

Features

- 16,777,216 word by 4 bit organization
- Single $3.3 \pm 0.3V$ power supply
- Extended Data Out
- \overline{CAS} before \overline{RAS} Refresh
 - 4096 cycles/Retention Time
- \overline{RAS} only Refresh
 - 8192 cycles/Retention Time
- 64ms Standard Power (SP) Retention Time
- 256ms Low Power (LP) Retention Time
- Hidden Refresh
- Self Refresh (400 μA) - LP Version Only

- Read-Modify-Write

- Performance:

		-50	-60
t_{RAC}	\overline{RAS} Access Time	50ns	60ns
t_{CAC}	\overline{CAS} Access Time	13ns	15ns
t_{AA}	Column Address Access Time	25ns	30ns
t_{RC}	Cycle Time	84ns	104ns
t_{HPC}	Hyper Page Mode Cycle Time	20ns	25ns

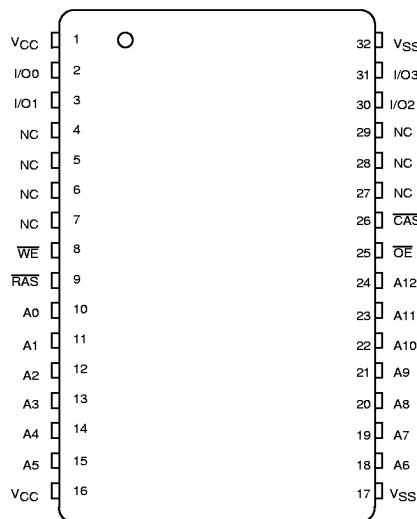
- Low Power Dissipation (-50)
 - Active: 360mW
 - Standby (SP version): 1.0 mA
 - Standby (LP version): 0.2 mA
- Package: SOJ-32(400mil), TSOP-32(400mil)

Description

The IBM0164405B/P is a dynamic RAM organized 16,777,216 words by 4 bits. This device is fabricated in IBM's most advanced CMOS silicon gate process technology. The circuit and process design allow this DRAM to achieve high performance and low power dissipation. The IBM0164405B/P operates with a single $3.3 \pm 0.3V$ power supply, and interfaces directly with either TTL or CMOS levels. The 24 addresses required to access any bit of data are

multiplexed (13 are strobed with \overline{RAS} , 11 are strobed with \overline{CAS}). They are packaged in a 32 pin plastic SOJ (400milx825mil), and a 32 pin plastic TSOP type II (400milx825mil). The IBM0164405P parts are low power devices supporting Self Refresh and a 256ms retention time.

Pin Assignments (Top View)



Pin Description

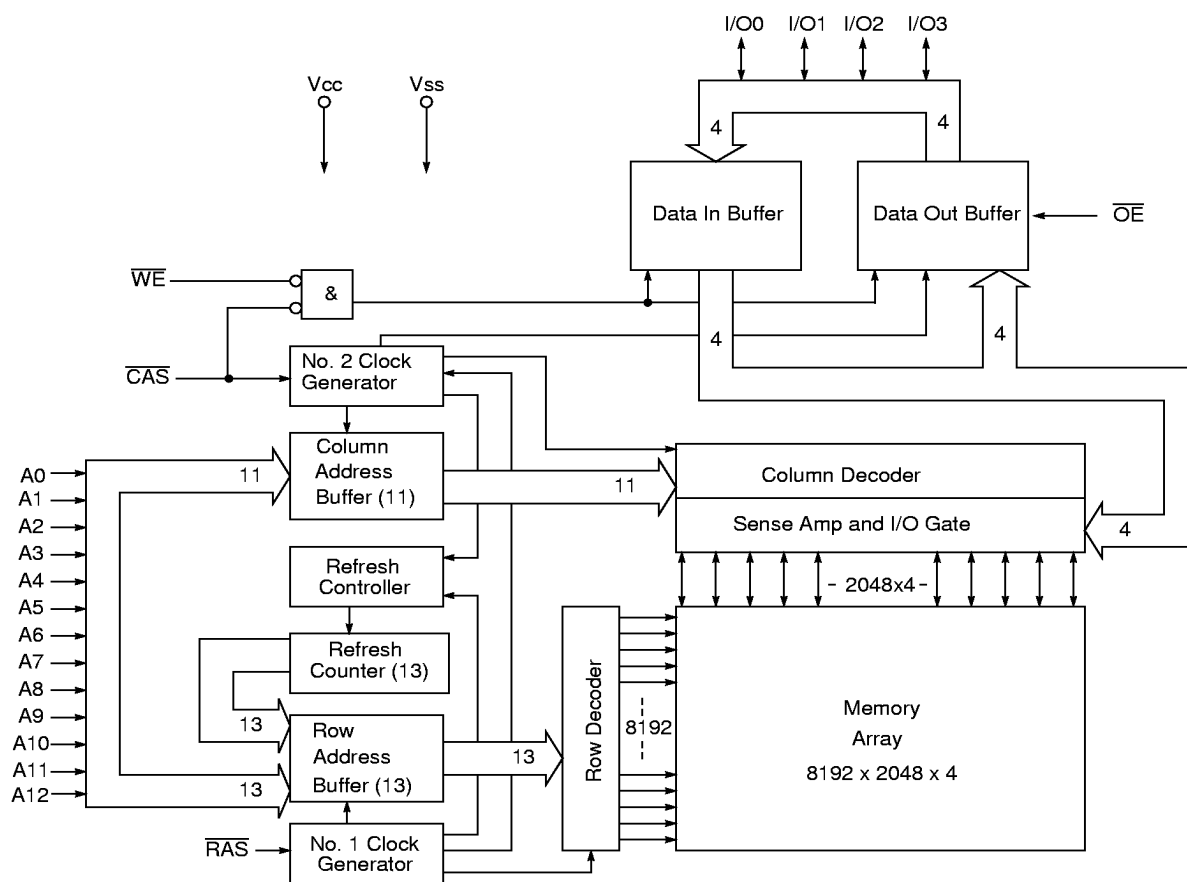
\overline{RAS}	Row Address Strobe
\overline{CAS}	Column Address Strobe
\overline{WE}	Read/write Input
A0 - A12	Address Inputs
\overline{OE}	Output Enable
I/O0 - I/O3	Data Input/output
V_{CC}	Power (+3.3V)
V_{SS}	Ground

Ordering Information

Part Number	Power	Self Refresh	Power Supply	Speed	Package	Notes
IBM0164405BJ3C-50	SP	No	3.3V	50ns	400mil SOJ 32	1
IBM0164405BJ3C-60	SP	No	3.3V	60ns	400mil SOJ 32	1
IBM0164405BT3C-50	SP	No	3.3V	50ns	400mil TSOP 32	1
IBM0164405BT3C-60	SP	No	3.3V	60ns	400mil TSOP 32	1
IBM0164405PT3C-50	LP	Yes	3.3V	50ns	400mil TSOP 32	1
IBM0164405PT3C-60	LP	Yes	3.3V	60ns	400mil TSOP 32	1

1. SP = Standard Power version (IBM0164405B); LP = Low Power version (IBM0164405P)

Block Diagram





Truth Table

Function		$\overline{\text{RAS}}$	$\overline{\text{CAS}}$	$\overline{\text{WE}}$	$\overline{\text{OE}}$	Row Address	Column Address	I/O0 - I/O3
Standby		H	H→X	X	X	X	X	High Impedance
Read		L	L	H	L	Row	Col.	Data Out
Early-Write		L	L	L	X	Row	Col.	Data In
Delayed-Write		L	L	H→L	H	Row	Col.	Data In
Read-Modify-Write		L	L	H→L	L→H	Row	Col.	Data Out, Data In
EDO (Hyper Page) Mode Read	1st Cycle	L	H→L	H	L	Row	Col.	Data Out
	2nd Cycle	L	H→L	H	L	N/A	Col.	Data Out
EDO (Hyper Page) Mode Write	1st Cycle	L	H→L	L	X	Row	Col.	Data In
	2nd Cycle	L	H→L	L	X	N/A	Col.	Data In
EDO (Hyper Page) Mode Read-Modify-Write	1st Cycle	L	H→L	H→L	L→H	Row	Col.	Data Out, Data In
	2nd Cycle	L	H→L	H→L	L→H	N/A	Col.	Data Out, Data In
$\overline{\text{RAS}}$ -Only Refresh		L	H	X	X	Row	N/A	High Impedance
$\overline{\text{CAS}}$ -Before- $\overline{\text{RAS}}$ Refresh		H→L	L	H	X	X	N/A	High Impedance
Hidden Refresh	Read	L→H→L	L	H	L	Row	Col.	Data Out
	Write	L→H→L	L	L→H	X	Row	Col.	Data In
Self Refresh (LP version only)		H→L	L	H	X	X	X	High Impedance

