

**VITELIC**

**V53C400**  
**HIGH PERFORMANCE, LOW POWER**  
**4M X 1 BIT FAST PAGE MODE**  
**CMOS DYNAMIC RAM**

**PRELIMINARY**

<b>HIGH PERFORMANCE V53C400</b>	<b>70/70L</b>	<b>80/80L</b>	<b>10/10L</b>
Max. $\overline{\text{RAS}}$ Access Time, ( $t_{\text{RAC}}$ )	70 ns	80 ns	100 ns
Max. Column Address Access Time, ( $t_{\text{CAA}}$ )	35 ns	40 ns	50 ns
Min. Fast Page Mode Cycle Time, ( $t_{\text{PC}}$ )	50 ns	55 ns	65 ns
Min. Read/Write Cycle Time, ( $t_{\text{RC}}$ )	130 ns	150 ns	180 ns

<b>LOW POWER V53C400L</b>	<b>70L</b>	<b>80L</b>	<b>10L</b>
Max. CMOS Standby Current, ( $I_{\text{DD6}}$ )	0.4 mA	0.4 mA	0.4 mA

**Features**

- 4M x 1-bit organization
- RAS access time: 70,80,100 ns
- Low power dissipation
  - V53C400-10
    - Operating Current – 70 mA max.
    - TTL Standby Current – 2.0 mA max.
- Low CMOS Standby Current
  - V53C400 – 1.0 mA max.
  - V53C400L – 0.4 mA max.
- Battery Back-up Mode (V53C400L Only)
- Read-Modify-Write,  $\overline{\text{RAS}}$ -Only Refresh,  $\overline{\text{CAS}}$ -Before- $\overline{\text{RAS}}$  Refresh capability
- Refresh Interval
  - V53C400 – 1024 cycles/16ms
  - V53C400L – 1024 cycles/64ms
- On-chip substrate bias generator
- Fast Page Mode for a sustained data rate greater than 20 MHz
- Available in 26/20 pin SOJ package (300 mil)

cated with Vitelic's VICMOS V technology, the V53C400 offers a combination of features: Fast Page Mode for high data bandwidth, fast usable speed, CMOS standby current and, on request, extended refresh for very low data retention power (V53C400L).

All inputs and outputs are TTL compatible. Input and output capacitances are significantly lowered to allow increased system performance. Fast Page Mode operation allows random access of up to 1024 bits within a row with cycle times as short as 50 ns. Because of static circuitry, the  $\overline{\text{CAS}}$  clock is not in the critical timing path. The flow-through column address latches allow address pipelining while relaxing many critical system timing requirements for fast usable speed. These features make the V53C400 ideally suited for graphics, digital signal processing and high performance computing systems.

**Description**

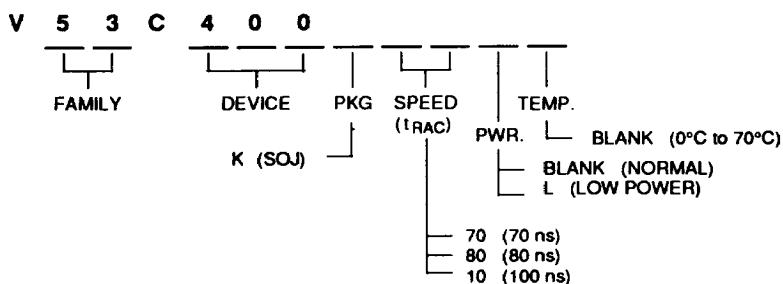
The Vitelic V53C400 is a high speed 4,194,304x1 bit CMOS dynamic random access memory. Fabri-

The V53C400L offers a maximum data retention power of 3.3 mW when operating in CMOS standby mode and performing  $\overline{\text{RAS}}$ -only or  $\overline{\text{CAS}}$ -before- $\overline{\text{RAS}}$  refresh cycles.

**Device Usage Chart**

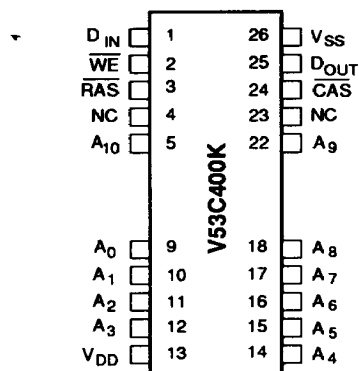
Operating Temperature Range	Package Outline	Access Time (ns)			Power		Temperature Mark
	K	70	80	100	Low	Std.	
0°C to 70 °C	•	•	•	•	•	•	Blank

V53C400 Rev. 01 September 1991

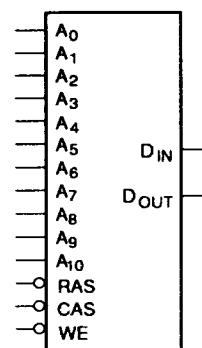


Description	Pkg.	Pin Count
SOJ	K	26/20

### 26/20 Lead SOJ Package PIN CONFIGURATION Top View



### LOGIC SYMBOL



### Pin Names

A <sub>0</sub> -A <sub>10</sub>	Address Inputs
$\overline{\text{RAS}}$	Row Address Strobe
$\overline{\text{CAS}}$	Column Address Strobe
$\overline{\text{WE}}$	Write Enable
D <sub>IN</sub>	Data Input
D <sub>OUT</sub>	Data Output
V <sub>DD</sub>	+5V Supply
V <sub>SS</sub>	0V Supply
NC	No Connect

### Absolute Maximum Ratings\*

#### Ambient Temperature

Under Bias ..... -10°C to +80°C  
 Storage Temperature (plastic) .... -55°C to +125°C  
 Voltage Relative to V<sub>SS</sub> ..... -1.0 V to +7.0 V  
 Data Out Current ..... 50 mA  
 Power Dissipation ..... 1.0 W

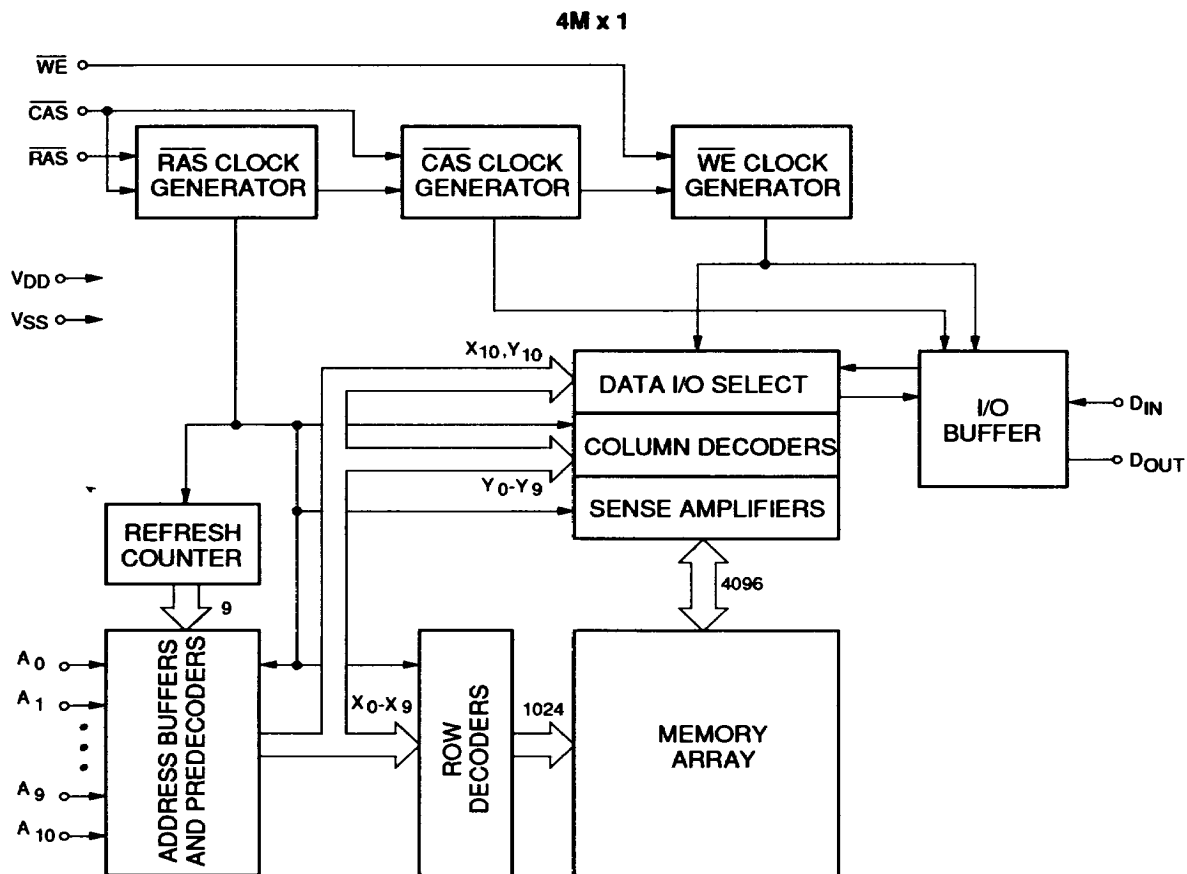
\*Note: Operation above Absolute Maximum Ratings can adversely affect device reliability.

