condition	Min	Тур	Max	Unit	Note
Peak Ringing Voltage	Active Ringing mode, RLOAD =1500 $\Omega$ , VBH = 80 V		70		V	
Output Impedance during internal ringing	Active Ringing mode, Quad ISLAC generating internal ringing		200		Ω	
Sinusoidal Ringing THD	Active Ringing mode, RLOAD =1500Ω, VBH = 80V, ISLAC generating internal sinusoidal ringing		2		%	
	Loop open, in anti-sat					
PSRR (VBH, VBL)	f = 50 Hz	2			dB	1, 2
	f = 200 to 3400 Hz	12				



#### Note:

- 1. Not tested or partially-tested in production.
- These numbers are only valid when an ISLIC device operates with an ISLAC device, because the ISLAC generates the anti-sat feed
  characteristic. When the Intelligent Access voice chipsets operate in the normal feed region, the performance is dominated by the ISLIC
  device. See appropriate ISLIC data sheet for specific PSRR.

## **DC Specifications**

No.	Item	Condition	Min	Тур	Max	Unit	Note
1	Input Low Voltage, I/O <sub>1</sub> –I/O <sub>4</sub>		-0.05		1.36 V		
'	All other digital inputs		-0.50		0.80 V	V	
	Input High Voltage, I/O <sub>1</sub> –I/O <sub>4</sub>		2.36		Vcc+0.4	- V	
2	All other digital inputs		2.0		5.25		
4	Input Leakage Current, I/O <sub>1</sub> –I/O <sub>4</sub>	0 to V <sub>CC</sub>	-10		+10	0	
4	All other digital inputs	0 to 5.25 V	-120		+180	μA	
5	Input hysteresis (PCLK/FS, FS/DCL, MCLK, DIO, DRA, DRB)		.15	.225	.3		2
	I/O1–I/O4		.16	.25	.34	1	
	Ternary output voltages, LD <sub>1</sub> –LD <sub>4</sub>					V	
6	High voltage	lout = 1 mA	VCC4		_	1	
0	Low voltage	lout = 2 mA	_		0.4		
	Medium voltage	±10 μA		VREF			
7	Output Low Voltage (DXA/DU, DIO, I/O <sub>1</sub> -I/O <sub>4</sub> , INT, TSCA, TSCB, DXB, P <sub>1</sub> -P <sub>3</sub> )	IoI = 1 mA			0.4		
8	Output Low Voltage (I/O <sub>1</sub> –I/O <sub>4</sub> , INT, TSCA, TSCB)	IoI = 10 mA			1.0	V	
9	Output High Voltage (All digital outputs except INT in open drain mode and TSCA, TSCB)	Ioh = 400 μA	VCC-0.4			_	
10	Input Leakage Current (VIN <sub>1</sub> –VIN <sub>4</sub> , VSAB <sub>1</sub> –VSAB <sub>4</sub> , VILG <sub>1</sub> –VILG <sub>4</sub> , VIMT <sub>1</sub> –VIMT <sub>4</sub> )		-1	0.2	1	μA	
	Input voltage (VIN <sub>1</sub> –VIN <sub>4</sub> )						
12	μ-law	3.205 dBm0	VREF		VREF		
12	A-law	3.14 dBm0 to insertion loss in ADC	-1.02		+1.02	V	
13	Input Voltage (VSAB <sub>1</sub> –VSAB <sub>4</sub> or VIMT <sub>1</sub> –VIMT <sub>4</sub> or VILG <sub>1</sub> –VILG <sub>4</sub> )	Vov–VREF  where Vov is input overload voltage	0.99	1.02	1.05		
14	Offset voltage allowed on VIN <sub>1</sub> –VIN <sub>4</sub>		-50		+50		
15	VOLIT VOLIT offset Voltage	DISN off	-40		+40	m\/	4
15	VOUT <sub>1</sub> –VOUT <sub>4</sub> offset Voltage	DISN on	-80		+80	mV	
16	VHL output offset voltage			TBD		1	
17	Output voltage, VREF	Load current = 0 to 10 mA		1.4		V	
		Source or Sink					
18	Capacitance load on VREF or VOUT <sub>1</sub> –VOUT <sub>4</sub>				200	pF	2
19	Output drive current, VOUT <sub>1</sub> –VOUT <sub>4</sub> or VLB <sub>1</sub> –VLB <sub>4</sub>	Source or Sink	-1		+1	mA	2
20	Output Leakage Current VOUT <sub>1</sub> -VOUT <sub>4</sub> or VLB <sub>1</sub> -VLB <sub>4</sub>		500	200	500	nA	



No.	ltem	Condition	Min	Тур	Max	Unit	Note
21	Maximum output voltage on VOUT	VOUT–VREF  with peak digital input	0.99	1.02	1.05		8
22	VLB <sub>1</sub> –VLB <sub>4</sub> operating voltage	Source current < 250µA or	VREF		VREF	V	
		Sink current < 25 μA.	-1.02		+1.02		
23	Maximum output voltage on VHL (KRFB)	VHL–VREF  with peak digital input	0.97	1.00	1.03		8
24	Gain from VSAB to VHL	VFD = 1	4.9	5	5.1	V/V	
25	Gain from VSAB to VHL	VFD = 0	0255	025	0245	V/V	
26	% error of VLB voltage (For VLB equation, see Am79R2xx/ Am79Q224x Technical Reference)		<b>-</b> 5		+5	%	
27	Capacitance load on VLB <sub>1</sub> –VLB <sub>4</sub>				120		2
28	Capacitance load on XSB <sub>1</sub> –XSB <sub>4</sub> , XSC				400	pF	2
00	Out I I I I A O Devent Distriction	One channel active (ISLIC state register set to active); three channels inactive (ISLIC state register set to standby)		183	235		
29	Quad ISLAC Power Dissipation	All channels active (ISLIC state register set to active)		264	340	mW	
		All channels inactive (ISLIC state register set to standby)		143	188		

## **Transmission and Signaling Specifications**

Table 1. 0 dBm0 Voltage Definitions with Unity Gain in X, R, GX, GR, AX, and AR

Signal at Digital Interface	Transmit	Receive	Unit
A-law digital mW or equivalent (0 dBm0)	0.5026	0.5026	
μ-law digital mW or equivalent (0 dBm0)	0.4987	0.4987	Vrms
±5,800 peak linear coded sine wave	0.5026	0.5025	]