Absolute Maximum Ratings

Symbol	Parameter	Rating	Units	Notes
V_{CC}	Power Supply Voltage	-0.5 to 4.6	V	1
V_{IN}	Input Voltage	-0.5 to min ($V_{CC}+0.5$, 4.6)	V	1
V_{OUT}	Output Voltage	-0.5 to min ($V_{CC}+0.5$, 4.6)	V	1
T_{OPR}	Operating Temperature	0 to +70	°C	1
T_{STG}	Storage Temperature	-55 to +150	°C	1
P_D	Power Dissipation	1.0	W	1
I_{OUT}	Short Circuit Output Current	50	mA	1

1. Stresses greater than those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. This is a stress rating only and functional operation of the device at these or any other conditions above those indicated in the operational sections of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect reliability.

Recommended DC Operating Conditions ($T_A=0$ to 70°C)

Symbol	Parameter	Min.	Typ.	Max.	Units	Notes
V_{CC}	Supply Voltage	3.0	3.3	3.6	V	1
V_{IH}	Input High Voltage	2.0	—	$V_{CC} + 0.3$	V	1,2
V_{IL}	Input Low Voltage	-0.3	—	0.8	V	1,2

1. All voltages referenced to V_{SS} .
2. V_{IH} may overshoot to $V_{CC} + 2.0\text{V}$ for pulse widths of $\leq 4.0\text{ns}$ with 3.3 Volt. V_{IL} may undershoot to -2.0V for pulse widths $\leq 4.0\text{ns}$ with 3.3 Volt. Pulse widths measured at 50% points with amplitude measured peak to DC reference

Capacitance ($T_A=0$ to $+70^{\circ}\text{C}$, $V_{CC}=3.3 \pm 0.3\text{V}$, $f=1\text{MHz}$)

Symbol	Parameter	Min.	Max.	Units	Notes
C_{I1}	Input Capacitance (A0 - A12)	—	5	pF	
C_{I2}	Input Capacitance ($\overline{\text{RAS}}$, $\overline{\text{CAS}}$, $\overline{\text{WE}}$, $\overline{\text{OE}}$)	—	7	pF	
C_{I3}	Data I/O Capacitance (I/O0 - I/O3)	—	7	pF	

DC Electrical Characteristics (T_A = 0 to +70°C, V_{CC} = 3.3 ± 0.3V)

Symbol	Parameter	Min.	Max.	Units	Notes
I _{CC1}	Operating Current Average Power Supply Operating Current (RAS, CAS, Address Cycling: t _{RC} = t _{RC} min)	-50	—	100	mA 1, 2, 3
		-60	—	85	
I _{CC2}	Standby Current (TTL) Power Supply Standby Current (RAS = CAS = V _{IH})	—	2	mA	
I _{CC3}	RAS Only Refresh Current Average Power Supply Current, RAS Only Mode (RAS Cycling, CAS = V _{IH} : t _{RC} = t _{RC} min)	-50	—	100	mA 1, 3
		-60	—	85	
I _{CC4}	EDO Mode Current Average Power Supply Current, Hyper Page Mode (RAS = V _{IL} , CAS, Address Cycling: t _{PC} = t _{PC} min)	-50	—	100	mA 1, 2, 3
		-60	—	80	
I _{CC5}	Standby Current (CMOS) Power Supply Standby Current (RAS = CAS = V _{CC} - 0.2V)	LP version	—	200	μA
		SP version	—	1	mA
I _{CC6}	CAS Before RAS Refresh Current Average Power Supply Current, CAS Before RAS Mode (RAS, CAS, Cycling: t _{RC} = t _{RC} min)	-50	—	140	mA 1, 2
		-60	—	115	
I _{CC7}	Self Refresh Current (LP version only) Average Power Supply Current during Self Refresh CBR cycle with RAS ≥ t _{RASS} (min); CAS held low; WE = V _{CC} - 0.2V; Addresses and D _{IN} = V _{CC} - 0.2V or 0.2V.	—	400	μA	
I _{I(L)}	Input Leakage Current Input Leakage Current, any input (0.0 ≥ V _{IN} ≥ V _{CC}), All Other Pins Not Under Test = 0V	-2	+2	μA	
I _{O(L)}	Output Leakage Current (D _{OUT} is disabled, 0.0 ≥ V _{OUT} ≥ V _{CC})	-2	+2	μA	
V _{OH}	Output High Level (TTL) Output "H" Level Voltage (I _{OUT} = -2mA)	2.4	—	V	
V _{OL}	Output Low Level (TTL) Output "L" Level Voltage (I _{OUT} = +2mA)	—	0.4	V	
1. I _{CC1} , I _{CC3} , I _{CC4} , I _{CC6} depend on cycle rate. 2. I _{CC1} , I _{CC4} depend on output loading. Specified values are obtained with the output open. 3. Column address can be changed once or less while RAS = V _{IL} and CAS = V _{IH} .					

AC Characteristics ($T_A=0$ to $+70^\circ\text{C}$, $V_{CC}=3.3 \pm 0.3\text{V}$)

1. An initial pause of 100 μs is required after power-up followed by 8 $\overline{\text{RAS}}$ only refresh cycles before proper device operation is achieved. In case of using internal refresh counter, a minimum of 8 $\overline{\text{CAS}}$ before $\overline{\text{RAS}}$ refresh cycles instead of 8 $\overline{\text{RAS}}$ only refresh cycles is required.
2. AC measurements assume $t_T=2\text{ns}$.
3. $V_{IH}(\text{min.})$ and $V_{IL}(\text{max.})$ are reference levels for measuring timing of input signals. Also, transition times are measured between V_{IH} and V_{IL} .
4. Valid column addresses are only A0 through A10

Read, Write, Read-Modify-Write and Refresh Cycle (Common Parameters)

Symbol	Parameter	-50		-60		Units	Notes
		Min.	Max.	Min.	Max.		
t_{RC}	Random Read or Write Cycle Time	84	—	104	—	ns	1
t_{RP}	$\overline{\text{RAS}}$ Precharge Time	30	—	40	—	ns	
t_{CP}	$\overline{\text{CAS}}$ Precharge Time	8	—	10	—	ns	
t_{RAS}	$\overline{\text{RAS}}$ Pulse Width	50	100k	60	100k	ns	1
t_{CAS}	$\overline{\text{CAS}}$ Pulse Width	8	100k	10	100k	ns	1
t_{ASR}	Row Address Setup Time	0	—	0	—	ns	
t_{RAH}	Row Address Hold Time	7	—	10	—	ns	
t_{ASC}	Column Address Setup Time	0	—	0	—	ns	
t_{CAH}	Column Address Hold Time	7	—	10	—	ns	
t_{RCD}	$\overline{\text{RAS}}$ to $\overline{\text{CAS}}$ Delay Time	11	37	14	45	ns	2
t_{RAD}	$\overline{\text{RAS}}$ to Col. Address Delay Time	9	25	12	30	ns	3
t_{RSH}	$\overline{\text{RAS}}$ Hold Time	8	—	10	—	ns	
t_{CSH}	$\overline{\text{CAS}}$ Hold Time	40	—	50	—	ns	1
t_{CRP}	$\overline{\text{CAS}}$ to $\overline{\text{RAS}}$ Precharge Time	5	—	5	—	ns	1
t_{DZO}	$\overline{\text{OE}}$ Delay Time From D_{IN}	0	—	0	—	ns	4
t_{DZC}	$\overline{\text{CAS}}$ Delay Time From D_{IN}	0	—	0	—	ns	4
t_T	Transition Time (Rise and Fall)	1	50	1	50	ns	6

