

HIGH VOLTAGE DUTY CYCLE CONTROLLER

SGS-THOMSON

30E D

ADVANCE DATA

- INTEGRATED 450V POWER DARLINGTON
- OUTPUT CURRENT UP TO 5A
- HIGH IMPEDANCE DIFFERENTIAL INPUTS
- PROGRAMMABLE DRIVER CURRENT
- DUTY CYCLE CONTROL LINEARITY WITHIN 1.5%
- SWITCHING FREQUENCY UP TO 100 kHz
- THERMAL PROTECTION
- INTEGRATED PROTECTION AT COMPARATOR INPUTS
- MINIMUM EXTERNAL COMPONENT COUNT

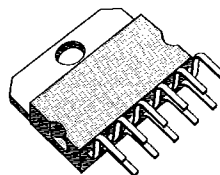
The VB100 is a monolithic integrated circuit which acts as a fully independent duty cycle controller with high voltage, high current open collector darlington output.

It is made using the innovative VI Power M1 technology merging a high voltage vertical discrete Darlington transistor together with bipolar control circuitry.

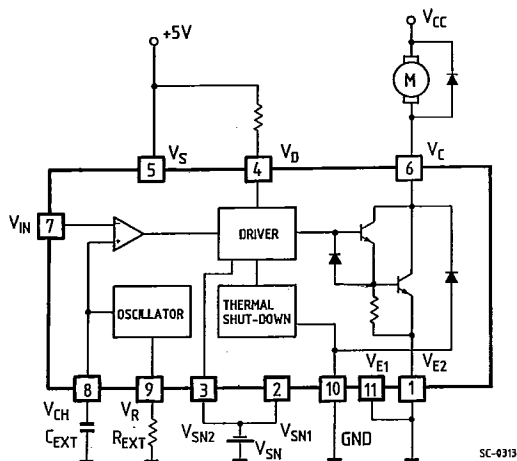
The VB100 is mainly intended as a D.C. motor and high voltage inductive load driver. It is able to adjust the output voltage duty cycle as a function of the input control voltage, at a switching frequency set by an internal stable sawtooth generator.

Built in thermal shut down switches off the power Darlington whenever the junction temperature exceeds an internally set value, typically 150°C with a 5V supply.

MULTIWATT-11



TEST AND APPLICATION CIRCUIT



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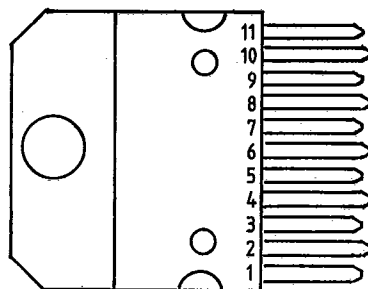
ABSOLUTE MAXIMUM RATINGS

V_{CE}	Power Darlington collector voltage	450	V
I_C	Power Darlington collector current	8	A
V_D	Driver stage supply voltage	15	V
V_S	Control stage supply voltage	15	V
I_D	Driver stage current	350	mA
V_{IN}, V_{NI}	Comparator input voltage	V_S to -10	V
P_{tot}	Power dissipation	internally limited	
T_{op}	Junction operating temperature	-45 to 150	°C
T_{stg}	Storage temperature	-55 to 150	°C

THERMAL DATA

$R_{thj - case}$	Thermal resistance junction-case	max	3.0	°C/W
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CONNECTION DIAGRAM (Top view)



