1 Megabit

 $(128K \times 8)$

PEROM

3-Volt Only

CMOS Flash

Features

- Single 3.3 V ± 10% Supply
- Three-Volt-Only Read and Write Operation
- Software Protected Programming
- Low Power Dissipation
 - 15 mA Active Current
- 20 µA CMOS Standby Current Fast Read Access Time - 200 ns
- **Sector Program Operation**
 - Single Cycle Reprogram (Erase and Program)
 - 1024 Sectors (128 bytes/sector)

internal Address and Data Latches for 128 Bytes

- Fast Sector Program Cycle Time 20 ms Max.
- **Internal Program Control and Timer**
- **DATA** Polling for End of Program Detection
- Typical Endurance > 10,000 Cycles
- **CMOS and TTL Compatible Inputs and Outputs**
- **Commercial and Industrial Temperature Ranges**

Description

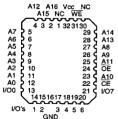
The AT29LV010 is a three-volt-only in-system Flash programmable erasable read only memory (PEROM). Its one megabit of memory is organized as 131,072 words by 8 bits. Manufactured with Atmel's advanced nonvolatile CMOS technology, the device offers access times to 200 ns with power dissipation of just 54 mW over the commercial temperature range. When the device is deselected, the CMOS standby current is less than 20 µA. The device endurance is such that any sector can typically be written to in excess of 10,000 times.

(continued)

Pin Configurations

Function
Addresses
Chip Enable
Output Enable
Write Enable
Data Inputs/Outputs
No Connect

PLCC, LCC Top View



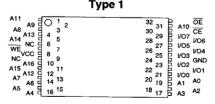
Note: PLCC package pin 30 is a DON'T CONNECT. Contact Atmel for availability of PLCC package with pin 30 as a NO CONNECT.

DIP Top View



TSOP Top View

Type 1





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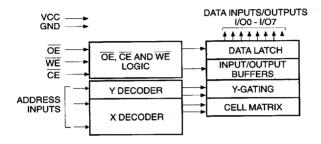
Description (Continued)

To allow for simple in-system reprogrammability, the AT29LV010 does not require high input voltages for programming. Three-volt-only commands determine the operation of the device. Reading data out of the device is similar to reading from an EPROM. Reprogramming the AT29LV010 is performed on a sector basis; 128 bytes of data are loaded into the device and then simultaneously programmed.

During a reprogram cycle, the address locations and 128 bytes of data are captured at microprocessor speed and internally

latched, freeing the address and data bus for other operations. Following the initiation of a program cycle, the device will automatically erase the sector and then program the latched data using an internal control timer. The end of a program cycle can be detected by DATA polling of I/O7. Once the end of a program cycle has been detected, a new access for a read or program can begin.

Block Diagram



Device Operation

READ: The AT29LV010 is accessed like an EPROM. When \overline{CE} and \overline{OE} are low and \overline{WE} is high, the data stored at the memory location determined by the address pins is asserted on the outputs. The outputs are put in the high impedance state whenever \overline{CE} or \overline{OE} is high. This dual-line control gives designers flexibility in preventing bus contention.

SOFTWARE DATA PROTECTION PROGRAMMING: The AT29LV010 has 1024 individual sectors, each 128 bytes. Using the software data protection feature, byte loads are used to enter the 128 bytes of a sector to be programmed. The AT29LV010 can only be programmed or reprogrammed using the software data protection feature. The device is programmed on a sector basis. If a byte of data within the sector is to be changed, data for the entire 128-byte sector must be loaded into the device. The AT29LV010 automatically does a sector erase prior to loading the data into the sector. An erase command is not required.

Software data protection protects the device from inadvertent programming. A series of three program commands to specific addresses with specific data must be presented to the device before programming may occur. The same three program commands must begin each program operation. All software program commands must obey the sector program timing specifications. Power transitions will not reset the software data protection feature, however the software feature will guard against inadvertent program cycles during power transitions.