1. In a Test Mode Read cycle, the value of t_{RAC} , t_{AA} , t_{CAC} and t_{CPA} are delayed by 5ns from the specified value. These parameters must be adjusted in Test Mode cycles by adding 5ns to the specified value. Associated timings must also be adjusted by 5ns.
2. Operation within the $t_{RCD}(\text{max.})$ limit ensures that $t_{RAC}(\text{max.})$ can be met. $t_{RCD}(\text{max.})$ is specified as a reference point only. If t_{RCD} is greater than the specified $t_{RCD}(\text{max.})$ limit, then access time is controlled by t_{CAC} .
3. Operation within the $t_{RAD}(\text{max.})$ limit ensures that $t_{RAC}(\text{max.})$ can be met. $t_{RAD}(\text{max.})$ is specified as a reference point only. If t_{RAD} is greater than the specified $t_{RAD}(\text{max.})$ limit, then access time is controlled by t_{AA} .
4. Either t_{DZC} or t_{DZO} must be satisfied.
5. AC measurements assume $t_T = 2\text{ns}$.



Write Cycle

Symbol	Parameter	-50		-60		Units	Notes
		Min.	Max.	Min.	Max.		
t_{WCS}	Write Command Set Up Time	0	—	0	—	ns	1
t_{WCH}	Write Command Hold Time	7	—	10	—	ns	
t_{WP}	Write Command Pulse Width	7	—	10	—	ns	
t_{RWL}	Write Command to \overline{RAS} Lead Time	8	—	10	—	ns	
t_{CWL}	Write Command to \overline{CAS} Lead Time	8	—	10	—	ns	
t_{OED}	\overline{OE} to D_{IN} Delay Time	13	—	15	—	ns	2
t_{DS}	D_{IN} Setup Time	0	—	0	—	ns	3
t_{DH}	D_{IN} Hold Time	7	—	10	—	ns	3

1. t_{WCS} , t_{RWD} , t_{CWD} , t_{AWD} and t_{CPWD} are not restrictive operating parameters. They are included in the data sheet as electrical characteristics only. If $t_{WCS} \geq t_{WCS}(\text{min.})$, the cycle is an early write cycle and the data pin will remain open circuit (high impedance) through the entire cycle. If $t_{RWD} \geq t_{RWD}(\text{min.})$, $t_{CWD} \geq t_{CWD}(\text{min.})$, $t_{AWD} \geq t_{AWD}(\text{min.})$, and $t_{CPWD} \geq t_{CPWD}(\text{min.})$ (Fast Page Mode), the cycle is a Read-Modify-Write cycle and the data out will contain data read from the selected cell. If neither of the above sets of conditions is satisfied, the condition of the data out (at access time) is indeterminate.
2. Either t_{CDD} or t_{OED} must be satisfied.
3. These parameters are referenced to \overline{CAS} leading edge in early write cycles and to \overline{WE} leading edge in Read-Modify-Write cycles.



Read Cycle

Symbol	Parameter	-50		-60		Units	Notes
		Min.	Max.	Min.	Max.		

Read Cycle

Symbol	Parameter	-50		-60		Units	Notes
		Min.	Max.	Min.	Max.		
t_{RAC}	Access Time from \overline{RAS}	—	50	—	60	ns	1, 2, 3, 5
t_{CAC}	Access Time from \overline{CAS}	—	13	—	15	ns	1, 2, 5
t_{AA}	Access Time from Address	—	25	—	30	ns	1, 2, 5
t_{OEA}	Access Time From \overline{OE}	—	13	—	15	ns	1, 5
t_{RCS}	Read Command Setup Time	0	—	0	—	ns	
t_{RCH}	Read Command Hold Time to \overline{CAS}	0	—	0	—	ns	6
t_{RRH}	Read Command Hold Time to \overline{RAS}	0	—	0	—	ns	
t_{RAL}	Column Address to \overline{RAS} Lead Time	25	—	30	—	ns	1
t_{CLZ}	\overline{CAS} to Output in Low-Z	0	—	0	—	ns	5
t_{OEZ}	Output Buffer Turn-Off Delay From \overline{OE}	0	13	0	15	ns	7
t_{CDD}	\overline{CAS} to D_{IN} Delay Time	13	—	15	—	ns	4
t_{OFF}	Output Buffer Turn-Off Delay	0	13	0	15	ns	7
t_{OES}	\overline{OE} Setup Time Prior to \overline{CAS}	5	—	5	—	ns	
t_{ORD}	\overline{OE} Setup Time Prior to \overline{RAS} (Hidden Refresh)	0	—	0	—	ns	

1. In a Test Mode Read cycle, the value of t_{RAC} , t_{AA} , t_{CAC} and t_{CPA} are delayed by 5ns from the specified value. These parameters must be adjusted in Test Mode cycles by adding 5ns to the specified value. Associated timings must also be adjusted by 5ns.
2. Operation within the $t_{RCD}(\max.)$ limit ensures that $t_{RAC}(\max.)$ can be met. $t_{RCD}(\max.)$ is specified as a reference point only. If t_{RCD} is greater than the specified $t_{RCD}(\max.)$ limit, then access time is controlled by t_{CAC} .
3. Operation within the $t_{RAD}(\max.)$ limit ensures that $t_{RAC}(\max.)$ can be met. $t_{RAD}(\max.)$ is specified as a reference point only. If t_{RAD} is greater than the specified $t_{RAD}(\max.)$ limit, then access time is controlled by t_{AA} .
4. Either t_{CDD} or t_{OED} must be satisfied.
5. Measured with the specified current load and 100pF.
6. Either t_{RCH} or t_{RRH} must be satisfied for a read cycle.
7. $t_{OFF}(\max.)$ and $t_{OEZ}(\max.)$ define the time at which the output achieves the open circuit condition and are not referenced to output voltage levels.

Read-Modify-Write Cycle

Symbol	Parameter	-50		-60		Units	Notes
		Min.	Max.	Min.	Max.		
t_{RWC}	Read-Modify-Write Cycle Time	109	—	135	—	ns	
t_{RWD}	\overline{RAS} to \overline{WE} Delay Time	65	—	79	—	ns	1
t_{CWD}	\overline{CAS} to \overline{WE} Delay Time	28	—	34	—	ns	1
t_{AWD}	Column Address to \overline{WE} Delay Time	40	—	49	—	ns	1
$t_{OE H}$	\overline{OE} Command Hold Time	7	—	10	—	ns	

1. t_{WCS} , t_{RWD} , t_{CWD} , t_{AWD} and t_{CPWD} are not restrictive operating parameters. They are included in the data sheet as electrical characteristics only. If $t_{WCS} \geq t_{WCS}(\text{min.})$, the cycle is an early write cycle and the data pin will remain open circuit (high impedance) through the entire cycle. If $t_{RWD} \geq t_{RWD}(\text{min.})$, $t_{CWD} \geq t_{CWD}(\text{min.})$, $t_{AWD} \geq t_{AWD}(\text{min.})$, and $t_{CPWD} \geq t_{CPWD}(\text{min.})$ (Fast Page Mode), the cycle is a Read-Modify-Write cycle and the data out will contain data read from the selected cell. If neither of the above sets of conditions is satisfied, the condition of the data out (at access time) is indeterminate.

