

# FM25160 FRAM® Serial Memory

Product Preview\*

#### Features

- 16Kbit Nonvolatile Ferroelectric RAM Organized as 2,048 x 8
- Low Power CMOS Technology
  - 10µA Standby Over Industrial Temperature Range
  - 5µA Standby Over Commercial Temperature Range
- Reliable Thin Film Ferroelectric Technology
  - 10 Billion (1010) Cycle Read/Write Endurance
  - 10 Year Data Retention
- High Performance
  - No Write Delay
  - Unlimited Sequential Write

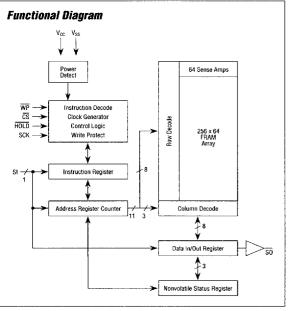
- Simple Three Wire Bus
  - SPI Compatible (CPOL = 0, CPHA = 0)
  - 2.1MHz Maximum Clock Rate
- Multiple Levels of Write Protection
  - Hardware Write Protect Pin
  - Internal Write Enable Latch
  - Block Protect Bits
  - Low Voltage Lockout
- ESD Protection Greater Than 2,000V On All Pins
- True 5V Only Operation
- 8-Pin Mini DIP and SOIC Packages
- -40° to +85°C Operating Range

# **Description**

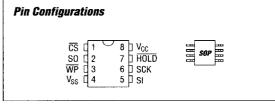
Ramtron's FM25160 ferroelectric random access memory, or FRAM® memory provides nonvolatile data integrity in a compact package. A three wire serial interface provides access to any byte within the memory while reducing the cost of the processor interface (as compared to parallel access memories). The FM25160 is useful in a wide variety of applications for the storage of configuration information, user programmable data/features, and calibration data.

With Ramtron's ferroelectric technology, all writes are nonvolatile, eliminating long delays, extra page mode control, or high voltage pins. The technology is designed for highly reliable operation, offering extended endurance and 10 year data retention.

The FM25160 uses the industry standard three wire SPI protocol for serial chip communication. It is available in 300 mil mini-DIP and 150 mil SOP packages.



\*This document describes a product under development. Ramtron reserves the right to change or discontinue this product without notice.



#### Pin Names

Pin Names	Function
<u>cs</u>	Chip Select
SO SO	Serial Data Out
WP	Write Protect
V <sub>SS</sub>	Ground
SI	Serial Data In
SCK	Serial Clock
HOLD	Hold Input
V <sub>CC</sub>	Supply Voltage

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#### **Absolute Maximum Ratings**

Description	Ratings
Ambient Storage or Operating Temperature to Guarantee Nonvolatility of Stored Data	-40°C to +85°C
Voltage on Any Pin with Respect to Ground	-1.0 to +7.0V
D.C. Output Current	5mA
Lead Temperature (Soldering, 10 Seconds)	300°C

Stresses above those listed under Absolute Maximum Ratings may cause permanent damage to the device. This is a stress rating only, and the functional operation of the device at these or any other conditions above those indicated in the operational sections of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

