

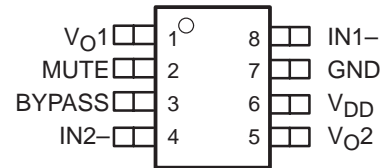
# TPA152

## 75-mW STEREO AUDIO POWER AMPLIFIER

SLOS210A – JUNE 1998 – REVISED MARCH 2000

- High-Fidelity Line-Out/HP Driver
- 75-mW Stereo Output
- PC Power Supply Compatible
- Pop Reduction Circuitry
- Internal Mid-Rail Generation
- Thermal and Short-Circuit Protection
- Surface-Mount Packaging
- Pin Compatible With TPA302

**D PACKAGE  
(TOP VIEW)**



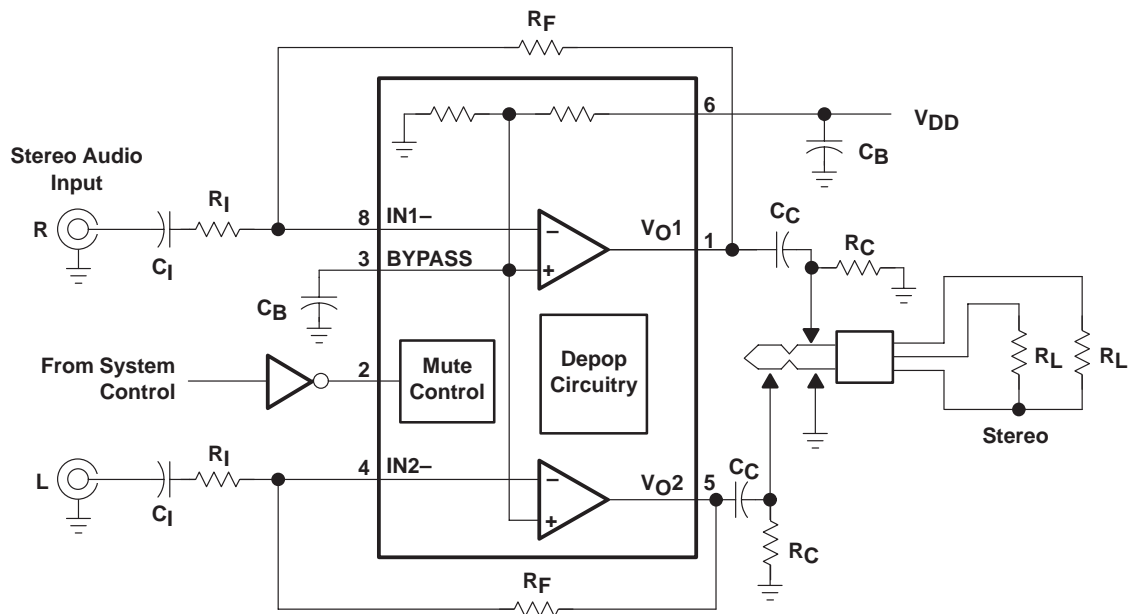
### description

The TPA152 is a stereo audio power amplifier capable of less than 0.1% THD+N at 1 kHz when delivering 75 mW per channel into a 32- $\Omega$  load. THD+N is less than 0.2% across the audio band of 20 to 20 kHz. For 10 k $\Omega$  loads, the THD+N performance is better than 0.005% at 1 kHz, and less than 0.01% across the audio band of 20 to 20 kHz.

The TPA152 is ideal for use as an output buffer for the audio CODEC in PC systems. It is also excellent for use where a high-performance head phone/line-out amplifier is needed. Depop circuitry is integrated to reduce transients during power up, power down, and mute mode.

Amplifier gain is externally configured by means of two resistors per input channel and does not require external compensation for settings of 1 to 10. The TPA152 is packaged in the 8-pin SOIC (D) package that reduces board space and facilitates automated assembly.

### typical application circuit



PRODUCTION DATA information is current as of publication date. Products conform to specifications per the terms of Texas Instruments standard warranty. Production processing does not necessarily include testing of all parameters.

**TEXAS  
INSTRUMENTS**

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# TPA152

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### AVAILABLE OPTIONS

T <sub>A</sub>	PACKAGED DEVICE
	SMALL OUTLINE
–40°C to 85°C	TPA152D†

† The D packages are available taped and reeled. To order a taped and reeled part, add the suffix R (e.g., TPA152DR)

### Terminal Functions

TERMINAL NAME	NO.	I/O	DESCRIPTION
BYPASS	3		BYPASS is the tap to the voltage divider for internal mid-supply bias. This terminal should be connected to a 0.1-μF to 1-μF capacitor.
GND	7		GND is the ground connection.
IN1–	8	I	IN1– is the inverting input for channel 1.
IN2–	4	I	IN2– is the inverting input for channel 2.
MUTE	2	I	A logic high puts the device into MUTE mode.
V <sub>DD</sub>	6	I	V <sub>DD</sub> is the supply voltage terminal.
V <sub>O1</sub>	1	O	V <sub>O1</sub> is the audio output for channel 1.
V <sub>O2</sub>	5	O	V <sub>O2</sub> is the audio output for channel 1.



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### absolute maximum ratings over operating free-air temperature range (unless otherwise noted)†

Supply voltage, $V_{DD}$	6 V
Input voltage, $V_I$	–0.3 V to $V_{DD} + 0.3$ V
Continuous total power dissipation	internally limited (See Dissipation Rating Table)
Operating junction temperature range, $T_J$	–40°C to 150°C
Operating case temperature range, $T_C$	–40°C to 125°C
Storage temperature range, $T_{stg}$	–65°C to 150°C
Lead temperature 1,6 mm (1/16 inch) from case for 10 seconds	260°C

† Stresses beyond those listed under “absolute maximum ratings” may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated under “recommended operating conditions” is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

DISSIPATION RATING TABLE

PACKAGE	$T_A \leq 25^\circ\text{C}$	DERATING FACTOR	$T_A = 70^\circ\text{C}$	$T_A = 85^\circ\text{C}$
D	724 mW	5.8 mW/°C	464 mW	376 mW

### recommended operating conditions

	MIN	MAX	UNIT
Supply voltage, $V_{DD}$	4.5	5.5	V
Operating free-air temperature, $T_A$	–40	85	°C

### dc electrical characteristics at $T_A = 25^\circ\text{C}$ , $V_{DD} = 5$ V

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
$V_{OO}$ Output offset voltage				10	mV
Supply ripple rejection ratio	$V_{DD} = 4.9$ V to 5.1 V		81		dB
$I_{DD}$ Supply current	See Figure 13		5.5	14	mA
$I_{DD}(\text{MUTE})$ Supply current in MUTE			5.5	14	mA
$Z_I$ Input impedance			>1		MΩ

### ac operating characteristics $V_{DD} = 5$ V, $T_A = 25^\circ\text{C}$ , $R_L = 32 \Omega$ (unless otherwise noted)

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
$P_O$ Output power (each channel)	THD $\leq 0.03\%$ , Gain = 1, See Figure 1		75†		mW
THD+N Total harmonic distortion plus noise	$P_O = 75$ mW, 20 Hz–20 kHz, Gain = 1, See Figure 2		0.2%		
$B_{OM}$ Maximum output power bandwidth	$A_V = 5$ , THD $< 0.6\%$ , See Figure 2		>20		kHz
Phase margin	Open loop, See Figure 16		80°		
Supply ripple rejection ratio	1 kHz, $C_B = 1 \mu\text{F}$ , See Figure 12		65		dB
Mute attenuation	See Figure 15		110		dB
Ch/Ch output separation	See Figure 13		102		dB
Signal-to-Noise ratio	$V_O = 1$ V(rms), Gain = 1 See Figure 11		104		dB
$V_N$ Noise output voltage	See Figure 10		6		$\mu\text{V}(\text{rms})$

† Measured at 1 kHz.

