

SANYO Semiconductors DATA SHEET

Monolithic Digital IC

LB11699H — For CD-ROM Drives Spindle Motor Driver IC

Overview

The LB11699H is a spindle motor driver IC for CD-ROM drives.

Features

• Three-phase brushless motor driver

Functions

- Current linear drive
- Voltage controlled amplifier
- The use of high side current detection means that there is no loss (or voltage drop) due to the current detection resistor.
- Built-in short-circuit braking circuit
- Built-in reverse rotation prevention circuit
- Hall sensor FG output
- Built-in start/stop function
- Built-in current limiter circuit (adjustable)
- Built-in Hall sensor power supply
- Built-in thermal shutdown circuit
- Supports 3.3V DSPs
- Maximum current rating: 2.0A

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Specifications

Maximum Ratings at $Ta = 25^{\circ}C$

Parameter	Symbol	Conditions	Ratings	Unit
Supply voltage1	V _{CC} 1 max		7.0	٧
Supply voltage 2	V _{CC} 2 max		14.4	V
Output apply voltage	V _O max		14.4	٧
Input apply voltage	V _I max		V _{CC} 1	٧
Output current	I _O max		2.0	Α
Allowable internal power	Pd max	Independent IC	0.8	W
dissipation		When mounted on a circuit board *1	1.9	
Operating temperature	Topr		-20 to +75	°C
Storage temperature	Tstg		-55 to +150	°C

^{*1} Specified circuit board : 114.3 \times 76.1 \times 1.6mm³, glass epoxy.

Operating Conditions at $Ta = 25^{\circ}C$

Parameter	Symbol	Conditions	Ratings	Unit
Supply voltage 1	V _{CC} 1		4 to 6	V
Supply voltage 2	V _{CC} ²	≥ V _{CC} 1	4 to 13.6	V

Application Example at $Ta = 25^{\circ}C$

(1) 12V model

Power supply pin	Conditions	Ratings	Unit
V _{CC} 1	Regulated voltage	4 to 6	V
V _{CC} ²	Unregulated voltage	4 to 13.6	V

Electrical Characteristics at Ta = 25°C, V_{CC}1 = 5.0V, V_{CC}2 = 12V (unless otherwise specified)

				-			
Parameter	Symbol	Conditions		Ratings			
Parameter	Symbol	Conditions	min	typ	max	Unit	
Supply Current							
Supply current 1	I _{CC} 1	VC = VCREF		6.0	9.0	mA	
Supply current 2	I _{CC} 2	VC = VCREF			1.0	mA	
Output stop current 1	I _{CC} 10Q	VS/S = 0V			200	μΑ	
Output stop current 2	I _{CC} 2OQ	VS/S = 0V			350	μΑ	
Output Block							
High-side saturation voltage 1	VOU1	I _O = -0.5A		1.0	1.5	V	
Low-side saturation voltage 1	VOD1	I _O = 0.5A		0.3	0.5	V	
High-side saturation voltage 2	VOU2	I _O = -1.5A		1.1	1.8	V	
Low-side saturation voltage 2	VOD2	I _O = 1.5A		0.6	1.2	V	
Hall Sensor Amplifier Block							
Common-mode input voltage range	VHCOM		1.2		V _{CC} 1 -	V	
Input bias current	VHIB			1		μΑ	
Hall sensor minimum input level	VHIN		60			mVp-p	
S/S Pin							
High-level voltage	VS/SH		2.0		V _{CC} 1	V	
Low-level voltage	VS/SL				0.7	V	
Input current	IS/SI	VS/S = 5V			200	μА	
Leakage current	IS/SL	VS/S = 0V	-30			μΑ	