#### **DC Operating Conditions**

 $T_A = -40$ °C to +85°C,  $Y_{CC} = 5.0V \pm 10\%$ , Unless Otherwise Specified

Symbol	Parameter	Min	<i>Typ</i> <sup>(1)</sup>	Max	Units	Test Conditions
V <sub>CC</sub>	Power Supply Voltage	4.5	5.0	5.5	٧	
I <sub>CC</sub>	V <sub>CC</sub> Supply Current		1.0	1.5	mA	SCK @ 2.1MHz, Read or Write SCK CMOS Levels, All Other Inputs = $V_{SS}$ or $V_{CC}$ - 0.3V
I <sub>CC</sub>	V <sub>CC</sub> Supply Current		500	700	μA	SCK @ 1.0MHz, Read or Write SCK CMOS Levels, All Other Inputs = V <sub>SS</sub> or V <sub>CC</sub> - 0.3V
I <sub>SB</sub>	Standby Current 0 to 70°C		1	5	μА	$SCK = SI = V_{CC}$ , All Other Inputs = $V_{SS}$ or $V_{CC}$
I <sub>SB</sub>	Standby Current -40 to 85°C		1	10	μA	SCK = SI = $V_{CC}$ , All Other Inputs = $V_{SS}$ or $V_{CC}$
I <sub>LI</sub>	Input Leakage Current			10	μА	V <sub>IN</sub> = V <sub>SS</sub> to V <sub>CC</sub>
I <sub>LO</sub>	Output Leakage Current			10	μА	V <sub>OUT</sub> = V <sub>SS</sub> to V <sub>CC</sub>
V <sub>IL</sub>	Input Low Voltage	-1.0		V <sub>CC</sub> x 0.3	ν	
V <sub>IH</sub>	Input High Voltage	V <sub>CC</sub> x 0.7		V <sub>CC</sub> + 0.5	٧	
V <sub>OL1</sub>	Output Low Voltage			0.4	٧	I <sub>OL</sub> = 2mA
V <sub>OH</sub>	Output High Voltage	V <sub>CC</sub> 8			٧	I <sub>OH</sub> = -1mA
V <sub>HYS</sub> <sup>(2)</sup>	Input Hysteresis	V <sub>CC</sub> x .05			٧	

- (1) Typical values at 25°C, 5.0V.
- (2) This parameter is periodically sampled and not 100% tested.

#### **Endurance and Data Retention**

Parameter	Min	Max	Units
Endurance	10 Billion		R/W Cycles
Data Retention	10		Years

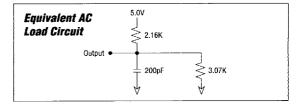
#### **AC Conditions of Test**

AC Conditions	Test
Input Pulse Levels	V <sub>CC</sub> x 0.1 to V <sub>CC</sub> x 0.9
Input Rise and Fall Times	10ns
Input and Output Timing Levels	V <sub>CC</sub> x 0.5

# Power-Up Timing (3)

Symbol	Parameter	Max	Units	
t <sub>PUR</sub> (3)	Power Up to Read Operation	1	μs	
t <sub>PUW</sub> (3)	Power Up to Write Operation	1	μs	

(3)  $t_{PUW}$  and  $t_{PUW}$  are the delays required from the time  $V_{CC}$  is stable until the specified operation can be initiated. These parameters are periodically sampled and not 100% tested.



#### **Capacitance**

 $T_A = 25$  °C, f = 1.0MHz,  $V_{CC} = 5$ V

Symbol	Test	Max	Units	Conditions
C <sub>OUT</sub> (2)	Output Capacitance	8	pF	V <sub>1/O</sub> = 0V
C <sub>IN</sub> <sup>(2)</sup>	Input Capacitance	6	pF	V <sub>IN</sub> = 0V

<sup>(2)</sup> This parameter is periodically sampled and not 100% tested.

# **Pin Descriptions** Serial Output (SO)

This pin is active only during a read operation. The pin is high impedance at all other times and when /HOLD is low. During a read operation, this line is driven high or low depending on the current data output bit. Data is clocked out of the FM25160 on the falling edge of the serial clock.

### Serial Input (SI)

Data is clocked into the FM25160 via this pin on the rising edge of the serial clock signal. Beyond the setup and hold times around this clock edge, the state on this pin is ignored. However, this pin should be driven to a valid logic level at all times to prevent excessive power dissipation.

#### Serial Clock (SCK)

Information is clocked into or out of the FM25160 using this pin when /CS is low and /HOLD is high. Input values are latched on the rising edge, while data output changes occur after the falling edge of this signal. The maximum clock rate is 2.1MHz. The FM25160 is a completely static design, so clocking may be interrupted at any point in time, or the clock rate may be arbitrarily slow.