TAB CONNECTED TO PIN 6

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PIN FUNCTION

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



N°	NAME	FUNCTION
1	V_{E1} High voltage Darlington emitter	Output stage ground n.1. It must be short circuited with V_{E2} ; if no current sensing is used, a filtering capacitor must be provided between this pin and the high voltage supply. If current sensing is required, a shunt resistor can be connected between pin V_{E1} and V_{E2} and power ground and the filtering capacitor must be connected between ground and high voltage supply.
2	V_{SN1} Signal negative supply voltage	This pin is connected to the PWM ground and to the control circuit substrate. Supply range is from 0 to $-5V$. The applied negative supply voltage must be the most negative voltage of the device and must be the same voltage of pin V_{SN2} .
3	V_{SN2} High current negative supply voltage	This pin is connected to the driver ground. Supply range is from 0 to $-5V$. An applied negative supply, speeds-up the output Darlington.
4	V_D Driver stage supply voltage	This pin supplies the base current for the darlington driver during t_{ON} (output darlington on-time) $I_{D(on)} = (V_S - V_{D(sat)})/R_D$
5	V_S Control circuit power supply	Supply voltage input. Being the internal reference voltage taken from V_S a $5V \pm 5\%$ D.C. supply is required.
6	V_C High voltage output collector	This pin is internally connected to package header. It is the high voltage open collector output.
7	V_{IN} Inverting input	Input of the PWM comparator. A D.C. value between V_{CHL} and V_{CHH} sets the output duty cycle from minimum to maximum value.
8	V_{CH} Non inverting input	Non inverting input of the PWM comparator and external capacitance pin. The capacitance C_{EXT} (together with R_{EXT}) fixes the sawtooth generator frequency (f_{osc}). A low leakage capacitance is necessary for a linear operation. The relationship between frequency and C_{EXT} R_{EXT} is: $f_{osc} \approx 1.1/(R_{EXT} \times C_{EXT})$
9	V_R Biasing Resistor	It fixes the current I_{ch} of the current generator which changes according to the following relation: $I_{ch} = 0.56 \times V_S/R_{EXT}$
10	GND Analog ground	It is the control circuit ground: for a reliable circuit operation only few millivolt drop ($< 10mV$) are allowed between this pin and C_{EXT} , R_{EXT} common point.
11	V_{E2} High voltage darlington emitter	Output stage ground n 2. It must be short circuited with V_{E1} ; if no current sensing is used, a filtering capacitor must be provided between this pin and the high voltage supply. If current sensing is required, a shunt resistor can be connected between pins V_{E1} and V_{E2} and power ground and a filtering capacitor must be connected between power ground and high voltage supply.

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ELECTRICAL CHARACTERISTICS: $V_S = 5V$; $V_{CC} = 300V$; $V_A = 2V$; $V_B = 0V$; $R_{IN} = 10k\Omega$; $R_{EXT} = 50k\Omega$; $R_{CC} = 88\Omega$; $R_D = 330\Omega$; $R_{CH} = 100\Omega$; $T_C = T_{case} = 25^\circ C$

See fig. 1. - unless otherwise specified.

Parameters	Test Conditions	Min.	Typ.	Max.	Unit
V_{CE} Voltage between pins 6 and 1		450			V
I_C (leak) High voltage collector leakage current	$V_{CC} = 350 V$			1	mA
V_{CE} (sat) Saturation voltage of the output Darlington (between pins 6 and 1)	$V_B = 2 V$ $I_C = 3 A$ $I_C = 5 A$ $V_A = 0$ $I_D = 150 mA$ $I_D = 250 mA$		2.5 2.7	2.9 3.3	V V
V_D (sat) Saturation voltage between pins 4 and 1	$V_B = 2 V$ $I_D = 50 mA$ $V_A = 0$ $I_C = 2A$		2.8	3.5	V
V_S Control circuit power supply		4.75	5.0	5.25	V
I_S off Control circuit current		20	30	45	mA
I_S on Control circuit current	$V_B = 2 V$ $V_A = 0$	2.5	6	10	mA
V_{inTHH} PWM comparator high threshold	$V_B = 2 V$ $T_C = -40$ to $130^\circ C$ $V_A = 0 \rightarrow 3 V$  (see fig. 2)	0		120	mV
V_{inTHL} PWM comparator low threshold	$V_B = 2 V$ $T_C = -40$ to $130^\circ C$ $V_A = 3 V \rightarrow 0 V$  (see fig. 2)	100		260	mV
$V_{inTH(hyst.)}$ PWM comparator hysteresis	$V_B = 2 V$ $T_C = -40$ to $130^\circ C$ (see fig. 2)	50		250	mV
I_{IN} PWM comparator input bias current	$V_B = 2 V$ $T_C = -40$ to $130^\circ C$ $V_C = 0.3 V$		1	10	μA
V_{CHH} High level threshold sawtooth generator	$V_A = 0 V \rightarrow 3.2 V$  $V_B = 0.3 V$	2.45	2.55	2.8	V
V_{CHL} Low level threshold sawtooth generator	$V_A = 3.2 V \rightarrow 0 V$ 	0.4	0.5	0.7	V
$\frac{I_{CH} - I_R}{I_R}$ External capacitor charging current, pin 8 versus I_R , pin 9	$I_R = 50$ to $110 \mu A$ $V_A = 1 V$ $V_B = 0.3 V$	-7		+7	%

