NEC

MOS INTEGRATED CIRCUIT

μPD78P058F

8-BIT SINGLE-CHIP MICROCONTROLLER

DESCRIPTION

The μPD78P058F is an Electro Magnetic Interface (EMI) noise reduction version in comparison with the usual μPD78P058.

The μPD78P058F is a member of the μPD78058F subseries of 78K/0 series products, in which the on-chip mask ROM is replaced with one-time programmable (OTP) ROM.

Because this device can be programmed by users, it is ideally suited for applications involving the small-scale production of many different products, and rapid development and time-to-market of a new product.

Details are given in the following User's Manuals. Be sure to read them before starting design.

μPD78058F, 78058FY Subseries User's Manual (to be prepared)

78K Series User's Manual—Instruction (IEU-1372)

FEATURES

- EMI noise reduction version (The overall peak level is reduced by 5 to 10 dB)
- Pin compatible with mask ROM versions (except the V_{PP} pin)
- Internal PROM : 60 Kbytes[Note1]
  Programmable once only (ideal for small-scale production)
- Internal high-speed RAM : 1024 bytes
- Internal expansion RAM : 1024 bytes[Note2]
- Buffer RAM : 32 bytes
- Operable in the same supply voltage range as mask ROM versions (V_{DD} = 2.7 to 6.0 V)
- One of the QTOP™ microcontrollers

Notes 1. Internal PROM capacity can be changed by memory size switching register (IMS).

2. Internal expansion RAM capacity can be changed by internal expansion RAM size switching register (IXS).

Remarks 1. For the difference between PROM and Mask ROM versions, see the chapter **1. DIFFERNCES BETWEEN μPD78P058F AND MASK ROM VERSIONS.**

2. QTOP Microcontroller is the general name of the microcontrollers with on-chip one-time PROM that are totally supported by NEC write service (from write to marking, screening and testing.)

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The mark * shows major revised points.

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ORDERING INFORMATION

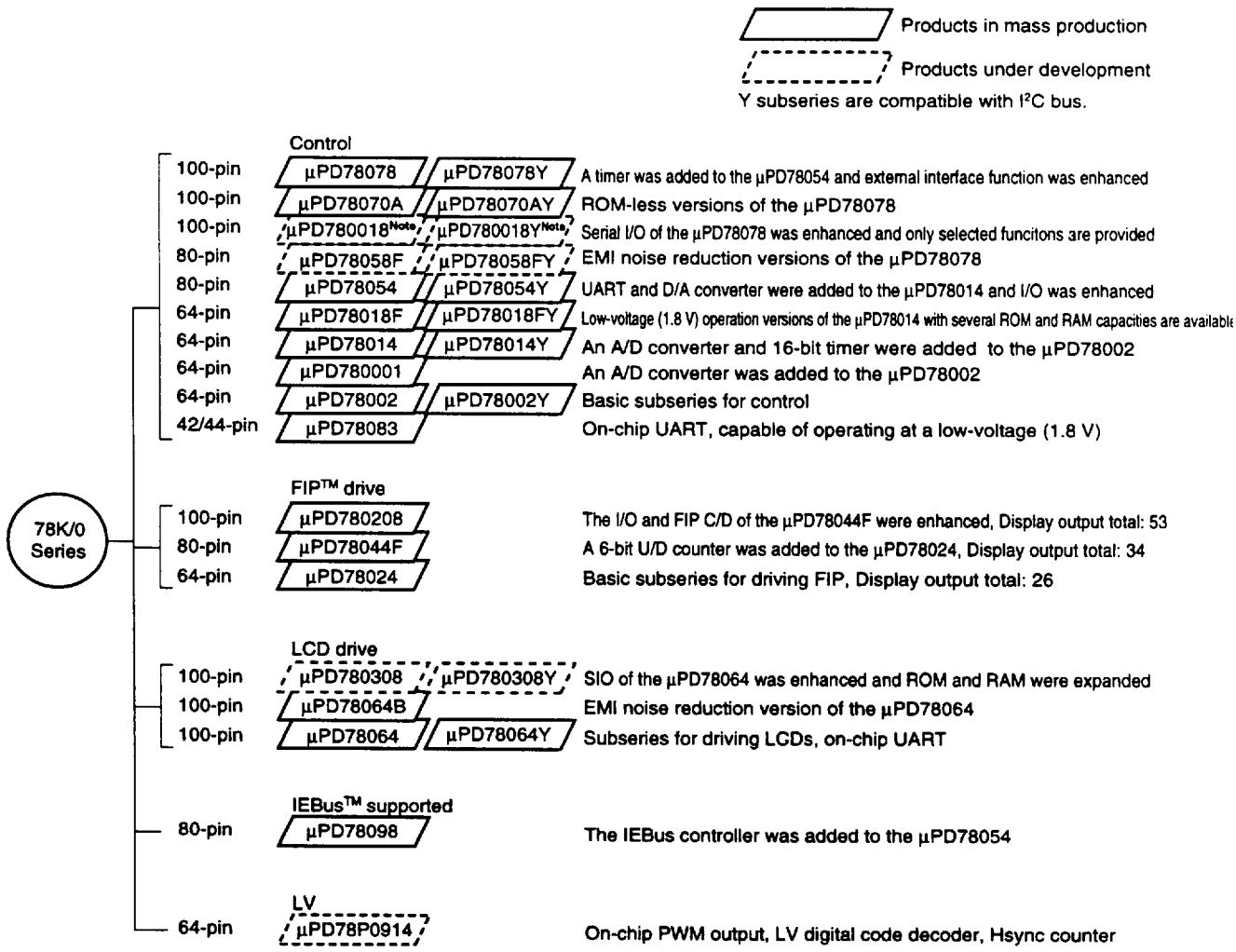
Part Number	Package	On-Chip ROM
μPD78P058FGC-3B9	80-pin plastic QFP (14 × 14 mm, Resin thickness: 2.7mm)	One-time PROM
μPD78P058FGC-8BT[Note]	80-pin plastic QFP (14 × 14 mm, Resin thickness: 1.4mm)	One-time PROM

Note Under development

Remark The μPD78P058FGC contains two types of packages (see the chapter **8. PACKAGE DRAWINGS**). For packages which can be supplied, consult your local NEC personnel.

78K/0 SERIES LINE-UP

These products are a further development in the 78K/0 series. The designations appearing inside the boxes are subseries names.



Note Under planning

The major functional differences among the subseries are shown below.

Subseries name \ Function		ROM Capacity	Timer 8-bit	Timer 16-bit	Timer Watch	Timer WDT	8-bit A/D	8-bit D/A	Serial Interface	I/O	VDD MIN. Value	External Expansion
Control	μPD78078	32 K-60 K	4ch	1ch	1ch	1ch	8ch	2ch	3ch (UART: 1ch)	88	1.8 V	√
	μPD78070A	–								61	2.7 V	
	μPD780018	48 K-60 K						–	2ch	88		
	μPD78058F		2ch					2ch	3ch (UART: 1ch)	69		
	μPD78054	16 K-60 K									2.0 V	
	μPD78018F	8 K-60 K						–	2ch	53	1.8 V	
	μPD78014	8 K-32 K									2.7 V	
	μPD780001	8 K		–	–				1ch	39		–
	μPD78002	8 K-16 K			1ch		–			53		√
	μPD78083				–		8ch		1ch (UART: 1ch)	33	1.8 V	–
FIP driving	μPD780208	32 K-60 K	2ch	1ch	1ch	1ch	8ch	–	2ch	74	2.7 V	–
	μPD78044F	16 K-40 K								68		
	μPD78024	24 K-32 K								54		
LCD driving	μPD780308	48 K-60 K	2ch	1ch	1ch	1ch	8ch	–	3ch (UART: 1ch)	57	1.8 V	–
	μPD78064B	32 K							2ch (UART: 1ch)		2.0 V	
	μPD78064	16 K-32 K										
IEBus supported	μPD78098	32 K-60 K	2ch	1ch	1ch	1ch	8ch	2ch	3ch (UART: 1ch)	69	2.7 V	√
LV	μPD78P0914	32 K	6ch	–	–	1ch	8ch	–	2ch	54	4.5 V	√

FUNCTION DESCRIPTION

Item		Function
Internal memory		• PROM : 60 Kbytes[Note1] • RAM Internal high-speed RAM : 1024 bytes Internal expansion RAM : 1024 bytes[Note2] Buffer RAM : 32 bytes
Memory space		64 Kbytes
General register		8 bits × 32 registers (8 bits × 8 registers × 4 banks)
Instruction cycles		Instruction execution time is variable.
	When main system clock is selected	0.4μs/0.8 μs/1.6 μs/3.2 μs/6.4 μs/12.8 μs (@ 5.0 MHz)
	When subsystem clock is selected	122 μs (@ 32.768 kHz)
Instruction set		• 16-bit operation • Multiply/divide (8-bit × 8-bit, 16-bit / 8-bit) • Bit manipulation (set, reset, test, Boolean operation) • BCD adjust, etc.
I/O ports		Total : 69 • CMOS input : 2 • CMOS input/output : 63 • N-ch open-drain input/output : 4
A/D converter		• 8-bit resolution × 8 ch
D/A converter		• 8-bit resolution × 2 ch
Serial interface		• 3-wire serial I/O, SBI, or 2-wire serial I/O mode selectable : 1 ch • 3-wire serial I/O mode (with on-chip max. 32-byte automatic transmit/receive function) : 1 ch • 3-wire serial I/O or UART mode selectable : 1 ch
Timer		• 16-bit timer/event counter : 1 ch • 8-bit timer/event counter : 2 ch • Watch timer : 1 ch • Watchdog timer : 1 ch
Timer output		3 pins (14-bit PWM output: 1 pin)
Clock output		19.5 kHz, 39.1 kHz, 78.1 kHz, 156 kHz, 313 kHz, 625 kHz, 1.25 MHz, 2.5 MHz, and 5.0 MHz (@ 5.0 MHz with main system clock) 32.768 kHz (@ 32.768 kHz with subsystem clock)
Buzzer output		1.2 kHz, 2.4 kHz, 4.9 kHz and 9.8 kHz (@ 5.0 MHz with main system clock)
Vectored interrupts	Maskable interrupts	Internal: 13, external: 7
	Non-maskable interrupts	Internal: 1
	Software interrupts	1
Test inputs		Internal: 1, external: 1
Supply voltage		V_{DD} = 2.7 to 6.0 V
Operating ambient temperature		T_A = −40 to +85 °C
Packages		• 80-pin plastic QFP (14 × 14 mm, Resin thickness: 2.7 mm) • 80-pin plastic QFP (14 × 14 mm, Resin thickness: 1.4 mm)

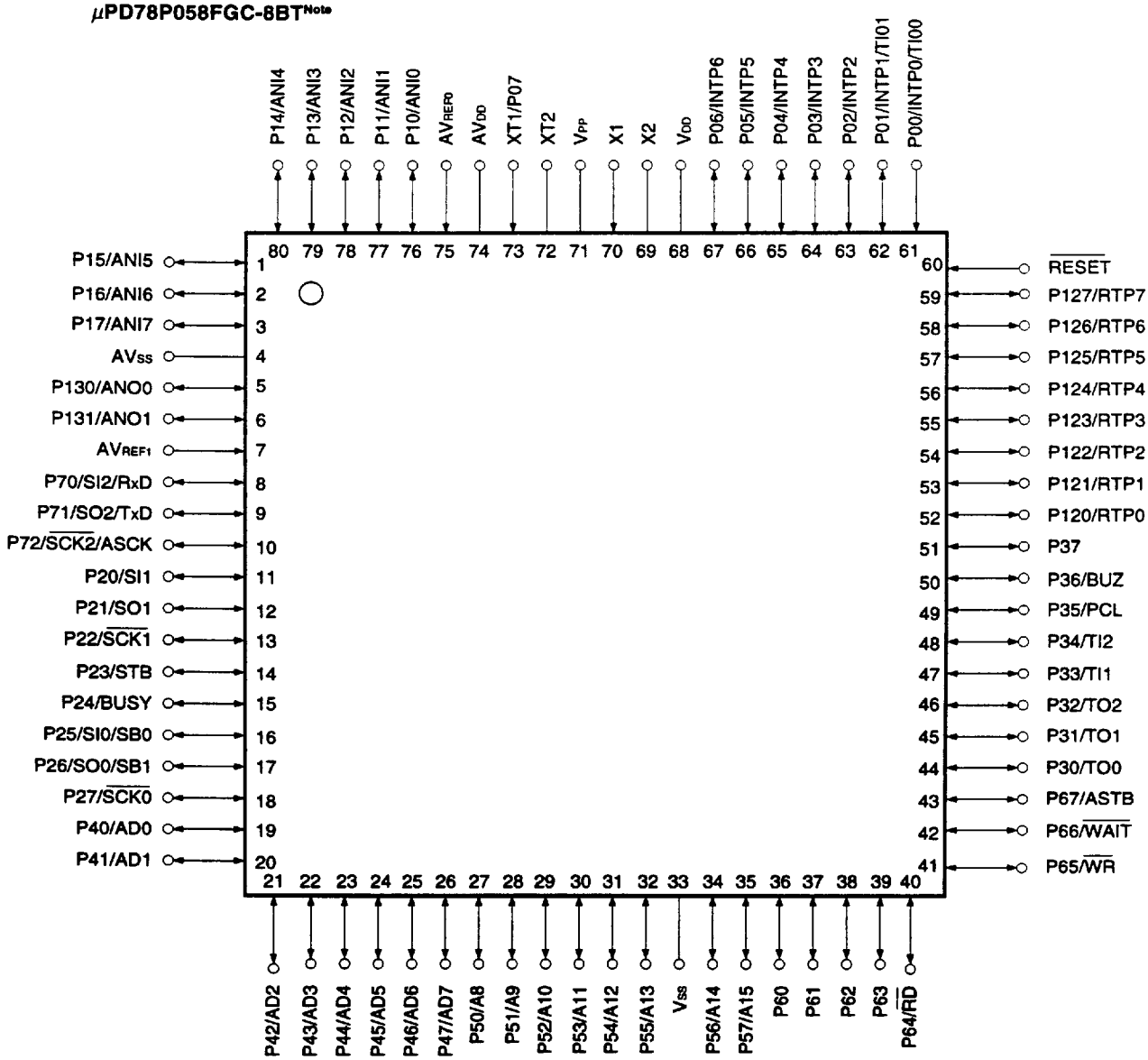
Notes 1. Internal PROM capacity can be changed by memory size switching register (IMS).

2. Internal expansion RAM capacity can be changed by internal expansion RAM size switching register (IXS).

PIN CONFIGURATIONS (TOP VIEW)

(1) Normal Operating Mode

- 80-pin plastic QFP (14 × 14 mm, Resin thickness: 2.7 mm)
  μPD78P058FGC-3B9
- 80-pin plastic QFP (14 × 14 mm, Resin thickness: 1.4 mm)
  μPD78P058FGC-8BT[Note]



Note Under development

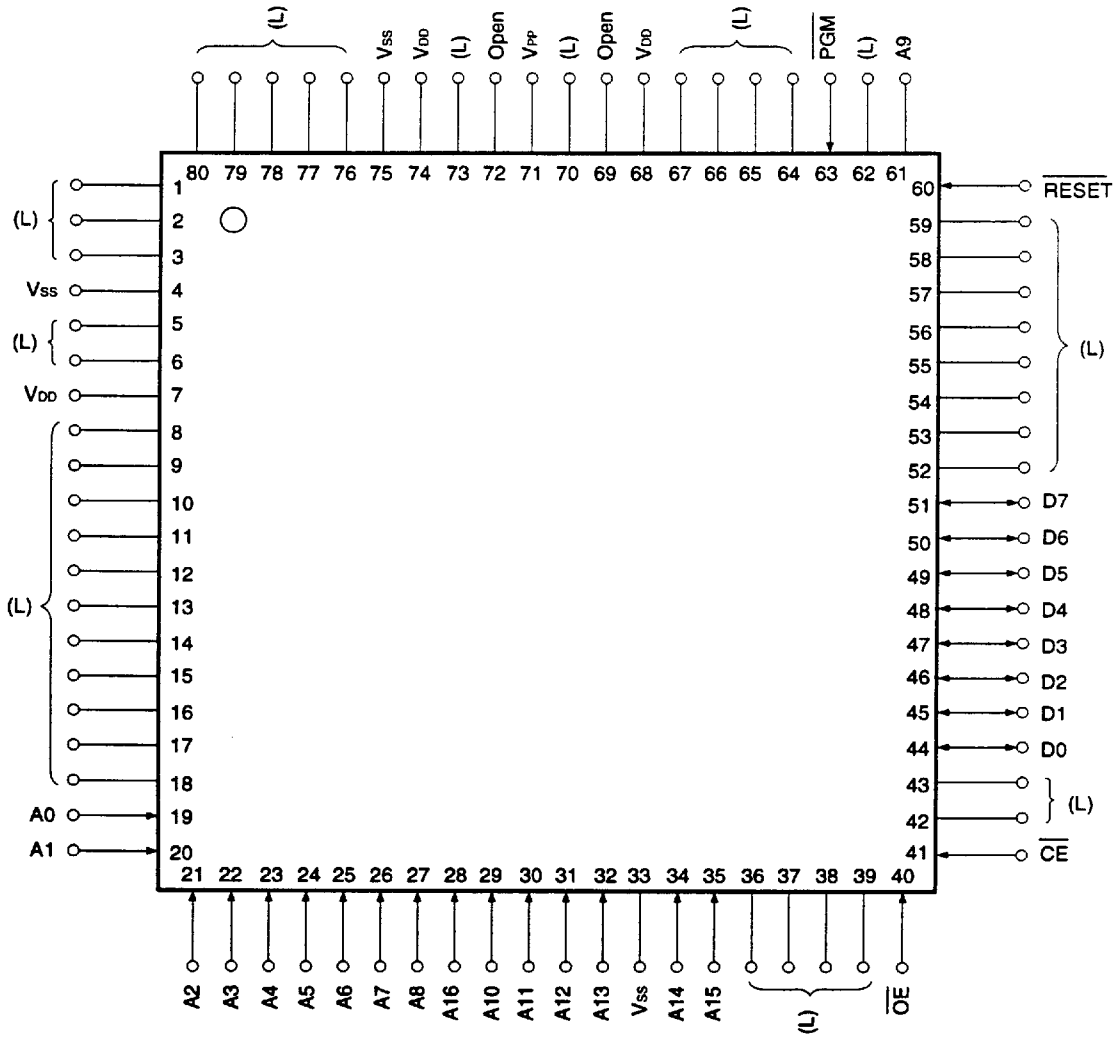
Cautions

1. **Connect the V_{PP} pin to V_{SS}.**
2. **The AV_{DD} pin functions as both an A/D converter power supply and a port power supply. When the μPD78P058F is used in applications where the noise generated inside the microcontroller needs to be reduced, connect the AV_{DD} pin to another power supply which has the same potencial as V_{DD}.**
3. **The AV_{SS} pin functions as both grounds of an A/D converter and D/A converter and of a port. When the μPD78P058F is used in applications where the noise generated inside the microcontroller needs to be reduced, connect the AV_{SS} pin to another ground line than V_{SS}.**

A8 to A15	:	Address Bus
AD0 to AD7	:	Address/ Data Bus
ANI0 to ANI7	:	Analog Input
ANO0 to ANO1	:	Analog Output
ASCK	:	Asynchronous Serial Clock
ASTB	:	Address Strobe
AV_{DD}	:	Analog Power Supply
AV_{REF0}, AV_{REF1}	:	Analog Reference Voltage
AV_{SS}	:	Analog Ground
BUSY	:	Busy
BUZ	:	Buzzer Clock
INTP0 to INTP6	:	Interrupt from Peripherals
P00 to P07	:	Port 0
P10 to P17	:	Port 1
P20 to P27	:	Port 2
P30 to P37	:	Port 3
P40 to P47	:	Port 4
P50 to P57	:	Port 5
P60 to P67	:	Port 6
P70 to P72	:	Port 7
P120 to P127	:	Port 12
P130, P131	:	Port 13
PCL	:	Programmable Clock
$\overline{RD}$	:	Read Strobe
$\overline{RESET}$	:	Reset
RTP0 to RTP7	:	Real-Time Output Port
RxD	:	Receive Data
SB0, SB1	:	Serial Bus
$\overline{SCK0}$ to $\overline{SCK2}$	:	Serial Clock
SI0 to SI2	:	Serial Input
SO0 to SO2	:	Serial Output
STB	:	Strobe
TI00, TI01	:	Timer Input
TI1,TI2	:	Timer Input
TO0 to TO2	:	Timer Output
TxD	:	Transmit Data
V_{DD}	:	Power Supply
V_{PP}	:	Programming Power Supply
V_{SS}	:	Ground
$\overline{WAIT}$	:	Wait
$\overline{WR}$	:	Write Strobe
X1, X2	:	Crystal (Main System Clock)
XT1, XT2	:	Crystal (Subsystem Clock)

(2) PROM Programming Mode

- 80-pin plastic QFP (14 × 14 mm, Resin thickness: 2.7 mm)
  μPD78P058FGC-3B9
- 80-pin plastic QFP (14 × 14 mm, Resin thickness: 1.4 mm)
  μPD78P058FGC-8BT[Note]