- NOTES: 1. The dc output voltage is approximately  $V_{DD}/2$ .  
2. Output power is measured at the output pins of the IC at 1 kHz.



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ac operating characteristics  $V_{DD} = 5\text{ V}$ ,  $T_A = 25^\circ\text{C}$ ,  $R_L = 10\text{ k}\Omega$

PARAMETER		TEST CONDITIONS		MIN	TYP	MAX	UNIT
THD+N	Total harmonic distortion plus noise	$V_I = 1\text{ V}_{(\text{rms})}$ , See Figure 6	20 Hz–20 kHz, Gain = 1,	0.005%			
		$V_O(\text{PP}) = 4\text{ V}$ , See Figure 8	20 Hz–20 kHz, Gain = 1,	0.005%			
B <sub>OM</sub>	Maximum output power bandwidth	G = 5,	THD <0.02%,	See Figure 6		>20	kHz
	Phase margin	Open loop,	See Figure 16		80°		
k <sub>SVR</sub>	Supply voltage rejection ratio	1 kHz,	C <sub>B</sub> = 1 μF,	See Figure 12		65	dB
	Mute attenuation	See Figure 15				110	dB
	Ch/Ch output separation	See Figure 13				102	dB
	Signal-to-Noise ratio	$V_O = 1\text{ V}_{(\text{rms})}$ ,	Gain = 1,	See Figure 11		104	dB
V <sub>n</sub>	Noise output voltage	See Figure 10				6	μV(rms)

† Measured at 1 kHz.

### TYPICAL CHARACTERISTICS

#### Table of Graphs

		FIGURE
THD+N Total harmonic distortion plus noise	vs Output power	1, 4
THD+N Total harmonic distortion plus noise	vs Frequency	2, 3, 6, 8, 9
THD+N Total harmonic distortion plus noise	vs Output voltage	5, 7
$V_n$ Output noise voltage	vs Frequency	10
SNR Signal-to-noise ratio	vs Gain	11
Supply ripple rejection ratio	vs Frequency	12
Crosstalk	vs Frequency	13, 14
Mute Attenuation	vs Frequency	15
Open-loop gain and phase	vs Frequency	16, 17
Closed-loop gain and phase	vs Frequency	18
$I_{DD}$ Supply current	vs Supply voltage	19
$P_O$ Output power	vs Load resistance	20
$P_D$ Power dissipation	vs Output power	21



