

**Z8030 SCC****LH8030****Serial Communication Controller****Features**

- Two independent, 0 to 1 Megabit-per-second, full-duplex channels, each with its own quartz oscillator, baud-rate generator, and digital phase-locked loop for clock recovery.
- Multi-protocol operation under program control.
- Asynchronous mode with 5 to 8 bits and 1, 1½, or 2 stop bits per character; programmable clock factor; break detection and generation; parity, overrun, and framing error detection.
- Local loopback and auto-echo modes.
- Bisynchronous mode with internal or external character synchronization on one or two sync characters and CRC generation and checking with CRC-16 or CRC-CCITT preset to either 1s or 0s.
- SDLC/HDLC mode with comprehensive frame-level control, automatic zero insertion and deletion, I-field residue handling, abort generation and detection, CRC generation and checking, and loop mode operation.
- Programmable for NRZ, NRZI, or FM coding.

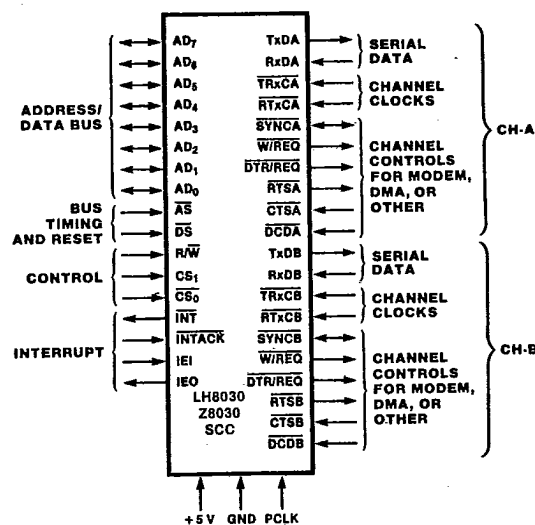
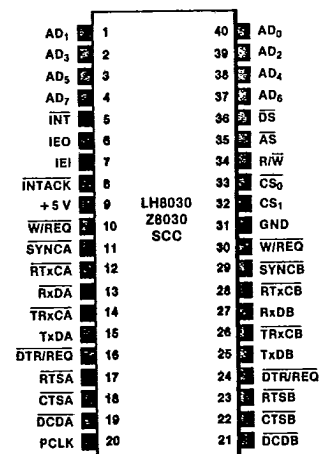
**Description**

The Z-SCC Serial Communication Controller is a dual-channel, multi-protocol data communication peripheral for Z-bus use. It is software-configured to satisfy a wide variety of serial communication applications. Its basic function is serial-to-parallel and parallel-to-serial conversion. However, the Z-SCC also contains a repertoire of new, sophisticated internal functions that minimize the need for

external random logic on the circuit card.

The Z-SCC handles asynchronous formats, synchronous byte-oriented protocols such as IBM Bisync, and synchronous bit-oriented protocols such as HDLC and IBM SDLC. This versatile device also supports virtually any other serial data transfer application (cassette or diskette interface, for example).

The device can generate and check CRC

**Figure 1. Pin Functions****Figure 2. Pin Assignments**

## Description (Continued)

codes in any synchronous mode and can be programmed to check data integrity in various modes. It also has facilities for modem controls in both channels. In applications where these controls are not needed, the modem controls can be used for general-purpose I/O.

As is standard among Zilog peripheral components, the Z-bus daisy-chain interrupt hierarchy is supported.

The Z-SCC contains the necessary multiplexed address/data bus interface with strobe and chip select lines to function as a Z-bus peripheral. It includes internal control and interrupt logic, two full-duplex channels and two baud-rate generators. Associated with each channel are several read and write registers for mode control as well as the logic necessary to interface to modems or other external devices.

The read and write register group for each channel includes eight control registers, two sync-character registers, and four status registers. Each baud rate generator has two read/write registers for holding the time constant that determines baud rate. Associated with the interrupt logic is a write register for interrupt vector and three read registers: vector with status, vector without status, and interrupt pending status.

The logic for both channels provides formatting, synchronization and validation for data transferred to and from the channel interface. The modem control inputs are monitored by the control logic under program control. All of the modem control signals are general purpose in nature and optionally can be used for functions other than modem control.

