NEC

MOS INTEGRATED CIRCUIT

μPD42S65165, 4265165

64 M-BIT DYNAMIC RAM
4 M-WORD BY 16-BIT, EDO,
BYTE READ/WRITE MODE

Description

The μPD42S65165, 4265165 are 4,194,304 words by 16 bits CMOS dynamic RAMs with optional EDO.
EDO is a kind of the page mode and is useful for the read operation.
Besides, the μPD42S65165 can execute $\overline{CAS}$ before $\overline{RAS}$ self refresh.
These are packaged in 50-pin plastic TSOP (II).

Features

- EDO (Hyper page mode)
- 4,194,304 words by 16 bits organization
- Single +3.3 V ± 0.3 V power supply
- Fast access and cycle time

Part number	Power consumption Active (MAX.)	Access time (MAX.)	R/W cycle time (MIN.)	EDO (Hyper page mode) cycle time (MIN.)
μPD42S65165-A50, 4265165-A50	540 mW	50 ns	84 ns	20 ns
μPD42S65165-A60, 4265165-A60	468 mW	60 ns	104 ns	25 ns

- The μPD42S65165 can execute $\overline{CAS}$ before $\overline{RAS}$ self refresh.

Part number	Refresh cycle	Refresh	Power consumption at standby (MAX.)
μPD42S65165	4,096 cycles/128 ms	$\overline{RAS}$ only refresh, Normal read/write, $\overline{CAS}$ before $\overline{RAS}$ self refresh, $\overline{CAS}$ before $\overline{RAS}$ refresh, Hidden refresh	0.72 mW (CMOS level input)
μPD4265165	4,096 cycles/64 ms	$\overline{RAS}$ only refresh, Normal read/write, $\overline{CAS}$ before $\overline{RAS}$ refresh, Hidden refresh	1.8 mW (CMOS level input)

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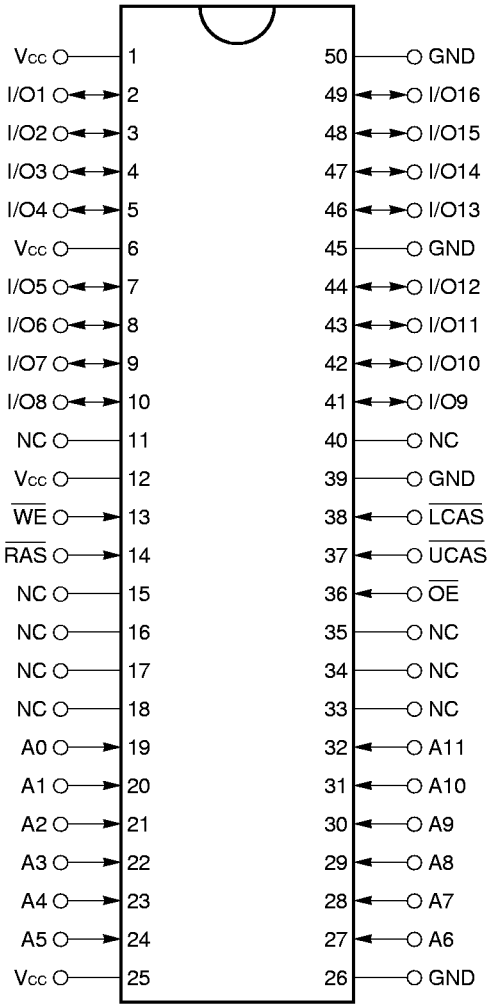
Ordering Information

Part number	Access time (MAX.)	Package	Refresh
μPD42S65165G5-A50-7JF	50 ns	50-pin plastic TSOP (II) (400 mil)	$\overline{CAS}$ before $\overline{RAS}$ self refresh $\overline{CAS}$ before $\overline{RAS}$ refresh $\overline{RAS}$ only refresh Hidden refresh
μPD42S65165G5-A60-7JF	60 ns		
μPD4265165G5-A50-7JF	50 ns	50-pin plastic TSOP (II) (400 mil)	$\overline{CAS}$ before $\overline{RAS}$ refresh $\overline{RAS}$ only refresh Hidden refresh
μPD4265165G5-A60-7JF	60 ns		

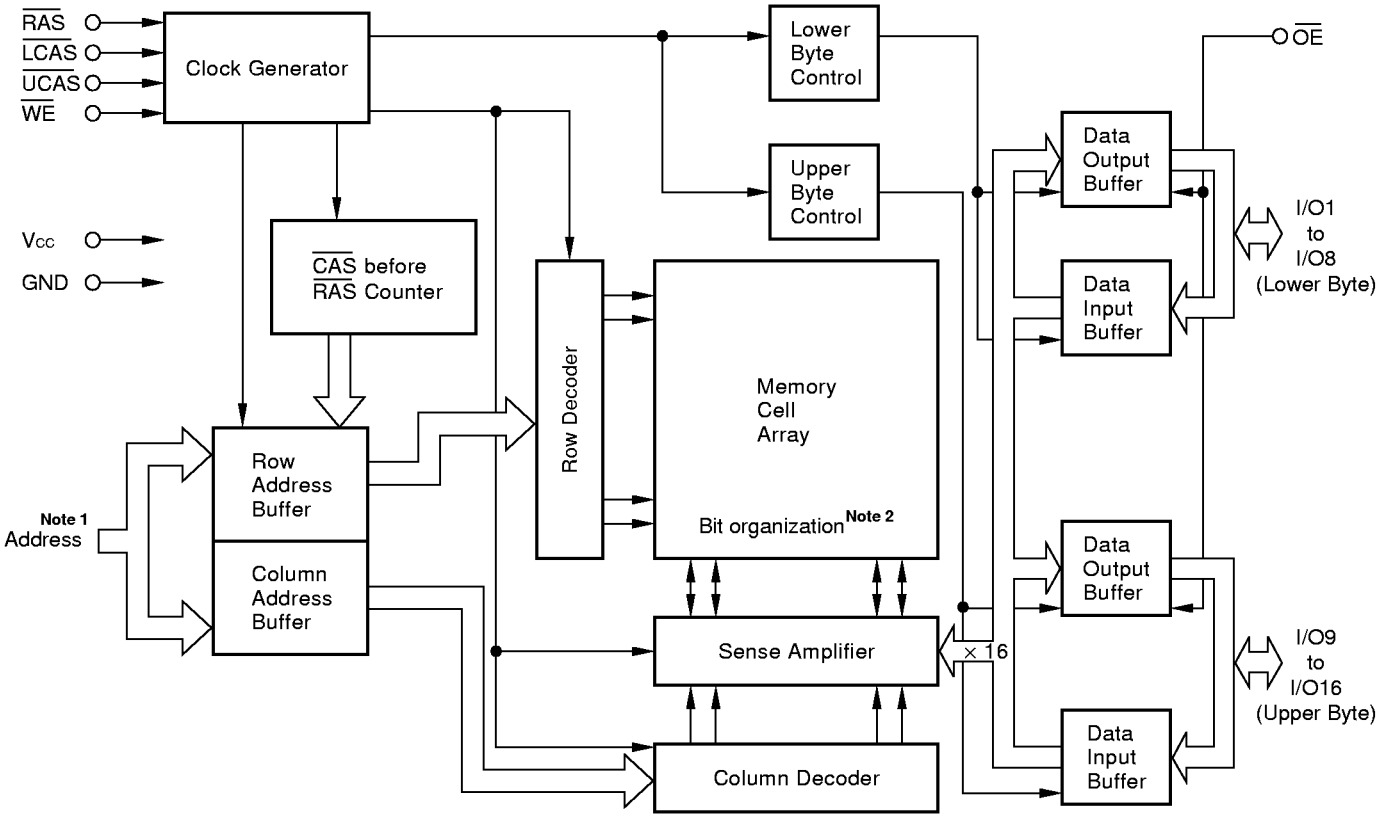
Pin Configuration (Marking Side)

50-pin Plastic TSOP (II) (400 mil)
μPD42S65165G5-7JF
μPD4265165G5-7JF



A0 to A11	:	Address Inputs
I/O1 to I/O16	:	Data Inputs/Outputs
$\overline{RAS}$	:	Row Address Strobe
$\overline{UCAS}$	:	Upper Byte Column Address Strobe
$\overline{LCAS}$	:	Lower Byte Column Address Strobe
$\overline{WE}$	:	Write Enable
$\overline{OE}$	:	Output Enable
VCC	:	Power Supply
GND	:	Ground
NC	:	No Connection

Block Diagram



Notes 1.

Part number	Row address	Column address
μPD42S65165, 4265165	A0 - A11	A0 - A9

2. 4,096 × 1,024 × 16

Input/Output Pin Functions

The μPD42S65165, 4265165 have input pins $\overline{RAS}$, $\overline{UCAS}$, $\overline{LCAS}$, $\overline{WE}$, $\overline{OE}$, A0 to A11 and input/output pins I/O1 to I/O16.

Pin name	Input/Output	Function
$\overline{RAS}$ (Row address strobe)	Input	$\overline{RAS}$ activates the sense amplifier by latching a row address and selecting a corresponding word line. It refreshes memory cell array of one line selected by the row address. It also selects the following function. • $\overline{CAS}$ before $\overline{RAS}$ self refresh, $\overline{CAS}$ before $\overline{RAS}$ refresh
$\overline{UCAS}$, $\overline{LCAS}$ (Upper, Lower column address strobe)	Input	$\overline{UCAS}$, $\overline{LCAS}$ activates data input/output circuit by latching column address and selecting a digit line connected with the sense amplifier.
A0 to A11 (Address inputs)	Input	Address bus. Input total 22-bit of address signal, upper 12-bit and lower 10-bit in sequence (address multiplex method). Therefore, one word is selected from 4,194,304-word by 16-bit memory cell array. In actual operation, latch row address by specifying row address and activating $\overline{RAS}$. Then, switch the address bus to column address and activate $\overline{CAS}$. Each address is taken into the device when $\overline{RAS}$ and $\overline{CAS}$ are activated. Therefore, the address input setup time (t_{ASR}, t_{ASC}) and hold time (t_{RAH}, t_{CAH}) are specified for the activation of $\overline{RAS}$ and $\overline{CAS}$.
$\overline{WE}$ (Write enable)	Input	Write control signal. Write operation is executed by activating $\overline{RAS}$, $\overline{CAS}$ and $\overline{WE}$.
$\overline{OE}$ (Output enable)	Input	Read control signal. Read operation can be executed by activating $\overline{RAS}$, $\overline{CAS}$ and $\overline{OE}$. If $\overline{WE}$ is activated during read operation, $\overline{OE}$ is to be ineffective in the device. Therefore, read operation cannot be executed.
I/O1 to I/O16 (Data inputs/outputs)	Input/Output	16-bit data bus. I/O1 to I/O16 are used to input/output data.

Hyper Page Mode (EDO)

The hyper page mode (EDO) is a kind of page mode with enhanced features. The two major features of the hyper page mode (EDO) are as follows.

1. Data output time is extended.

In the hyper page mode (EDO), the output data is held to the next $\overline{CAS}$ cycle's falling edge, instead of the rising edge. For this reason, valid data output time in the hyper page mode (EDO) is extended compared with the fast page mode (= data extend function). In the fast page mode, the data output time becomes shorter as the $\overline{CAS}$ cycle time becomes shorter. Therefore, in the hyper page mode (EDO), the timing margin in read cycle is larger than that of the fast page mode even if the $\overline{CAS}$ cycle time becomes shorter.

2. The $\overline{CAS}$ cycle time in the hyper page mode (EDO) is shorter than that in the fast page mode.

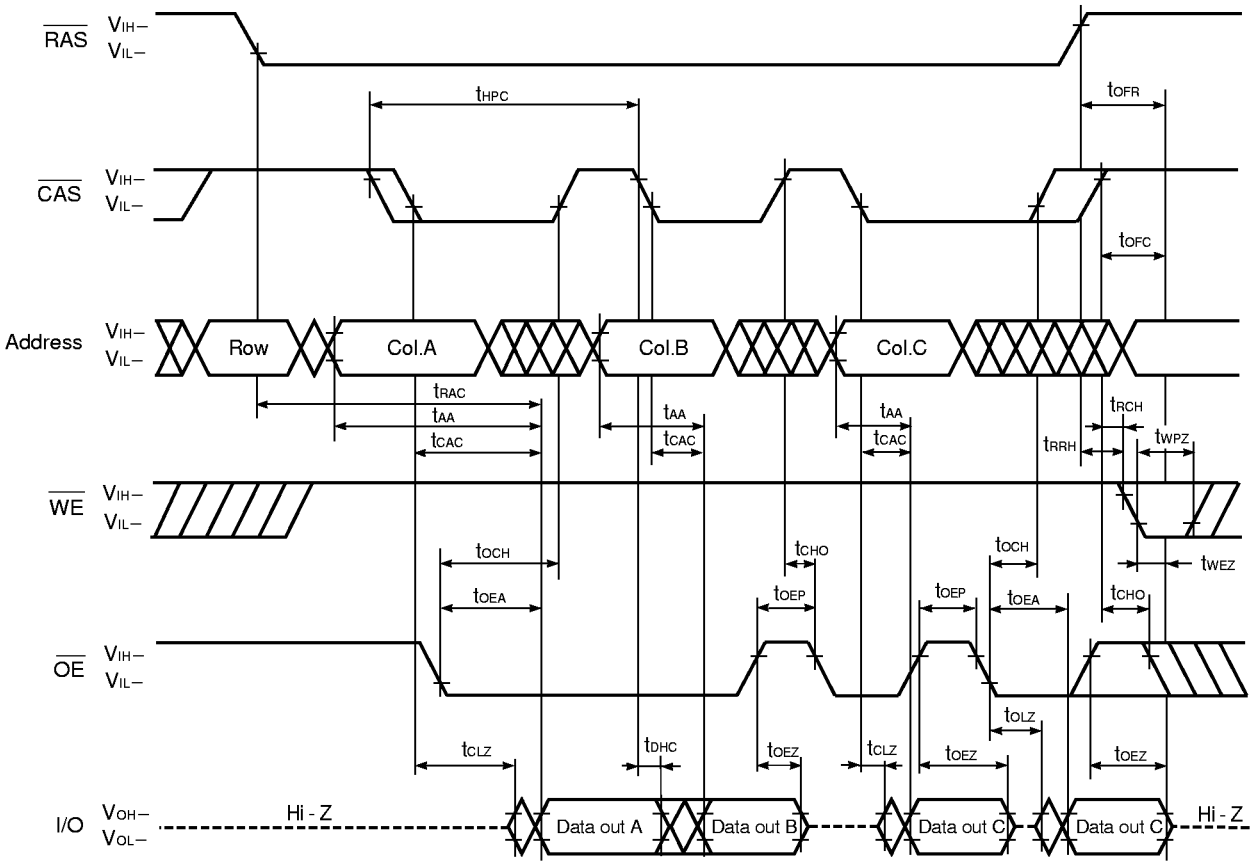
In the hyper page mode (EDO), due to the data extend function, the $\overline{CAS}$ cycle time can be shorter than in the fast page mode if the timing margin is the same.

Taking a device whose t_{RAC} is 60 ns as an example, the $\overline{CAS}$ cycle time in the fast page mode is 25 ns while that in the fast page mode is 40 ns.

In the hyper page mode (EDO), read (data out) and write (data in) cycles can be executed repeatedly during one $\overline{RAS}$ cycle. The hyper page mode (EDO) allows both read and write operations during one cycle.

The following shows a part of the hyper page mode (EDO) read cycle. Specifications to be observed are described in the next page.

Hyper Page Mode (EDO) Read Cycle



Cautions when using the hyper page mode (EDO)

1. $\overline{CAS}$ access should be used to operate t_{HPC} at the MIN. value.
2. To make I/Os to Hi-Z in read cycle, it is necessary to control $\overline{RAS}$, $\overline{CAS}$, $\overline{WE}$, $\overline{OE}$ as follows. The effective specification depends on the state of each signal.
   (1) Both $\overline{RAS}$ and $\overline{CAS}$ are inactive (at the end of read cycle)
   $\overline{WE}$: inactive, $\overline{OE}$: active
   t_{OFC} is effective when $\overline{RAS}$ is inactivated before $\overline{CAS}$ is inactivated.
   t_{OFR} is effective when $\overline{CAS}$ is inactivated before $\overline{RAS}$ is inactivated.
   The slower of t_{OFC} and t_{OFR} becomes effective.
   (2) Both $\overline{RAS}$ and $\overline{CAS}$ are active or either $\overline{RAS}$ or $\overline{CAS}$ is active (in read cycle)
   $\overline{WE}$, $\overline{OE}$: inactive ····· t_{OEZ} is effective.
   Both $\overline{RAS}$ and $\overline{CAS}$ are inactive or $\overline{RAS}$ is active and $\overline{CAS}$ is inactive (at the end of read cycle)
   $\overline{WE}$, $\overline{OE}$: active and either t_{RRH} or t_{RCH} must be met ····· t_{WEZ} and t_{WPZ} are effective.
   The faster of t_{OEZ} and t_{WEZ} becomes effective.
   The faster of (1) and (2) becomes effective.
3. In read cycle, the effective specification depends on the state of $\overline{CAS}$ signal when controlling data output with the $\overline{OE}$ signal.
   (1) $\overline{CAS}$: inactive, $\overline{OE}$: active ····· t_{CHO} is effective.
   (2) $\overline{CAS}$, $\overline{OE}$: active ····· t_{OCH} is effective.

Electrical Specifications

- $\overline{CAS}$ means $\overline{UCAS}$ and $\overline{LCAS}$.
- All voltages are referenced to GND.
- After power up ($V_{CC} \geq V_{CC(MIN.)}$), wait more than 100 μs ($\overline{RAS}$, $\overline{CAS}$ inactive) and then, execute eight $\overline{CAS}$ before $\overline{RAS}$ or $\overline{RAS}$ only refresh cycles as dummy cycles to initialize internal circuit.

Absolute Maximum Ratings

Parameter	Symbol	Condition	Rating	Unit
Voltage on any pin relative to GND	V_T		–0.5 to +4.6	V
Supply voltage	V_{CC}		–0.5 to +4.6	V
Output current	I_O		50	mA
Power dissipation	P_D		1	W
Operating ambient temperature	T_A		0 to +70	°C
Storage temperature	T_{stg}		–55 to +125	°C

Caution Exposing the device to stress above those listed in Absolute Maximum Ratings could cause permanent damage. The device is not meant to be operated under conditions outside the limits described in the operational section of this specification. Exposure to Absolute Maximum Rating conditions for extended periods may affect device reliability.