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## TYPICAL CHARACTERISTICS

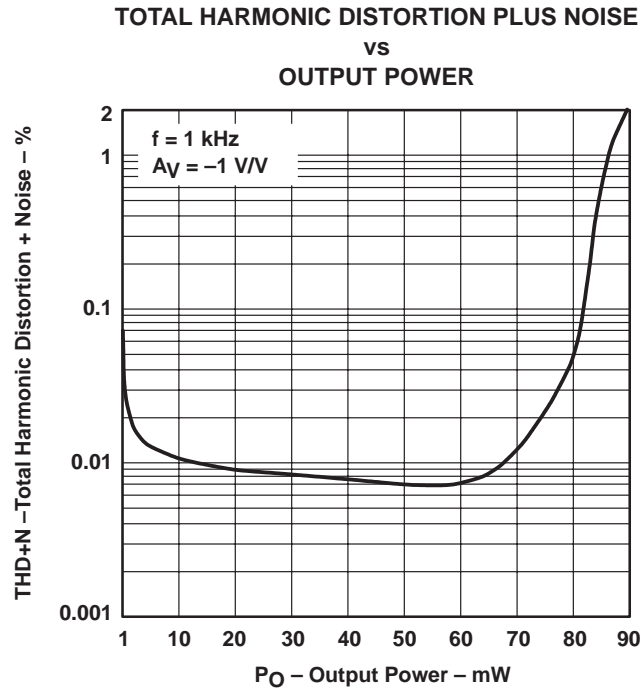


Figure 1

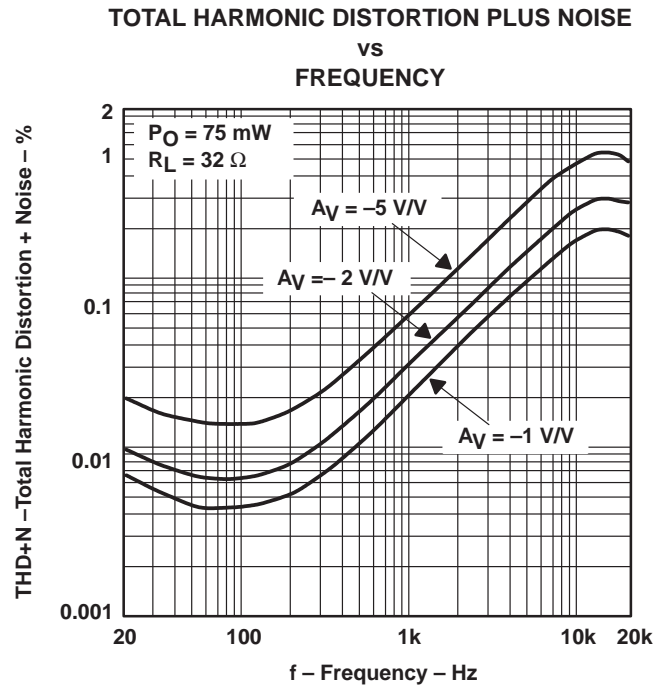


Figure 2

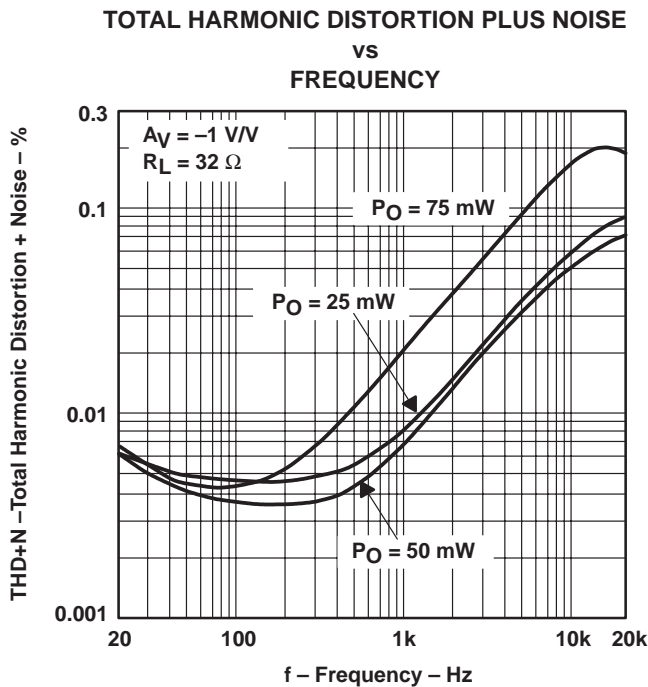


Figure 3

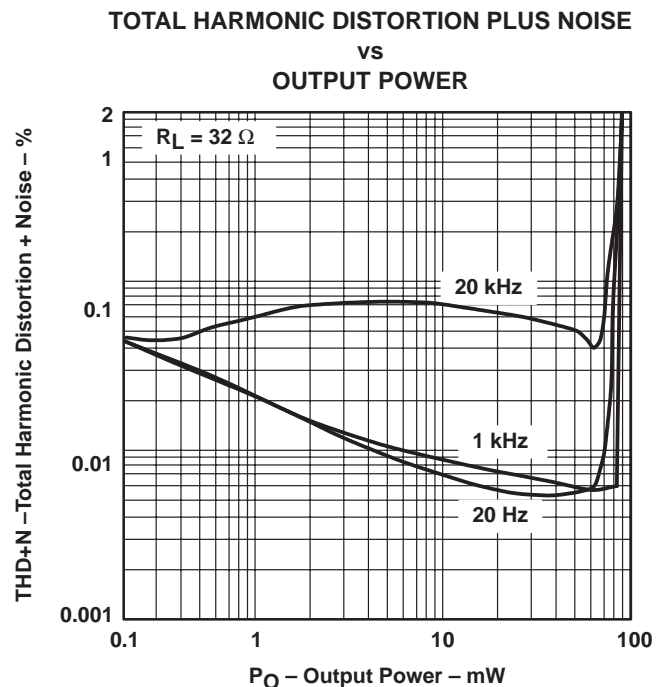


Figure 4

# TPA152

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### TYPICAL CHARACTERISTICS

TOTAL HARMONIC DISTORTION PLUS NOISE  
vs  
OUTPUT VOLTAGE

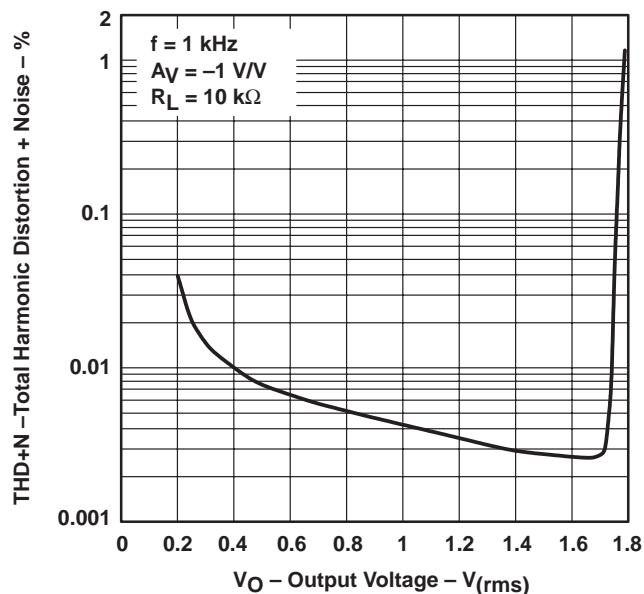


Figure 5