Any attempt to write to the device without the three-byte command sequence will start the internal write timers. No data will be written to the device; however, for the duration of twc, a read operation will effectively be a polling operation.

After the software data protection's three-byte command code is given, a byte load is performed by applying a low pulse on the WE or CE input with CE or WE low (respectively) and OE high. The address is latched on the falling edge of CE or WE, whichever occurs last. The data is latched by the first rising edge of CE or WE.

The 128 bytes of data must be loaded into each sector. Any byte that is not loaded during the programming of its sector will be erased to read FFh. Once the bytes of a sector are loaded into the device, they are simultaneously programmed during the internal programming period. After the first data byte has been loaded into the device, successive bytes are entered in the same manner. Each new byte to be programmed must have its high to low transition on WE (or CE) within 150 µs of the low to high transition of WE (or CE) of the preceding byte. If a high to low transition is not detected within 150 µs of the last low to high transition, the load period will end and the internal programming period will start. A7 to A16 specify the sector address. The sector address must be valid during each high to low transition of \overline{WE} (or \overline{CE}). A0 to A6 specify the byte address within the sector. The bytes may be loaded in any order; sequential loading is not required. Once a programming operation has been initiated, and for the duration of twc, a read operation will effectively be a polling operation.

(continued)

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AT29LV010

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Device Operation (Continued)

HARDWARE DATA PROTECTION: Hardware features protect against inadvertent programs to the AT29LV010 in the following ways: (a) V_{CC} sense—if V_{CC} is below 1.8 V (typical), the program function is inhibited. (b) V_{CC} power on delay—once V_{CC} has reached the V_{CC} sense level, the device will automatically time out 10 ms (typical) before programming. (c) Program inhibit—holding any one of \overline{OE} low, \overline{CE} high or \overline{WE} high inhibits program cycles. (d) Noise filter—pulses of less than 15 ns (typical) on the \overline{WE} or \overline{CE} inputs will not initiate a program cycle.

INPUT LEVELS: While operating with a 3.3 V $\pm 10\%$ power supply, the address inputs and control inputs $(\overline{OE}, \overline{CE} \text{ and } \overline{WE})$ may be driven from 0 to 5.5 V without adversely affecting the operation of the device. The I/O lines can only be driven from 0 to 3.6 volts.

PRODUCT IDENTIFICATION: The product identification mode identifies the device and manufacturer as Atmel. It may be accessed by hardware or software operation. The hardware operation mode can be used by an external programmer to identify the correct programming algorithm for the Atmel product. In addition, users may wish to use the software product identification mode to identify the part (i.e. using the device code), and have the system software use the appropriate sector size for program operations. In this manner, the user can have a common

board design for 256K to 4-megabit densities and, with each density's sector size in a memory map, have the system software apply the appropriate sector size.

For details, see Operating Modes (for hardware operation) or Software Product Identification. The manufacturer and device code is the same for both modes.

DATA POLLING: The AT29LV010 features DATA polling to indicate the end of a program cycle. During a program cycle an attempted read of the last byte loaded will result in the complement of the loaded data on I/O7. Once the program cycle has been completed, true data is valid on all outputs and the next cycle may begin. DATA polling may begin at any time during the program cycle.

TOGGLE BIT: In addition to DATA polling the AT29LV010 provides another method for determining the end of a program or erase cycle. During a program or erase operation, successive attempts to read data from the device will result in I/O6 toggling between one and zero. Once the program cycle has completed, I/O6 will stop toggling and valid data will be read. Examining the toggle bit may begin at any time during a program cycle. OPTIONAL CHIP ERASE MODE: The entire device can be

erased by using a six-byte software code. Please see Software

Chip Erase application note for details.