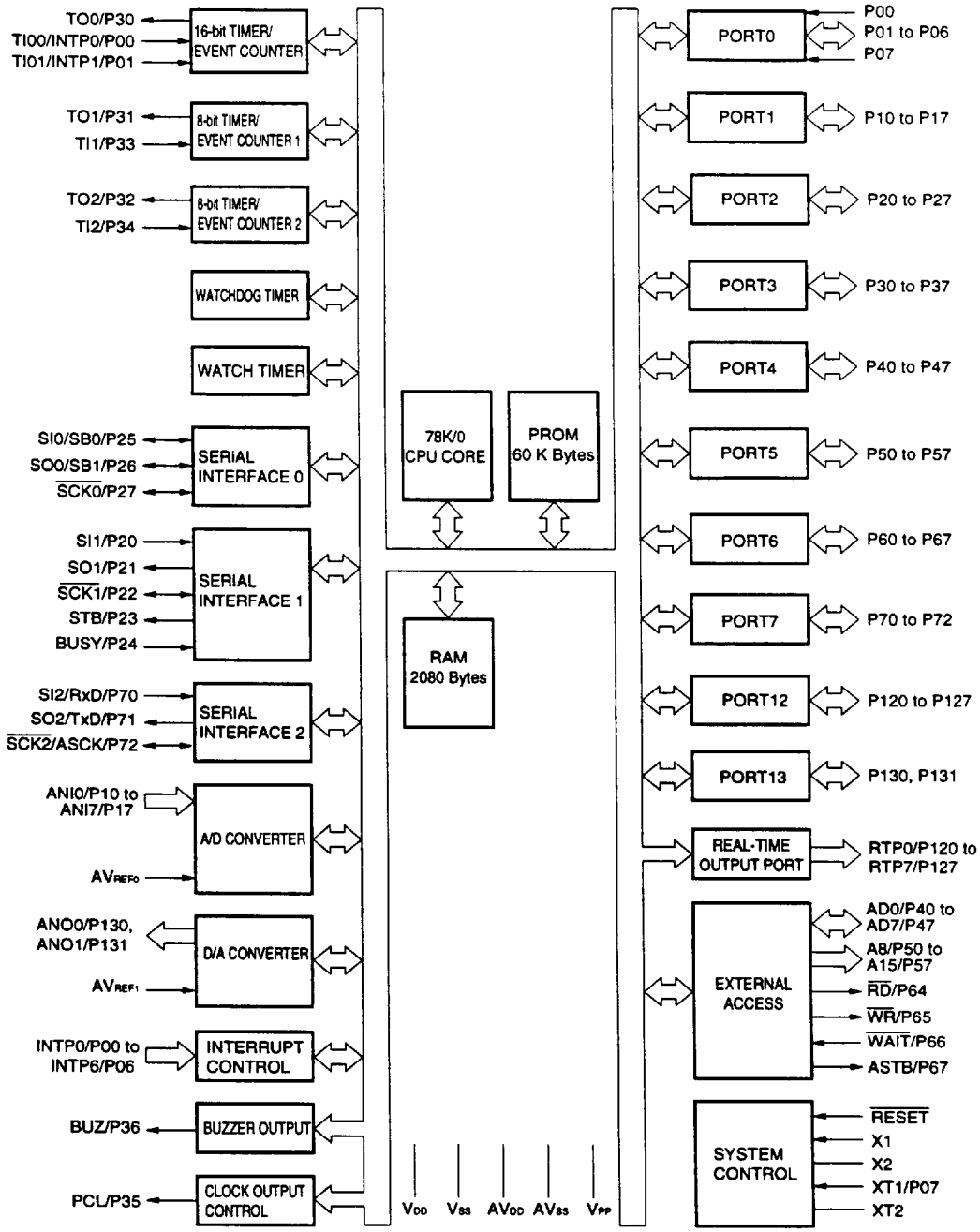


Note Under development

Cautions 1. (L) : **Individually connect to Vss via a pull-down resistor.**
2. Vss : **Connect to GND.**
3. $\overline{\text{RESET}}$: **Set to low level.**
4. Open : **No connection**

A0 to A16	: Address Bus	$\overline{\text{RESET}}$	: Reset
D0 to D7	: Data Bus	V_{DD}	: Power Supply
$\overline{\text{CE}}$	: Chip Enable	V_{PP}	: Programming Power Supply
$\overline{\text{OE}}$	: Output Enable	Vss	: Ground
$\overline{\text{PGM}}$	: Program		

BLOCK DIAGRAM



CONTENTS

1. DIFFERENCES BETWEEN μPD78P058F AND MASK ROM VERSIONS

The μPD78P058F is a single-chip microcontroller with an on-chip one-time writable PROM.

Setting the memory size switching register (IMS) and internal expansion RAM size switching register (IXS) enables the identical functions to mask ROM versions (μPD78P056F, 58F) except the functions of PROM specifications and of mask options for P60 to P63.

Differences between the μPD78P058F and mask ROM versions are shown in Table 1-1.

Table 1-1. Differences between μPD78P058F and Mask ROM Versions

Item	μPD78P058F	Mask ROM versions
ROM structure	One-time PROM	Mask ROM
ROM capacity	60 Kbytes	μPD78056F : 48 Kbytes μPD78058F : 60 Kbytes
Internal expansion RAM capacity	1024 bytes	μPD78056F : None μPD78058F : 1024 bytes
Change of internal ROM capacity by memory size switching register	Can be changed[Note]	Cannot be changed
Change of internal expansion RAM capacity by internal expansion RAM size switching register	Can be changed[Note]	Cannot be changed
IC pin	None	Provided
V_{PP} pin	Provided	None
Electrical chatacteristics	See each Data Sheet	

Note The $\overline{\text{RESET}}$ input sets the internal PROM and internal expansion RAM to 60 Kbytes and 1024 bytes, respectively.

2. PIN FUNCTIONS

2.1 Pins in Normal Operating Mode

(1) Port Pins (1/2)

Pin Name	Input/Output	Function		After Reset	Alternate Function
P00	Input	Port 0 8-bit input/output port	Input only	Input	INTP0/TI00
P01	Input/output		Input/output is specifiable bit-wise. When used as the input port, it is possible to use an on-chip pull-up resistor by software.	Input	INTP1/TI01
P02					INTP2
P03					INTP3
P04					INTP4
P05					INTP5
P06					INTP6
P07[Note1]	Input		Input only	Input	XT1
P10 to P17	Input/output	Port 1 8-bit input/output port Input/output is specifiable bit-wise. When used as the input port, it is possible to use an on-chip pull-up resistor by software.[Note2]		Input	ANI0 to ANI7
P20	Input/output	Port 2 8-bit input/output port Input/output is specifiable bit-wise. When used as the input port, it is possible to use an on-chip pull-up resistor by software.		Input	SI1
P21					SO1
P22					$\overline{SCK1}$
P23					STB
P24					BUSY
P25					SI0/SB0
P26					SO0/SB1
P27					$\overline{SCK0}$
P30	Input/output	Port 3 8-bit input/output port Input/output is specifiable bit-wise. When used as the input port, it is possible to use an on-chip pull-up resistor by software.		Input	TO0
P31					TO1
P32					TO2
P33					TI1
P34					TI2
P35					PCL
P36					BUZ
P37					—

Notes 1. When P07/XT1 pins are used as the input ports, set the processor clock control register (PCC) bit 6 (FRC) to 1, be sure not to use the feedback resistor of the subsystem clock oscillation circuit.

2. When P10/ANI0 to P17/ANI7 pins are used as the analog inputs for A/D converter, their pull-up resistor are automatically disabled.

Caution For pins which also function as port pins, do not perform the following operations during A/D conversion. If these operations are performed, the total error ratings cannot be kept (except for LCD segment output alternate-function pin).

<1> Rewrite the output latch while the pin is used as a port pin.

<2> Change the output level of the pin used as an output pin, even if it is not used as a port pin.

(1) Port Pins (2/2)

Pin Name	Input/Output	Function		After Reset	Alternate Function
P40 to P47	Input/output	Port 4 8-bit input/output port Input/output is specifiable as 8-bit unit. When used as the input port, it is possible to use an on-chip pull-up resistor by software. Set test input flag(KRIF) to 1 by falling edge detection.		Input	AD0 to AD7
P50 to P57	Input/output	Port 5 8-bit input/output port It is possible to directly drive LEDs. Input/output is specifiable bit-wise. When used as the input port, it is possible to use an on-chip pull-up resistor by software.		Input	A8 to A15
P60	Input/output	Port 6 8-bit input/output port Input/output is specifiable bit-wise.	N-ch open-drain input/output port. It is possible to directly drive LEDs.	Input	—
P61					
P62					
P63					
P64			When used as the input port, it is possible to connect an on-chip pull-up resistor by software.	Input	$\overline{RD}$
P65					$\overline{WR}$
P66					$\overline{WAIT}$
P67					ASTB
P70	Input/output	Port 7 3-bit input/output port Input/output is specifiable bit-wise. When used as the input port, it is possible to use an on-chip pull-up resistor by software.		Input	SI2/RxD
P71					SO2/TxD
P72					$\overline{SCK2}$/ASCK
P120 to P127	Input/output	Port 12 8-bit input/output port Input/output is specifiable bit-wise. When used as the input port, it is possible to use an on-chip pull-up resistor by software.		Input	RTP0 to RTP7
P130, P131	Input/output	Port 13 2-bit input/output port Input/output is specifiable bit-wise. When used as the input port, it is possible to use an on-chip pull-up resistor by software.		Input	ANO0, ANO1

Caution For pins which also function as port pins, do not perform the following operations during A/D conversion. If these operations are performed, the total error ratings cannot be kept (except for LCD segment output alternate-function pin).

<1> Rewrite the output latch while the pin is used as a port pin.

<2> Change the output level of the pin used as an output pin, even if it is not used as a port pin.

(2) Non-Port Pins (1/2)

Pin Name	Input/Output	Function	After Reset	Alternate Function
INTP0	Input	External interrupt inputs, with specifiable valid edges (rising edge, falling edge, and both rising and falling edges).	Input	P00/TI00
INTP1				P01/TI01
INTP2				P02
INTP3				P03
INTP4				P04
INTP5				P05
INTP6				P06
SI0	Input	Serial data input of the serial interface	Input	P25/SB0
SI1				P20
SI2				P70/RxD
SO0	Output	Serial data output of the serial interface	Input	P26/SB1
SO1				P21
SO2				P71/TxD
SB0	Input/output	Serial data input/output of the serial interface	Input	P25/SI0
SB1				P26/SO0
$\overline{SCK0}$	Input/output	Serial clock input/output of the serial interface	Input	P27
$\overline{SCK1}$				P22
$\overline{SCK2}$				P72/ASCK
STB	Output	Automatic transmitting/receiving strobe output of the serial interface	Input	P23
BUSY	Input	Automatic transmitting/receiving busy input of the serial interface	Input	P24
RxD	Input	Serial data input for asynchronous serial interface	Input	P70/SI2
TxD	Output	Serial data output for asynchronous serial interface	Input	P71/SO2
ASCK	Input	Serial clock input for asynchronous serial interface	Input	P72/$\overline{SCK2}$
TI00	Input	External count clock input to 16-bit timer (TM0)	Input	P00/INTP0
TI01		Capture trigger signal input to capture register (CR00)		P01/INTP1
TI1		External count clock input to 8-bit timer (TM1)		P33
TI2		External count clock input to 8-bit timer (TM2)		P34
TO0	Output	16-bit timer (TM0) output (Can be used together with 14-bit PWM output.)	Input	P30
TO1		8-bit timer (TM1) output		P31
TO2		8-bit timer (TM2) output		P32

(2) Non-Port Pins (2/2)

Pin Name	Input/Output	Function	After Reset	Alternate Function
PCL	Output	Clock output (for trimming main system clock and subsystem clock)	Input	P35
BUZ	Output	Buzzer output	Input	P36
RTP0 to RTP7	Output	Real-time output port which outputs data in synchronization with trigger.	Input	P120 to P127
AD0 to AD7	Input/output	Low-order address/data bus when expanding memory to the outside.	Input	P40 to P47
A8 to A15	Output	High-order address bus when expanding memory to the outside.	Input	P50 to P57
$\overline{RD}$	Output	Strobe signal output for the external memory read operation	Input	P64
$\overline{WR}$		Strobe signal output for the external memory write operation	Input	P65
$\overline{WAIT}$	Input	Wait insertion when accessing external memory	Input	P66
ASTB	Output	Strobe output to externally latches address information which is output to ports 4 and 5 for accessing external memory.	Input	P67
ANI0 to ANI7	Input	Analog input of A/D converter	Input	P10 to P17
ANO0, ANO1	Output	Analog output of D/A converter	Input	P130, P131
AV_{REF0}	Input	Reference voltage input of A/D converter	—	—
AV_{REF1}	Input	Reference voltage input of D/A converter	—	—
AV_{DD}	—	Analog power supply of A/D converter (shared with the port power supply).	—	—
AV_{SS}	—	Ground potential of A/D converter and D/A converter (shared with the port ground potential).	—	—
$\overline{RESET}$	Input	System reset input	—	—
X1	Input	Main system clock oscillation crystal connection	—	—
X2	—		—	—
XT1	Input	Subsystem clock oscillation crystal connection	Input	P07
XT2	—		—	—
V_{DD}	—	Positive power supply (except for port)	—	—
V_{PP}	—	High-voltage applied during program write/verify. Connected to V_{SS} in normal operating mode.	—	—
V_{SS}	—	Ground potential (except for port)	—	—

Cautions 1. The AV_{DD} pin functions as both an A/D converter power supply and a port power supply. When the μPD78P058F is used in applications where the noise generated inside the microcontroller needs to be reduced, connect the AV_{DD} pin to another power supply which has the same potential as V_{DD}.

2. The AV_{SS} pin functions as both grounds of an A/D converter and D/A converter and of a port. When the μPD78P058F is used in applications where the noise generated inside the microcontroller needs to be reduced, connect the AV_{SS} pin to another ground line than V_{SS}.

2.2 Pins in PROM Programming Mode

Pin Name	Input/Output	Function
$\overline{\text{RESET}}$	Input	PROM programming mode setting When +5 V or +12.5 V is applied to the V_{PP} pin and a low-level signal is applied to the $\overline{\text{RESET}}$ pin, this chip is set in the PROM programming mode.
V_{PP}	Input	PROM programming mode setting and high-voltage applied during program write/ verification
A0 to A16	Input	Address bus
D0 to D7	Input/output	Data bus
$\overline{\text{CE}}$	Input	PROM enable input/program pulse input
$\overline{\text{OE}}$	Input	Read strobe input to PROM
$\overline{\text{PGM}}$	Input	Program/program inhibit input in PROM programing mode.
V_{DD}	—	Positive power supply
V_{SS}	—	Ground potential

2.3 Pin Input/Output Circuits and Recomended Connection of Unused Pins

Types of input/output circuits of the pins and recommeded connection of unused pins are shown in Table 2-1. For the configuration of each type of input/output circuit, see Figure 2-1.

Table 2-1. Pin Input/Output Circuits (1/2)

Pin Name	Input/Output Circuit Type	Input/Output	Recommended Connecting Method when Unused
P00/INTP0/TI00	2	Input	Connect to Vss.
P01/INTP1/TI01	8-D	Input/output	Independently connect to Vss through resistor.
P02/INTP2			
P03/INTP3			
P04/INTP4			
P05/INTP5			
P06/INTP6			
P07/XT1	16	Input	Connect to VDD.
P10/ANI0 to P17/ANI7	11-C	Input/output	Independently connect to VDD or Vss through resistor.
P20/SI1	8-D		
P21/SO1	5-J		
P22/$\overline{SCK1}$	8-D		
P23/STB	5-J		
P24/BUSY	8-D		
P25/SI0/SB0	10-C		
P26/SO0/SB1			
P27/$\overline{SCK0}$			
P30/TO0	5-J		
P31/TO1			
P32/TO2			
P33/TI1	8-D		
P34/TI2			
P35/PCL	5-J		
P36/BUZ			
P37			
P40/AD0 to P47/AD7	5-O		Independently connect to VDD through resistor.

Table 2-1. Pin Input/Output Circuits (2/2)

Pin Name	Input/Output Circuit Type	Input/Output	Recommended Connecting Method when Unused
P50/A8 to P57/A15	5-J	Input/output	Independently connect to V_{DD} or V_{SS} through resistor.
P60 to P63	13-H		Independently connect to V_{DD} through resistor.
P64/$\overline{RD}$	5-J	Input/output	Independently connect to V_{DD} or V_{SS}.
P65/$\overline{WR}$			
P66/$\overline{WAIT}$			
P67/ASTB			
P70/SI2/RxD	8-D	Input/output	
P71/SO2/TxD	5-J		
P72/$\overline{SCK2}$/ASCK	8-D		
P120/RTP0 to P127/RTP7	5-J	Input/output	
P130/ANO0, P131/ANO1	12-B	Input/output	Independently connect to V_{SS} through resistor.
$\overline{RESET}$	2	Input	—
XT2	16	—	Leave open.
AV_{REF0}	—		Connect to V_{SS}.
AV_{REF1}			Connect to V_{DD}.
AV_{DD}			Connect to another ground line which has the same potential as V_{DD}.
AV_{SS}			Connect to another power supply which has the same potential as V_{SS}.
V_{PP}			Connect to V_{SS}.

Figure 2-1. Pin Input/Output Circuits (1/2)

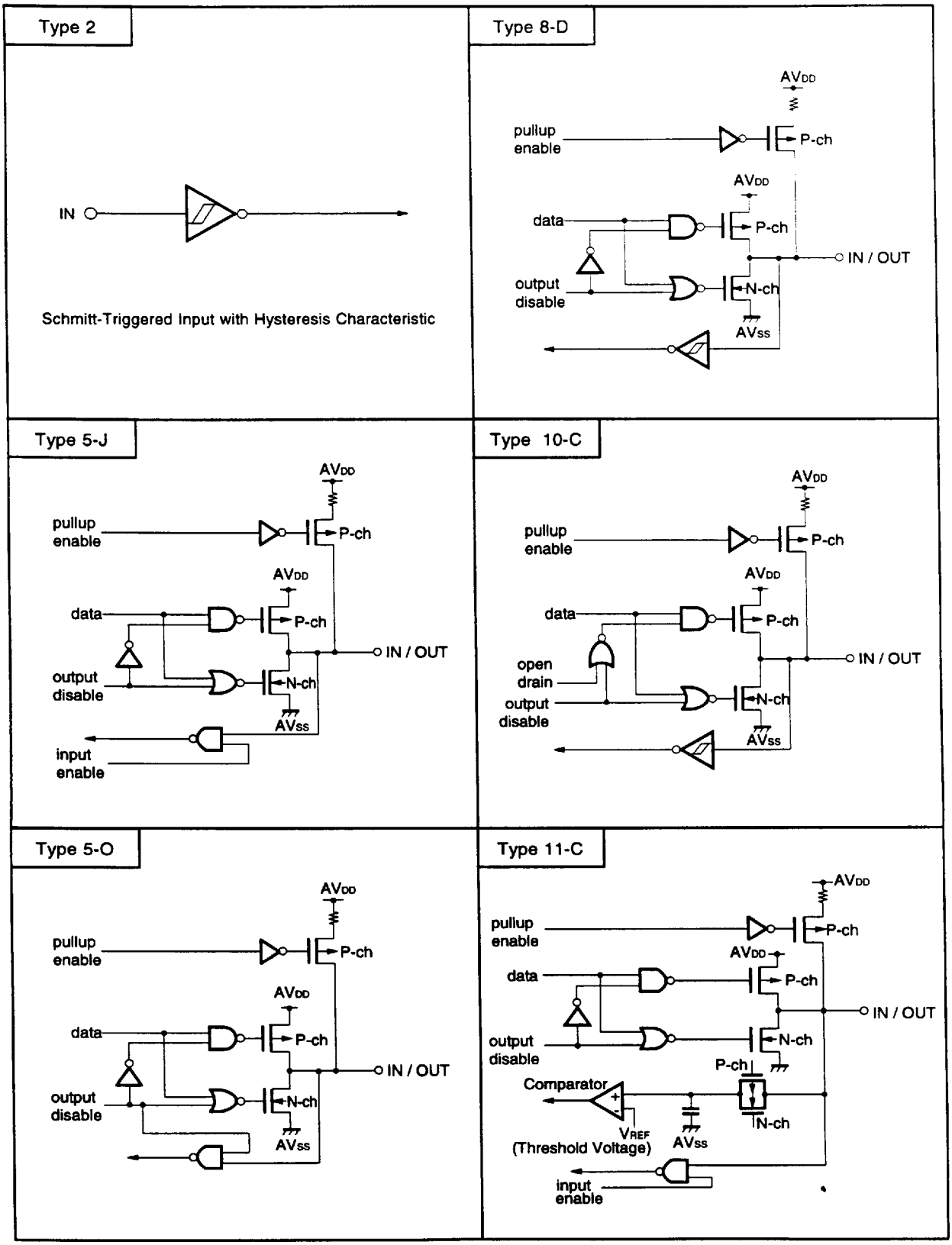
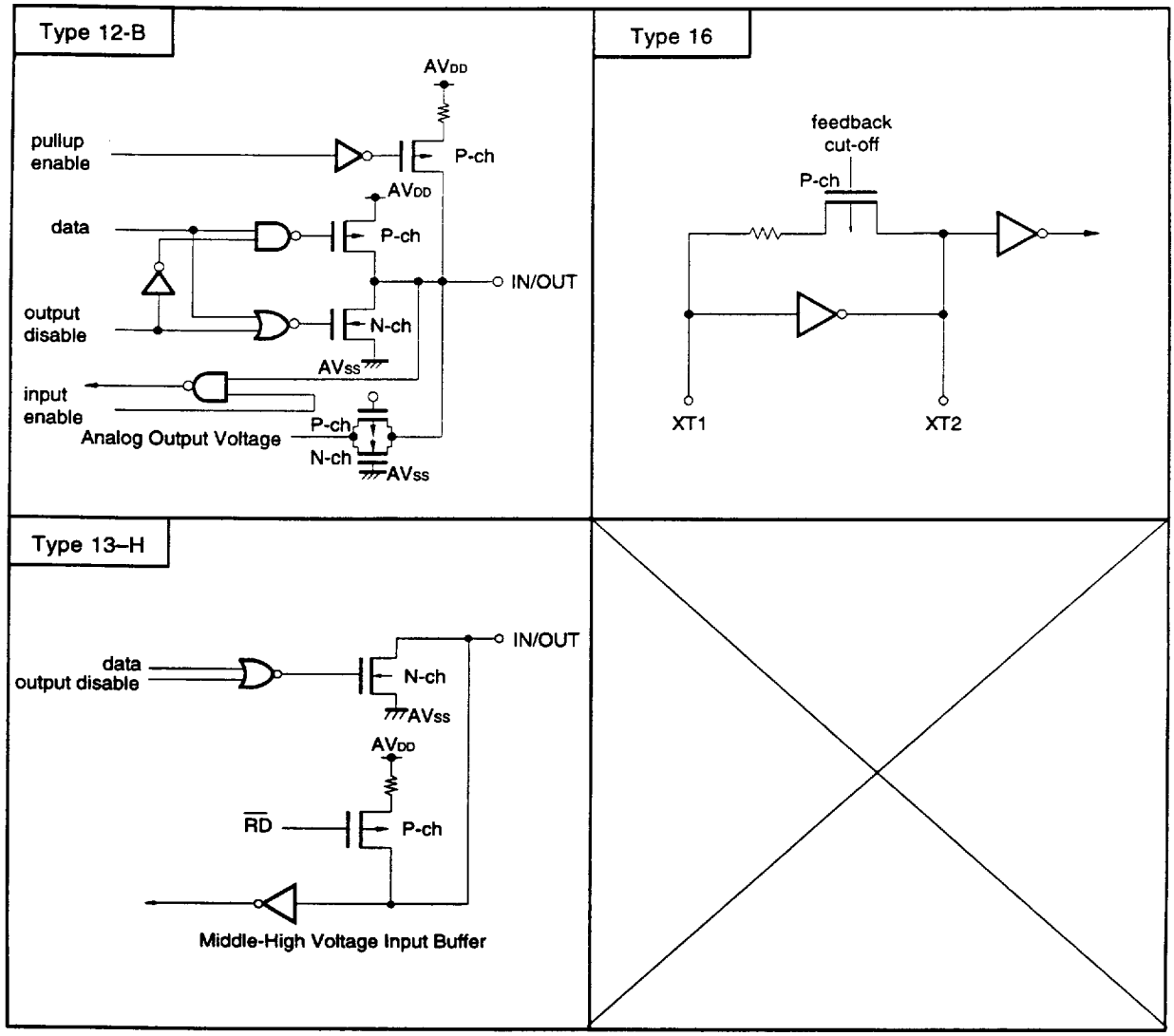


Figure 2-1. Pin Input/Output Circuits (2/2)



3. MEMORY SIZE SWITCHING REGISTER (IMS)

This is a register to disable use of part of internal memories by software. By setting this memory size switching register (IMS), it is possible to get the same memory mapping as that of mask ROM version having different internal memories (ROM).

