

June 1989

CMOS Programmable Interval Timer

Features

- This Circuit is Processed in Accordance to Mil-Std-883 and is Fully Conformant Under the Provisions of Paragraph 1.2.1.
- Compatible with NMOS 8254
 - ▶ Enhanced Version of NMOS 8253
- 8MHz Clock Input Frequency
- Three Independent 16 Bit Counters
- Six Programmable Counter Modes
- Status Read Back Command
- Binary or BCD Counting
- Fully TTL Compatible
- Scaled SAJI IV CMOS Process
- Single 5V Power Supply
- Low Power - ICCSB = 10 μ A
- Military Operating Temperature Range -55°C to +125°C

Description

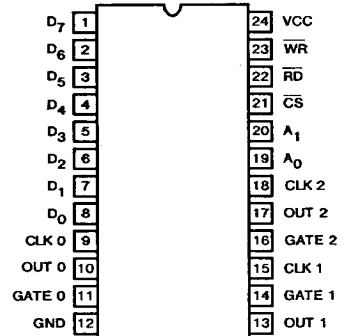
The Harris 82C54/883 is a high performance CMOS Programmable Interval Timer manufactured using a self-aligned silicon gate CMOS process (Scaled SAJI IV). The 82C54/883 has three independently programmable and functional 16 bit counters, each capable of handling clock input frequencies of up to 8MHz. The high speed and industry standard configuration of the 82C54/883 make it compatible with the Harris 80C86 and 80C88 CMOS microprocessors along with many other industry standard processors.

Six programmable timer modes allow the 82C54/883 to be used as an event counter, elapsed time indicator, programmable one-shot along with many other applications.

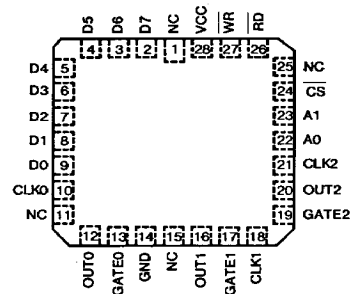
Static CMOS circuit design insures low operating power. Harris advanced SAJI process results in a significant reduction in power with performance equal to or greater than existing functionally equivalent products.

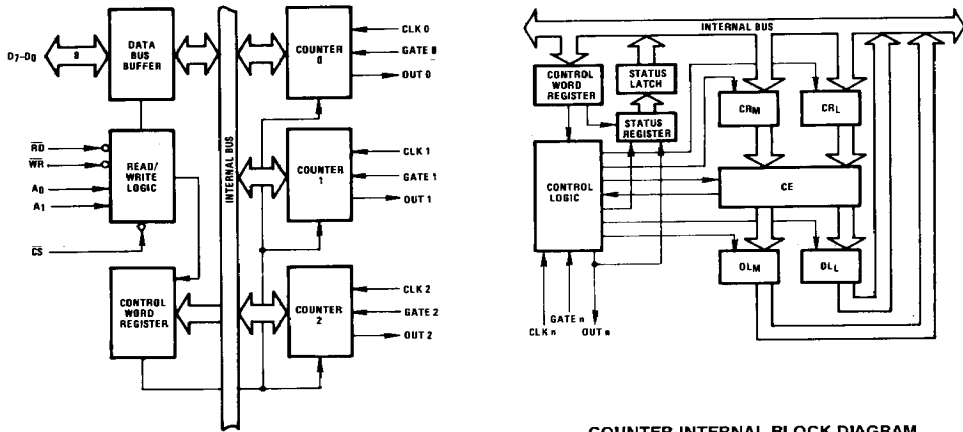
Pinouts

82C54/883 (CERAMIC DIP)
TOP VIEW



82C54/883 (CERAMIC LCC)
TOP VIEW



Functional Diagram**COUNTER INTERNAL BLOCK DIAGRAM****Pin Description**

SYMBOL	DIP PIN NUMBER	TYPE	DEFINITION															
D7-D0	1-8	I/O	DATA: Bi-directional three state data bus lines, connected to system data bus.															
CLK 0	9	I	CLOCK 0: Clock input of Counter 0.															
OUT 0	10	O	OUT 0: Output of Counter 0.															
GATE 0	11	I	GATE 0: Gate input of Counter 0.															
GND	12		GROUND: Power supply connection.															
OUT 1	13	O	OUT 1: Output of Counter 1.															
GATE 1	14	I	GATE 1: Gate input of Counter 1.															
CLK 1	15	I	CLOCK 1: Clock input of Counter 1.															
GATE 2	16	I	GATE 2: Gate input of Counter 2.															
OUT 2	17	O	OUT2: Output of Counter 2.															
CLK 2	18	I	CLOCK 2: Clock input of Counter 2.															
A0, A1	19-20	I	ADDRESS: Select inputs for one of the three counters or Control Word Register for read/write operations. Normally connected to the system address bus. <table><tr><th>A1</th><th>A0</th><th>SELECTS</th></tr><tr><td>0</td><td>0</td><td>Counter 0</td></tr><tr><td>0</td><td>1</td><td>Counter 1</td></tr><tr><td>1</td><td>0</td><td>Counter 2</td></tr><tr><td>1</td><td>1</td><td>Control Word Register</td></tr></table>	A1	A0	SELECTS	0	0	Counter 0	0	1	Counter 1	1	0	Counter 2	1	1	Control Word Register
A1	A0	SELECTS																
0	0	Counter 0																
0	1	Counter 1																
1	0	Counter 2																
1	1	Control Word Register																
$\overline{\text{CS}}$	21	I	CHIP SELECT: A low on this input enables the 82C54 to respond to $\overline{\text{RD}}$ and $\overline{\text{WR}}$ signals. $\overline{\text{RD}}$ and $\overline{\text{WR}}$ are ignored otherwise.															
$\overline{\text{RD}}$	22	I	READ: This input is low during CPU read operations.															
$\overline{\text{WR}}$	23	I	WRITE: This input is low during CPU write operations.															
VCC	24		VCC: The +5V power supply Pin. A 0.1 μF capacitor between pins VCC and GND is recommended for decoupling.															