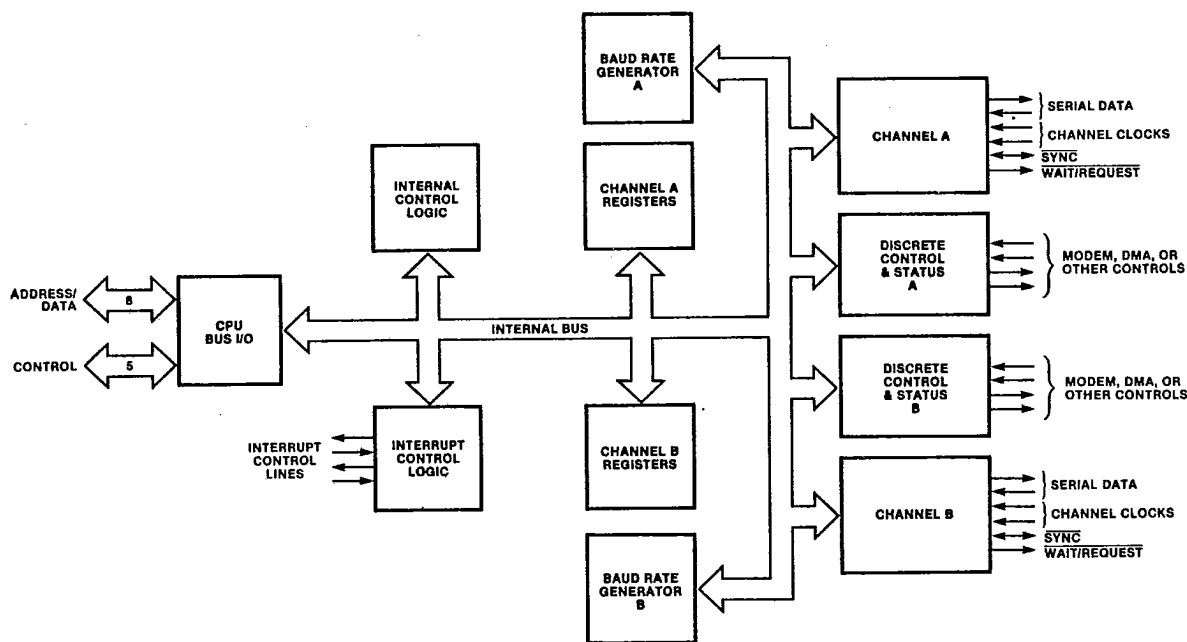


Figure 3. Functional Block Diagram

## Pin Description

The following section describes the pin functions of the Z-SCC. Figures 1 and 2 detail the respective pin functions and pin assignments.

**AD<sub>0</sub>-AD<sub>7</sub>.** *Address/Data Bus* (bidirectional, active High, 3-state). These multiplexed lines carry register addresses to the Z-SCC as well as data or control information to and from the Z-SCC.

**AS.** *Address Strobe* (input, active Low). Addresses on AD<sub>0</sub>-AD<sub>7</sub> are latched by the rising edge of this signal.

**CS<sub>0</sub>.** *Chip Select 0* (input, active Low). This signal is latched concurrently with the addresses on AD<sub>0</sub>-AD<sub>7</sub> and must be active for the intended bus transaction to occur.

**CS<sub>1</sub>.** *Chip Select 1* (input, active High). This second select signal must also be active before the intended bus transaction can occur. CS<sub>1</sub> must remain active throughout the transaction.

**CTSA, CTSE.** *Clear to Send* (inputs, active Low). If these pins are programmed as Auto Enables, a Low on the inputs enables their respective transmitters. If not programmed as Auto Enables, they may be used as general-purpose inputs. Both inputs are Schmitt-trigger buffered to accommodate slow rise-time inputs. The Z-SCC detects pulses on these inputs and can interrupt the CPU on both logic level transitions.

**DCDA, DCDB.** *Data Carrier Detect* (inputs, active Low). These pins function as receiver enables if they are programmed for Auto Enables; otherwise they may be used as general-purpose input pins. Both pins are Schmitt-trigger buffered to accommodate slow rise-time signals. The Z-SCC detects pulses on these pins and can interrupt the CPU on both logic level transitions.

**DS.** *Data Strobe* (input, active Low). This signal provides timing for the transfer of data into and out of the Z-SCC. If AS and DS coincide, this is interpreted as a reset.

**Pin  
Description  
(Continued)**

**DTR/REQA, DTR/REQB.** *Data Terminal Ready/Request* (outputs, active Low). These outputs follow the state programmed into the DTR bit. They can also be used as general-purpose outputs or as Request lines for a DMA controller.