### Capacitance\*

T<sub>A</sub> = 25°C, V<sub>DD</sub> = 5 V ±10%, V<sub>SS</sub> = 0 V

Symbol	Parameter	Typ.	Max.	Unit
C <sub>IN1</sub>	Address	—	6	pF
C <sub>IN2</sub>	$\overline{\text{RAS}}$ , $\overline{\text{CAS}}$ , $\overline{\text{WE}}$	—	7	pF
C <sub>OUT</sub>	D <sub>IN</sub> /D <sub>OUT</sub>	—	7	pF

\*Note: Capacitance is sampled and not 100% tested

**Block Diagram**


**DC and Operating Characteristics (1-2)**
 $T_A = 0^{\circ}\text{C to } 70^{\circ}\text{C}$ ,  $V_{DD} = 5\text{ V} \pm 10\%$ ,  $V_{SS} = 0\text{ V}$ , unless otherwise specified.

Symbol	Parameter	Access Time	V53C400		V53C400L		Unit	Test Conditions	Notes
			Min.	Max.	Min.	Max.			
$I_{LI}$	Input Leakage Current (any input pin)		-10	10	-10	10	$\mu\text{A}$	$V_{SS} \leq V_{IN} \leq V_{DD}$	
$I_{LO}$	Output Leakage Current (for High-Z State)		-10	10	-10	10	$\mu\text{A}$	$V_{SS} \leq V_{OUT} \leq V_{DD}$ $\overline{\text{RAS}}, \text{CAS at } V_{IH}$	
$I_{DD1}$	$V_{DD}$ Supply Current, Operating	70		90		90	mA	$t_{RC} = t_{RC}(\text{min.})$	1, 2
		80		80		80			
		100		70		70			
$I_{DD2}$	$V_{DD}$ Supply Current, TTL Standby			2.0		2.0	mA	$\overline{\text{RAS}}, \text{CAS at } V_{IH}$ other inputs $\geq V_{SS}$	
$I_{DD3}$	$V_{DD}$ Supply Current, $\overline{\text{RAS}}$ -Only Refresh	70		90		90	mA	$t_{RC} = t_{RC}(\text{min.})$	2
		80		80		80			
		100		70		70			
$I_{DD4}$	$V_{DD}$ Supply Current, Fast Page Mode Operation	70		80		80	mA	Minimum Cycle	1, 2
		80		70		70			
		100		60		60			
$I_{DD5}$	$V_{DD}$ Supply Current, Standby, Output Enabled			5		4	mA	$\overline{\text{RAS}} = V_{IH}$ , $\overline{\text{CAS}} = V_{IL}$ other inputs $\geq V_{SS}$	
$I_{DD6}$	$V_{DD}$ Supply Current, CMOS Standby			1		0.4	mA	$\overline{\text{RAS}} \geq V_{DD} - 0.2\text{ V}$ $\overline{\text{CAS}} \geq V_{DD} - 0.2\text{ V}$ other inputs $\geq V_{SS}$	
$I_{DD7}$	Battery Back-up Data Retention Current (Only V53C400L)			N.A.		0.6	mA	$\overline{\text{CAS}}$ -Before- $\overline{\text{RAS}}$ Refresh cycle $t_{RC} = 62.5\text{ }\mu\text{s}$ CMOS clock levels	18
$V_{IL}$	Input Low Voltage		-1.0	0.8	-1.0	0.8	V		3
$V_{IH}$	Input High Voltage		2.4	$V_{DD}+1$	2.4	$V_{DD}+1$	V		3
$V_{OL}$	Output Low Voltage			0.4		0.4	V	$I_{OL} = 4.2\text{ mA}$	
$V_{OH}$	Output High Voltage		2.4		2.4			$I_{OH} = -5\text{ mA}$	

**AC Characteristics**
 $T_A = 0^\circ\text{C to } 70^\circ\text{C}$ ,  $V_{DD} = 5\text{ V} \pm 10\%$ ,  $V_{SS} = 0\text{ V}$ , unless otherwise noted

#	JEDEC Symbol	Symbol	Parameter	70/L		80/L		10/L		Unit	Notes
				Min.	Max.	Min.	Max.	Min.	Max.		
1	$t_{RL1RH1}$	$t_{RAS}$	$\overline{RAS}$ Pulse Width	70	75K	80	75K	100	75K	ns	
2	$t_{RL2RL}$	$t_{RC}$	Read or Write Cycle Time	130		150		180		ns	
3	$t_{RH2RL2}$	$t_{RP}$	$\overline{RAS}$ Precharge Time	50		60		70		ns	
4	$t_{AVRL2}$	$t_{ASR}$	Row Address Setup Time	0		0		0		ns	
5	$t_{RL1AX}$	$t_{RAH}$	Row Address Hold Time	10		10		15		ns	
6	$t_{AVRH1}$	$t_{CAR}$	Column Address to $\overline{RAS}$ Setup Time	35		40		50		ns	
7	$t_{RL1AV}$	$t_{RAD}$	$\overline{RAS}$ to Column Address Delay Time	15	35	15	40	20	50	ns	4
8	$t_{AVCL2}$	$t_{ASC}$	Column Address Setup Time	0		0		0		ns	
9	$t_{CL1AX}$	$t_{CAH}$	Column Address Hold Time	15		15		20		ns	
10	$t_{RL1CL1}$	$t_{RCD}$	$\overline{RAS}$ to $\overline{CAS}$ Delay	20	50	20	60	25	75	ns	5
11	$t_{RL1QV}$	$t_{RAC}$	Access Time from $\overline{RAS}$		70		80		100	ns	6,7,8
12	$t_{AVQV}$	$t_{CAA}$	Access Time from Column Address		35		40		50	ns	8,9,10
13	$t_{CL1QV}$	$t_{CAC}$	Access Time from $\overline{CAS}$		20		20		25	ns	8,10
14	$t_{CL1CH1(R)}$	$t_{CAS(R)}$	$\overline{CAS}$ Pulse Width in Read Cycle	20		20		25		ns	
15	$t_{CL1RH1(R)}$	$t_{RSH(R)}$	$\overline{RAS}$ Hold Time (Read Cycle)	20		20		25		ns	
16	$t_{WH2CL2}$	$t_{RCS}$	Read Command Setup Time	0		0		0		ns	
17	$t_{CH2WX}$	$t_{RCH}$	Read Command Hold Time Referenced to $\overline{CAS}$	0		0		0		ns	11
18	$t_{RH2WX}$	$t_{RRH}$	Read Command Hold Time Referenced to $\overline{RAS}$	0		0		0		ns	11
19	$t_{CH2RL2}$	$t_{CRP}$	$\overline{CAS}$ to $\overline{RAS}$ Precharge Time	5		5		10		ns	
20	$t_{CH2QX}$	$t_{OFF}$	Output Buffer Turn Off Delay	0	15	0	20	0	25	ns	12

**AC Characteristics (Cont'd.)**

#	JEDEC Symbol	Symbol	Parameter	70/L		80/L		10/L		Unit	Notes
				Min.	Max.	Min.	Max.	Min.	Max.		
21	$t_{CH2QV}$	$t_{OH}$	Data Hold Time from $\overline{CAS}$	0		0		0		ns	11
22	$t_{WL1WH1}$	$t_{WP}$	Write Pulse Width	10		15		20		ns	
23	$t_{CH2CL2}$	$t_{CP}$	$\overline{CAS}$ Precharge Time	10		10		10		ns	
24	$t_{RL1AX}$	$t_{AR}$	Column Address Hold Time from $\overline{RAS}$	55		60		75		ns	
25	$t_{CL1CH1(W)}$	$t_{CAS(W)}$	$\overline{CAS}$ Pulse Width in Write Cycle	20		20		25		ns	
26	$t_{CL1RH1(W)}$	$t_{RSH(W)}$	$\overline{RAS}$ or $\overline{CAS}$ Hold Time in Write Cycle	20		20		25		ns	
27	$t_{RL1WH1}$	$t_{WCR}$	Write Command Hold Time from $\overline{RAS}$	55		60		75		ns	
28	$t_{WL1CL2}$	$t_{WCS}$	Write Command Setup Time	0		0		0		ns	13,14
29	$t_{CL1WH1}$	$t_{WCH}$	Write Command Hold Time	10		15		20		ns	
30	$t_{DVL2}$	$t_{DS}$	Data In Setup Time	0		0		0		ns	15
31	$t_{WH1DX}$	$t_{DH}$	Data In Hold Time	15		15		20		ns	15
32	$t_{RL1DX}$	$t_{DHR}$	Data In Hold Time Referenced to $\overline{RAS}$	55		60		75		ns	
33	$t_{RL2RL2(RMW)}$	$t_{RWC}$	Read-Modify-Write Cycle Time	155		175		210		ns	
34	$t_{RL1RH1(RMW)}$	$t_{RRW}$	Read-Modify-Write Cycle $\overline{RAS}$ Pulse Width	95		105		130		ns	
35	$t_{RL1WL2}$	$t_{RWD}$	$\overline{RAS}$ to $\overline{WE}$ Delay Time Read-Modify-Write Cycle	70		80		100		ns	13
36	$t_{CL1WL2}$	$t_{CWD}$	$\overline{CAS}$ to $\overline{WE}$ Delay	20		20		25		ns	13
37	$t_{AVWL2}$	$t_{AWD}$	Column Address to $\overline{WE}$ Delay	35		40		50		ns	13
38	$t_{CH2QV}$	$t_{CAP}$	Access Time from Column Precharge		40		45		55	ns	17
39	$t_{CL2CL2(R)}$	$t_{PC}$	Fast Page Mode Read or Write Cycle Time	50		55		65		ns	