Absolute Maximum Ratings

Supply Voltage +8.0V
 Input, Output or I/O Voltage Applied GND-0.5V to VCC+0.5V
 Storage Temperature Range -65°C to +150°C
 Junction Temperature +175°C
 Lead Temperature (Soldering 10 sec) +300°C
 ESD Classification Class 1

Reliability Information

Thermal Resistance θ_{ja} θ_{jc}
 Ceramic DIP Package 47°C/W 80°C/W
 Ceramic LCC Package 49°C/W 50°C/W
 Maximum Package Power Dissipation at +125°C
 Ceramic DIP Package 1.07W
 Ceramic LCC Package 1.03W
 Gate Count 2250 Gates

CAUTION: Stresses above those listed in "Absolute Maximum Ratings" may cause permanent damage to the device. This is a stress only rating and operation of the device at these or any other conditions above those indicated in the operational sections of this specification is not implied.

Operating Conditions

Operating Temperature Range -55°C to +125°C
 Operating Voltage Range +4.5V to 5.5V

TABLE 1. 82C54/883 D.C. ELECTRICAL PERFORMANCE CHARACTERISTICS

Device Guaranteed and 100% Tested

PARAMETER	SYMBOL	CONDITIONS	GROUP A SUBGROUPS	TEMPERATURE	LIMITS		UNITS
					MIN	MAX	
Logical One Input Voltage	VIH	VCC = 5.5V	1, 2, 3	$-55^{\circ}\text{C} \leq T_A \leq +125^{\circ}\text{C}$	2.2	-	V
Logical Zero Input Voltage	VIL	VCC = 4.5V	1, 2, 3	$-55^{\circ}\text{C} \leq T_A \leq +125^{\circ}\text{C}$	-	0.8	V
Output High Voltage	VOH	VCC = 4.5V, IOH = -2.5mA, IOH = -100µA (Note 1)	1, 2, 3	$-55^{\circ}\text{C} \leq T_A \leq +125^{\circ}\text{C}$	3.0 VCC-0.4	-	V
Output Low Voltage	VOL	VCC = 4.5V, IOL = +2.5mA (Note 1)	1, 2, 3	$-55^{\circ}\text{C} \leq T_A \leq +125^{\circ}\text{C}$	-	0.4	V
Input Leakage Current	II	VCC = 5.5V, VIN = GND or VCC, DIP Pins 9, 11, 14-16, 18-23	1, 2, 3	$-55^{\circ}\text{C} \leq T_A \leq +125^{\circ}\text{C}$	-1.0	+1.0	µA
I/O Leakage Current	IO	VCC = 5.5V, VIN = GND or VCC, DIP Pins 1-8	1, 2, 3	$-55^{\circ}\text{C} \leq T_A \leq +125^{\circ}\text{C}$	-10.0	+10.0	µA
Standby Power Supply Current	ICCSB	VCC = 5.5V, Outputs Open Counters Programmed	1, 2, 3	$-55^{\circ}\text{C} \leq T_A \leq +125^{\circ}\text{C}$	-	10	µA
Operating Supply Current	ICCOP	VCC = 5.5V, CLK0 = CLK1 = CLK2 = 8MHz, Outputs Open	1, 2, 3	$-55^{\circ}\text{C} \leq T_A \leq +125^{\circ}\text{C}$	-	10	mA

NOTE: 1. Interchanging of force and sense conditions is permitted.

CAUTION: These devices are sensitive to electronic discharge. Proper I.C. handling procedures should be followed.