The IMS is set up by the 8-bit memory manipulation instruction.

CFH will result by the $\overline{\text{RESET}}$ input.

Figure 3-1. Memory Size Switching Register Format

Symbol	7	6	5	4	3	2	1	0	Address	After Reset	R/W
IMS	RAM2	RAM1	RAM0	0	ROM3	ROM2	ROM1	ROM0	FFF0H	CFH	R/W

ROM3	ROM2	ROM1	ROM0	Selection of Internal ROM Capacity
1	1	0	0	48K bytes
1	1	1	0	56K bytes[Note]
1	1	1	1	60K bytes
Other than above				Setting prohibited

RAM2	RAM1	RAM0	Selection of Internal High-Speed RAM Capacity
1	1	0	1024 bytes
Other than above			Setting prohibited

Note Set the internal ROM capacity to 56K bytes or less when external device expansion function is used.

Table 3-1 shows the setting values of IMS which makes the memory mapping the same as that of the various mask ROM versions.

Table 3-1. Memory Size Switching Register Setting Values

Target Mask ROM Version	IMS Setting Value
μPD78056F	CCH
μPD78058F	CFH

4. INTERNAL EXPANSION RAM SIZE SWITCHING REGISTER (IXS)

This is a register to set the internal expansion RAM capacity by software. By setting this internal expansion RAM size switching register (IXS), it is possible to get the same memory mapping as that of mask ROM version having different internal expansion RAM.

The IXS is set up by 8-bit memory manipulation instruction.

0AH will result by the $\overline{\text{RESET}}$ input.

Figure 4-1. Internal Expansion RAM Size Switching Register Format

Symbol	7	6	5	4	3	2	1	0	Address	After Reset	R/W
IXS	0	0	0	0	IXRAM3	IXRAM2	IXRAM1	IXRAM0	FFF4H	0AH	W

IXRAM3	IXRAM2	IXRAM1	IXRAM0	Selection of Internal Expansion RAM Capacity
1	1	0	0	0 byte
1	0	1	0	1024 bytes
Other than above				Setting prohibited

Table 4-1 shows the setting values of IXS which makes the memory mapping the same as that of the various mask ROM versions.

Table 4-1. Internal Expansion RAM Size Switching Register Setting Values

Target Mask ROM Version	IXS Setting Value
μPD78056F	0CH
μPD78058F	0AH

Remark Even if the μPD78P058F program that includes "MOV IXS, #0CH" is implemented on the μPD78056F, its operation will not be affected.

5. PROM PROGRAMMING

The μPD78P058F has an on-chip 60K-byte PROM as a program memory. For programming, set the PROM programming mode by the V_{PP} and $\overline{RESET}$ pins. For connecting unused pins, refer to **"PIN CONFIGURATIONS (TOP VIEW) (2) PROM Programming Mode."**

Caution Program writing should be performed in the address range 0000H to EFFFH (the last address, EFFFH, should be specified). Writing cannot be performed with a PROM programmer that cannot specify the write addresses.

5.1 Operating Modes

When +5 V or +12.5 V is applied to the V_{PP} pin and a low level signal is applied to the $\overline{RESET}$ pin, the PROM programming mode is set. This mode will become the operating mode as shown in Table 5-1 when the $\overline{CE}$, $\overline{OE}$ and $\overline{PGM}$ pins are set as shown.

Further, when the read mode is set, it is possible to read the contents of the PROM.

Table 5-1. Operating Modes of PROM Programming

Pin / Operating Mode	$\overline{RESET}$	V_{PP}	V_{DD}	$\overline{CE}$	$\overline{OE}$	$\overline{PGM}$	D0 to D7
Page data latch	L	+12.5 V	+6.5 V	H	L	H	Data input
Page write				H	H	L	High-impedance
Byte write				L	H	L	Data input
Program verify				L	L	H	Data output
Program inhibit				×	H	H	High-impedance
				×	L	L	
Read		+5 V	+5 V	L	L	H	Data output
Output disable				L	H	×	High-impedance
Standby				H	×	×	High-impedance

Remark × : L or H

(1) Read mode

Read mode is set if $\overline{CE}$ = L, $\overline{OE}$ = L is set.

(2) Output disable mode

Data output becomes high-impedance, and is in the output disable mode, if $\overline{OE}$ = H is set.

Therefore, it allows data to be read from any device by controlling the $\overline{OE}$ pin, if multiple μPD78P058F are connected to the data bus.

(3) Standby mode

Standby mode is set if $\overline{CE}$ = H is set.

In this mode, data outputs become high-impedance irrespective of the $\overline{OE}$ status.

(4) Page data latch mode

Page data latch mode is set if $\overline{CE}$ = H, $\overline{PGM}$ = H, $\overline{OE}$ = L are set at the beginning of page write mode.

In this mode, 1 page 4-byte data is latched in an internal address/data latch circuit.

(5) Page write mode

After 1 page 4 bytes of addresses and data are latched in the page data latch mode, a page write is executed by applying a 0.1 ms program pulse (active low) to the $\overline{PGM}$ pin with $\overline{CE}$ = H, $\overline{OE}$ = H. Then, program verification can be performed, if $\overline{CE}$ = L, $\overline{OE}$ = L are set.

If programming is not performed by a one-time program pulse, X (X ≤ 10) write and verification operations should be executed repeatedly.

(6) Byte write mode

Byte write is executed when a 0.1 ms program pulse (active low) is applied to the $\overline{PGM}$ pin with $\overline{CE}$ = L, $\overline{OE}$ = H. Then, program verification can be performed if $\overline{OE}$ = L is set.

If programming is not performed by a one-time program pulse, X (X ≤ 10) write and verification operations should be executed repeatedly.

(7) Program verify mode

Program verify mode is set if $\overline{CE}$ = L, $\overline{PGM}$ = H, $\overline{OE}$ = L are set.

In this mode, check if a write operation is performed correctly, after the write.

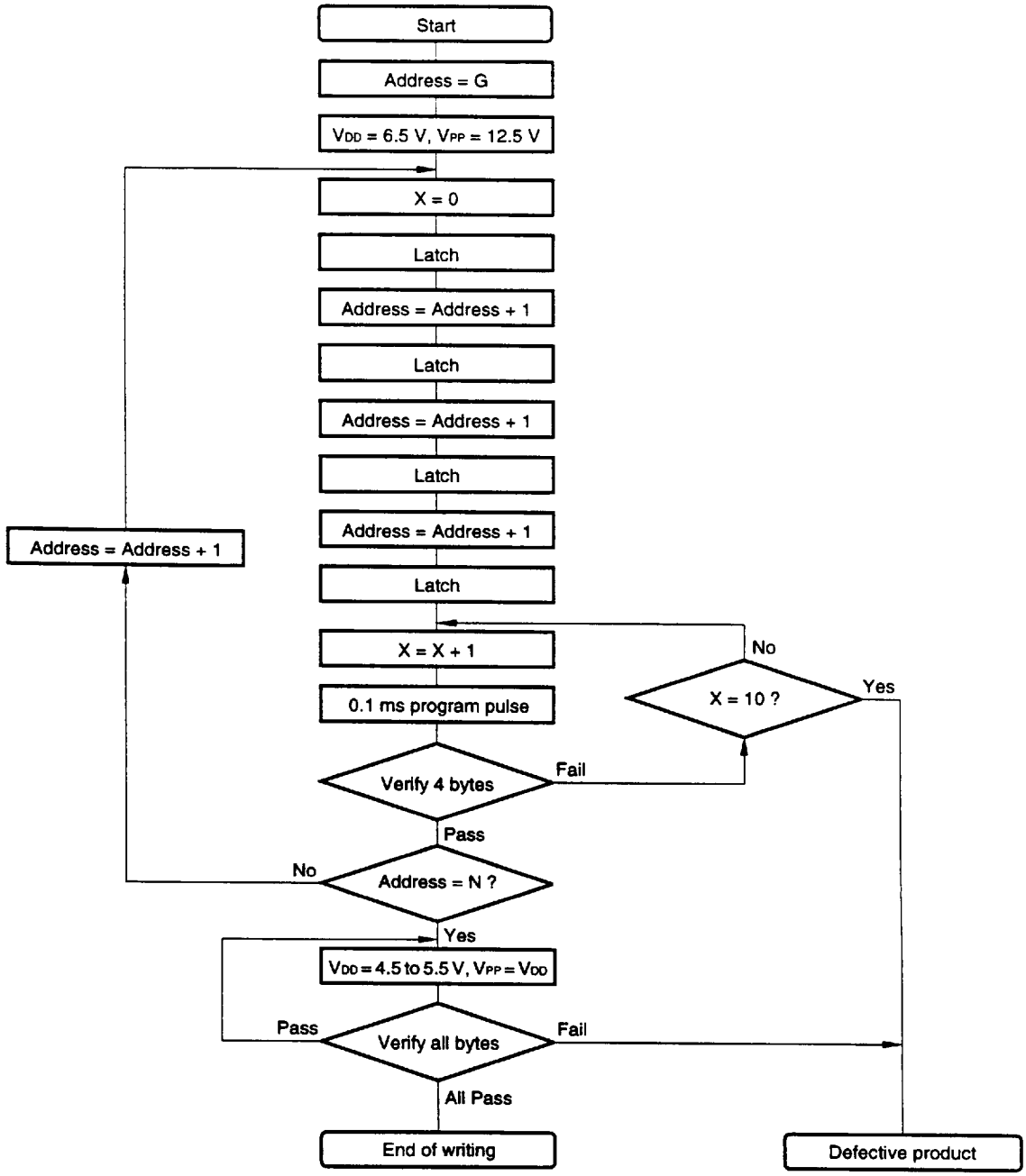
(8) Program inhibit mode

Program inhibit mode is used when the $\overline{OE}$ pin, V_{PP} pin, and D0 to D7 pins of multiple μPD78P058Fs are connected in parallel and a write is performed to one of those devices.

When a write operation is performed, the page write mode or byte write mode described above is used. At this time, a write is not performed to a device which has the $\overline{PGM}$ pin driven high.

5.2 PROM Write Pocedure

Figure 5-1. Page Program Mode Flowchart



Remark G = Start address
N = Program last address

Figure 5-2. Page Program Mode Timing

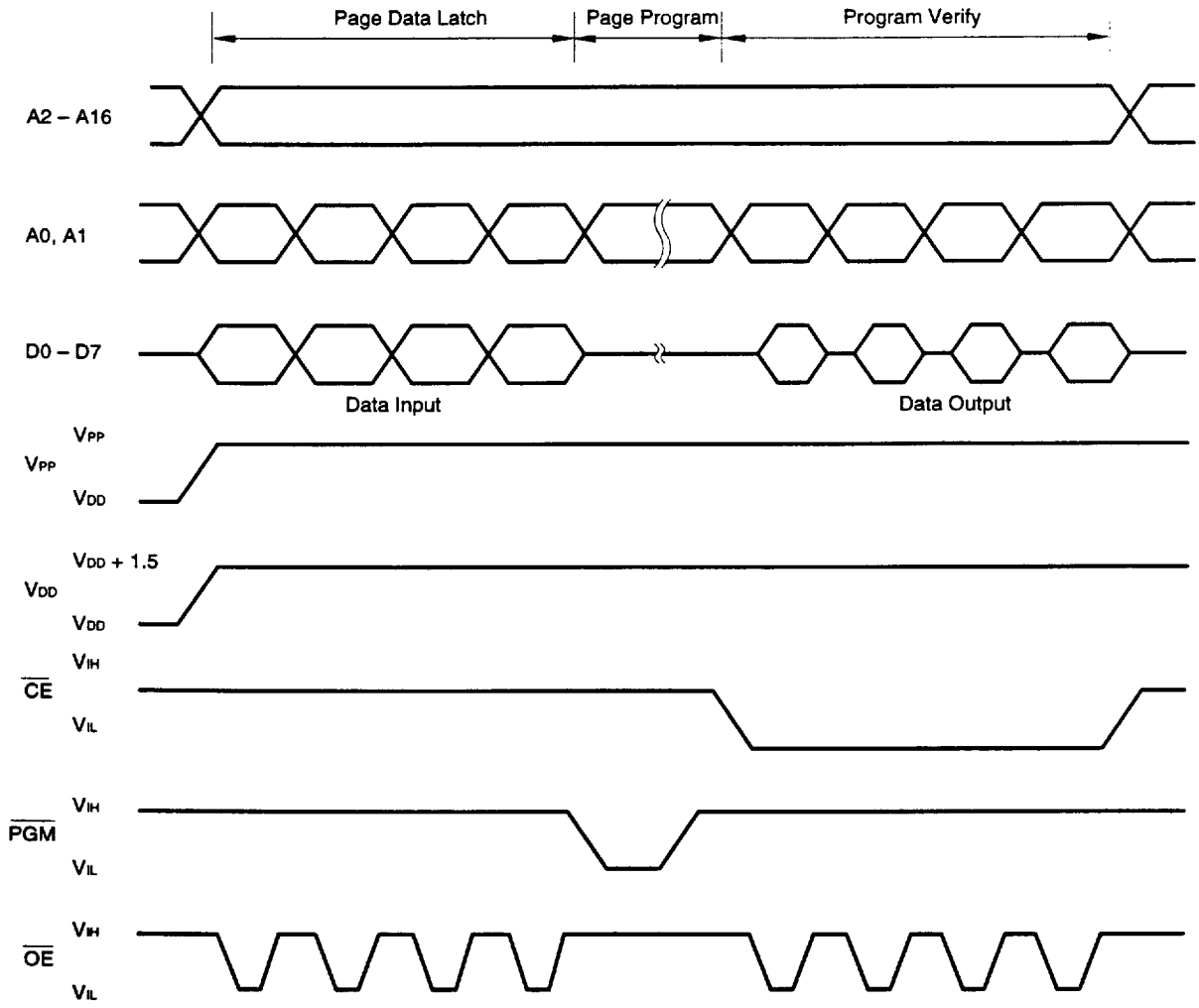
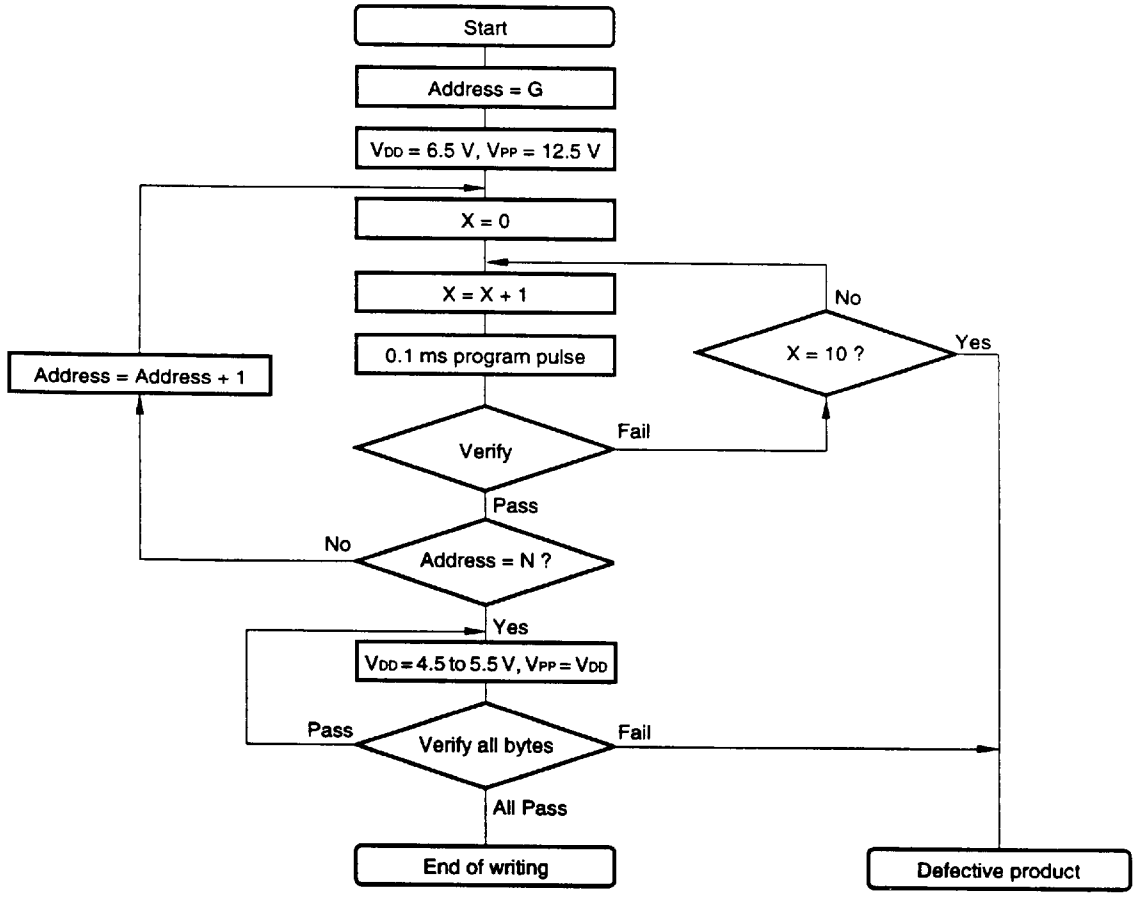
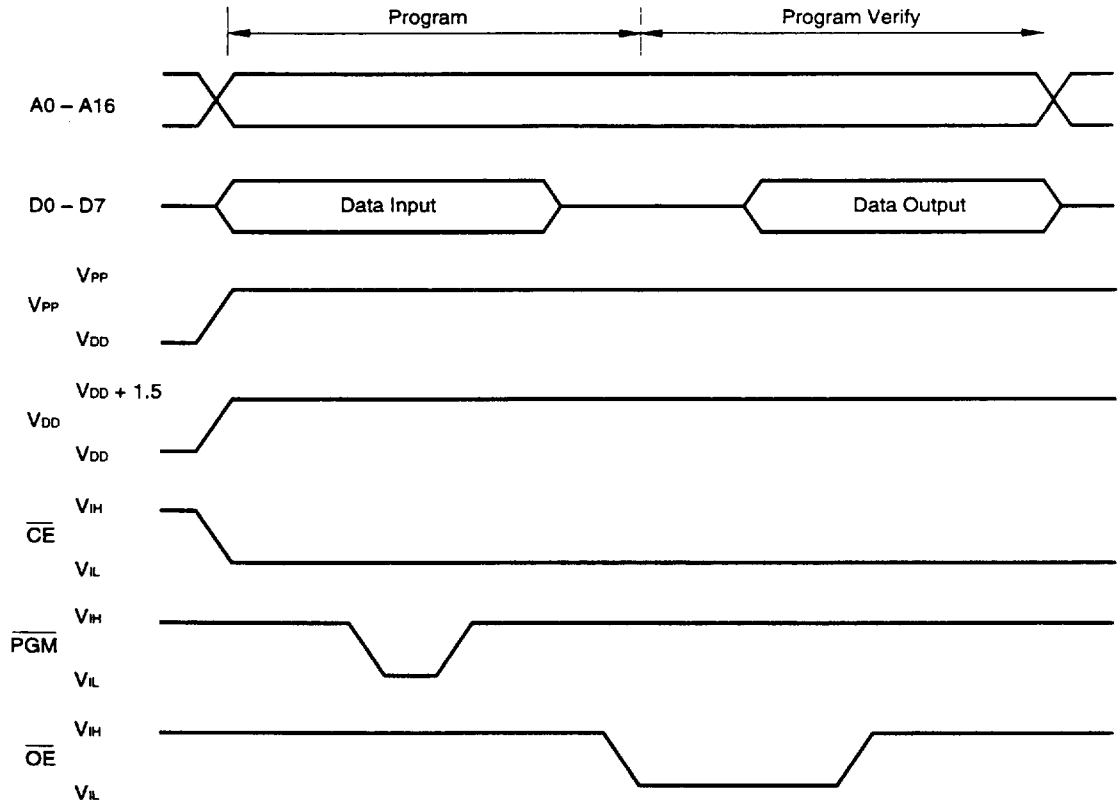


Figure 5-3. Byte Program Mode Flowchart



Remark G = Start address
N = Program last address

Figure 5-4. Byte Program Mode Timing



Cautions
1. **V_{DD} should be applied before V_{PP} and removed after V_{PP}.**
2. **V_{PP} must not exceed +13.5 V including overshoot.**
3. **Reliability may be adversely affected if removal/reinsertion is performed while +12.5 V is being applied to V_{PP}.**

5.3 PROM Read Procedure

The contents of PROM are readable to the external data bus (D0 to D7) according to the read procedure shown below.