Absolute Maximum Ratings*

Temperature Under Bias55°C to +125°C
Storage Temperature65°C to +150°C
All Input Voltages (including N.C. Pins) with Respect to Ground0.6 V to +6.25 V
All Output Voltages with Respect to Ground0.6 V to V _{CC} +0.6 V
Voltage on A9 (including N.C. Pins)

*NOTICE: Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. This is a stress rating only and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

Pin Capacitance $(f = 1 \text{ MHz}, T = 25^{\circ}\text{C})^{(1)}$

with Respect to Ground-0.6 V to +13.5 V

	Тур	Мах	Units	Conditions
CIN	44	6	pF	ViN = 0 V
Cout	8	12	pF	Vout = 0 V

Note: 1. These parameters are characterized and not 100% tested.



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D.C. and A.C. Operating Range

	•	
	AT29LV010-20	AT29LV010-25
Com.	0°C - 70°C	0°C - 70°C
	-40°C - 85°C	-40°C - 85°C
	3.3 V ± 0.3 V	3.3 V ± 0.3 V
	Com.	AT29LV010-20 Com. 0°C - 70°C Ind. -40°C - 85°C

Operating Modes

perating wodes		ŌĒ	WE	Ai	VO
Mode	CE	OE			
Read	VIL _	VIL	ViH	Ai	D _{OUT}
Program ⁽²⁾	VIL	ViH	ViL	Ai	DIN
Standby/Write Inhibit	ViH	X ⁽¹⁾	Х	X	High Z
Program Inhibit	Χ	X	ViH		
Program Inhibit	Х	VIL	X		
Output Disable	X	ViH	X		High Z
Product Identification			.,	A1-A16 = V _{IL} , A9 = V _H ⁽³⁾ , A0 = V _{IL}	Manufacturer Code ⁽⁴⁾
Hardware	VIL	VIL	ViH	A1-A16 = V _{IL} , A9 = V _H ⁽³⁾ , A0 = V _{IH}	Device Code ⁽⁴⁾
/=\				A0 = VIL	Manufacturer Code ⁽⁴
Software ⁽⁵⁾				A0 = V _{IH}	Device Code ⁽⁴⁾

Notes: 1. X can be V_{IL} or V_{IH} .

2. Refer to A.C. Programming Waveforms.

3. $V_H = 12.0 \text{ V} \pm 0.5 \text{ V}$.

4. Manufacturer Code: 1F, Device Code: 35.

5. See details under Software Product Identification Entry/Exit.

D.C. Characteristics

Symbol	Parameter	Condition		Min	Max	Units
lui	Input Load Current	VIN = 0 V to VCC			1	μΑ
ILO	Output Leakage Current	V _{I/O} = 0 V to V _C C			1	μΑ
ILO			Com.		20	μΑ
Is _{B1}	V _{CC} Standby Current CMOS	$\overline{CE} = V_{CC} - 0.3 \text{ V to V}_{CC}$	Ind.		50	μΑ
ISB2	V _{CC} Standby Current TTL	CE = 2.0 V to Vcc			1	_mA
Icc	Vcc Active Current	f = 5 MHz; lout = 0 mA; V	cc = 3.6 V		15	m <u>A</u>
VIL	Input Low Voltage				0.6	V
VIH	Input High Voltage			2.0		V
Vol	Output Low Voltage	IOL = 1.6 mA; Vcc = 3.0 V	<u>'</u>		.45	V
Vol	Output High Voltage	$I_{OH} = -100 \mu A; V_{CC} = 3.0$	V	2.4		V

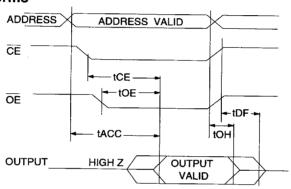
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A.C. Read Characteristics

		AT29L	V010-20	AT29L	V010-25	
Symbol	Parameter	Min	Max	Min	Max	Units
tacc	Address to Output Delay		200		250	ns
	CE to Output Delay		200		250	ns
	OE to Output Delay	0	100	0	120	ns
t _{DF} (3,4)	CE or OE to Output Float	0	50	0	60	ns
tон	Output Hold from OE, CE or Address, whichever occurred first	0		0		ns