TABLE 2. 82C54/883 A.C. ELECTRICAL PERFORMANCE CHARACTERISTICS

Device Guaranteed and 100% Tested

PARAMETER	SYMBOL	(NOTE 1) CONDITIONS	GROUP A SUBGROUPS	TEMPERATURE	LIMITS		UNITS
					MIN	MAX	
Address Stable Before RD	TAR(1)	VCC = 4.5V and 5.5V	9, 10, 11	$-55^{\circ}\text{C} \leq T_A \leq +125^{\circ}\text{C}$	30	–	ns
CS Stable Before RD	TSR(2)	VCC = 4.5V and 5.5V	9, 10, 11	$-55^{\circ}\text{C} \leq T_A \leq +125^{\circ}\text{C}$	0	–	ns
Address Hold Time After RD	TRA(3)	VCC = 4.5V and 5.5V	9, 10, 11	$-55^{\circ}\text{C} \leq T_A \leq +125^{\circ}\text{C}$	0	–	ns
RD Pulse Width	TRR(4)	VCC = 4.5V and 5.5V	9, 10, 11	$-55^{\circ}\text{C} \leq T_A \leq +125^{\circ}\text{C}$	150	–	ns
Data Delay from RD	TRD(5)	VCC = 4.5V and 5.5V	9, 10, 11	$-55^{\circ}\text{C} \leq T_A \leq +125^{\circ}\text{C}$	–	120	ns
Data Delay from Address	TAD(6)	VCC = 4.5V and 5.5V	9, 10, 11	$-55^{\circ}\text{C} \leq T_A \leq +125^{\circ}\text{C}$	–	210	ns
Command Recovery Time	TRV(8)	VCC = 4.5V and 5.5V	9, 10, 11	$-55^{\circ}\text{C} \leq T_A \leq +125^{\circ}\text{C}$	200	–	ns
WRITE CYCLE TIMING							
Address Stable Before WR	TAW(9)	VCC = 4.5V and 5.5V	9, 10, 11	$-55^{\circ}\text{C} \leq T_A \leq +125^{\circ}\text{C}$	0	–	ns
CS Stable Before WR	TSW(10)	VCC = 4.5V and 5.5V	9, 10, 11	$-55^{\circ}\text{C} \leq T_A \leq +125^{\circ}\text{C}$	0	–	ns
Address Hold Time After WR	TWA(11)	VCC = 4.5V and 5.5V	9, 10, 11	$-55^{\circ}\text{C} \leq T_A \leq +125^{\circ}\text{C}$	0	–	ns
WR Pulse Width	TWW(12)	VCC = 4.5V and 5.5V	9, 10, 11	$-55^{\circ}\text{C} \leq T_A \leq +125^{\circ}\text{C}$	95	–	ns
Data Setup Time Before WR	TDW(13)	VCC = 4.5V and 5.5V	9, 10, 11	$-55^{\circ}\text{C} \leq T_A \leq +125^{\circ}\text{C}$	140	–	ns
Data Setup Time Before WR	TWD(14)	VCC = 4.5V and 5.5V	9, 10, 11	$-55^{\circ}\text{C} \leq T_A \leq +125^{\circ}\text{C}$	25	–	ns
Command Recovery Time	TRV(15)	VCC = 4.5V and 5.5V	9, 10, 11	$-55^{\circ}\text{C} \leq T_A \leq +125^{\circ}\text{C}$	200	–	ns
CLOCK AND GATE TIMING							
Clock Period	TCLK(16)	VCC = 4.5V and 5.5V	9, 10, 11	$-55^{\circ}\text{C} \leq T_A \leq +125^{\circ}\text{C}$	125	–	ns
High Pulse Width	TPWH(17)	VCC = 4.5V and 5.5V	9, 10, 11	$-55^{\circ}\text{C} \leq T_A \leq +125^{\circ}\text{C}$	60	–	ns
Low Pulse Width	TPWL(18)	VCC = 4.5V and 5.5V	9, 10, 11	$-55^{\circ}\text{C} \leq T_A \leq +125^{\circ}\text{C}$	60	–	ns
Gate Width High	TGW(21)	VCC = 4.5V and 5.5V	9, 10, 11	$-55^{\circ}\text{C} \leq T_A \leq +125^{\circ}\text{C}$	50	–	ns
Gate Width Low	TGL(22)	VCC = 4.5V and 5.5V	9, 10, 11	$-55^{\circ}\text{C} \leq T_A \leq +125^{\circ}\text{C}$	50	–	ns
Gate Setup Time to CLK	TGS(23)	VCC = 4.5V and 5.5V	9, 10, 11	$-55^{\circ}\text{C} \leq T_A \leq +125^{\circ}\text{C}$	50	–	ns
Gate Hold Time to CLK	TGH(24)	VCC = 4.5V and 5.5V	9, 10, 11	$-55^{\circ}\text{C} \leq T_A \leq +125^{\circ}\text{C}$	50	–	ns
Output Delay from CLK	TOD(25)	VCC = 4.5V and 5.5V	9, 10, 11	$-55^{\circ}\text{C} \leq T_A \leq +125^{\circ}\text{C}$	–	150	ns
Output Delay from GATE	TODG(26)	VCC = 4.5V and 5.5V	9, 10, 11	$-55^{\circ}\text{C} \leq T_A \leq +125^{\circ}\text{C}$	–	120	ns
OUT Delay from Mode Write	TWO(27)	VCC = 4.5V and 5.5V	9, 10, 11	$-55^{\circ}\text{C} \leq T_A \leq +125^{\circ}\text{C}$	–	260	ns

NOTES: 1. Tested as follows: $f = 1\text{MHz}$, $V_{IH} = 2.6\text{V}$, $V_{IL} = 0.4\text{V}$, $C_L = 50\text{pF}$ (Unless Otherwise Specified), $V_{OH} \geq 1.5\text{V}$, $V_{OL} \leq 1.5\text{V}$.

2. Outputs loaded as shown in Test Condition 1.

CAUTION: These devices are sensitive to electrostatic discharge. Proper I.C. handling procedures should be followed.