No.	ltem	Condition	Min	Тур	Max	Unit	Note
1	Insertion Loss A-D D-A	Input: 1014Hz, -10dBm0 AR = AX = GR = GX = 0 dB, DISN, R, X, B and Z disabled	-0.25	0	+0.25		
	A-D + D-A	Temperature = 70°C	-0.15	0	+0.15		
	A-D – D-A	Variation over temperature	-0.1	0	+0.1	dB	3, 8
2	Level set error (Error between setting and actual value)	A-D AX + GX D-A AR + GR	-0.1		0.1		, ,
3	DR to DX gain in full digital loopback mode	DR Input: 1014 Hz, –10 dBm0 AR=AX=GR=GX=0 dB, DISN, R, X, B and Z filters default	-0.3		+0.3		
4	Idle Channel Noise,	A-D (PCM output)			-69	dBm0p	
~	Psophometric Weighted (A-law)	D-A (V <sub>OUT</sub> )			-78	авттор	5
Idle Channel Noise,		A-D (PCM output)			+19	dBrnC0	3
	C Message weighted (μ-law)	D-A (V <sub>OUT</sub>			+12	ubili00	
6	Coder Offset decision value, Xn	A-D, Input signal = 0 V	<b>-</b> 7		+7	Bits	2



No.	ite	em		Condition		Тур	Max	Unit	Note
7	PSRR (VCC)	A-D	Input: 4.8 to 7.8 kHz, 200 mV p-p		37			dB	
,	Image frequenc	cy D-A	Measure 8 frequency	3000 Hz-Input	01			QD.	1
8	DISN gain accu	ıracy	Gdisn = -0.9375 to 0.9375 Vin = 0 dBm0		-0.25		+0.25	dB	
9	End-to-end gro	up delay	1014Hz; –10dBm0 B = Z = 0; X = R = 1				525	μS	2, 6, 7
10	Crosstalk	TX to RX	0 dBm0	300 Hz to 3400 Hz			-75	dBm0	2
10	same channel	channel RX to TX 0 dBm0 300 Hz to 3400 H		300 Hz to 3400 Hz			_,,	abilio	_
11	Crosstalk	TX or RX to TX	0 dBm0	1014 Hz			-76	dBm0	2
''	Crosstalk	TX or RX to RX	0 dBm0	1014 Hz			-78		

- 1. Not tested or partially tested in production. This parameter is guaranteed by characterization or correlation to other tests.
- 2. Guaranteed by design.
- 3. Overall 1.014 kHz insertion loss error of the Intelligent Access voice chipset is guaranteed to be 0.34 dB
- 4. These voltages are referred to VREF.
- 5. When relative levels (dBm0) are used, the specification holds for any setting of (AX + GX) gain from 0 to 12 dB or (AR + GR) from 0 to –12 dB.
- 6. Group delay spec valid only when Channels 1–4 occupy consecutive slots in the frame. Programming channels in non-consecutive timeslots can add up to 1 frame delay in the Group delay measurements.
- 7. The Group delay specification is defined as the sum of the minimum values of the group delays for transmit and the receive paths when the B, X, R, and Z filters are disabled with null coefficients. See Figure 8 for Group Delay Distortion.
- 8. Requires that the calibration command (7Ch) must be performed to achieve this performance.

### **Transmit and Receive Paths**

In this section, the transmit path is defined as the analog input to the ISLAC device (VIN<sub>n</sub>) to the PCM voice output of the ISLAC A-law/ $\mu$ -law speech compressor. The receive path is defined as the PCM voice input to the ISLAC speech expander to the analog output of the ISLAC device (VOUT<sub>n</sub>). All limits defined in this section are tested with B = 0, Z = 0 and X = R = GR = 1.

When AR is enabled, a nominal gain of -6.02 dB is added to the analog section of the receive path.

When AX is enabled, a nominal gain of +6.02 dB is added to the analog section of the transmit path.

When relative levels (dBm0) are used in any of the following transmission characteristics, the specification holds for any setting of (AX + GX) gain from 0 to 12 dB or (AR + GR) from 0 to -12 dB.

These transmission characteristics are valid for 0 to 70° C.

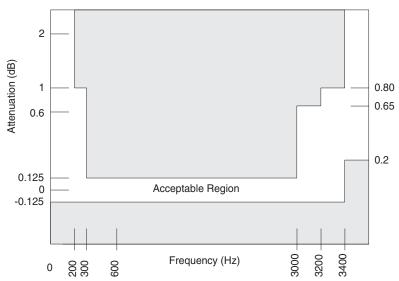


### **Attenuation Distortion**

The attenuation of the signal in either path is nominally independent of the frequency. The deviations from nominal attenuation will stay within the limits shown in Figure 4 and Figure 5. The reference frequency is 1014 Hz and the signal level is -10 dBm0. The minimum transmit attenuation at 60 Hz is 24 dB.

Figure 4. Transmit Path Attenuation vs. Frequency 2 Attenuation (dB) 0.80 0.65 0.6 0.2 0.125 Acceptable Region -0.125 3200 Frequency (Hz) 200

Figure 5. Receive Path Attenuation vs. Frequency





## **Group Delay Distortion**

For either transmission path, the group delay distortion is within the limits shown in Figure 6. The minimum value of the group delay is taken as the reference. The signal level is –10 dBm0.

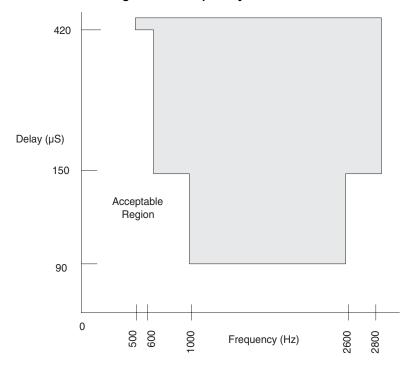


Figure 6. Group Delay Distortion

## **Single Frequency Distortion**

The output signal level, at any single frequency in the range of 300 to 3400 Hz, other than that due to an applied 0 dBm0 sine wave signal with frequency f in the same frequency range, is less than –46 dBm0. With f swept between 0 to 300 Hz and 3.4 to 12 kHz, any generated output signals other than f are less than –28 dBm0. This specification is valid for either transmission path.

### **Intermodulation Distortion**

**TBD** 



### **Gain Linearity**

The gain deviation relative to the gain at -10 dBm0 is within the limits shown in Figure 7 (A-law) and Figure 8 ( $\mu$ -law) for either transmission path when the input is a sine wave signal of 1014 Hz.