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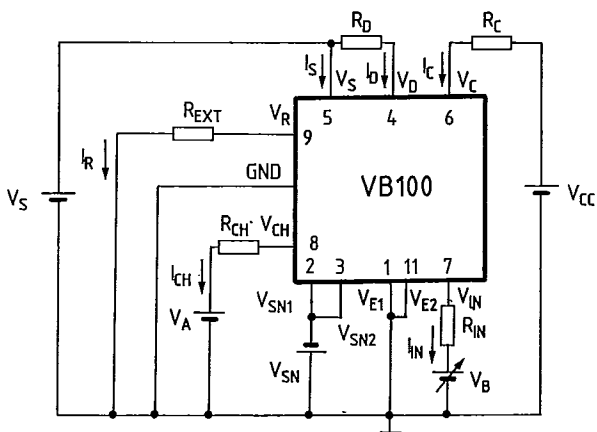
ELECTRICAL CHARACTERISTICS:

Parameters		Test Conditions		Min.	Typ.	Max.	Unit
$\frac{I_{CH}^*}{T} \times \frac{1}{I_{CH}}$	Capacitor charging current change with temperature (pin 8)	$V_A = 1\text{ V}$ $I_R = 100\text{ }\mu\text{A}$	$V_B = 0.3\text{ V}$ $T_C = -40\text{ to }130^\circ\text{C}$			300	$\frac{\text{ppm}}{^\circ\text{C}}$
V_R	Reference bias voltage pin 11	$I_R = 100\text{ }\mu\text{A}$		2.7	2.8	2.92	V
t_r	Rise time of the Darlington collector current, I_C (see fig. 3)	$I_D = 150\text{ mA}$	$I_C = 3\text{ A}$		0.25		μs
t_s	Storage time of the Darlington collector current, I_C (see fig. 3)	$I_C = 3\text{ A}$ $V_{SN} = -5\text{ V}$ $V_{SN} = 0\text{ V}$	$I_D = 150\text{ mA}$		1.5 8.0		μs μs
t_f	Fall time of the Darlington collector current, I_C (see fig. 3)	$I_C = 3\text{ A}$ $V_{SN} = -5\text{ V}$ $V_{SN} = 0\text{ V}$	$I_D = 150\text{ mA}$		0.2 1.0		μs μs
$t_{ON}(\text{min})$	Minimum duration of the Darlington collector current, I_C (see fig. 3)	$I_C = 3\text{ A}$ $V_{SN} = -5\text{ V}$ $V_{SN} = 0\text{ V}$	$I_D = 150\text{ mA}$		2.0 10.0		μs μs

$$I_{CH}^* = I_{CH}(130^\circ\text{C}) - I_{CH}(-40^\circ\text{C})$$

N.B.* pulsed operation: $t_{rep.} = 10 \text{ ms}$ $t_{ON} = 100 \mu s$

Fig. 1 Test Circuit



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Fig. 2 Comparator threshold hysteresis