TABLE 3. 82C54/883 ELECTRICAL PERFORMANCE CHARACTERISTICS

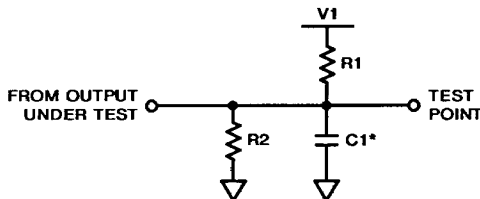
PARAMETER	SYMBOL	CONDITIONS	NOTES	TEMPERATURE	LIMITS		UNITS
					MIN	MAX	
Input Capacitance	CIN	VCC = OPEN, f = 1MHz, All Measurements Referenced to Device GND	1	T _A = +25°C	-	10	pF
Output Capacitance	CO _{UT}	VCC = OPEN, f = 1MHz, All Measurements Referenced to Device GND	1	T _A = +25°C	-	20	pF
I/O Capacitance	CI/O	VCC = OPEN, f = 1MHz, All Measurements Referenced to Device GND	1	T _A = +25°C	-	20	pF
R _D to Data Floating Time	TDF(7)	VCC = 4.5V and 5.5V	1, 2	-55°C ≤ T _A ≤ +125°C	5	85	ns
Clock Period	TCLK(16)	VCC = 4.5V and 5.5V	1, 2	-55°C ≤ T _A ≤ +125°C	-	DC	ns
Clock Rise Time	TR(19)	VCC = 4.5V and 5.5V	1, 2	-55°C ≤ T _A ≤ +125°C	-	25	ns
Clock Fall Time	TF(20)	VCC = 4.5V and 5.5V	1, 2	-55°C ≤ T _A ≤ +125°C	-	25	ns

NOTES: 1. The parameters listed in table 3 are controlled via design or process parameters and are not directly tested. These parameters are characterized upon initial design and after major process and/or design changes.
 2. Tested as follows: f = 1MHz, V_{IH} = 2.6V, V_{IL} = 0.4V, C_L = 50pF, V_{OH} ≥ 1.5V, V_{OL} ≤ 1.5V. Tested using Test Condition 2 of Test Condition Definition Table.

TABLE 4. APPLICABLE SUBGROUPS

CONFORMANCE GROUPS	METHOD	SUBGROUPS
Initial Test	100%/5004	-
Interim Test	100%/5004	1, 7, 9
PDA	100%	1
Final Test	100%	2, 3, 8A, 8B, 10, 11
Group A	-	1, 2, 3, 7, 8A, 8B, 9, 10, 11
Groups C & D	Samples/5005	1, 7, 9

Test Load Circuit

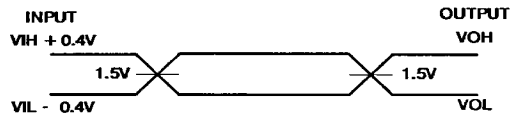


* Includes Stray and Jig Capacitance

TEST CONDITION DEFINITION TABLE

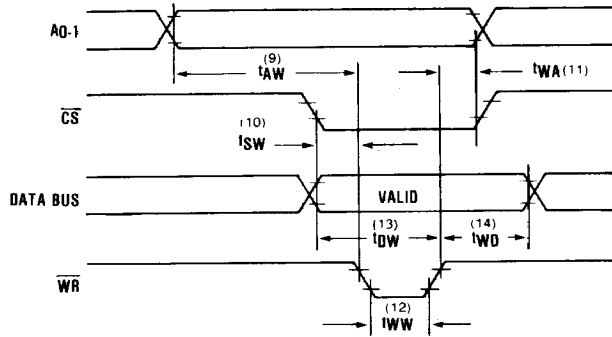
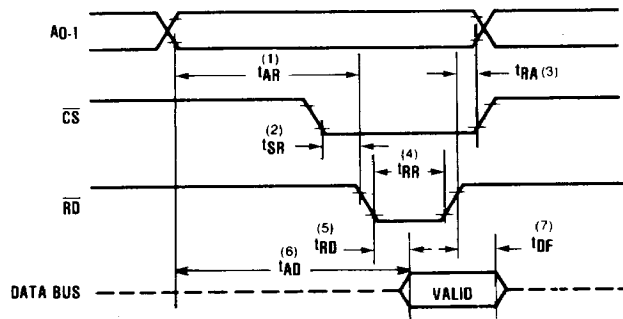
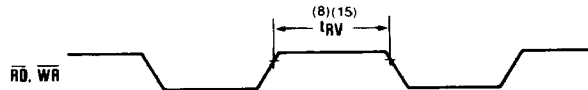
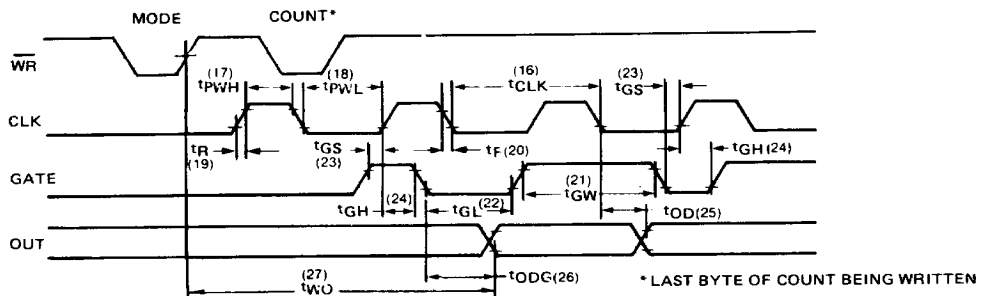
TEST CONDITION	V1	R1	R2	C1
1	1.7V	523	OPEN	150pF
2	VCC	2K	1.7K	50pF