#### Chip Select (/CS)

When this signal is low, the FM25160 will respond to transitions on the SCK signal. When it is high, inputs are ignored, outputs are placed in a high impedance state, and the FM25160 goes into its low power standby mode. A high to low transition is required on this pin before each opcode.

#### Write Protect (/WP)

This pin provides a hardware write protect for the status register. When WPEN is high and /WP is low, then writes to the status register are disabled. Note that the operation of this pin differs from its function in the FM25040. In the FM25040, /WP provides write protection for the status register *and* the FRAM memory array. The /WP function is enabled by the WPEN bit in the status register.

#### Hold (/HOLD)

/HOLD may be used to pause the sequence if the CPU must process some other event in the middle of an operation. While /HOLD is low, the FM25160 will ignore any transitions on the SCK and /CS pins. When /HOLD is high, all operations will proceed normally. Transitions on the /HOLD pin must occur while SCK is low.

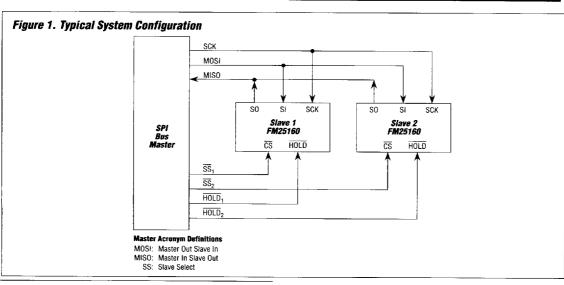
# **Device Operation**

The FM25160 is a serial ferroelectric memory designed to interface easily with the Serial Peripheral Interface (SPI) port common to many MC6805 and MC68HC11 processors. The SPI communications channel uses three wires (clock, serial data in, and serial data out) that can be shared among a number of devices. Additionally, a fourth pin (chip select) selects the device on the time multiplexed bus that should respond to the access request. A typical system configuration is shown in Figure 1.

Data is transferred to and from the FM25160 in bytes of eight bits each, governed by edges on the SCK signal. Data is transferred with the most significant bit (MSB) first. For any operation the first byte to be transferred is the operation code (opcode) which determines what is to be performed by the memory. There are six operations that may be performed by the FM25160. Table 1 lists the operation with its corresponding opcode.

Table 1. Opcode Commands

Opcode	Description	Name
0000 0110	Set Write Enable Latch	WREN
0000 0100	Write Disable	WRDI
0000 0101	Read Status Register	RDSR
0000 0001	Write Status Register	WRSR
00AA A011	Read Data	READ
00AA A010	Write Data	WRITE



#### Status Register

Table 2 shows the organization of the status register. The register is read using the RDSR instruction. Bits 0 and 4 through 6 are unused. When read, they return a 0. The value of the status register is transmitted directly after the RDSR opcode. Executing of the RDSR instruction has no effect on the status register bits. (This is unlike the WRSR instruction which clears the Write Enable Latch [WEL] bit.)

Bit 1 is the WEL. The function of the WEL bit is to write protect the status register *and* the FRAM memory array. When set, writes may take place to the part. When reset, all writes will be ignored.

Bits 2 and 3 are nonvolatile block protect bits (BP0 and BP1). These bits provide further protection to portions of the array as specified in Table 3. Note that bytes within blocks that are *not* protected with BP0 and BP1 will still only be written if the write enable latch is set.

Writing to the status register is a two step process:

- The WEL bit must be set to enable a write. This is done using the WREN instruction.
- The WRSR instruction is then used to change the block protect bits or the WPEN bit. Note that execution of the WRSR instruction clears the WEL bit.

Bit 7 is the write protect enable latch bit. WPEN enables the hardware write protect feature provided by the /WP pin. When WPEN is high and /WP is low, then the status register is write protected.