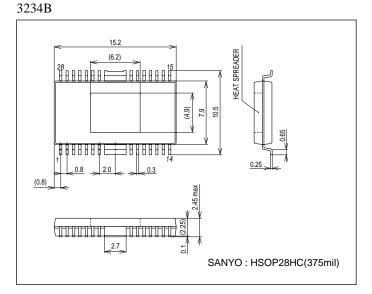
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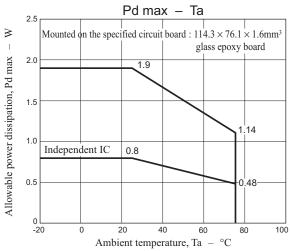
Dorometer	Cuma la al	Conditions	Ratings			Unit	
Parameter	Symbol Conditions		min	typ	max	Onit	
Control Block							
VC pin input current	IVC	VC = VCREF = 1.65V	-1			μΑ	
VCREF pin input current	IVCREF	VC = VCRE F= 1.65V	-1			μΑ	
Voltage gain	GVCO	ΔVRF/ΔVC		0.4		Times/ deg	
Rising voltage	VCTH	VCREF = 1.65V	1.5		1.8	٧	
Rising voltage width	ΔVCTH	VCREF = 1.65V	50		150	mV	
Hall Sensor Power Supply							
Hall sensor supply voltage	VH	I _H = 5mA		0.8		V	
Allowable current	IH		20			mA	
Thermal Shutdown Circuit							
Thermal shutdown operating temperature	TTSD	Design target value*	150	180	210	°C	
Thermal shutdown temperature hysteresis	ΔTTSD	Design target value*		15		°C	
Short-Circuit Braking							
BRAKE pin high-level voltage	VBRH		2.5		5	٧	
BRAKE pin low-level voltage	VBRL		0		1	٧	
Single Hall Sensor/Three Hall Se	nsor FG Switch	ing					
FGSEL pin high-level voltage	VFSH		2.5		5	V	
FGSEL pin low-level voltage	VFSL		0		1	V	
Current Limiter Setting				•			
Current limiter set voltage	VCL1	REF = 0.39Ω, VLMC = VREF		0.4		V	
VLMC pin input voltage range	VLMCC	Design target value*	0		1.3	V	
Reference voltage	VREF	IVREF =10μA		1.25		V	

Note: The Hall comparator output goes to the high level when the S/S pin is in the off state (standby mode).

Package Dimensions

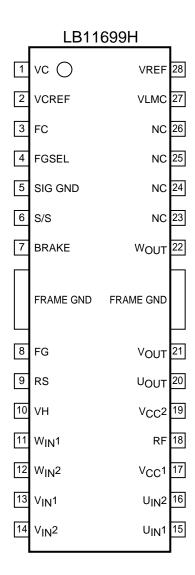
unit: mm (typ)





 $[\]ensuremath{^{\star}}$ The design specification items are design guarantees and are not measured.

Pin Assignment



Top view

Truth Table

	Source → Sink		Input		Comband wells are
	Source → Sink	U	V	W	Control voltage
4	W phase \rightarrow V phase	I II ale	LUmb	1	High
1	$V \text{ phase} \rightarrow W \text{ phase}$	High	High High Low		Low
2	W phase \rightarrow U phase	Llink	Law	Low	High
2	$U\;phase\toW\;phase$	High	Low	Low	Low
3	$V \; phase \rightarrow W \; phase$			Lliab	High
3	W phase \rightarrow V phase	Low	Low	High	Low
4	$U\;phase\toV\;phase$	Low		Low	High
4	$V \ phase \rightarrow U \ phase$	Low	High	LOW	Low
5	V phase \rightarrow U phase	Lliab	1	Lliada	High
5	$\mbox{U phase} \rightarrow \mbox{V phase}$	nign	High Low Hig		Low
6	$U\;phase\toW\;phase$	Low	18.1	115.1	High
О	W phase \rightarrow U phase	LOW	High	High	Low