A.C. Testing Input, Output Waveform



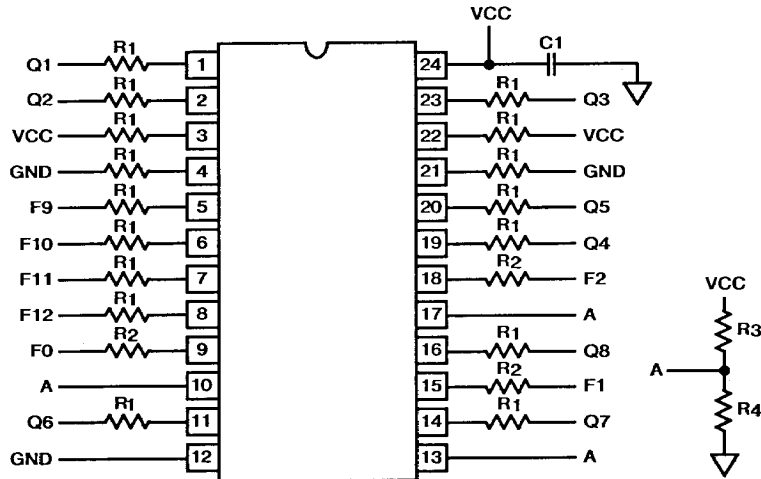
A.C. Testing: All input signals must switch between V_{IL} -0.4V and V_{IH} +0.4V. Input rise and fall times are driven at 1ns/V.

CAUTION: These devices are sensitive to electronic discharge. Proper I.C. handling procedures should be followed.

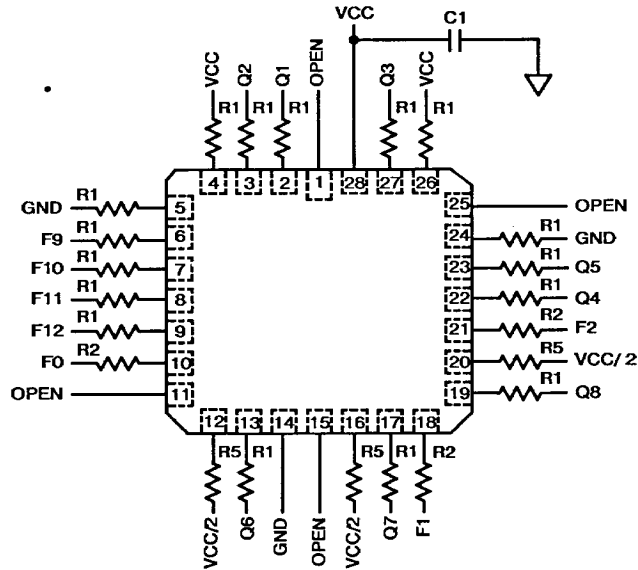
Timing Waveforms**WRITE****READ****RECOVERY****CLOCK AND GATE**

Burn-In Circuits

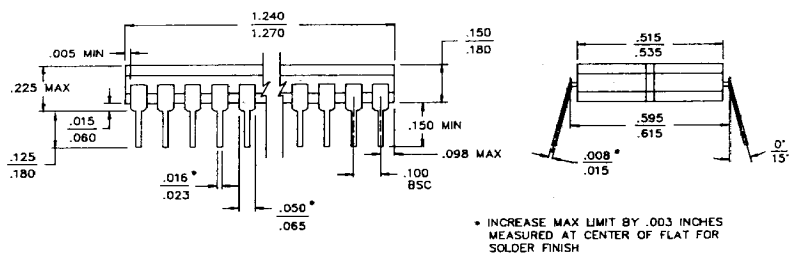
82C54/883 CERAMIC DIP



82C54/883 CERAMIC LCC



$VCC = 5.5V \pm 0.5V$,
 $GND = 0V$
 $VIN = 4.5V \pm 10\%$
 $VIL = -0.2V \text{ to } 0.4V$
 $R1 = 47k\Omega \pm 5\%$
 $R2 = 1.0k\Omega \pm 5\%$
 $R3 = 2.7k\Omega \pm 5\%$
 $R4 = 1.8k\Omega \pm 5\%$
 $R5 = 1.2k\Omega \pm 5\%$
 $C1 = 0.01\mu F \text{ Minimum}$
 $f0 = 100kHz \pm 10\%$
 $f1 = f0/2, f2 = f1/2, \dots, f12 = f11/2$

Packaging†**24 PIN CERAMIC DIP****LEAD MATERIAL:** Type B**LEAD FINISH:** Type A**PACKAGE MATERIAL:** Ceramic 90% Alumina**PACKAGE SEAL:**

