

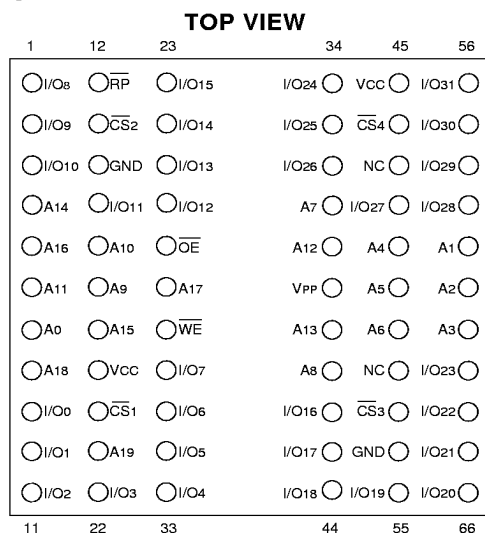


## 1Mx32 12V FLASH MODULE, SMD 5962-94613

### FEATURES

- Access Times of 100, 150ns
- Packaging:
  - 66-pin, PGA Type, 1.385 inch square, Hermetic Ceramic HIP (Package 402)
  - 68 lead, 40mm Low Profile CQFP, 3.5mm (0.140"), (Package 502)
  - 68 lead, Hermetic CQFP (G2), 22mm (0.880 inch) square (Package 500). Designed to fit JEDEC 68 lead 0.990" CQFJ footprint (Fig. 3)
- Sector Architecture
  - 16 equal size sectors of 64KBytes per each 1024Kx8 chip
  - Two step sequence of erase ensures that memory contents are not accidentally erased.
- 100,000 Erase/Program Cycles Minimum (0°C to 70°C)
- Organized as 1Mx32, user configurable as 2Mx16 or 4Mx8.
- Commercial, Industrial and Military Temperature Ranges
- 12 Volt Programming. 5V ± 10% Supply.
- Low Power CMOS, 3mA Standby Typical
- Automated Byte Write and Block Erase
  - Command User Interface
  - Status Register
- Built in Decoupling Caps and Multiple Ground Pins for Low Noise Operation
- Microsoft Flash File System (FFS)
- Weight
  - WF1M32-XG2X - 8 grams typical
  - WF1M32-XH2X - 13 grams typical
  - WF1M32-XG4TX - 20 grams typical

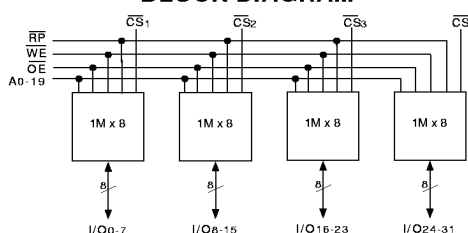
**FIG. 1 PIN CONFIGURATION FOR WF1M32-XH2X, SMD 5962-94613**

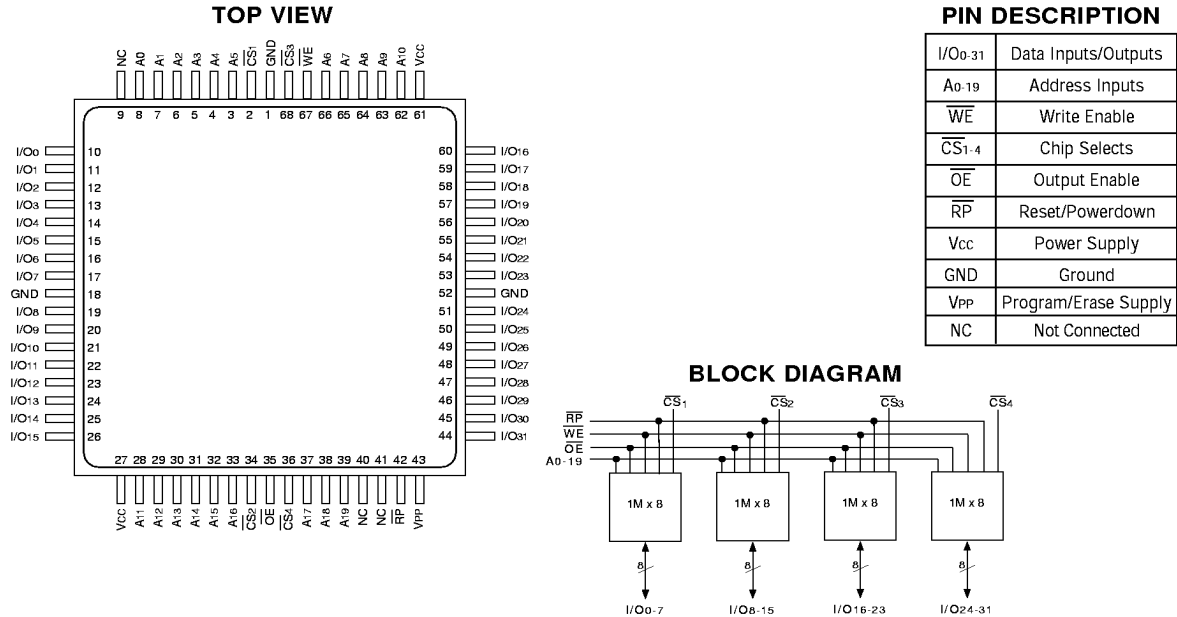
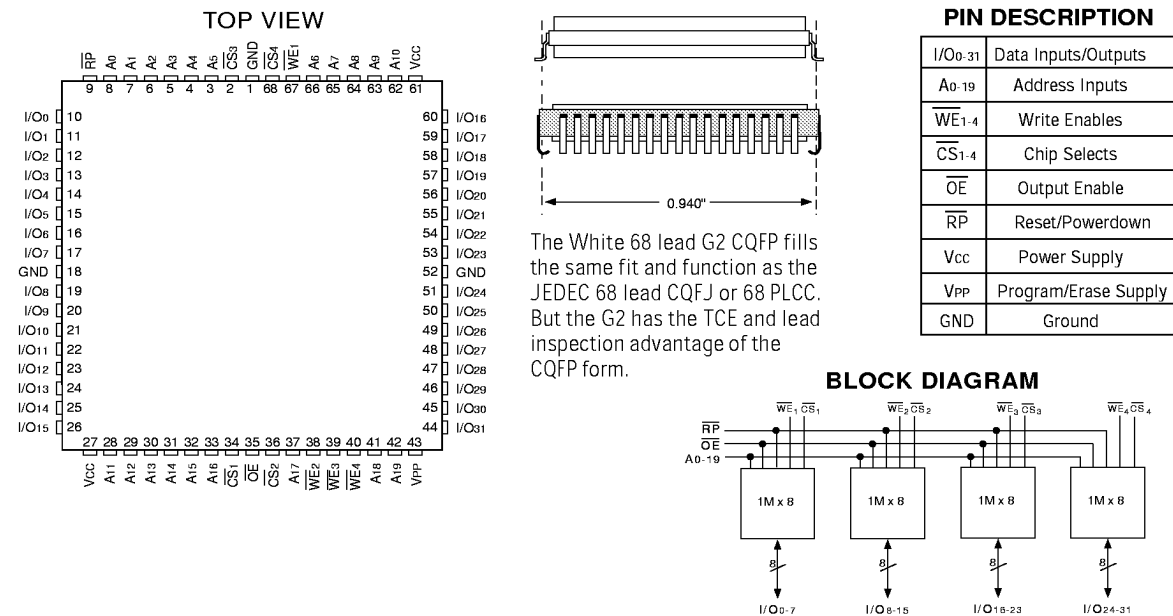


### PIN DESCRIPTION

I/O0-31	Data Inputs/Outputs
A0-19	Address Inputs
WE	Write Enable
CS1-4	Chip Selects
OE	Output Enable
RP	Reset/Powerdown
Vcc	Power Supply
VPP	Program/Erase Supply
GND	Ground
NC	Not Connected

### BLOCK DIAGRAM



**FIG. 2** PIN CONFIGURATION FOR WF1M32C-XG4TX, SMD 5962-94613**FIG. 3** PIN CONFIGURATION FOR WF1M32-XG2X, Package Under Development

**ABSOLUTE MAXIMUM RATINGS**

Parameter		Unit
Voltage on Any Pin with Respect to GND (except V <sub>CC</sub> and V <sub>PP</sub> )	-2.0 to +7.0	V
V <sub>PP</sub> Program Voltage with Respect to GND during Block Erase/Byte Write	-2.0 to +14.0	V
V <sub>CC</sub> Supply Voltage with Respect to GND	-2.0 to +7.0	V
Output Short Circuit Current	100	mA

**NOTES:**

1. Minimum DC voltage is -0.5V on input/output pins. During transitions, this level may undershoot to -2.0V for periods <20ns. Maximum DC voltage on input/output pins is V<sub>CC</sub> + 0.5V which, during transitions, may overshoot to V<sub>CC</sub> + 2.0V for periods <20 ns.
2. Maximum DC voltage on V<sub>PP</sub> may overshoot to +14.0V for periods <20 ns.
3. Output shorted for no more than one second. No more than one output shorted at a time.