**IEI.** *Interrupt Enable In* (input, active High). IEI is used with IEO to form an interrupt daisy chain when there is more than one interrupt-driven device. A High IEI indicates that no other higher priority device has an interrupt under service or is requesting an interrupt.

**IEO.** *Interrupt Enable Out* (output, active High). IEO is High only if IEI is High and the CPU is not servicing a Z-SCC interrupt or the Z-SCC is not requesting an interrupt (Interrupt Acknowledge cycle only). IEO is connected to the next lower priority device's IEI input and thus inhibits interrupts from lower priority devices.

**INT.** *Interrupt Request* (output, open-drain, active Low). This signal is activated when the Z-SCC requests an interrupt.

**INTACK.** *Interrupt Acknowledge* (input, active Low). This signal indicates an active Interrupt Acknowledge cycle. During this cycle, the Z-SCC interrupt daisy chain settles. When  $\overline{DS}$  becomes active, the Z-SCC places an interrupt vector on the data bus (if IEI is High).  $\overline{INTACK}$  is latched by the rising edge of  $\overline{AS}$ .

**PCLK.** *Clock* (input). This is the master Z-SCC clock used to synchronize internal signals. PCLK is not required to have any phase relationship with the master system clock, although the frequency of this clock must be at least 90% of the CPU clock frequency for a Z8000. PCLK is a TTL level signal.

**RxDA, RxDB.** *Receive Data* (inputs, active High). These input signals receive serial data at standard TTL levels.

**RTxCA, RTxCB.** *Receive/Transmit Clocks* (inputs, active Low). These pins can be programmed in several different modes of operation. In each channel,  $\overline{RTxC}$  may supply the receive clock, the transmit clock, the clock for the baud rate generator, or the clock of the Digital Phase-Locked Loop. These pins can also be programmed for use with the respective  $\overline{SYNC}$  pins as a crystal oscillator. The receive clock may be 1, 16, 32, or 64 times the data rate in Asynchronous modes.

**RTSA, RTSB.** *Request To Send* (outputs, active Low). When the Request To Send (RTS) bit in Write Register 5 (Figure 11) is set, the  $\overline{RTS}$  signal goes Low. When the RTS bit is reset in the Asynchronous mode and Auto Enable is on, the signal goes High after the transmitter is empty. In Synchronous mode or in Asynchronous mode with Auto Enable off, the  $\overline{RTS}$  pin strictly follows the state of the RTS bit. Both pins can be used as general-purpose outputs.

**R/W.** *Read/Write* (input). This signal specifies whether the operation to be performed is a read or a write.

**SYNCA, SYNCB.** *Synchronization* (inputs or outputs, active Low). These pins can act either as inputs, outputs, or part of the crystal oscillator circuit.

In the Asynchronous Receive mode (crystal oscillator option not selected), these pins are inputs similar to CTS and DCD. In this mode, transitions on these lines affect the state of the Synchronous/Hunt status bits in Read Register 0 (Figure 10) but have no other function.

In External Synchronization mode with the crystal oscillator not selected, these lines also act as inputs. In this mode,  $\overline{SYNC}$  must be driven Low two receive clock cycles after the last bit in the synchronous character is received. Character assembly begins on the rising edge of the receive clock immediately preceding the activation of  $\overline{SYNC}$ .

In the Internal Synchronization mode (Monosync and Bisync) with the crystal oscillator not selected, these pins act as outputs and are active only during the part of the receive clock cycle in which synchronous characters are recognized. The synchronous condition is not latched, so these outputs are active each time a synchronization pattern is recognized (regardless of character boundaries). In SDLC mode, these pins act as outputs and are valid on receipt of a flag.

**TxDA, TxDB.** *Transmit Data* (outputs, active High). These output signals transmit serial data at standard TTL levels.

**TRxCA, TRxCB.** *Transmit/Receive Clocks* (inputs or outputs, active Low). These pins can be programmed in several different modes of operation.  $\overline{TRxC}$  may supply the receive clock or the transmit clock in the input mode or supply the output of the Digital Phase-Locked Loop, the crystal oscillator, the baud rate generator, or the transmit clock in the output mode.

**W/REQA, W/REQB.** *Wait/Request* (outputs, open-drain when programmed for a Wait function, driven High or Low when programmed for a Request function). These dual-purpose outputs may be programmed as Request lines for a DMA controller or as Wait lines to synchronize the CPU to the Z-SCC data rate. The reset state is Wait.