Material: Glass Frit

Temperature: 450°C ± 10°C

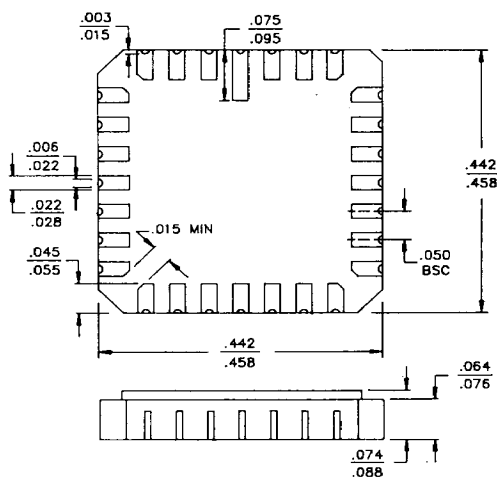
Method: Furnace Seal

INTERNAL LEAD WIRE:

Material: Aluminum

Diameter: 1.25 Mil

Bonding Method: Ultrasonic

COMPLIANT OUTLINE: 38510 D-3**28 PAD CERAMIC LCC
BOTTOM VIEW****PAD MATERIAL:** Type C**PAD FINISH:** Type A**FINISH DIMENSION:** Type A**PACKAGE MATERIAL:** Multilayer Ceramic, 90% Alumina**PACKAGE SEAL:**

Material: Gold/Tin (80/20)

Temperature: 320°C ± 10°C

Method: Furnace Braze

INTERNAL LEAD WIRE:

Material: Aluminum

Diameter: 1.25 Mil

Bonding Method: Ultrasonic

COMPLIANT OUTLINE: 38510 C-4NOTE: All Dimensions are $\frac{\text{Min}}{\text{Max}}$, Dimensions are in inches.

† Mil-M-38510 Compliant Materials, Finishes, and Dimensions.

Metallization Topology**DIE DIMENSIONS:**

183.5 x 215.7 x 19 ± 1 mils

METALLIZATION:

Type: Silicon - Aluminum

Thickness: 11kÅ ± 2kÅ

GLASSIVATION:Type: SiO₂

Thickness: 8kÅ ± 1kÅ

DIE ATTACH:

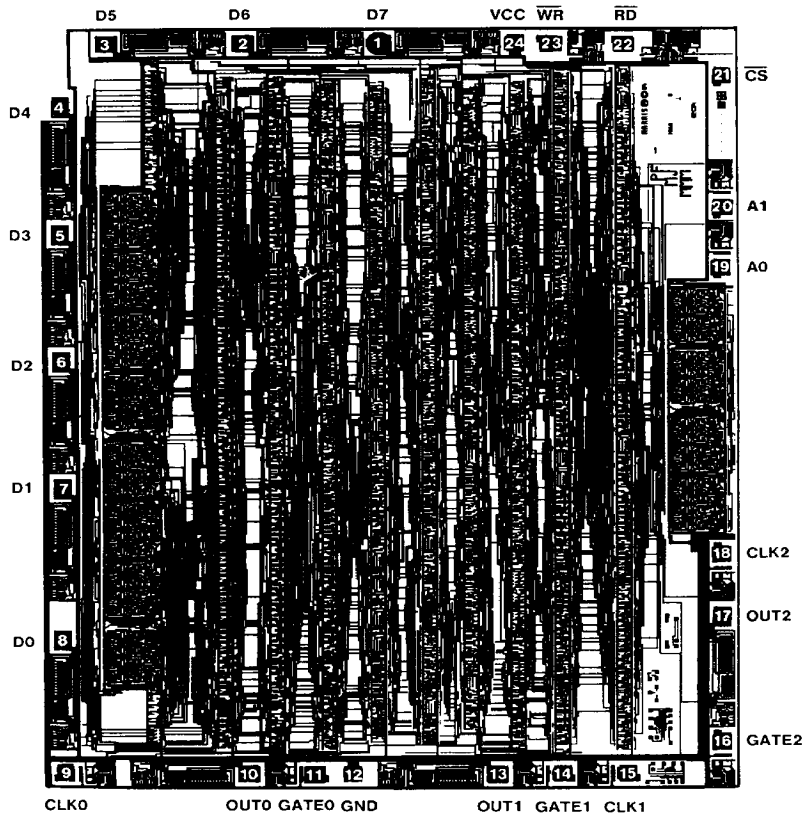
Material: Gold - Silicon Eutectic Alloy (LCC has Gold Preform)

Temperature: Ceramic DIP — 460°C (Max)

Ceramic LCC — 420°C (Max)

WORST CASE CURRENT DENSITY:0.26 x 10⁵ A/cm²**Metallization Mask Layout**

82C54/883



DESIGN INFORMATION

CMOS Programmable Interval Timer

The information contained in this section has been developed through characterization by Harris Semiconductor and is for use as application and design information only. No guarantee is implied.

Functional Description

General

The 82C54 is a programmable interval timer/counter designed for use with microcomputer systems. It is a general purpose, multi-timing element that can be treated as an array of I/O ports in the system software.

The 82C54 solves one of the most common problems in any microcomputer system, the generation of accurate time delays under software control. Instead of setting up timing loops in software, the programmer configures the 82C54 to match his requirements and programs one of the counters for the desired delay. After the desired delay, the 82C54 will interrupt the CPU. Software overhead is minimal and variable length delays can easily be accommodated.