Figure 7. A-law Gain Linearity with Tone Input (Both Paths)

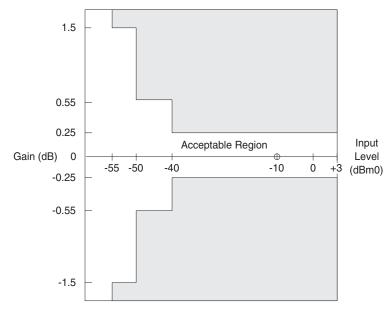
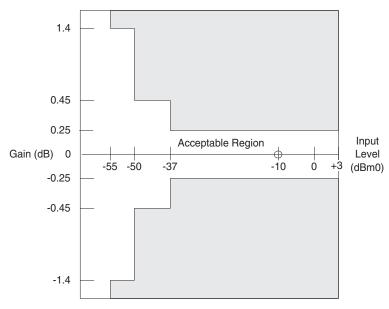


Figure 8.  $\mu$ -law Gain Linearity with Tone Input (Both Paths)





### **Total Distortion Including Quantizing Distortion**

The signal to total distortion ratio will exceed the limits shown in Figure 9 for either path when the input signal is a sine wave signal of frequency 1014 Hz.

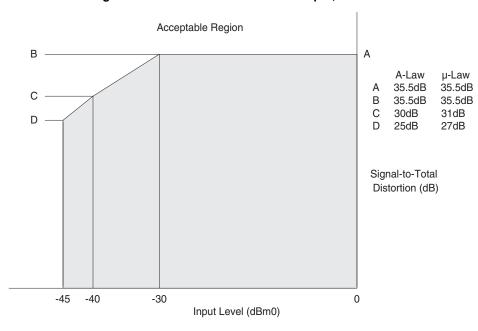


Figure 9. Total Distortion with Tone Input, Both Paths

### **Overload Compression**

Figure 10 shows the acceptable region of operation for input signal levels above the reference input power (0 dBm0). The conditions for this figure are:

(1) 1 dB <  $GX \le +12$  dB; (2) -12 dB  $\le GR < -1$  dB; (3) Digital voice output connected to digital voice input; and (4) measurement analog to analog.

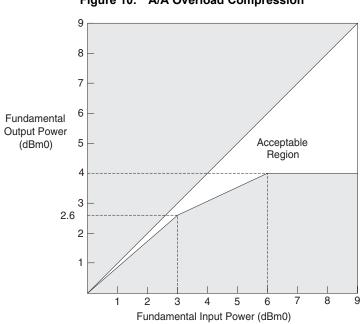


Figure 10. A/A Overload Compression



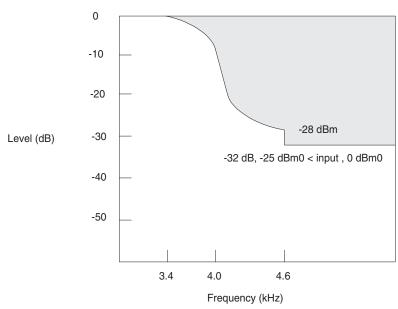
### **Discrimination Against Out-of-Band Input Signals**

When an out-of-band sine wave signal with frequency and level A is applied to the analog input, there may be frequency components below 4 kHz at the digital output which are caused by the out-of-band signal. These components are at least the specified dB level below the level of a signal at the same output originating from a 1014 Hz sine wave signal with a level of A dBm0 also applied to the analog input. The minimum specifications are shown in the following table

Table 2. Minimum Specifications for Out-of-Band Input Signals

Frequency of Out-of-Band Signal	Amplitude of Out-of-Band Signal	Level below A
16.6 Hz < f < 45 Hz	-25 dBm0 < A ≤ 0 dBm0	18 dB
45 Hz < f < 65 Hz	-25 dBm0 < A ≤ 0 dBm0	25 dB
65 Hz < f < 100 Hz	-25 dBm0 < A ≤ 0 dBm0	10 dB
3400 Hz < f < 4600 Hz	-25 dBm0 < A ≤ 0 dBm0	see Figure 11
4600 Hz < f < 100 kHz	-25 dBm0 < A ≤ 0 dBm0	32 dB

Figure 11. Discrimination Against Out-of-Band Signals



#### Note:

The attenuation of the waveform below amplitude A between 3400 Hz and 4600 Hz is given by the formula:

Attenuation (db) = 
$$14 - 14 \sin \frac{\pi (4000 - f)}{1200}$$

## Spurious Out-of-Band Signals at the Analog Output

With PCM code words representing a sine wave signal in the range of 300 Hz to 3400 Hz at a level of 0 dBm0 applied to the digital input, the level of the spurious out-of-band signals at the analog output is less than the limits shown below.

Table 3. Limits for Spurious Out-of-Band Signals

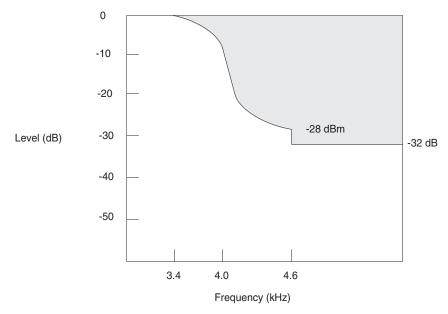
Frequency	Level
4.6 kHz to 40 kHz	-32 dBm0
40 kHz to 240 kHz	-46 dBm0
240 kHz to 1 MHz	–36 dBm0

With code words representing any sine wave signal in the range 3.4 kHz to 4.0 kHz at a level of 0 dBm0 applied to the digital input, the level of the signals at the analog output are below the limits in Figure 12. The amplitude of the spurious out-of-band signals between 3400 Hz and 4600 Hz is given by the formula:

$$A = -14 - 14 \sin \frac{\pi (f - 4000)}{1200} dBm0$$



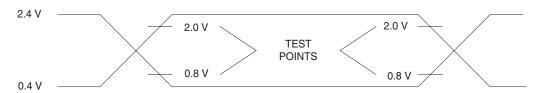
Figure 12. Spurious Out-of-Band Signals



### **SWITCHING CHARACTERISTICS**

## **PCM Switching Characteristics**

Figure 13. PCM Switching Characteristics



 $VCC = 3.3 \text{ V} \pm 5\%$ , AGND = DGND = 0 V.



### **Microprocessor Interface**

Min and max values are valid for all digital outputs with a 100 pF load, except DIO,DXA,  $\overline{\text{INT}}$ , TSCA, TSCB and DXB which are valid with 150 pF loads.