(1) Fix the $\overline{\text{RESET}}$ pin at low level, supply +5 V to the V_{PP} pin, and connect all other unused pins as shown in **"PIN CONFIGURATION (TOP VIEW) (2) PROM Programming Mode"**.

(2) Supply +5 V to the V_{DD} and V_{PP} pins.

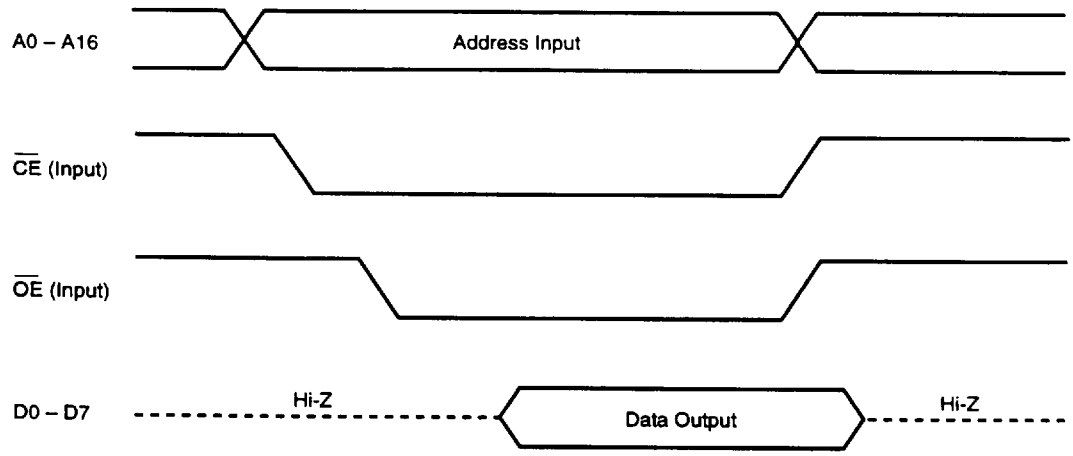
(3) Input address of read data into the A0 to A16 pins.

(4) Read mode

(5) Output data to D0 to D7 pins.

The timings of the above steps (2) to (5) are shown in Figure 5-5.

Figure 5-5. PROM Read Timings



6. SCREENING OF ONE-TIME PROM VERSIONS

The one-time PROM version (μPD78P058FGC-3B9, 78P058FGC-8BT) can not be tested completely by NEC before it is shipped, because of its structure. It is recommended to perform screening to verify PROM after writing necessary data and performing high-temperature storage under the condition below.

Storage Temperature	Storage Time
125 °C	24 hours

At present, a fee is charged by NEC for one-time PROM after-programming imprinting, screening, and verify service for the QTOP Microcontroller. For details, contact your sales representative.

7. ELECTRICAL SPECIFICATIONS

Absolute Maximum Ratings (T_A = 25 °C)

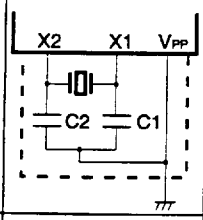
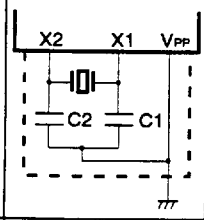
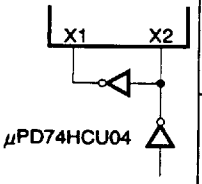
PARAMETER	SYMBOL	TEST CONDITIONS		RATING	UNIT
Supply voltage	V_{DD}			−0.3 to +7.0	V
	V_{PP}			−0.3 to +13.5	V
	AV_{DD}			−0.3 to V_{DD} + 0.3	V
	AV_{REF0}			−0.3 to V_{DD} + 0.3	V
	AV_{REF1}			−0.3 to V_{DD} + 0.3	V
	AV_{SS}			−0.3 to + 0.3	V
Input voltage	V_{I1}	P00 to P07, P10 to P17, P20 to P27, P30 to P37, P40 to 47, P50 to P57, P64 to P67, P70 to P72, P120 to P127, P130, P131, X1, X2, XT2, $\overline{RESET}$		−0.3 to V_{DD} + 0.3	
	V_{I2}	P60 to P63	N-ch open drain	−0.3 to +16	V
	V_{I3}	A9	PROM programming mode	−0.3 to +13.5	V
Output voltage	V_O			−0.3 to V_{DD} + 0.3	V
Analog input voltage	V_{AN}	P10 to P17	Analog input pins	AV_{SS} − 0.3 to AV_{REF0} + 0.3	V
Output current, high	I_{OH}	Per pin		−10	mA
		Total for P01 to P06, P30 to P37, P56, P57, P60 to P67, P120 to P127		−15	mA
		Total for P10 to P17, P20 to P27, P40 to P47, P50 to P55, P70 to P72, P130, P131		−15	mA
Output current, low	I_{OL} Note	Per pin	peak value	30	mA
			r.m.s. value	15	mA
		Total for P50 to P55	peak value	100	mA
			r.m.s. value	70	mA
		Total for P56, P57, P60 to P63	peak value	100	mA
			r.m.s. value	70	mA
		Total for P10 to P17, P20 to P27, P40 to P47, P70 to P72, P130, P131	peak value	50	mA
			r.m.s. value	20	mA
		Total for P01 to P06, P30 to P37, P64 to P67, P120 to P127	peak value	50	mA
			r.m.s value	20	mA
Operating ambient temperature	T_A			−40 to +85	°C
Storage temperature	T_{stg}			−65 to +150	°C

Note r.m.s. values should be calculated as follows: [r.m.s. value] = [peak value] x $\sqrt{\text{Duty}}$

Caution Product quality may suffer if the absolute maximum rating is exceeded for even a single parameter, or even momentarily. In other words, the absolute maximum ratings are rated values at which the product is on the verge of suffering physical damage, and therefore the product must be used under conditions which ensure that the absolute maximum ratings are not exceeded.

Remark Unless otherwise specified, dual-function pin characteristics are the same as port pin characteristics.

Main System Clock Oscillator Characteristics (T_A = −40 to +85 °C, V_{DD} = 2.7 to 6.0 V)

RESONATOR	RECOMMENDED CIRCUIT	PARAMETER	TEST CONDITIONS	MIN.	TYP.	MAX.	UNIT
Ceramic resonator		Oscillatior frequency (fx)Note1	V_{DD} = Oscillation voltage range	1.0		5.0	MHz
		Oscillatior stabilization timeNote2	After V_{DD} has reached MIN. of oscillation voltage range			4	ms
Crystal resonator		Oscillatior frequency (fx)Note1		1.0		5.0	MHz
		Oscillatior stabilization timeNote2	V_{DD} = 4.5 to 6.0 V			10	ms
						30	
External clock		X1 input frequency (fx)Note1		1.0		5.0	MHz
		X1 input high-/low-level width (t_{XH}/t_{XL})		85		500	ns

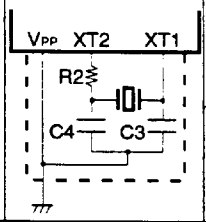
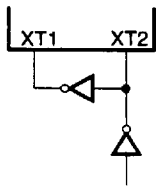
Notes 1. Only the oscillator characteristics are shown. See the AC characteristics for instruction execution times.
2. This is the time required for oscillation to stabilize after a reset or STOP mode release.

Cautions **1. When the main system clock oscillator is used, the following should be noted concerning wiring in the area in the figure enclosed by broken lines to prevent the influence of wiring capacitance, etc.**

- **The wiring should be kept as short as possible.**
- **No other signal lines should be crossed.**
- **Keep away from lines carrying a high fluctuating current.**
- **The oscillator capacitor grounding point should always be at the same potential as Vss.**
- **Do not connect to a ground pattern carrying a high current.**
- **A signal should not be taken from the oscillator.**

2. When the main system clock is stopped and the device is operating on the subsystem clock, wait until the oscillation stabilization time has been secured by the program before switching back to the main system clock.

Subsystem Clock Osillator Characteristics (T_A = –40 to +85 °C, V_{DD} = 2.7 to 6.0 V)

RESONATOR	RECOMMENDED CIRCUIT	PARAMETER	TEST CONDITIONS	MIN.	TYP.	MAX.	UNIT
Ceramic resonator		Oscillatior frequency (f_X)[Note1]		32	32.768	35	kHz
		Oscillatior stabilization time[Note2]	V_{DD} = 4.5 to 6.0 V		1.2	2	s
						10	
External clock		X1 input frequency (f_{XT})[Note1]		32		100	kHz
		X1 input high-/low-level width (t_{XTH}/t_{XTL})		5		15	μs

Notes 1. Only the oscillator characteristics are shown. See the AC characteristics for instruction execution times.
2. This is the time required for oscillation to stabilize after power (V_{DD}) is turned on.

Cautions **1. When the subsystem clock oscillator is used, the following should be noted concerning wiring in the area in the figure enclosed by broken lines to prevent the influence of wiring capacitance, etc.**

- **The wiring should be kept as short as possible.**
- **No other signal lines should be crossed.**
- **Keep away from lines carrying a high fluctuating current.**
- **The oscillator capacitor grounding point should always be at the same potential as VSS.**
- **Do not connect to a ground pattern carrying a high current.**
- **A signal should not be taken from the oscillator.**

2. The subsystem clock oscillator is a low-amplitude circuit in order to achieve a low consumption current, and is more prone to misoperation due to noise than the main system clock oscillator. Particular care is therefore required with the wiring method when the subsystem clock is used.

Capacitance (T_A = 25 °C, V_{DD} = V_{SS} = 0 V)

PARAMETER	SYMBOL	TEST CONDITIONS		MIN.	TYP.	MAX.	UNIT
Input capacitance	C_{IN}	f = 1 MHz, Measured pins returned to 0 V.				15	pF
Input/output capacitance	C_{IO}	f = 1 MHz Measured pins returned to 0	P01 to P06, P10 to P17, P20 to P27, P30 to P37, P40 to P47, P50 to P57, P64 to P67, P70 to P72, P120 to P127, P130, P131			15	pF
			P60 to P63			20	pF

Remark Unless specified otherwise, dual-function pin characteristics are the same as port pin characteristics.

DC Characteristics (T_A = −40 to +85°C, V_{DD} = 2.7 to 6.0 V)

PARAMETER	SYMBOL	TEST CONDITIONS		MIN.	TYP.	MAX.	UNIT
Input voltage, high	V_{IH1}	P10 to P17, P21, P23, P30 to P32, P35 to P37, P40 to P47, P50 to P57, P64 to P67, P71, P120 to P127, P130, P131		0.7 V_{DD}		V_{DD}	V
	V_{IH2}	P00 to P06, P20, P22, P24 to P27, P33, P34, P70, P72, $\overline{RESET}$		0.8 V_{DD}		V_{DD}	V
	V_{IH3}	P60 to P63 (N-ch open-drain)		0.7 V_{DD}		15	V
	V_{IH4}	X1, X2		V_{DD} − 0.5		V_{DD}	V
	V_{IH5}	XT1/P07, XT2	V_{DD} = 4.5 to 6.0 V	0.8 V_{DD}		V_{DD}	V
				0.9 V_{DD}		V_{DD}	V
Input voltage, low	V_{IL1}	P10 to P17, P21, P23, P30 to P32, P35 to P37, P40 to P47, P50 to P57, P64 to P67, P71, P120 to P127, P130, P131		0		0.3 V_{DD}	V
	V_{IL2}	P00 to P06, P20, P22, P24 to P27, P33, P34, P70, P72, $\overline{RESET}$		0		0.2 V_{DD}	V
	V_{IL3}	P60 to P63	V_{DD} = 4.5 to 6.0 V	0		0.3 V_{DD}	V
				0		0.2 V_{DD}	V
	V_{IL4}	X1, X2		0		0.4	V
	V_{IL5}	XT1/P07, XT2	V_{DD} = 4.5 to 6.0 V	0		0.2 V_{DD}	V
				0		0.1 V_{DD}	V
Output voltage, high	V_{OH}	V_{DD} = 4.5 to 6.0 V, I_{OH} = − 1mA		V_{DD} − 1.0			V
		I_{OH} = −100 μA		V_{DD} − 0.5			V
Output voltage, low	V_{OL1}	P50 to P57, P60 to P63	V_{DD} = 4.5 to 6.0 V, I_{OL} = 15 mA		0.4	2.0	V
		P01 to P06, P10 to P17, P20 to P27, P30 to P37, P40 to P47, P64 to P67, P70 to P72, P120 to P127, P130, P131	V_{DD} = 4.5 to 6.0 V, I_{OL} = 1.6 mA			0.4	V
	V_{OL2}	SB0, SB1, $\overline{SCK0}$	V_{DD} = 4.5 to 6.0 V, N-ch open-drain at pull-up time (R = 1 kΩ)			0.2 V_{DD}	V
	V_{OL3}	I_{OL} = 400 μA				0.5	V
Input leakage current, high	I_{LIH1}	V_{IN} = V_{DD}	P00 to P06, P10 to P17, P20 to P27, P30 to P37, P40 to P47, P50 to P57, P60 to P67, P70 to P72, P120 to P127, P130, P131, $\overline{RESET}$			3	μA
	I_{LIH2}		X1, X2, XT1/P07, XT2			20	μA
	I_{LIH3}	V_{IN} = 15 V	P60 to P63			80	μA

Remark Unless specified otherwise, dual-function pin characteristics are the same as port pin characteristics.

DC Characteristics (T_A = −40 to +85 °C, V_{DD} = 2.7 to 6.0 V)

PARAMETER	SYMBOL	TEST CONDITIONS		MIN.	TYP.	MAX.	UNIT
Input leakage current, low	I_{LIL1}	V_{IN} = 0 V	P00 to P06, P10 to P17, P20 to P27, P30 to P37, P40 to P47, P50 to P57, P60 to P67, P70 to P72, P120 to P127, P130, P131, $\overline{RESET}$			−3	μA
	I_{LIL2}		X1, X2, XT1/P07, XT2			−20	μA
	I_{LIL3}		P60 to P63			−3[Note]	μA
Output leakage current, high	I_{LOH}	V_{OUT} = V_{DD}				3	μA
Output leakage current, low	I_{LOL}	V_{OUT} = 0 V				−3	μA
Software pull-up resistor	R_2	V_{IN} = 0 V, P01 to P06, P10 to P17, P20 to P27, P30 to P37, P40 to P47, P50 to P57, P64 to P67, P70 to P72, P120 to P127, P130, P131	V_{DD} = 4.5 to 6.0 V	15	40	90	kΩ
				20		500	kΩ

Note When the pull-up resistor is not included in P60 to P63 (specified by a mask option), the −200 μA (MAX.) low-level input leakage current is passed only at the 1.5 clock interval (no wait) when the read instruction to the port6 (P6) and port mode register (PM6) is executed. Other than the 1.5 clock interval, −3 μA (MAX.) is passed.

Remark Unless specified otherwise, dual-function pin characteristics are the same as port pin characteristics.

DC Characteristics (T_A = −40 to +85 °C, V_{DD} = 2.7 to 6.0 V)

PARAMETER	SYMBOL	TEST CONDITIONS		MIN.	TYP.	MAX.	UNIT
Supply current[Note1]	I_{DD1}	5.0 MHz crystal oscillation operating mode (f_{XX} = 2.5 MHz)[Note2]	V_{DD} = 5.0 V ± 10%[Note5]		5	15	mA
			V_{DD} = 3.0 V ± 10%[Note6]		0.7	2.1	mA
		5.0 MHz crystal oscillation operating mode (f_{XX} = 5.0 MHz)[Note3]	V_{DD} = 5.0 V ± 10%[Note5]		9.0	27.0	mA
			V_{DD} = 3.0 V ± 10%[Note6]		1.0	3.0	mA
	I_{DD2}	5.0 MHz crystal oscillation HALT mode (f_{XX} = 2.5 MHz)[Note2]	V_{DD} = 5.0 V ± 10%		1.4	4.2	mA
			V_{DD} = 3.0 V ± 10%		0.5	1.5	mA
		5.0 MHz crystal oscillation HALT mode (f_{XX} = 5.0 MHz)[Note3]	V_{DD} = 5.0 V ± 10%		1.6	4.8	mA
			V_{DD} = 3.0 V ± 10%		0.65	1.95	mA
	I_{DD3}	32.768 kHz crystal oscillation operating mode[Note4]	V_{DD} = 5.0 V ± 10%		135	270	μA
			V_{DD} = 3.0 V ± 10%		95	190	μA
	I_{DD4}	32.768 kHz crystal oscillation HALT mode[Note4]	V_{DD} = 5.0 V ± 10%		25	55	μA
			V_{DD} = 3.0 V ± 10%		5	15	μA
	I_{DD5}	XT1 = V_{DD} STOP mode Feedback resistor used	V_{DD} = 5.0 V ± 10%		1	30	μA
			V_{DD} = 3.0 V ± 10%		0.5	10	μA
	I_{DD6}	XT1 = V_{DD} STOP mode Feedback resistor not used	V_{DD} = 5.0 V ± 10%		0.1	30	μA
			V_{DD} = 3.0 V ± 10%		0.05	10	μA

Notes
1. Passed through the V_{DD} and AV_{DD} pins. Not include the current which is passed through the A/D converter, D/A converter, and on-chip pull-up resistor.
2. f_{XX} = f_X/2 operation (when an oscillation mode selection register (OSMS) is set to 00H)
3. f_{XX} = f_X operation (when the OSMS is set to 01H)
4. When the main system clock is stopped
5. High-speed mode operation (when a processor clock control register (PCC) is set to 00H)
6. Low-speed mode operation (when the PCC is set to 04H)

Remarks
1. f_{XX} : Main system clock frequency (f_X or f_X/2)
2. f_X : Main system clock oscillator frequency

AC Characteristics

(1) Basic Operation (T_A = –40 to +85 °C, V_{DD} = 2.7 to 6.0 V)

PARAMETER	SYMBOL	TEST CONDITIONS			MIN.	TYP.	MAX.	UNIT
Cycle time (minimum instruction execution time)	T_{CY}	Operating on main system clock	$f_{XX} = f_X/2^{N}$ (Note 1)		0.8		64	μs
			$f_{XX} = f_X$ (Note 2)	V_{DD} = 4.5 to 6.0 V	0.4		32	μs
					0.8		32	μs
		Operating on subsystem clock			40	122	125	μs
TI00 input high-/low level width	t_{TIH00}, t_{TIL00}	V_{DD} = 4.5 to 6.0 V			$2/f_{sam} + 0.1$ (Note 3)			μs
					$2/f_{sam} + 0.2$ (Note 3)			μs
TI01 input high-/low level width	t_{TIH01}, t_{TIL01}				10			μs
TI1, TI2 input frequency	f_{TI1}	V_{DD} = 4.5 to 6.0 V			0		4	MHz
					0		275	kHz
TI1, TI2 input high-/low-level width	t_{TIH1}, t_{TIL1}	V_{DD} = 4.5 to 6.0 V			100			ns
					1.8			μs
Interrupt input high-/low-level width	t_{INTL}, t_{INTH}	INTP0		V_{DD} = 4.5 to 6.0 V	$2/f_{sam} + 0.1$ (Note 3)			μs
					$2/f_{sam} + 0.2$ (Note 3)			μs
		INTP1 to INTP6, KR0 to KR7			10			μs
$\overline{\text{RESET}}$ low-level width	t_{RSL}				10			μs

Notes 1. When oscillation mode selection register (OSMS) is set to 00H.