Recommended Operating Conditions

Parameter	Symbol	Condition	MIN.	TYP.	MAX.	Unit
Supply voltage	V_{CC}		3.0	3.3	3.6	V
High level input voltage	V_{IH}		2.0		V_{CC} + 0.3	V
Low level input voltage	V_{IL}		–0.3		+0.8	V
Operating ambient temperature	T_A		0		70	°C

Capacitance (T_A = 25 °C, f = 1 MHz)

Parameter	Symbol	Test condition	MIN.	TYP.	MAX.	Unit
Input capacitance	C_{I1}	Address			5	pF
	C_{I2}	$\overline{RAS}$, $\overline{CAS}$, $\overline{WE}$, $\overline{OE}$			7	
Data input/output capacitance	$C_{I/O}$	I/O			7	pF

DC Characteristics (Recommended operating conditions unless otherwise noted)

[μPD42S65165, 4265165]

Parameter		Symbol	Test condition		MIN.	MAX.	Unit	Notes
Operating current		I_{CC1}	$\overline{RAS}$, $\overline{CAS}$ cycling	t_{RAC} = 50 ns		150	mA	1, 2, 3
			$t_{RC} = t_{RC\ (MIN.)}$, I_O = 0 mA	t_{RAC} = 60 ns		130		
Standby current	μPD42S65165	I_{CC2}	$\overline{RAS}$, $\overline{CAS} \geq V_{IH\ (MIN.)}$, I_O = 0 mA			1.0	mA	
			$\overline{RAS}$, $\overline{CAS} \geq V_{CC}$ – 0.2 V, I_O = 0 mA			0.2		
	μPD4265165		$\overline{RAS}$, $\overline{CAS} \geq V_{IH\ (MIN.)}$, I_O = 0 mA			1.0		
			$\overline{RAS}$, $\overline{CAS} \geq V_{CC}$ – 0.2 V, I_O = 0 mA			0.5		
$\overline{RAS}$ only refresh current		I_{CC3}	$\overline{RAS}$ cycling, $\overline{CAS} \geq V_{IH\ (MIN.)}$	t_{RAC} = 50 ns		150	mA	1, 2, 3 ,4
			$t_{RC} = t_{RC\ (MIN.)}$, I_O = 0 mA	t_{RAC} = 60 ns		130		
Operating current (Hyper page mode (EDO))		I_{CC4}	$\overline{RAS} \leq V_{IL\ (MAX.)}$, $\overline{CAS}$ cycling	t_{RAC} = 50 ns		120	mA	1, 2, 5
			$t_{HPC} = t_{HPC\ (MIN.)}$, I_O = 0 mA	t_{RAC} = 60 ns		100		
$\overline{CAS}$ before $\overline{RAS}$ refresh current		I_{CC5}	$\overline{RAS}$ cycling	t_{RAC} = 50 ns		150	mA	1, 2
			$t_{RC} = t_{RC\ (MIN.)}$, I_O = 0 mA	t_{RAC} = 60 ns		130		
$\overline{CAS}$ before $\overline{RAS}$ long refresh current (4,096 cycles/128 ms, only for the μPD42S65165)		I_{CC6}	$\overline{CAS}$ before $\overline{RAS}$ refresh: t_{RC} = 31.3 μs, $\overline{RAS}$, $\overline{CAS}$: V_{CC} – 0.2 V ≤ $V_{IH} \leq V_{IH\ (MAX.)}$, 0 V ≤ $V_{IL} \leq$ 0.2 V	$t_{RAS} \leq$ 300 ns		500	μA	1, 2
			Standby: $\overline{RAS}$, $\overline{CAS} \geq V_{CC}$ – 0.2 V, Address: V_{IH} or V_{IL}, $\overline{WE}$, $\overline{OE}$: V_{IH}, I_O = 0 mA	$t_{RAS} \leq$ 1 μs		600	μA	1, 2
$\overline{CAS}$ before $\overline{RAS}$ self refresh current (only for the μPD42S65165)		I_{CC7}	$\overline{RAS}$, $\overline{CAS}$: t_{RASS} = 5 ms, V_{CC} – 0.2 V ≤ $V_{IH} \leq V_{IH\ (MAX.)}$, 0 V ≤ $V_{IL} \leq$ 0.2 V, I_O = 0 mA			400	μA	2
Input leakage current		$I_{I\ (L)}$	V_I = 0 to 3.6 V, All other pins not under test = 0 V		–5	+5	μA	
Output leakage current		$I_{O\ (L)}$	V_O = 0 to 3.6 V, Output is disabled (Hi-Z)		–5	+5	μA	
High level output voltage		V_{OH}	I_O = –2.0 mA		2.4		V	
Low level output voltage		V_{OL}	I_O = +2.0 mA			0.4	V	

Notes 1. I_{CC1}, I_{CC3}, I_{CC4}, I_{CC5} and I_{CC6} depend on cycle rates (t_{RC} and t_{HPC}).

2. Specified values are obtained with outputs unloaded.

3. I_{CC1} and I_{CC3} are measured assuming that address can be changed once or less during $\overline{RAS} \leq V_{IL\ (MAX.)}$ and $\overline{CAS} \geq V_{IH\ (MIN.)}$.

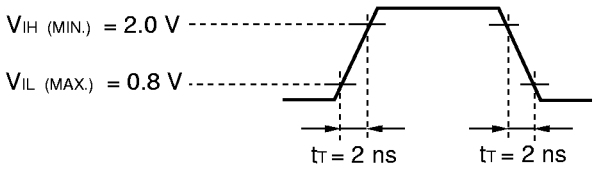
4. I_{CC3} is measured assuming that all column address inputs are held at either high or low.

5. I_{CC4} is measured assuming that all column address inputs are switched only once during each Hyper page (EDO) cycle.

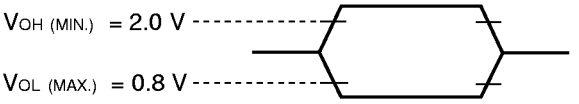
AC Characteristics (Recommended Operating Conditions unless otherwise noted)

AC Characteristics Test Conditions

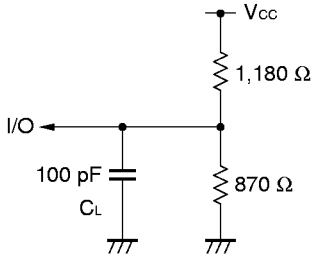
(1) Input timing specification



(2) Output timing specification



(3) Output load condition



Common to Read, Write, Read Modify Write Cycle

Parameter		Symbol	t_{RAC} = 50 ns		t_{RAC} = 60 ns		Unit	Notes
			MIN.	MAX.	MIN.	MAX.		
Read / Write cycle time		t_{RC}	84	–	104	–	ns	
$\overline{RAS}$ precharge time		t_{RP}	30	–	40	–	ns	
$\overline{CAS}$ precharge time		t_{CPN}	7	–	10	–	ns	
$\overline{RAS}$ pulse width		t_{RAS}	50	10,000	60	10,000	ns	1
$\overline{CAS}$ pulse width		t_{CAS}	8	10,000	10	10,000	ns	
$\overline{RAS}$ hold time		t_{RSH}	13	–	15	–	ns	
$\overline{CAS}$ hold time		t_{CSH}	38	–	40	–	ns	
$\overline{RAS}$ to $\overline{CAS}$ delay time		t_{RCD}	11	37	14	45	ns	2
$\overline{RAS}$ to column address delay time		t_{RAD}	9	25	12	30	ns	2
$\overline{CAS}$ to $\overline{RAS}$ precharge time		t_{CRP}	5	–	5	–	ns	3
Row address setup time		t_{ASR}	0	–	0	–	ns	
Row address hold time		t_{RAH}	7	–	10	–	ns	
Column address setup time		t_{ASC}	0	–	0	–	ns	
Column address hold time		t_{CAH}	7	–	10	–	ns	
$\overline{OE}$ lead time referenced to $\overline{RAS}$		t_{OES}	0	–	0	–	ns	
$\overline{CAS}$ to data setup time		t_{CLZ}	0	–	0	–	ns	
$\overline{OE}$ to data setup time		t_{OLZ}	0	–	0	–	ns	
$\overline{OE}$ to data delay time		t_{OED}	10	–	13	–	ns	
Masked byte write hold time referenced to $\overline{RAS}$		t_{MRH}	0	–	0	–	ns	
Transition time (rise and fall)		t_T	1	50	1	50	ns	
Refresh time	μPD42S65165	t_{REF}	–	128	–	128	ms	4
	μPD4265165		–	64	–	64	ms	

Notes 1. In $\overline{CAS}$ before $\overline{RAS}$ refresh cycles, $t_{RAS\ (MAX.)}$ is 100 μs. If 10 μs < t_{RAS} < 100 μs, $\overline{RAS}$ precharge time for $\overline{CAS}$ before $\overline{RAS}$ self refresh (t_{RPS}) is applied.

2. For read cycles, access time is defined as follows:

Input conditions	Access time	Access time from $\overline{RAS}$
$t_{RAD} \leq t_{RAD\ (MAX.)}$ and $t_{RCD} \leq t_{RCD\ (MAX.)}$	$t_{RAC\ (MAX.)}$	$t_{RAC\ (MAX.)}$
$t_{RAD} > t_{RAD\ (MAX.)}$ and $t_{RCD} \leq t_{RCD\ (MAX.)}$	$t_{AA\ (MAX.)}$	$t_{RAD} + t_{AA\ (MAX.)}$
$t_{RCD} > t_{RCD\ (MAX.)}$	$t_{CAC\ (MAX.)}$	$t_{RCD} + t_{CAC\ (MAX.)}$

$t_{RAD\ (MAX.)}$ and $t_{RCD\ (MAX.)}$ are specified as reference points only; they are not restrictive operating parameters. They are used to determine which access time (t_{RAC}, t_{AA} or t_{CAC}) is to be used for finding out when output data will be available. Therefore, the input conditions $t_{RAD} \geq t_{RAD\ (MAX.)}$ and $t_{RCD} \geq t_{RCD\ (MAX.)}$ will not cause any operation problems.

3. $t_{CRP\ (MIN.)}$ requirement is applied to $\overline{RAS}$, $\overline{CAS}$ cycles.

4. This specification is applied only to the μPD42S65165.

Read Cycle

Parameter	Symbol	t_{RAC} = 50 ns		t_{RAC} = 60 ns		Unit	Notes
		MIN.	MAX.	MIN.	MAX.		
Access time from $\overline{RAS}$	t_{RAC}	–	50	–	60	ns	1
Access time from $\overline{CAS}$	t_{CAC}	–	15	–	15	ns	1
Access time from column address	t_{AA}	–	25	–	30	ns	1
Access time from $\overline{OE}$	t_{OEA}	–	13	–	15	ns	
Column address lead time referenced to $\overline{RAS}$	t_{RAL}	25	–	30	–	ns	
Read command setup time	t_{RCS}	0	–	0	–	ns	
Read command hold time referenced to $\overline{RAS}$	t_{RRH}	0	–	0	–	ns	2
Read command hold time referenced to $\overline{CAS}$	t_{RCH}	0	–	0	–	ns	2
Output buffer turn-off delay time from $\overline{OE}$	t_{OEZ}	0	10	0	13	ns	3
$\overline{CAS}$ hold time to $\overline{OE}$	t_{CHO}	5	–	5	–	ns	4

Notes 1. For read cycles, access time is defined as follows:

Input conditions	Access time	Access time from $\overline{RAS}$
$t_{RAD} \leq t_{RAD\ (MAX.)}$ and $t_{RCD} \leq t_{RCD\ (MAX.)}$	$t_{RAC\ (MAX.)}$	$t_{RAC\ (MAX.)}$
$t_{RAD} > t_{RAD\ (MAX.)}$ and $t_{RCD} \leq t_{RCD\ (MAX.)}$	$t_{AA\ (MAX.)}$	$t_{RAD} + t_{AA\ (MAX.)}$
$t_{RCD} > t_{RCD\ (MAX.)}$	$t_{CAC\ (MAX.)}$	$t_{RCD} + t_{CAC\ (MAX.)}$

$t_{RAD\ (MAX.)}$ and $t_{RCD\ (MAX.)}$ are specified as reference points only; they are not restrictive operating parameters. They are used to determine which access time (t_{RAC}, t_{AA} or t_{CAC}) is to be used for finding out when output data will be available. Therefore, the input conditions $t_{RAD} \geq t_{RAD\ (MAX.)}$ and $t_{RCD} \geq t_{RCD\ (MAX.)}$ will not cause any operation problems.

2. Either $t_{RCH\ (MIN.)}$ or $t_{RRH\ (MIN.)}$ should be met in read cycles.

3. $t_{OEZ(MAX.)}$ defines the time when the output achieves the condition of Hi-Z and is not referenced to V_{OH} or V_{OL}.

4. $\overline{WE}$: inactive (in read cycle)
$\overline{CAS}$: inactive, $\overline{OE}$: active·····t_{CHO} is effective.
$\overline{CAS}$, $\overline{OE}$: active·····t_{OCH} is effective.

Write Cycle

Parameter	Symbol	t_{RAC} = 50 ns		t_{RAC} = 60 ns		Unit	Notes
		MIN.	MAX.	MIN.	MAX.		
$\overline{WE}$ hold time referenced to $\overline{CAS}$	t_{WCH}	7	–	10	–	ns	1
$\overline{WE}$ pulse width	t_{WP}	7	–	10	–	ns	1
$\overline{WE}$ lead time referenced to $\overline{RAS}$	t_{RWL}	13	–	15	–	ns	
$\overline{WE}$ lead time referenced to $\overline{CAS}$	t_{CWL}	7	–	10	–	ns	
$\overline{WE}$ setup time	t_{WCS}	0	–	0	–	ns	2
$\overline{OE}$ hold time	t_{OEH}	0	–	0	–	ns	
Data-in setup time	t_{DS}	0	–	0	–	ns	3
Data-in hold time	t_{DH}	7	–	10	–	ns	3

Notes 1. $t_{WP\ (MIN.)}$ is applied to late write cycles or read modify write cycles. In early write cycles, $t_{WCH\ (MIN.)}$ should be met.

2. If $t_{WCS} \geq t_{WCS\ (MIN.)}$, the cycle is an early write cycle and the data out will remain Hi-Z through the entire cycle.

3. $t_{DS\ (MIN.)}$ and $t_{DH\ (MIN.)}$ are referenced to the $\overline{CAS}$ falling edge in early write cycles. In late write cycles and read modify write cycles, they are referenced to the $\overline{WE}$ falling edge.

Read Modify Write Cycle

Parameter	Symbol	t_{RAC} = 50 ns		t_{RAC} = 60 ns		Unit	Note
		MIN.	MAX.	MIN.	MAX.		
Read modify write cycle time	t_{RWC}	107	–	133	–	ns	
$\overline{RAS}$ to $\overline{WE}$ delay time	t_{RWD}	64	–	77	–	ns	1
$\overline{CAS}$ to $\overline{WE}$ delay time	t_{CWD}	27	–	32	–	ns	1
Column address to $\overline{WE}$ delay time	t_{AWD}	39	–	47	–	ns	1

Note 1. If $t_{WCS} \geq t_{WCS\ (MIN.)}$, the cycle is an early write cycle and the data out will remain Hi-Z through the entire cycle. If $t_{RWD} \geq t_{RWD\ (MIN.)}$, $t_{CWD} \geq t_{CWD\ (MIN.)}$, $t_{AWD} \geq t_{AWD\ (MIN.)}$ and $t_{CPWD} \geq t_{CPWD\ (MIN.)}$, the cycle is a read modify write cycle and the data out will contain data read from the selected cell. If neither of the above conditions is met, the state of the data out is indeterminate.

Hyper Page Mode (EDO)

Parameter	Symbol	t_{RAC} = 50 ns		t_{RAC} = 60 ns		Unit	Notes
		MIN.	MAX.	MIN.	MAX.		
Read / Write cycle time	t_{HPC}	20	–	25	–	ns	1
$\overline{RAS}$ pulse width	t_{RASP}	50	125,000	60	125,000	ns	
$\overline{CAS}$ pulse width	t_{HCAS}	8	10,000	10	10,000	ns	
$\overline{CAS}$ precharge time	t_{CP}	7	–	10	–	ns	
Access time from $\overline{CAS}$ precharge	t_{ACP}	–	30	–	35	ns	
$\overline{CAS}$ precharge to $\overline{WE}$ delay time	t_{CPWD}	41	–	52	–	ns	2
$\overline{RAS}$ hold time from $\overline{CAS}$ precharge	t_{RHCP}	30	–	35	–	ns	
Read modify write cycle time	t_{HPRWC}	52	–	66	–	ns	
Data output hold time	t_{DHC}	5	–	5	–	ns	
$\overline{OE}$ to $\overline{CAS}$ hold time	t_{OCH}	5	–	5	–	ns	3
$\overline{OE}$ precharge time	t_{OEP}	5	–	5	–	ns	
Output buffer turn-off delay from $\overline{WE}$	t_{WEZ}	0	10	0	13	ns	4, 5
$\overline{WE}$ pulse width	t_{WPZ}	7	–	10	–	ns	5
Output buffer turn-off delay from $\overline{RAS}$	t_{OFR}	0	10	0	13	ns	4, 5
Output buffer turn-off delay from $\overline{CAS}$	t_{OFC}	0	10	0	13	ns	4, 5

Notes 1. $t_{HPC\ (MIN.)}$ is applied to $\overline{CAS}$ access.

2. If $t_{WCS} \geq t_{WCS\ (MIN.)}$, the cycle is an early write cycle and the data out will remain Hi-Z through the entire cycle. If $t_{RWD} \geq t_{RWD\ (MIN.)}$, $t_{CWD} \geq t_{CWD\ (MIN.)}$, $t_{AWD} \geq t_{AWD\ (MIN.)}$ and $t_{CPWD} \geq t_{CPWD\ (MIN.)}$, the cycle is a read modify write cycle and the data out will contain data read from the selected cell. If neither of the above conditions is met, the state of the data out is indeterminate.

3. $\overline{WE}$: inactive (in read cycle)
$\overline{CAS}$: inactive, $\overline{OE}$: active ····· t_{CHO} is effective.
$\overline{CAS}$, $\overline{OE}$: active ····· t_{OCH} is effective.