The internal write enable latch on the FM25160 prevents writes to the data within the part while it is cleared. /WEL = 0 protects the nonvolatile memory array and the status register bits. It is automatically cleared on power up or whenever the power

Table 2. Status Register Organization

Bit	7	6	5	4	3	2	1	0
Name	WPEN	0	0	0	BP1	BP0	WEL	0

Table 3. Memory Block Protect Bits

BP1	BP0	Protected Address Range (Hex)
0	0	None
0	1	$600 \rightarrow 7FF$ (upper 1/4 of the array)
1	0	$400 \rightarrow 7FF$ (upper 1/2 of the array)
1	1	000 → 7FF (all of the array)

Table 4. Write Protection

supply falls below 3.5V (typical). It is also cleared after all write operations (including WRSR).

The user can set or reset the WEL bit by transmitting the corresponding opcode to the FM25160 (WREN or WRDI, respectively). No address or data bytes follow the opcode. Note that following the write enable latch instruction (WREN), chip select must rise again before a write sequence may be started. The FM25160 will ignore all bits transmitted after the opcode but before the rise of /CS.

#### Write Protection

The write protection features of the FM25160 are extensive. The features are summarized in Table 4. In lines 0 through 3, write protection of the status register is disabled since WPEN is low. The status of the /WP does not matter, and the WEL bit controls write protection for the unprotected blocks and the FRAM array together. In lines 6 and 7, the same situation occurs but this time it is due to the fact that /WP is high. In lines 4 and 5, the status register is protected by /WP being low and WPEN being high. Line 5 provides a semi-permanent write protect feature. With /WP low, taking WPEN high prevents further writes to the protected blocks and the status register. This can only be unlocked by taking /WP high.

#### Read and Write Sequences

For a read or write operation, an address byte must be transmitted to the FM25160 after the opcode. Bits 5, 4, and 3 of the opcode are address bits  $A_{10}$ ,  $A_9$ , and  $A_8$ , respectively. Following the address byte, data bytes should be transferred MSB first. Any number of bytes may be read or written in sequential order starting with the specified address, and wrapping around to address 0 after the byte at address 7FF (hex) is accessed. The read or write sequence continues until /CS is brought high.

Note that on the FRAM device, any number of bytes may be written with a single write sequence, while EEPROM based 25160 devices are limited to one through four bytes only. To accommodate this feature, the actual write to the nonvolatile array takes place after the eighth bit in each byte is transmitted. If /CS rises during a write operation, only the byte that has not been completely transmitted will be ignored.

### Low Voltage Protection

When powering up, the FM25160 will automatically perform an internal reset and await a high to low transition on /CS from the bus master. The bus master should wait  $T_{PUR}$  (or  $T_{PUW}$ ) after  $V_{CC}$  reaches 4.5V before selecting the part. Additionally, whenever  $V_{CC}$  falls below 3.5V (typical), the part goes into its low voltage protection mode. In this mode, all accesses to the part are inhibited and the part performs an internal reset. If an access was in progress when the power supply fails, it will be automatically aborted by the FM25160.

Line Number	WPEN	WP	WEL	Protected Blocks	Unprotected Blocks	Status Register
0	0	0	0	Protected	Protected	Protected
1	0	0	1	Protected Unprotected Unprotec		Unprotected
2	0	1	0	Protected Protected Prot		Protected
3	0	1	1	Protected Unprotected Unprot		Unprotected
4	1	0	0	Protected Protected Protect		Protected
5	1	0	1	Protected	Protected Unprotected F	
6	1	1	0	Protected Protected Pro		Protected
7	1	1	1	Protected	Unprotected	Unprotected

# Serial Data Output Timing

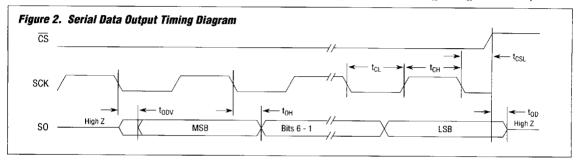
Serial output timing is shown in Figure 2. Data is placed by the FM25160 on it serial output pin (SO)  $t_{\rm ODV}$  seconds after the falling edge of SCK. The clock frequency is arbitrary with a maximum clock rate of 2.1MHz. This is the timing sequence that applies to the reading of the status register bits and nonvolatile memory.