**AC Characteristics (Cont'd.)**

#	JEDEC Symbol	Symbol	Parameter	70/L		80/L		10/L		Unit	Notes
				Min.	Max.	Min.	Max.	Min.	Max.		
40	$t_{CL2CL2}$	$t_{PCM}^{(RMW)}$	Fast Page Mode Read-Modify-Write Cycle Time	75		80		95		ns	
41	$t_{WL1RH1}$	$t_{RWL}$	Write Command to $\overline{RAS}$ Lead Time	20		20		25		ns	
42	$t_{WL1CH1}$	$t_{CWL}$	Write Command to $\overline{CAS}$ Lead Time	20		20		25		ns	
43	$t_{RH2CL2}$	$t_{RPC}$	$\overline{RAS}$ to $\overline{CAS}$ Precharge Time	5		5		5		ns	
44	$t_{CL1RL2}$	$t_{CSR}$	$\overline{CAS}$ Setup Time $\overline{CAS}$ -before- $\overline{RAS}$ Refresh	5		5		5		ns	
45	$t_{RL1CH1}$	$t_{CHR}$	$\overline{CAS}$ Hold Time $\overline{CAS}$ -before- $\overline{RAS}$ Cycle	15		15		15		ns	
46	$t_{RL1CH1}$	$t_{CSH}$	$\overline{CAS}$ Hold Time	70		80		100		ns	
47	$t_{WH2RL2}$	$t_{WRP}$	$\overline{WE}$ to $\overline{RAS}$ precharge time ( $\overline{CAS}$ -Before- $\overline{RAS}$ Refresh cycle)	10		10		10		ns	
48	$t_{RL1WL2}$	$t_{WRH}$	$\overline{WE}$ Hold Time from $\overline{RAS}$ ( $\overline{CAS}$ -Before- $\overline{RAS}$ Refresh Cycle)	10		10		10		ns	
49	$t_{WL1RL2}$	$t_{WSR}$	$\overline{RAS}$ to $\overline{WE}$ set-up Time (Test Mode)	10		10		10		ns	20, 21
50	$t_{RL1WH1}$	$t_{WHR}$	$\overline{RAS}$ to $\overline{WE}$ hold Time (Test Mode)	10		10		10		ns	20, 21
51	$t_T$	$t_T$	Transition Time (Rise and Fall)	3	50	3	50	3	50	ns	16
52		$t_{REF}$	Refresh Interval (1024 Cycles)		16		16		16	ms	19
53		$t_{REF}$	Refresh Interval V53C400L Only (1024 Cycles, $t_{RC} = 62.5 \mu s$ )		64		64		64	ms	18,19



**Notes:**

1.  $I_{DD}$  is dependent on output loading when the device output is selected. Specified  $I_{DD}$  (max.) is measured with the output open.
2.  $I_{DD}$  is dependent upon the number of address transitions. Specified  $I_{DD}$  (max.) is measured with a maximum of two transitions per address cycle in Fast Page Mode.
3. Specified  $V_{IL}$  (min.) is steady state operating. During transitions,  $V_{IL}$  (min.) may undershoot to  $-1.0$  V for a period not to exceed 20 ns. All AC parameters are measured with  $V_{IL}$  (min.)  $\geq V_{SS}$  and  $V_{IH}$  (max.)  $\leq V_{DD}$ .
4. Operation within the  $t_{RAD}$  (max.) limit ensures that  $t_{RAC}$  (max.) can be met.  $t_{RAD}$  (max.) is specified as a reference point only. If  $t_{RAD}$  is greater than the specified  $t_{RAD}$  (max.) limit, the access time is controlled by  $t_{CAA}$  and  $t_{CAC}$ .
5.  $t_{RCD}$  (max.) is specified for reference only. Operation within  $t_{RCD}$  (max.) limits insures that  $t_{RAC}$  (max.) and  $t_{CAA}$  (max.) can be met. If  $t_{RCD}$  is greater than the specified  $t_{RCD}$  (max.), the access time is controlled by  $t_{CAA}$  and  $t_{CAC}$ .
6. Assumes that  $t_{RAD} \leq t_{RAD}$  (max.). If  $t_{RAD}$  is greater than  $t_{RAD}$  (max.),  $t_{RAC}$  will increase by the amount that  $t_{RAD}$  exceeds  $t_{RAD}$  (max.).
7. Assumes that  $t_{RCD} \leq t_{RCD}$  (max.). If  $t_{RCD}$  is greater than  $t_{RCD}$  (max.),  $t_{RAC}$  will increase by the amount that  $t_{RCD}$  exceeds  $t_{RCD}$  (max.).
8. Measured with a load equivalent to two TTL inputs and 100 pF.
9. Assumes that  $t_{RAD} \geq t_{RAD}$  (max.).
10. Access time is determined by the longest of  $t_{CAA}$ ,  $t_{CAC}$  and  $t_{CAP}$ .
11. Either  $t_{RRH}$  or  $t_{RCH}$  must be satisfied for a Read Cycle to occur.
12.  $t_{OFF}$  and  $t_{ON}$  define the time at which  $D_{OUT}$  reaches an open circuit condition and are not referenced to the output voltage level.
13.  $t_{WCS}$ ,  $t_{RWD}$ ,  $t_{AWD}$  and  $t_{CWD}$  are not restrictive operating parameters.
14.  $t_{WCS}$  (min.) must be satisfied in an Early Write Cycle.
15.  $t_{DS}$  and  $t_{DH}$  are referenced to the latter occurrence of  $\overline{CAS}$  or  $\overline{WE}$ .
16.  $t_T$  is measured between  $V_{IH}$  (min.) and  $V_{IL}$  (max.). AC-measurements assume  $t_T = 5$  ns.
17. Assumes a three-state test load (5 pF and a 380 Ohm Thevenin equivalent).
18. An initial 200  $\mu$ s pause and 8  $\overline{RAS}$ -containing cycles are required when exiting an extended period of bias without clocks. An extended period of time without clocks is defined as one that exceeds the specified Refresh Interval.
19. This is battery backup data retention mode under  $\overline{CAS}$ -before- $\overline{RAS}$  refresh cycles.

$$t_{BC} = 62.5 \mu s \text{ (} 62.5 \mu s \times 1024 = 64 \text{ ms)}$$

$$t_{BAS} = t_{BAS} \text{ (min) to } 1 \mu s$$

Input voltages :  $\overline{\text{RAS}}$  and  $\overline{\text{CAS}}$   $V_{IH} > V_{DD} - 0.2 \text{ V}$

$$V_H < 0.2 \text{ V}$$

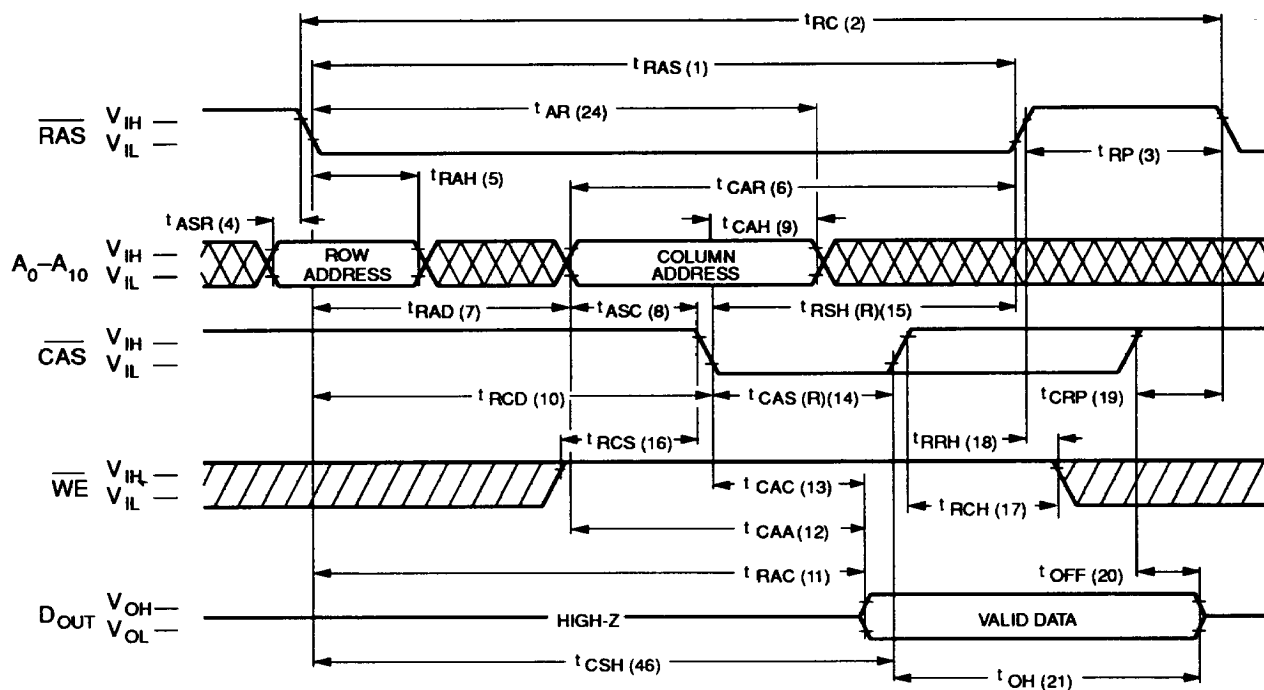
$$\overline{\text{WE}} \text{ and } \overline{\text{OE}} \quad V_{\text{IN}} > V_{\text{DD}} - 0.2 \text{ V}$$