No.	Symbol	Parameter	Min	Тур	Max	Unit	Note
1	t <sub>DCY</sub>	Data clock period	122				
2	t <sub>DCH</sub>	Data clock HIGH pulse width	48				1
3	t <sub>DCL</sub>	Data clock LOW pulse width	48				1
4	t <sub>DCR</sub>	Rise time of clock			15		
5	t <sub>DCF</sub>	Fall time of clock			15		
6	t <sub>ICSS</sub>	Chip select setup time, Input mode	30		t <sub>DCY</sub> -10	ns	
7	t <sub>ICSH</sub>	Chip select hold time, Input mode	0		t <sub>DCH</sub> -20	1	
8	t <sub>ICSL</sub>	Chip select pulse width, Input mode		7.5t <sub>DCY</sub>			7
9	t <sub>ICSO</sub>	Chip select off time, Input mode					1,6
10	t <sub>IDS</sub>	Input data setup time	25				5
11	t <sub>IDH</sub>	Input data hold time	30				
13	t <sub>ocss</sub>	Chip select setup time, Output mode	30		t <sub>DCY</sub> -10		
14	t <sub>ocsh</sub>	Chip select hold time, Output mode			t <sub>DCH</sub> -20		
15	t <sub>ocsl</sub>	Chip select pulse width, Output mode		8t <sub>DCY</sub>			
16	tocso	Chip select off time, output Mode	2000			ns	1,6
17	t <sub>ODD</sub>	Output data turn on delay			50	1 115	
18	t <sub>ODH</sub>	Output data hold time	3			1	
19	t <sub>ODOF</sub>	Output data turn off delay			50	1	
20	t <sub>ODC</sub>	Output data valid	0		50	1	

### **PCM Interface**

No.	Symbol	Parameter	Min.	Тур	Max	Unit	Note
22	t <sub>PCY</sub>	PCM clock period	0.122		7.8125	μs	2
23	t <sub>PCH</sub>	PCM clock HIGH pulse width	48				
24	t <sub>PCL</sub>	PCM clock LOW pulse width	48				
25	t <sub>PCF</sub>	Fall time of clock			15		
26	t <sub>PCR</sub>	Rise time of clock			15		
27	t <sub>FSS</sub>	FS setup time	30		t <sub>PCY</sub> -30		
28	t <sub>FSH</sub>	FS hold time	50				
29	t <sub>TSD</sub>	Delay to TSCX valid	5		80	ns	3
30	t <sub>TSO</sub>	Delay to TSCX off	5			115	4
31	t <sub>DXD</sub>	PCM data output delay	5		70		
32	t <sub>DXH</sub>	PCM data output hold time	5		70		
33	t <sub>DXZ</sub>	PCM data output delay to high-Z	10		70		4
34	t <sub>DRS</sub>	PCM data input setup time	25				
35	t <sub>DRH</sub>	PCM data input hold time	5				
36	t <sub>FST</sub>	PCM or frame sync jitter time	-97		97		



### **Master Clock:**

For a 2.048 mHz  $\pm$  100 PPM, 4.096 mHz  $\pm$  100 PPM, or 8.192  $\pm$  100 PPM operation:

No.	Symbol	Parameter	Min	Тур	Max	Unit	No
37	t <sub>MCY</sub>	Period	122		7812	ns	2,8
38	t <sub>MCR</sub>	Rise time of clock			15		
39	t <sub>MCF</sub>	Fall time of clock			15		
40	t <sub>MCH</sub>	MCLK HIGH pulse width	48				
41	t <sub>MCL</sub>	MCLK LOW pulse width	48				

#### Note:

- 1. DCLK may be stopped in the HIGH or LOW state indefinitely without loss of information. When  $\overline{CS}$  makes a transition to the High state, the last byte received will be interpreted by the Microprocessor Interface logic.
- 2. The PCM clock (PCLK) frequency must be an integer multiple of the frame sync (FS) frequency and synchronous to the MCLK frequency. The actual PCLK rate is dependent on the number of channels allocated within a frame. A PCLK of 1.544 mHz can be used for standard US transmission systems. The minimum clock frequency is 128 kHz.
- TSCA is delayed from FS by a typical value of N t<sub>PCY</sub>, where N is the value stored in the time/clock slot register.
- t<sub>TSO</sub> is defined as the delay time the output driver turns off after the PCLK transaction. The actual delay time is dependent on the load circuitry. The maximum load capacitance on TSCX is 150 pF and the minimum pull-up resistance is 360 Ω.
- 5. The first data bit is enabled on the falling edge of  $\overline{\text{CS}}$  or on the falling edge of DCLK, whichever occurs last.
- 6. If the MPI is being accessed while the MCLK (or PCLK if combined with MCLK) input is not active, a Chip Select Off time of 20 μs is required when accessing coefficient RAM.
- 7. If chip select is held low for 16 or more DCLK cycles, the part will reset.
- 8. MCLK's frequency can range from 128 kHz to 8.192 MHz and can be set with: Write/Read Device Configuration Register 1, and if necessary Write/Read Master Clock Correction Register.



## **PCM Switching Waveforms**

Figure 14. Master Clock Timing

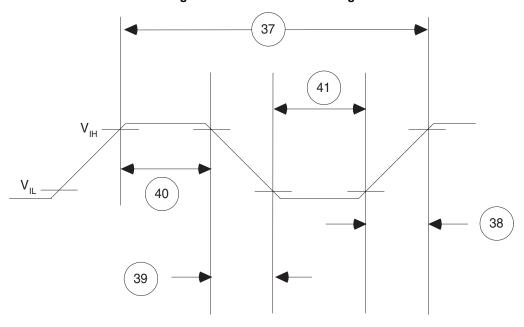


Figure 15. Microprocessor Interface (Input Mode)

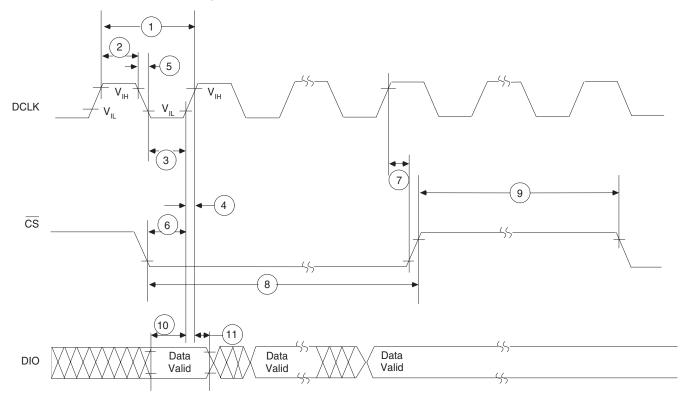




Figure 16. Microprocessor Interface (Output Mode)