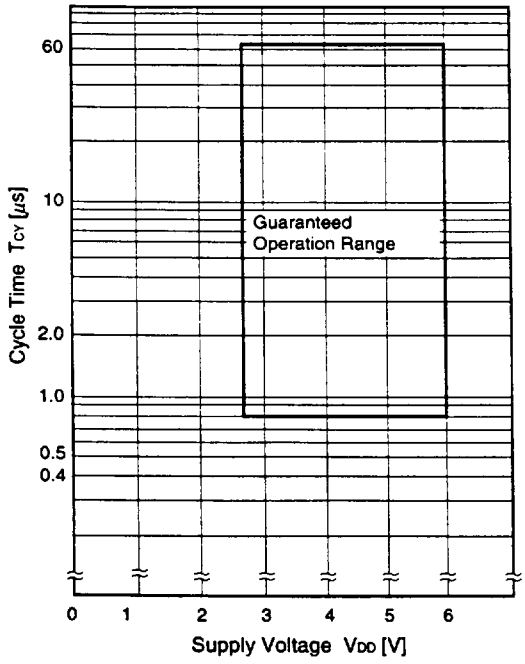
2. When OSMS is set to 01H.

3. f_{sam} can be selected as $f_{XX}/2^N$, $f_{XX}/32$, $f_{XX}/64$, or $f_{XX}/128$ (N = 0 to 4) by bits 0 and 1 (SCS0 and SCS1) of the sampling clock selection register (SCS).

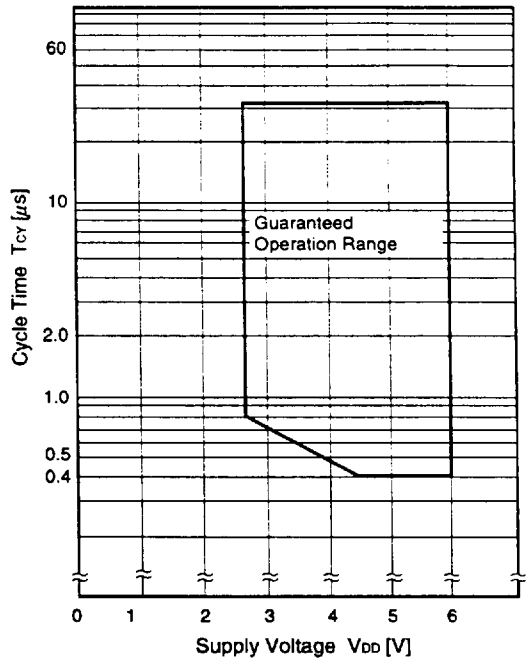
Remarks 1. f_{XX} : Main system clock frequency (f_X or $f_X/2$)

2. f_X : Main system clock oscillatior frequency

T_{CY} vs V_{DD} (Main System Clock, fxx = fx/2)



T_{CY} vs V_{DD} (Main System Clock, fxx = fx)



(2) Read/Write Operations

(a) When MCS = 1, PCC2 to PCC0 = 000B (T_A = −40 to +85 °C, V_{DD} = 4.5 to 6.0 V)

PARAMETER	SYMBOL	TEST CONDITIONS	MIN.	MAX.	UNIT
ASTB high-level width	t_{ASTH}		0.85 t_{CY} − 50		ns
Address setup time	t_{ADS}		0.85 t_{CY} − 50		ns
Address hold time	t_{ADH}		50		ns
Data input time from address	t_{ADD1}			(2.85 + 2n)t_{CY} − 80	ns
	t_{ADD2}			(4 + 2n)t_{CY} − 100	ns
Data input time from $\overline{RD}$↓	t_{RDD1}			(2 + 2n)t_{CY} − 100	ns
	t_{RDD2}			(2.85 + 2n)t_{CY} − 100	ns
Read data hold time	t_{RDH}		0		ns
$\overline{RD}$ low-level width	t_{RDL1}		(2 + 2n)t_{CY} − 60		ns
	t_{RDL2}		(2.85 + 2n)t_{CY} − 60		ns
$\overline{WAIT}$↓ input time from $\overline{RD}$↓	t_{RDWT1}			0.85 t_{CY} − 50	ns
	t_{RDWT2}			2 t_{CY} − 60	ns
$\overline{WAIT}$↓ input time from $\overline{WR}$↓	t_{WRWT}			2 t_{CY} − 60	ns
$\overline{WAIT}$ low-level width	t_{WTL}		(1.15 + 2n)t_{CY}	(2 + 2n)t_{CY}	ns
Write data setup time	t_{WDS}		(2.85 + 2n)t_{CY} − 100		ns
Write data hold time	t_{WDH}		20		ns
$\overline{WR}$ low-level width	t_{WRL1}		(2.85 + 2n)t_{CY} − 60		ns
$\overline{RD}$↓ delay time from ASTB↓	t_{ASTRD}		25		ns
$\overline{WR}$↓ delay time from ASTB↓	t_{ASTWR}		0.85 t_{CY} + 20		ns
ASTB↑delay time from $\overline{RD}$↑ in external fetch	t_{RDAST}		0.85 t_{CY} − 10	1.15 t_{CY} + 20	ns
Address hold time from $\overline{RD}$↑ in external fetch	t_{RDADH}		0.85 t_{CY} − 50	1.15 t_{CY} + 50	ns
Write data output time from $\overline{RD}$↑	t_{RDWD}		40		ns
Write data output time from $\overline{WR}$↓	t_{WRWD}		0	50	ns
Address hold time from $\overline{WR}$↑	t_{WRADH}		0.85 t_{CY}	1.15 t_{CY} + 40	ns
$\overline{RD}$↑ delay time from $\overline{WAIT}$↑	t_{WTRD}		1.15 t_{CY} + 40	3.15 t_{CY} + 40	ns
$\overline{WR}$↑ delay time from $\overline{WAIT}$↑	t_{WTWR}		1.15 t_{CY} + 30	3.15 t_{CY} + 30	ns

Remarks
1. MCS: Bit 0 of the oscillation mode selection register (OSMS)
2. PCC2 to PCC0: Bit 2 to bit 0 of the processor clock control register (PCC)
3. $t_{CY} = T_{CY}/4$
4. n indicates the number of waits.

(b) Except when MCS = 1, PCC2 to PCC0 = 000B (T_A = −40 to +85 °C, V_{DD} = 2.7 to 6.0 V)

PARAMETER	SYMBOL	TEST CONDITIONS	MIN.	MAX.	UNIT
ASTB high-level width	t_{ASTH}		t_{CY} − 80		ns
Address setup time	t_{ADS}		t_{CY} − 80		ns
Address hold time	t_{ADH}		0.4 t_{CY} − 10		ns
Data input time from address	t_{ADD1}			(3 + 2n)t_{CY} − 160	ns
	t_{ADD2}			(4 + 2n)t_{CY} − 200	ns
Data input time from $\overline{RD}\downarrow$	t_{RDD1}			(1.4 + 2n)t_{CY} − 70	ns
	t_{RDD2}			(2.4 + 2n)t_{CY} − 70	ns
Read data hold time	t_{RDH}		0		ns
$\overline{RD}$ low-level width	t_{RDL1}		(1.4 + 2n)t_{CY} − 20		ns
	t_{RDL2}		(2.4 + 2n)t_{CY} − 20		ns
$\overline{WAIT}\downarrow$ input time from $\overline{RD}\downarrow$	t_{RDWT1}			t_{CY} − 100	ns
	t_{RDWT2}			2 t_{CY} − 100	ns
$\overline{WAIT}\downarrow$ input time from $\overline{WR}\downarrow$	t_{WRWT}			2t_{CY} − 100	ns
$\overline{WAIT}$ low-level width	t_{WTL}		(1 + 2n)t_{CY}	(2 + 2n)t_{CY}	ns
Write data setup time	t_{WDS}		(2.4 + 2n)t_{CY} − 60		ns
Write data hold time	t_{WDH}		20		ns
$\overline{WR}$ low-level width	t_{WRL1}		(2.4 + 2n)t_{CY} − 20		ns
$\overline{RD}\downarrow$ delay time from ASTB↓	t_{ASTRD}		0.4 t_{CY} − 30		ns
$\overline{WR}\downarrow$ delay time from ASTB↓	t_{ASTWR}		1.4 t_{CY} − 30		ns
ASTB↑delay time from $\overline{RD}\uparrow$ in external fetch	t_{RDAST}		t_{CY} − 10	t_{CY} + 20	ns
Address hold time from $\overline{RD}\uparrow$ in external fetch	t_{RDADH}		t_{CY} − 50	t_{CY} + 50	ns
Write data output time from $\overline{RD}\uparrow$	t_{RDWD}		0.4t_{CY} − 20		ns
Write data output time from $\overline{WR}\downarrow$	t_{WRWD}		0	60	ns
Address hold time from $\overline{WR}\uparrow$	t_{WRADH}		t_{CY}	t_{CY} + 60	ns
$\overline{RD}\uparrow$ delay time from $\overline{WAIT}\uparrow$	t_{WTRD}		0.6 t_{CY} + 180	2.6 t_{CY} + 180	ns
$\overline{WR}\uparrow$ delay time from $\overline{WAIT}\uparrow$	t_{WTWR}		0.6 t_{CY} + 120	2.6 t_{CY} + 120	ns

Remarks
1. MCS: Bit 0 of the oscillation mode selection register (OSMS)
2. PCC2 to PCC0: Bit 2 to bit 0 of the processor clock control register (PCC)
3. $t_{CY} = T_{CY}/4$
4. n indicates the number of waits.

(3) Serial Interface (T_A = −40 to +85 °C, V_{DD} = 2.7 to 6.0 V)

(a) Serial interface channel 0

(i) 3-wire serial I/O mode ($\overline{SCK0}$ ... internal clock output)

PARAMETER	SYMBOL	TEST CONDITIONS	MIN.	TYP.	MAX.	UNIT
$\overline{SCK0}$ cycle time	t_{KCY1}	V_{DD} = 4.5 to 6.0 V	800			ns
			1600			ns
$\overline{SCK0}$ high-/low-level width	t_{KH1},	V_{DD} = 4.5 to 6.0 V	$t_{KCY1}/2 - 50$			ns
	t_{KL1}		$t_{KCY1}/2 - 100$			ns
SI0 setup time (to $\overline{SCK0}$↑)	t_{SIK1}	V_{DD} = 4.5 to 6.0 V	100			ns
			150			ns
SI0 hold time (from $\overline{SCK0}$↑)	t_{KSI1}		400			ns
SO0 output delay time from $\overline{SCK0}$↓	t_{KSO1}	C = 100 pF[Note]			300	ns

Note C is the $\overline{SCK0}$ and SO0 output line load capacitance.

(ii) 3-wire serial I/O mode ($\overline{SCK0}$ ... external clock input)

PARAMETER	SYMBOL	TEST CONDITIONS	MIN.	TYP.	MAX.	UNIT
$\overline{SCK0}$ cycle time	t_{KCY2}	V_{DD} = 4.5 to 6.0 V	800			ns
			1600			ns
$\overline{SCK0}$ high-/low-level width	t_{KH2},	V_{DD} = 4.5 to 6.0 V	400			ns
	t_{KL2}		800			ns
SI0 setup time (to $\overline{SCK0}$↑)	t_{SIK2}		100			ns
SI0 hold time (from $\overline{SCK0}$↑)	t_{KSI2}		400			ns
SO0 output delay time from $\overline{SCK0}$↓	t_{KSO2}	C = 100 pF[Note]			300	ns
$\overline{SCK0}$ rise, fall time	t_{R2}, t_{F2}	When using external device expansion function			160	ns
		When not using external device expansion function			1000	ns

Note C is the SO0 output line load capacitance.

(iii) SBI mode ($\overline{SCK0}$ ... internal clock output)

PARAMETER	SYMBOL	TEST CONDITIONS		MIN.	TYP.	MAX.	UNIT
$\overline{SCK0}$ cycle time	t_{KCY3}	V_{DD} = 4.5 to 6.0 V		800			ns
				3200			ns
$\overline{SCK0}$ high-/low-level width	t_{KH3}, t_{KL3}	V_{DD} = 4.5 to 6.0 V		$t_{KCY3}/2 - 50$			ns
				$t_{KCY3}/2 - 100$			ns
SB0, SB1 setup time (to $\overline{SCK0}$↑)	t_{SIK3}	V_{DD} = 4.5 to 6.0 V		100			ns
				300			ns
SB0, SB1 hold time (from $\overline{SCK0}$↑)	t_{KSI3}			$t_{KCY3}/2$			ns
SB0, SB1 output delay time from $\overline{SCK0}$↓	t_{KSO3}	R = 1 kΩ,	V_{DD} = 4.5 to 6.0 V	0		250	ns
		C = 100 pF[Note]		0		1000	ns
SB0, SB1↓ from $\overline{SCK0}$↑	t_{KSB}			t_{KCY3}			ns
$\overline{SCK0}$↓ from SB0, SB1↓	t_{SBK}			t_{KCY3}			ns
SB0, SB1 high-level width	t_{SBH}			t_{KCY3}			ns
SB0, SB1 low-level width	t_{SBL}			t_{KCY3}			ns

Note R and C are the $\overline{SCK0}$, SB0, and SB1 output line load resistance and load capacitance.

(iv) SBI mode ($\overline{SCK0}$ ... external clock input)

PARAMETER	SYMBOL	TEST CONDITIONS		MIN.	TYP.	MAX.	UNIT
$\overline{SCK0}$ cycle time	t_{KCY4}	V_{DD} = 4.5 to 6.0 V		800			ns
				3200			ns
$\overline{SCK0}$ high-/low-level width	t_{KH4}, t_{KL4}	V_{DD} = 4.5 to 6.0 V		400			ns
				1600			ns
SB0, SB1 setup time (to $\overline{SCK0}$↑)	t_{SIK4}	V_{DD} = 4.5 to 6.0 V		100			ns
				300			ns
SB0, SB1 hold time (from $\overline{SCK0}$↑)	t_{KSI4}			$t_{KCY4}/2$			ns
SB0, SB1 output delay time from $\overline{SCK0}$↓	t_{KSO4}	R = 1 kΩ,	V_{DD} = 4.5 to 6.0 V	0		300	ns
		C = 100 pF[Note]		0		1000	ns
SB0, SB1↓ from $\overline{SCK0}$↑	t_{KSB}			t_{KCY4}			ns
$\overline{SCK0}$↓ from SB0, SB1↓	t_{SBK}			t_{KCY4}			ns
SB0, SB1 high-level width	t_{SBH}			t_{KCY4}			ns
SB0, SB1 low-level width	t_{SBL}			t_{KCY4}			ns
$\overline{SCK0}$ rise, fall time	t_{R4}, t_{F4}	When using external device expansion function				160	ns
		When not using external device expansion function				1000	ns

Note R and C are the SB0 and SB1 output line load resistance and load capacitance.

(v) 2-wire serial I/O mode ($\overline{SCK0}$ ... internal clock output)

PARAMETER	SYMBOL	TEST CONDITIONS		MIN.	TYP.	MAX.	UNIT
$\overline{SCK0}$ cycle time	t_{KCY5}	R = 1 kΩ, C = 100 pF[Note]		1600			ns
$\overline{SCK0}$ high-level width	t_{KH5}			$t_{KCY5}/2 - 160$			ns
$\overline{SCK0}$ low-level width	t_{KL5}		V_{DD} = 4.5 to 6.0 V	$t_{KCY5}/2 - 50$			ns
				$t_{KCY5}/2 - 100$			ns
SB0, SB1 setup time (to $\overline{SCK0}$↑)	t_{SIK5}		V_{DD} = 4.5 to 6.0 V	300			ns
				350			ns
SB0, SB1 hold time (from $\overline{SCK0}$↑)	t_{KSI5}			600			ns
SB0, SB1 output delay time from $\overline{SCK0}$↓	t_{KSO5}			0		300	ns

Note R and C are the $\overline{SCK0}$, SB0, and SB1 output line load resistance and load capacitance.

(vi) 2-wire serial I/O mode ($\overline{SCK0}$ ... external clock input)

PARAMETER	SYMBOL	TEST CONDITIONS		MIN.	TYP.	MAX.	UNIT
$\overline{SCK0}$ cycle time	t_{KCY6}			1600			ns
$\overline{SCK0}$ high-level width	t_{KH6}			650			ns
$\overline{SCK0}$ low-level width	t_{KL6}			800			ns
SB0, SB1 setup time (to $\overline{SCK0}$↑)	t_{SIK6}			100			ns
SB0, SB1 hold time (from $\overline{SCK0}$↑)	t_{KSI6}			$t_{KCY6}/2$			ns
SB0, SB1 output delay time from $\overline{SCK0}$↓	t_{KSO6}	R = 1 kΩ, C = 100 pF[Note]	V_{DD} = 4.5 to 6.0 V	0		300	ns
				0		500	ns
$\overline{SCK0}$ rise, fall time	t_{R6}, t_{F6}	When using external device expansion function				160	ns
		When not using external device expansion function				1000	ns

Note R and C are the SB0 and SB1 output line load resistance and load capacitance.

(b) Serial interface channel 1

(i) 3-wire serial I/O mode ($\overline{SCK1}$...internal clock output)

PARAMETER	SYMBOL	TEST CONDITIONS	MIN.	TYP.	MAX.	UNIT
$\overline{SCK1}$ cycle time	t_{KCY7}	V_{DD} = 4.5 to 6.0 V	800			ns
			1600			ns
$\overline{SCK1}$ high-/low-level width	t_{KH7},	V_{DD} = 4.5 to 6.0 V	$t_{KCY7}/2 - 50$			ns
	t_{KL7}		$t_{KCY7}/2 - 100$			ns
SI1 setup time (to $\overline{SCK1}$↑)	t_{SIK7}	V_{DD} = 4.5 to 6.0 V	100			ns
			150			ns
SI1 hold time (to $\overline{SCK1}$ ↑)	t_{KSI7}		400			ns
SO1 output delay time from $\overline{SCK1}$↓	t_{KSO7}	C = 100 pF[Note]			300	ns

Note C is the $\overline{SCK1}$ and SO1 output line load capacitance.

(ii) 3-wire serial I/O mode ($\overline{SCK1}$...external clock output)

PARAMETER	SYMBOL	TEST CONDITIONS	MIN.	TYP.	MAX.	UNIT
$\overline{SCK1}$ cycle time	t_{KCY8}	V_{DD} = 4.5 to 6.0 V	800			ns
			1600			ns
$\overline{SCK1}$ high-/low-level width	t_{KH8},	V_{DD} = 4.5 to 6.0 V	400			ns
	t_{KL8}		800			ns
SI1 setup time (to $\overline{SCK1}$ ↑)	t_{SIK8}		100			ns
SI1 hold time (to $\overline{SCK1}$ ↑)	t_{KSI8}		400			ns
SO1 output delay time from $\overline{SCK1}$	t_{KSO8}	C = 100 pF[Note]			300	ns
$\overline{SCK1}$ rise, fall time	t_{R8}, t_{F8}	When using external device expansion function			160	ns
		When not using external device expansion function			1000	ns

Note C is the SO1 output line load capacitance.

(iii) Automatic transmission/reception function 3-wire serial I/O mode ($\overline{SCK1}$ ... internal clock output)

PARAMETER	SYMBOL	TEST CONDITIONS	MIN.	TYP.	MAX.	UNIT
$\overline{SCK1}$ cycle time	t_{KCY9}	V_{DD} = 4.5 to 6.0 V	800			ns
			1600			ns
$\overline{SCK1}$ high-/low-level width	t_{KH9}, t_{KL9}	V_{DD} = 4.5 to 6.0 V	$t_{KCY9}/2 - 50$			ns
			$t_{KCY9}/2 - 100$			ns
SI1 setup time (to $\overline{SCK1}$↑)	t_{SIK9}	V_{DD} = 4.5 to 6.0 V	100			ns
			150			ns
SI1 hold time (from $\overline{SCK1}$↑)	t_{KSI9}		400			ns
SO1 output delay time from $\overline{SCK1}$↓	t_{KSO9}	C = 100 pF[Note]			300	ns
STB↑ from $\overline{SCK1}$↑	t_{SBD}		$t_{KCY9}/2 - 100$		$t_{KCY9}/2 + 100$	ns
Strobe signal high-level width	t_{SBW}		$t_{KCY9} - 30$		$t_{KCY9} + 30$	ns
Busy signal setup time (to busy signal detection timing)	t_{BYS}		100			ns
Busy signal hold time (from busy signal detection timing)	t_{BYH}	V_{DD} = 4.5 to 6.0 V	100			ns
			150			ns
$\overline{SCK1}$↓ from busy inactivation	t_{SPS}				$2t_{KCY9}$	ns

Note C is the $\overline{SCK1}$ and SO1 output line load capacitance.

(iv) Automatic transmission/reception function 3-wire serial I/O mode ($\overline{SCK1}$ ... external clock input)

PARAMETER	SYMBOL	TEST CONDITIONS	MIN.	TYP.	MAX.	UNIT
$\overline{SCK1}$ cycle time	t_{KCY10}	V_{DD} = 4.5 to 6.0 V	800			ns
			1600			ns
$\overline{SCK1}$ high-/low-level width	t_{KH10}, t_{KL10}	V_{DD} = 4.5 to 6.0 V	400			ns
			800			ns
SI1 setup time (to $\overline{SCK1}$↑)	t_{SIK10}		100			ns
SI1 hold time (from $\overline{SCK1}$↑)	t_{KSI10}		400			ns
SO output delay time from $\overline{SCK1}$↓	t_{KSO10}	C = 100 pF[Note]			300	ns
$\overline{SCK1}$ rise, fall time	t_{R10}, t_{F10}	When using external device expansion function			160	ns
		When not using external device expansion function			1000	ns

Note C is the SO1 output line load capacitance.