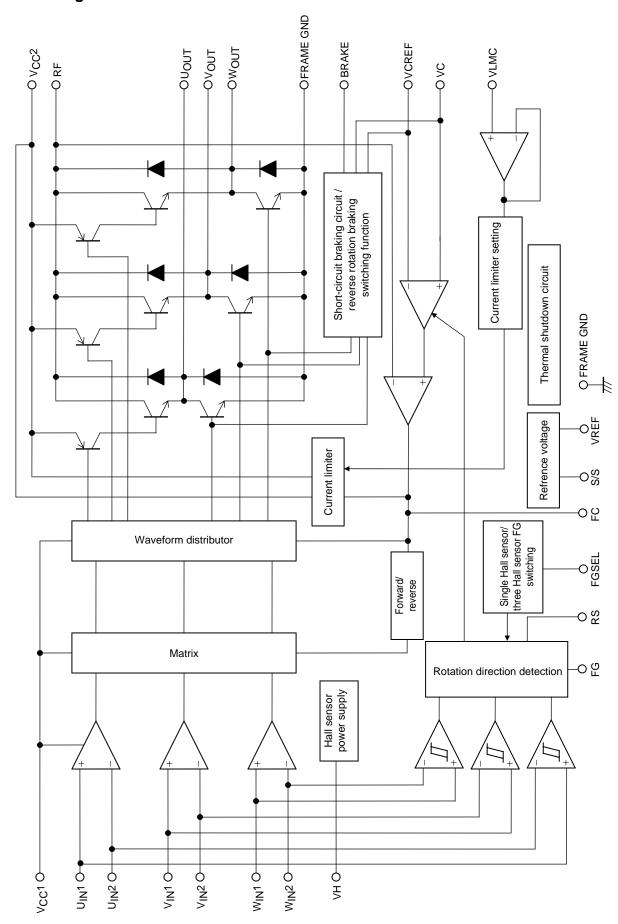
Input high: Input 1 is at least 0.2V higher than input 2 for a given phase.

Input low: Input 2 is at least 0.2V higher than input 1 for a given phase.

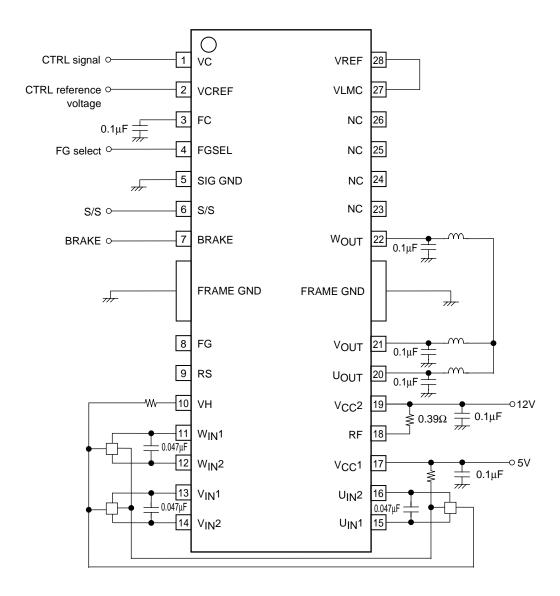
Brake Operation Truth Table

BRAKE pin	Operation at VC < VCREF	
High	Short-circuit braking	
Low or open	Reverse torque braking	

Block Diagrams

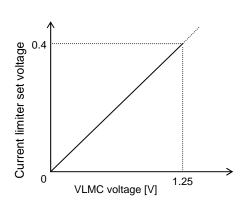


Application Example



The values of the capacitors between power supply and ground, between output and ground, and between the Hall sensor inputs vary depending on the motor used. In particular, the Hall sensor input capacitors may not be required for some motors.

<Information> Current Limiter Setting



The LB11699H current limiter set voltage is the VLMC pin voltage, and varies as shown in the figure to the left. When the VLMC pin voltage is 0V, the current limiter set voltage will be 0V and no output current will flow.