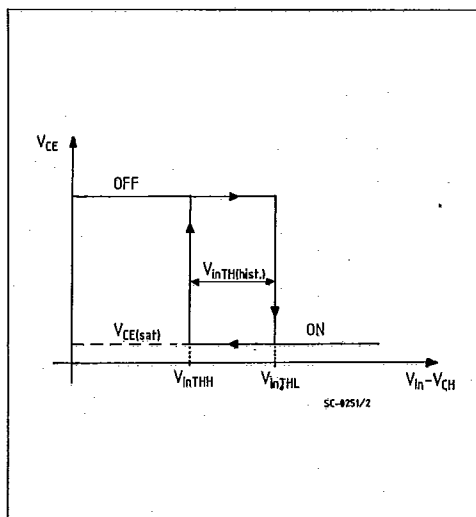


Fig. 3 Switching waveforms

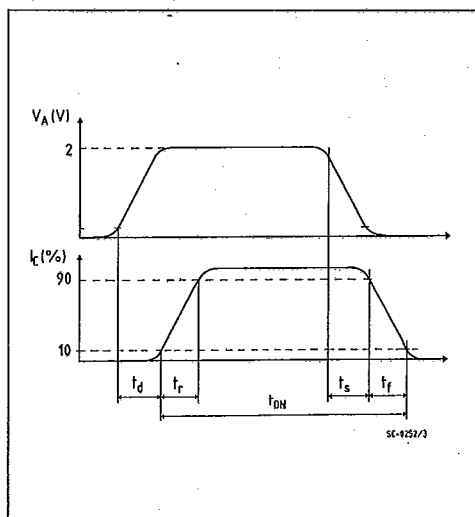
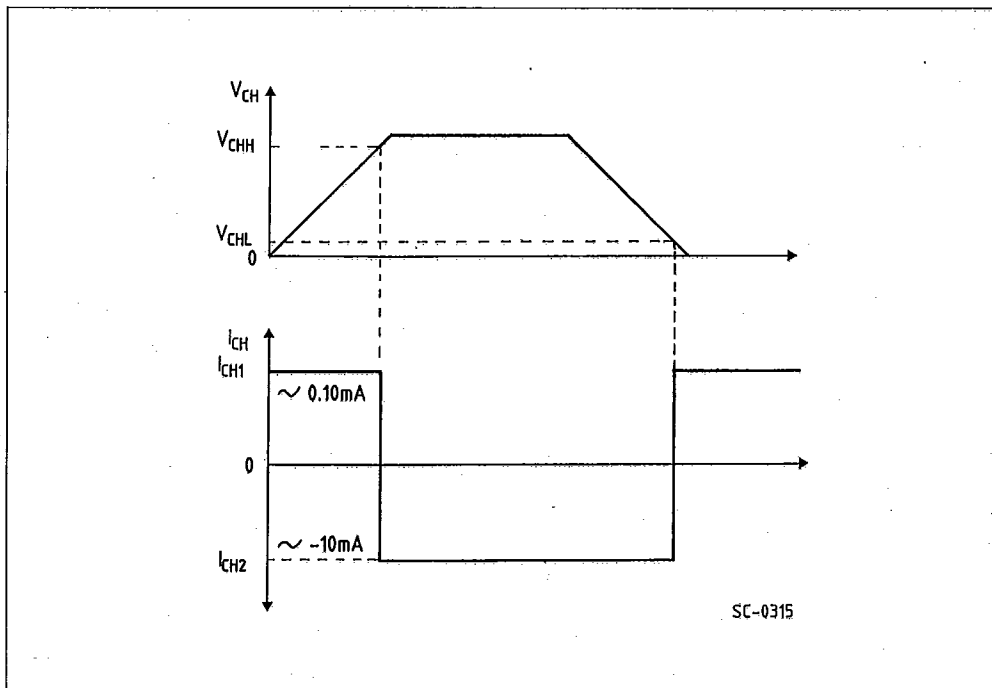


Fig. 4 Switching waveforms



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APPLICATION INFORMATION

The VB100 is mainly intended as a quarter bridge controller. The sawtooth generator frequency is set by two external components, R_{EXT} and C_{EXT} :

$$f_{osc} = 1.1 / (R_{EXT} \times C_{EXT})$$

in the ranges:

$$\begin{aligned} 23.3 \text{ k}\Omega &< R_{EXT} < 100 \text{ k}\Omega \\ 400 \text{ pF} &< C_{EXT} < 200 \text{ }\mu\text{F} \\ 0.5 \text{ Hz} &< f_{osc} < 100 \text{ kHz} \end{aligned}$$