(c) Serial interface channel 2

(i) 3-wire serial I/O mode ($\overline{SCK2}$...internal clock output)

PARAMETER	SYMBOL	TEST CONDITIONS	MIN.	TYP.	MAX.	UNIT
$\overline{SCK2}$ cycle time	t_{KCY11}	V_{DD} = 4.5 to 6.0 V	800			ns
			1600			ns
$\overline{SCK2}$ high-/low-level width	t_{KH11}, t_{KL11}	V_{DD} = 4.5 to 6.0 V	$t_{KCY11}/2 - 50$			ns
			$t_{KCY11}/2 - 100$			ns
SI2 setup time (to $\overline{SCK2}$↑)	t_{SIK11}	V_{DD} = 4.5 to 6.0 V	100			ns
			150			ns
SI2 hold time (to $\overline{SCK2}$↑)	t_{KSI11}		400			ns
SO2 output delay time from $\overline{SCK2}$↓	t_{KSO11}	C = 100 pF[Note]			300	ns

Note C is the load capacitance of $\overline{SCK2}$ and SO2 output lines.

(ii) 3-wire serial I/O mode ($\overline{SCK2}$...external clock output)

PARAMETER	SYMBOL	TEST CONDITIONS	MIN.	TYP.	MAX.	UNIT
$\overline{SCK2}$ cycle time	t_{KCY12}	V_{DD} = 4.5 to 6.0 V	800			ns
			1600			ns
$\overline{SCK2}$ high-/low-level width	t_{KH12}, t_{KL12}	V_{DD} = 4.5 to 6.0 V	400			ns
			800			ns
SI2 setup time (to $\overline{SCK2}$ ↑)	t_{SIK12}		100			ns
SI2 hold time (to $\overline{SCK2}$ ↑)	t_{KSI12}		400			ns
SO2 output delay time from $\overline{SCK2}$↓	t_{KSO12}	C = 100 pF[Note]			300	ns
$\overline{SCK2}$ rise, fall time	t_{R12}, t_{F12}	V_{DD} = 4.5 to 6.0 V, when not using external device expansion function			1000	ns
					160	ns

Note C is the SO2 output line load capacitance.

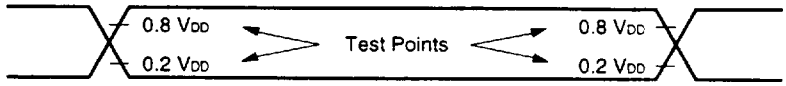
(iii) UART mode (Dedicated baud rate generator output)

PARAMETER	SYMBOL	TEST CONDITIONS	MIN.	TYP.	MAX.	UNIT
Transfer rate		V_{DD} = 4.5 to 6.0 V			78125	bps
					39063	bps

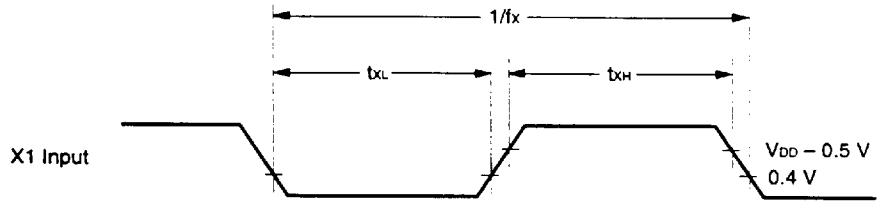
(iv) UART mode (External clock input)

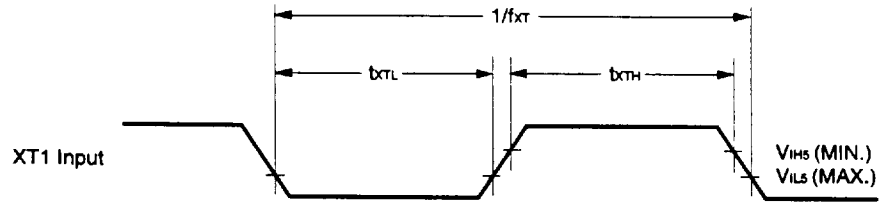
PARAMETER	SYMBOL	TEST CONDITIONS	MIN.	TYP.	MAX.	UNIT
ASCK cycle time	t_{KCY13}	V_{DD} = 4.5 to 6.0 V	800			ns
			1600			ns
ASCK high-/low-level width	t_{KH13}, t_{KL13}	V_{DD} = 4.5 to 6.0 V	400			ns
			800			ns
Transfer rate		V_{DD} = 4.5 to 6.0 V			39063	bps
					19531	bps
$\overline{SCK}$ rise, fall time	t_{R13}, t_{F13}	V_{DD} = 4.5 to 6.0 V, when not using external device expansion function			1000	ns
					160	ns

AC Timing Test Point (Excluding X1, XT1 Input)

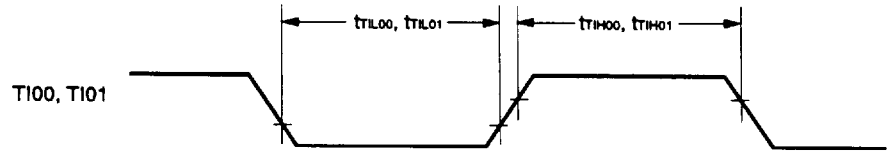


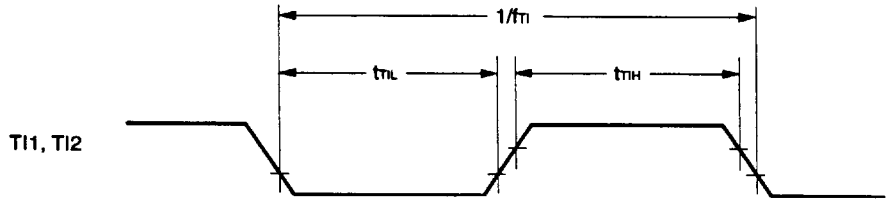
Clock Timing





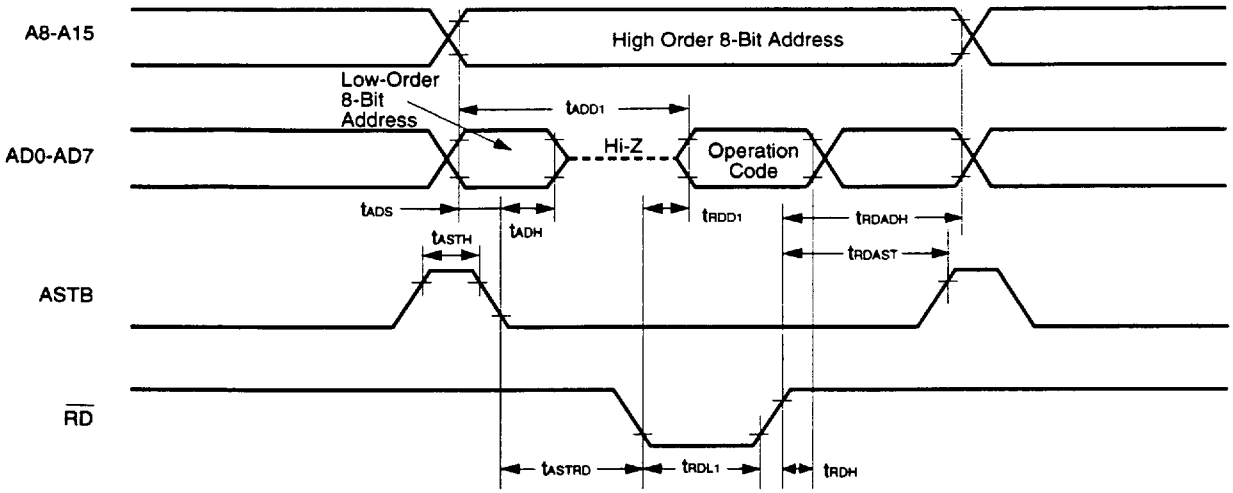
TI Timing



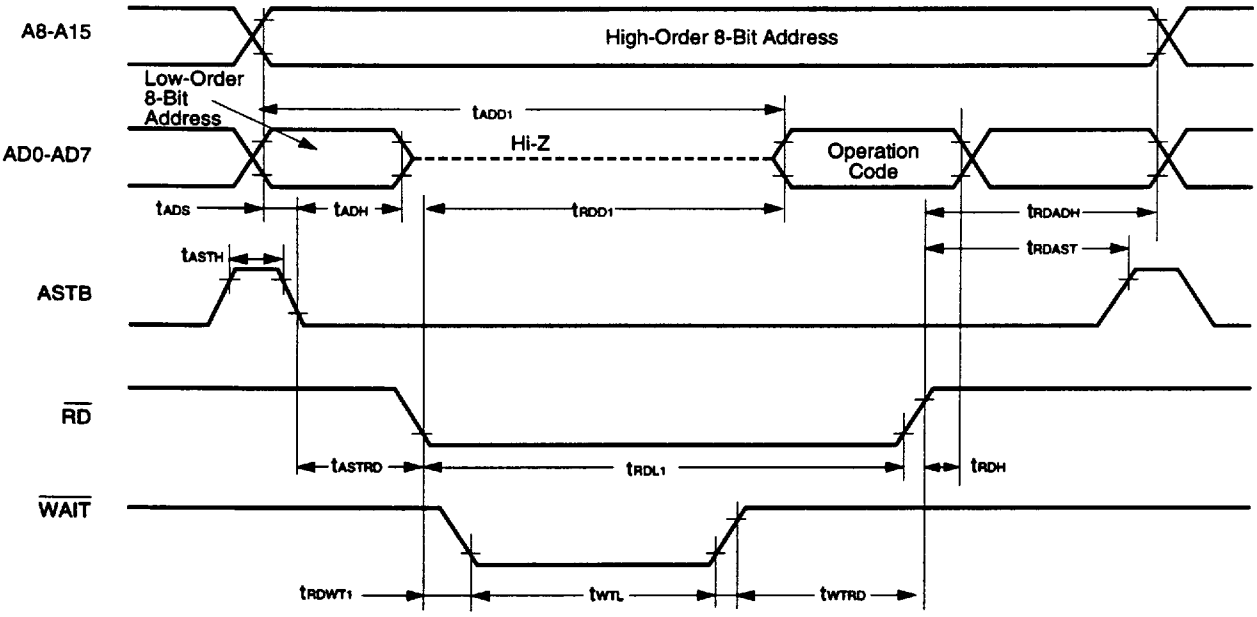


Read/Write Operations

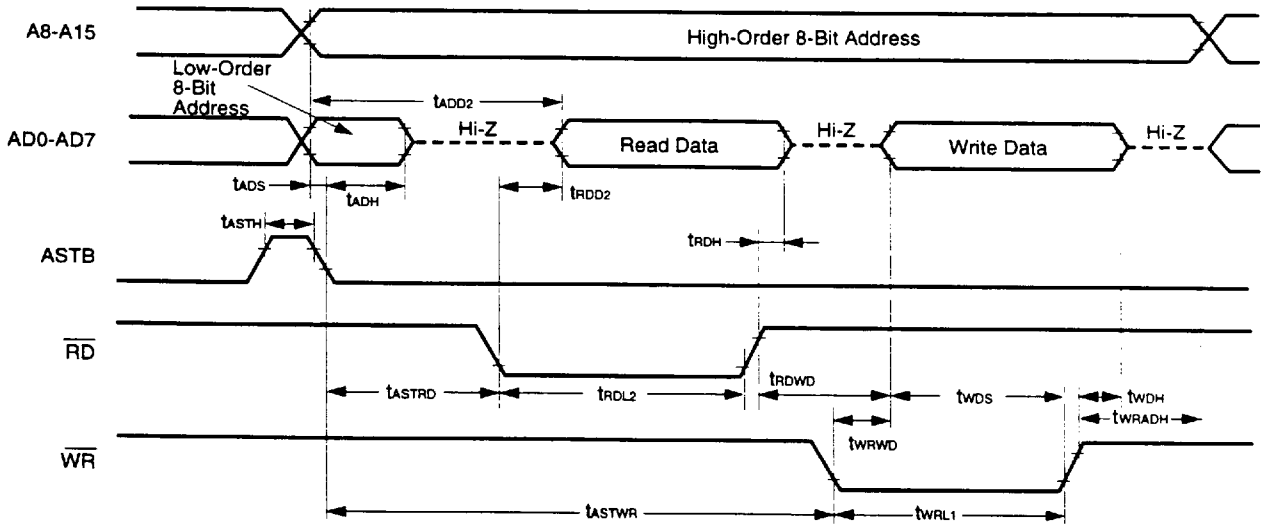
External fetch (no wait):



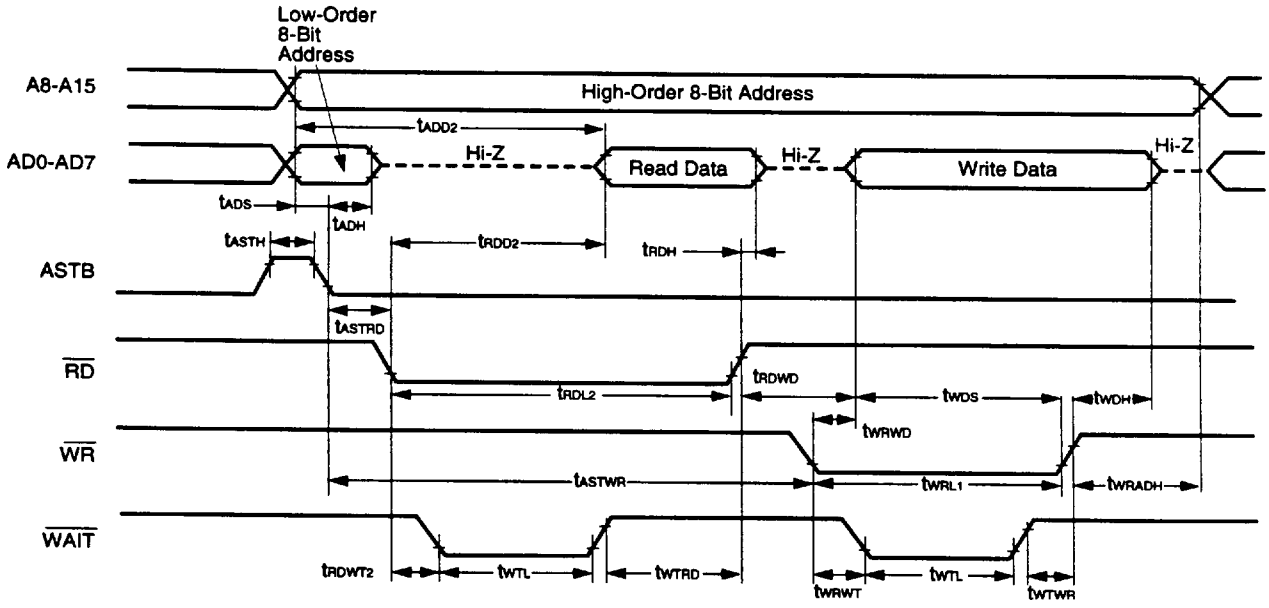
External fetch (wait insertion):



External data access (no wait):

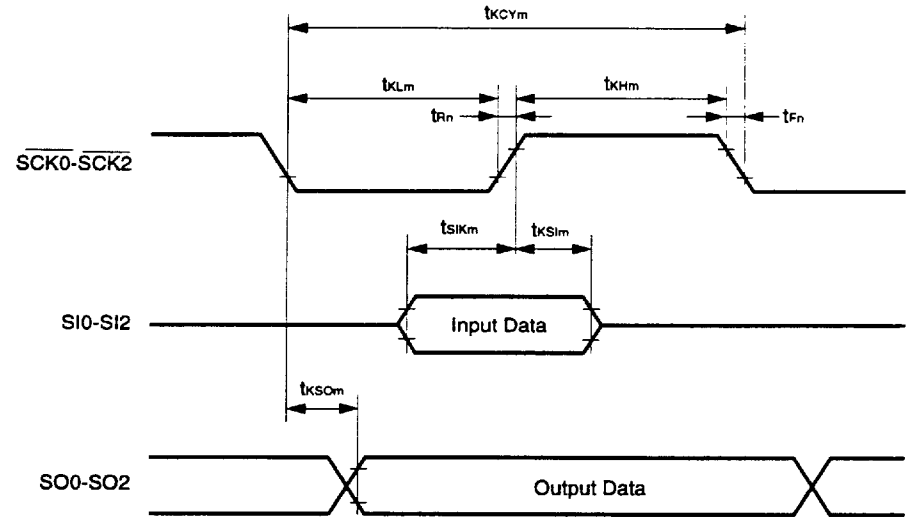


External data access (wait insertion):



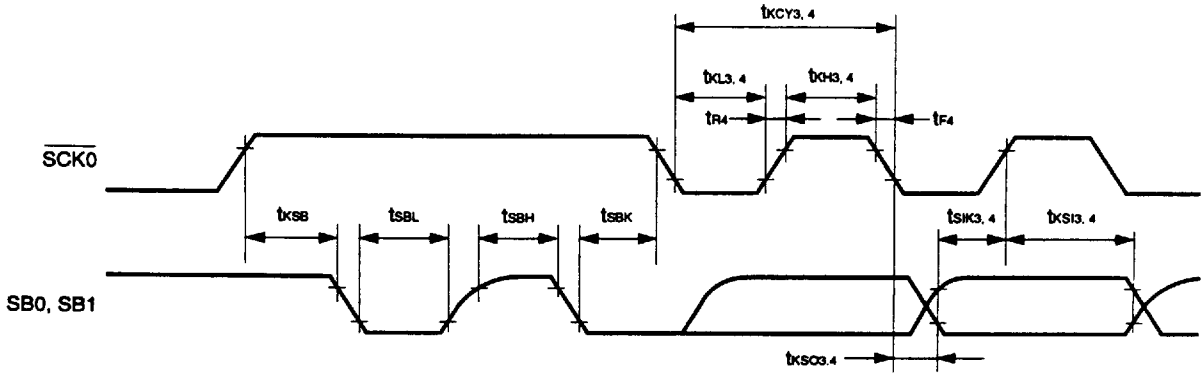
Serial Transfer Timing

3-wire serial I/O mode:

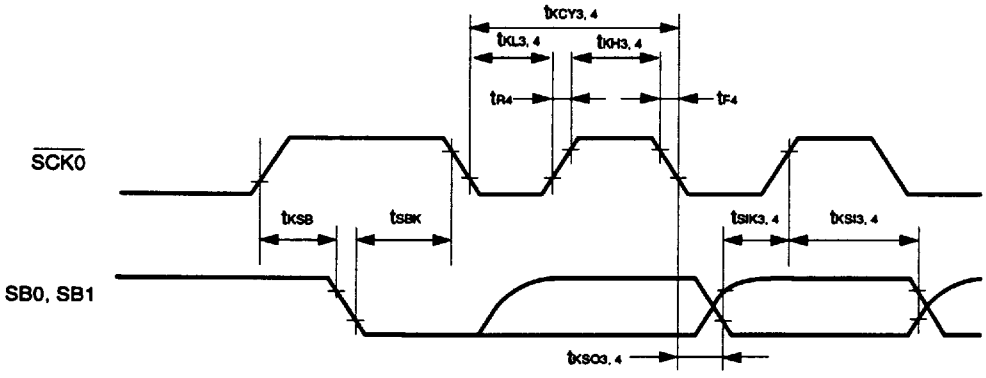


Remark m = 1, 2, 7, 8, 11 or 12
n = 2, 8, or 12

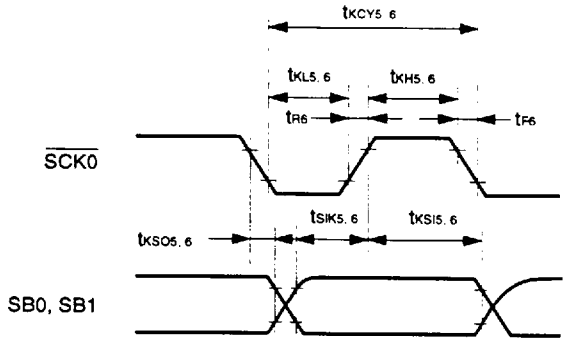
SBI mode (bus release signal transfer):



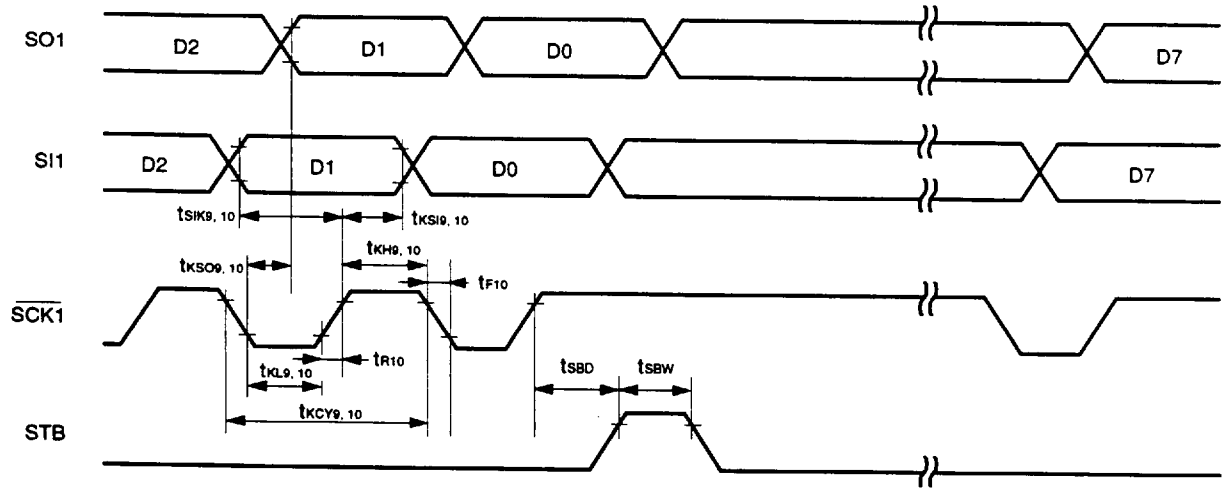
SBI mode (command signal transfer):



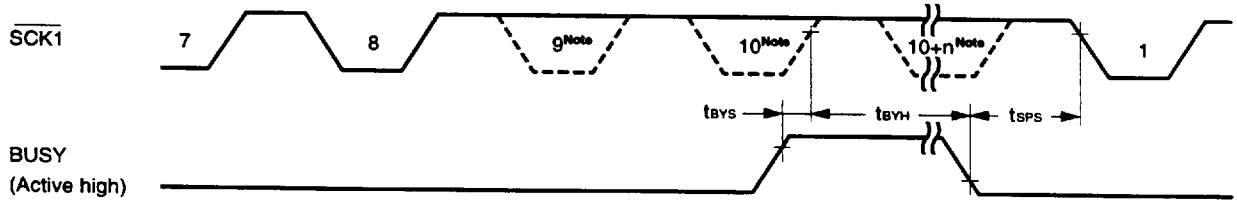
2-wire serial I/O mode:



Automatic transmission/reception function 3-wire serial I/O mode:

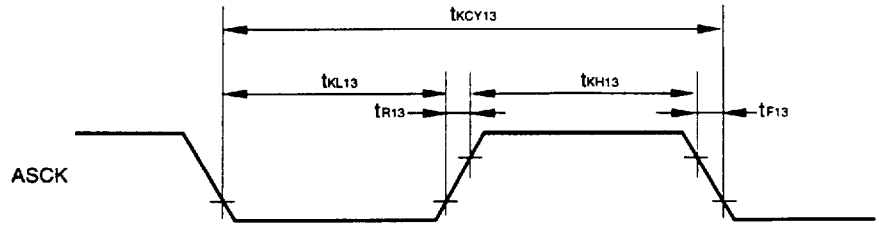


Automatic transmission/reception function 3-wire serial I/O mode (busy processing):



Note The signal is not actually low here, but is represented in this way to show the timing.