All other inputs at stable  $V_{IH}$  or  $V_{IL}$

20. The test mode is initiated by performing a  $\overline{\text{WE}}$  and  $\overline{\text{CAS}}$ -before- $\overline{\text{RAS}}$  cycle. This mode is latched and remains in effect until the exit cycle is generated. The test mode specified in this data sheet is 8-bits parallel testing function.  $\text{RA}_{10}$ ,  $\text{CA}_{10}$ ,  $\text{CA}_0$  are not used. In the read cycle, if two internal bits on one I/O pin are equal, the I/O pin will indicate a high level. If internal bits on one I/O are not equal, then the I/O pin will indicate a low level. The test mode is cleared and the memory device returned to its normal operational state by performing a  $\overline{\text{RAS}}$ -only refresh cycle or a  $\overline{\text{CAS}}$ -before- $\overline{\text{RAS}}$  refresh cycle.
21. In a test mode read cycle, the value of access time parameters is delayed by 5 ns for the specified value. These parameters should be specified in test mode cycles by adding the above value (5 ns) to the specified value in this data sheet.

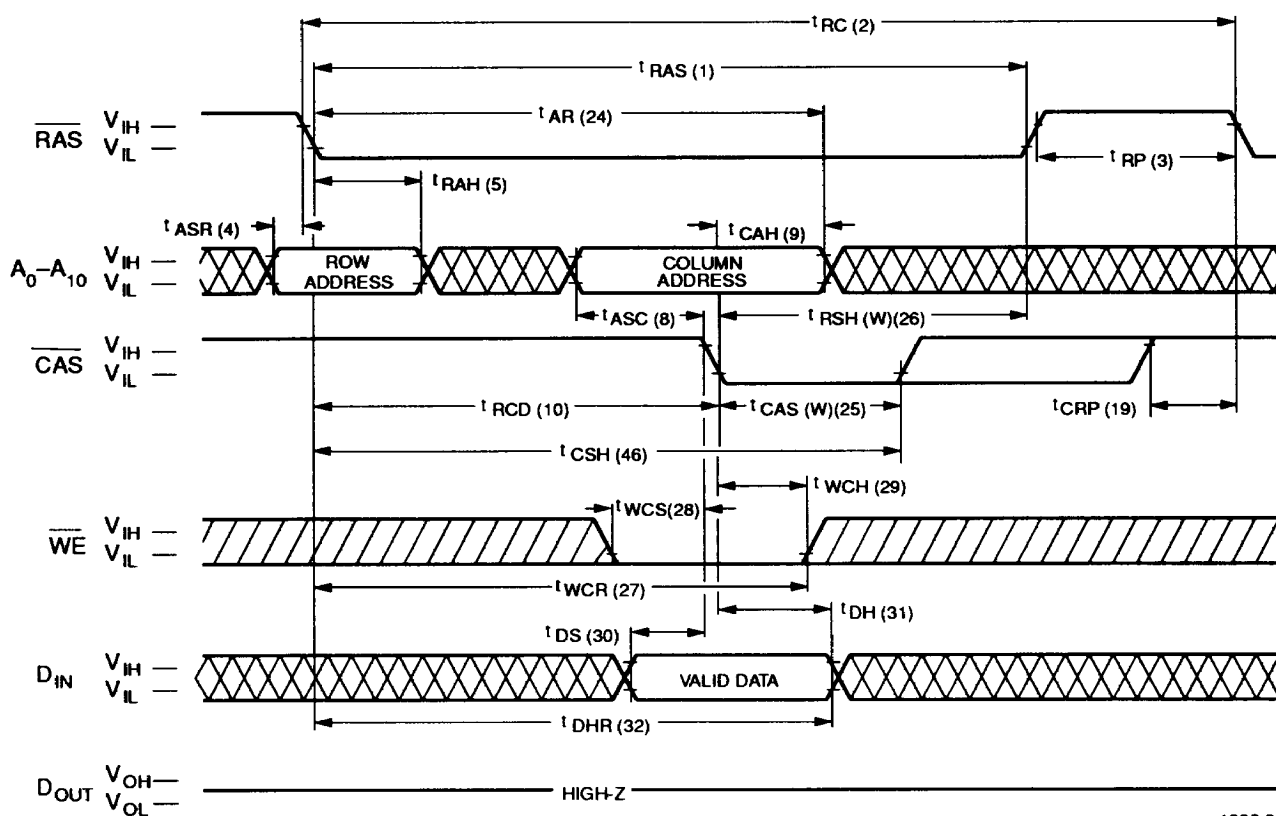


### Waveforms of Read Cycle



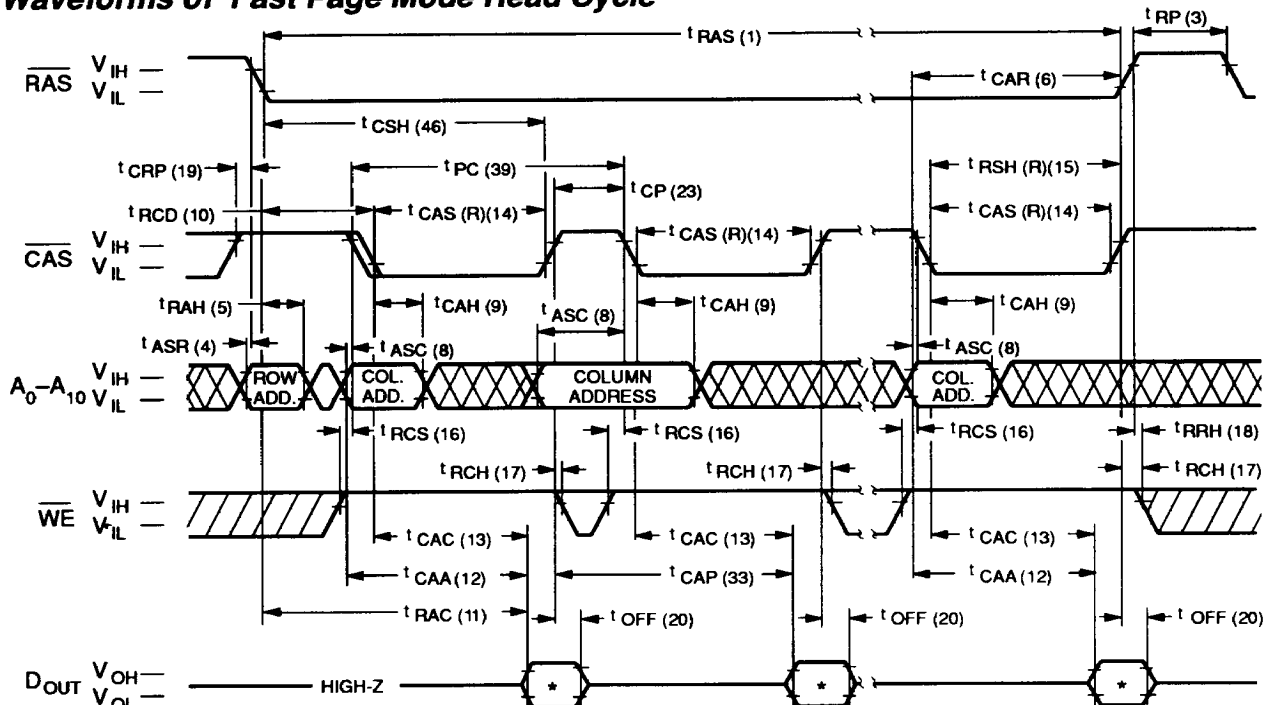
1002 01

### Waveforms of Early Write Cycle



1002 02

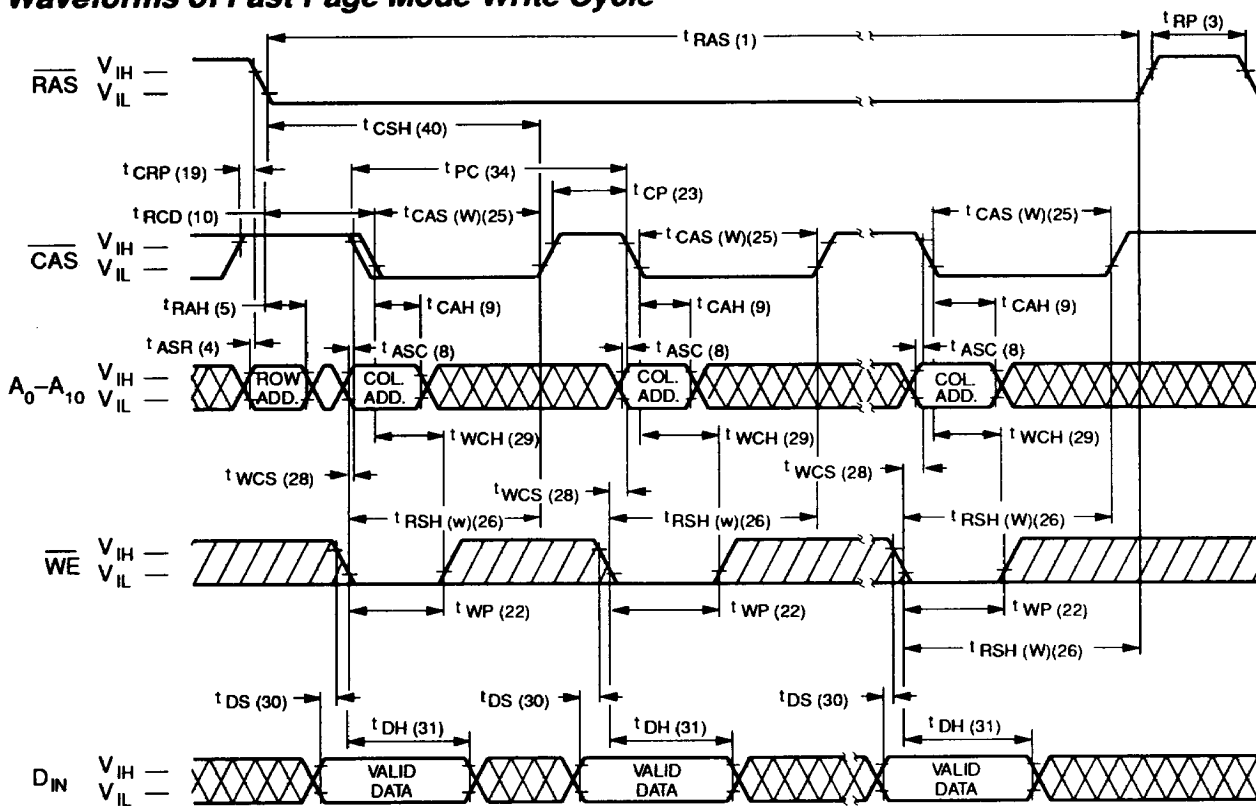
### Waveforms of Fast Page Mode Read Cycle



\* Valid Data

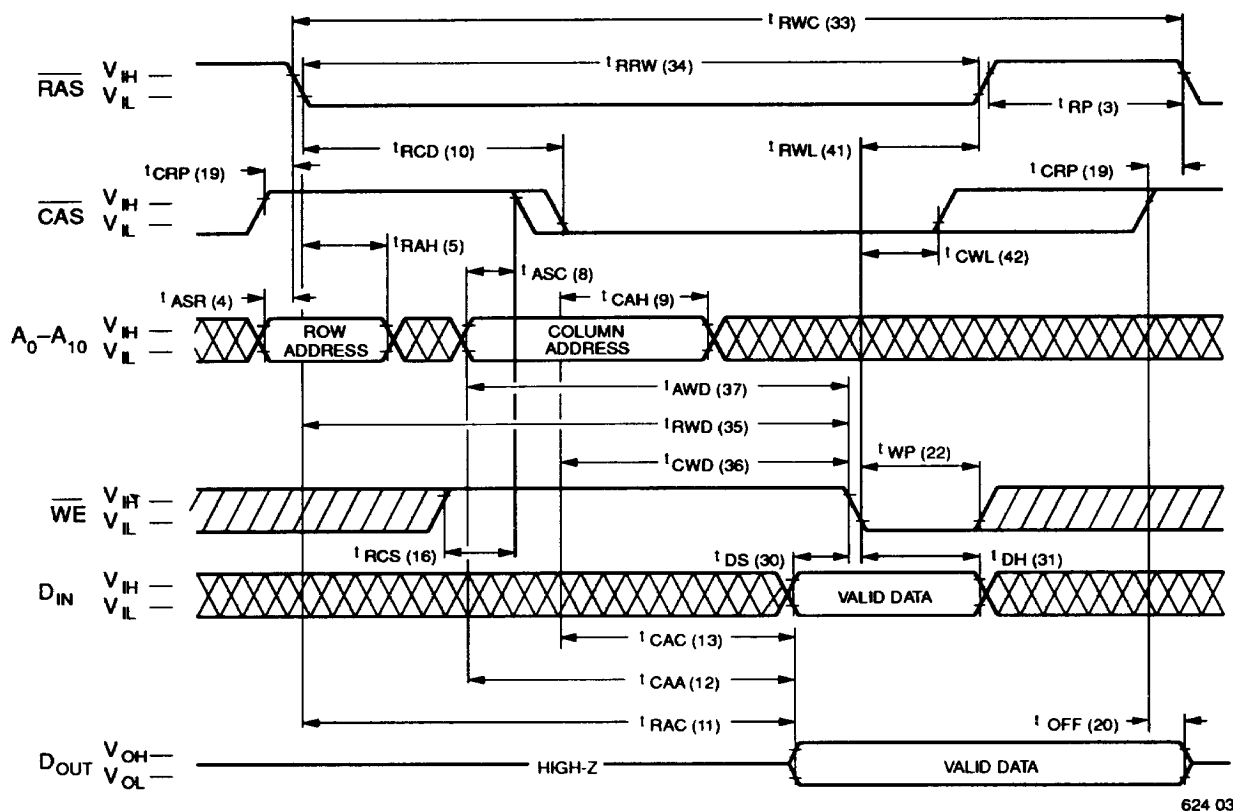
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### Waveforms of Fast Page Mode Write Cycle