4. $t_{OFC\ (MAX.)}$, $t_{OFR\ (MAX.)}$ and $t_{WEZ\ (MAX.)}$ define the time when the output achieves the conditions of Hi-Z and is not referenced to V_{OH} or V_{OL}.

5. To make I/Os to Hi-Z in read cycle, it is necessary to control $\overline{RAS}$, $\overline{CAS}$, $\overline{WE}$, $\overline{OE}$ as follows. The effective specification depends on state of each signal.

(1) Both $\overline{RAS}$ and $\overline{CAS}$ are inactive (at the end of the read cycle)
$\overline{WE}$: inactive, $\overline{OE}$: active
t_{OFC} is effective when $\overline{RAS}$ is inactivated before $\overline{CAS}$ is inactivated.
t_{OFR} is effective when $\overline{CAS}$ is inactivated before $\overline{RAS}$ is inactivated.
The slower of t_{OFC} and t_{OFR} becomes effective.

(2) Both $\overline{RAS}$ and $\overline{CAS}$ are active or either $\overline{RAS}$ or $\overline{CAS}$ is active (in read cycle)
$\overline{WE}$, $\overline{OE}$: inactive ····· t_{OEZ} is effective.
Both $\overline{RAS}$ and $\overline{CAS}$ are inactive or $\overline{RAS}$ is active and $\overline{CAS}$ is inactive (at the end of read cycle)
$\overline{WE}$, $\overline{OE}$: active and either t_{RRH} or t_{RCH} must be met ····· t_{WEZ} and t_{WPZ} are effective.
The faster of t_{OEZ} and t_{WEZ} becomes effective.

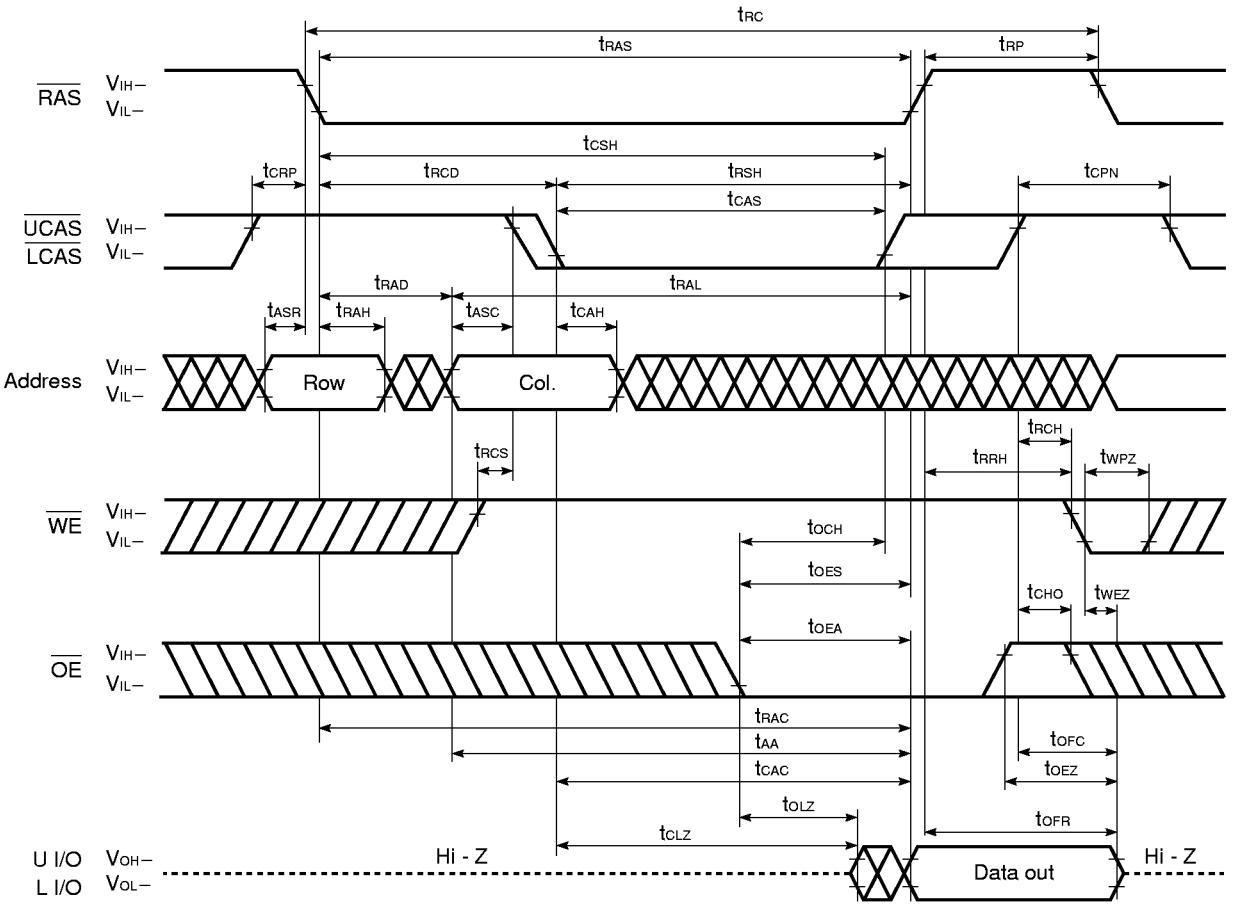
The faster of (1) and (2) becomes effective.

Refresh Cycle

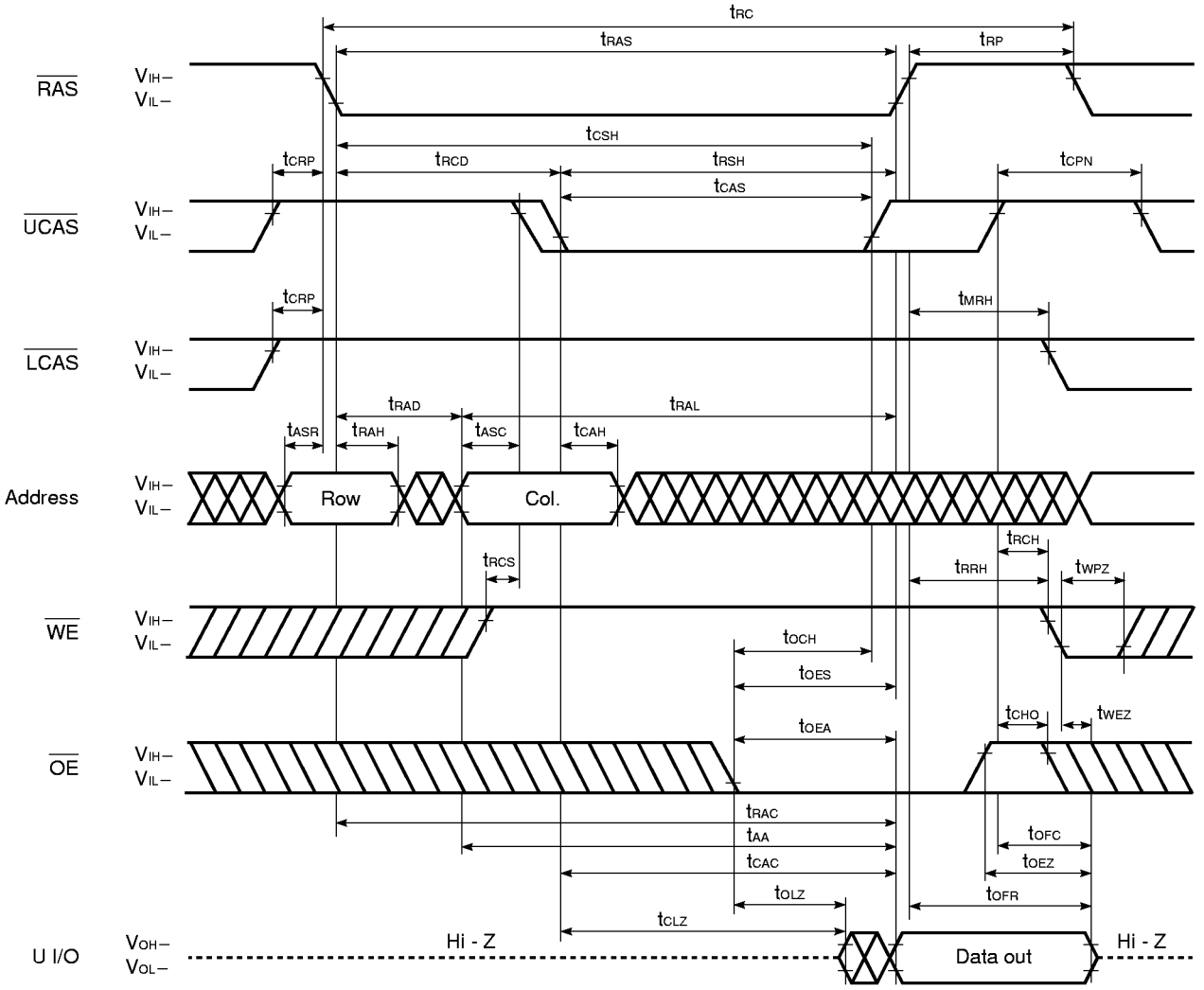
Parameter	Symbol	t_{RAC} = 50 ns		t_{RAC} = 60 ns		Unit	Note
		MIN.	MAX.	MIN.	MAX.		
$\overline{CAS}$ setup time	t_{CSR}	5	–	5	–	ns	
$\overline{CAS}$ hold time ($\overline{CAS}$ before $\overline{RAS}$ refresh)	t_{CHR}	10	–	10	–	ns	
$\overline{RAS}$ precharge $\overline{CAS}$ hold time	t_{RPC}	5	–	5	–	ns	
$\overline{RAS}$ pulse width ($\overline{CAS}$ before $\overline{RAS}$ self refresh)	t_{RASS}	100	–	100	–	μs	1
$\overline{RAS}$ precharge time ($\overline{CAS}$ before $\overline{RAS}$ self refresh)	t_{RPS}	90	–	110	–	ns	1
$\overline{CAS}$ hold time ($\overline{CAS}$ before $\overline{RAS}$ self refresh)	t_{CHS}	–50	–	–50	–	ns	1
$\overline{WE}$ setup time	t_{WSR}	10	–	10	–	ns	
$\overline{WE}$ hold time	t_{WHR}	15	–	15	–	ns	

Note 1. This specification is applied only to the μPD42S65165.

Read Cycle

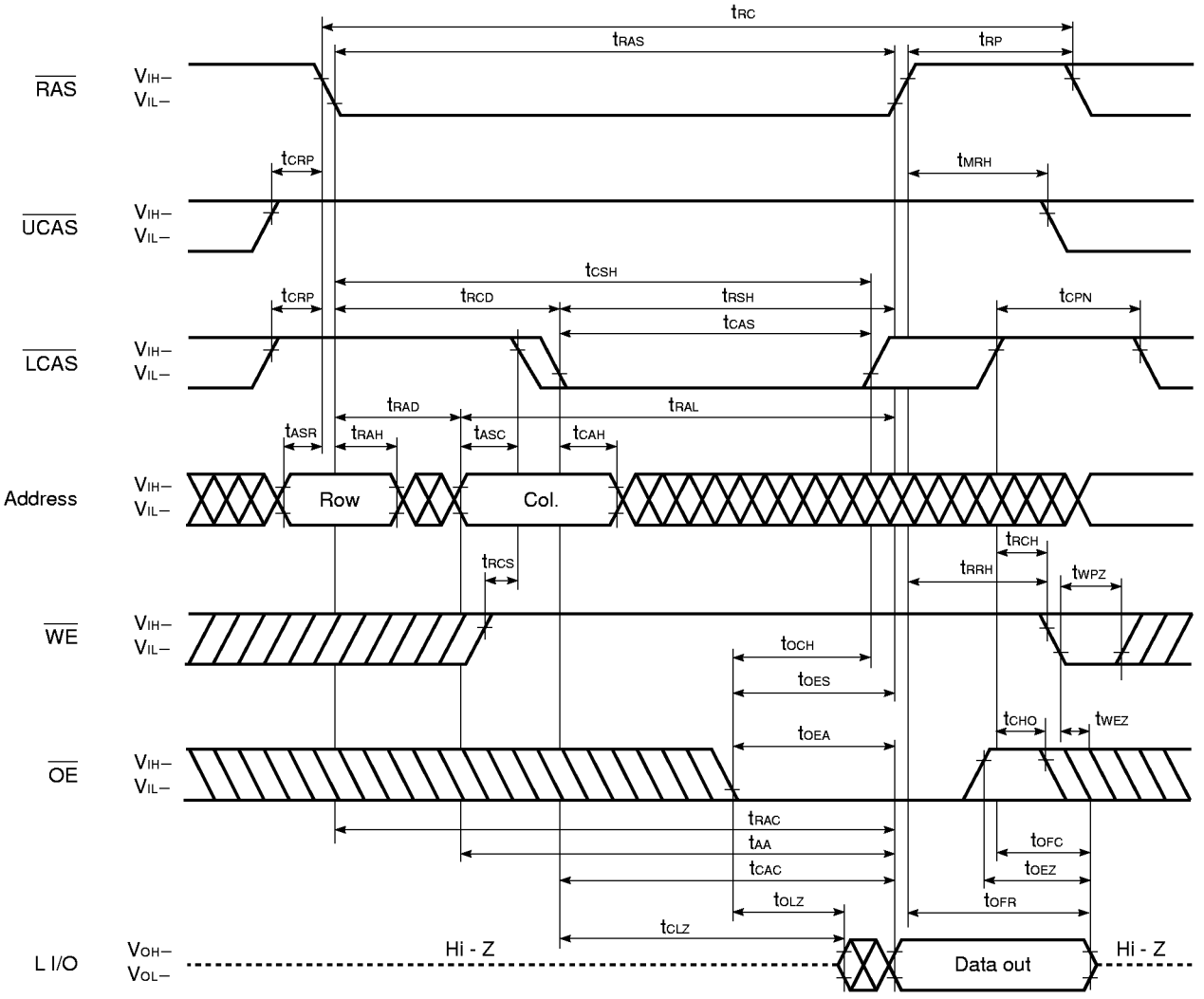

tRC
tRAS
tRP
RAS
VIH–
VIL–
tCSH
tCRP
tRCD
tRSH
tCPN
tCAS
UCAS
LCAS
tRAD
tRAL
tASR
tRAH
tASC
tCAH
Address
Row
Col.
tRCH
tRCS
tRRH
tWPZ
WE
tOCH
tOES
tCHO
tWEZ
tOEA
OE
tRAC
tAA
tOFC
tCAC
tOEZ
tOLZ
tOFR
tCLZ
U I/O
L I/O
VOH–
VOL–
Hi - Z
Data out
Hi - Z