Extended Data Out (Hyper Page) Mode Cycle

Symbol	Parameter	-50		-60		Units	Notes
		Min.	Max.	Min.	Max.		
t_{HCAS}	\overline{CAS} Pulse Width (Hyper Page Mode)	8	100K	10	10K	ns	
t_{HPC}	Hyper Page Mode Cycle Time (Read/Write)	20	—	25	—	ns	
t_{HPRWC}	Hyper Page Mode Read Modify Write Cycle Time	54	—	66	—	ns	
t_{DOH}	Data-out Hold Time from \overline{CAS}	5	—	5	—	ns	
t_{WHZ}	Output buffer Turn-Off Delay from \overline{WE}	0	10	0	10	ns	
t_{WPZ}	\overline{WE} Pulse Width to Output Disable at \overline{CAS} High	7	—	10	—	ns	
t_{CPRH}	\overline{RAS} Hold Time from \overline{CAS} Precharge	27	—	35	—	ns	
t_{CPA}	Access Time from \overline{CAS} Precharge	—	27	—	35	ns	1
t_{RASP}	Hyper Page Mode \overline{RAS} Pulse Width	50	200K	60	200K	ns	
t_{OEP}	\overline{OE} High Pulse Width	5	—	10	—	ns	
t_{OEHC}	\overline{OE} High Hold Time from \overline{CAS} High	5	—	10	—	ns	

1. Measured with the specified current load and 100pF at $V_{OL} = 0.8V$ and $V_{OH} = 2.0V$.

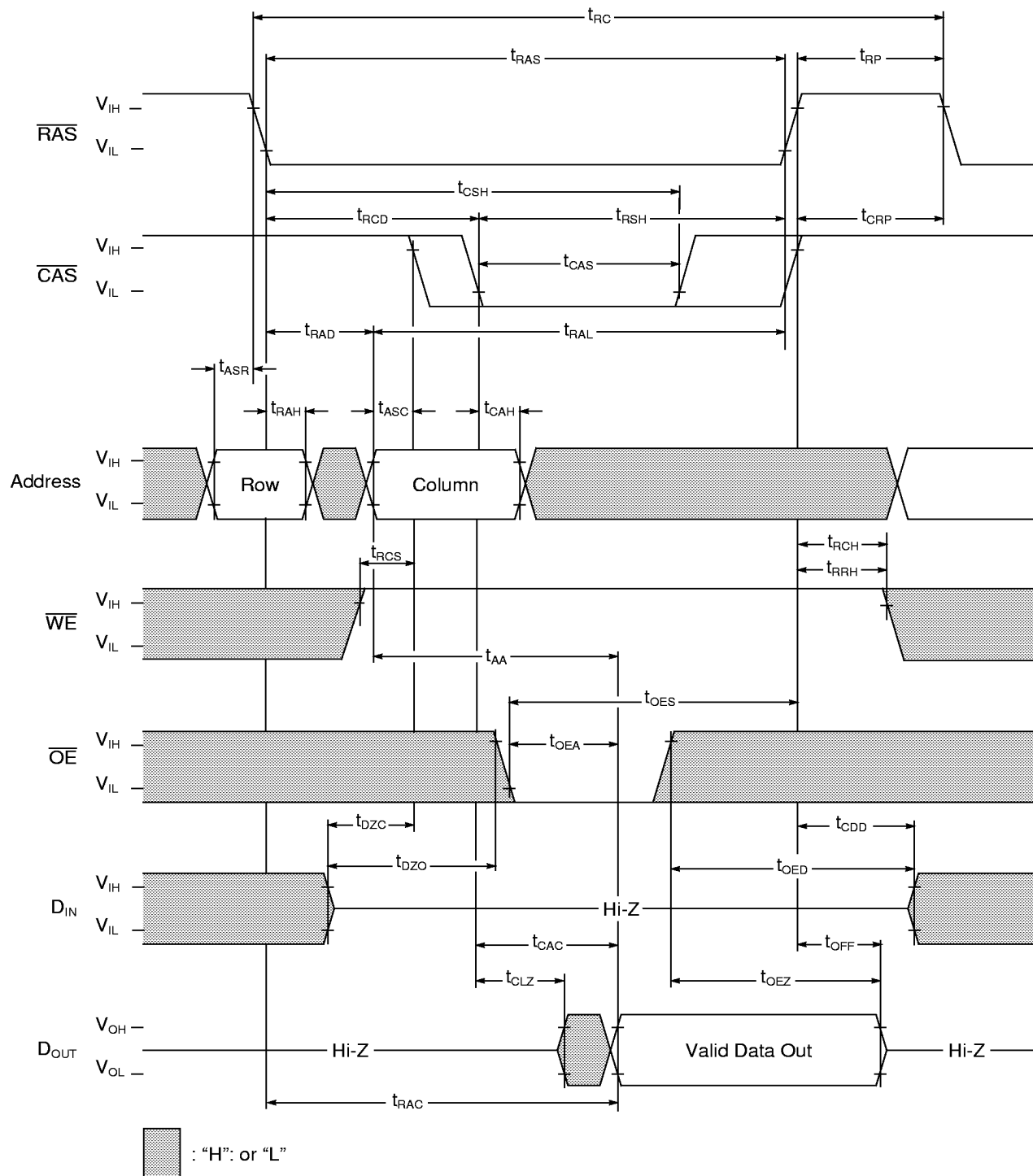
Self Refresh Cycle - Low Power Version Only

Symbol	Parameter	-50		-60		Units	Notes
		Min.	Max.	Min.	Max.		
t_{RASS}	RAS Pulse Width During Self Refresh Cycle	100	—	100	—	μs	1
t_{RPS}	RAS Precharge Time During Self Refresh Cycle	84	—	104	—	ns	1
t_{CHS}	CAS Hold Time During Self Refresh Cycle	-50	—	-50	—	ns	1
1. When using Self Refresh mode, the following refresh operations must be performed to ensure proper DRAM operation: If row addresses are being refreshed in an EVENLY DISTRIBUTED manner over the refresh interval using CBR refresh cycles, then only one CBR cycle must be performed immediately after exit from Self Refresh. If row addresses are being refreshed in any other manner (ROR- Distributed/Burst; or CBR-Burst) over the refresh interval, then a full set of row refreshes must be performed immediately before entry to and immediately after exit from Self Refresh.							