Stresses above those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. This is a Stress rating only and functional operation of the device at these or any other conditions above those indicated in the operational sections of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

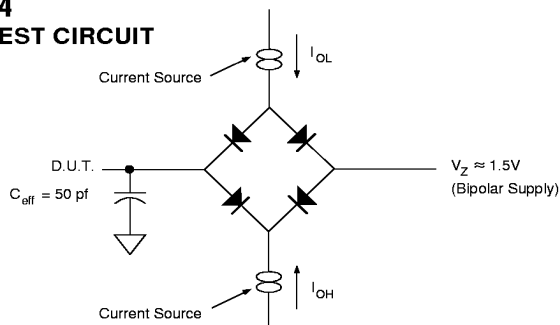
**RECOMMENDED OPERATING CONDITIONS**

Parameter	Symbol	Min	Max	Unit
Supply Voltage	V <sub>CC</sub>	4.5	5.5	V
Input High Voltage	V <sub>IH</sub>	2.0	V <sub>CC</sub> + 0.5	V
Input Low Voltage	V <sub>IL</sub>	-0.5	+0.8	V
Operating Temp. (Mil.)	T <sub>A</sub>	-55	+125	°C

**CAPACITANCE**(T<sub>A</sub> = +25°C)

Parameter	Symbol	Conditions	Max	Unit
OE capacitance	C <sub>OE</sub>	V <sub>IN</sub> = 0 V, f = 1.0 MHz	50	pF
WE <sub>1-4</sub> capacitance HIP (PGA)	C <sub>WE</sub>	V <sub>IN</sub> = 0 V, f = 1.0 MHz	50	pF
CQFP G4			50	
CQFP G2			20	
CS <sub>1-4</sub> capacitance	C <sub>CS</sub>	V <sub>IN</sub> = 0 V, f = 1.0 MHz	20	pF
Data I/O capacitance	C <sub>I/O</sub>	V <sub>I/O</sub> = 0 V, f = 1.0 MHz	20	pF
Address input capacitance	C <sub>AD</sub>	V <sub>IN</sub> = 0 V, f = 1.0 MHz	50	pF

This parameter is guaranteed by design but not tested.

**FIG. 4**  
**AC TEST CIRCUIT****AC TEST CONDITIONS**

Parameter	Typ	Unit
Input Pulse Levels	V <sub>IL</sub> = 0, V <sub>IH</sub> = 3.0	V
Input Rise and Fall	5	ns
Input and Output Reference Level	1.5	V
Output Timing Reference Level	1.5	V

**NOTES:**

V<sub>Z</sub> is programmable from -2V to +7V.  
I<sub>OL</sub> & I<sub>OIH</sub> programmable from 0 to 16mA.  
Tester Impedance Z<sub>0</sub> = 75 Ω.  
V<sub>Z</sub> is typically the midpoint of V<sub>OH</sub> and V<sub>OL</sub>.  
I<sub>OL</sub> & I<sub>OIH</sub> are adjusted to simulate a typical resistive load circuit.  
ATE tester includes jig capacitance.

**DC CHARACTERISTICS - CMOS COMPATIBLE**(V<sub>CC</sub> = 5.0V, V<sub>SS</sub> = 0V, T<sub>A</sub> = -55°C to +125°C)

Parameter	Symbol	Conditions	Min	Typ	Max	Unit
Input Leakage Current	I <sub>LI</sub>	V <sub>CC</sub> = 5.5, V <sub>IN</sub> = V <sub>CC</sub> to GND			10	μA
Output Leakage Current	I <sub>LO</sub>	V <sub>CC</sub> = 5.5, V <sub>OUT</sub> = V <sub>CC</sub> to GND			10	μA
V <sub>CC</sub> Standby Current (4)	I <sub>CCS</sub>	V <sub>CC</sub> = 5.5, $\overline{CS} = \overline{RP} = V_{IH}$ , f = 5MHz		3.0	10.0	mA
V <sub>CC</sub> Read Current	I <sub>CCR</sub>	V <sub>CC</sub> = 5.5, $\overline{CS} = V_{IL}$ , f = 5 MHz, I <sub>OUT</sub> = 0mA		80	180	mA
V <sub>CC</sub> Byte Write Current	I <sub>CCW</sub>	Byte Write in Progress, V <sub>PP</sub> = V <sub>PPH</sub> = 12.6V		30	160	mA
V <sub>CC</sub> Block Erase Current	I <sub>CCE</sub>	Block Erase in Progress, V <sub>PP</sub> = V <sub>PPH</sub> = 12.6V		30	160	mA
V <sub>CC</sub> Powerdown Current (4)	I <sub>CCD</sub>	$\overline{RP} = GND$ I <sub>OUT</sub>		8.0	200	μA
V <sub>PP</sub> Standby Current	I <sub>PPS</sub>	V <sub>PP</sub> < V <sub>CC</sub>		4	100	μA
V <sub>PP</sub> Deep Powerdown Current (4)	I <sub>PPD</sub>	$\overline{RP} = GND$		8	200	μA
V <sub>PP</sub> Write Current	I <sub>PPW</sub>	V <sub>PP</sub> = V <sub>PPH</sub> = 12.6V, Byte Write in Progress		40	200	mA
V <sub>PP</sub> Block Erase Current	I <sub>PPE</sub>	V <sub>PP</sub> = V <sub>PPH</sub> = 12.6V, Block Erase in Progress		40	200	mA
Output Low Voltage (4)	V <sub>OL</sub>	V <sub>CC</sub> = 4.5, I <sub>OL</sub> = 5.8 mA			0.45	V
Output High Voltage (4)	V <sub>OH</sub>	V <sub>CC</sub> = 4.5, I <sub>OH</sub> = -2.5 mA	2.4			V
V <sub>PP</sub> during Normal Operations (3)	V <sub>PLL</sub>		0.0		6.5	V
V <sub>PP</sub> during Erase/Write Operations	V <sub>PPH</sub>		11.4	12.0	12.6	V
V <sub>CC</sub> Erase/Write Lock Voltage	V <sub>LKO</sub>		2.0			V

**NOTES:**

1. All currents are in RMS unless otherwise noted. Typical values at V<sub>CC</sub> = 5.0V, V<sub>PP</sub> = 12.0V, T = 25°C. Valid for all speeds.
2. I<sub>CCES</sub> is specified with the device deselected. If the device is read while in erase suspend mode, current draw is the sum of I<sub>CCES</sub> and I<sub>CCR</sub>.
3. Block Erases/Byte Writes are inhibited when V<sub>PP</sub> = V<sub>PLL</sub> and not guaranteed in the range between V<sub>PPH</sub> and V<sub>PLL</sub>.
4.  $\overline{RP}$  is not available in WF1M32E-XXH.
5. DC test conditions V<sub>IL</sub> = 0.3V, V<sub>IH</sub> = V<sub>CC</sub> - 0.3V

**AC CHARACTERISTICS – WRITE/ERASE/PROGRAM OPERATIONS -  $\overline{WE}$  CONTROLLED**(V<sub>CC</sub> = 5.0V, V<sub>SS</sub> = 0V, T<sub>A</sub> = -55°C to +125°C)