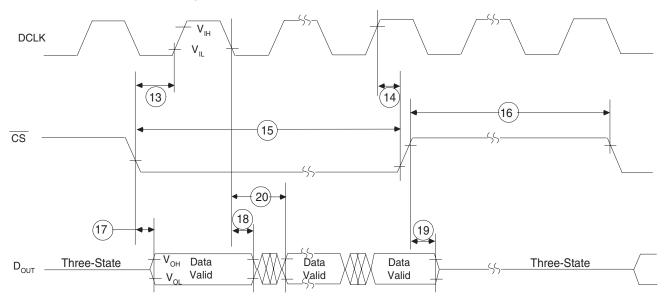
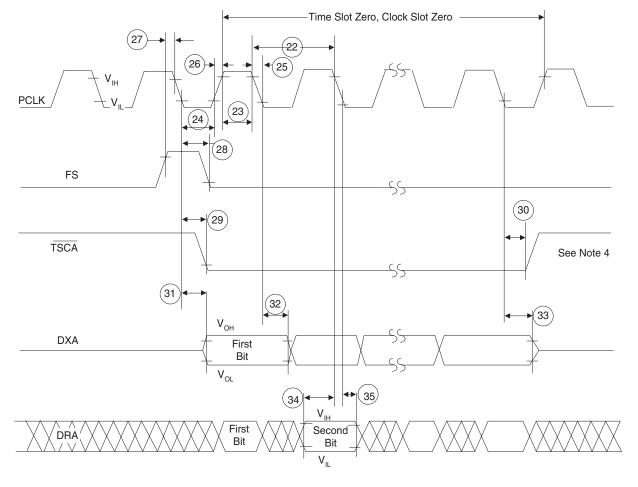
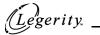


Figure 17. PCM Highway Timing for XE = 0 (Transmit on Negative PCLK Edge)





Time Slot Zero, Clock Slot Zero (27 (26 25 23 24 FS (28) (30 29 TSCA See Note 4 (31) (32) **√**(33 DXA First Bit  ${\bf V}_{\rm OL}$ (35) (34)  $V_{\text{IH}}$ First Bit Bit

Figure 18. PCM Highway Timing for XE = 1 (Transmit on Positive PCLK Edge)

## **GCI Timing Specifications**

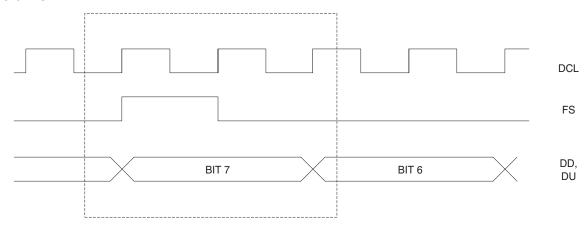
Symbol	Signal	Parameter	Min	Тур	Max	Unit
t <sub>R</sub> , t <sub>F</sub>	DCL	Rise/fall time			60	
t	DCL	Period, F <sub>DCL</sub> = 2048 kHz	478		498	
t <sub>DCL</sub>	DCL	F <sub>DCL</sub> = 4096 kHz	239		249	
t <sub>WH</sub> , t <sub>WL</sub>	DCL	Pulse width	90			
t <sub>R</sub> , t <sub>F</sub>	FS	Rise/fall time			60	
t <sub>SF</sub>	FS	Setup time	70		t <sub>DCL</sub> -50	ns
t <sub>HF</sub>	FS	Hold time	50			115
t <sub>WFH</sub>	FS	High pulse width	130			
t <sub>DDC</sub>	DU	Delay from DCL edge			100	
t <sub>DDF</sub>	DU	Delay from FS edge			150	
t <sub>SD</sub>	DD	Data setup	twH+20			
t <sub>HD</sub>	DD	Data hold	50			
t <sub>RST</sub>	RST	Reset pulse width	1.1			ms

### Note:

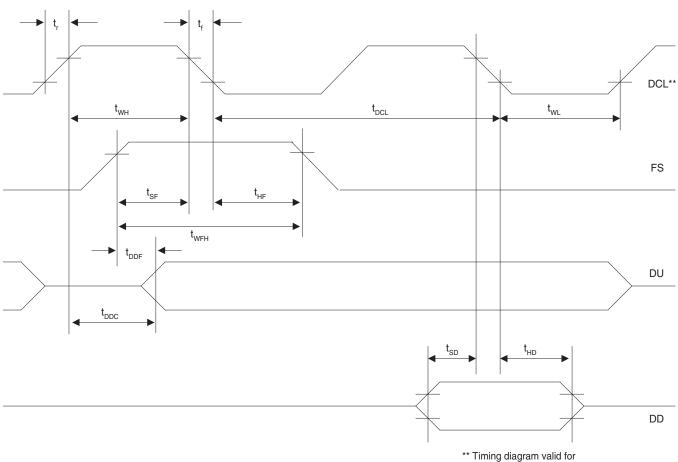
- 1. The Data Clock (DCL) can be stopped in the high or low state without loss of information.
- 2. A temporary stoppage of DCL must not put the ISLAC into a state in which it does not respond to a software reset command.
- 3. All frequency-dependent specifications are guaranteed for clock frequencies within ±100 PPM from nominal.