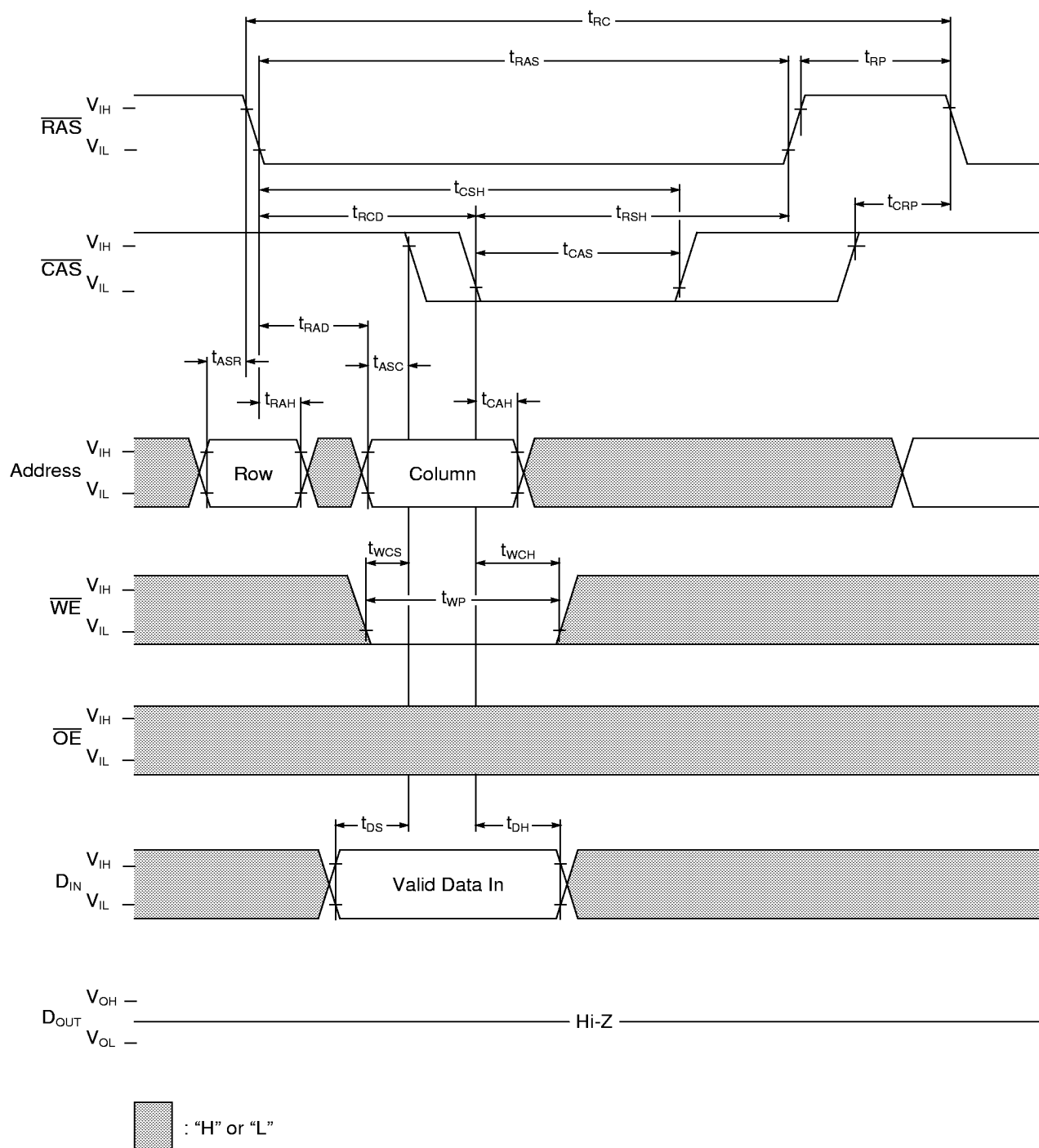
Refresh Cycle

Symbol	Parameter		-50		-60		Units	Notes
			Min.	Max.	Min.	Max.		
t _{CSR}	CAS Setup Time (CAS before RAS Refresh Cycle)		5	—	5	—	ns	
t _{CHR}	CAS Hold Time (CAS before RAS Refresh Cycle)		5	—	10	—	ns	
t _{WRP}	WE Setup Time (CAS before RAS Refresh Cycle)		5	—	10	—	ns	
t _{WRH}	WE Hold Time (CAS before RAS Refresh Cycle)		5	—	10	—	ns	
t _{RPC}	RAS Precharge to CAS Hold Time		5	—	5	—	ns	
t _{REF}	Refresh Period	SP version	—	64	—	64	ms	1
		LP version	—	256	—	256		
1. 8192 cycles for RAS Only Refresh; 4096 cycles for CBR Refresh.								

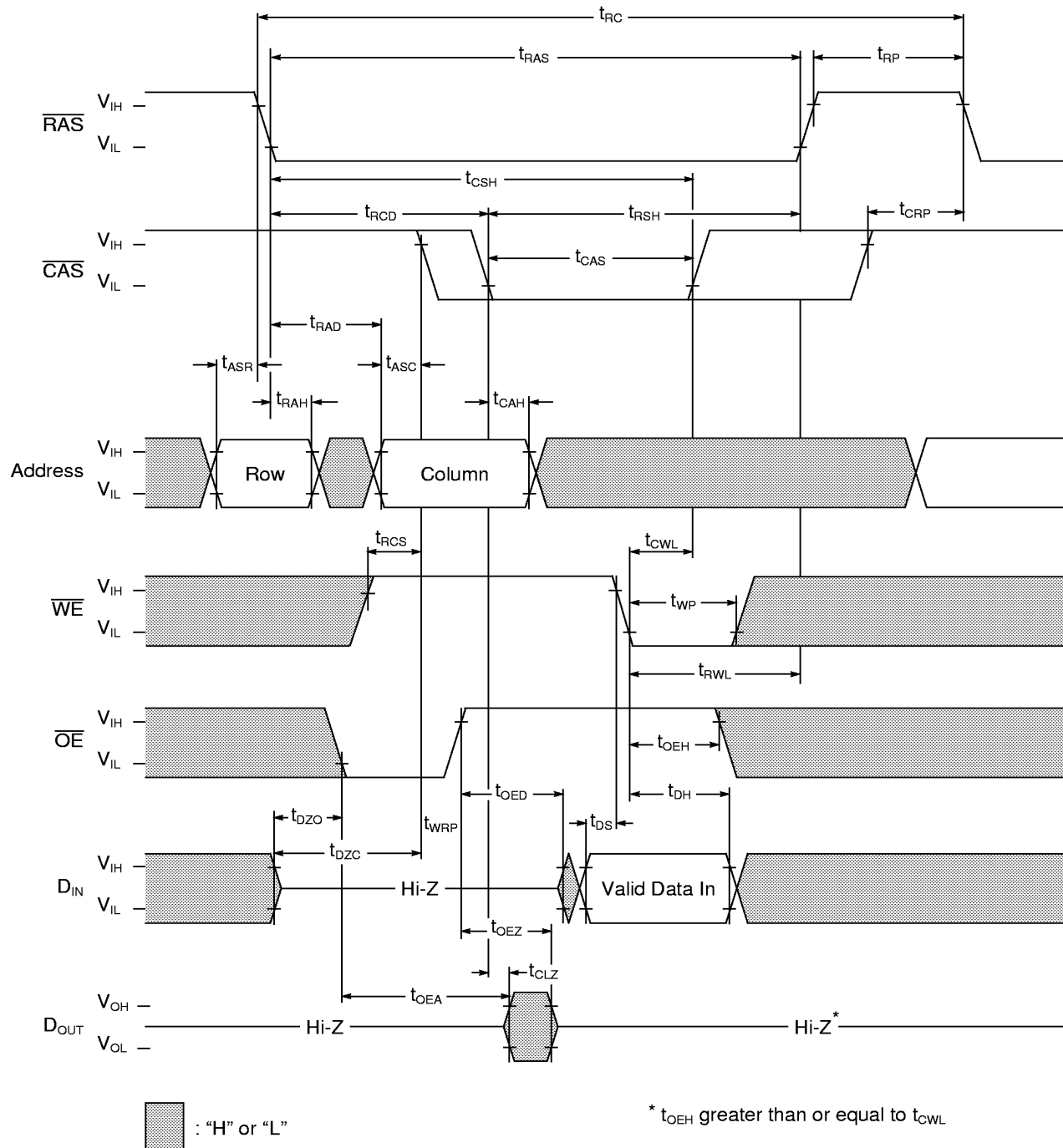
Read Cycle



Write Cycle (Early Write)



Write Cycle (Delayed Write)



The diagram illustrates the timing relationships between several control and data signals during memory access operations. The signals shown are:

- RAS**: Row Address Strobe, active low.
- CAS**: Column Address Strobe, active low.
- Address**: Memory address bus, showing Row, Column 1, Column 2, ..., Column N.
- WE**: Write Enable, active low.
- OE**: Output Enable, active low.
- D_{OUT}**: Data output bus, showing Hi-Z state and Data Out 1, Data Out 2, ..., Data Out N.