TOTAL HARMONIC DISTORTION PLUS NOISE  
vs  
FREQUENCY

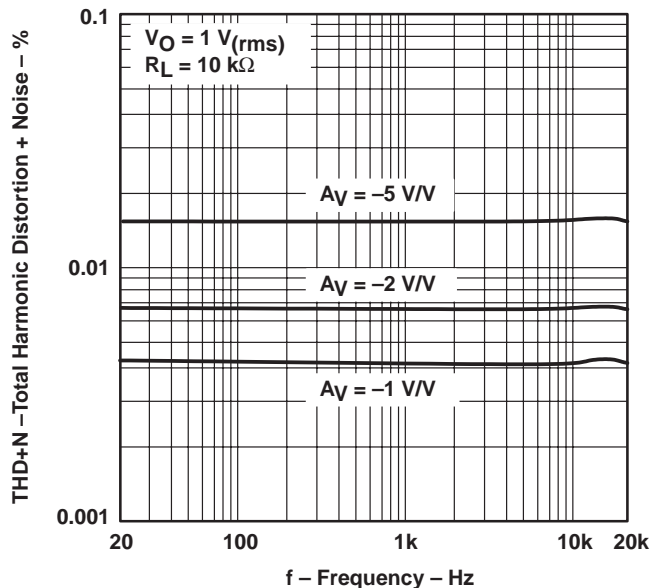


Figure 6

TOTAL HARMONIC DISTORTION PLUS NOISE  
vs  
OUTPUT VOLTAGE

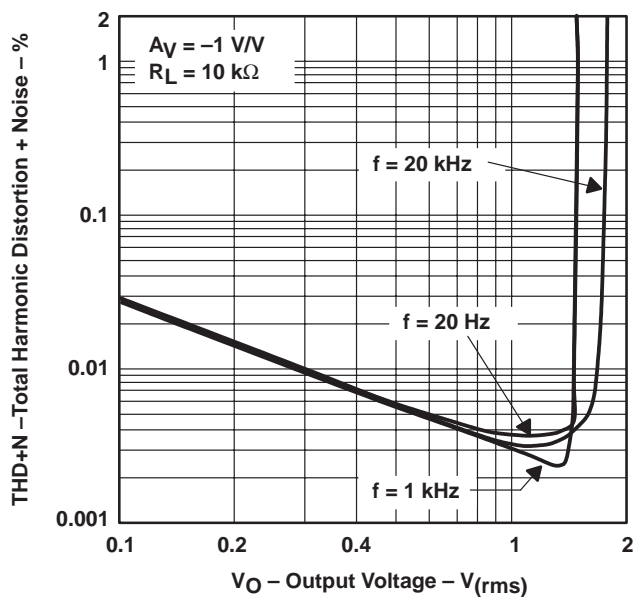


Figure 7

TOTAL HARMONIC DISTORTION PLUS NOISE  
vs  
FREQUENCY

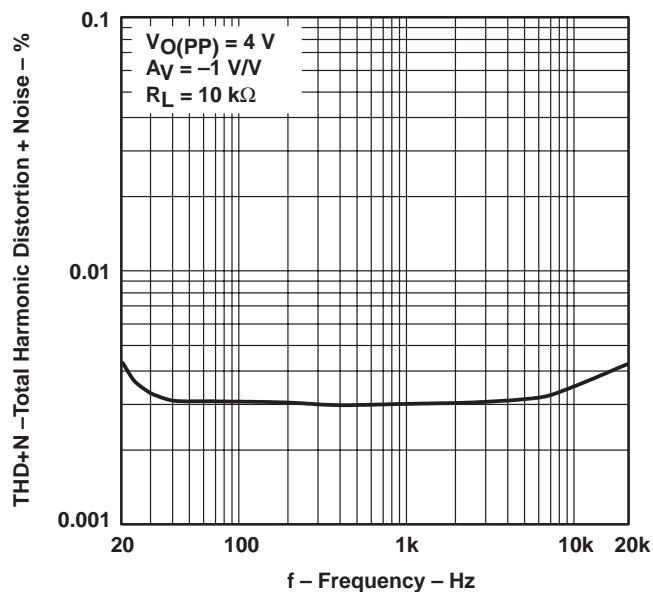


Figure 8

# TYPICAL CHARACTERISTICS

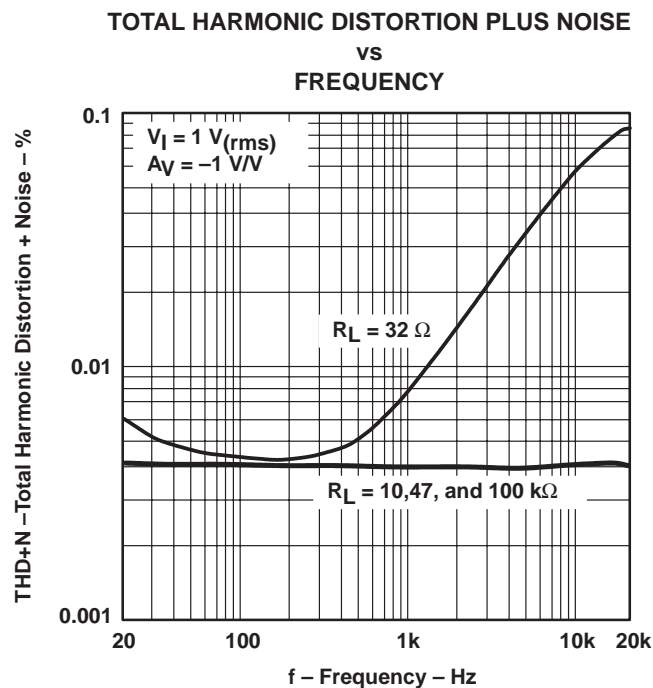


Figure 9

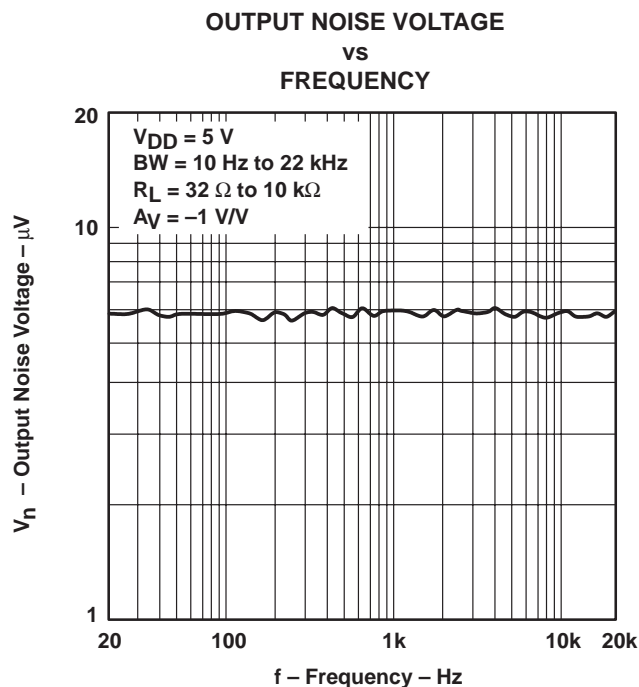


Figure 10

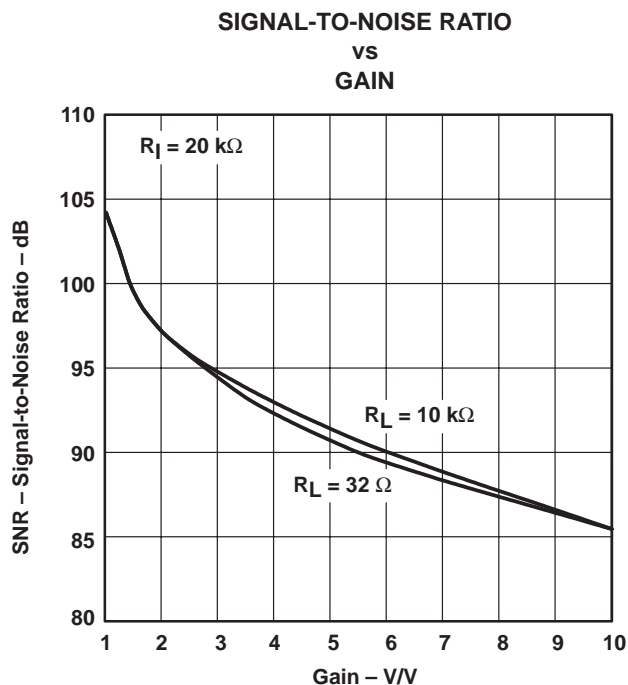


Figure 11