Upper Byte Read Cycle



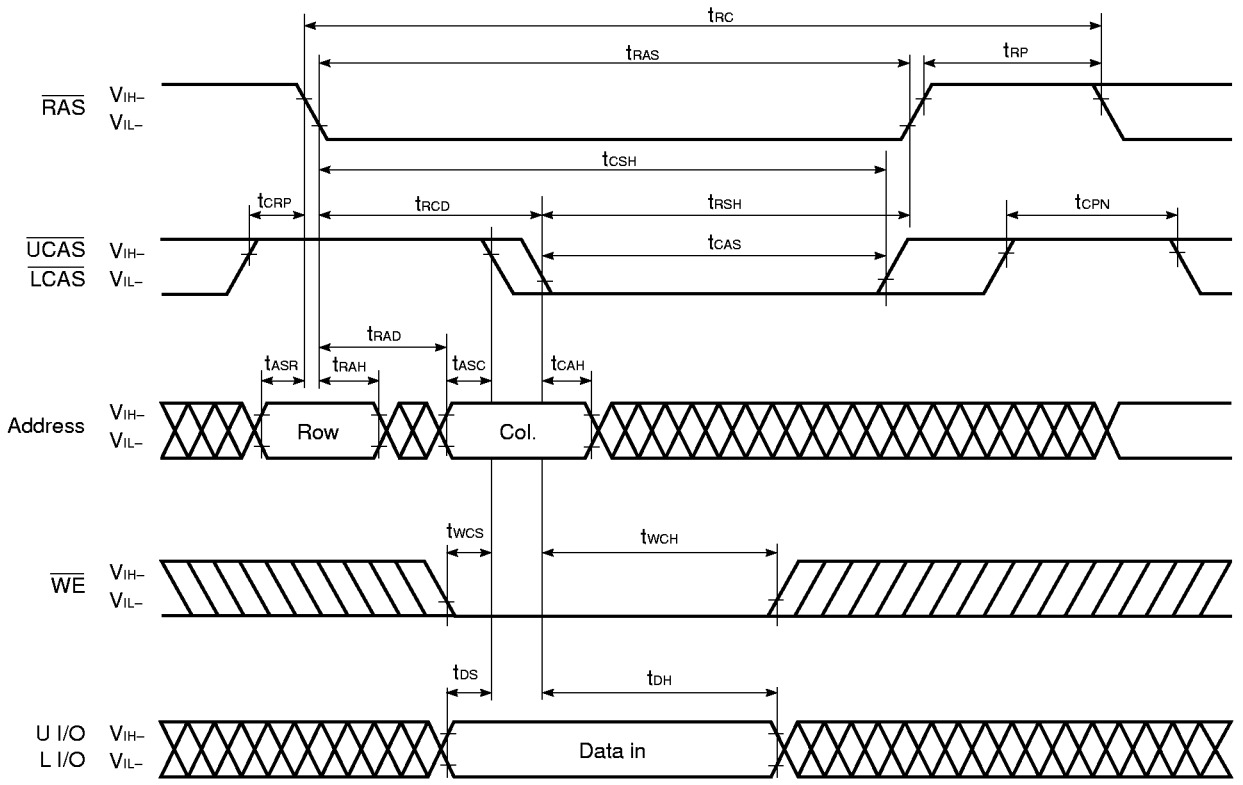
Remark L I/O: Hi-Z

Lower Byte Read Cycle



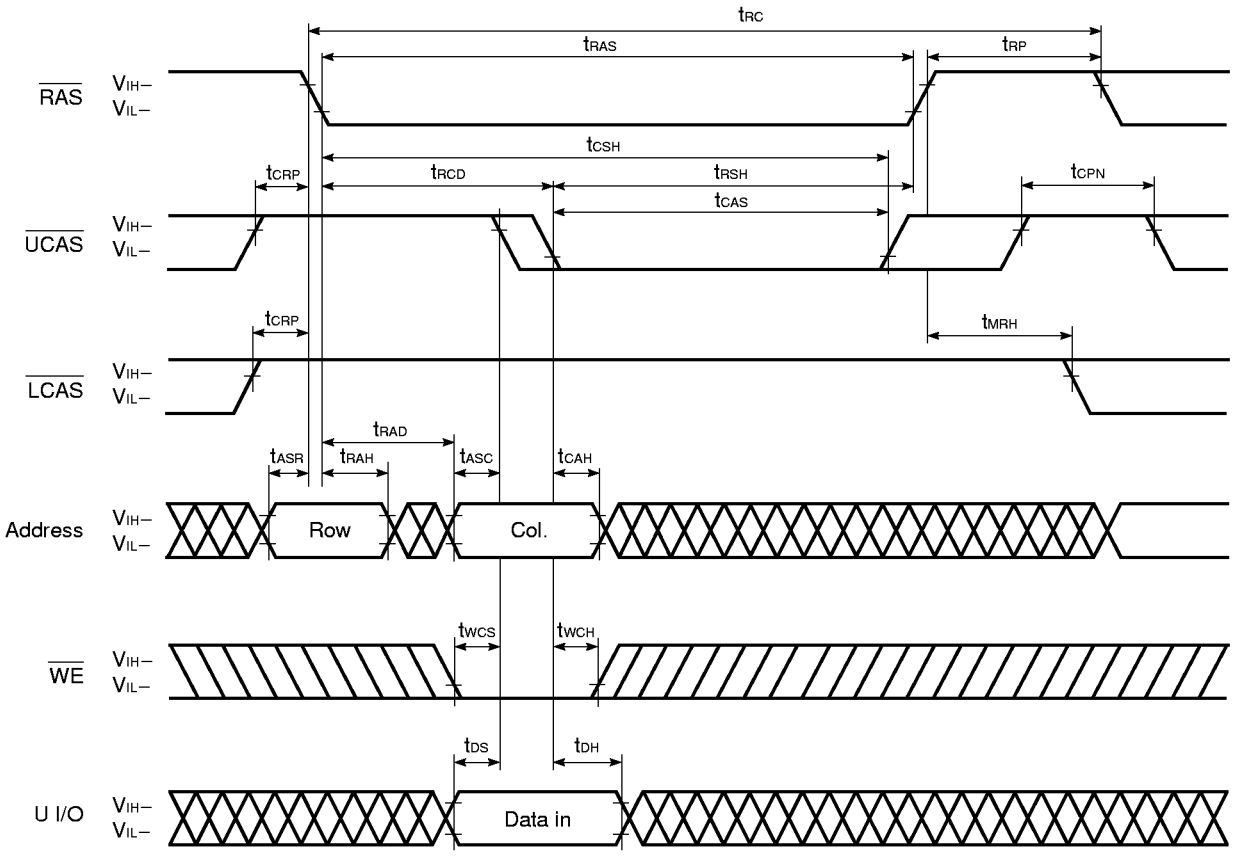
Remark U I/O: Hi-Z

Early Write Cycle



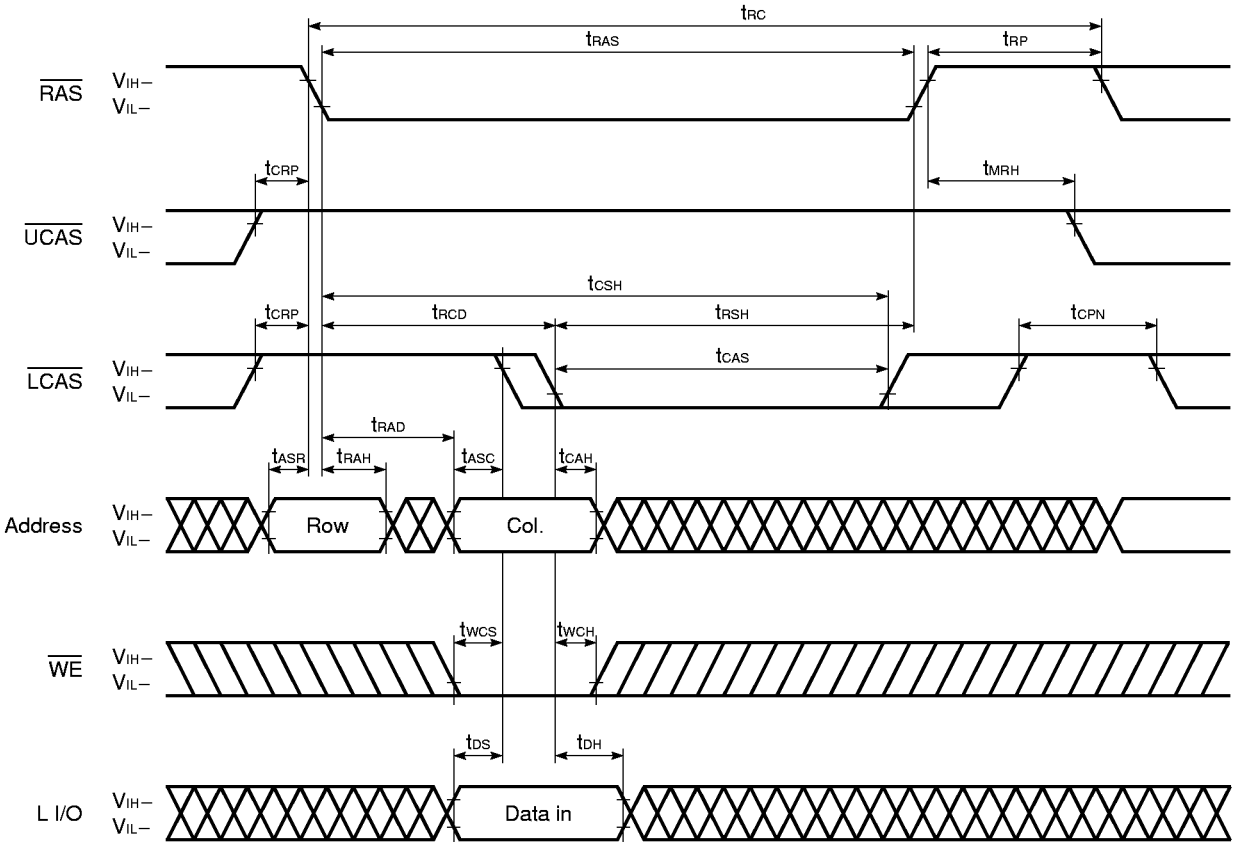
Remark $\overline{OE}$: Don't care

Upper Byte Early Write Cycle



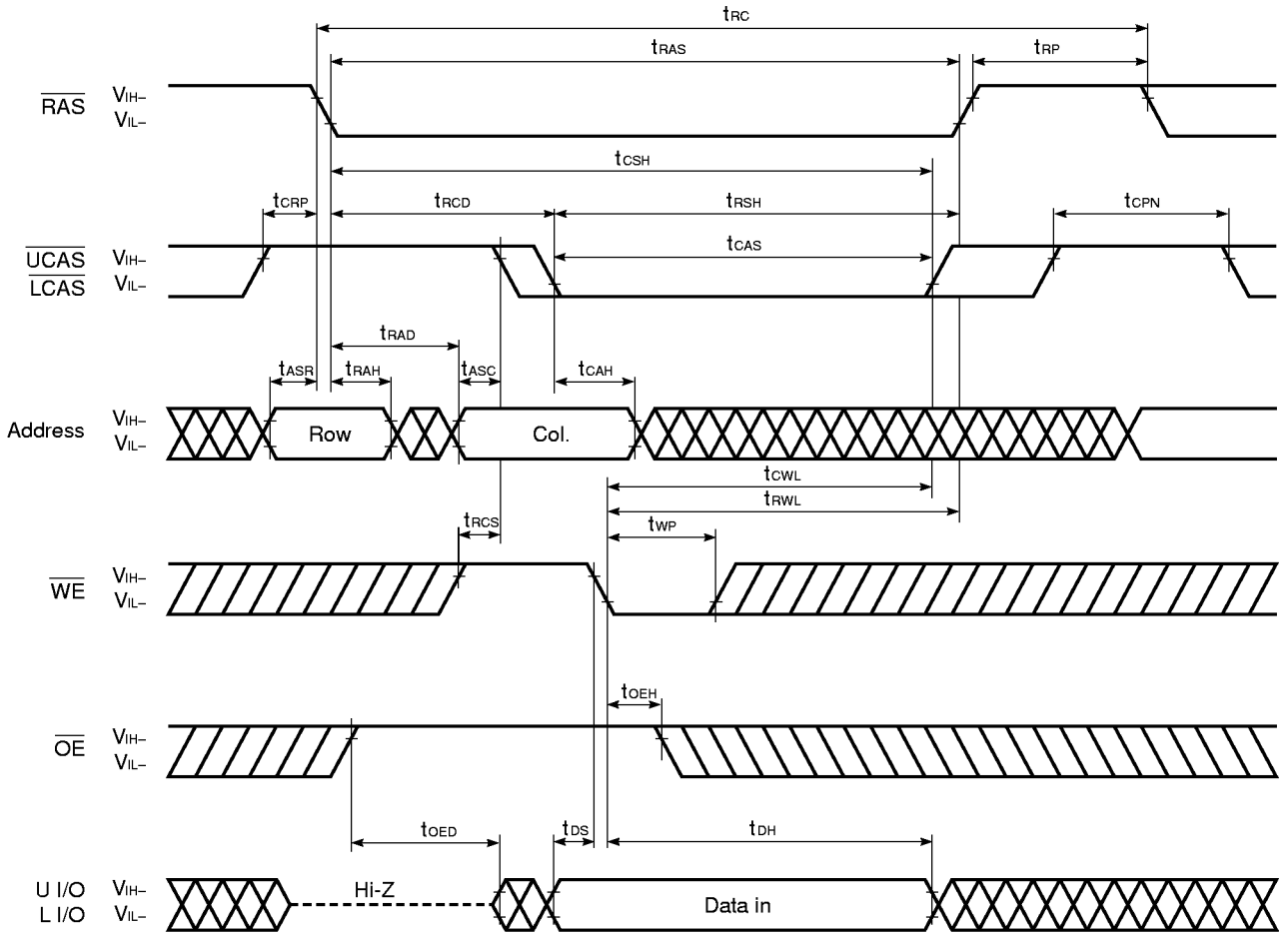
Remark $\overline{OE}$, L I/O: Don't care