Key timing parameters labeled include:

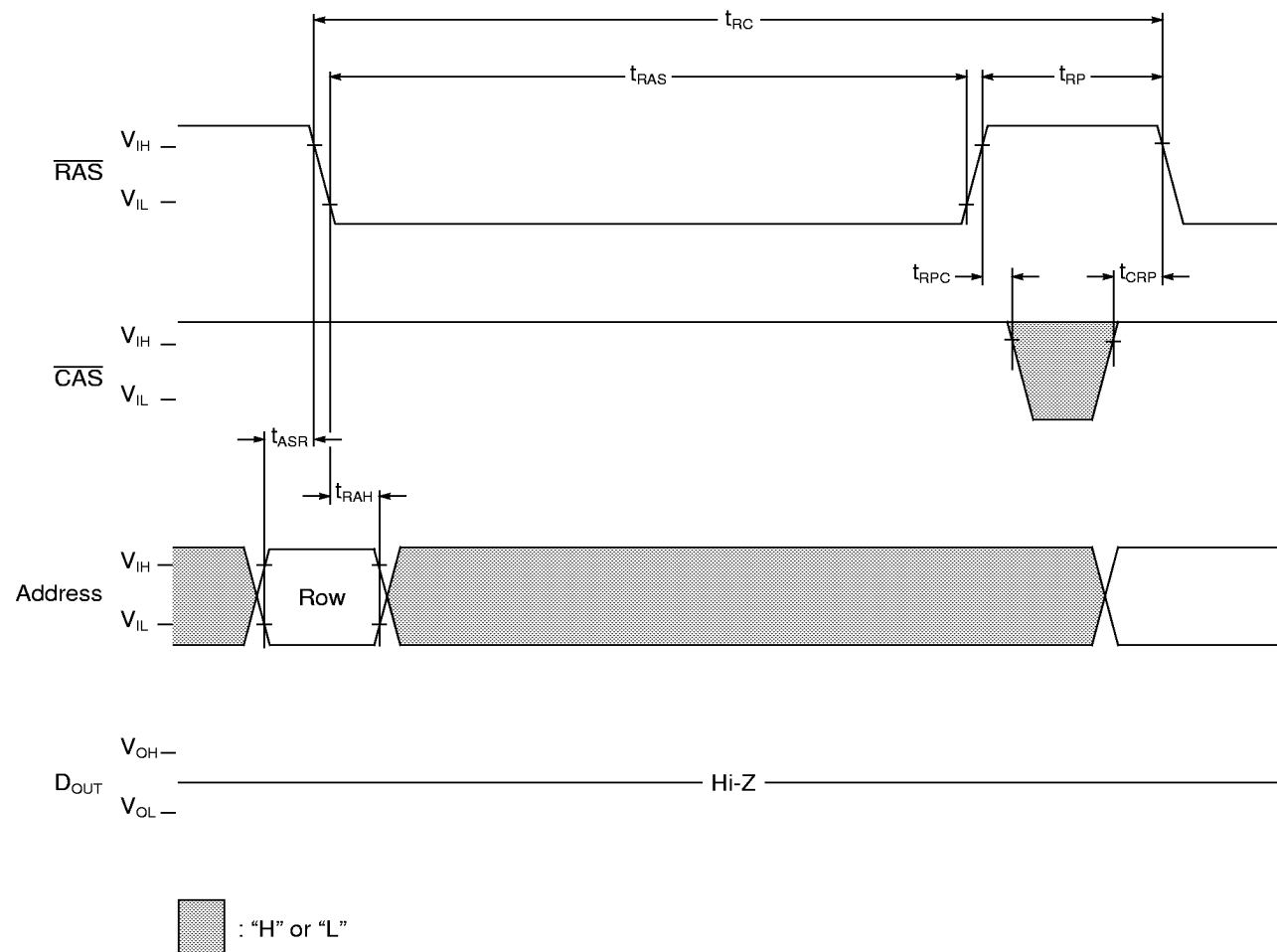
- t_{RASP} : RAS pulse width.
- t_{CPRH} : CAS precharge time from RAS high to CAS high.
- t_{CRP} : CAS rise time.
- t_{TRP} : RAS recovery time after RAS high.
- t_{RCD} : Row to column delay.
- t_{HPC} : Horizontal precharge time.
- t_{CP} : Column precharge time.
- t_{HCAS} : High-to-low transition time of CAS.
- t_{CSH} : Low-to-high transition time of CAS.
- t_{ASC} : Address setup time before CAS.
- t_{CAH} : Address hold time after CAS.
- t_{RAL} : Read after write latency.
- t_{RAD} : Row address delay.
- t_{RAS} : RAS setup time before WE.
- t_{RCH} : RAS high-to-low transition time.
- t_{RRH} : RAS recovery time after RAS high.
- t_{CAC} : Column access time.
- t_{CPA} : Column precharge time.
- t_{AA} : Access time.
- t_{DOH} : Data output hold time.
- t_{CLZ} : Column load time.
- t_{OES} : Output enable setup time.
- t_{OEA} : Output enable arrival time.
- t_{TOFF} : Turn-off time.
- t_{WTP} : Write time period.
- t_{OEZ} : Output enable zero current time.

A legend at the bottom indicates that shaded areas represent "H" or "L" levels.

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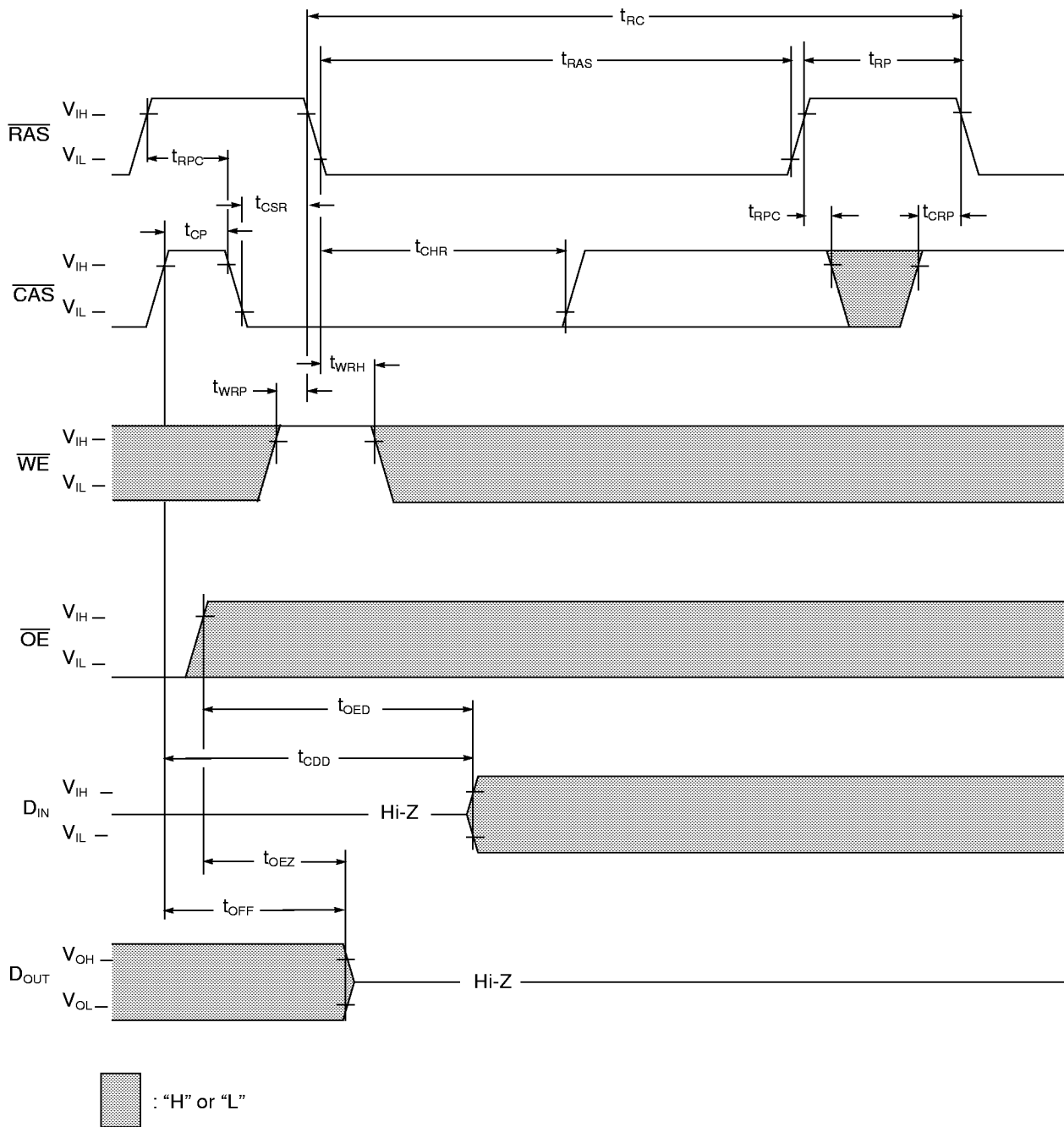
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$\overline{\text{RAS}}$ Only Refresh Cycle