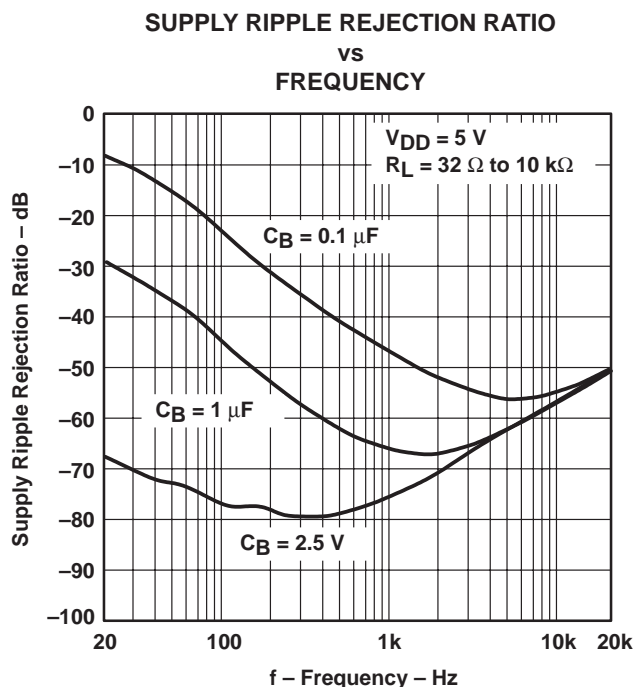


Figure 12

# TPA152

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### TYPICAL CHARACTERISTICS

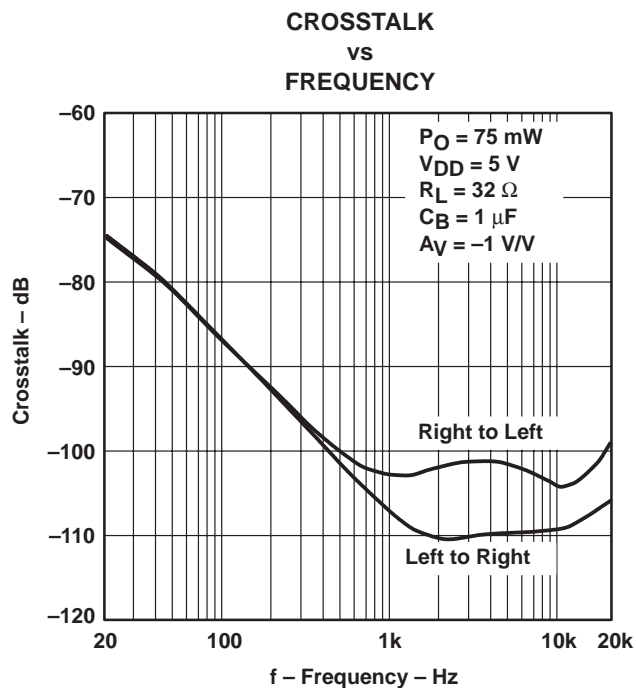


Figure 13

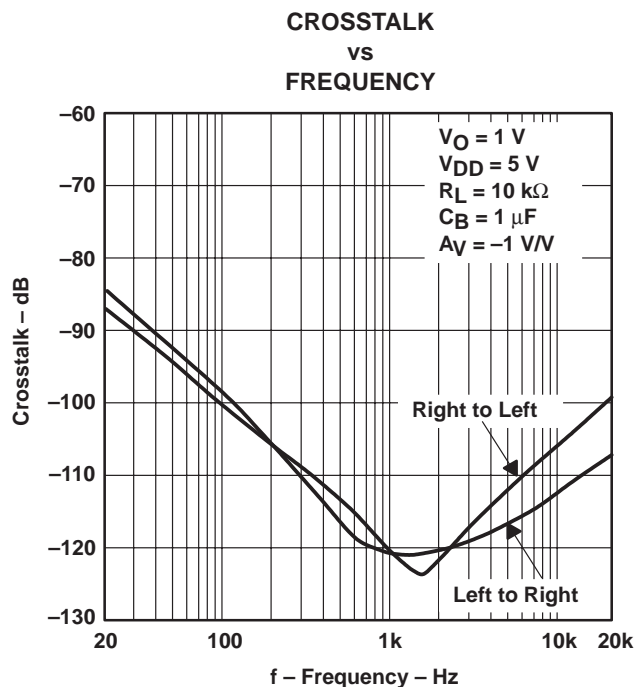


Figure 14

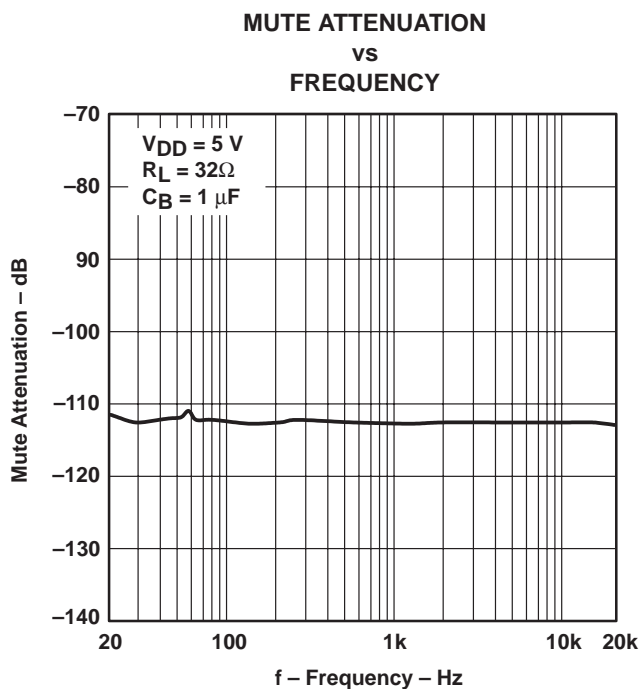


Figure 15



## TYPICAL CHARACTERISTICS

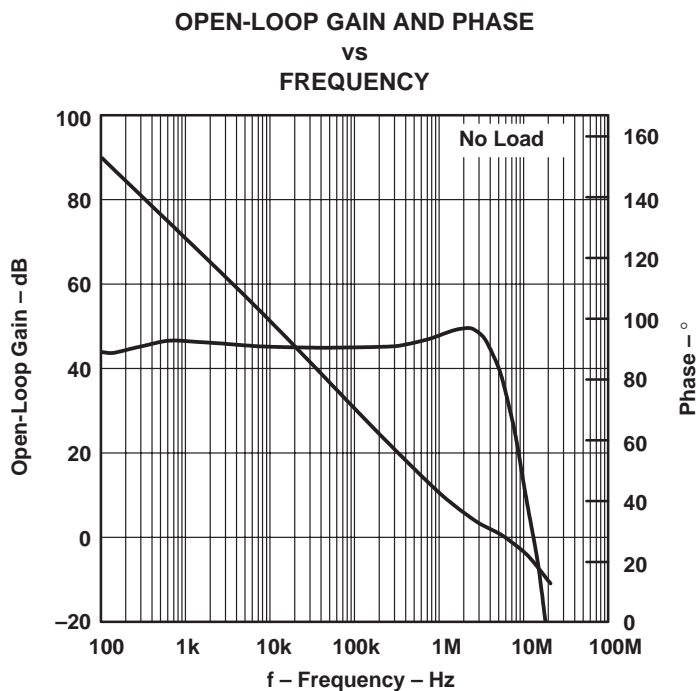


Figure 16

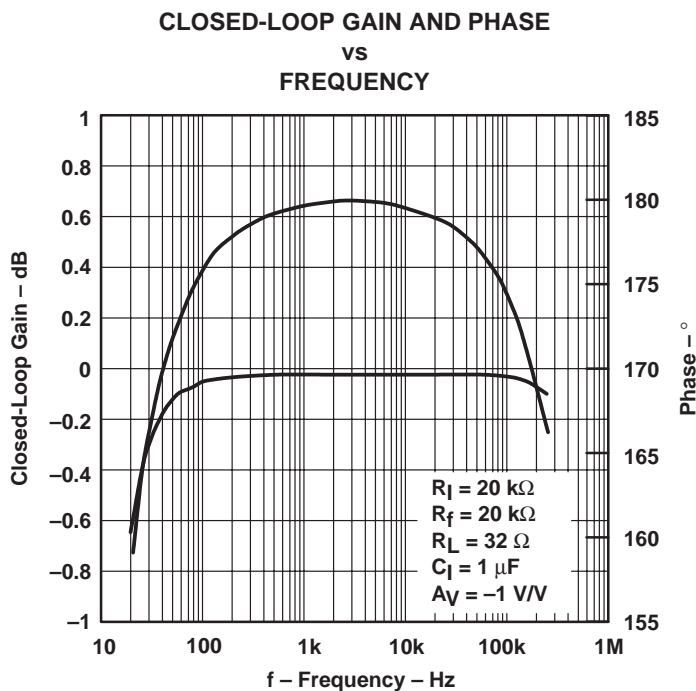


Figure 17

TPA152  
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TYPICAL CHARACTERISTICS