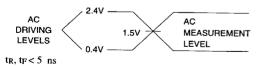
A.C. Read Waveforms^(1,2,3,4)



Notes:

- CE may be delayed up to t_{ACC} t_{CE} after the address transition without impact on t_{ACC}.
- OE may be delayed up to tce toe after the falling edge of CE without impact on tce or by tacc - toe after an address change without impact on tacc.
- 3. t_{DF} is specified from \overline{OE} or \overline{CE} whichever occurs first (C_L = 5pF).
- 4. This parameter is characterized and is not 100% tested.

Input Test Waveforms and Measurement Level



Output Test Load





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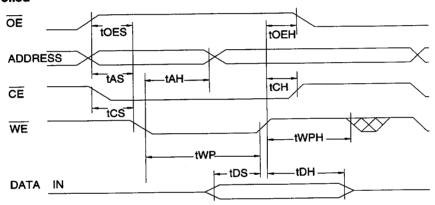


A.C. Byte Load Characteristics

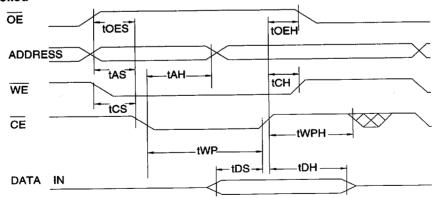
Symbol	Parameter	Min	Max	Units
tas, toes	Address, OE Set-up Time	10		ns
t _{AH}	Address Hold Time	100		ns
tcs	Chip Select Set-up Time	0		ns
tch	Chip Select Hold Time	0		ns
twp	Write Pulse Width (WE or CE)	200		ns
tos	Data Set-up Time	100		ns
ton,toen	Data, OE Hold Time	10		ns
twpH	Write Pulse Width High	200		ns

A.C. Byte Load Waveforms (1,2)

WE Controlled



CE Controlled



Notes:

- The software data protection commands must be applied prior to byte loads.
- A complete sector (128 bytes) should be loaded using these waveforms as shown in the Software Protected Byte Load waveforms (see previous page).

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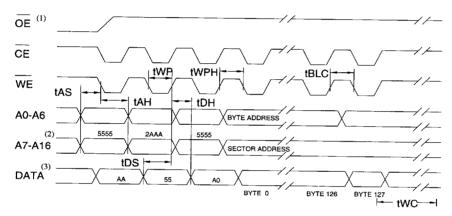
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Program Cycle Characteristics

Symbol	Parameter	Min	Max	Units
twc	Write Cycle Time		20	ms
tas	Address Set-up Time	10		ns
tah	Address Hold Time	100		ns
tos	Data Set-up Time	100		ns
tон	Data Hold Time	10		ns
twp	Write Pulse Width	200		ns
tBLC	Byte Load Cycle Time		150	μs
twen	Write Pulse Width High	200		ns

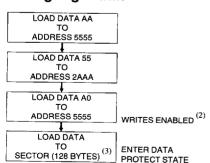
Software Protected Program Waveform (1,2,3)



Notes:

- 1. \overline{OE} must be high when \overline{WE} and \overline{CE} are both low.
- 2. A7 through A16 must specify the sector address during each high to low transition of WE (or CE) after the software code has been entered.
- 3. All bytes that are not loaded within the sector being programmed will be erased to FF.

Programming Algorithm (1)



PROTECT STATE

Notes for software program code:

- 1. Data Format: 1/07-1/00 (Hex); Address Format: A14-A0 (Hex).
- 2. Data Protect state will be re-activated at end of program cycle.
- 3. 128 bytes of data MUST BE loaded.