Some of the other computer/timer functions common to microcomputers which can be implemented with the 82C54 are:

- Real time clock
- Event counter
- Digital one-shot
- Programmable rate generator
- Square wave generator
- Binary rate multiplier
- Complex waveform generator
- Complex motor controller

Data Bus Buffer

This three-state, bi-directional, 8-bit buffer is used to interface the 82C54 to the system bus (see Figure 1).

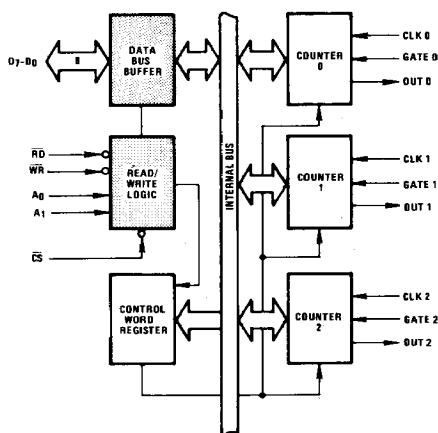


FIGURE 1. DATA BUS BUFFER AND READ/WRITE LOGIC FUNCTIONS

Read/Write Logic

The Read/Write Logic accepts inputs from the system bus and generates control signals for the other functional blocks of the 82C54. A1 and A0 select one of the three counters or the Control Word Register to be read from/written into. A "low" on the RD input tells the 82C54 that the CPU is reading one of the counters. A "low" on the WR input tells the 82C54 that the CPU is writing either a Control Word or an initial count. Both RD and WR are qualified by CS; RD and WR are ignored unless the 82C54 has been selected by holding CS low.

Control Word Register

The Control Word Register (Figure 2) is selected by the Read/Write Logic when A1, A0 = 11. If the CPU then does a write operation to the 82C54, the data is stored in the Control Word Register and is interpreted as a Control Word used to define the Counter operation.

The Control Word Register can only be written to; status information is available with the Read-Back Command.

Counter 0, Counter 1, Counter 2

These three functional blocks are identical in operation, so only a single Counter will be described. The internal block diagram of a single counter is shown in Figure 3. The counters are fully independent. Each Counter may operate in a different Mode.

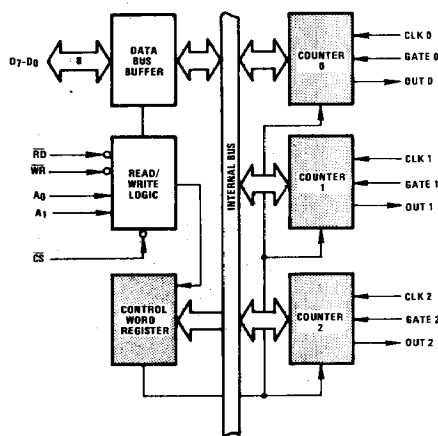


FIGURE 2. CONTROL WORD REGISTER AND COUNTER FUNCTIONS

DESIGN INFORMATION (Continued)

The information contained in this section has been developed through characterization by Harris Semiconductor and is for use as application and design information only. No guarantee is implied.

The Control Word Register is shown in the figure; it is not part of the Counter itself, but its contents determine how the Counter operates.

The status register, shown in the figure, when latched, contains the current contents of the Control Word Register and status of the output and null count flag. (See detailed explanation of the Read-Back command.)

The actual counter is labeled CE (for Counting Element). It is a 16 bit presettable synchronous down counter.

OLM and OLL are two 8-bit latches. OL stands for "Output Latch"; the subscripts M and L for "Most significant byte" and "Least significant byte", respectively. Both are normally referred to as one unit and called just OL. These latches normally "follow" the CE, but if a suitable Counter Latch Command is sent to the 82C54, the latches "latch" the present count until read by the CPU and then return to "following" the CE. One latch at a time is enabled by the counter's Control Logic to drive the internal bus. This is how the 16-bit Counter communicates over the 8-bit internal bus. Note that the CE itself cannot be read; whenever you read the count, it is the OL that is being read.

Similarly, there are two 8-bit registers called CRM and CRL (for "Count Register"). Both are normally referred to as one unit and called just CR. When a new count is written to the Counter, the count is stored in the CR and later transferred to the CE. The Control Logic allows one register at a time to be loaded from the internal bus. Both bytes are transferred to the CE simultaneously. CRM and CRL are cleared when the Counter is programmed for one byte counts (either most significant byte only or least significant byte only) the other byte will be zero. Note that the CE cannot be written into; whenever a count is written, it is written into the CR.

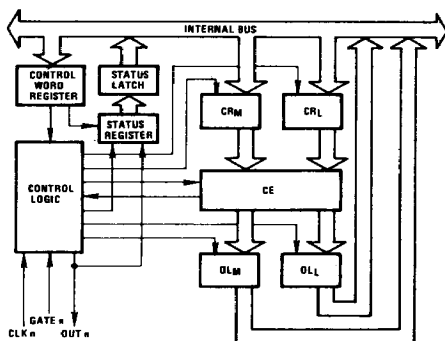


FIGURE 3. COUNTER INTERNAL BLOCK DIAGRAM

The Control Logic is also shown in the diagram. CLK n, GATE n, and OUT n are all connected to the outside world through the Control Logic.

82C54 System Interface

The 82C54 is treated by the system software as an array of peripheral I/O ports; three are counters and the fourth is a control register for MODE programming.