CLOSED-LOOP GAIN AND PHASE  
VS  
FREQUENCY

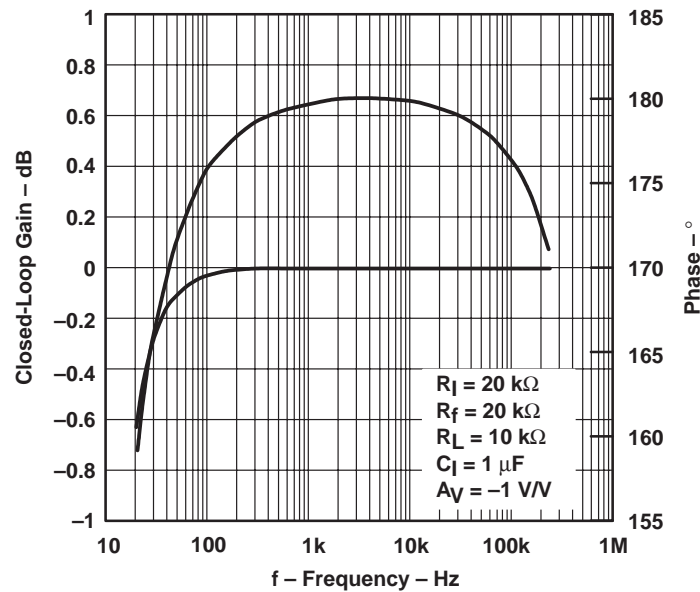


Figure 18

SUPPLY CURRENT  
VS  
SUPPLY VOLTAGE

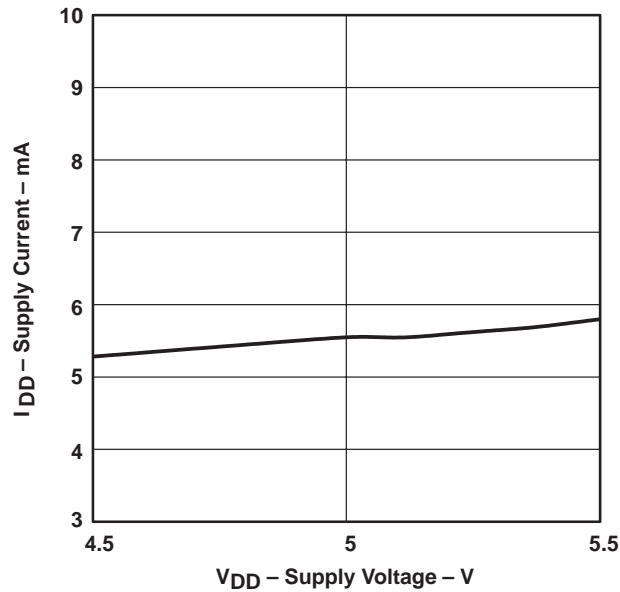


Figure 19

OUTPUT POWER  
VS  
LOAD RESISTANCE

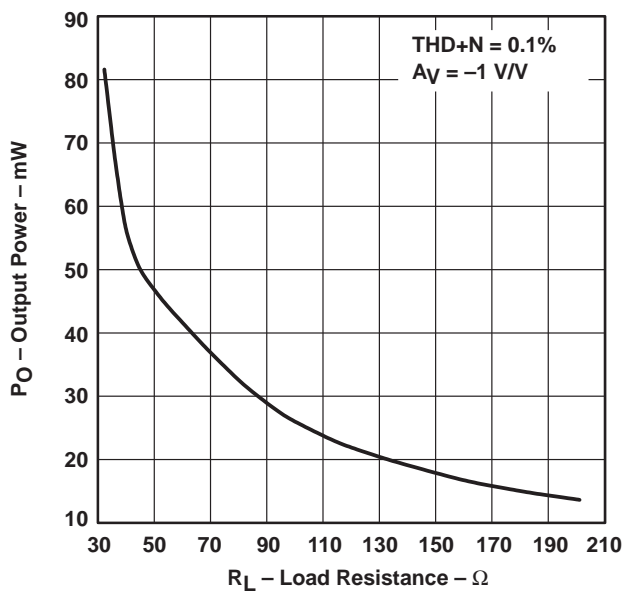


Figure 20

## TYPICAL CHARACTERISTICS

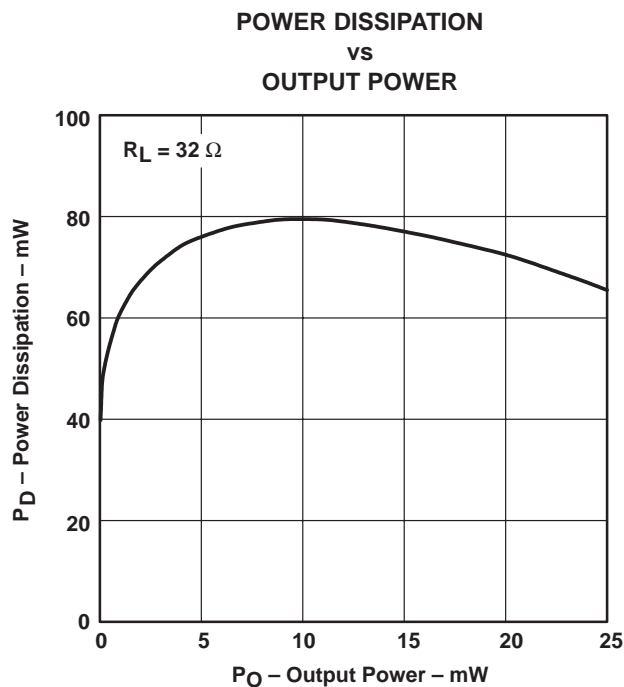
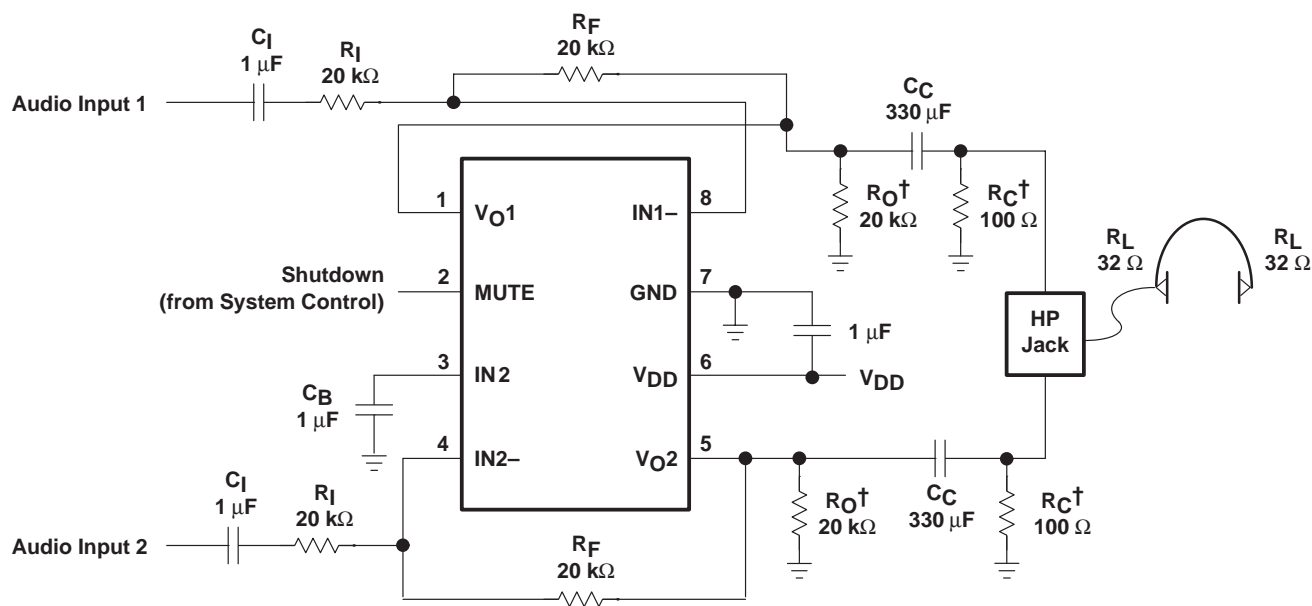