Parameter	Symbol		<u>-100</u>		<u>-150</u>		Unit
			Min	Max	Min	Max	
Write Cycle Time	t <sub>AVAV</sub>	t <sub>WC</sub>	100		150		ns
Chip Select Setup Time	t <sub>ELWL</sub>	t <sub>CS</sub>	10		10		ns
Write Enable Pulse Width	t <sub>WLWH</sub>	t <sub>WP</sub>	40		40		ns
V <sub>PP</sub> Setup Time (1)	t <sub>VPWH</sub>	t <sub>VPS</sub>	100		100		ns
Address Setup Time	t <sub>AVWH</sub>	t <sub>AS</sub>	40		40		ns
Data Setup Time	t <sub>DVWH</sub>	t <sub>DS</sub>	40		40		ns
Data Hold Time	t <sub>WHDX</sub>	t <sub>DH</sub>	5		5		ns
Address Hold Time	t <sub>WHAX</sub>	t <sub>AH</sub>	5		5		ns
Chip Select Hold Time	t <sub>WHEH</sub>	t <sub>CH</sub>	10		10		ns
Write Enable Pulse Width High	t <sub>WHWL</sub>	t <sub>WPH</sub>	30		30		ns
Duration of Byte Write Operation (1,2,3)	t <sub>WHQV1</sub>		6		6		μs
Duration of Block Erase Operation (1,2,3)	t <sub>WHQV2</sub>		0.3		0.3		sec
Write Recovery before Read	t <sub>WHGL</sub>		0		0		μs
$\overline{RP}$ High Recovery Time (4)	t <sub>PHWL</sub>	t <sub>PS</sub>	1.0		1.0		μs

**NOTES:**

1. Guaranteed by design, not tested.
2. The on-chip Write State Machine incorporates all byte write and block erase functions and overhead of the flash memory, this includes byte program and verify, block precondition and verify, erase and verify.
3. Byte write and block erase durations are measured to completion (SR, 7 = 1). V<sub>PP</sub> should be held at V<sub>PPH</sub> until determination of byte write/block erase success (SR, 3/4/5 = 0).
4.  $\overline{RP}$  is not available in Wf1M32E-XHX.

**AC CHARACTERISTICS – WRITE OPERATION -  $\overline{CS}$  CONTROLLED <sup>(1)</sup>**(V<sub>CC</sub> = 5.0V, V<sub>SS</sub> = 0V, T<sub>A</sub> = -55°C to +125°C)

Parameter	Symbol		-100		-150		Unit
			Min	Max	Min	Max	
Write Enable Cycle Time	t <sub>AVAV</sub>	t <sub>WC</sub>	100		150		ns
Write Enable Setup Time	t <sub>WLEL</sub>	t <sub>WS</sub>	0		0		ns
Chip Select Pulse Width	t <sub>ELEH</sub>	t <sub>CP</sub>	60		60		ns
V <sub>PP</sub> Setup Time (1)	t <sub>VPEH</sub>	t <sub>VPS</sub>	100		100		ns
Address Setup Time	t <sub>AVEH</sub>	t <sub>AS</sub>	40		40		ns
Data Setup Time	t <sub>DVEH</sub>	t <sub>DS</sub>	40		40		ns
Data Hold Time	t <sub>EHDX</sub>	t <sub>DH</sub>	5		5		ns
Address Hold Time	t <sub>EHAX</sub>	t <sub>AH</sub>	5		5		ns
Write Enable Hold Time	t <sub>EHWH</sub>	t <sub>WH</sub>	0		0		ns
Chip Select Pulse Width High	t <sub>EHXL</sub>	t <sub>EPH</sub>	30		30		ns
Duration of Byte Write Operation (3)	t <sub>EHQV1</sub>		6		6		μs
Duration of Block Erase Operation (3)	t <sub>EHQV2</sub>		0.3		0.3		sec
Write Recovery before Read	t <sub>EHGL</sub>		0		0		μs
$\overline{RP}$ High Recovery to $\overline{CS}$ Low (4)	t <sub>PHXL</sub>	t <sub>PS</sub>	1		1		μs

**NOTES:**

1. Chip-Select Controlled Writes: Write operations are driven by the valid combination of  $\overline{CS}$  and  $\overline{WE}$ . In systems where  $\overline{CS}$  defines the write pulse width (within a longer  $\overline{WE}$  timing waveform), all setup, hold and inactive  $\overline{WE}$  times should be measured relative to the  $\overline{CS}$  waveform.
2. Guaranteed by design, not tested.
3. Byte write and block erase durations are measured to completion (SR.7 = 1, V<sub>OH</sub>). V<sub>PP</sub> should be held at V<sub>PPH</sub> until determination of byte write/block erase success (SR.3/4/5 = 0).
4.  $\overline{RP}$  available in WF1M32C-XG4X only.

**AC CHARACTERISTICS – READ-ONLY OPERATIONS**(V<sub>CC</sub> = 5.0V, V<sub>SS</sub> = 0V, T<sub>A</sub> = -55°C to +125°C)

Parameter	Symbol		-100		-150		Unit
			Min	Max	Min	Max	
Read Cycle Time	t <sub>AVAV</sub>	t <sub>RC</sub>	100		150		ns
Address Access Time	t <sub>AVQV</sub>	t <sub>ACC</sub>		100		150	ns
Chip Select to Output Valid (1)	t <sub>ELQV</sub>	t <sub>CE</sub>		100		150	ns
Output Enable to Output Valid (1)	t <sub>GLQV</sub>	t <sub>OE</sub>		50		70	ns
Chip Select to Output Low Z (2)	t <sub>ELQX</sub>	t <sub>LZ</sub>	0		0		ns
Chip Select High to Output High Z (2)	t <sub>EHQZ</sub>	t <sub>HZ</sub>		65		65	ns
Output Enable to Output Low Z (2)	t <sub>GLOX</sub>	t <sub>OLZ</sub>	0		0		ns
Reset to Output Valid (3)	t <sub>PHQV</sub>	t <sub>PWH</sub>		400		400	ns
Output EnableHigh to Output High Z (2)	t <sub>GHQZ</sub>	t <sub>DF</sub>		50		50	ns
Output Hold from Addresses, $\overline{CS}$ or $\overline{OE}$ Change, Whichever is First <sup>2</sup>		t <sub>OH</sub>	0		0		ns

**NOTES:**

1.  $\overline{OE}$  may be delayed up to t<sub>CE</sub>-t<sub>OE</sub> after the falling edge of  $\overline{CS}$  without impact on t<sub>CS</sub>.
2. Guaranteed by design, not tested.
3.  $\overline{RP}$  is not available in WF1M32E-XHX.