UART mode (external Clock Input):



A/D Converter Characteristics (T_A = −40 to +85 °C, AV_{DD} = V_{DD} = 2.7 to 6.0 V, AV_{SS} = V_{SS} = 0 V)

PARAMETER	SYMBOL	TEST CONDITIONS	MIN.	TYP.	MAX.	UNIT
Resolution			8	8	8	bit
Total error[Note]		2.7 V ≤ AV_{REF0} ≤ AV_{DD}			1.4	%
Conversion time	t_{CONV}		19.1		200	μs
Sampling time	t_{SAMP}		12/fxx			μs
Analog input voltage	V_{IAN}		AVss		AV_{REF0}	V
Reference voltage	AV_{REF0}		2.7		AV_{DD}	V
AV_{REF0}-AVss resistance	R_{AIREF0}		4	14		kΩ

Note Excluding quantization error (±1/2 LSB). Shown as a percentage of the full scale value.

Caution For pins which also function as port pins, do not perform the following operations during A/D conversion. If these operations are performed, the total error ratings cannot be kept (except for LCD segment output alternate-function pin).

<1> Rewrite the output latch while the pin is used as a port pin.

<2> Change the output level of the pin used as an output pin, even if it is not used as a port pin.

Remarks 1. fxx : Main system clock frequency (fx or fx/2)

2. fx : Main system clock oscillatior frequency

D/A Converter Characteristics (T_A = −40 to +85 °C, V_{DD} = 2.7 to 6.0 V, AV_{SS} = V_{SS} = 0 V)

PARAMETER	SYMBOL	TEST CONDITIONS		MIN.	TYP.	MAX.	UNIT
Resolution						8	bit
Total error		R = 2 MΩ[Note 1]				1.2	%
		R = 4 MΩ[Note 1]				0.8	%
		R = 10 MΩ[Note 1]				0.6	%
Settling time		C = 30 pF[Note 1]	4.5 V ≤ AV_{REF1} ≤ 6.0 V			10	μs
			2.7 V ≤ AV_{REF1} < 4.5 V			15	μs
Output resistor	R_O	Note 2			10		kΩ
Analog reference voltage	AV_{REF1}			2.0		V_{DD}	V
Resistance between AV_{REF1} and AVss	R_{AIREF1}	DACS0, DACS1 = 55H[Note 2]		4	8		mA

Notes 1. R and C are the D/A converter output pin load resistance and load capacitance.

2. Value for one D/A converter channel.

Remark DACS0, DACS1 : D/A conversion value setting register 0, 1

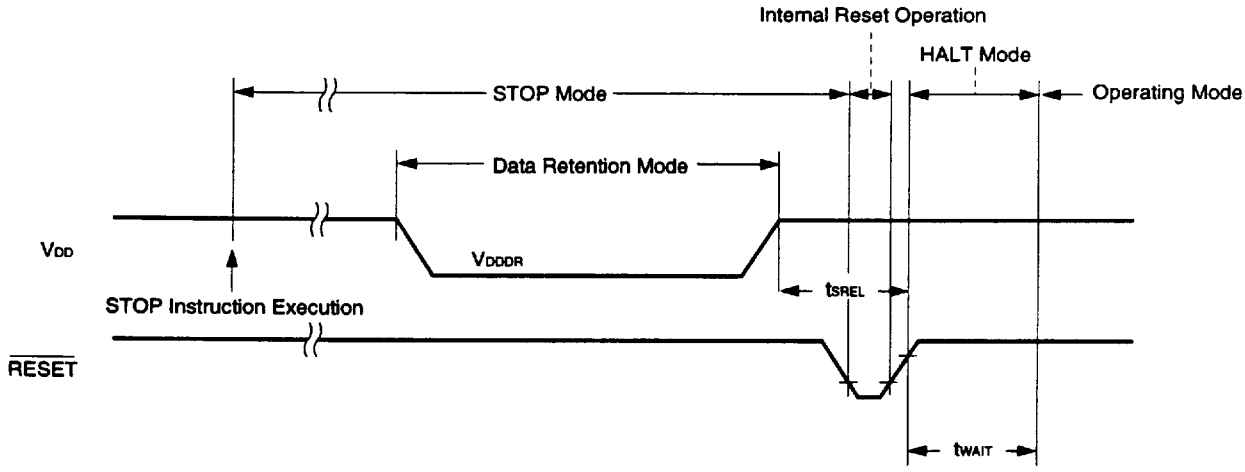
Data Memory STOP Mode Low Supply Voltage Data Retention Characteristics (T_A = –40 to +85 °C)

PARAMETER	SYMBOL	TEST CONDITIONS	MIN.	TYP.	MAX.	UNIT
Data retention supply voltage	V_{DDDR}		1.8		6.0	V
Data retention supply current	I_{DDDR}	V_{DDDR} = 1.8 V Subsystem clock stopped, feedback resister disconnected		0.1	10	μA
Release signal setup time	t_{SREL}		0			μs
Oscillation stabilization wait time	t_{WAIT}	Release by $\overline{RESET}$		$2^{17}/f_x$		ms
		Release by interrupt		**Note**		ms

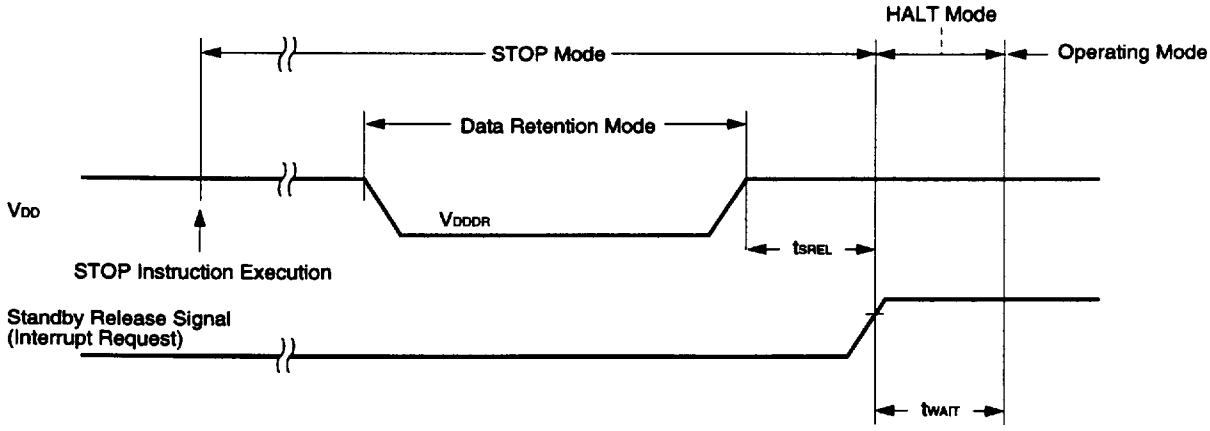
Note 2^{12}/fxx, or 2^{14}/fxx through 2^{17}fxx can be selected by bits 0 to 2 (OSTS0 to OSTS2) of the oscillation stabilization time selection register (OSTS).

Remark fxx : Main system clock frequency (fx or fx/2)
fx : Main system clock oscillatior frequency

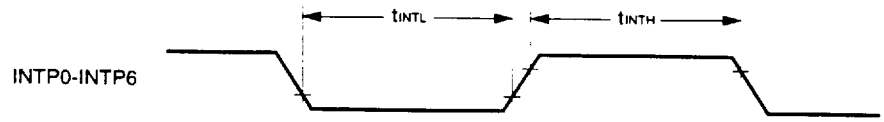
Data Retention Timing (STOP mode release by $\overline{RESET}$)



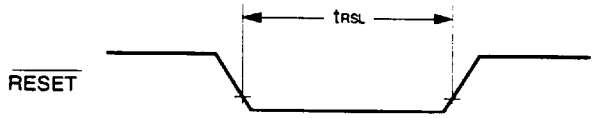
Data Retention Timing (STOP mode release by standby release signal: interrupt signal)



Interrupt Input Timing



$\overline{\text{RESET}}$ Input Timing



PROM PROGRAMMING CHARACTERISTICS

DC Characteristics

(1) PROM Write Mode (T_A = 25 ± 5 °C, V_{DD} = 6.5 ± 0.25 V, V_{PP} = 12.5 ± 0.3 V)

PARAMETER	SYMBOL	SYMBOL[Note]	TEST CONDITIONS	MIN.	TYP.	MAX.	UNIT
Input voltage, high	V_{IH}	V_{IH}		0.7 V_{DD}		V_{DD}	V
Input voltage, low	V_{IL}	V_{IL}		0		0.3 V_{DD}	V
Output voltage, high	V_{OH}	V_{OH}	I_{OH} = −1 mA	V_{DD} − 1.0			V
Output voltage, low	V_{OL}	V_{OL}	I_{OL} = 1.6 mA			0.4	V
Input leakage current	I_{LI}	I_{LI}	0 ≤ V_{IN} ≤ V_{DD}	−10		+10	μA
V_{PP} supply voltage	V_{PP}	V_{PP}		12.2	12.5	12.8	V
V_{DD} supply voltage	V_{DD}	V_{CC}		6.25	6.5	6.75	V
V_{PP} supply current	I_{PP}	I_{PP}	$\overline{PGM}$ = V_{IL}			50	mA
V_{DD} supply current	I_{DD}	I_{CC}				50	mA

(2) PROM Read Mode (T_A = 25 ± 5 °C, V_{DD} = 5.0 ± 0.5 V, V_{PP} = V_{DD} ± 0.6 V)

PARAMETER	SYMBOL	SYMBOL[Note]	TEST CONDITIONS	MIN.	TYP.	MAX.	UNIT
Input voltage, high	V_{IH}	V_{IH}		0.7 V_{DD}		V_{DD}	V
Input voltage, low	V_{IL}	V_{IL}		0		0.3 V_{DD}	V
Output voltage, high	V_{OH1}	V_{OH1}	I_{OH} = −1 mA	V_{DD} − 1.0			V
	V_{OH2}	V_{OH2}	I_{OH} = −100 μA	V_{DD} − 0.5			V
Output voltage, low	V_{OL}	V_{OL}	I_{OL} = 1.6 mA			0.4	V
Input leakage current	I_{LI}	I_{LI}	0 ≤ V_{IN} ≤ V_{DD}	−10		+10	μA
Output leakage current	I_{LO}	I_{LO}	0 ≤ V_{OUT} ≤ V_{DD}, $\overline{OE}$ = V_{IH}	−10		+10	μA
V_{PP} supply voltage	V_{PP}	V_{PP}		V_{DD} − 0.6	V_{DD}	V_{DD} + 0.6	V
V_{DD} supply voltage	V_{DD}	V_{CC}		4.5	5.0	5.5	V
V_{PP} supply current	I_{PP}	I_{PP}	V_{PP} = V_{DD}			100	μA
V_{DD} supply current	I_{DD}	I_{CCA1}	$\overline{CE}$ = V_{IL}, V_{IN} = V_{IH}			50	mA

Note Correspond symbols for the μPD27C1001A.

AC Characteristics

(1) PROM Write Mode

(a) Page program mode (T_A = 25 ± 5 °C, V_{DD} = 6.5 ± 0.25 V, V_{PP} = 12.5 ± 0.3 V)

PARAMETER	SYMBOL	SYMBOL[Note]	TEST CONDITIONS	MIN.	TYP.	MAX.	UNIT
Address setup time (to $\overline{OE}\downarrow$)	t_{AS}	t_{AS}		2			μs
$\overline{OE}$ setup time	t_{OES}	t_{OES}		2			μs
$\overline{CE}$ setup time (to $\overline{OE}\downarrow$)	t_{CES}	t_{CES}		2			μs
Input data setup time (to $\overline{OE}\downarrow$)	t_{DS}	t_{DS}		2			μs
Address hold time (from $\overline{OE}\uparrow$)	t_{AH}	t_{AH}		2			μs
	t_{AHL}	t_{AHL}		2			μs
	t_{AHV}	t_{AHV}		0			μs
Input data hold time (from $\overline{OE}\uparrow$)	t_{DH}	t_{DH}		2			μs
Data output float delay time from $\overline{OE}\uparrow$	t_{DF}	t_{DF}		0		250	ns
V_{PP} setup time (to $\overline{OE}\downarrow$)	t_{VPS}	t_{VPS}		1.0			ms
V_{DD} setup time (to $\overline{OE}\downarrow$)	t_{VDS}	t_{VCS}		1.0			ms
Program pulse width	t_{PW}	t_{PW}		0.095	0.1	0.105	ms
Valid data delay time from $\overline{OE}\downarrow$	t_{OE}	t_{OE}				1	μs
$\overline{OE}$ pulse width during data latching	t_{LW}	t_{LW}		1			μs
$\overline{PGM}$ setup time	t_{PGMS}	t_{PGMS}		2			μs
$\overline{CE}$ hold time	t_{CEH}	t_{CEH}		2			μs
$\overline{OE}$ hold time	t_{OEH}	t_{OEH}		2			μs

(b) Byte program mode (T_A = 25 ± 5 °C, V_{DD} = 6.5 ± 0.25 V, V_{PP} = 12.5 ± 0.3 V)

PARAMETER	SYMBOL	SYMBOL[Note]	TEST CONDITIONS	MIN.	TYP.	MAX.	UNIT
Address setup time (to $\overline{PGM}\downarrow$)	t_{AS}	t_{AS}		2			μs
$\overline{OE}$ setup time	t_{OES}	t_{OES}		2			μs
$\overline{CE}$ setup time (to $\overline{PGM}\downarrow$)	t_{CES}	t_{CES}		2			μs
Input data setup time (to $\overline{PGM}\downarrow$)	t_{DS}	t_{DS}		2			μs
Address hold time (from $\overline{OE}\uparrow$)	t_{AH}	t_{AH}		2			μs
Input data hold time (from $\overline{PGM}\uparrow$)	t_{DH}	t_{DH}		2			μs
Data output float delay time from $\overline{OE}\uparrow$	t_{DF}	t_{DF}		0		250	ns
V_{PP} setup time (to $\overline{PGM}\downarrow$)	t_{VPS}	t_{VPS}		1.0			ms
V_{DD} setup time (to $\overline{PGM}\downarrow$)	t_{VDS}	t_{VCS}		1.0			ms
Program pulse width	t_{PW}	t_{PW}		0.095	0.1	0.105	ms
Valid data delay time from $\overline{OE}\downarrow$	t_{OE}	t_{OE}				1	μs
$\overline{OE}$ hold time	t_{OEH}	—		2			μs

Note Correspond symbols for the μPD27C1001A.

(2) PROM Read Mode (T_A = 25 ± 5 °C, V_{DD} = 5.0 ± 0.5 V, V_{PP} = V_{DD} ± 0.6 V)

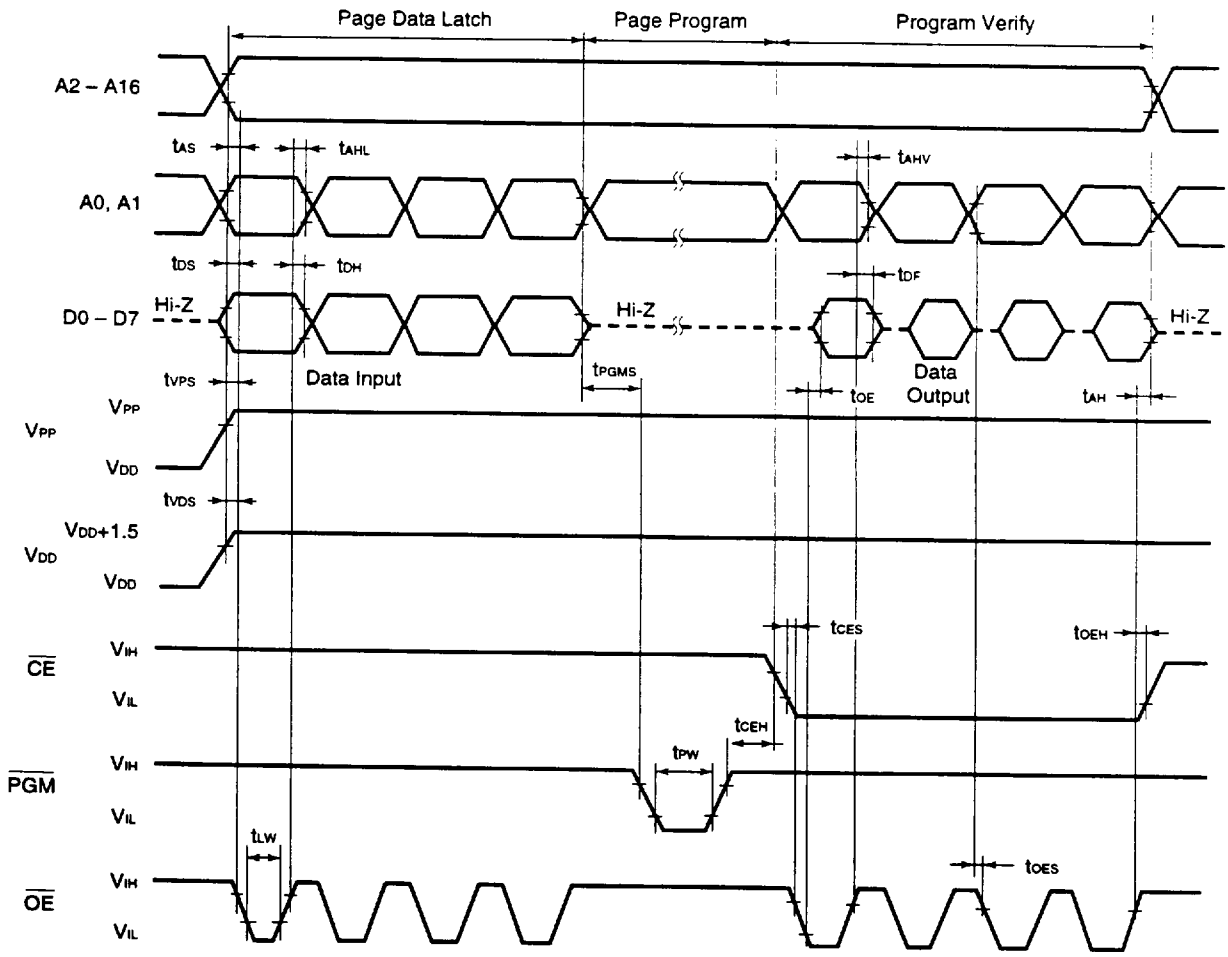
PARAMETER	SYMBOL	SYMBOL[Note]	TEST CONDITIONS	MIN.	TYP.	MAX.	UNIT
Data output delay time from address	t_{ACC}	t_{ACC}	$\overline{CE}$ = $\overline{OE}$ = V_{IL}			800	ns
Data output delay time from $\overline{CE}$↓	t_{CE}	t_{CE}	$\overline{OE}$ = V_{IL}			800	ns
Data output delay time from $\overline{OE}$↓	t_{OE}	t_{OE}	$\overline{CE}$ = V_{IL}			200	ns
Data output float delay time from $\overline{OE}$↑	t_{DF}	t_{DF}	$\overline{CE}$ = V_{IL}	0		60	ns
Data hold time from address	t_{OH}	t_{OH}	$\overline{CE}$ = $\overline{OE}$ = V_{IL}	0			ns

Note Correspond symbols for the μPD27C1001A.