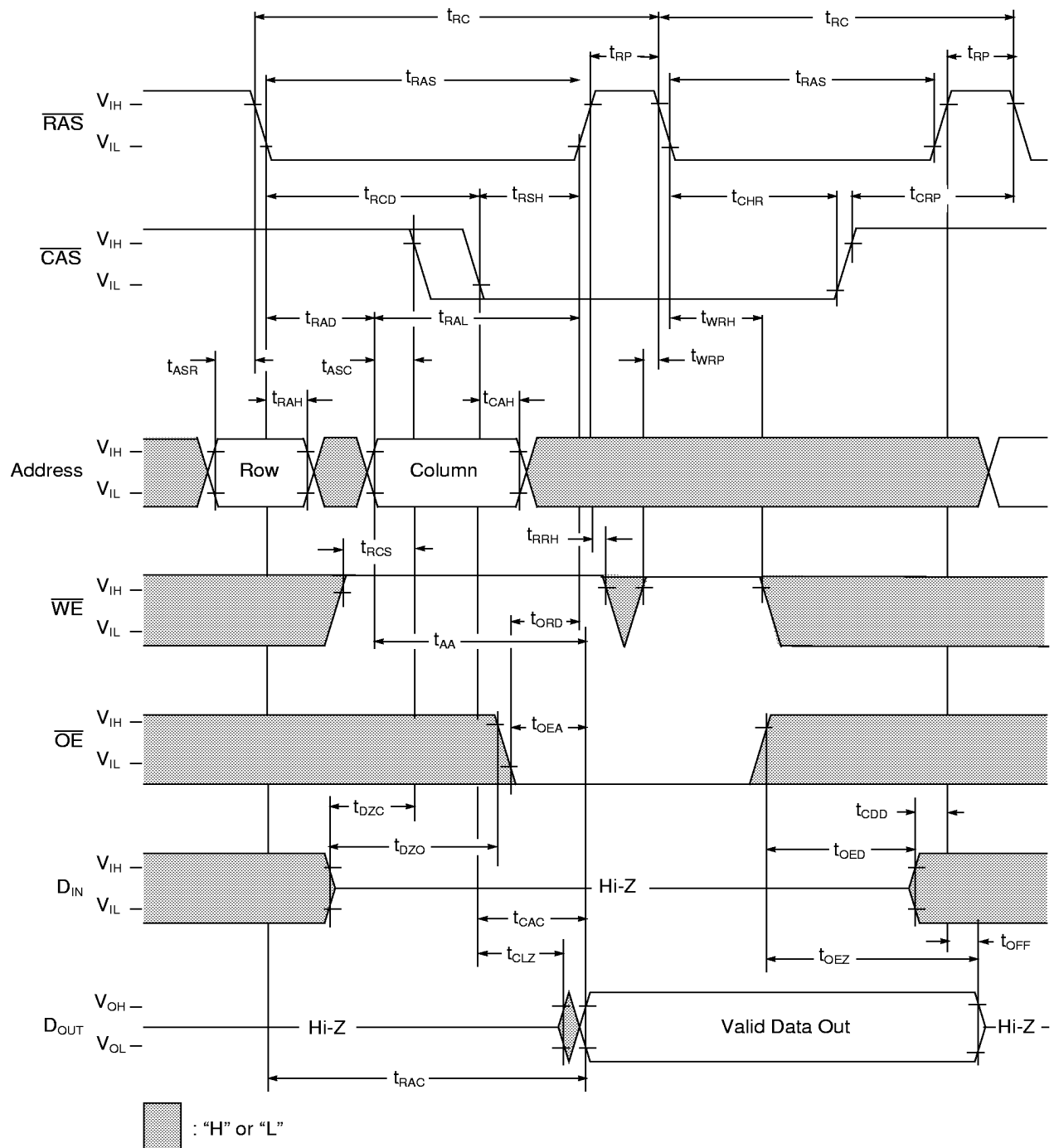
NOTE: $\overline{\text{WE}}$, $\overline{\text{OE}}$ and D_{IN} are "H" or "L"

CAS Before RAS Refresh Cycle

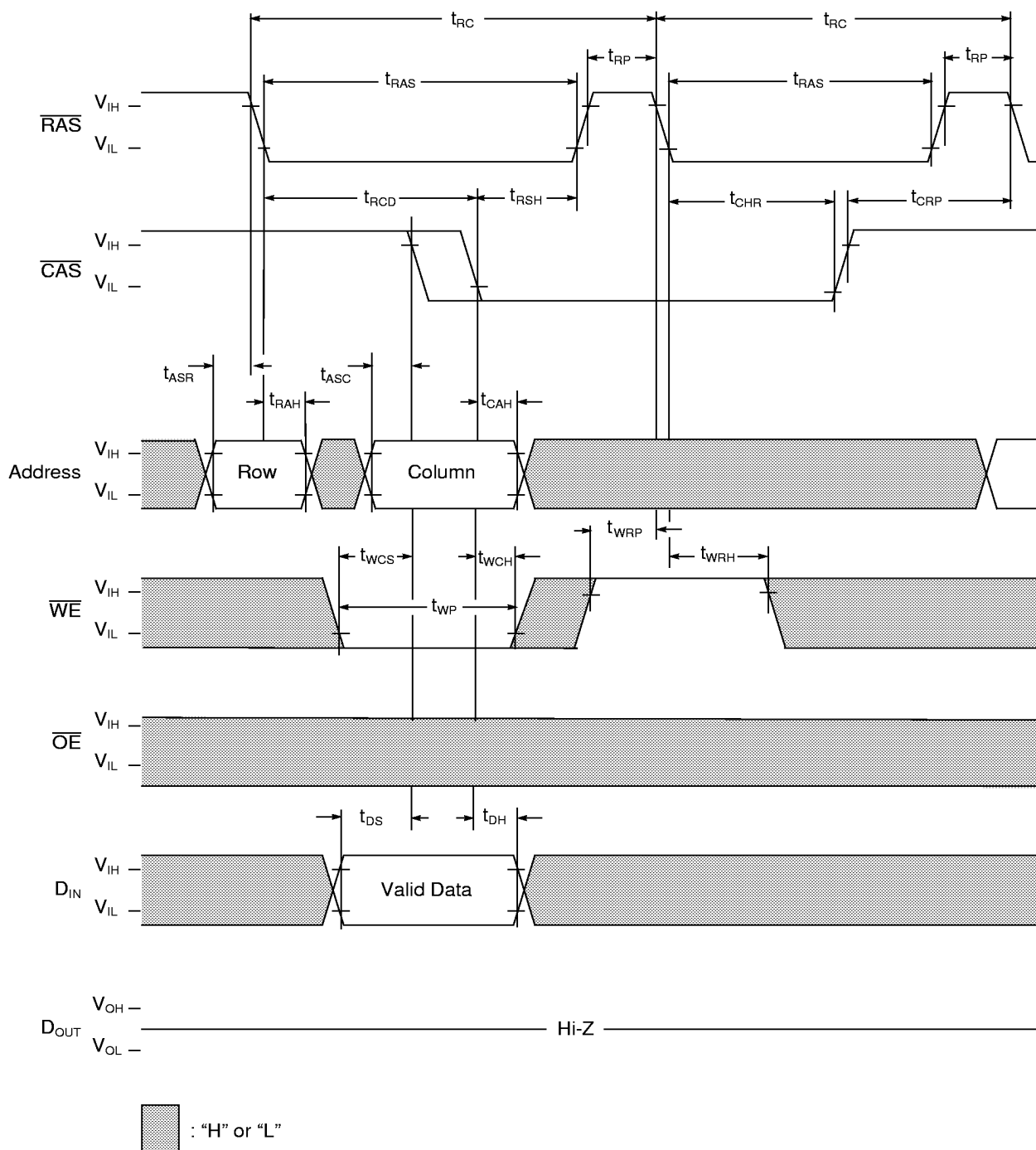


NOTE: Address is "H" or "L"