FIG. 5 AC WAVEFORMS FOR WRITE-ERASE-PHASE OPERATIONS,  $\overline{WE}$  CONTROLLED

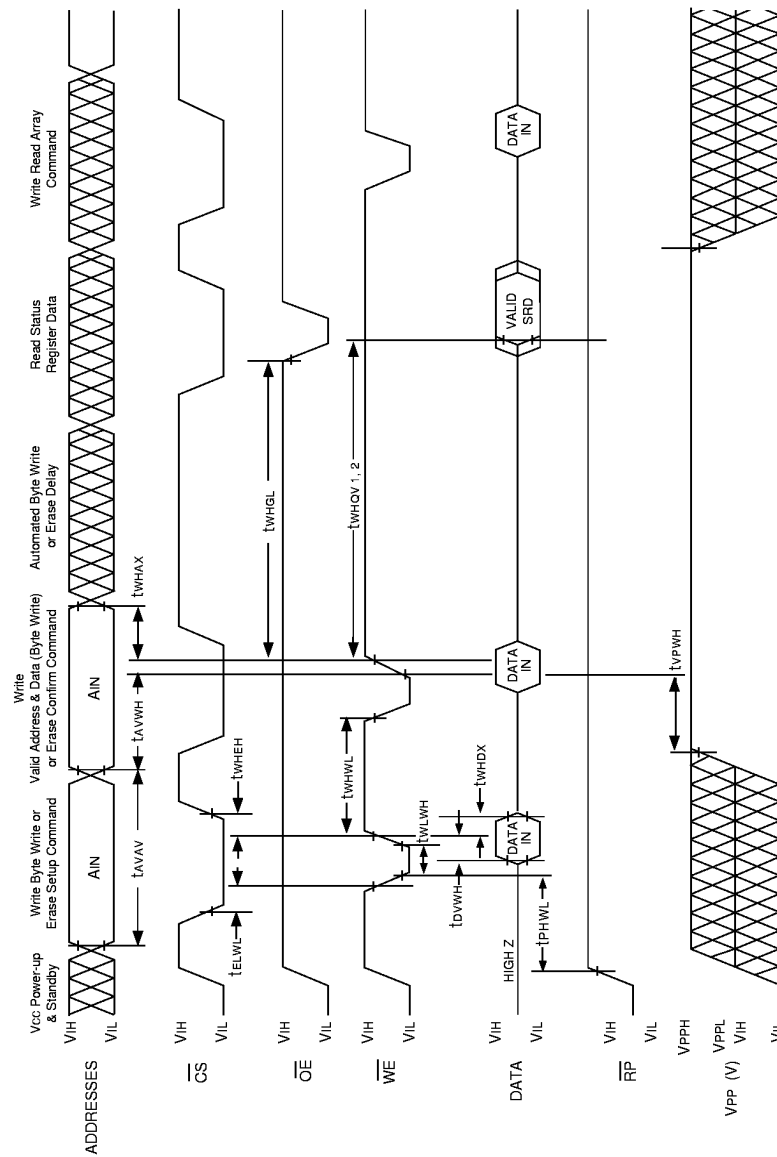
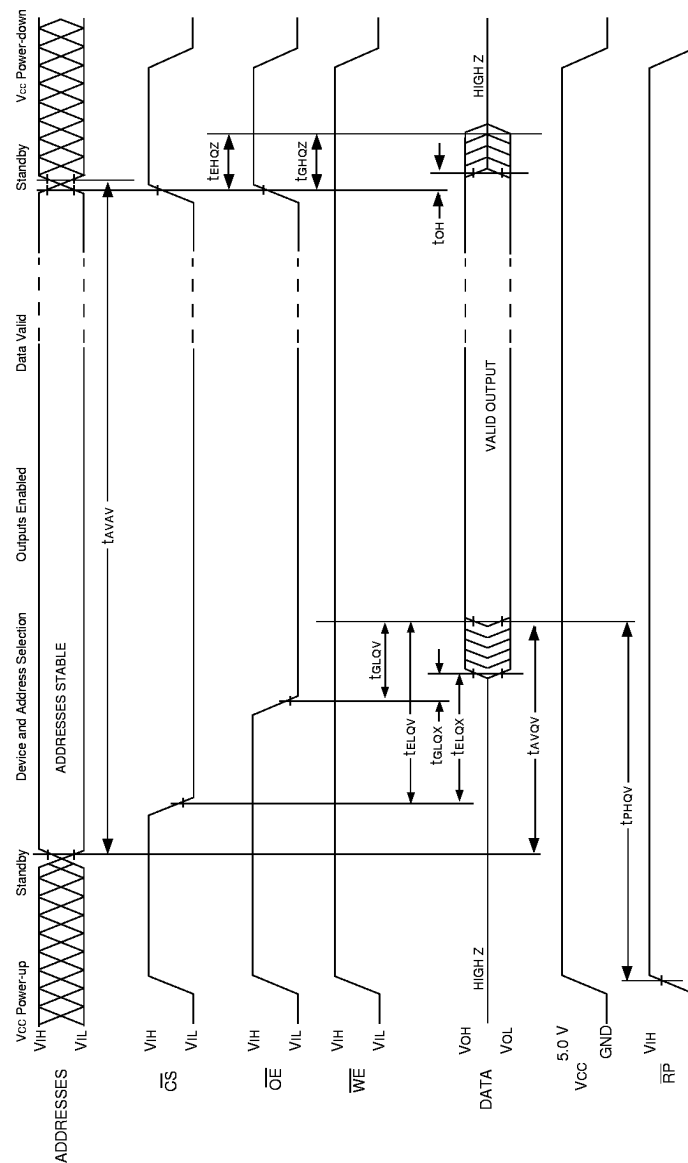








FIG. 7 AC WAVEFORM FOR READ OPERATIONS





## PRINCIPLES OF OPERATION

The following Principles of Operation of the WF1M32-XXX MCM is applicable to each of the four memory chips inside the MCM. Chip 1 is distinguished by  $\overline{CS}1$  and I/O0-7, Chip 2 by  $\overline{CS}2$  and I/O8-15, Chip 3 by  $\overline{CS}3$  and I/O16-23, and Chip 4 by  $\overline{CS}4$  and I/O24-31.

The WF1M32-XXX includes write automation to manage write and erase functions. The Write State Machine allows for 100% TTL-level control inputs; fixed power supplies during block erasure and byte write; and minimal processor overhead with RAM-like interface timings.

After initial device powerup the WF1M32-XXX functions as a read-only memory. Manipulation of external memory-control pins allow array read, standby and output disable operations. The status register can also be accessed through the command user interface when  $V_{PP} = V_{PPL}$ .

This same subset of operations is also available when high voltage is applied to the  $V_{PP}$  pin. In addition, high voltage on  $V_{PP}$  enables successful block erasure and byte writing of the device. Functions associated with altering memory contents—byte write, block erase—are accessed via the command user interface and verified thru the status register.

Commands are written using standard microprocessor write timings. Command user interface contents serve as input to the write status machine, which controls the block erase and byte write circuitry. Write cycles also internally latch addresses and data needed for byte write or block erase operations.

Interface software to initiate and poll progress of internal byte write and block erase can be stored in any of the blocks. This code is copied to, and executed from, system RAM during actual flash memory update. After successful completion of byte write and/or block erase, code/data reads from the device are again possible via the read array command. Erase suspend/resume capability allows system software to suspend block erase to read data and execute code from any other block.

## COMMAND USER INTERFACE AND WRITE AUTOMATION

An on-chip state machine controls block erase and byte write, freeing the system processor for other tasks. After receiving the Erase Setup and Erase Confirm commands, the state machine controls block pre-conditioning and erase, returning progress via the Status Register on each of the four memory chips in the MCM. Byte write is similarly controlled, after destination address and expected data are supplied.

## DATA PROTECTION

Depending on the application, the system designer may choose to make the  $V_{PP}$  power supply switchable (available only when memory byte writes/block erases are required) or hardwired to  $V_{PPH}$ . When  $V_{PP} = V_{PPL}$ , memory contents cannot be altered. Additionally, all functions are disabled whenever  $V_{CC}$  is below the write lockout voltage  $V_{LKO}$  or when  $RP$  is at  $V_{IL}$ . The two-step byte write/block erase command user interface write sequence provides additional software write protection.

## BUS OPERATION

Flash memory reads, erase and writes in-system via the local CPU. All bus cycles to or from the flash memory conform to standard microprocessor bus cycles.

## READ

The WF1M32-XXX can be read from any of its blocks, and information can be read from the status register of each chip selected.  $V_{PP}$  can be at either  $V_{PPL}$  or  $V_{PPH}$ .

The first task is to write the appropriate read mode command to the command user interface. The device automatically resets to read array mode upon initial device powerup or after exit from deep powerdown. Chip select  $\overline{CS}$  is the device selection control, and when active enables the selected memory device. Output Enable ( $\overline{OE}$ ) is the data input/output (I/O0-I/O31) direction control, and when active drives data from the select memory onto the I/O bus.  $RP$  and  $WE$  must also be at  $V_{IH}$ . Figure 7 illustrates read bus cycle waveforms.

## OUTPUT DISABLE

With  $\overline{OE}$  at a logic-high level ( $V_{IH}$ ), the device outputs are disabled. Output pins (I/O0-31) are placed in a high-impedance state.

## STANDBY

$\overline{CS}$  at a logic-high level ( $V_{IH}$ ) places the device in a standby mode. Standby operation disables much of the device's circuitry and substantially reduces device power consumption. The outputs (I/O0-31) are placed in a high-impedance state independent of the status of  $\overline{OE}$ . If the device is deselected during block erase or byte write, it will continue functioning and consuming normal active power until the operation is completed.



## WRITE

Writes to the command user interface enable reading of device data. They also control inspection and cleaning of the status register. Additionally, when  $V_{PP} = V_{PPH}$ , the command user interface controls block erasure and byte write. The contents of the interface register serve as input to the internal state machine.

The command user interface itself does not occupy an addressable memory location. The interface register is a latch used to store the command and address and data information needed to execute the command. Erase setup and erase confirm commands require both appropriate command data and an address within the block to be erased. The Byte Write Setup command requires both appropriate command data and the address of the location to be written, while the Byte Write command consists of the data to be written and the address of the location to be written.