The input voltage V_{IN} sets the duration of t_{ON} for

the output stage. As V_{IN} increases t_{ON} increases following the relationship:

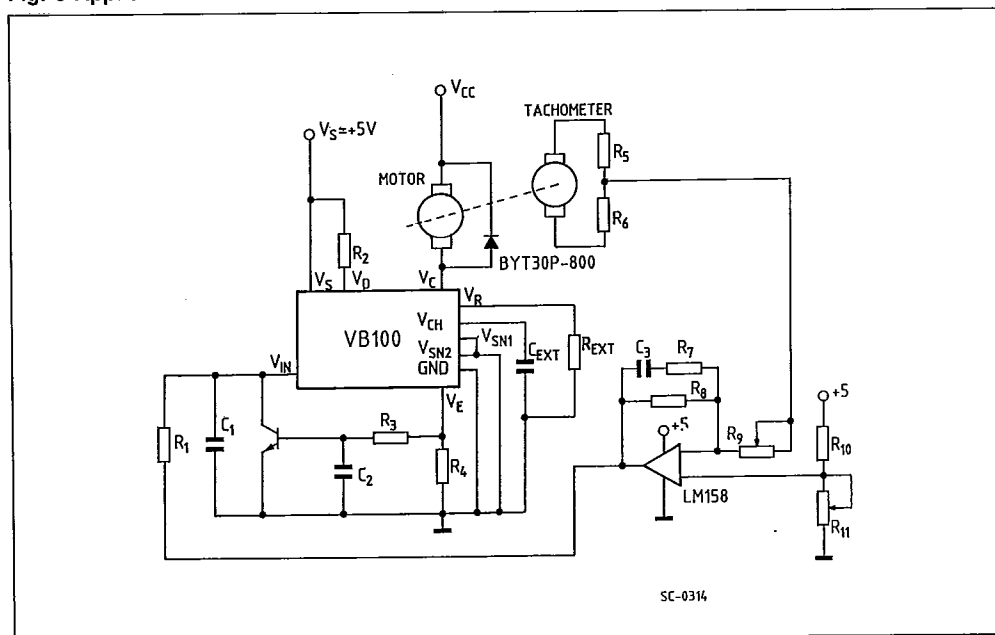
$$t_{ON} = t_s + t_r + t_f + 0.91 \times \frac{R_{EXT} \times C_{EXT}}{(V_{CHH} - V_{CHL})} \times V_{IN}$$

in the range:

$$\begin{aligned} 0.5 \text{ Hz} &< f_{osc} < 5 \text{ kHz} && \text{with } V_{SN} = 0 \\ 0.5 \text{ Hz} &< f_{osc} < 20 \text{ kHz} && \text{with } V_{SN} = -5 \text{ V} \end{aligned}$$

If an inductive load is used, it is necessary to provide a current limiting circuit. The device can form part of a closed loop control by just adding a few external components; fig. 5 shows a typical application example.

Fig. 5 Application Circuit



$$\begin{aligned} R_1 &= 100 \\ R_2 &= 33 \text{ }\Omega \\ R_3 &= 1 \text{ k}\Omega \\ R_4 &= 0.15 \text{ }\Omega \end{aligned}$$

$$\begin{aligned} R_5 &= 100 \text{ k}\Omega \\ R_6 &= 1.8 \text{ k}\Omega \\ R_7 &= 2 \text{ k}\Omega \\ R_8 &= 100 \text{ k}\Omega \end{aligned}$$

$$\begin{aligned} R_9 &= 50 \text{ k}\Omega \\ R_{10} &= 3.3 \text{ k}\Omega \\ R_{11} &= 4.7 \text{ k}\Omega \\ R_{EXT} &= 50 \text{ k}\Omega \end{aligned}$$

$$\begin{aligned} C_1 &= 1 \text{ nF} \\ C_2 &= 1 \text{ nF} \\ C_3 &= 33 \text{ nF} \\ C_{EXT} &= 1.8 \text{ nF} \end{aligned}$$