### **GCI Waveforms**



DETAIL A

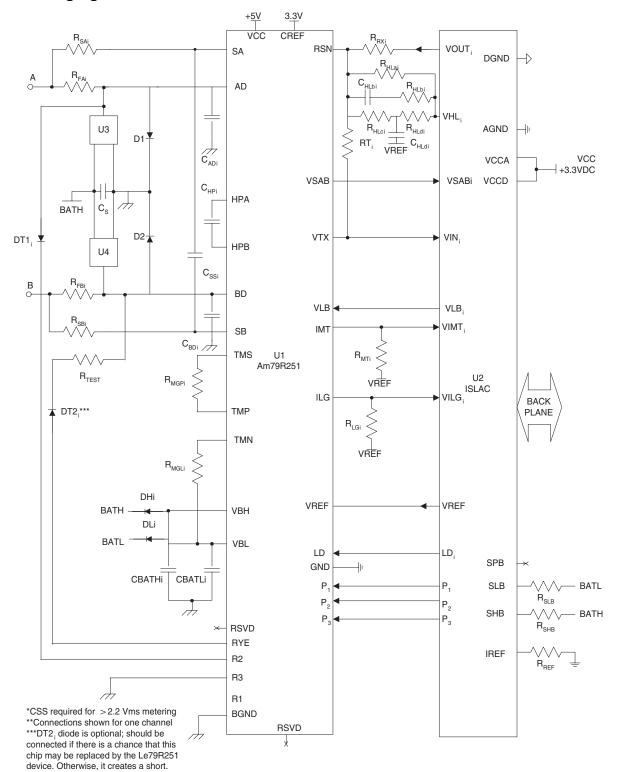


\*\* Timing diagram valid for F<sub>DCL</sub> = 2048 or 4096 KHz



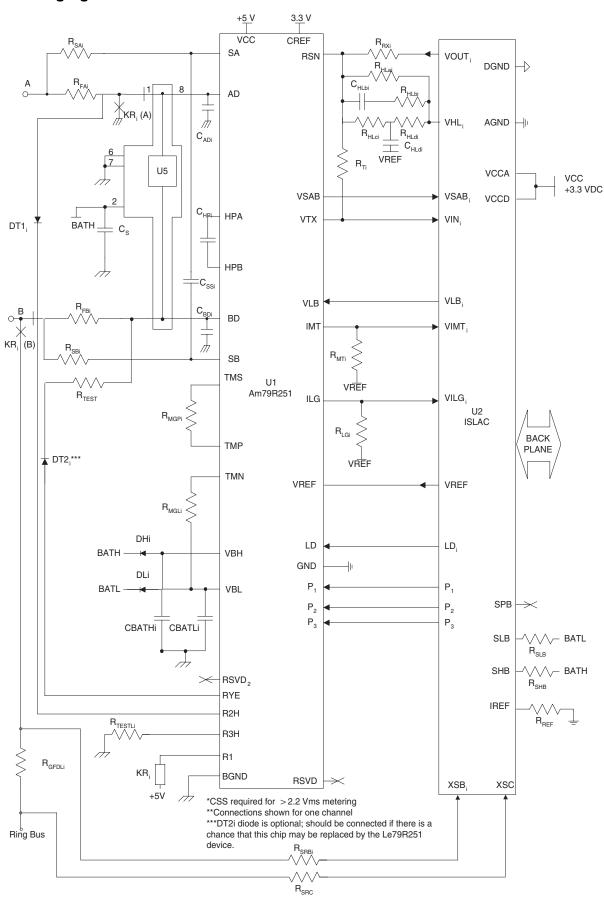
## **APPLICATION CIRCUITS**

## **Internal Ringing Linecard Schematic**





## **External Ringing Linecard Schematic**





### **LINECARD PARTS LIST**

The following list defines the parts and part values required to meet target specification limits for channel i of the linecard (i = 1, 2, 3, 4)..

Item	Туре	Value	Tol.	Rating	Comments	
U1	Am79R241				ISLIC device	
U2	Am79X22xx				ISLAC device	
U3, U4	B1100CC			100 V	TECCOR Battrax protector	
U5	TISP61089A				Transient Voltage Suppressor, Power Innovations	
D1, D2	Diode	1 A		100 V		
DH <sub>i</sub> , DL <sub>i</sub> , DT1 <sub>i</sub> , DT2 <sub>i</sub> <sup>4</sup>	Diode	100 mA		100 V	50 ns	
R <sub>FAi</sub> , R <sub>FBi</sub>	Resistor	50 Ω	2%	2 W	Fusible PTC protection resistors	
R <sub>SAi</sub> , R <sub>SBi</sub>	Resistor	200 kΩ	2%	1/4 W	Sense resistors	
R <sub>Ti</sub>	Resistor	80.6 kΩ	1%	1/10 W		
R <sub>RXi</sub>	Resistor	100 kΩ	1%	1/10 W		
R <sub>REF</sub>	Resistor	69.8 kΩ	1%	1/10 W	Current reference	
R <sub>MGLi</sub> , R <sub>MGPi</sub>	Resistor	1 kΩ	5%	1 W	Thermal management resistors	
R <sub>SHB</sub> , R <sub>SLB</sub>	Resistor	750 kΩ	1%	1/8 W		
R <sub>HLai</sub>	Resistor	40.2 kΩ	1%	1/10 W		
R <sub>HLbi</sub>	Resistor	4.32 kΩ	1%	1/10 W		
R <sub>HLci</sub>	Resistor	2.87 kΩ	1%	1/10 W		
R <sub>HLdi</sub>	Resistor	2.87 kΩ	1%	1/10 W		
C <sub>HLbi</sub>	Capacitor	3.3 nF	10 %	10 V	Not Polarized	
C <sub>HLdi</sub>	Capacitor	0.82 mF	10 %	10 V	Ceramic	
R <sub>MTi</sub>	Resistor	3.01 kΩ	1%	1/8 W		
R <sub>LGi</sub>	Resistor	6.04 kΩ	1%	1/8 W		
R <sub>TEST</sub>	Resistor	2 kΩ	1%	1 W	Test board	
C <sub>ADi</sub> , C <sub>BDi</sub> <sup>1</sup>	Capacitor	22 nF	10%	100 V	Ceramic, not voltage sensitive	
C <sub>BATHi</sub> , C <sub>BATLi</sub>	Capacitor	100 nF	20%	100 V	Ceramic	
C <sub>HPi</sub>	Capacitor	22 nF	20%	100 V	Ceramic	
C <sub>Si</sub> <sup>1</sup>	Capacitor	100 nF	20%	100 V	Protector speed up capacitor	
C <sub>SSi</sub> <sup>3</sup>	Capacitor	56 pF	5%	100 V	Ceramic	
Components for Exter	nal Ringing	1	ı	I	L	
R <sub>GFDi</sub>	Resistor	510 Ω	2%	2 W	1.2 W typ	
R <sub>SRBi</sub> , R <sub>SRc</sub>	Resistor	750 kΩ	2%	1/4 W	Matched to within 0.2% for initial tolerance and 0 to 70° C ambient temperature range. <sup>2</sup> 17 mW typ	
K <sub>Ri</sub>	Relay	5 V Coil			DPDT	

#### Note:

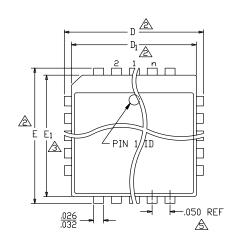
- 1. Value can be adjusted to suit application.
- 2. Can be less stringent for relaxed ring-trip requirements.
- 3. Required for metering > 2.2 Vrms, otherwise must be omitted.
- 4. DT2<sub>i</sub> is optional Should be put if there is a chance that this chip may be replaced by Am79R251.