Pin Functions

Pin No.	Pin	Pin	Description	Equivalent Circuit
riii NO.		voltage	Description	Equivalent Circuit
19	V _{CC} ²	4V to 13.6V	Power supply that provides the source side predriver voltage. Power supply that provides the constant current control amplifier voltage.	
17	V _{CC} 1	4V to 6V	Power supply that provides all voltages other than those for the output transistors, the source side predrivers, and the low-current control amplifier.	
9	RS		Reverse rotation detection Outputs a high level for forward rotation. Outputs a low level for reverse rotation.	100μA ↓ 10kΩ ≸
8	FG		One or three Hall sensor Schmitt trigger comparator synthesized output	
15	U _{IN} 1	1.2V to V _{CC} 1-1V	U phase Hall sensor input and reverse rotation detection U phase Schmitt trigger comparator input.	
16	U _{IN} 2		The logical high state indicates the state where $U_{IN}1 > U_{IN}2$.	Vcc1
13	V _{IN} 1		V phase Hall sensor input and reverse rotation detection V phase Schmitt trigger comparator input.	25μA (ψ) (16) (14) (17) (14) (17) (17) (17) (17) (17) (17) (17) (17
14	V _{IN} 2		The logical high state indicates the state where $V_{IN}1 > V_{IN}2$.	25μA ψ 25μA ψ // // // // // // // // // // // // /
11	W _{IN} 1		W phase Hall sensor input and reverse rotation detection W phase Schmitt trigger comparator input.	
12	W _{IN} 2		The logical high state indicates the state where $W_{IN}1 > W_{IN}2$.	
10	VH		Provides the Hall sensor low side device voltage.	75μA ↓
6	S/S	ov to VCC1	All internal circuits are stopped by setting this pin to 0.7V or lower or by setting it open. Set this pin to 2.0V or higher when driving the motor.	V _{CC} 1 75kΩ 75kΩ 50kΩ 75kΩ
5	SIG GND		Ground for all systems except the output	
	1	1	system.	

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Continued from	m preceding pag		T	T
Pin No.	Pin	Pin voltage	Description	Equivalent Circuit
3	FC		Control loop frequency characteristics correction Current control system closed loop oscillations can be prevented by connecting a capacitor between this pin and ground.	Vcc1 \$2kΩ \$20kΩ \$5kΩ
2	VCREF	0V	Control system reference voltage input	
		to V _{CC} 1-1.5V	The control system start voltage is determined by this voltage.	V _C C ¹ 15μA (Ψ) 25μA (Ψ) (Ψ) 15μA
1	VC	ov to Vcc1	Speed control voltage input This is a voltage controlled system in which: The motor turns in the forward direction when VC > VCREF, and The motor turns decelerates when VC < VCREF. (Since the LB11699H includes a reverse rotation prevention circuit, the motor will never turn in the reverse direction.)	100μA 25μA 200Ω 200Ω 200Ω 200Ω 200Ω 200Ω 200Ω 200
22	W _{OUT}		W phase output	
	FRAME GND		Output transistor ground	
21	Vout		V phase output	18
20	UOUT		U phase output	3.9Ω
18	RF		High side output transistor collector (common to all three phases) Connect a resistor between the RF pin and V _{CC} 3 for current detection. The LB11699H detects this voltage to operate the constant current control and current limiter functions.	3.9Ω (20) (21) (22) FRAME GND
27	VLMC	0 to 1.3V	This pin determines the current limiter set voltage. The current limiter set voltage can be changed by applying a voltage to this pin.	Vcc1 6μAΨ 6μAΨ 6μAΨ 200Ω 4π π π π π π
28	VREF		Reference voltage (1.25V typical) output	VCC1 Continued on next page.

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Continued from preceding page Pin Pin No. Pin **Equivalent Circuit** Description voltage 7 **BRAKE** Short-circuit braking pin 0V V_{CC}1 $BRAKE: High \rightarrow brake$ $\text{Low} \to \text{drive}$ V_{CC}1 Open $75k\Omega$ **≶**50kΩ **FGSEL** Single Hall sensor/three Hall sensor FG 4 0V V_CC1 switching pin V_{CC}1 100μΑ FGSEL : High \rightarrow three Hall senso $75k\Omega$ Low → single Hall sensor Open $50k\Omega$

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