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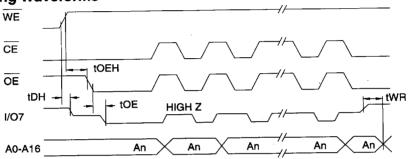
Data Polling Characteristics (1)

Symbol	Parameter	Min	Тур	Max	Units
tрн	Data Hold Time	10			ns
toeh	OE Hold Time	10			ns
toE	OE to Output Delay ⁽²⁾				ns
twn	Write Recovery Time	0			ns

Notes: 1. These parameters are characterized and not 100% tested.

2. See toE spec in A.C. Read Characteristics.

Data Polling Waveforms



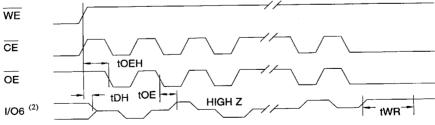
Toggle Bit Characteristics(1)

-				
Parameter	Min	Тур	Max	Units
Data Hold Time	10			ns
OE Hold Time	10			ns
OE to Output Delay ⁽²⁾				ns
OE High Pulse	150			ns
Write Recovery Time	0			ns
	Parameter Data Hold Time OE Hold Time OE to Output Delay ⁽²⁾ OE High Pulse	Parameter Min Data Hold Time 10 OE Hold Time 10 OE to Output Delay ⁽²⁾ OE High Pulse 150	Parameter Min Typ Data Hold Time 10 OE Hold Time 10 OE to Output Delay ⁽²⁾ OE High Pulse 150	Parameter Min Typ Max Data Hold Time 10 OE Hold Time 10 OE to Output Delay ⁽²⁾ OE High Pulse 150

Notes: 1. These parameters are characterized and not 100% tested.

2. See toE spec in A.C. Read Characteristics.

Toggle Bit Waveforms (1,3)

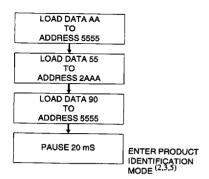


- 1. Toggling either \overline{OE} or \overline{CE} or both \overline{OE} and \overline{CE} will operate toggle bit.
- 2. Beginning and ending state of I/O6 will vary.
- 3. Any address location may be used but the address should not vary.

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Software Product Identification Entry (1)

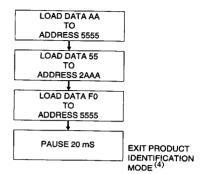


Notes for software product identification:

- 1. Data Format: I/O7 I/O0 (Hex); Address Format: A14 - A0 (Hex).
- 2. $A1 A16 = V_{1L}$ Manufacture Code is read for $A0 = V_{IL}$; Device Code is read for $A0 = V_{IH}$.
- 3. The device does not remain in identification mode if powered down.

 4. The device returns to standard operation mode.
- 5. Manufacturer Code: 1F Device Code: 35

Software Product Identification Exit







Ordering Information

tacc	Icc (mA)		Ordering Code	Package	Operation Range
(ns)	Active	Standby	Ordering Code	1 donage	
200	15	0.02	AT29LV010-20DC AT29LV010-20JC AT29LV010-20PC AT29LV010-20TC	32D6 32J 32P6 32T	Commercial (0° to 70°C)
	15	0.05	AT29LV010-20DI AT29LV010-20JI AT29LV010-20PI	32D6 32J 32P6	Industrial (-40° to 85°C)
250	15	0.02	AT29LV010-25DC AT29LV010-25JC AT29LV010-25PC AT29LV010-25TC	32D6 32J 32P6 32T	Commercial (0° to 70°C)
	15	0.05	AT29LV010-25DI AT29LV010-25JI AT29LV010-25PI	32D6 32J 32P6	Industrial (-40° to 85°C)

Package Type		
32D6	32 Lead, 0.600" Wide, Non-Windowed, Ceramic Dual Inline Package (Cerdip)	
32J	32 Lead, Plastic J-Leaded Chip Carrier (PLCC)	
32P6	32 Lead, 0.600" Wide, Plastic Dual Inline Package (PDIP)	
32T	32 Lead, Thin Small Outline Package (TSOP)	

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