Lower Byte Early Write Cycle

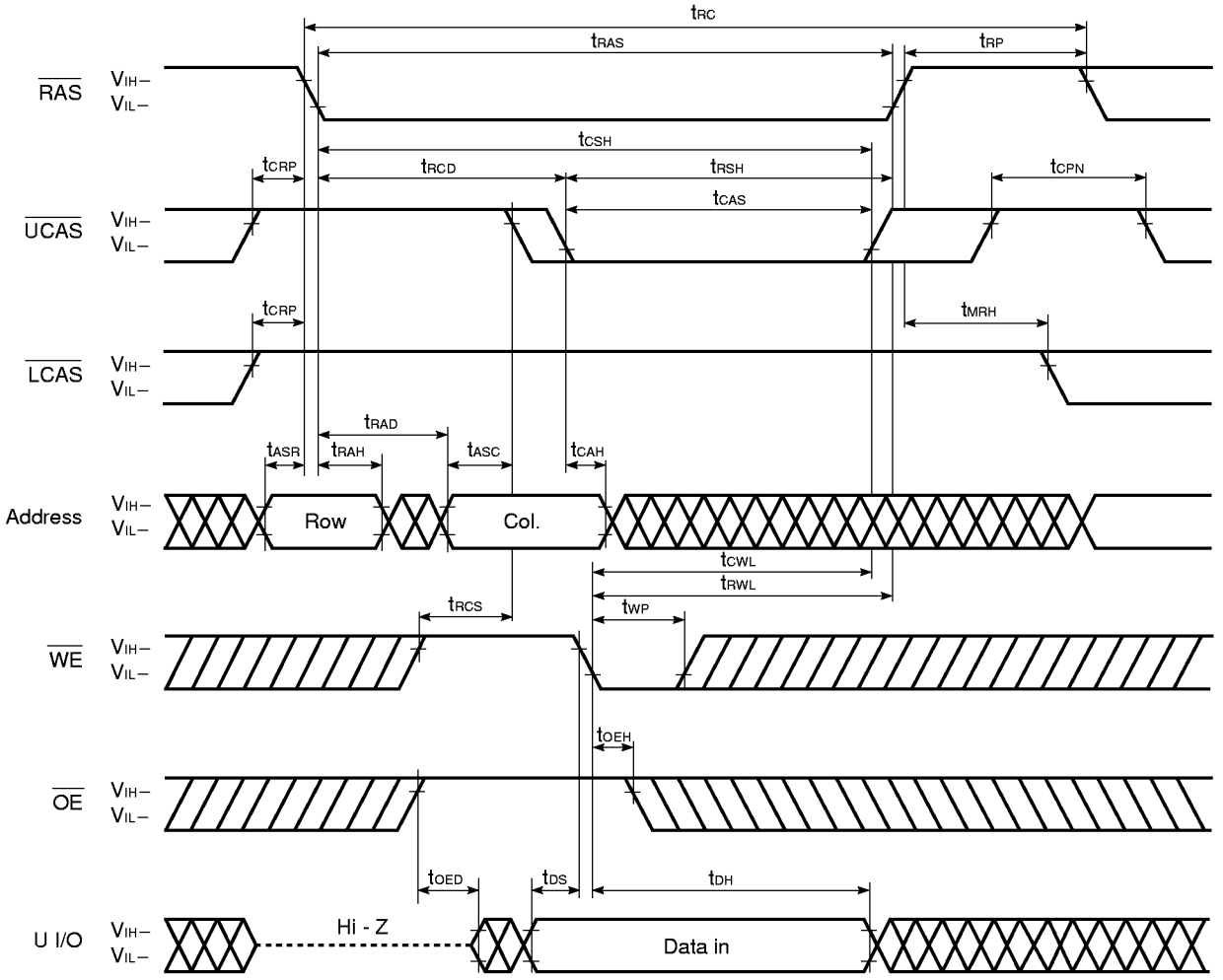


Remark $\overline{OE}$, U I/O: Don't care

Late Write Cycle

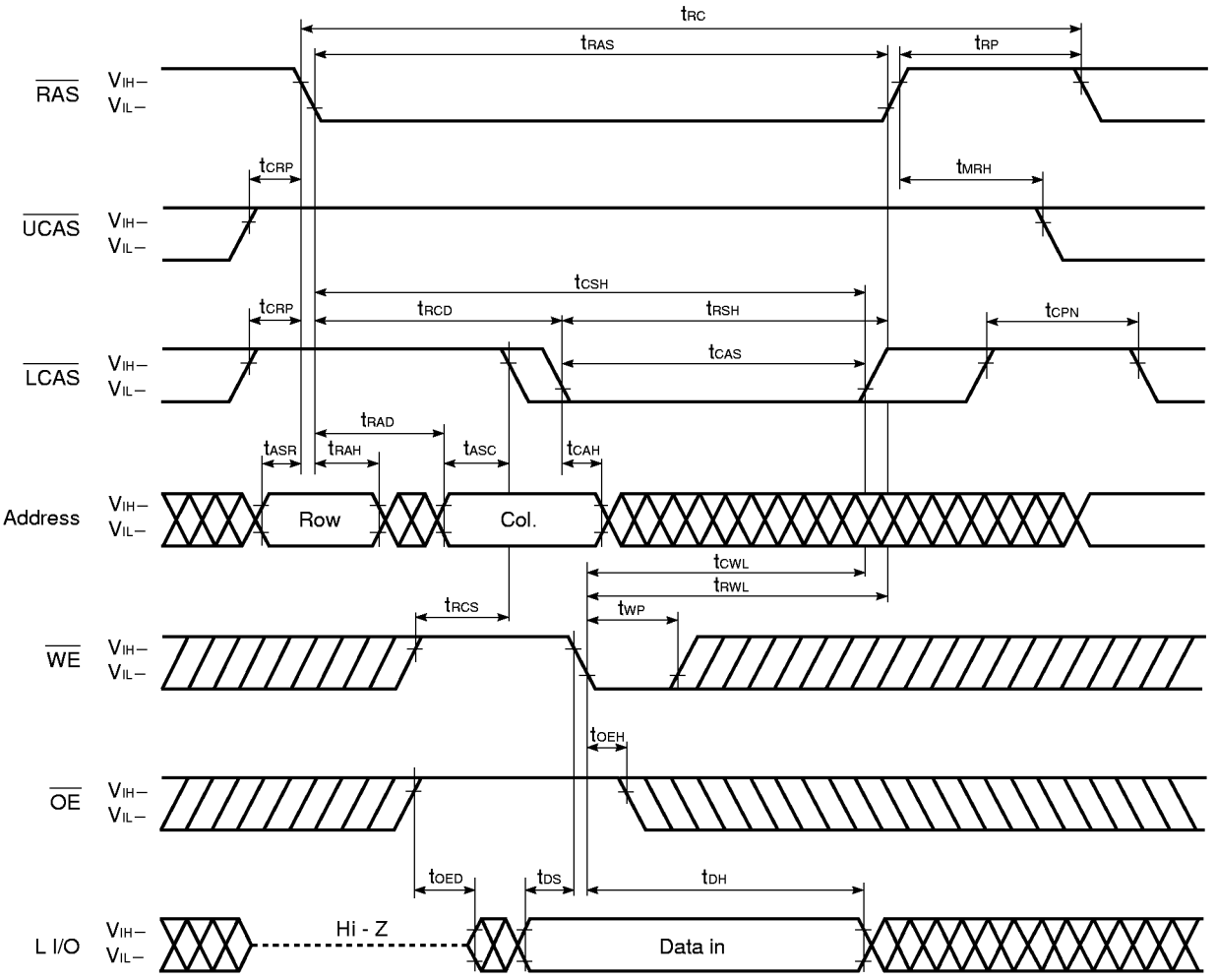


Upper Byte Late Write Cycle



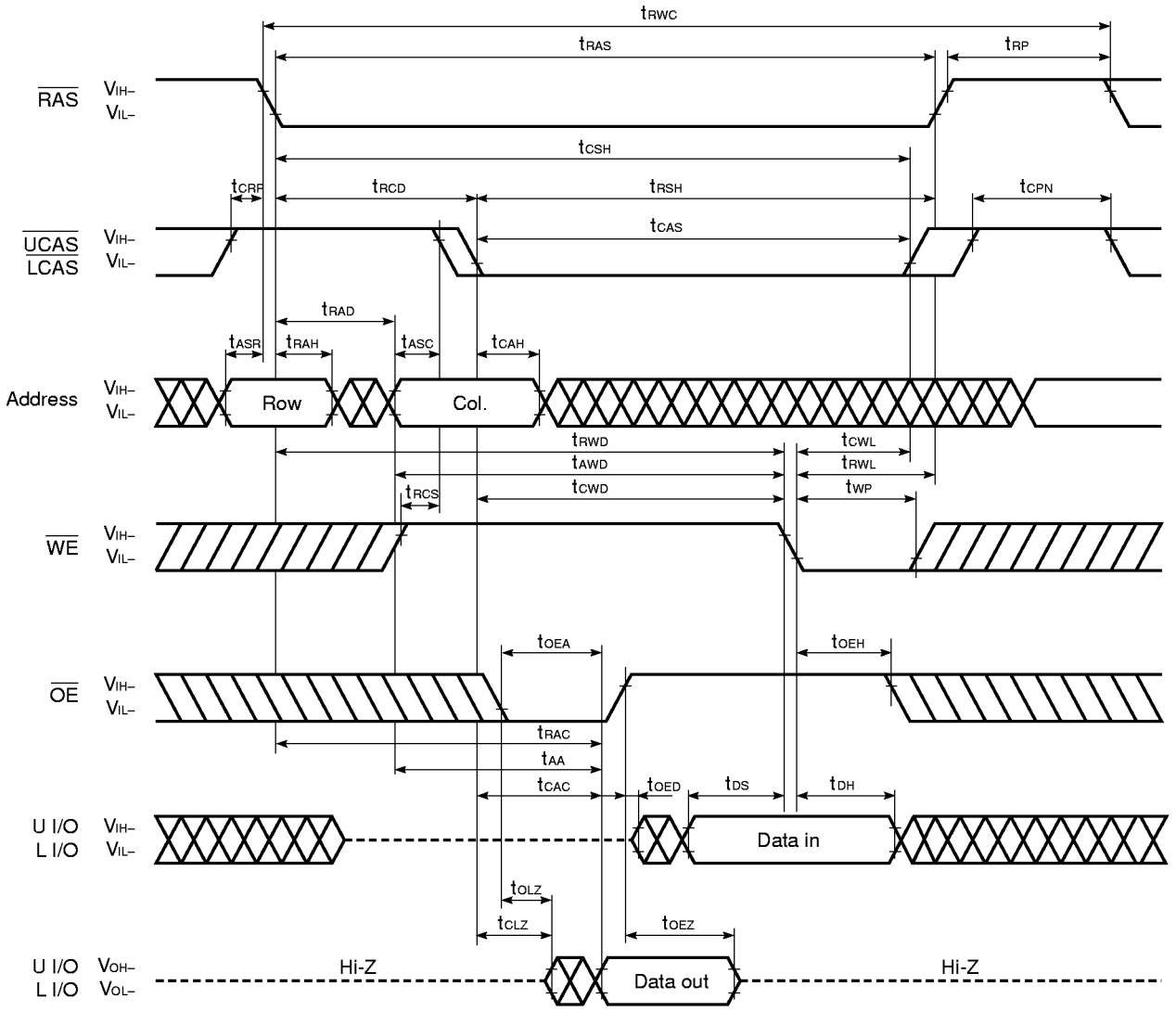
Remark L I/O: Don't care

Lower Byte Late Write Cycle

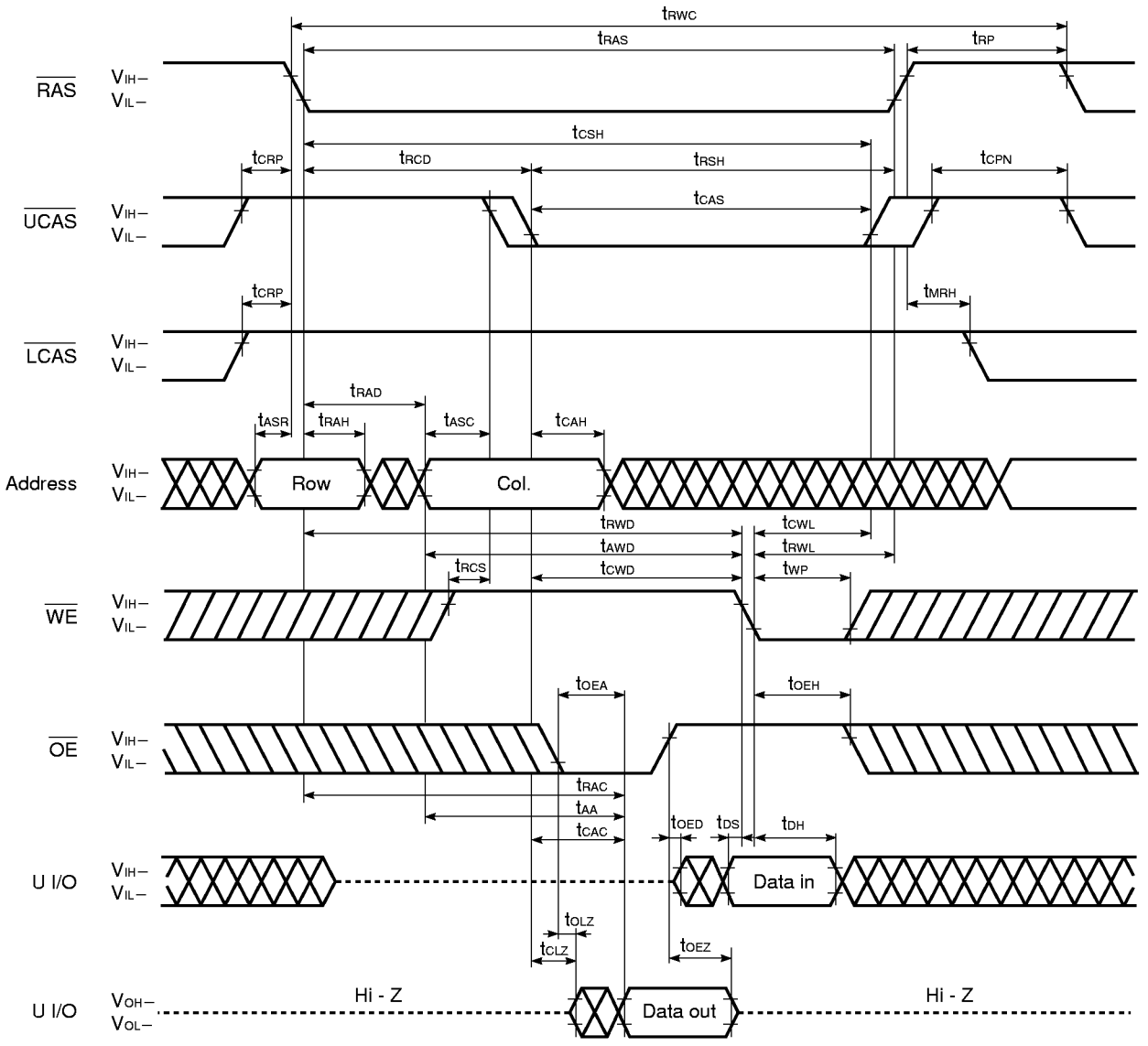


Remark U I/O: Don't care

Read Modify Write Cycle

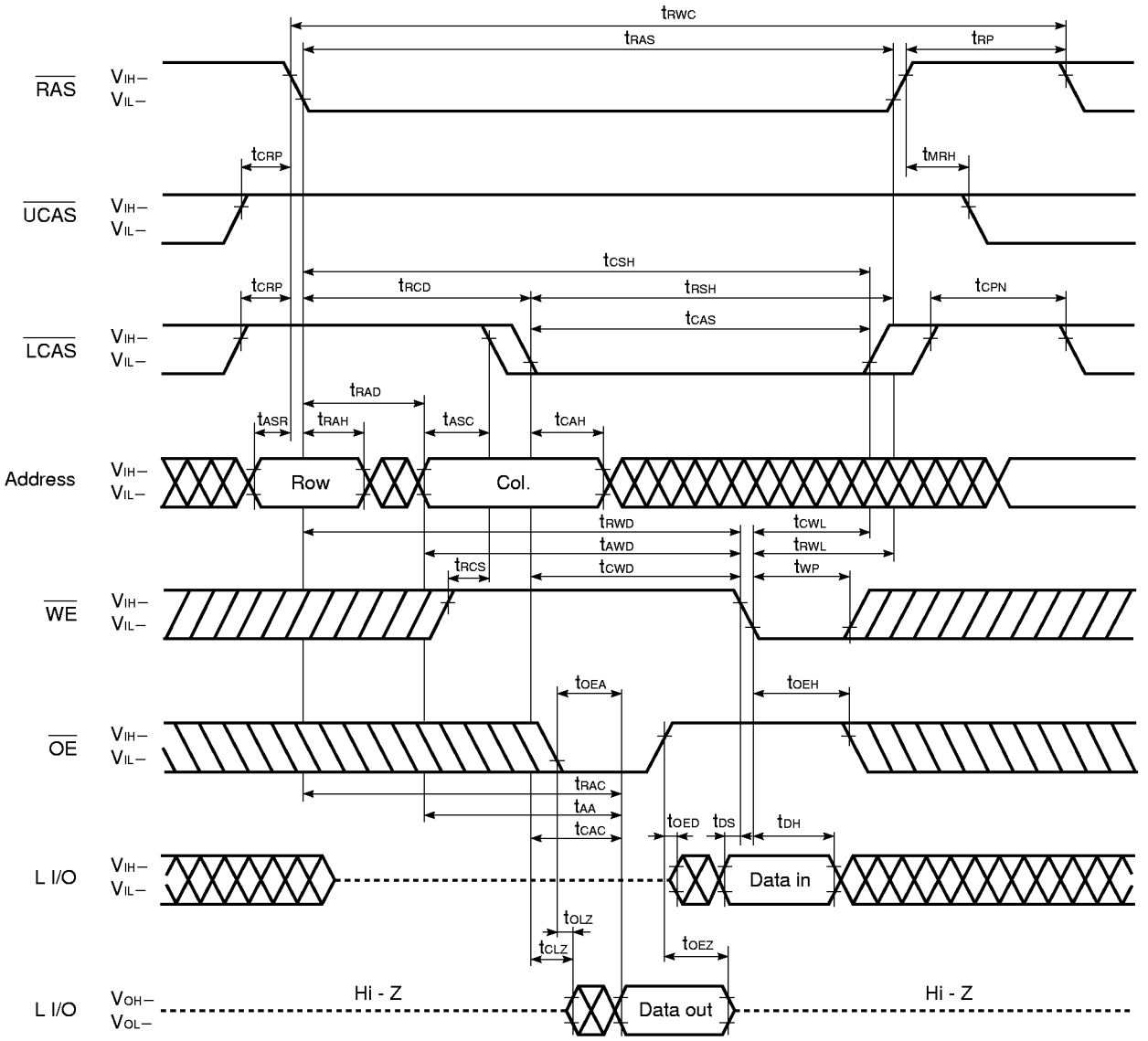


Upper Byte Read Modify Write Cycle



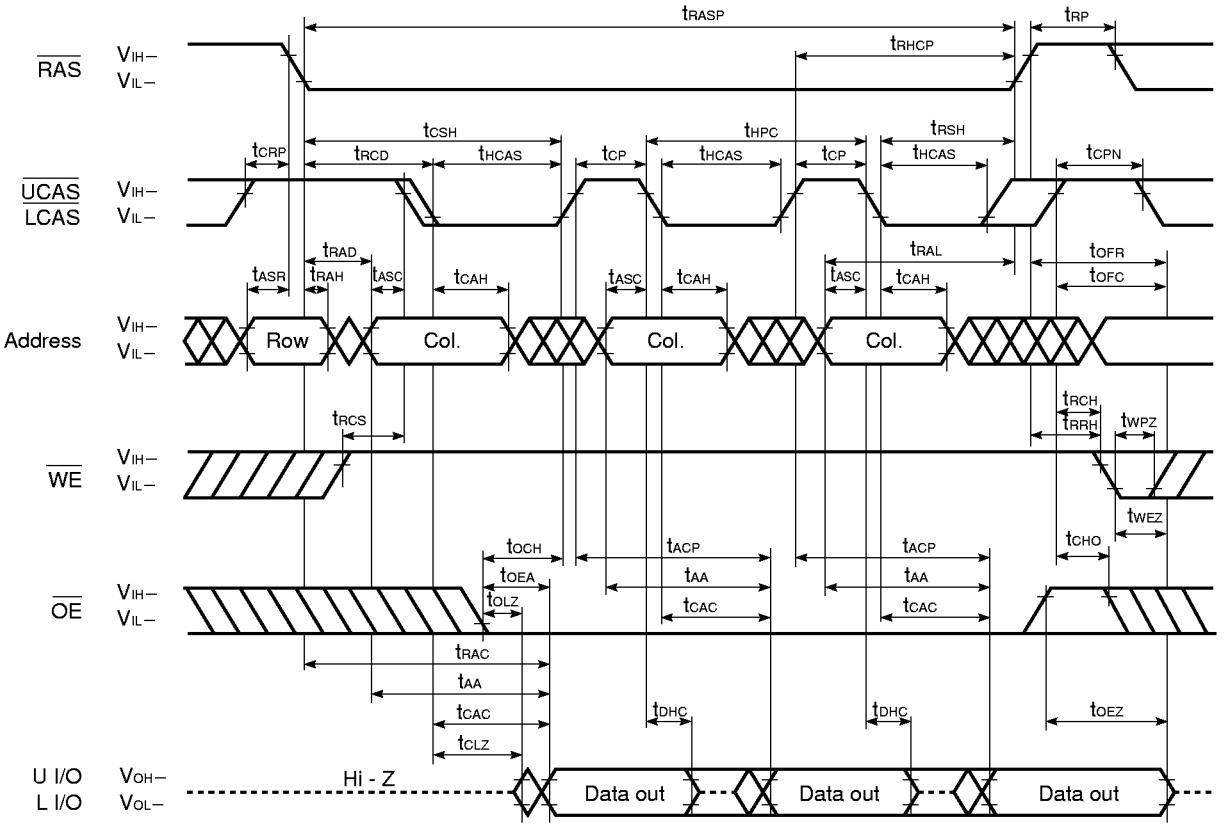
Remark In this cycle, the input data to Lower I/O is ineffective. The data out of that remains Hi-Z.

Lower Byte Read Modify Write Cycle



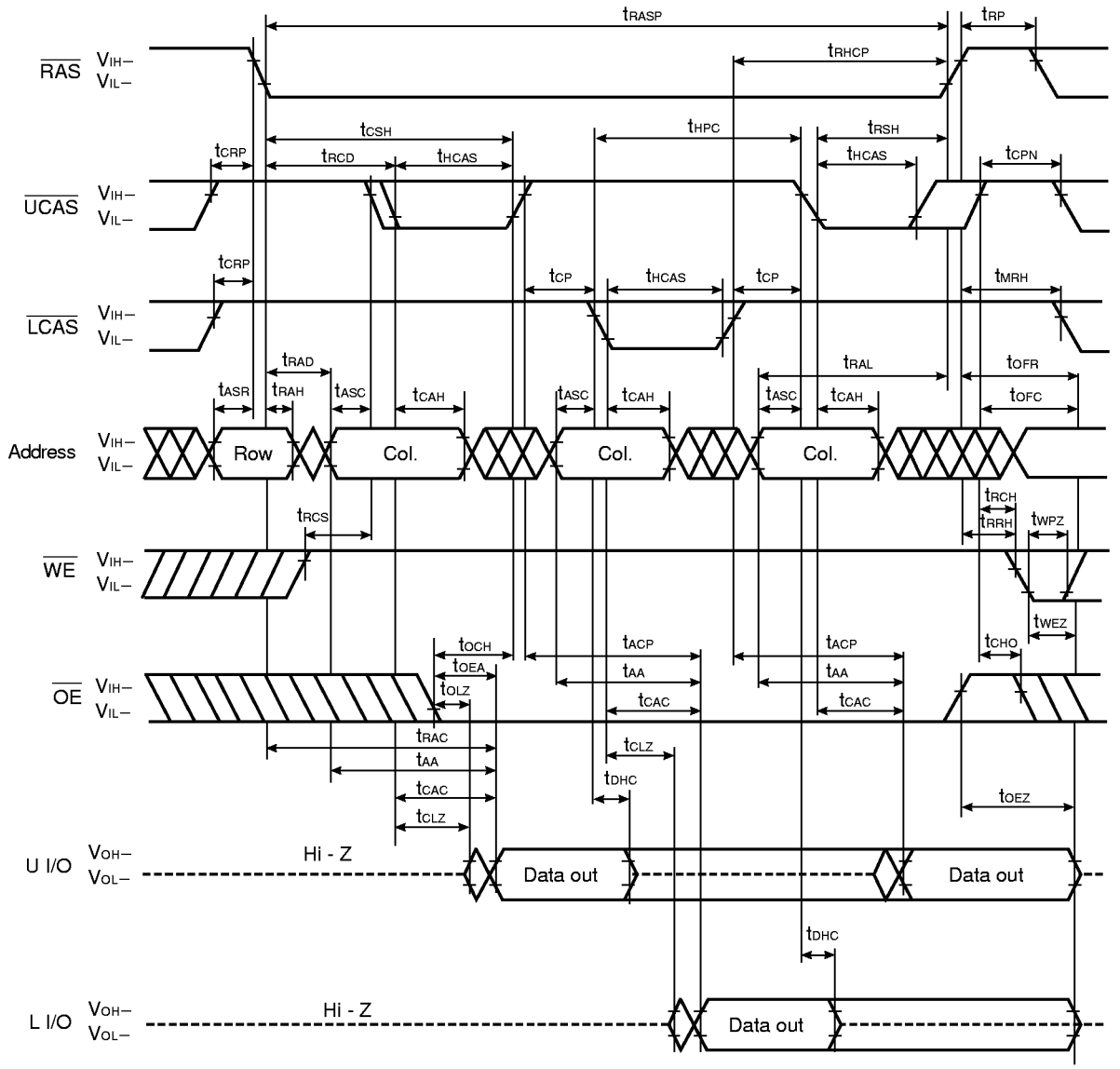
Remark In this cycle, the input data to Upper I/O is ineffective. The data out of that remains Hi-Z.