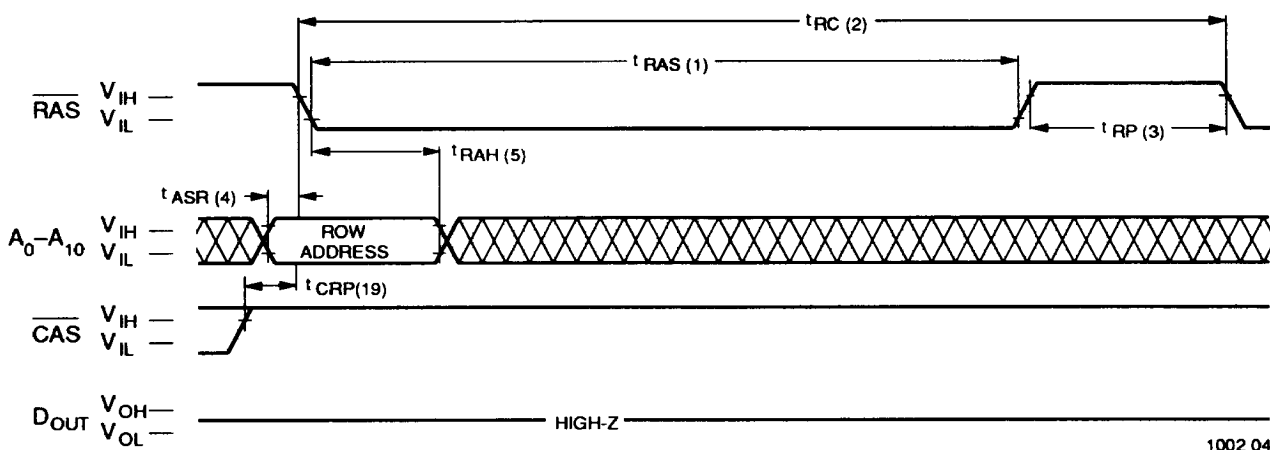


1002 09

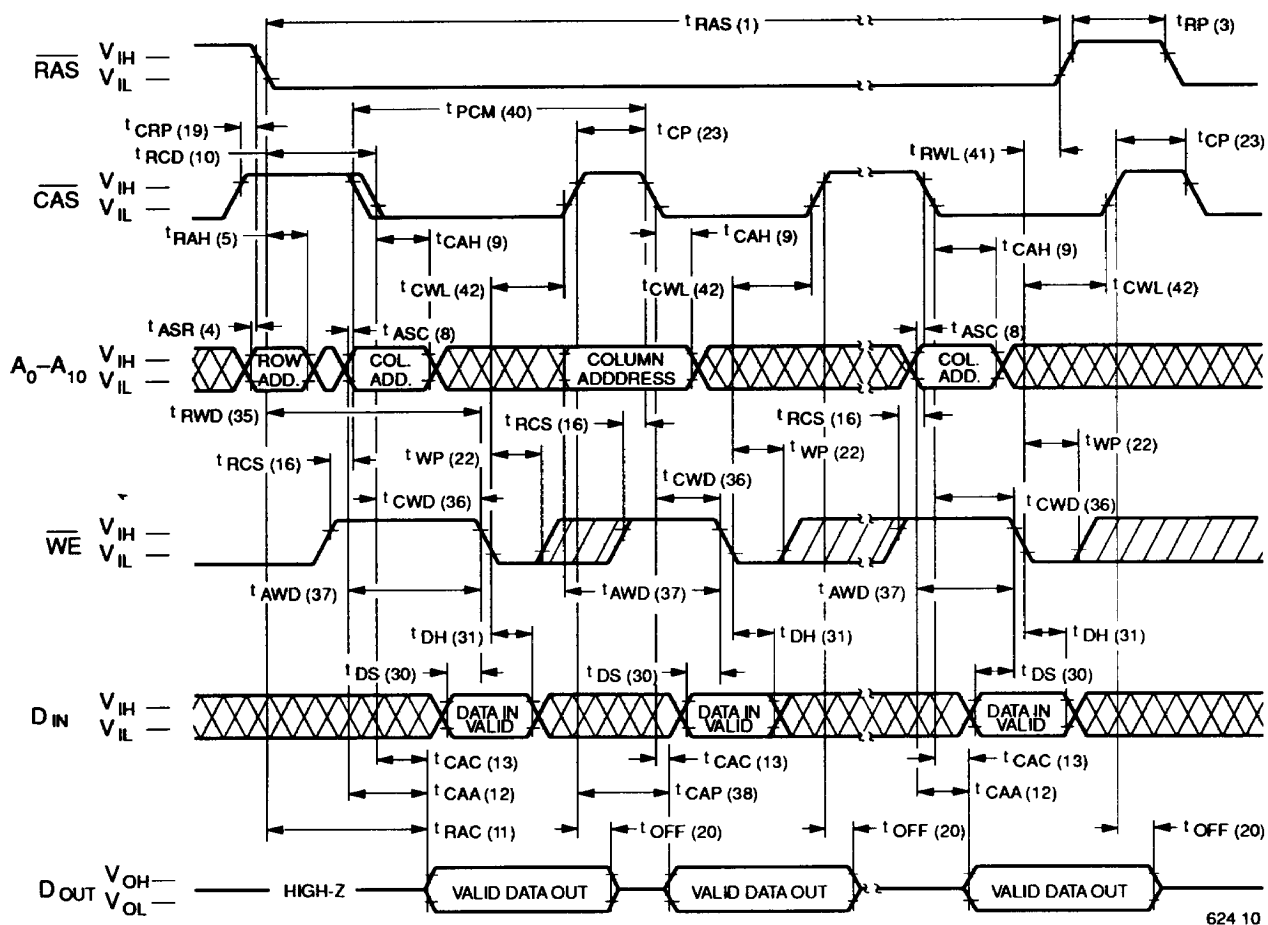
### Waveforms of Read-Modify-Write Cycle



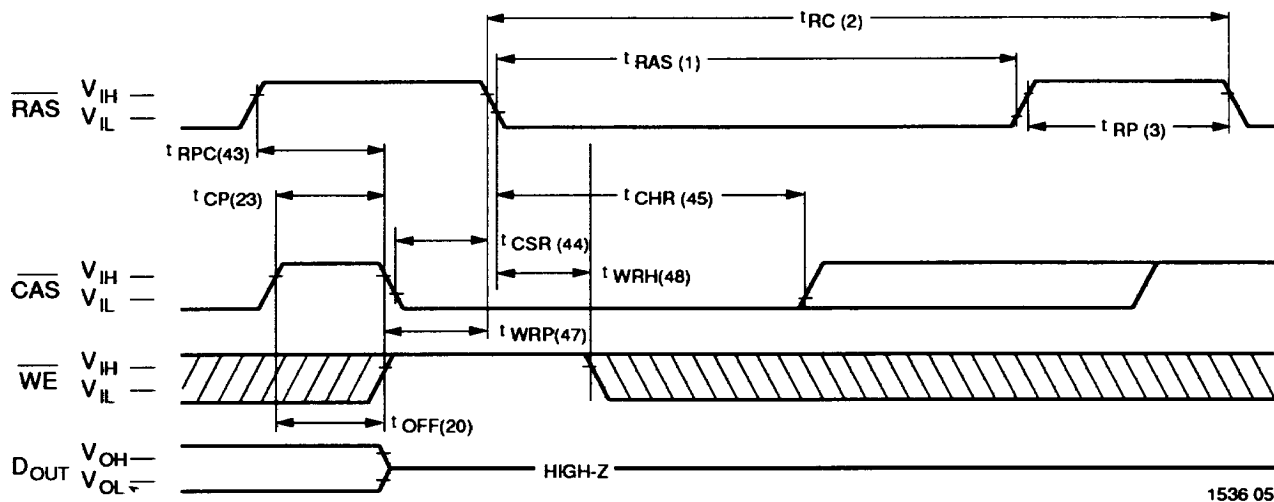
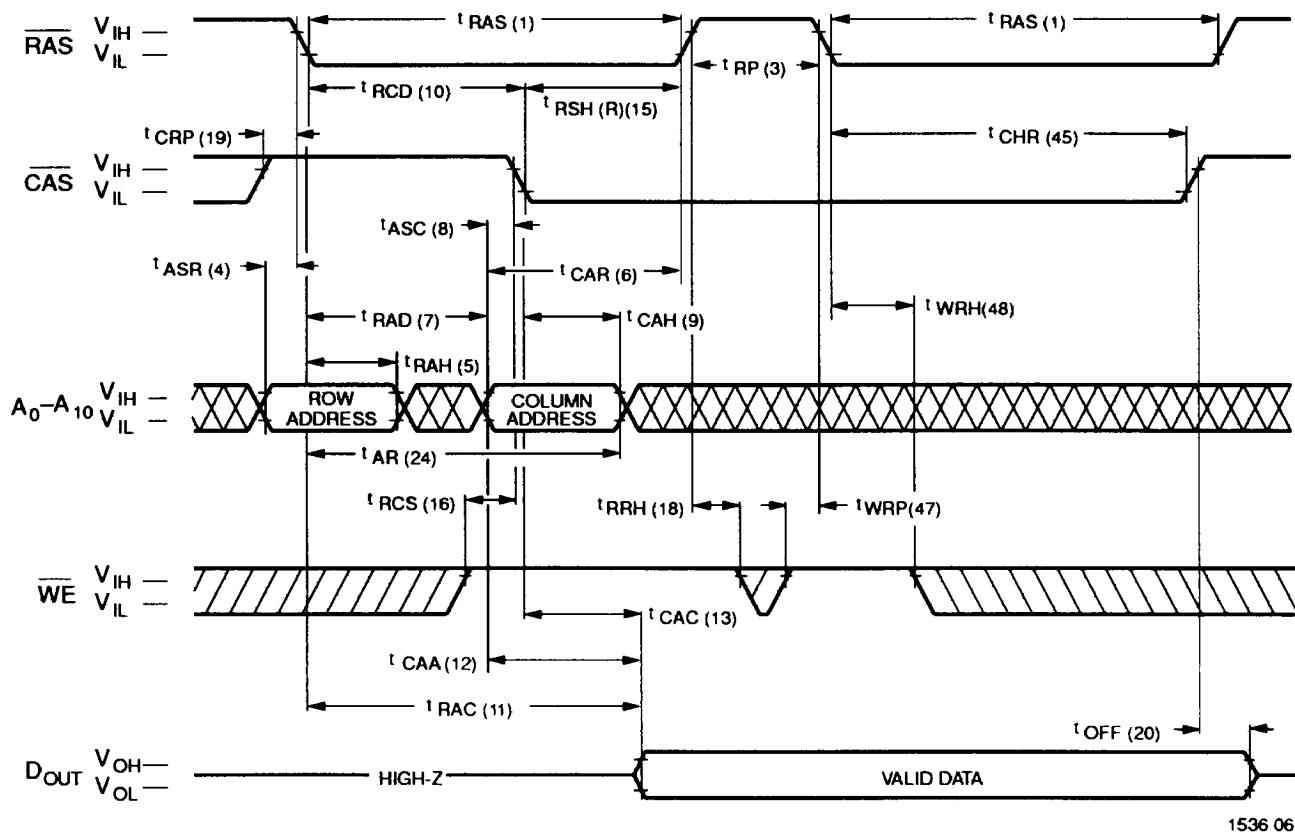
### Waveforms of RAS-Only Refresh Cycle