### Serial Data Output Timing Parameters (4,5)

Symbol	Parameter	Min	Max	Units
f <sub>CK</sub>	Clock Frequency	0	2.1	MHz
t <sub>CH</sub>	Clock High Time	190		ns
t <sub>CL</sub>	Clack Low Time	190		ns
t <sub>CSL</sub>	Chip Select Lag Time	240		ns
t <sub>OD</sub>	Output Disable Time		240	ns
t <sub>ODV</sub>	Output Data Valid Time		240	ns
t <sub>OH</sub>	Output Hold Time	0		ns

(4)  $T_A = -40$ °C to +85°C,  $V_{CC} = 5.0V \pm 10\%$ , Unless Otherwise Specified

<sup>(5)</sup> Switching Times Measured from 50% V<sub>CC</sub> to 50% V<sub>CC</sub> Unless Otherwise Specified



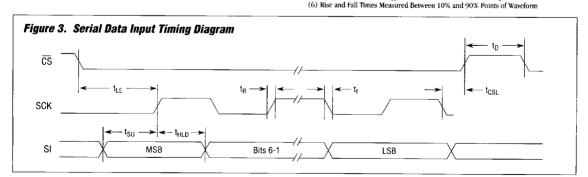
# Serial Data Input Timing

Serial input timing is shown in Figure 3. Input data is latched on the rising edge of SCK. The data bit must be valid  $t_{\rm SU}$  seconds before this rising edge. In addition, data must be held  $t_{\rm HLD}$  seconds after this rising edge. This is the timing sequence that applies to the clocking of all opcodes, addresses, and data to be written to the status register and memory.

### Serial Data Input Timing Parameters (4)

Symbol	Parameter	Min	Max	Units
t <sub>D</sub>	Deselect Time	240		ns
t <sub>F</sub> (6)	Data Fall Time		2.0	μs
t <sub>HLD</sub>	Data Hold Time	100		ns
t <sub>LE</sub>	Chip Select Lead Time	240		ns
t <sub>R</sub> (6)	Data Rise Time		2.0	μs
t <sub>SU</sub>	Data Setup Time	100		ns

(4)  $T_A = -40$ °C to +85°C,  $V_{CC} = 5.0V \pm 10\%$ , Unless Otherwise Specified



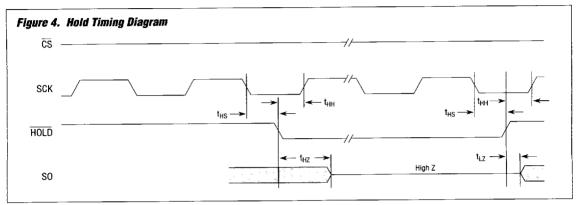
# **Hold Timing**

Hold timing is shown in Figure 4. Hold is used to pause a timing sequence to allow the processor to service a higher priority task. Note that /CS and SCK must be low during transitions of the /HOLD signal.