Hyper Page Mode (EDO) Read Cycle



Remark In the hyper page mode (EDO), read, write and read modify write cycles are available for each of the consecutive $\overline{CAS}$ cycles within the same $\overline{RAS}$ cycle.

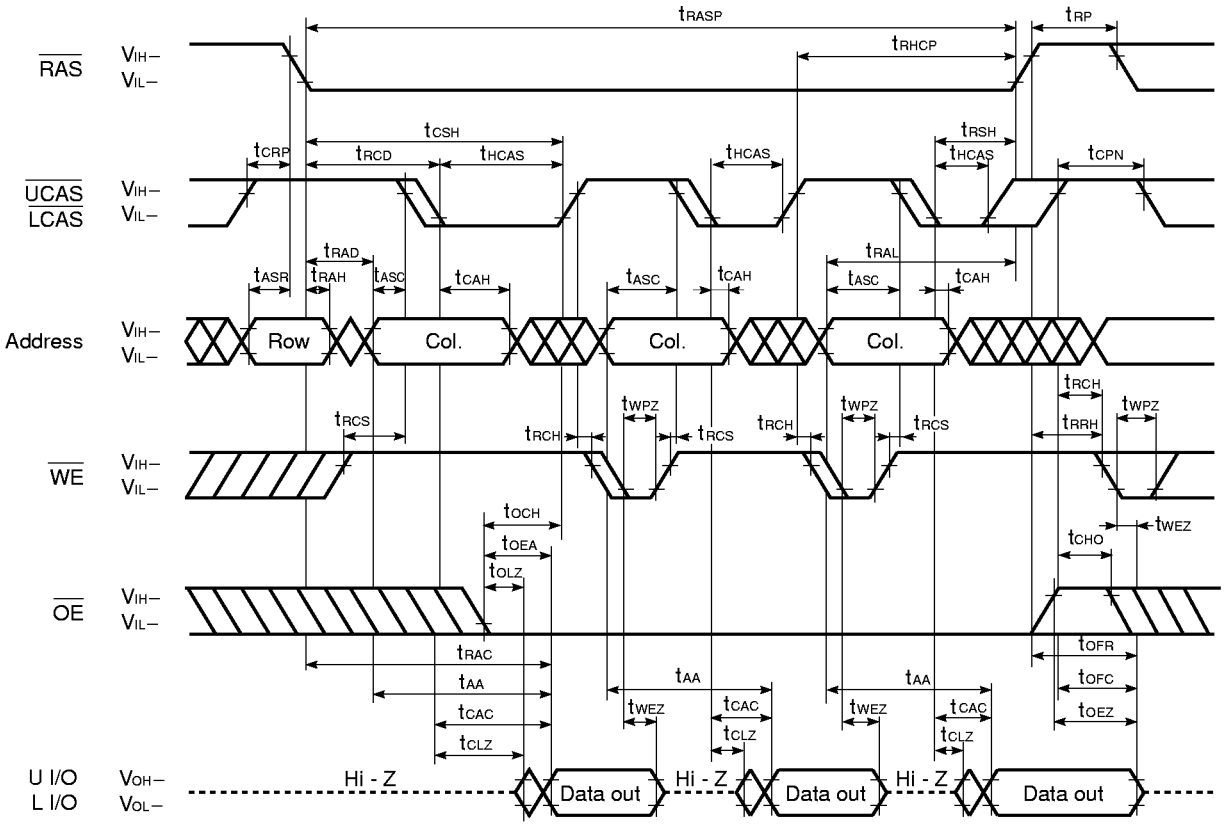
Hyper Page Mode (EDO) Byte Read Cycle



Remarks 1. In the hyper page mode (EDO), read, write and read modify write cycles are available for each of the consecutive $\overline{CAS}$ cycles within the same $\overline{RAS}$ cycle.

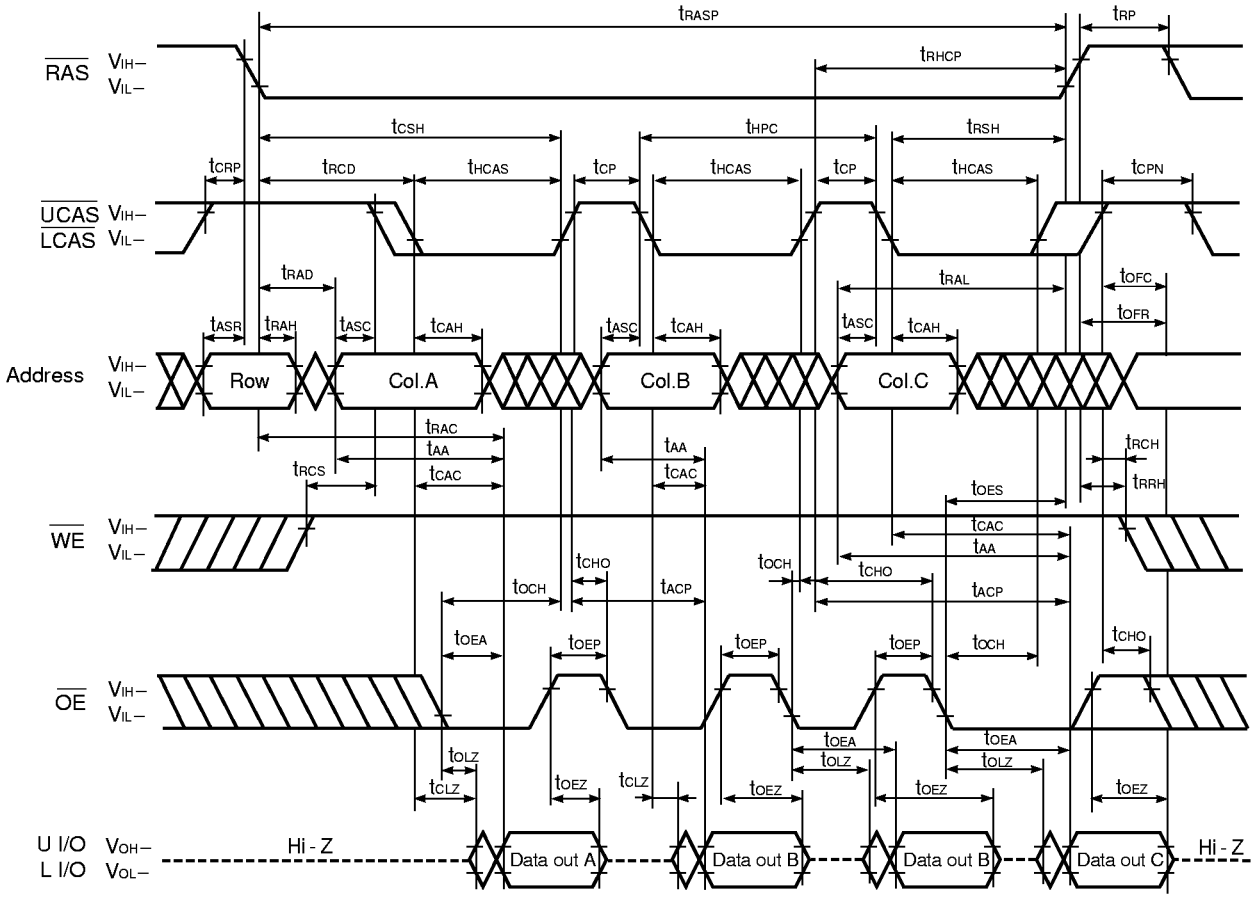
2. This cycle can be used to control either $\overline{UCAS}$ or $\overline{LCAS}$ only. Or, it can be used to control $\overline{UCAS}$ or $\overline{LCAS}$ simultaneously, or at random.

Hyper Page Mode (EDO) Read Cycle ($\overline{WE}$ Control)



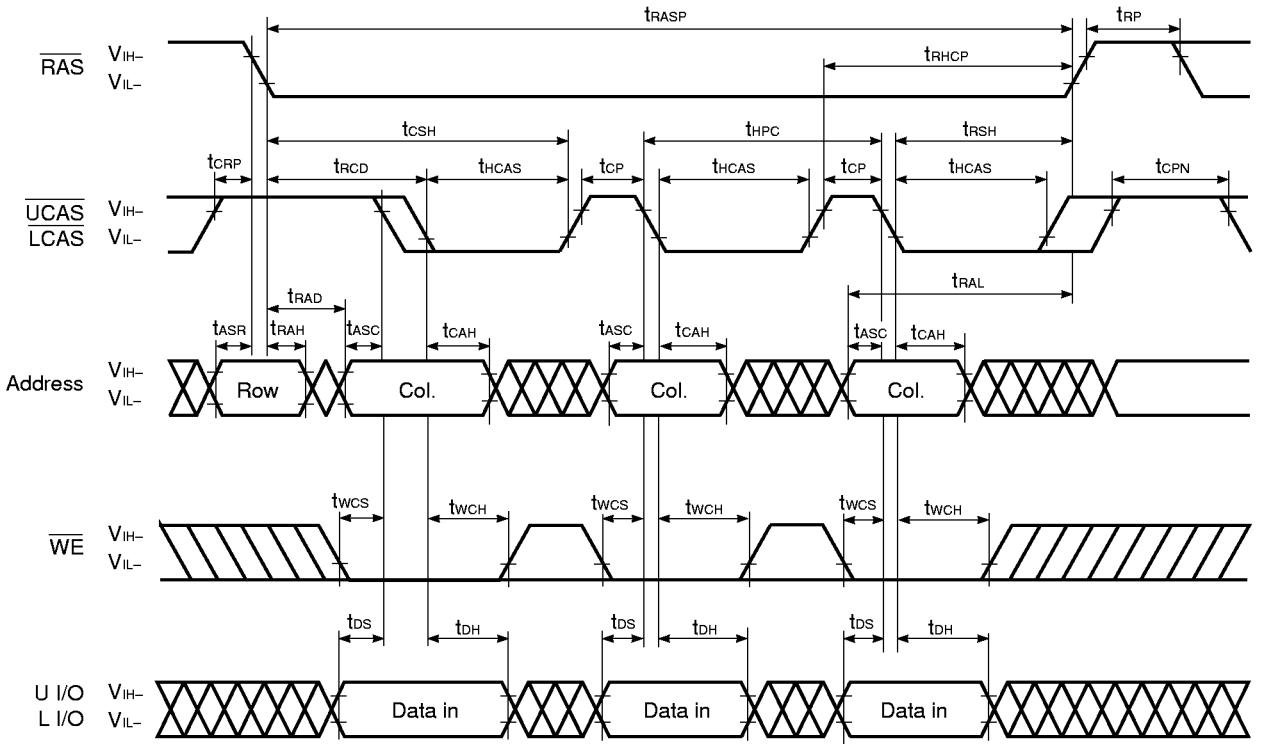
Remark In the hyper page mode (EDO), read, write and read modify write cycles are available for each of the consecutive $\overline{CAS}$ cycles within the same $\overline{RAS}$ cycle.

Hyper Page Mode (EDO) Read Cycle ($\overline{OE}$ Control)



Remark In the hyper page mode (EDO), read, write and read modify write cycles are available for each of the consecutive $\overline{CAS}$ cycles within the same $\overline{RAS}$ cycle.

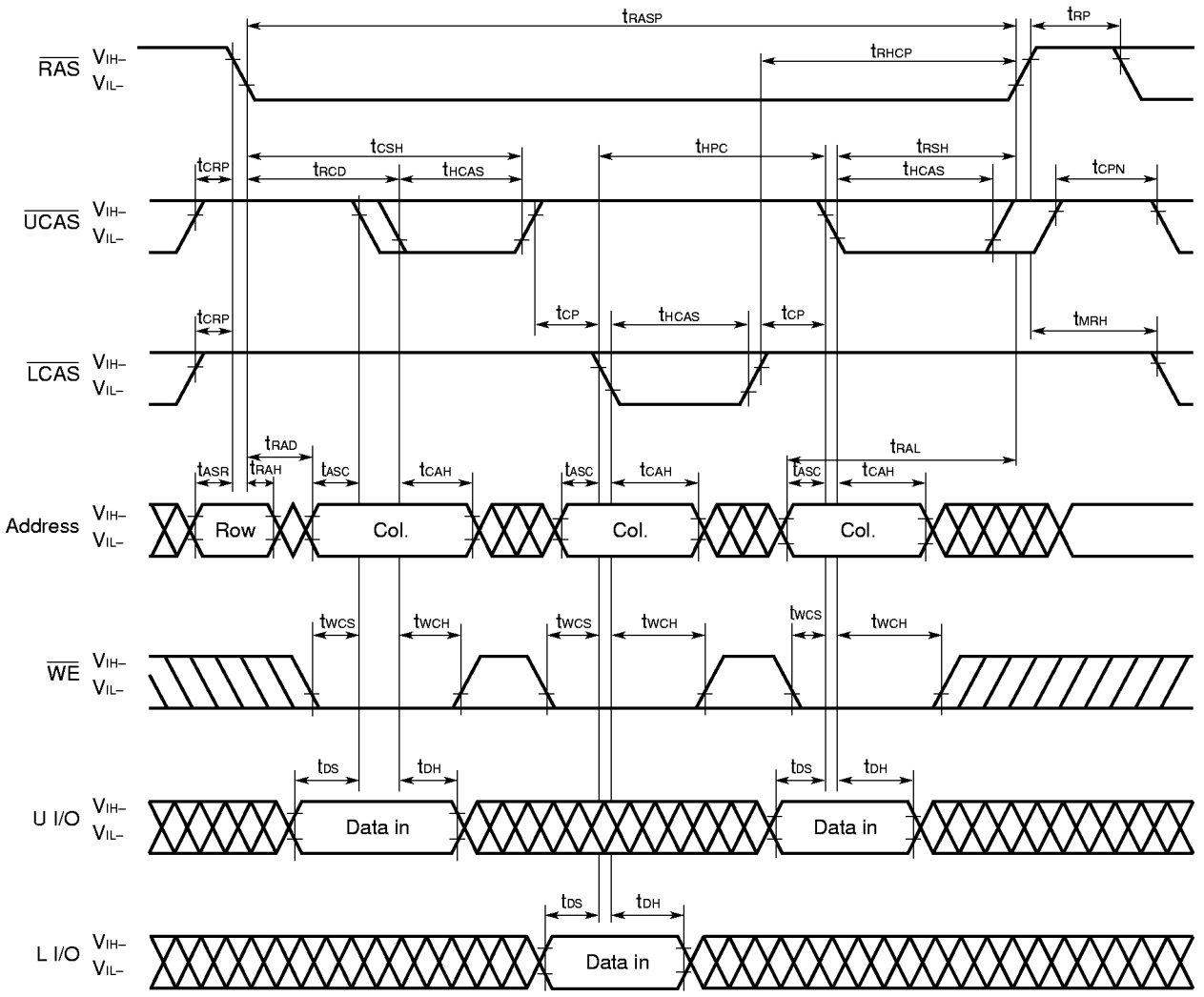
Hyper Page Mode (EDO) Early Write Cycle



Remarks 1. $\overline{OE}$: Don't care

2. In the hyper page mode (EDO), read, write and read modify write cycles are available for each of the consecutive $\overline{CAS}$ cycles within the same $\overline{RAS}$ cycle.

Hyper Page Mode (EDO) Byte Early Write Cycle

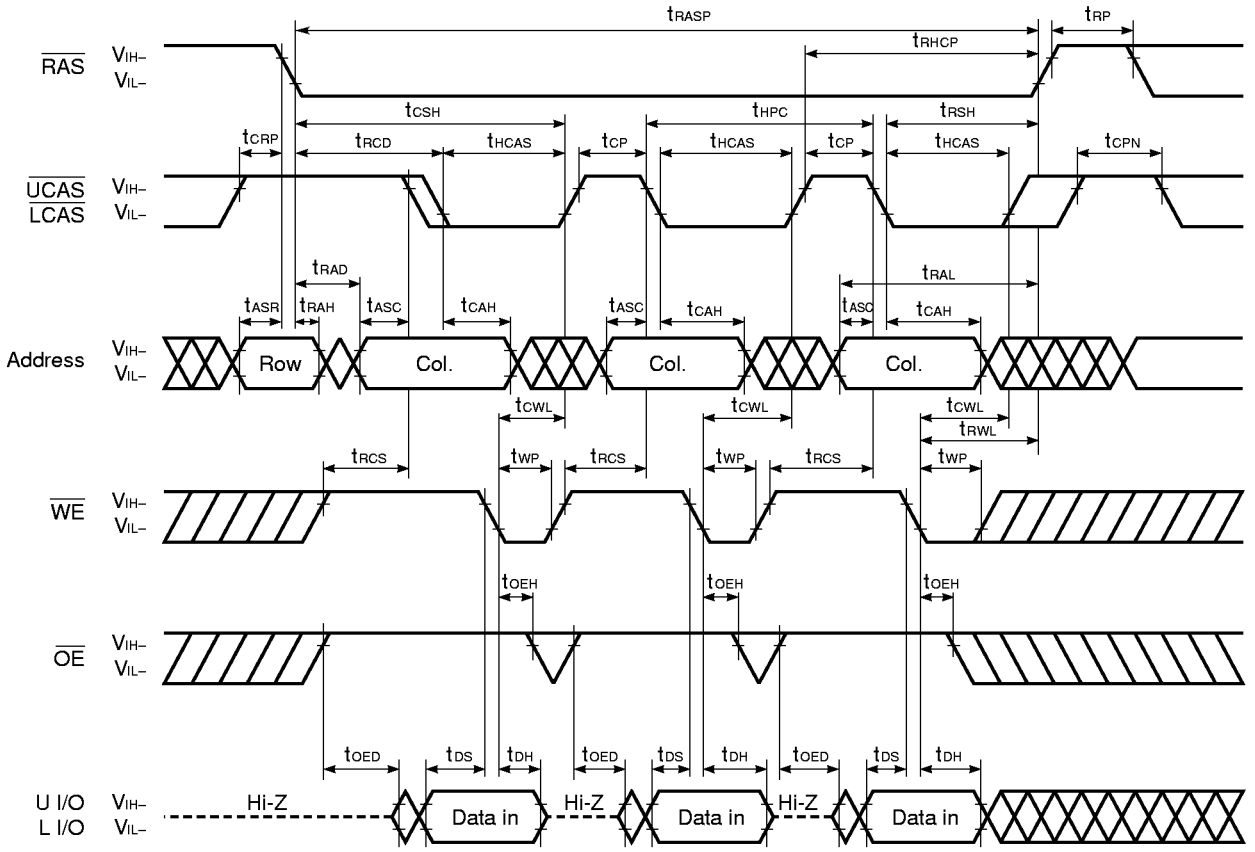


Remarks 1. $\overline{OE}$: Don't care

2. In the hyper page mode (EDO), read, write and read modify write cycles are available for each of the consecutive $\overline{CAS}$ cycles within the same $\overline{RAS}$ cycle.