Figure 21

## APPLICATION INFORMATION

### selection of components

Figure 22 is a schematic diagram of a typical application circuit.



† These resistors are optional. Adding these resistors improves the depop performance of the TPA152.

Figure 22. TPA152 Typical Application Circuit

# TPA152

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### APPLICATION INFORMATION

#### gain setting resistors, $R_F$ and $R_I$

The gain for the TPA152 is set by resistors  $R_F$  and  $R_I$  according to equation 1.

$$\text{Gain} = - \left( \frac{R_F}{R_I} \right) \quad (1)$$

Given that the TPA152 is a MOS amplifier, the input impedance is very high, consequently input leakage currents are not generally a concern although noise in the circuit increases as the value of  $R_F$  increases. In addition, a certain range of  $R_F$  values are required for proper start-up operation of the amplifier. Taken together it is recommended that the effective impedance seen by the inverting node of the amplifier be set between 5 k $\Omega$  and 20 k $\Omega$ . The effective impedance is calculated in equation 2.

$$\text{Effective Impedance} = \frac{R_F R_I}{R_F + R_I} \quad (2)$$

As an example, consider an input resistance of 20 k $\Omega$  and a feedback resistor of 20 k $\Omega$ . The gain of the amplifier would be  $-1$  and the effective impedance at the inverting terminal would be 10 k $\Omega$ , which is within the recommended range.

For high performance applications, metal film resistors are recommended because they tend to have lower noise levels than carbon resistors. For values of  $R_F$  above 50 k $\Omega$ , the amplifier tends to become unstable due to a pole formed from  $R_F$  and the inherent input capacitance of the MOS input structure. For this reason, a small compensation capacitor of approximately 5 pF should be placed in parallel with  $R_F$ . This, in effect, creates a low-pass filter network with the cutoff frequency defined in equation 3.

$$f_{c(\text{lowpass})} = \frac{1}{2\pi R_F C_F} \quad (3)$$

For example if  $R_F$  is 100 k $\Omega$  and  $C_F$  is 5 pF then  $f_{c(\text{lowpass})}$  is 318 kHz, which is well outside the audio range.

#### input capacitor, $C_I$

In the typical application, an input capacitor,  $C_I$ , is required to allow the amplifier to bias the input signal to the proper dc level for optimum operation. In this case,  $C_I$  and  $R_I$  form a high-pass filter with the corner frequency determined in equation 4.

$$f_{c(\text{highpass})} = \frac{1}{2\pi R_I C_I} \quad (4)$$

The value of  $C_I$  is important to consider as it directly affects the bass (low frequency) performance of the circuit. Consider the example where  $R_I$  is 20 k $\Omega$  and the specification calls for a flat bass response down to 20 Hz. Equation 4 is reconfigured as equation 5.

$$C_I = \frac{1}{2\pi R_I f_{c(\text{highpass})}} \quad (5)$$

In this example,  $C_I$  is 0.40  $\mu\text{F}$ , so one would likely choose a value in the range of 0.47  $\mu\text{F}$  to 1  $\mu\text{F}$ . A further consideration for this capacitor is the leakage path from the input source through the input network ( $R_I$ ,  $C_I$ ) and the feedback resistor ( $R_F$ ) to the load. This leakage current creates a dc offset voltage at the input to the amplifier that reduces useful headroom, especially in high-gain applications ( $> 10$ ). For this reason a low-leakage tantalum or ceramic capacitor is the best choice. When polarized capacitors are used, the positive side of the capacitor should face the amplifier input in most applications, as the dc level there is held at  $V_{DD}/2$ , which is likely higher than the source dc level. Please note that it is important to confirm the capacitor polarity in the application.

## APPLICATION INFORMATION

### power supply decoupling, $C_S$

The TPA152 is a high-performance CMOS audio amplifier that requires adequate power supply decoupling to ensure that the output total harmonic distortion (THD) is as low as possible. Power supply decoupling also prevents oscillations for long lead lengths between the amplifier and the speaker. The optimum decoupling is achieved by using two capacitors of different types that target different types of noise on the power supply leads. For higher frequency transients, spikes, or digital hash on the line, a good low equivalent-series-resistance (ESR) ceramic capacitor, typically 0.1  $\mu\text{F}$ , placed as close as possible to the device  $V_{DD}$  lead, works best. For filtering lower-frequency noise signals, a larger aluminum electrolytic capacitor of 10  $\mu\text{F}$  or greater placed near the power amplifier is recommended.

### midrail bypass capacitor, $C_B$

The midrail bypass capacitor,  $C_B$ , serves several important functions. During startup or recovery from shutdown mode,  $C_B$  determines the rate at which the amplifier starts up. This helps to push the start-up pop noise into the subaudible range (so slow it can not be heard). The second function is to reduce noise produced by the power supply caused by coupling into the output drive signal. This noise is from the midrail generation circuit internal to the amplifier. The capacitor is fed from a 160-k $\Omega$  source inside the amplifier. To keep the start-up pop as low as possible, the relationship shown in equation 6 should be maintained.

$$\frac{1}{(C_B \times 160 \text{ k}\Omega)} \leq \frac{1}{(C_I R_I)} \quad (6)$$

As an example, consider a circuit where  $C_B$  is 1  $\mu\text{F}$ ,  $C_I$  is 1  $\mu\text{F}$  and  $R_I$  is 20 k $\Omega$ . Inserting these values into the equation 9 results in:

$$6.25 \leq 50$$

which satisfies the rule. Bypass capacitor,  $C_B$ , values of 0.1  $\mu\text{F}$  to 1  $\mu\text{F}$  ceramic or tantalum low-ESR capacitors are recommended for the best THD and noise performance.