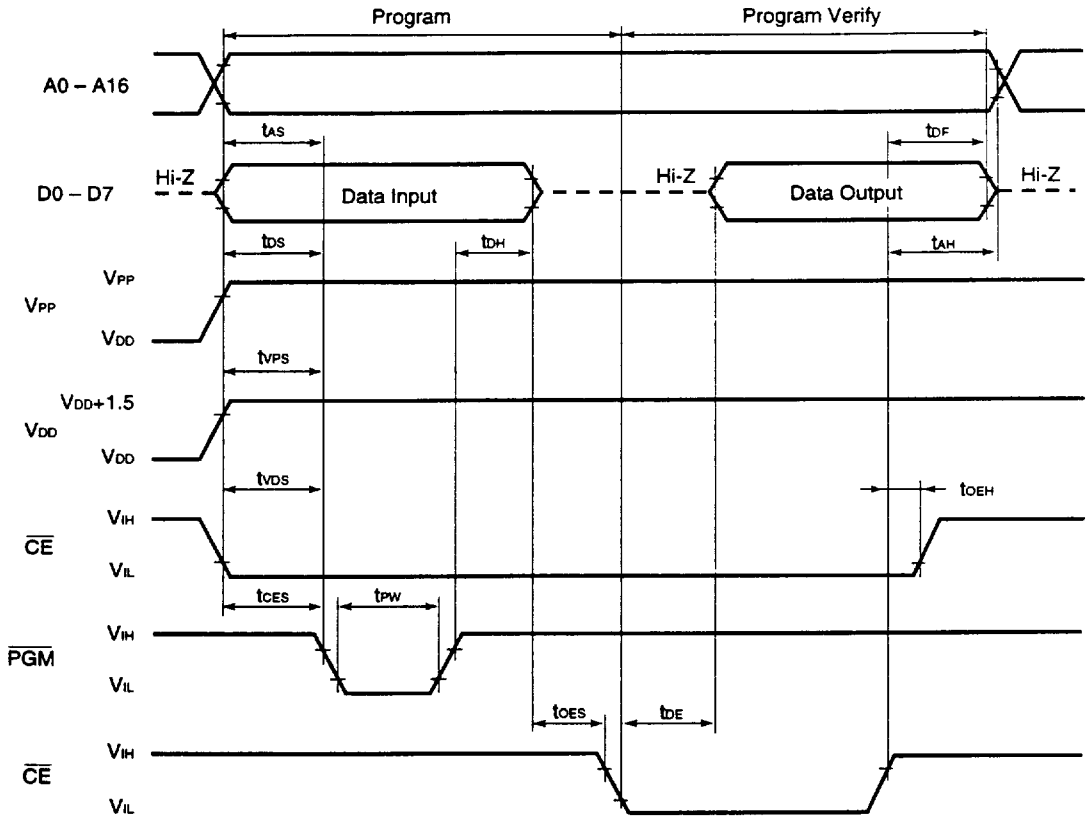
(3) PROM Programming Mode Setting (T_A = 25 °C, V_{SS} = 0 V)

PARAMETER	SYMBOL	TEST CONDITIONS	MIN.	TYP.	MAX.	UNIT
PROM programming mode setup time	t_{SMA}		10			μs

PROM Write Mode Timing (page program mode)



PROM Write Mode Timing (byte program mode)

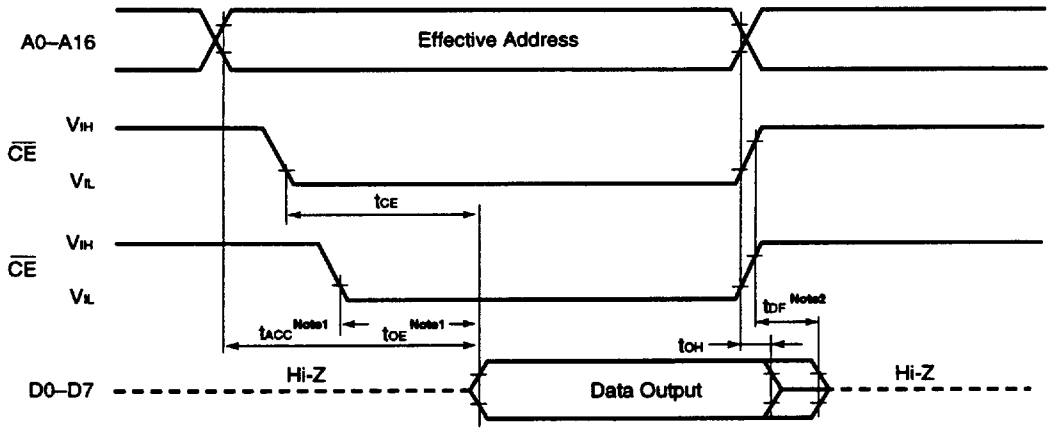


Cautions 1. V_{DD} shonld be applied before V_{PP}, and removed after V_{PP}.

2. V_{PP} shonld not exceed +13.5 V including overshoot.

3. Disconnection during application of ±12.5V to VPP may have an adverse effect on reliability.

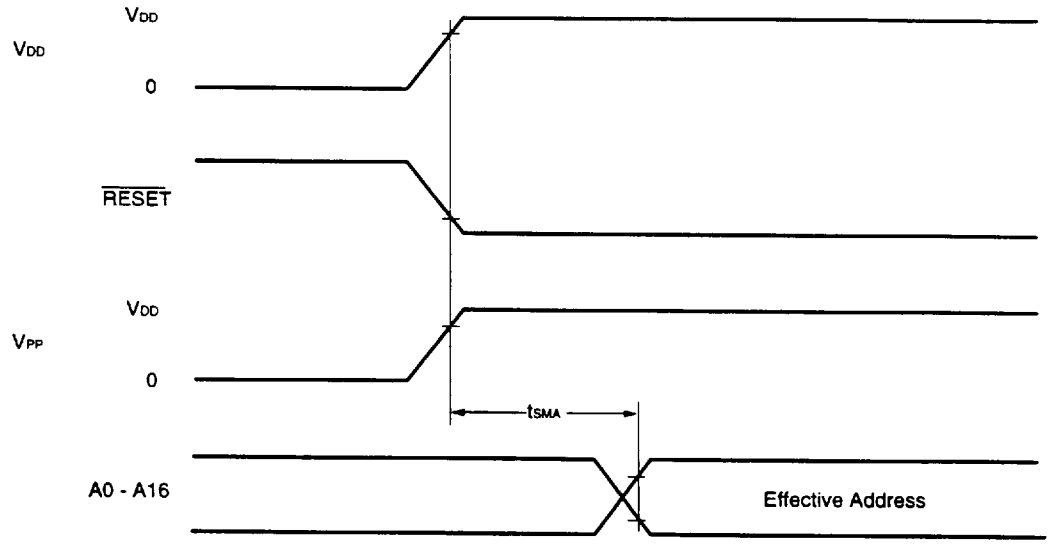
PROM Read Mode Timing



Notes 1. If you want to read within the t_{ACC} range, make the $\overline{OE}$ input delay time from the fall of $\overline{CE}$ a maxmum of $t_{ACC} - t_{OE}$.

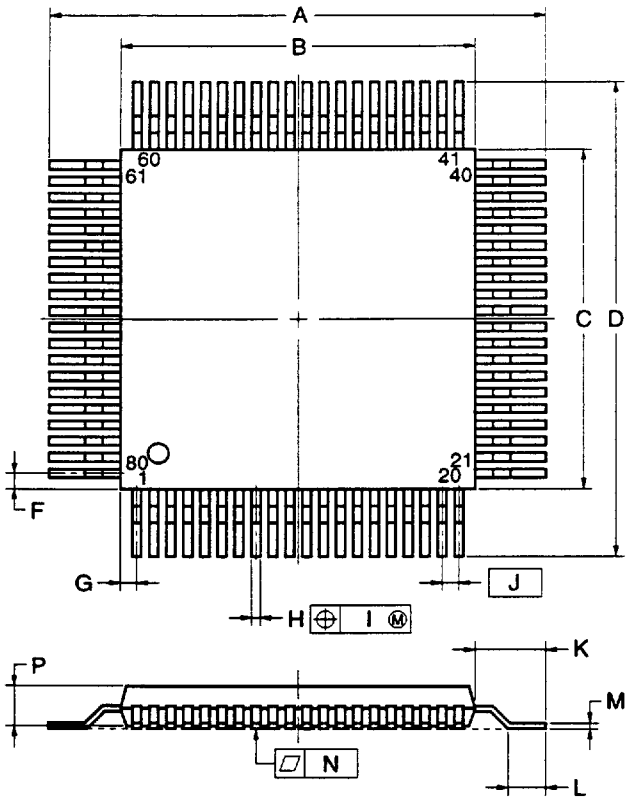
2. t_{DF} is the time from when either $\overline{OE}$ or $\overline{CE}$ first reaches VIH.

PROM Programming Mode Setting Timing

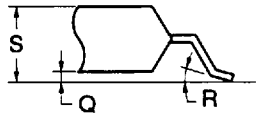


8. PACKAGE DRAWINGS

80 PIN PLASTIC QFP (14×14)



detail of lead end



NOTE

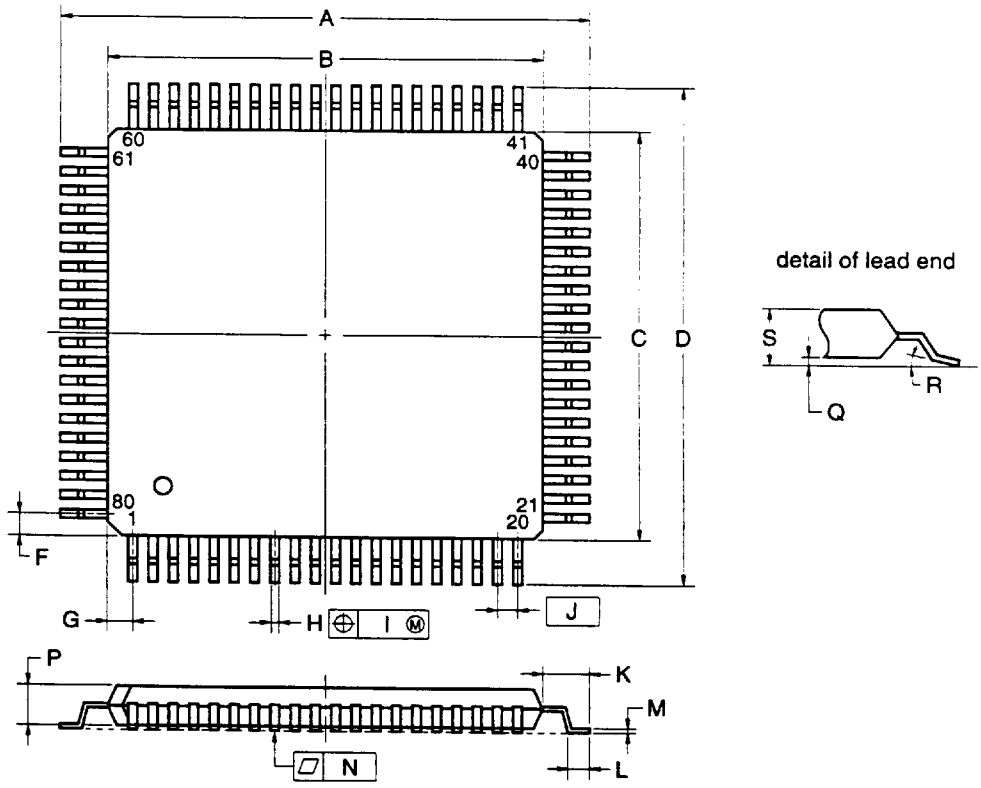
Each lead centerline is located within 0.13 mm (0.005 inch) of its true position (T.P.) at maximum material condition.

ITEM	MILLIMETERS	INCHES
A	17.2±0.4	0.677±0.016
B	14.0±0.2	$0.551^{+0.009}_{-0.008}$
C	14.0±0.2	$0.551^{+0.009}_{-0.008}$
D	17.2±0.4	0.677±0.016
F	0.825	0.032
G	0.825	0.032
H	0.30±0.10	$0.012^{+0.004}_{-0.005}$
I	0.13	0.005
J	0.65 (T.P.)	0.026 (T.P.)
K	1.6±0.2	0.063±0.008
L	0.8±0.2	$0.031^{+0.009}_{-0.008}$
M	$0.15^{+0.10}_{-0.05}$	$0.006^{+0.004}_{-0.003}$
N	0.10	0.004
P	2.7	0.106
Q	0.1±0.1	0.004±0.004
R	5°±5°	5°±5°
S	3.0 MAX.	0.119 MAX.

S80GC-65-3B9-4

Remark Dimensions and materials of ES product are the same as those of mass-production products.

80 PIN PLASTIC QFP (14×14)



NOTE

Each lead centerline is located within 0.13 mm (0.005 inch) of its true position (T.P.) at maximum material condition.

ITEM	MILLIMETERS	INCHES
A	17.20±0.20	0.677±0.008
B	14.00±0.20	$0.551^{+0.009}_{-0.008}$
C	14.00±0.20	$0.551^{+0.009}_{-0.008}$
D	17.20±0.20	0.677±0.008
F	0.825	0.032
G	0.825	0.032
H	0.32±0.06	$0.013^{+0.002}_{-0.003}$
I	0.13	0.005
J	0.65 (T.P.)	0.026 (T.P.)
K	1.60±0.20	0.063±0.008
L	0.80±0.20	$0.031^{+0.009}_{-0.008}$
M	$0.17^{+0.03}_{-0.07}$	$0.007^{+0.001}_{-0.003}$
N	0.10	0.004
P	1.40±0.10	0.055±0.004
Q	0.125±0.075	0.005±0.003
R	$3°^{+7°}_{-3°}$	$3°^{+7°}_{-3°}$
S	1.70 MAX.	0.067 MAX.

P80GC-65-8BT

9. RECOMMENDED SOLDERING CONDITIONS

These products should be soldered and mounted under the conditions recommended below.

For details of recommended soldering conditions, refer to the information document **"Semiconductor Device Mounting Technology Manual (C10535E)"**.

For soldering methods and conditions other than those recommended, please contact your NEC sales representative.

Table 9-1. Surface Mount Type Soldering Conditions

μPD78P058FGC-3B9 : 80-Pin Plastic QFP (14 × 14 mm, Resin thickness: 2.7 mm)

Soldering Method	Soldering Conditions	Recommended Condition Symbol
Infrared reflow	Package peak temperature: 235°C, Duration: 30 sec. max. (210°C or above) Number of times: Max. 2 Time limit: 7 days[Note] (thereafter 20 hours 125°C prebaking required)	IR35-207-3
VPS	Package peak temperature: 215°C, Duration: 40 sec. max. (200°C or above) Number of times: Max. 2 Time limit: 7 days[Note] (thereafter 20 hours 125°C prebaking required)	VP15-207-3
Wave soldering	Solder bath temperature: 260°C max., Duration: 10 sec. max., Number of times: once, Preheating temperature: 120°C max. (package serface temperature), Time limit: 7 days[Note] (thereafter 20 hours 125°C prebaking required)	WS60-207-1
Partial heating	Pin temperature: 300°C or less Duration: 3 sec. max. (per side of device)	—

Note For the storage period after dry-pack decapsulation, storage conditions are max. 25°C, 65% RH.

Caution Use of more than one soldering method should be avoided (except in the case of partial heating).

APPENDIX A. DEVELOPMENT TOOLS

The following support tools are available for system development using the μPD78P058.

Language Processing Software

RA78K/0[Notes 1, 2, 3, 4]	78K/0 series common assembler package
CC78K/0[Notes 1, 2, 3, 4]	78K/0 series common C compiler package
DF78054[Notes 1, 2, 3, 4]	μPD78054 subseries common device file
CC78K/0-L[Notes 1, 2, 3, 4]	78K/0 series common C compiler library source file

PROM Writing Tools

PG-1500	PROM programmer
PA-78P054GC	Programmer adapter connected to a PG-1500
PG-1500 controller[Notes 1, 2]	PG-1500 control program

Debugging Tools

IE-78000-R	78K/0 series common in-circuit emulator
IE-78000-R-A[Note 8]	78K/0 series common in-circuit emulator (for integrated debugger)
IE-78000-R-BK	78K/0 series common break board
IE-78064-R-EM	Emulation board common to μPD78064 subseries
EP-78230GC-R	Emulation probe common to μPD78234 subseries
EV-9200GC-80	Socket for mounting on user system board created for 80-pin plastic QFP use
SM78K0[Notes 5, 6, 7]	78K/0 series common system simulator
ID78K0[Notes 4, 5, 6, 7]	Integrarted debugger for IE-78000-R
SD78K/0[Notes 1, 2]	Screen debugger for IE-78000-R
DF78054[Notes 1, 2, 4, 5, 6, 7]	Device file for μPD78054 subseries

Notes
1. PC-9800 series (MS-DOS™) based
2. IBM PC/AT™ and its compatibles (PC DOS™/IBM DOS™/MS-DOS) based
3. HP9000 series 300™ (HP-UX™) based
4. HP9000 series 700™ (HP-UX) based, SPARCstation™ (SunOS™) based, EWS4800 series (EWS-UX/V) based
5. PC-9800 series (MS-DOS + Windows™) based
6. IBM PC/AT (PC DOS + Windows) based
7. NEWS™ (NEWS-OS™) based
8. Under development

Remarks
1. For third party development tools, see the 78K/0 Series Selection Guide (U11126E).
2. RA78K/0, CC78K/0, SM78K0, ID78K0, and SD78K/0 are used in combination with DF78054.

Real-Time OS

RX78K/0[Notes 1, 2, 3, 4]	78K/0 series real-time OS
MX78K0[Notes 1, 2, 3, 4]	78K/0 series OS

Fuzzy Inference Development Support System

FE9000[Note 1]/FE9200[Note 5]	Fuzzy knowledge data creation tool
FT9080[Note 1]/FT9085[Note 2]	Translator
FI78K0[Notes 1, 2]	Fuzzy inference module
FD78K0[Notes 1, 2]	Fuzzy inference debugger

Notes 1. PC-9800 series (MS-DOS) based
2. IBM PC/AT and its compatibles (PC DOS/IBM DOS/MS-DOS) based
3. HP9000 series 300 (HP-UX) based
4. HP9000 series 700 (HP-UX) based, SPARCstation (SunOS) based, EWS4800 series (EWS-UX/V) based
5. IBM PC/AT and its compatibles (PC DOS/IBM DOS/MS-DOS + Windows) based

Remarks 1. For third party development tools, see the 78K/0 Series Selection Guide (U11126E).
2. RX78K/0 is used in combination with DF78054.

APPENDIX B. RELATED DOCUMENTS

Device Documents

Document Name	Document No. (English)	Document No. (Japanese)
μPD78058F, 78058FY Subseries User's Manual	To be prepared	To be prepared
μPD78P058F Data Sheet	This document	U11796J
μPD78056F, 58F Data Sheet	To be prepared	U11795J
78K/0 Series User's Manual Instruction	IEU-1372	IEU-849
78K/0 Series Instruction Set	—	U10904J
78K/0 Series Instruction Table	—	U10903J

Development Tool Documents (User's Manual)

Document Name		Document No. (English)	Document No. (Japanese)
RA78K Series Assembler Package	Operation	EEU-1399	EEU-809
	Language	EEU-1404	EEU-815
RA78K Series Structured Assembler Preprocessor		EEU-1402	EEU-817
CC78K Series C Compiler	Operation	EEU-1280	EEU-656
	Language	EEU-1284	EEU-655
CC78K/0 C Compiler	Operation	—	U11517J
	Language	—	U11518J
CC78K Series Library Source File		—	EEU-777
PG-1500 PROM Programmer		EEU-1335	EEU-651
PG-1500 Controller PC-9800 Series (MS-DOS) based		EEU-1291	EEU-704
PG-1500 Controller IBM PC Series (PC DOS) based		U10540E	EEU-5008
IE-78000-R		U11376E	EEU-810
IE-78000-R-A		U10057E	U10057J
IE-78000-R-BK		EEU-1427	EEU-867
IE-78064-R-EM		EEU-1443	EEU-905
EP-78230		EEU-1515	EEU-985
EP-78054GK-R		EEU-1468	EEU-932
SM78K0 System Simulator Windows based	Reference	U10181E	U10181J
SM78K Series System Simulator	External parts user open interface specification	U10092E	U10092J
ID78K0 Integrated Debugger EWS based	Reference	U11151E	U11151J
ID78K0 Integrated Debugger PC based	Reference	U11539E	U11539J
ID78K0 Integrated Debugger Windows based	Guide	U11649E	U11649J
SD78K/0 Screen Debugger PC-9800 Series (MS-DOS) based	Introduction	—	EEU-852
	Reference	—	U10952J
SD78K/0 Screen Debugger IBM PC/AT (PC DOS) based	Introduction	EEU-1414	EEU-5024
	Reference	EEU-1413	U11279J

Caution The contents of the above documents are subject to change without notice. Please ensure that the latest versions are used in design work, etc.

Embedded Software Documents (User's Manual)

Document Name		Document No. (English)	Document No. (Japanese)
78K/0 Series Realtime OS	Basics	—	U11537J
	Installation	—	U11536J
	Technical	—	U11538J
78K/0 Series OS MX78K0	Basics	—	EEU-5010
Fuzzy Knowledge Data Creation Tool		EEU-1438	EEU-829
78K/0, 78K/II, 87AD Series Fuzzy, Inference Development Support System—Translator		EEU-1444	EEU-862
78K/0 Series Fuzzy Inference Development Support System	Fuzzy Inference Module	EEU-1441	EEU-858
78K/0 Series Fuzzy Inference Development Support System	Fuzzy Inference Debugger	EEU-1458	EEU-921

Other Documents

Document Name	Document No. (English)	Document No. (Japanese)
IC Package Manual	C10943X	
Semiconductor Device Mounting Technology Manual	C10535E	C10535J
Quality Guides on NEC Semiconductor Devices	IEI-1209	IEI-620
NEC Semiconductor Device Reliability and Quality Control	C10983E	C10983J
Electrostatic Discharge (ESD) Test	—	MEM-539
Semiconductor Device Quality Assurance Guide	MEI-1202	MEI-603
Microcomputer-related Product Guide (Products by other Manufacturers)	—	MEI-604

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