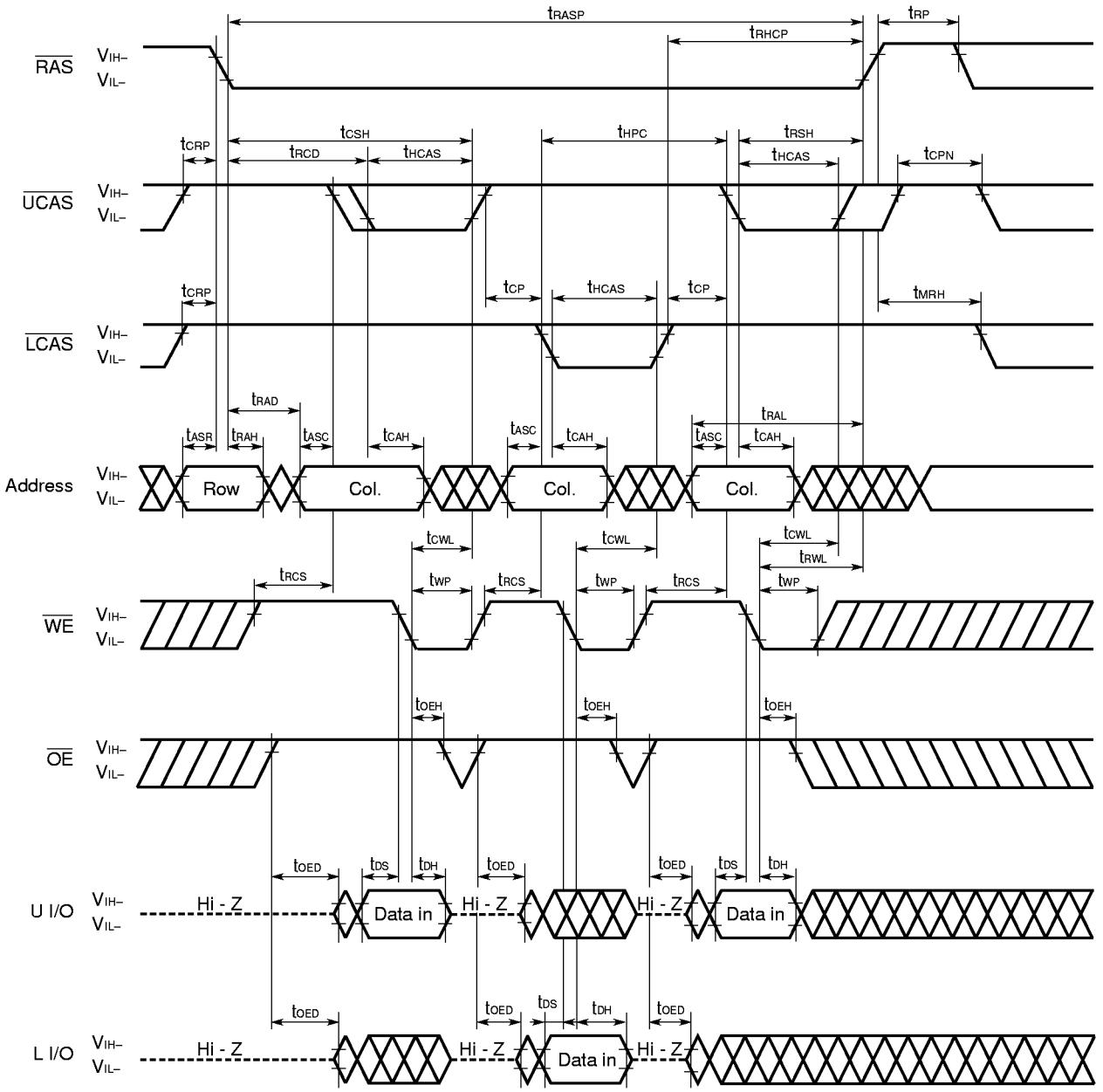
3. This cycle can be used to control either $\overline{UCAS}$ or $\overline{LCAS}$ only. Or, it can be used to control $\overline{UCAS}$ or $\overline{LCAS}$ simultaneously, or at random.

Hyper Page Mode (EDO) Late Write Cycle



Remark In the hyper page mode (EDO), read, write and read modify write cycles are available for each of the consecutive $\overline{CAS}$ cycles within the same $\overline{RAS}$ cycle.

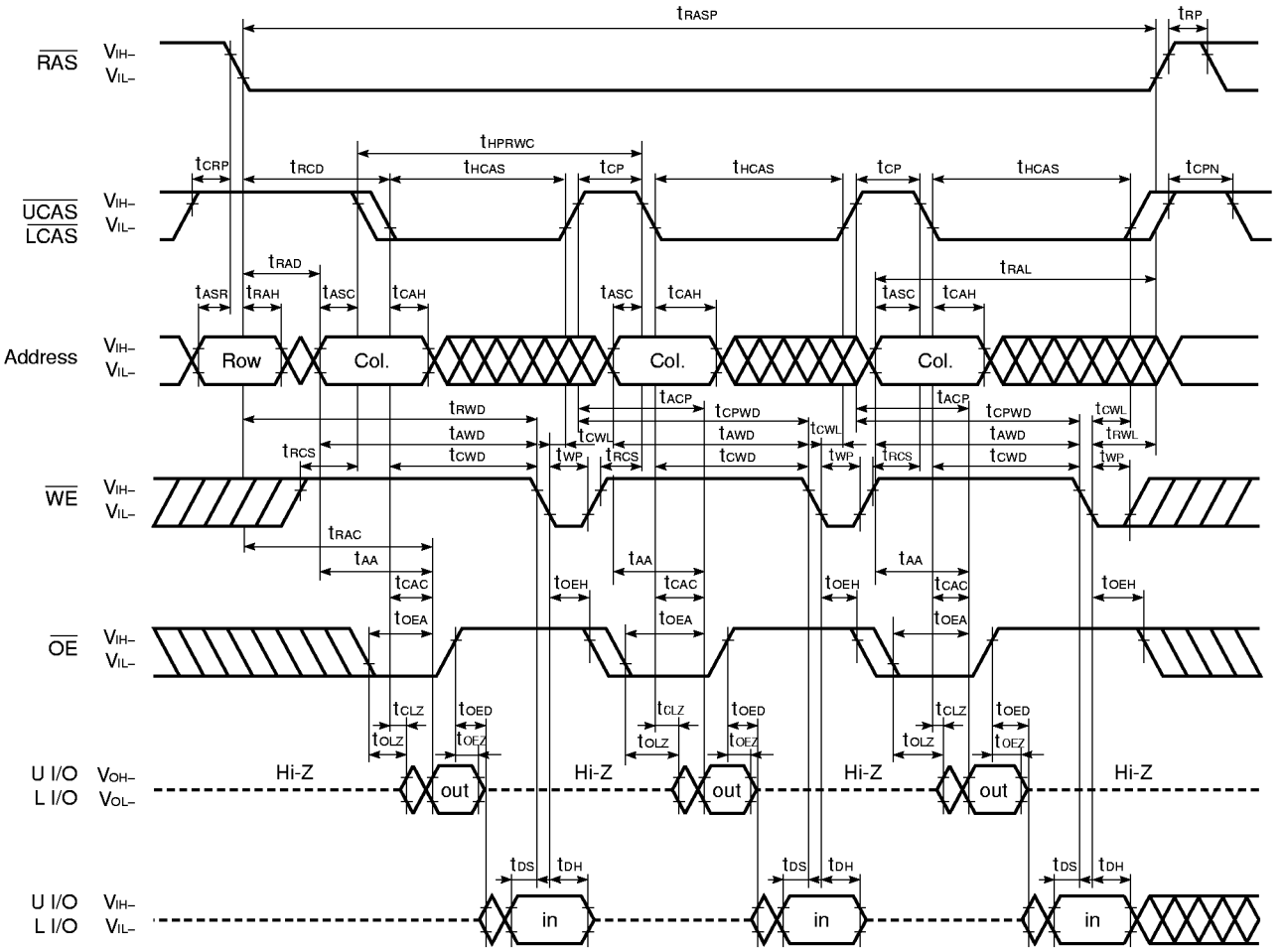
Hyper Page Mode (EDO) Byte Late Write Cycle



Remarks 1. In the hyper page mode (EDO), read, write and read modify write cycles are available for each of the consecutive $\overline{CAS}$ cycles within the same $\overline{RAS}$ cycle.

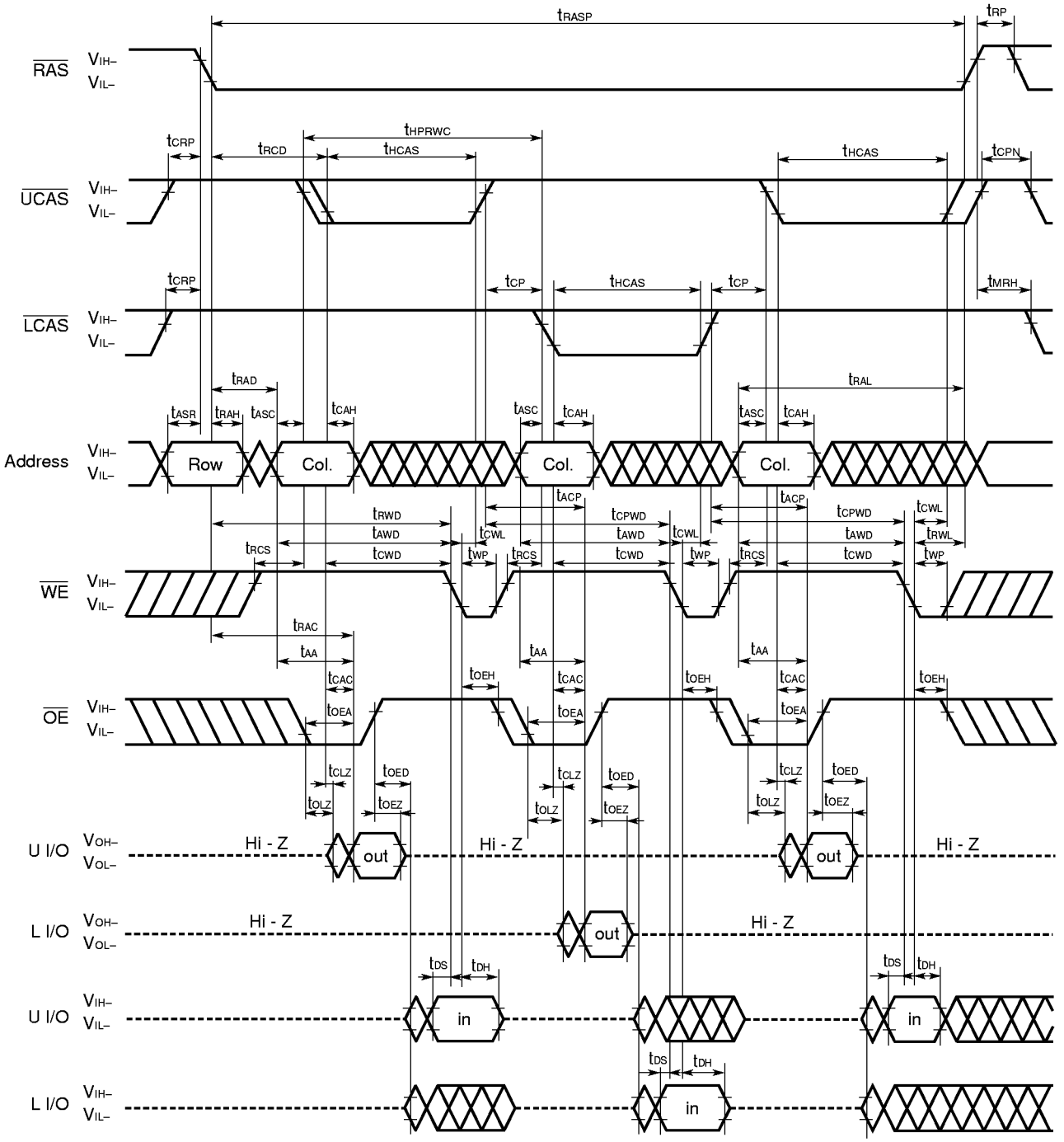
2. This cycle can be used to control either $\overline{UCAS}$ or $\overline{LCAS}$ only. Or, it can be used to control $\overline{UCAS}$ or $\overline{LCAS}$ simultaneously, or at random.

Hyper Page Mode (EDO) Read Modify Write Cycle



Remark In the hyper page mode (EDO), read, write and read modify write cycles are available for each of the consecutive $\overline{CAS}$ cycles within the same $\overline{RAS}$ cycle.

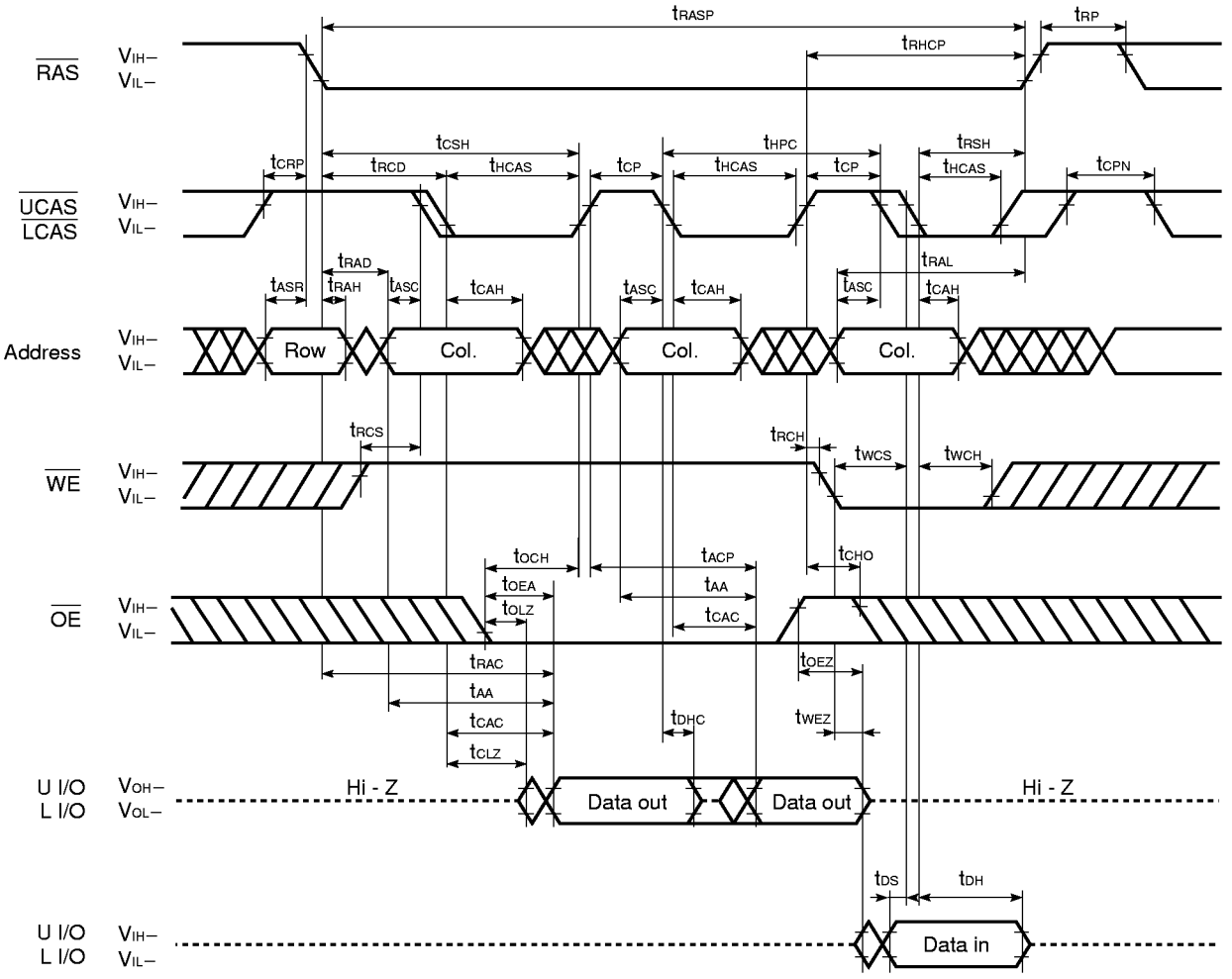
Hyper Page Mode (EDO) Byte Read Modify Write Cycle



Remarks 1. In the hyper page mode (EDO), read, write and read modify write cycles are available for each of the consecutive $\overline{CAS}$ cycles within the same $\overline{RAS}$ cycle.

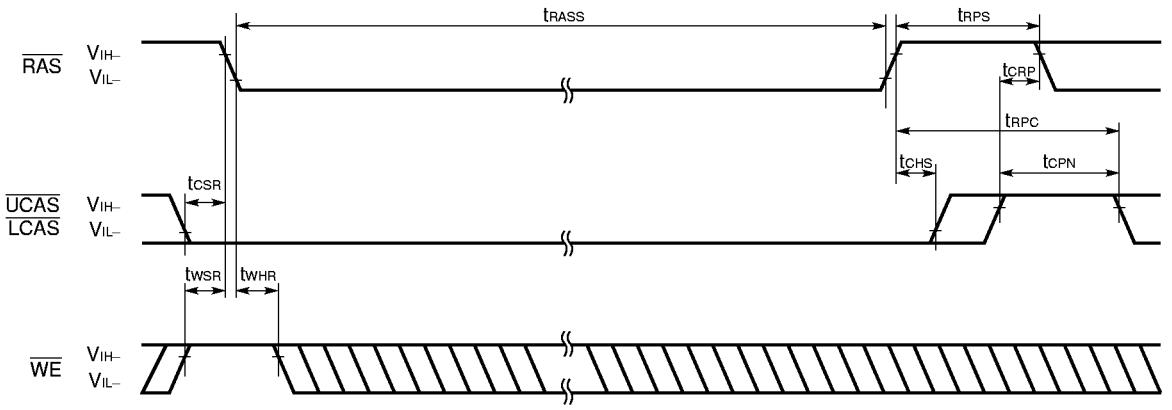
2. This cycle can be used to control either $\overline{UCAS}$ or $\overline{LCAS}$ only. Or, it can be used to control $\overline{UCAS}$ or $\overline{LCAS}$ simultaneously, or at random.