The command user interface is written by bringing  $\overline{WE}$  to a logic-low level ( $V_{IL}$ ) while  $\overline{CS}$  is low. Address and data are latched on the rising edge of  $\overline{WE}$ . Standard microprocessor write timings are used.

Refer to AC Write Characteristics and the AC Waveforms for Write Operation, Figures 5 and 6, for specific timing parameters.

## COMMAND DEFINITIONS

When  $V_{PPL}$  is applied to the  $V_{PP}$  pin of the chip selected, read operations from the status register, or array blocks are enabled. Placing  $V_{PPH}$  on  $V_{PP}$  enables successful byte write and block erase operations as well.

Device operations are selected by writing specific commands into the command user interface of the chip selected. Table 2 defines the WF1M32-XXX commands.

## READ ARRAY COMMAND

Upon initial device powerup the device defaults to Read Array mode. This operation is also initiated by writing FFH into the command user interface. Microprocessor read cycles retrieve array data. The device remains enabled for reads until the command user interface contents are altered. Once the internal Write State Machine has started a block erase or byte write operation, the device will not recognize the Read Array command, until the WSM has completed its operation. The Read Array command is functional when  $V_{PP} = V_{PPL}$  or  $V_{PPH}$ .

TABLE 1 - BUS OPERATIONS

Mode	$\overline{RP}$	$\overline{CS}$	$\overline{OE}$	$\overline{WE}$	$V_{PP}$	I/O0-31
Read (1,2,4)	$V_{IH}$	$V_{IL}$	$V_{IL}$	$V_{IH}$	X	DOUT
Output Disable (4)	$V_{IH}$	$V_{IL}$	$V_{IH}$	$V_{IH}$	X	High Z
Standby (4)	$V_{IH}$	$V_{IH}$	X	X	X	High Z
Deep Powerdown	$V_{IL}$	X	X	X	X	High Z
Write (3,4)	$V_{IH}$	$V_{IL}$	$V_{IH}$	$V_{IL}$	X	DIN

### NOTES:

1. Refer to DC Characteristics. When  $V_{PP} = V_{PPL}$ , memory contents can be read but not written or erased.
2. X can be  $V_{IL}$  or  $V_{IH}$  for control pins and  $V_{PPL}$  or  $V_{PPH}$  for  $V_{PP}$ . See DC Characteristics for  $V_{PPL}$  and  $V_{PPH}$  voltages.
3. Command writes involving block erase or byte write are only successfully executed when  $V_{PP} = V_{PPH}$ .
4.  $\overline{RP}$  is not available in WF1M32E-XHX.

TABLE 2 - COMMAND DEFINITIONS

Command	Bus Cycles Req'd	First Bus Cycle			Second Bus Cycle		
		Operation	Address	Data	Operation	Address	Data
Read Array/Reset	1	Write	X	FFH			
Read Status Register	2	Write	X	70H	Read	X	SRD
Clear Status Register	1	Write	X	50H			
Erase Setup/Erase Confirm	2	Write	BA <sup>1</sup>	20H	Write	BA <sup>1</sup>	DOH
Erase Suspend/Erase Resume	2	Write	X	BOH	Write	X	DOH
Byte Write Setup/Write	2	Write	WA <sup>1</sup>	40H <sup>3</sup>	Write	WA <sup>1</sup>	WD <sup>2</sup>
Alternate Byte Write Setup/Write	2	Write	WA <sup>1</sup>	10H <sup>3</sup>	Write	WA <sup>1</sup>	WD <sup>2</sup>

### NOTES:

1. BA = Address within the block being erased. WA = Address of memory location to be written.
2. SRD = Data read from status register. See Table 3 for a description of the status register bits. WD = Data to be written at location WA. Data is latched on the rising edge of  $\overline{WE}$ .
3. Either 40H or 10H are recognized by the WSM as the Byte Write Setup command.

**TABLE 3**  
**STATUS REGISTER DEFINITIONS**

WSMS	ESS	ES	BWS	VPPS	R	R	R
7	6	5	4	3	2	1	0

**SR.7 = WRITE STATE MACHINE STATUS**

- 1 = Ready
- 0 = Busy

**SR.6 = ERASE SUSPENDED STATUS**

- 1 = Erase Suspended
- 0 = Erase in Progress/Completed

**SR.5 = ERASE STATUS**

- 1 = Error in Block Erasure
- 0 = Successful Block Erase

**SR.4 = BYTE WRITE STATUS**

- 1 = Error in Byte Write
- 0 = Successful Byte Write

**SR.3 = VPP STATUS**

- 1 = VPP Low Detect; Operation Abort
- 0 = VPP OK

**SR.2-SR.0 = RESERVED FOR FUTURE ENHANCEMENTS**

These bits are reserved for future use and should be masked out when polling the status register.

**NOTES:**

The Write State Machine Status bit must first be checked to determine byte write or block erase completion, before the Byte Write or Erase Status bit are checked for success.

If the Byte Write and Erase Status bits are set to "1"s during a block erase attempt, an improper command sequence was entered. Attempt the operation again.

If VPP low status is detected, the status register must be cleared before another byte write or block erase operation is attempted.

The VPP Status bit, unlike an A/D converter, does not provide continuous indication of VPP level. The WSM interrogates the VPP level only after the byte write or block erase command sequences have been entered and informs the system if VPP has not been switched on. The VPP Status bit is not guaranteed to report accurate feedback between V<sub>PPL</sub> and V<sub>PPH</sub>.

**READ STATUS REGISTER COMMAND**

Each chip of the WF1M32-XXX contains a status register which may be read to determine when a byte write or block erase operation is complete, and whether that operation completed successfully. The status register may be read at any time by writing the read status register command (70H) to the command user interface. After writing this command, all subsequent read operations output data from the status register, until another valid command is written to the command user interface. The contents of the status register are latched on the falling edge of OE or CS, whichever occurs last in the read cycle. OE or CS must be toggled to VIH before further reads to update the status register latch. The read status register command functions when VPP = V<sub>PPL</sub> or V<sub>PPH</sub>.

**CLEAR STATUS REGISTER COMMAND**

The erase status and byte write status bits are set to "1"s by the Write State Machine on each chip and can only be reset by the clear status register command. These bits indicate various failure conditions (see Table 3). By allowing system software to control the resetting of these bits, several operations may be performed (such as cumulatively writing several bytes or erasing multiple blocks in sequence). The status register may then be polled to determine if an error occurred during that sequence. This adds flexibility to the way the device may be used.

Additionally, the VPP Status bit (SR.3) of the chip selected MUST be reset by system software before further byte writes or block erases are attempted. To clear the status register, the clear status register command (50H) is written to the command user interface. The clear status register command is functional when VPP = V<sub>PPL</sub> or V<sub>PPH</sub>.

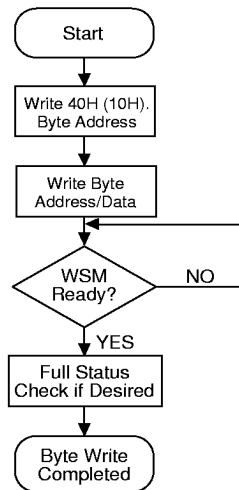
**ERASE SETUP/ERASE CONFIRM COMMANDS**

Erase is executed one block at a time, initiated by a two-cycle command sequence. An erase setup command (20H) is first written to the command user interface, followed by the Erase Confirm command (DOH). These commands require both appropriate sequencing and address within the block to be erased to FFH. Block preconditioning, erase and verify are all handled internally by the Write State Machine, invisible to the system. After the two command erase sequence is written to it, the WF1M32-XXX automatically outputs status register data when read (see Figure 9; Block Erase Algorithm). The CPU can detect the completion of the erase event by analyzing the output of the WSM Status bit of the status register.