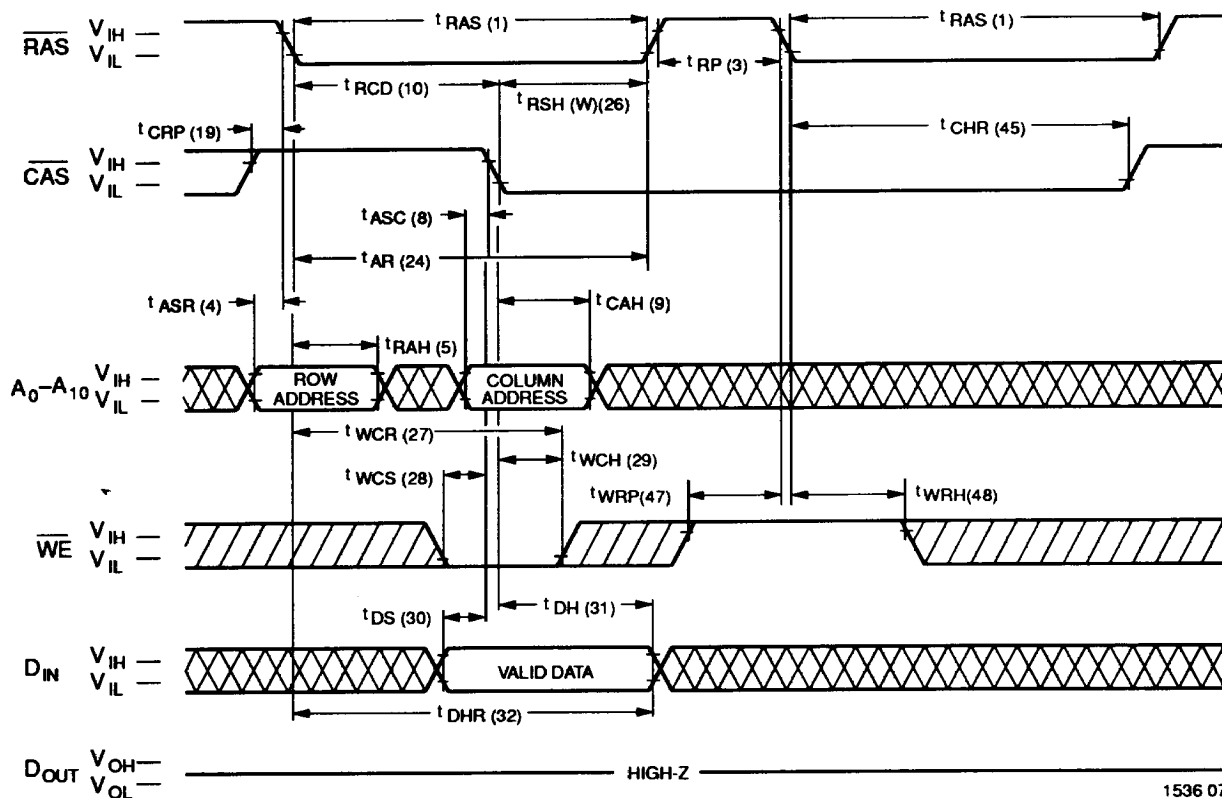
### Waveforms of Fast Page Mode Read-Modify-Write Cycle



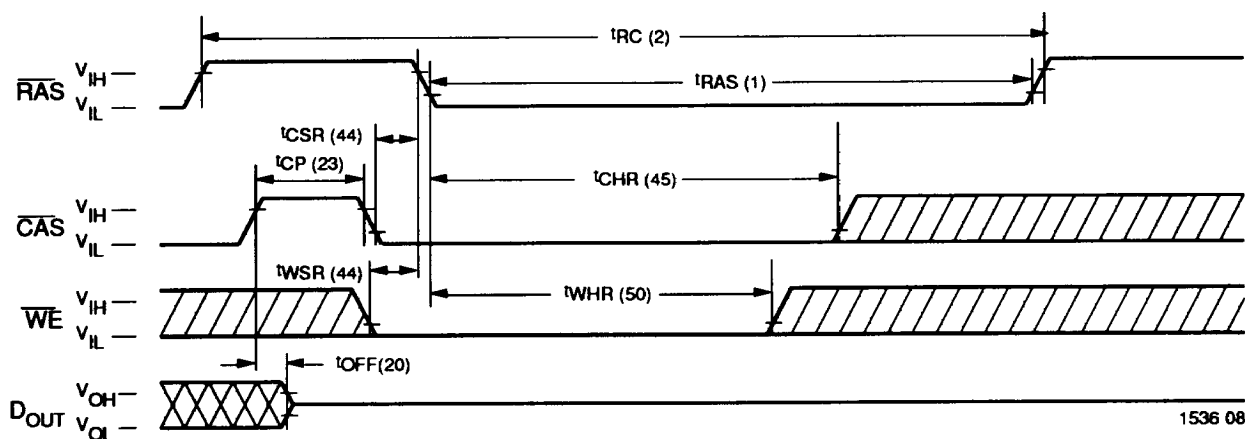
624 10

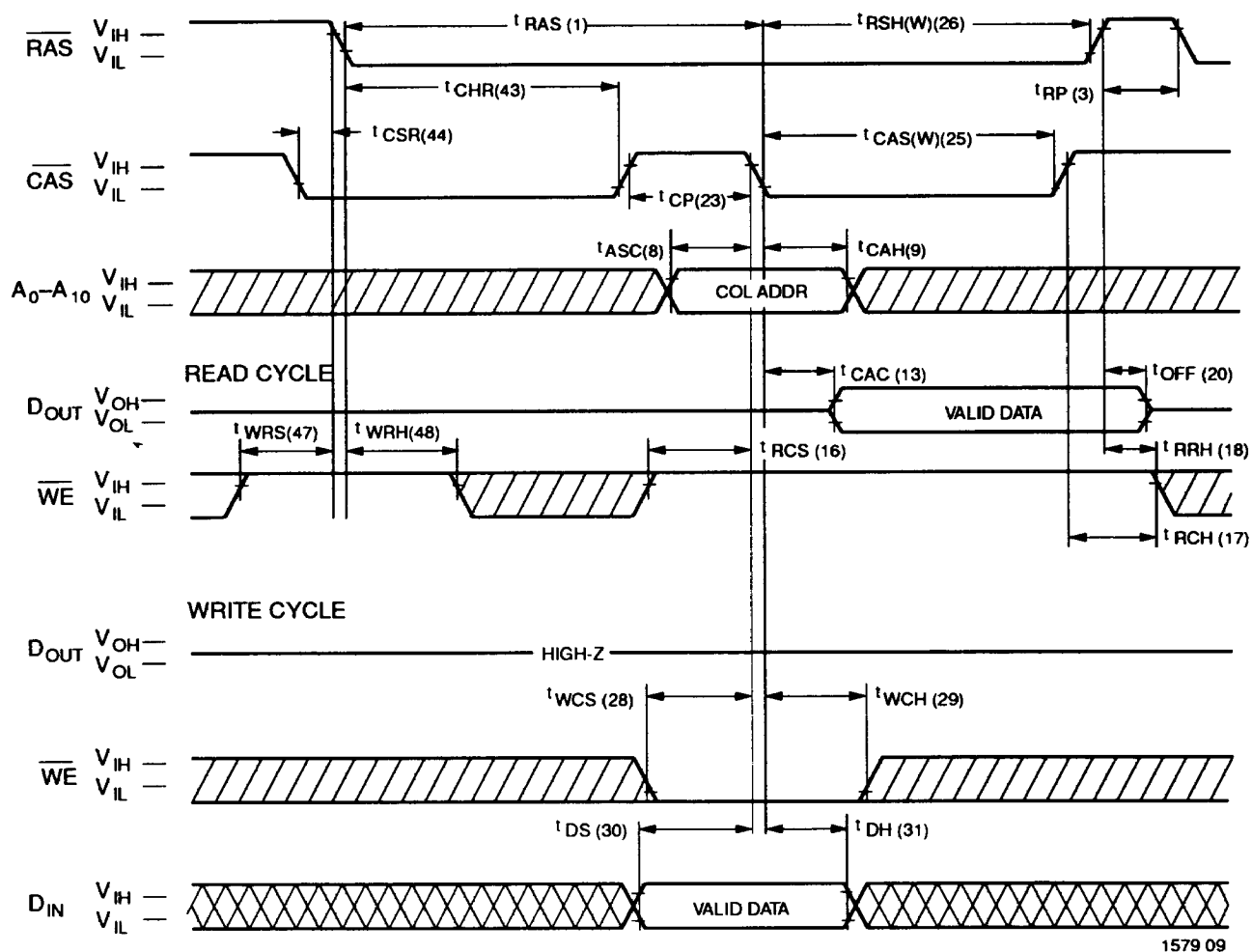
**Waveforms of CAS-before-RAS Refresh Cycle****Waveforms of Hidden Refresh Cycle (Read)**

### Waveforms of Hidden Refresh Cycle (Write)



### Test Mode Initiation Cycle



**Waveforms of  $\overline{\text{CAS}}$ -Before- $\overline{\text{RAS}}$  Refresh Counter Test Cycle**

## Functional Description

The V53C400 is a CMOS dynamic RAM optimized for high data bandwidth, low power applications. It is functionally similar to a traditional dynamic RAM. The V53C400 reads and writes data by multiplexing a 22-bit address into an 11-bit row and an 11-bit column address. The row address is latched by the Row Address Strobe ( $\overline{\text{RAS}}$ ). The column address flows through an internal address buffer and is latched by the Column Address Strobe ( $\text{CAS}$ ). Because access time is primarily dependent on a valid column address rather than the precise time that the  $\text{CAS}$  edge occurs, the delay from  $\text{RAS}$  to  $\text{CAS}$  has little effect on the access time.