Hyper Page Mode (EDO) Read and Write Cycle



Remark In the hyper page mode (EDO), read, write and read modify write cycles are available for each of the consecutive $\overline{CAS}$ cycles within the same $\overline{RAS}$ cycle.

$\overline{CAS}$ Before $\overline{RAS}$ Self Refresh Cycle (Only for the μPD42S65165)



Remark Address, $\overline{OE}$: Don't care L I/O, U I/O: Hi-Z

Cautions on Use of $\overline{CAS}$ Before $\overline{RAS}$ Self Refresh

$\overline{CAS}$ before $\overline{RAS}$ self refresh can be used independently when used in combination with distributed $\overline{CAS}$ before $\overline{RAS}$ long refresh; However, when used in combination with burst $\overline{CAS}$ before $\overline{RAS}$ long refresh or with long $\overline{RAS}$ only refresh (both distributed and burst), the following cautions must be observed.

(1) Normal Combined Use of $\overline{CAS}$ Before $\overline{RAS}$ Self Refresh and Burst $\overline{CAS}$ Before $\overline{RAS}$ Long Refresh

When $\overline{CAS}$ before $\overline{RAS}$ self refresh and burst $\overline{CAS}$ before $\overline{RAS}$ long refresh are used in combination, please perform $\overline{CAS}$ before $\overline{RAS}$ refresh 4,096 times within a 64 ms interval just before and after setting $\overline{CAS}$ before $\overline{RAS}$ self refresh.

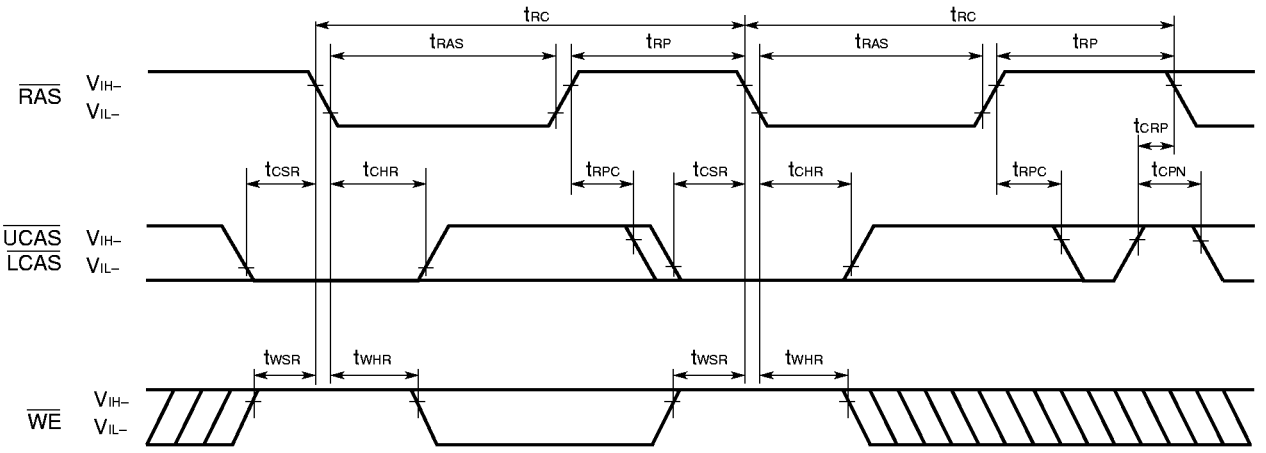
(2) Normal Combined Use of $\overline{CAS}$ Before $\overline{RAS}$ Self Refresh and Long $\overline{RAS}$ Only Refresh

When $\overline{CAS}$ before $\overline{RAS}$ self refresh and $\overline{RAS}$ only refresh are used in combination, please perform $\overline{RAS}$ only refresh 4,096 times within a 64 ms interval just before and after setting $\overline{CAS}$ before $\overline{RAS}$ self refresh.

(3) If $t_{RASS\ (MIN.)}$ is not satisfied at the beginning of $\overline{CAS}$ before $\overline{RAS}$ self refresh cycles (t_{RAS} < 100 μs), $\overline{CAS}$ before $\overline{RAS}$ refresh cycles will be executed one time.
If 10 μs < t_{RAS} < 100 μs, $\overline{RAS}$ precharge time for $\overline{CAS}$ before $\overline{RAS}$ self refresh (t_{RPS}) is applied.
And refresh cycles (4,096/128 ms) should be met.

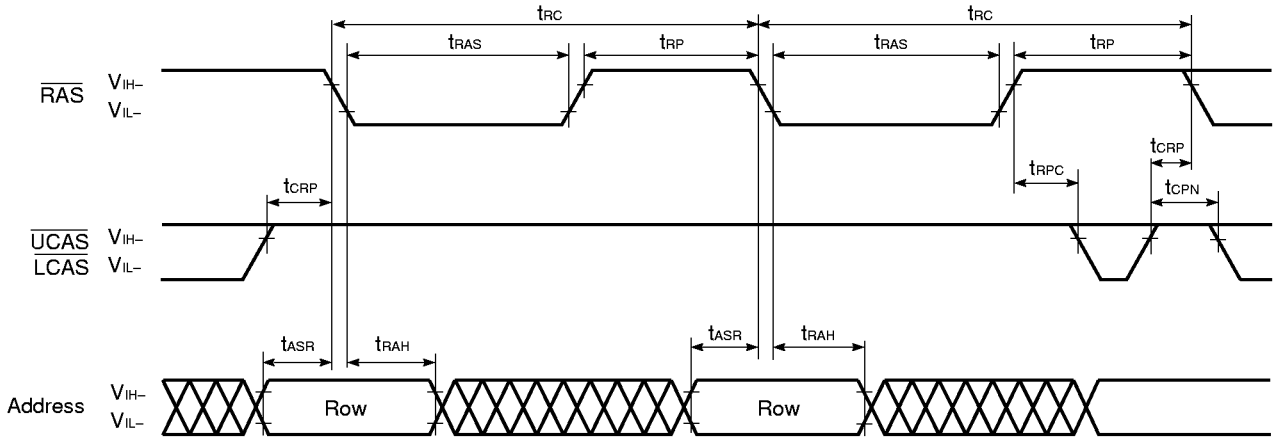
For details, please refer to **How to use DRAM** User's Manual.

$\overline{CAS}$ Before $\overline{RAS}$ Refresh Cycle



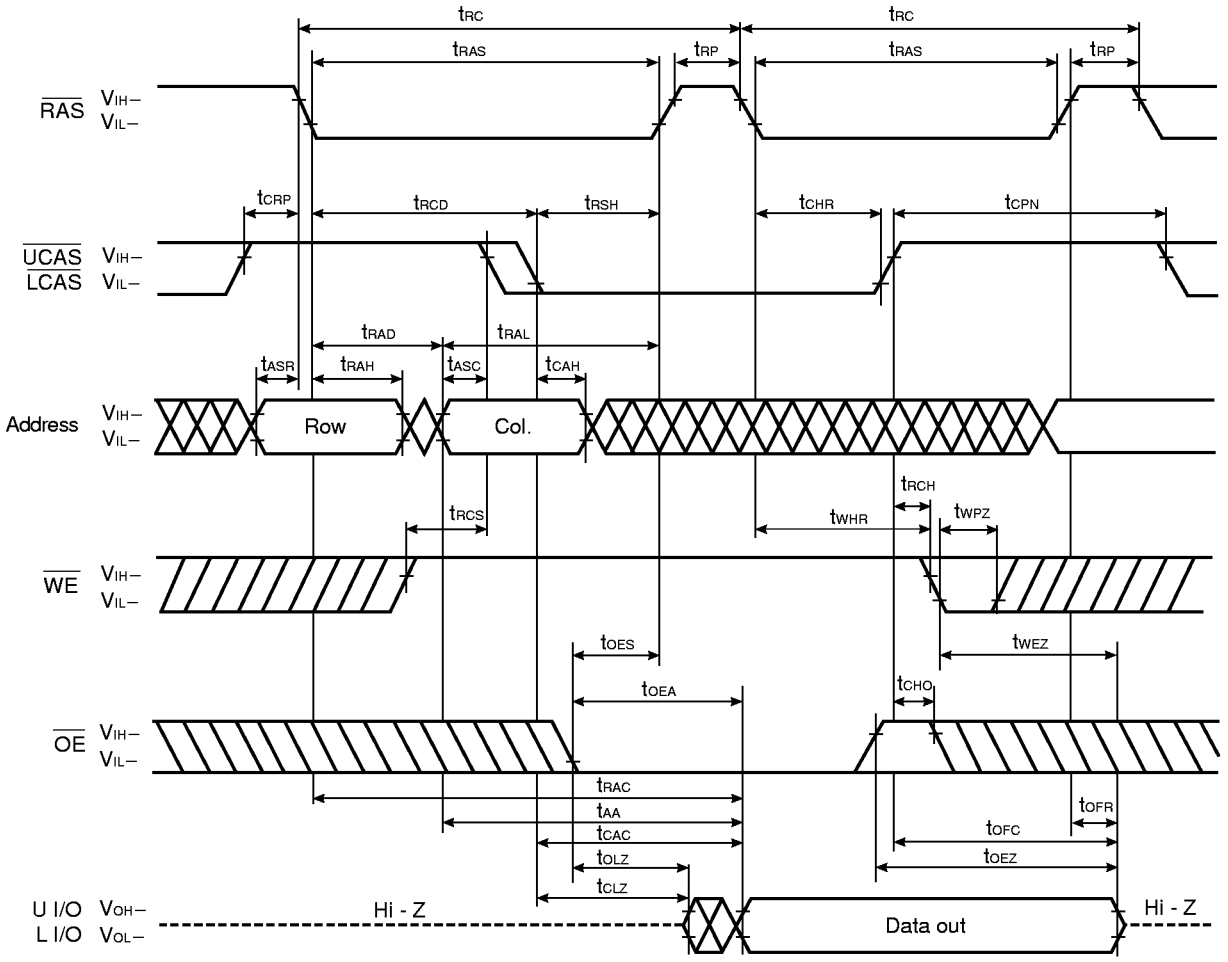
Remark Address, $\overline{OE}$: Don't care L I/O, U I/O: Hi-Z

$\overline{RAS}$ Only Refresh Cycle

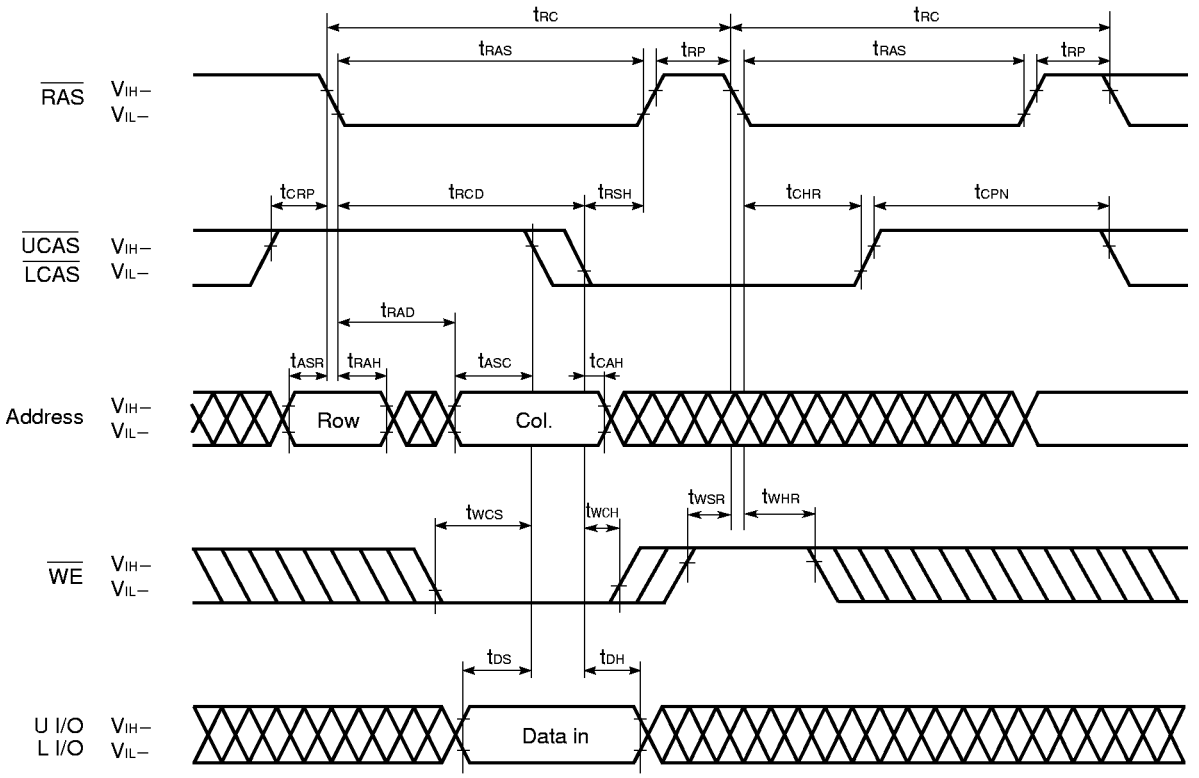


Remark $\overline{WE}$, $\overline{OE}$: Don't care L I/O, U I/O: Hi-Z

Hidden Refresh Cycle (Read)



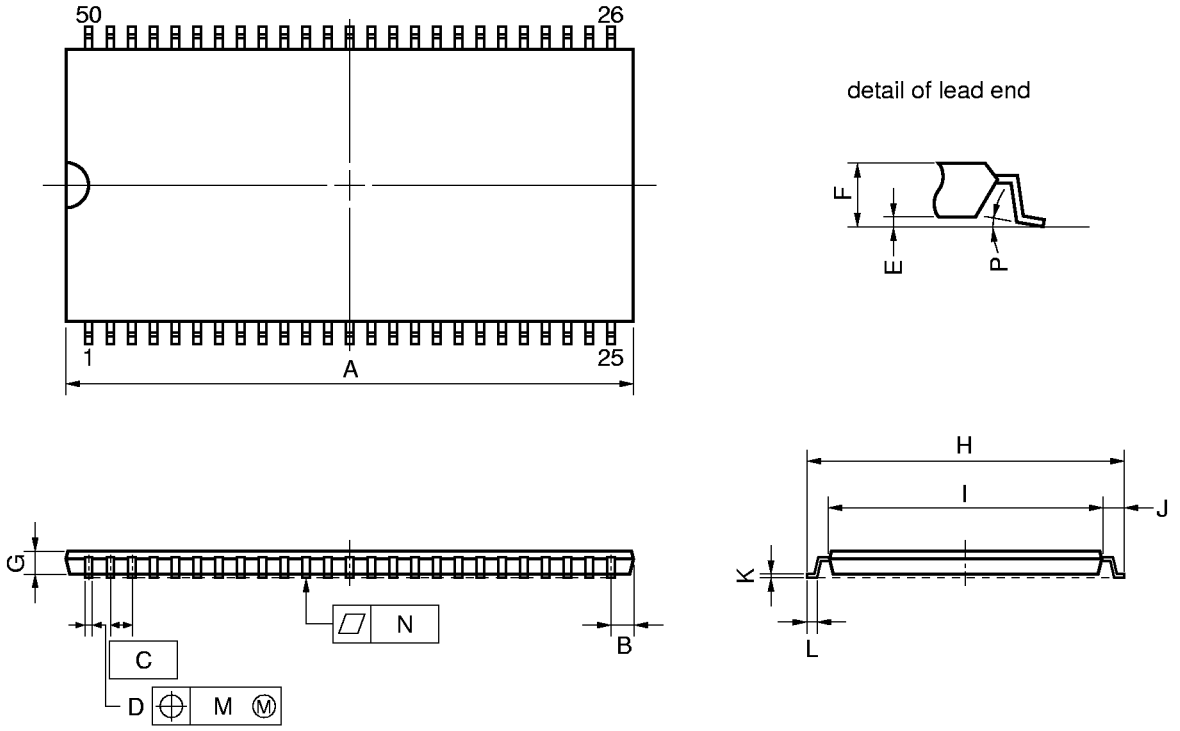
Hidden Refresh Cycle (Write)



Remark $\overline{OE}$: Don't care

Package Drawing

50PIN PLASTIC TSOP(II) (400 mil)



NOTE

Each lead centerline is located within 0.13 mm (0.005 inch) of its true position (T.P.) at maximum material condition.

ITEM	MILLIMETERS	INCHES
A	21.17 MAX.	0.834 MAX.
B	1.0 MAX.	0.040 MAX.
C	0.8 (T.P.)	0.031 (T.P.)
D	$0.32^{+0.08}_{-0.07}$	0.013±0.003
E	0.1±0.05	0.004±0.002
F	1.2 MAX.	0.048 MAX.
G	0.97	0.038
H	11.76±0.2	0.463±0.008
I	10.16±0.1	0.400±0.004
J	0.8±0.2	$0.031^{+0.009}_{-0.008}$
K	$0.145^{+0.025}_{-0.015}$	0.006±0.001
L	0.5±0.1	$0.020^{+0.004}_{-0.005}$
M	0.13	0.005
N	0.10	0.004
P	$3°^{+7°}_{-3°}$	$3°^{+7°}_{-3°}$

S50G5-80-7JF3

Recommended Soldering Conditions

Please consult with our sales offices for soldering conditions of the μPD42S65165, 4265165.

Type of Surface Mount Device

μPD42S65165G5-7JF, 4265165G5-7JF: 50-pin plastic TSOP (II) (400 mil)