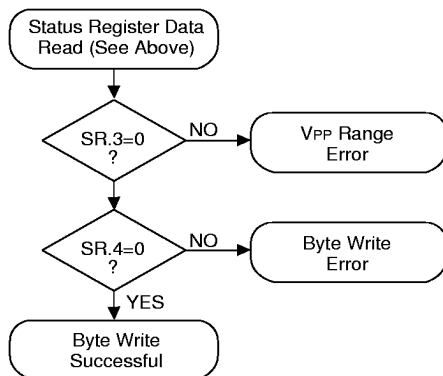


FIG. 8

## AUTOMATED BYTE WRITE ALGORITHM



## FULL STATUS CHECK PROCEDURE



Bus Operation	Command	Comments
Write	Byte Write Setup	Data = 40H (10H) Address = Byte to be Written
Write	Byte Write	Data to be written Address = Byte to be Written
Standby/Read		Check WSMS bit V <sub>OH</sub> = Ready, V <sub>OL</sub> = Busy or Read Status Register Check SR.7 1 = Ready, 0 = Busy Toggle OE or CS to update Status Register

Repeat for subsequent bytes

Full status check can be done after each byte or after a sequence of bytes

Write FFH after the last byte write operation to reset the device to Ready Array Mode

Bus Operation	Command	Comments
Optional Read		CPU may already have read Status Register data in WSM Ready polling above
Standby		Check SR.3 1 = V <sub>PP</sub> Low Detect
Standby		Check SR.4 Both 1 = Byte Write Error

SR.3 MUST be cleared, if set during a block erase attempt, before further attempts are allowed by the Write State Machine.

SR.4 is only cleared by the clear status register command, in cases where multiple bytes are written before full status is checked.

If error is detected, clear the status register before attempting retry or other error recovery.



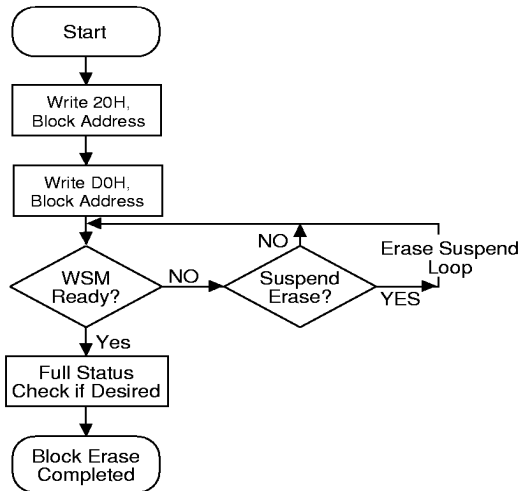
When erase is completed, the Erase Status bit should be checked. If erase error is detected, the status register should be cleared. The command user interface remains in read status register mode until further commands are issued to it.

This two-step sequence of set-up followed by execution ensures that memory contents are not accidentally erased. Also, reliable block erase can only occur when  $V_{PP} = V_{PPH}$ . In the absence of this high voltage, memory contents are protected against erasure. If block erase is attempted while  $V_{PP} = V_{PPL}$ , the  $V_{PP}$  status bit will be set to "1". Erase attempts while  $V_{PPL} < V_{PP} < V_{PPH}$  produce spurious results and should not be attempted.

### **BYTE WRITE SETUP/WRITE COMMANDS**

Byte write is executed by a two-command sequence. The byte write setup command (40H) is written to the command user interface of the chip selected, followed by a second write specifying the address and data (latched on the rising edge of WE) to be written. The WSM then takes over, controlling the byte write and write verify algorithms internally. After the two-command byte write sequence is written to it, the device automatically outputs status register data when read (see Figure 8; Byte Write Algorithm). The CPU can detect the completion of the byte write event by analyzing the output of the WSM Status bit of the status register. Only the read status register command is valid while byte write is active.

When byte write is complete, the byte write status bit should be checked. If byte write error is detected, the status register should be cleared. The internal WSM verify only detects errors for "1"s that do not successfully write to "0"s. The command user interface remains in read status register mode until further commands are issued to it. If byte write is attempted while  $V_{PP} = V_{PPL}$ , the  $V_{PP}$  status bit will be set to "1". Byte write attempts while  $V_{PPL} < V_{PP} < V_{PPH}$  produce spurious results and should not be attempted.

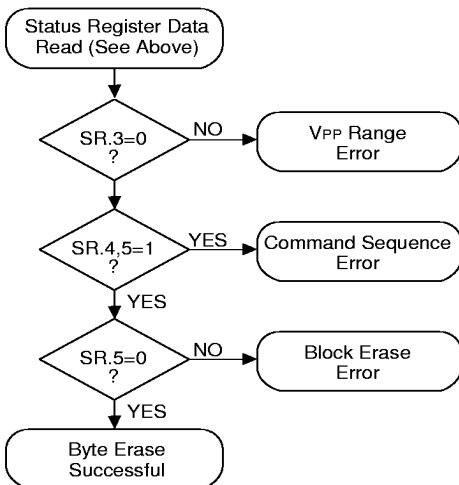
**FIG. 9**  
**AUTOMATED BLOCK ERASE ALGORITHM**

Bus Operation	Command	Comments
Write	Erase Setup	Data = 20H Address = Within block to be erased
Write	Erase	Data = D0H Address = Within block to be erased
Standby/Read		Check WSMS bit V <sub>OH</sub> = Ready, V <sub>OL</sub> = Busy or Read Status Register Check SR.7 1 = Ready, 0 = Busy Toggle $\overline{OE}$ or $\overline{CS}$ to update Status Register

Repeat for subsequent bytes

Full status check can be done after each byte or after a sequence of bytes

Write FFH after the last byte write operation to reset the device to Ready Array Mode

**FULL STATUS CHECK PROCEDURE**

Bus Operation	Command	Comments
Optional Read		CPU may already have read Status Register data in WSM Ready polling above
Standby		Check SR.3 1 = V <sub>PP</sub> Low Detect
Standby		Check SR.4, 5 Both 1 = Command Sequence Error
Standby		Check SR.5 1 = Block Erase Error

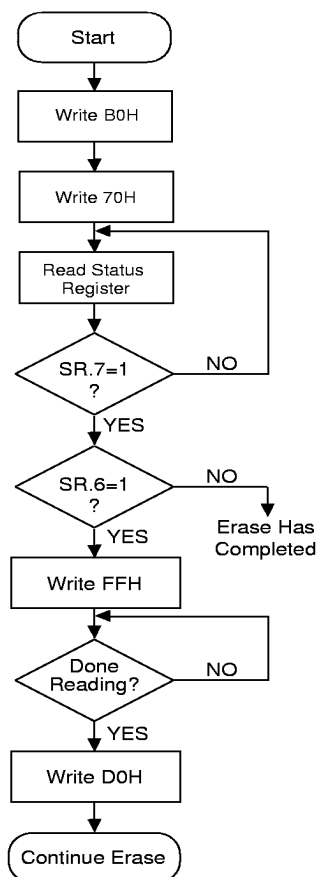
SR.3 MUST be cleared, if set during a block erase attempt, before further attempts are allowed by the Write State Machine.

SR.5 is only cleared by the clear status register command, in cases where multiple bytes are written before full status is checked.

If error is detected, clear the status register before attempting retry or other error recovery.



**FIG. 10**  
**ERASE SUSPEND/RESUME ALGORITHM**



Bus Operation	Command	Comments
Write	Erase Suspend	Data = B0H
Write	Read Status Register	Data = 70H
Standby/Read		Check Read Status Register
		Check SR.7 1 = Ready, 0 = Busy Toggle $\overline{OE}$ or $\overline{CS}$ to update Status Register
Standby		Check SR.6 1 = Suspended
Write	Read Array	Data = FFH
Read		Read array data from block other than that being erased.
Write	Erase Resume	Data = D0H





## ERASE SUSPEND/ERASE RESUME COMMANDS

The erase suspend command allows block erase interruption in order to read data from another block of memory. Once the erase process starts, writing the erase suspend command (B0H) to the command user interface requests that the WSM suspend the erase sequence at a predetermined point in the erase algorithm. The WF1M32-XXX continues to output status register data when read, after the erase suspend command is written to it. Polling the WSM status and erase suspend status bits will determine when the erase operation has been suspended (both will be set to "1").

At this point, a read array command can be written to the command user interface to read data from blocks other than that which is suspended. The only other valid commands at this time are read status register (70H) and erase resume (D0H), at which time the WSM will continue with the erase process. The erase suspend status and WSM status bits of the status register will be automatically cleared. After the erase resume command is written to it, the device automatically outputs status register data when read (see Figure 10).  $V_{PP}$  must remain at  $V_{PPH}$  while in erase suspend.

