



Used as an application specific integrated circuit for electronic energy meters, FM2032 has the ability to calculate bi-directional active power, and in this way has overcome the limitation of the traditional inductive energy meter that only active power of which the voltage and current must be of the same phase can be calculated. On the other hand, the electrical energy meter using this IC has several advantages such as high precision, low power consumption, high reliability, good environment suitability and low raw material consumption, therefore is now the new generation product of the traditional inductive energy meters.

## FEATURES

- ◆ Prevention of power-theft, positive and negative power registering
- ◆ Ideal linearity between  $5\%I_b - 4I_b$ , measurement error less than 0.3%
- ◆ Fast pulse output and current direction indication are suitable for computer data processing
- ◆ Slow pulse output gives directly drive for electromechanical counter and two phase stepper motor
- ◆ Electrostatic discharge circuitry, safe under 2000V discharges
- ◆ BiCMOS process, reliable quality
- ◆ Perfect solution for household single phase energy meters

## PIN FUNCTIONS

| Pin | Symbol          | Function Description                      | Pin | Symbol          | Function Description        |
|-----|-----------------|-------------------------------------------|-----|-----------------|-----------------------------|
| 1   | V <sub>I</sub>  | Current sampling signal input             | 11  | V <sub>SS</sub> | Negative power supply (-5V) |
| 2   | V <sub>I2</sub> | Current sampling signal input             | 12  | GNDD            | Digital ground              |
| 3   | GNDA            | Analog ground                             | 13  | Mo              | Stepper motor drive output  |
| 4   | V <sub>V</sub>  | Voltage sampling signal input             | 14  | Mo              | Stepper motor drive output  |
| 5   | V <sub>V</sub>  | Internally connected with Pin4            | 15  | Osc1            | Crystal oscillator          |
| 6   | V <sub>R6</sub> | External adjustment for voltage reference | 16  | Osc2            | Crystal oscillator          |
| 7   | V <sub>R7</sub> | External adjustment for voltage reference | 17  | V <sub>DD</sub> | Positive power supply (+5V) |
| 8   | P8              | Active power integral pulse               | 18  | C <sub>1</sub>  | Integral capacity           |
| 9   | S9              | Negative power signaling                  | 19  | C <sub>12</sub> | Integral capacity           |
| 10  | Tc              | Testing control                           | 20  | C <sub>2</sub>  | Integral capacity           |

## ABSOLUTE MAXIMUM RATINGS (Ta=25°C)

| Symbol                 | Parameter       | Absolute value                                            | Unit | Symbol        | Parameter        | Absolute value                                            | Unit |
|------------------------|-----------------|-----------------------------------------------------------|------|---------------|------------------|-----------------------------------------------------------|------|
| positive power voltage | V <sub>DD</sub> | +7(max)                                                   | V    | entry voltage | V <sub>I</sub>   | V <sub>SS</sub> +0.5<V <sub>I</sub> <V <sub>DD</sub> -0.5 | V    |
| negative power voltage | V <sub>SS</sub> | -7(min)                                                   | V    | work temp     | T <sub>opr</sub> | -20 ~ +70                                                 | °C   |
| entry voltage          | V <sub>I</sub>  | V <sub>SS</sub> +0.5<V <sub>I</sub> <V <sub>DD</sub> -0.5 | V    | store temp    | T <sub>str</sub> | -55 ~ +150                                                | °C   |

## SPECIFICATIONS

(V<sub>DD</sub>=5V, V<sub>SS</sub>= -5V, f<sub>clk</sub>=32.768kHz, T<sub>a</sub>=25°C, pin3, pin9 connected to ground through 1.0kΩ)