### output coupling capacitor, $C_C$

In the typical single-supply single-ended (SE) configuration, an output coupling capacitor ( $C_C$ ) is required to block the dc bias at the output of the amplifier thus preventing dc currents in the load. As with the input coupling capacitor, the output coupling capacitor and impedance of the load form a high-pass filter governed by equation 7.

$$f_{c(\text{high})} = \frac{1}{2\pi R_L C_C} \quad (7)$$

The main disadvantage, from a performance standpoint, is that the load impedances are typically small, which drive the low-frequency corner higher. Large values of  $C_C$  are required to pass low frequencies into the load. Consider the example where a  $C_C$  of 68  $\mu\text{F}$  is chosen and loads vary from 32  $\Omega$  to 47 k $\Omega$ . Table 1 summarizes the frequency response characteristics of each configuration.

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### APPLICATION INFORMATION

**Table 1. Common Load Impedances vs Low Frequency Output Characteristics in SE Mode**

$R_L$	$C_C$	LOWEST FREQUENCY
32 $\Omega$	68 $\mu F$	73 Hz
10,000 $\Omega$	68 $\mu F$	0.23 Hz
47,000 $\Omega$	68 $\mu F$	0.05 Hz

As Table 1 indicates, headphone response is adequate and drive into line level inputs (a home stereo for example) is very good.

The output coupling capacitor required in single-supply SE mode also places additional constraints on the selection of other components in the amplifier circuit. With the rules described earlier still valid, add the following relationship:

$$\frac{1}{(C_B \times 160 \text{ k}\Omega)} \leq \frac{1}{(C_I R_I)} \ll \frac{1}{R_L C_C} \quad (8)$$

#### output pull-down resistor, $R_C + R_O$

Placing a 100- $\Omega$  resistor,  $R_C$ , from the output side of the coupling capacitor to ground insures the coupling capacitor,  $C_C$ , is charged before a plug is inserted into the jack. Without this resistor, the coupling capacitor would charge rapidly upon insertion of a plug, leading to an audible pop in the headphones.

Placing a 20-k $\Omega$  resistor,  $R_O$ , from the output of the IC to ground insures that the coupling capacitor fully discharges at power down. If the supply is rapidly cycled without this capacitor, a small pop may be audible in 10-k $\Omega$  loads.

#### using low-ESR capacitors

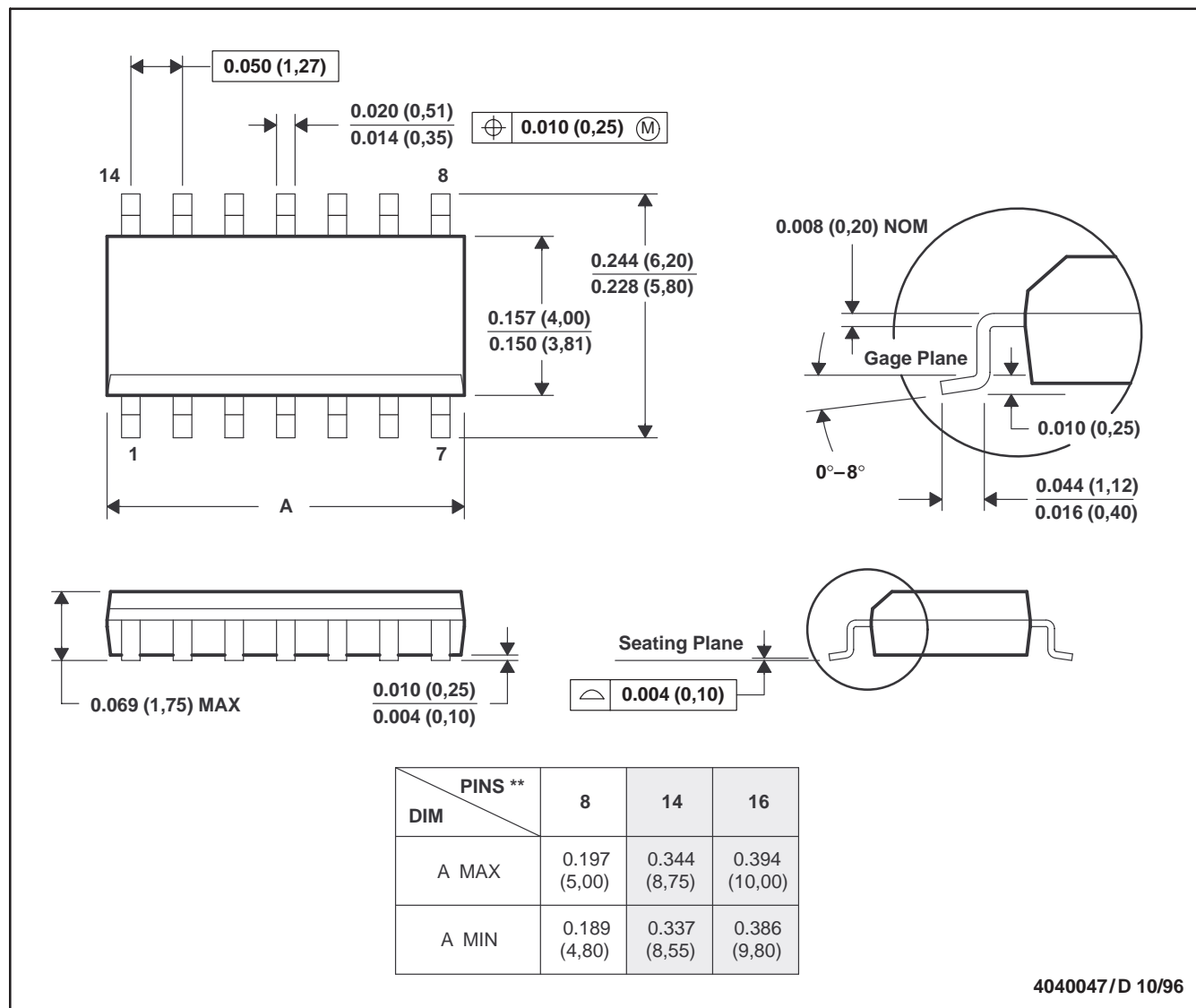
Low-ESR capacitors are recommended throughout this applications section. A real capacitor can be modeled simply as a resistor in series with an ideal capacitor. The voltage drop across this resistor minimizes the beneficial effects of the capacitor in the circuit. The lower the equivalent value of this resistance, the more the real capacitor behaves like an ideal capacitor.

# MECHANICAL DATA

D (R-PDSO-G\*\*)

PLASTIC SMALL-OUTLINE PACKAGE

14 PINS SHOWN



- NOTES: A. All linear dimensions are in inches (millimeters).  
B. This drawing is subject to change without notice.  
C. Body dimensions do not include mold flash or protrusion, not to exceed 0.006 (0,15).  
D. Falls within JEDEC MS-012

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