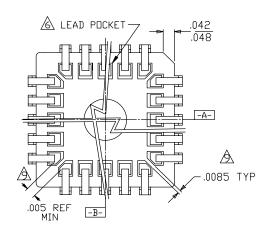


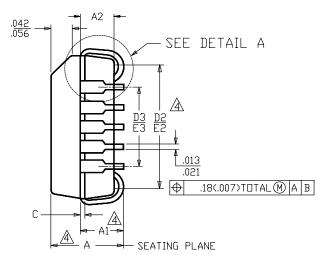
### **PHYSICAL DIMENSIONS**

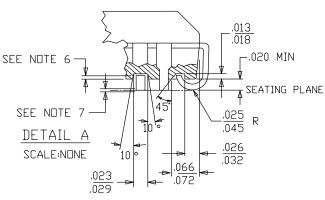
### 68-Pin PLCC











Dwg rev. AN; 8/00

PACKAGE	PL 068		
JEDEC	M□-04	47(B)AE	
SYMBOL	MIN	MAX	
Α	.165	.180	
A1	.090	.130	
A2	.062	.083	
D	.985	.995	
D1	.950	.956	
D2	.890	.930	
D3	.800	REF	
E	.985	.995	
E1	.950	.956	
E2	.890	.930	
E3	.800	REF	
С	.007	.013	

NOTES: (UNLESS OTHERWISE SPECIFIED)

- 1. ALL DIMENSIONS ARE IN INCHES.
- DIMENSIONS "D" AND "E" ARE MEASURED FROM DUTERMOST POINT.
- DIMENSIONS D1 AND E1 DO NOT INCLUDE CORNER MOLD FLASH. ALLOWABLE CORNER MOLD FLASH IS .010 INCH
- A DIMENSIONS "A", "A1", "D2" AND "E2" ARE
- MEASURED AT THE POINTS OF CONTACT TO BASE PLANE  $\triangle$  LEAD SPACING AS MEASURED FROM CENTERLINE
- TO CENTERLINE SHALL BE WITHIN ±.005 INCH.

  J-LEAD TIPS SHOULD BE LOCATED INSIDE
- THE "POCKET.

  7. LEAD COPLANARITY SHALL BE WITHIN .004 INCH AS MEASURED FROM SEATING PLANE, COPLANARITY IS
- MEASURED PER AMD 06-500.

  8. LEAD TWEEZE SHALL BE WITHIN .0045 INCH ON EACH SIDE AS MEASURED FROM A VERTICAL FLAT PLANE.
  TWEEZE IS MEASURED PER AMD 06-500.
- LEAD POCKET MAY BE RECTANGULAR (AS SHOWN) OR OVAL.

  IF CORNER LEAD POCKETS ARE CONNECTED THEN 5 MILS

  MINIMUM CORNER LEAD SPACING IS REQUIRED.



### 64-Pin Thin Quad Flat Pack (TQFP)

**JEDEC** 

SYMBOL

A1

Α2

D

D1

Ε

E1

L

Ν

ρ

b

b1

MIN

0.05

0.95

MS-026 (C) ACD

 $N\square M$ 

1.00

BSC

BSC

RSC

BSC

0.75

0.27

0.23

12.00

10.00

12.00

10.00

0.60

64

0.50 BSC.

0.22

0.20

0.45

0.17

0.17

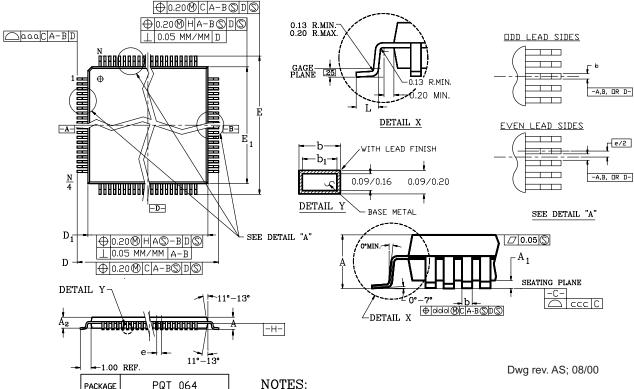
MAX

1.20

0.15

1.05

**PQT 064** 



### NOTES:

- ALL DIMENSIONS AND TOLERANCES CONFORM TO ANSI Y14.5M-1982.
- DATUM PLANE -H- IS LOCATED AT THE MOLD PARTING LINE AND IS COINCIDENT WITH THE BOTTOM OF THE LEAD WHERE THE LEAD EXITS THE PLASTIC BODY.
- 3. DIMENSIONS "D1" AND "E1" DO NOT INCLUDE MOLD PROTRUSION. ALLOWABLE PROTRUSION IS 0.254mm PER SIDE. DIMENSIONS "D1" AND "E1" INCLUDE MOLD MISMATCH AND ARE DETERMINED AT DATUM PLANE -H-
- 4. DIMENSION "B" DOES NOT INCLUDE DAMBAR PROTRUSION. ALLOWABLE DAMBAR PROTRUSION SHALL BE 0.08mm TOTAL IN EXCESS OF THE 6 DIMENSION AT MAXIMUM MATERIAL CONDITION. DAMBAR CAN NOT BE LOCATED ON THE LOWER RADIUS OR THE FOOT.
- 5. CONTROLLING DIMENSIONS: MILLIMETER.
- 6. DIMENSIONS "D" AND "E" ARE MEASURED FROM BOTH INNERMOST AND OUTERMOST POINTS.
- 7. DEVIATION FROM LEAD-TIP TRUE POSITION SHALL BE WITHIN ±0.076 MM. FOR PITCH >0.5mm.
  - AND WITHIN  $\pm 0.04$  FOR PITCH  $\leq 0.5$  mm.
- LEAD COPLANARITY SHALL BE WITHIN: (REFER TO 06-500) 1- 0.10 mm FOR DEVICES WITH LEAD PITCH OF 0.65-0.80 mm. 2- 0.076 mm FOR DEVICES WITH LEAD PITCH OF 0.50 mm. COPLANARITY IS MEASURED PER SPECIFICATION 06-500.
- 9. HALF SPAN (CENTER OF PACKAGE TO LEAD TIP) SHALL BE 15.30±.165{.602"±.0065"}
- 10. "N" IS THE TOTAL NUMBER OF TERMINALS.
- 11. THE TOP OF PACKAGE IS SMALLER THAN THE BOTTOM OF THE PACKAGE BY 0.15 MILLIMETERS.
- THIS OUTLINE CONFORMS TO JEDEC PUBLICATION 95 REGISTRATION MS-026.
- THE 160 LEAD IS A COMPLIANT DEPOPULATION OF THE 176 LEAD MS-026 VARIATION BGA.