## VCC, VPP, $\overline{RP}$ TRANSITIONS AND THE COMMAND/STATUS REGISTERS

Byte write and block erase completion are not guaranteed if  $V_{PP}$  drops below  $V_{PPH}$ . If the  $V_{PP}$  Status bit of the Status Register (SR.3) is set to "1", a Clear Status Register command MUST be issued before further byte write/block erase attempts are allowed by the WSM. Otherwise, the Byte Write (SR.4) or Erase (SR.5) Status bits of the Status Register will be set to "1"s if error is detected.  $\overline{RP}$  transitions to  $V_{IL}$  during byte write and block erase also abort the operations. Data is partially altered in either case, and the command sequence must be repeated after normal operation is restored. Device poweroff, or  $\overline{RP}$  transitions to  $V_{IL}$ , clear the Status Register to initial value 10000 for the upper 5 bits.

The Command User Interface latches commands as issued by system software and is not altered by  $V_{PP}$  or  $\overline{CS}$  transitions or WSM actions. Its state upon powerup, after exit from deep powerdown or after  $V_{CC}$  transitions below  $V_{LKO}$ , is Read Array Mode.

After byte write or block erase is complete, even after  $V_{PP}$  transitions down to  $V_{PPL}$ , the Command User interface must be reset to Read Array mode via the Read Array command if access to the memory array is desired.

NOTE:  $\overline{RP}$  is not available in WF1M32E-XHX.

## POWER UP/DOWN PROTECTION

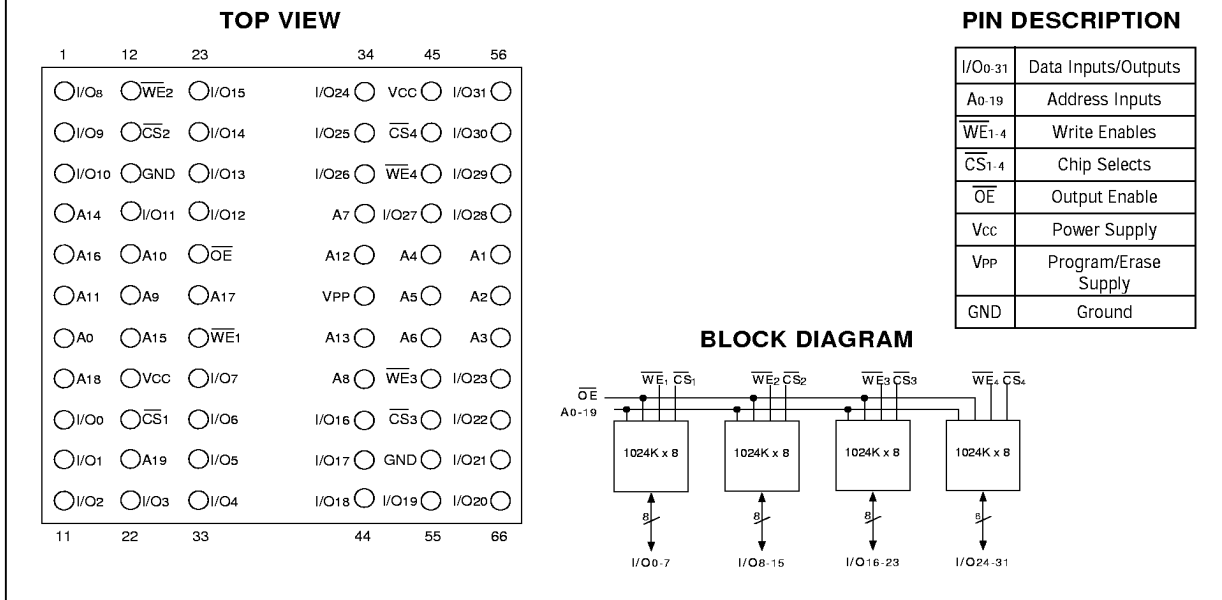
The WF1M32-XXX is designed to offer protection against accidental block erasure or byte writing during power transitions. Upon power-up, the device is indifferent as to which power supply,  $V_{PP}$  or  $V_{CC}$ , powers up first. Power supply sequencing is not required. Internal circuitry in the device ensures that the Command User interface is reset to the Read Array mode on power up.

## POWERDOWN AND RESET

The WF1M32-XG4X offers a deep power-down feature, entered when  $\overline{RP}$  is a  $V_{IL}$ . During read modes,  $\overline{RP}$ -low deselects the memory, places output drivers in a high-impedance state and turns off all internal circuits. The device requires time  $t_{PWH}$  (see AC Characteristics-Read-Only Operations) after return from powerdown until initial memory access outputs are valid. After this wakeup interval, normal operation is restored. The Command User Interface is reset to Read Array, and the upper 5 bits of the Status Register are cleared to value 10000, upon return to normal operation.

During block erase or bytewrite modes,  $\overline{RP}$  low will abort either operation. Memory contents of the block being altered are no longer valid as the data will be partially written or erased. Time  $t_{PS}$  after  $\overline{RP}$  goes to logic-high ( $V_{IH}$ ) is required before another command can be written.

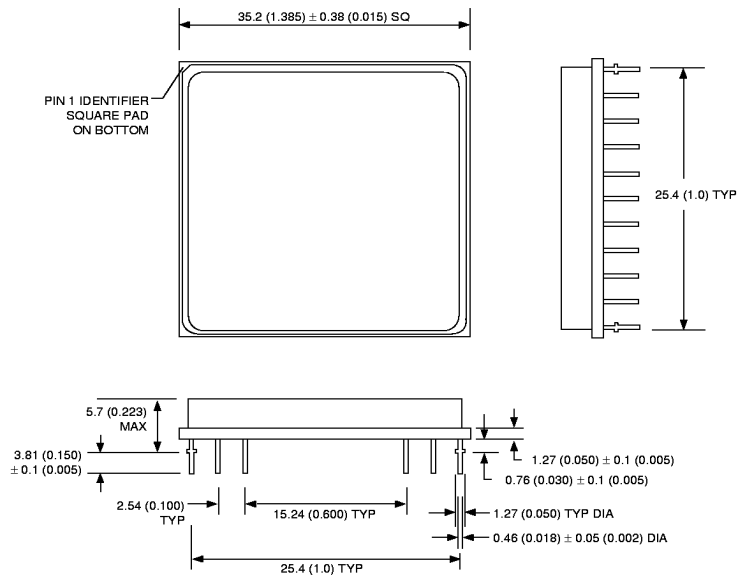
This use of  $\overline{RP}$  during system reset is important with automated write/erase devices. When the system comes out of reset it expects to read from the flash memory. Automated flash memories provide status information when accessed during write/erase modes. If a CPU reset occurs with no flash memory reset, proper CPU initialization would not occur because the flash memory would be providing the status information instead of array data. These flash memories allow proper CPU initialization following a system reset through the use of the  $\overline{RP}$  input. In this application  $\overline{RP}$  is controlled by the same RESET signal that resets the system CPU.

**FIG. 10 PIN CONFIGURATION FOR WF1M32E-XH2X****PIN DESCRIPTION**

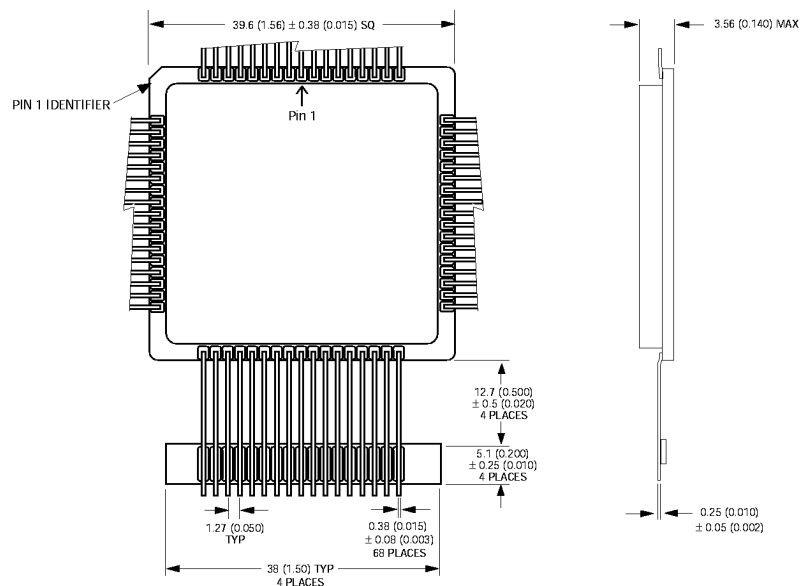
I/O <sub>0</sub> -31	Data Inputs/Outputs
A <sub>0</sub> -19	Address Inputs
$\overline{\text{WE}}_1$ -4	Write Enables
$\overline{\text{CS}}_1$ -4	Chip Selects
$\overline{\text{OE}}$	Output Enable
V <sub>CC</sub>	Power Supply
V <sub>PP</sub>	Program/Erase Supply
GND	Ground