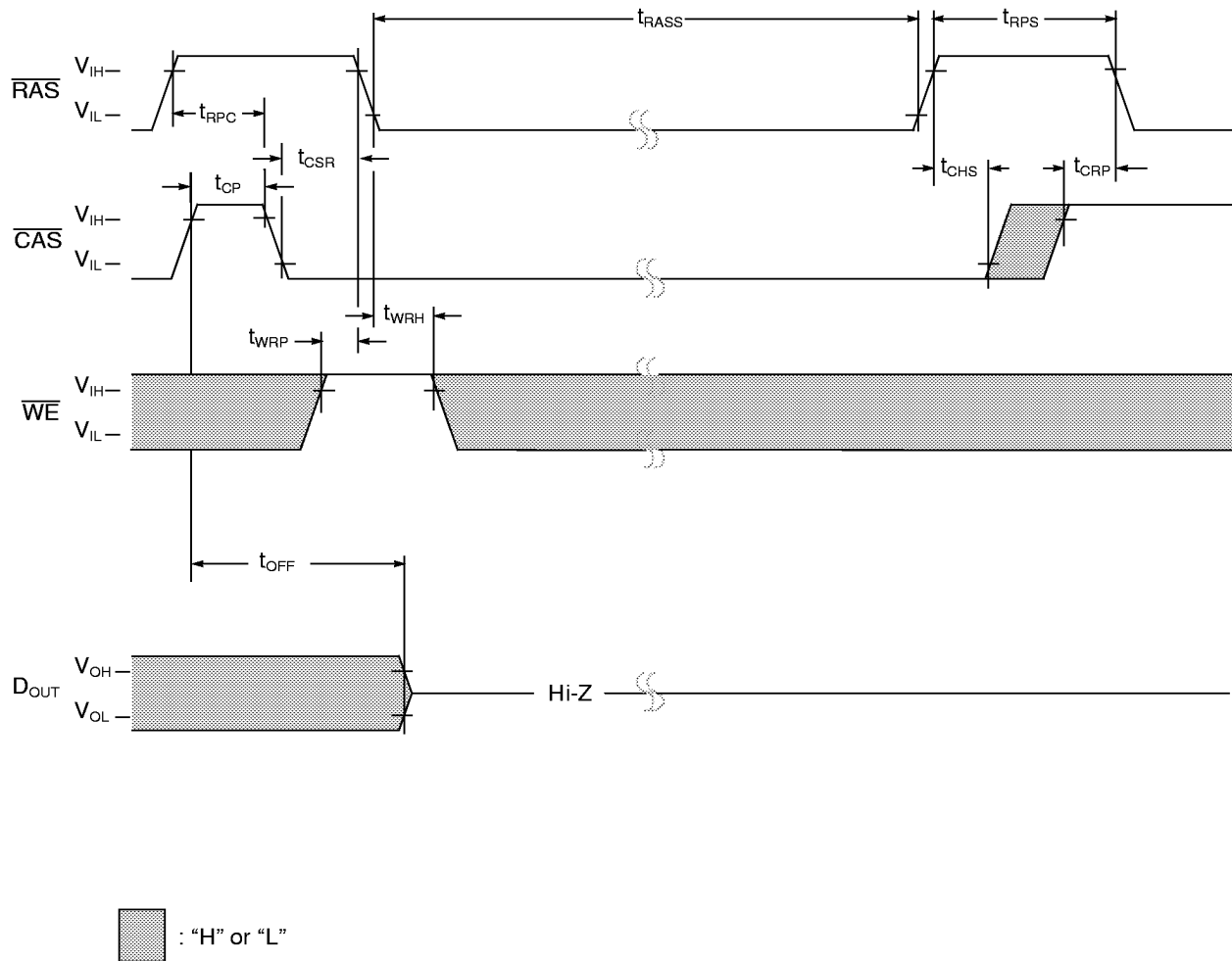
Hidden Refresh Cycle (Read)



Hidden Refresh Cycle (Write)



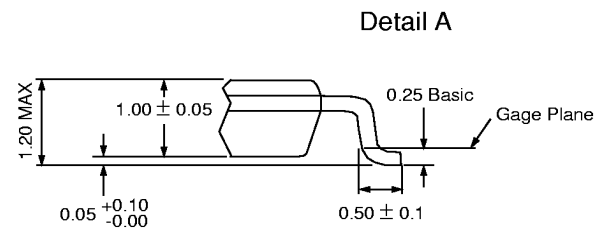
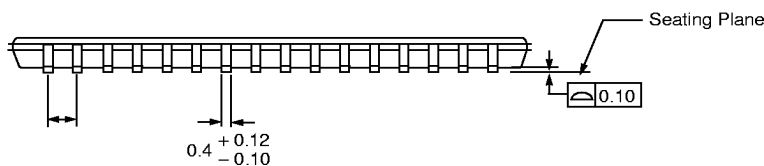
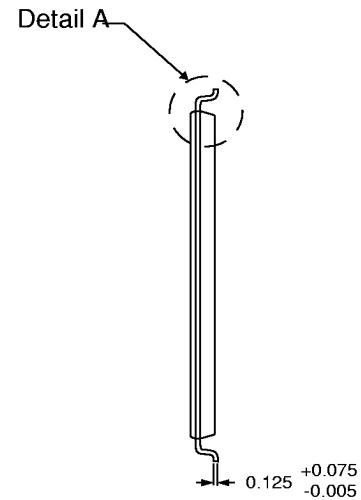
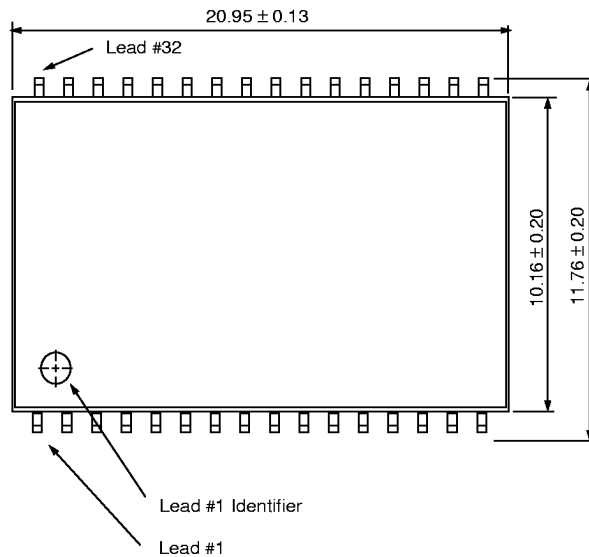
Self Refresh Cycle (Sleep Mode) - Low Power version only



NOTE: Address and OE are "H" or "L"

Once t_{RASS} (min) is provided and RAS remains low, the DRAM will be in Self Refresh, commonly known as "Sleep Mode."

Package Dimensions (400 mil; 32lead; Thin Small Outline Package)



NOTE: All dimensions are in millimeters. Reference JEDEC Standard MS-24

Revision Log

Revision	Contents of Modification
1/2/97	Initial specification release.
03/19/97	<ol style="list-style-type: none">1. \overline{WE} for the Hidden Refresh Write cycle in the Truth Table was changed from "H" to "L→H".2. t_{OED} was moved from the Common Parameters table to the Write Cycle Parameters Table.3. The note "Implementing \overline{WE} at \overline{RAS} time during a Read or Write cycle is optional. Doing so will facilitate compatibility with future EDO DRAMs." was removed from all of the Read and Write timing diagrams.4. t_{ODD} was changed to t_{OED} in notes in the Write Cycle and Read Cycle Parameters tables.5. "Hyper Page Mode" was changed to "EDO (Hyper Page) Mode" in the timing diagram titles.6. Removed the Test Mode parameters and timing diagrams.7. LVTTTL/LVCMOS changed to TTL/CMOS.8. LVCMOS currents were removed.9. Power numbers on the spec cover were recalculated.