## Memory Cycle

A memory cycle is initiated by bringing  $\overline{\text{RAS}}$  low. Any memory cycle, once initiated, must not be ended or aborted before the minimum  $t_{\text{RAS}}$  time has expired. This ensures proper device operation and data integrity. A new cycle must not be initiated until the minimum precharge time  $t_{\text{RP}}/t_{\text{CP}}$  has elapsed.

## Read Cycle

A Read cycle is performed by holding the Write Enable ( $\text{WE}$ ) signal high during a  $\text{RAS}/\text{CAS}$  operation. The column address must be held for a minimum time specified by  $t_{\text{AR}}$ . Data Out becomes valid only when  $t_{\text{RAC}}$ ,  $t_{\text{CAA}}$  and  $t_{\text{CAC}}$  are all satisfied. As a result, the access time is dependent on the timing relationships between  $t_{\text{RAC}}$ ,  $t_{\text{CAA}}$  and  $t_{\text{CAC}}$ . For example, the access time is limited by  $t_{\text{CAA}}$  when  $t_{\text{RAC}}$  (min.) and  $t_{\text{CAC}}$  (min.) are both satisfied.

## Write Cycle

A Write cycle is performed by taking  $\text{WE}$  and  $\text{CAS}$  low during a  $\text{RAS}$  operation. The column address is latched by  $\text{CAS}$ . The write can be  $\text{WE}$  controlled or  $\text{CAS}$  controlled depending on whether  $\text{WE}$  or  $\text{CAS}$  falls later. Consequently, the input data must be valid at or before the falling edge of  $\text{WE}$  or  $\text{CAS}$ , whichever occurs last. In a  $\text{CAS}$ -controlled Write Cycle when the leading edge of  $\text{WE}$  occurs prior to the  $\text{CAS}$  low transition, the output ( $\text{D}_{\text{OUT}}$ ) pin will be in the High-Z state at the beginning of the Write function. Ending the Write with  $\text{RAS}$  or  $\text{CAS}$  will maintain the output in the High-Z state.

## Refresh Cycle

To retain data, 1024 Refresh Cycles are required in each 16 ms period. There are two ways to Refresh the memory:

1. By selecting all 1024 address combinations of A0 through A9 each 16 ms, a refresh of all rows is completed. Any Read, Write, Read-Modify-Write or  $\text{RAS}$ -only cycle refreshes the addressed row.
2. Using a  $\text{CAS}$ -before- $\text{RAS}$  Refresh Cycle. If  $\text{CAS}$  makes a transition from low to high to low after the previous cycle and before  $\text{RAS}$  falls,  $\text{CAS}$ -before- $\text{RAS}$  refresh is activated. The V53C400 will use the output of an internal 10-bit counter as the source of row addresses and ignore external address inputs.

$\text{CAS}$ -before- $\text{RAS}$  is a "refresh-only" mode and no data access or device selection is allowed. Thus,  $\text{D}_{\text{OUT}}$  will remain in the High-Z state during the cycle.

A  $\text{CAS}$ -before- $\text{RAS}$  counter test mode is provided to ensure reliable operation of the internal refresh counter. The user can use the counter test mode to write consecutive data patterns (1024 Write cycles) and then verify the written data by applying 1024 consecutive Read cycles. In this mode, the V53C400 ignores external row/column addresses and takes the output from the internal counter instead.

## Data Retention Mode

The V53C400 offers a CMOS standby mode that is entered by causing the  $\text{RAS}$  clock to swing between a valid  $V_{\text{IL}}$  and an "extra high"  $V_{\text{IH}}$  within 0.2 V of  $V_{\text{DD}}$ . While the  $\text{RAS}$  clock is at the "extra high" level, the V53C400 power consumption is reduced to the low  $I_{\text{DD6}}$  level. Overall  $I_{\text{DD}}$  consumption when operating in this mode can be calculated as follows:

$$I = \frac{(t_{\text{RC}}) \times (I_{\text{DD1}}) + (t_{\text{RX}} - t_{\text{RC}}) \times (I_{\text{DD6}})}{t_{\text{RX}}}$$

Where  $t_{\text{RC}}$  = Refresh Cycle Time  
 $t_{\text{RX}}$  = Refresh Interval / 1024



### Fast Page Mode Operation

Fast Page Mode operation permits all 2048 columns within a selected row of the device to be randomly accessed at a high data rate. Maintaining  $\overline{\text{RAS}}$  low while performing successive  $\overline{\text{CAS}}$  cycles retains the row address internally and eliminates the need to reapply it for each cycle. The column address buffer acts as a transparent or flow-through latch while  $\overline{\text{CAS}}$  is high.

Thus, access begins at the occurrence of a valid column address rather than at the falling edge of  $\overline{\text{CAS}}$ , eliminating  $t_{\text{ASC}}$  and  $t_{\text{r}}$  from the critical timing path.  $\overline{\text{CAS}}$  latches the address into the column address buffer and acts as an output enable.

During Fast Page Mode operation, Read, Write, Read-Modify-Write, or Read-Write-Read cycles are possible at random addresses within a row. Following the initial entry cycle into Fast Page Mode, access is  $t_{\text{CAA}}$  or  $t_{\text{CAP}}$  controlled. If the column address is valid prior to the rising edge of  $\overline{\text{CAS}}$ , the access time is determined by the  $\overline{\text{CAS}}$  rising edge. If the column address is valid after the rising edge of  $\overline{\text{CAS}}$ , the access is timed from the occurrence of the valid address and is specified by  $t_{\text{CAA}}$ . In both cases, the falling edge of  $\overline{\text{CAS}}$  latches the address and enables the output.

Fast Page Mode provides a sustained data rate of over 20 MHz for applications that require high data rates like bit-mapped graphics or high-speed signal processing. The following equation can be used to calculate the data rate:

$$\text{Data Rate} = \frac{2,048}{t_{\text{RC}} + 2,047 \times t_{\text{PC}}}$$

### Data Output Operation

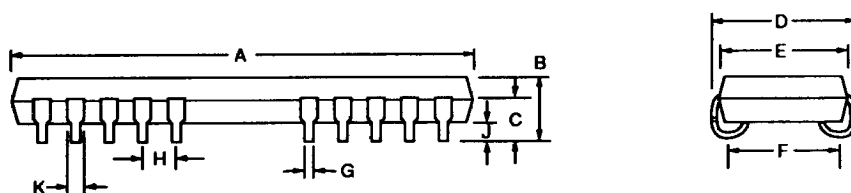
The V53C400 Data Output pin ( $D_{\text{OUT}}$ ) has a three-state capability and is controlled by  $\overline{\text{CAS}}$ . When  $\overline{\text{CAS}}$  is high ( $\geq V_{\text{IH}}$ ), the output is in the High-Z state. Table 1 summarizes the  $D_{\text{OUT}}$  states possible for various memory cycles.

### Power On

After application of the  $V_{\text{DD}}$ , an initial pause of 200  $\mu\text{s}$  is required followed by a minimum of 8 initialization cycles (any combination of cycles containing a  $\overline{\text{RAS}}$  clock). Eight initialization cycles are required after extended periods of bias without clocks (greater than the Refresh Interval). During power on, the  $V_{\text{DD}}$  current requirement of the V53C400 is dependent on the input levels of  $\overline{\text{RAS}}$  and  $\overline{\text{CAS}}$ . If  $\overline{\text{RAS}}$  is Low during power on, the device will go into an active cycle and  $I_{\text{DD}}$  will exhibit current transients. It is recommended that  $\overline{\text{RAS}}$  and  $\overline{\text{CAS}}$  track with  $V_{\text{DD}}$  or be held at a valid  $V_{\text{IH}}$  during power on to avoid current surges.

**Table 1. Vitellic V53C400 Data Output Operation for Various Cycle Types**

Cycle Type	$D_{\text{OUT}}$ State
Read Cycles	Data from Addressed Memory Cell
$\overline{\text{CAS}}$ -Controlled Write Cycle (Early Write)	High-Z
$\overline{\text{WE}}$ -Controlled Write Cycle (Late Write)	Active, not valid
Read-Modify-Write Cycles	Data from Addressed Memory Cell
Fast Page Mode Read Cycle	Data from Addressed Memory Cell
Fast Page Mode Write Cycle (Early Write)	High-Z
Fast Page Mode Read-Modify-Write Cycle	Data from Addressed Memory Cell
$\overline{\text{RAS}}$ -only Refresh	High-Z
$\overline{\text{CAS}}$ -before- $\overline{\text{RAS}}$ Refresh Cycle	Data remains as in previous cycle
$\overline{\text{CAS}}$ -only Cycles	High-Z

**26/20-pin SOJ**

Dimension	Inches	Millimeters
A	0.672/0.684	17.069/17.374
B	0.125/0.135	3.175/3.429
C	0.082/0.093	2.083/2.362
D	0.332/0.342	8.433/8.687
E	0.296/0.304	7.518/7.722
F	0.255/0.275	6.477/6.985
G	0.018 Typ.	0.457 Typ.
H	0.05 Typ.	1.270 Typ.
J	0.026 Min.	0.660 Min.
K	0.028 Typ.	0.711 Typ.

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