| Test item                   | Symbol          | Test condition                                                  | Test point | Min  | Typ    | Max    | Unit |
|-----------------------------|-----------------|-----------------------------------------------------------------|------------|------|--------|--------|------|
| Positive power current      | I <sub>DD</sub> | V <sub>V</sub> , V <sub>I</sub> =0                              | Pin17      | 1.0  | 2.0    | 3      | mA   |
| Negative power current      | I <sub>SS</sub> | V <sub>V</sub> , V <sub>I</sub> =0                              | Pin11      | 1.5  | 2.5    | 3.5    | mA   |
| Reference voltage           | V <sub>R1</sub> | V <sub>V</sub> , V <sub>I</sub> =0                              | Pin6       | -1.2 | -1.25  | -1.3   | V    |
| Reference voltage           | V <sub>R2</sub> | V <sub>V</sub> , V <sub>I</sub> =0                              | Pin7       | -0.6 | -0.625 | -0.65  | V    |
| Negative power indication   | V <sub>9</sub>  | V <sub>V</sub> =0.65V <sub>V</sub><br>V <sub>I</sub> =10mV, a=π | Pin9       |      |        | -4     | V    |
| Active power Integral pulse | V <sub>8</sub>  | V <sub>V</sub> =1V, V <sub>I</sub> =10mV                        | Pin8       |      |        | -4     | V    |
| Stepper motor drive voltage | V <sub>m</sub>  | Pin13, 14 400Ω                                                  | Pin13, 14  |      |        | -4     | V    |
| Non-linear Error%           | E <sub>NL</sub> | V <sub>V</sub> =0.65<br>V <sub>I</sub> =120μV ~ 12mV            | Pin8       |      |        | ± 1.0% |      |

|                                           |              |                                                              |          |             |             |         |
|-------------------------------------------|--------------|--------------------------------------------------------------|----------|-------------|-------------|---------|
| Non-linear Error%                         | $E_{NL}$     | $V_s=0.65$<br>$V_{in}=60\mu V-12mV$                          | Pin8     |             | $\pm 1.5\%$ |         |
| Start-up current                          | $I_{START}$  | $\phi=0$ $V_s=0.65V$                                         | Pin8     | $0.4\% I_b$ |             | A       |
| Negative active power error %             | $E_{NP}$     | $V_s=0.65V$<br>$V_{in}=120\mu V-12mV$<br>$\phi=0$ $\phi=\pi$ | Pin8     |             | $\pm 1.5\%$ |         |
| Output frequency<br>Of pin13,14 over pin8 | $f_o/f_s$    | $V_s=0.65V$<br>$V_{in}=10mV$                                 | Pin13,14 |             | 1:16        |         |
| Leak current of pin8                      | $I_{l8}$     | $V_o V_{in}=0V, V_8=0V$                                      | Pin8     |             | -100        | $\mu A$ |
| Leak current of pin9                      | $I_{l9}$     | $V_o V_{in}=0V, V_9=0V$                                      | Pin9     |             | -100        | $\mu A$ |
| Leak current of pin13,14                  | $I_{l13,14}$ | $V_o V_{in}=0V, V_{13,14}=0V$                                |          |             | -100        | $\mu A$ |

1. Non-linear error%: No compensation is added on Pin8 and Pin2,  $V_s$  the alternative current voltage between Pin4-Pin12,  $\phi=0$  power factor correct

$\phi=\pi$  anti-signal (all errors small signal 25%) error%  $\pm 100\%$

2. Start-up current: When  $V_s=0.65V$  is motor current  $I_{in}$  basic current  $I_{in}=1.5V_s=0.975V$  the smallest alternative current that can make Pin8 give output

3. Negative active power error%

same as 1) \*Note: it is recommended that not measure under positive power.

## APPLICATION INFORMATION

The relationship between pin10, input power (positive/negative) and Pin8, Pin9, Pin13, Pin14

| Pin10(IN) | Input power | Pin8(OUT)                            | Pin9(OUT)         | Pin13(OUT)                                        | Pin14(OUT)                                        |
|-----------|-------------|--------------------------------------|-------------------|---------------------------------------------------|---------------------------------------------------|
| GND       | Positive    | Negative modulated power pulse(0-5V) | 0V(DC)            | Negative pulse of 250ms width, 1/16 of Pin8 freq. | Negative pulse of 250ms width, 1/16 of Pin8 freq. |
| GND       | Negative    | Same as above                        | -5V(DC)           | Same as above                                     | Same as above                                     |
| -5V       | Positive    | Power pulse(0-5V)                    | 0V(DC)            | Same as above                                     | Same as above                                     |
| -5V       | Negative    | Same as above                        | Power pulse(0-5V) | Same as above                                     | Same as above                                     |

1) Input power(positive/negative) is defined as the product of  $V_s$ , the voltage sampling signal between Pin4-Pin1 and  $V_i$ , the current sampling signal between Pin2-Pin1. Sign of  $V_s=V_{in}$  determines that of the input power i.e., if bigger than zero then positive, if lower, negative.

2) The output pulses of Pin13 and Pin14 are located in the mid-point of the other's period, therefore the combined output frequency of Pin13, Pin14 is 1/8 that of Pin8.

## APPLICATION CIRCUIT ( $I_b=5A, c=3200p/kwh$ )