**PIN CONFIGURATION OPTIONS**

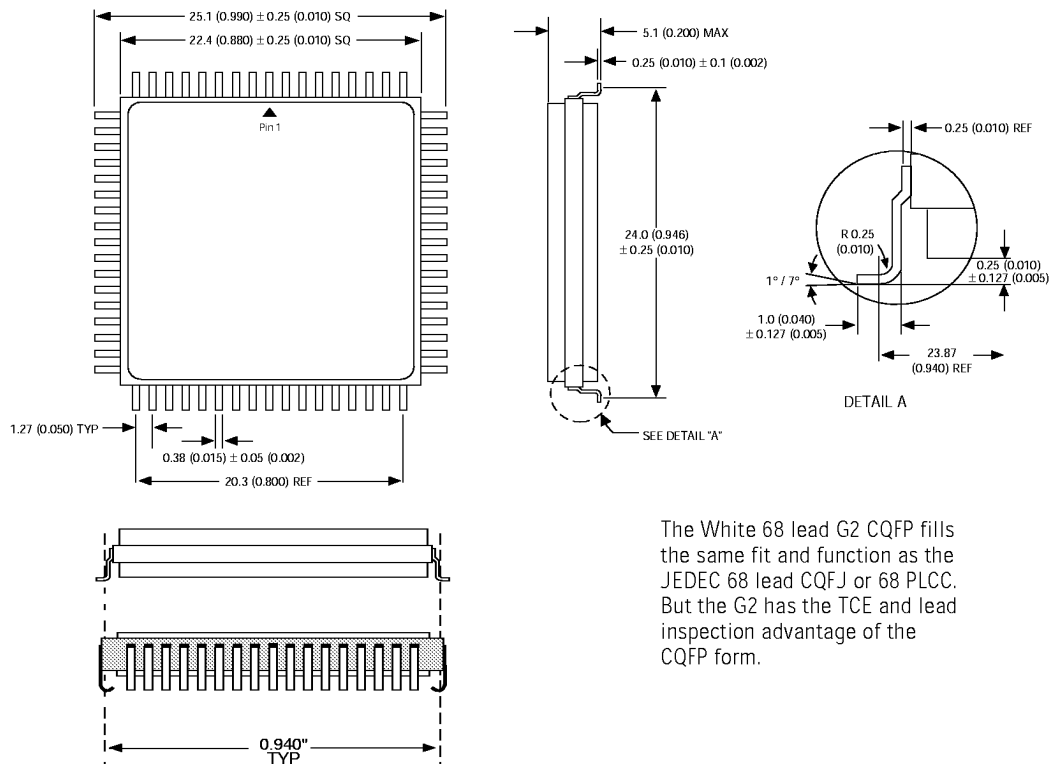
Package	Pin Configuration Option(s)	WM Part Number
HIP (PGA)	4 $\overline{\text{CS}}$ , 1 $\overline{\text{WE}}$ , $\overline{\text{RP}}$ (FIG. 1)	WF1M32-XH2X
	4 $\overline{\text{CS}}$ , 4 $\overline{\text{WE}}$ (FIG. 10)	WF1M32E-XH2X
CQFP (G4)	4 $\overline{\text{CS}}$ , 1 $\overline{\text{WE}}$ , $\overline{\text{RP}}$ (FIG. 2)	WF1M32C-XG4X
Low Profile CQFP (G4T)	Upgradable to 2M x 32 and 4M x 32 in the same footprint	WF1M32C-XG4TX
CQFP (G2)	4 $\overline{\text{CS}}$ , 4 $\overline{\text{WE}}$ , $\overline{\text{RP}}$ (FIG. 3)	WF1M32-XG2X

**PACKAGE 402: 66 PIN, PGA TYPE, CERAMIC HEX-IN-LINE PACKAGE, HIP (H2)**

ALL LINEAR DIMENSIONS ARE MILLIMETERS AND PARENTHETICALLY IN INCHES

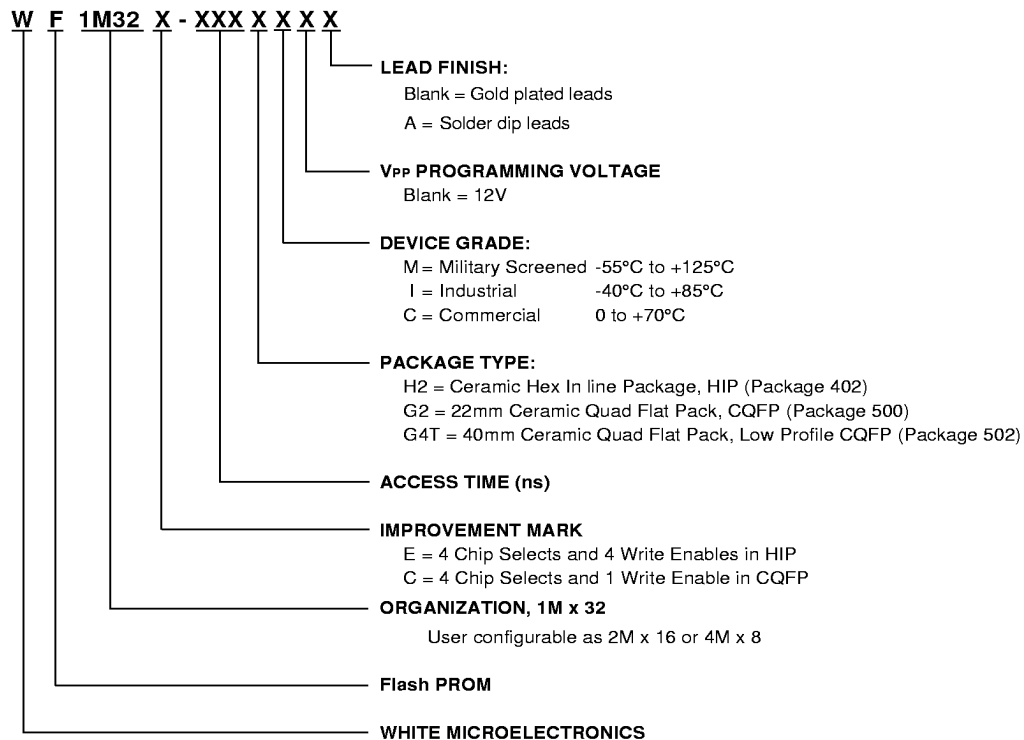
**PACKAGE 502: 68 LEAD, CERAMIC QUAD FLAT PACK, LOW PROFILE CQFP (G4T)**

ALL LINEAR DIMENSIONS ARE MILLIMETERS AND PARENTHETICALLY IN INCHES

**PACKAGE 500: 68 LEAD, CERAMIC QUAD FLAT PACK, CQFP (G2)**

The White 68 lead G2 CQFP fills the same fit and function as the JEDEC 68 lead CQFJ or 68 PLCC. But the G2 has the TCE and lead inspection advantage of the CQFP form.

ALL LINEAR DIMENSIONS ARE MILLIMETERS AND PARENTHETICALLY IN INCHES

**ORDERING INFORMATION**

DEVICE TYPE	SPEED	PACKAGE	SMD NO.
1M x 32 Flash	150ns	66 pin HIP (H2)	5962-94613 01HXX
1M x 32 Flash	100ns	66 pin HIP (H2)	5962-94613 02HXX
1M x 32 Flash	150ns	68 lead CQFP, Low Profile (G4T)	5962-94613 01HZX
1M x 32 Flash	100ns	68 lead CQFP, Low Profile (G4T)	5962-94613 02HZX