### Hold Timing Parameters (4)

Court of	Coromotor	Min	Мах	Units
Symbol	Parameter			
t <sub>HH</sub>	Hold Hold Time	90		ns
t <sub>HS</sub>	Hold Setup Time	90		ns
t <sub>HZ</sub>	HOLD Low to High Z		100	ns
t <sub>LZ</sub>	HOLD High to Low Z		100	ns

(4)  $T_A = -40$  °C to +85 °C,  $V_{CC} = 5.0V \pm 10\%$ , Unless Otherwise Specified

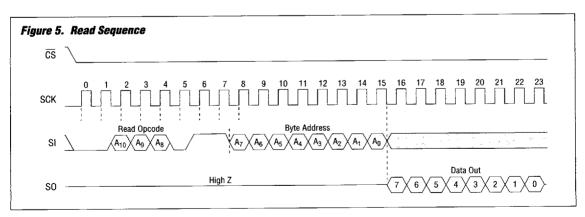


### Read Protocol

The detailed read protocol is shown in Figure 5. The sequence is as follows:

- i) The master initiates the sequence by pulling /CS low.
- The very next rising edge of SCK begins the input clocking of the opcode into the FM25160.
- iii) The eight bit opcode is clocked into the FM25160. Note that bits 5, 4, and 3 are address bits A<sub>10</sub>, A<sub>9</sub>, and A<sub>8</sub>, respectively.
- iv) The byte address (A7 through A0) follows immediately.

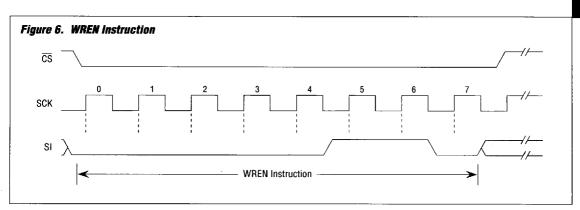
- The data is shifted out of the FM25160 (on SO) immediately following the byte address using the falling edge of SCK.
- vi) Data can be continuously shifted out of the FM25160 by continually supplying clock pulses. When the highest byte address is read, the address counter wraps to zero and reading continues.
- vii) The master terminates the read by taking /CS high.

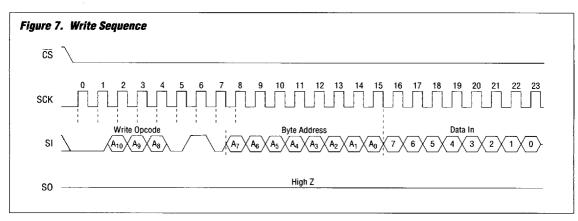


# Write Protocol

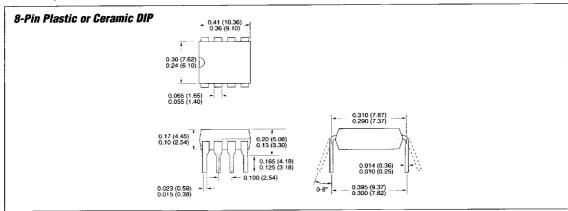
The detailed write protocol is shown in Figures 6 and 7. The sequence is as follows:

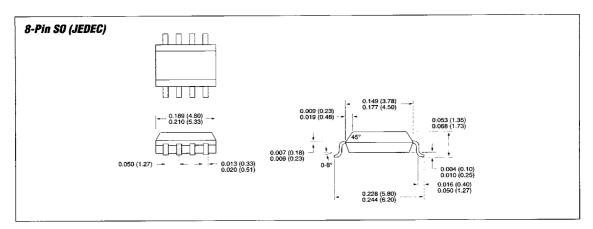
- i) The master must enable writes to the FM25160 by issuing the WREN instruction as shown in Figure 6. Note that /CS must be taken high after the LSB of the WREN instruction is transmitted from the master to the FM25160.
- ii) The master writes the write opcode, byte address, and any number of sequential bytes to the FM25160 as shown in Figure 7. Again, the operation must be terminated by taking /CS high after the LSB in the last byte.



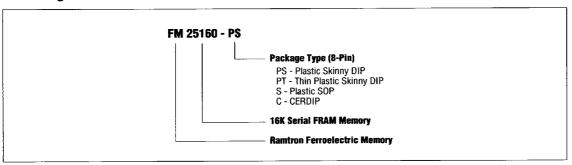


# **Packaging Information**





# **Ordering Information**



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