#### CCC0.08 ddd 0.08 aaa 0.20

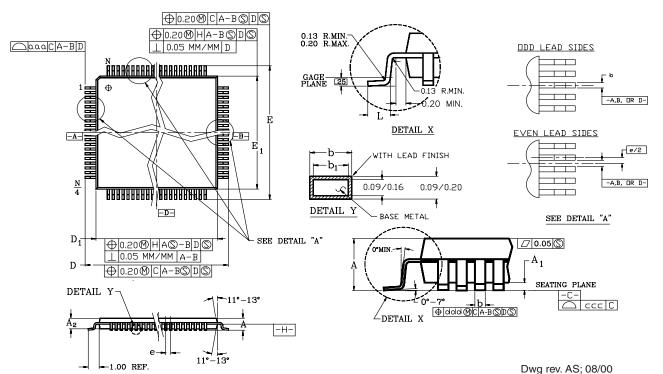
TOLERANCES OF FORM

AND POSITION



### 80-Pin Thin Quad Flat Pack (TQFP)

**PQT 080** 



PACKAGE	F	PQT 080			
JEDEC	M2-0	26 (C)	ADD		
SYMBOL	MIN	NDM	MAX		
Α	_	_	1.20		
A1	0.05	_	0.15		
A2	0.95	1.00	1.05		
D	14.	00 BS	:C		
D1	12.	00 BS	:C		
E	14.00 BSC				
E1	12.00 BSC				
L	0.45	0.60	0.75		
N		80			
е	0.5	0 BAS	SIC		
b	0.17	0.22	0.27		
b1	0.16	0.20	0.23		
TOLERANCES OF FORM AND POSITION					
ccc	_	_	0.08		
ddd			0.08		
aaa	_	_	0.20		

#### NOTES:

- . ALL DIMENSIONS AND TOLERANCES CONFORM TO ANSI Y14.5M-1982.
- DATUM PLANE —H— IS LOCATED AT THE MOLD PARTING LINE AND IS COINCIDENT WITH THE BOTTOM OF THE LEAD WHERE THE LEAD EXITS THE PLASTIC BODY.
- 3. DIMENSIONS "D1" AND "E1" DO NOT INCLUDE MOLD PROTRUSION. ALLOWABLE PROTRUSION IS 0.254mm PER SIDE. DIMENSIONS "D1" AND "E1" INCLUDE MOLD MISMATCH AND ARE DETERMINED AT DATUM PLANE —H—
- 4. DIMENSION "B" DOES NOT INCLUDE DAMBAR PROTRUSION.
  ALLOWABLE DAMBAR PROTRUSION SHALL BE 0.08mm TOTAL IN
  EXCESS OF THE 6 DIMENSION AT MAXIMUM MATERIAL CONDITION.
  DAMBAR CAN NOT BE LOCATED ON THE LOWER RADIUS OR THE
  FOOT.
- 5. CONTROLLING DIMENSIONS: MILLIMETER.
- DIMENSIONS "D" AND "E" ARE MEASURED FROM BOTH INNERMOST AND OUTERMOST POINTS.
- 7. DEVIATION FROM LEAD—TIP TRUE POSITION SHALL BE WITHIN  $\pm 0.076$  MM. FOR PITCH >0.5 mm.
  - AND WITHIN  $\pm 0.04$  FOR PITCH  $\leq 0.5$  mm.
- LEAD COPLANARITY SHALL BE WITHIN: (REFER TO 06-500)
   1- 0.10 mm FOR DEVICES WITH LEAD PITCH OF 0.65-0.80 mm.
   2- 0.076 mm FOR DEVICES WITH LEAD PITCH OF 0.50 mm.
   COPLANARITY IS MEASURED PER SPECIFICATION 06-500.
- 9. HALF SPAN (CENTER OF PACKAGE TO LEAD TIP) SHALL BE 15.30±.165{.602"±.0065"}
- 10. "N" IS THE TOTAL NUMBER OF TERMINALS.
- 11. THE TOP OF PACKAGE IS SMALLER THAN THE BOTTOM OF THE PACKAGE BY 0.15 MILLIMETERS.
- 12. THIS OUTLINE CONFORMS TO JEDEC PUBLICATION 95 REGISTRATION MS-026.
- 13. THE 160 LEAD IS A COMPLIANT DEPOPULATION OF THE 176 LEAD MS-026 VARIATION BGA.



### REVISION SUMMARY

### Revision A to Revision B

Revision A was a condensed version of the datasheet while Revision B contains the full version.

#### Revision B to RevisionC

• Page 14, Linecard Parts List, Rows CHLbi and CHLdi: switched the numbers in the "Values" column.

#### Revision C to Revision D

- Page 12, Figure 5, DT1i was added and the last note was modified.
- Page 14, Linecard Parts List, Item U3, U4 Type information was changed.

### **Revision D to Revision E**

- · Updated document to new format.
- In Pin Descriptions Table, changed I/O status of TSCB to "O"
- In DC Specifications Table, the following changes were made:
  - changed information for "Quad ISLAC Power Dissipation".
  - Updated "Min", "Max", and "Typ" values for Input Leakage Current (VIN1-4, VSAB1-4, VILG1-4, VIMT1-4, VSAB1-4)
  - Updated "Min", "Max", and "Typ" values for Output Leakage Current (VOUT1-4 or VLB1-4)
- Made the following changes to the Transmission and Signaling Specifications table:
  - Reformatted table
  - For Insertion Loss, changed one of the "A-D + D-A" items to "A-D D-A"
  - For PSRR, added "A-D" to item; added Min value of 37
  - For Image frequency, added "D-A" to item; added Min value of 37
  - For DISN gain accuracy, changed conditions to: Gdisn = -0.9375 to 0.9375; Vin = 0 dBm0
  - For Crosstalk TX or RX to TX; TX or RX to RX, added 0dBm0 to conditions
- Divided Transmit and Receive Path Attenuation vs. Frequency graphic into two separate graphics
- In the "Intermodulation Distortion" section, changed text to "TBD"
- Updated PCM Switching Characteristics graphic.
- In "Master Clock" section, added information for t<sub>MCY</sub>; added Note 8
- · Updated External Ringing Linecard schematic.
- · Added a linecard parts list.
- Updated all "Physical Dimensions" graphics.

### Revision E to Revision F

- In Pin Descriptions Table, pins LD1-LD4, changed description for logic 0 to < 0.4 V; changed description for logic 1 to (V<sub>CC</sub> - 0.4 V)
- In DC Specifications Table, item 6, removed "Output current" row; inserted "Medium Voltage" row.
- · Subscripted channel numbers throughout document.

#### Revision F to G

· Corrected physical dimensions for 64-Pin TQFP.



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