Basically, the select inputs A0, A1 connect to the A0, A1 address bus signals of the CPU. The \overline{CS} can be derived directly from the address bus using a linear select method or it can be connected to the output of a decoder, such as a Harris HD-6440 for larger systems.

Operational Description

General

After power-up, the state of the 82C54 is undefined. The Mode, count value, and output of all Counters are undefined.

How each Counter operates is determined when it is programmed. Each Counter must be programmed before it can be used. Unused counters need not be programmed.

Programming The 82C54

Counters are programmed by writing a Control Word and then an initial count.

All Control Words are written into the Control Word Register, which is selected when A1, A0 = 11. The Control Word specifies which Counter is being programmed.

By contrast, initial counts are written into the Counters, not the Control Word Register. The A1, A0 inputs are used to select the Counter to be written into. The format of the initial count is determined by the Control Word used.

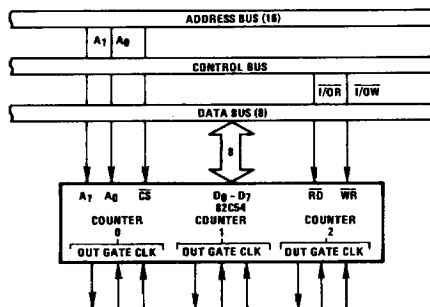


FIGURE 4. 82C54 SYSTEM INTERFACE

DESIGN INFORMATION (Continued)

The information contained in this section has been developed through characterization by Harris Semiconductor and is for use as application and design information only. No guarantee is implied.

Write Operations

The programming procedure for the 82C54 is very flexible. Only two conventions need to be remembered:

1. For each Counter, the Control Word must be written before the initial count is written.
2. The initial count must follow the count format specified in the Control Word (least significant byte only, most significant byte only, or least significant byte and then most significant byte).

Since the Control Word Register and the three Counters have separate addresses (selected by the A1, A0 inputs), and each Control Word specifies the Counter it applies to (SC0, SC1 bits), no special instruction sequence is required. Any programming sequence that follows the conventions above is acceptable.

Control Word Format

A1, A0 = 11; \overline{CS} = 0; \overline{RD} = 1; \overline{WR} = 0

D7	D6	D5	D4	D3	D2	D1	D0
SC1	SC0	RW1	RW0	M2	M1	M0	BCD

SC - Select Counter:

SC1	SC0	
0	0	Select Counter 0
0	1	Select Counter 1
1	0	Select Counter 2
1	1	Read-Back Command (See Read Operations)

RW - Read/Write:

RW1	RW0	
0	0	Counter Latch Command (See Read Operations)
0	1	Read/Write least significant byte only.
1	0	Read/Write most significant byte only.
1	1	Read/Write least significant byte first, then most significant byte.

M - Mode:

M2	M1	M0	
0	0	0	Mode 0
0	0	1	Mode 1
X	1	0	Mode 2
X	1	1	Mode 3
1	0	0	Mode 4
1	0	1	Mode 5

BCD - Binary Coded Decimal:

0	Binary Counter 16-bits
1	Binary Coded Decimal (BCD) Counter (4 Decades)

NOTE: Don't Care bits (X) should be 0 to insure compatibility with future products.

FIGURE 5. CONTROL WORD FORMAT

	A1	A0
Control Word - Counter 0	1	1
LSB of Count - Counter 0	0	0
MSB of Count - Counter 0	0	0
Control Word - Counter 1	1	1
LSB of Count - Counter 1	0	1
MSB of Count - Counter 1	0	1
Control Word - Counter 2	1	1
LSB of Count - Counter 2	1	0
MSB of Count - Counter 2	1	0

	A1	A0
Control Word - Counter 0	1	1
Control Word - Counter 1	1	1
Control Word - Counter 2	1	1
LSB of Count - Counter 2	1	0
LSB of Count - Counter 1	0	1
LSB of Count - Counter 0	0	0
MSB of Count - Counter 0	0	0
MSB of Count - Counter 1	0	1
MSB of Count - Counter 2	1	0

	A1	A0
Control Word - Counter 2	1	1
Control Word - Counter 1	1	1
Control Word - Counter 0	1	1
LSB of Count - Counter 2	1	0
MSB of Count - Counter 2	1	0
LSB of Count - Counter 1	0	1
MSB of Count - Counter 1	0	1
LSB of Count - Counter 0	0	0
MSB of Count - Counter 0	0	0

	A1	A0
Control Word - Counter 1	1	1
Control Word - Counter 0	1	1
LSB of Count - Counter 1	0	1
Control Word - Counter 2	1	1
LSB of Count - Counter 0	0	0
MSB of Count - Counter 1	0	1
LSB of Count - Counter 2	1	0
MSB of Count - Counter 0	0	0
MSB of Count - Counter 2	1	0

NOTE: In all four examples, all counters are programmed to Read/Write two-byte counts. These are only four of many programming sequences.

FIGURE 6. A FEW POSSIBLE PROGRAMMING SEQUENCES

DESIGN INFORMATION (Continued)

The information contained in this section has been developed through characterization by Harris Semiconductor and is for use as application and design information only. No guarantee is implied.

A new initial count may be written to a Counter at any time without affecting the Counter's programmed Mode in any way. Counting will be affected as described in the Mode definitions. The new count must follow the programmed count format.

If a Counter is programmed to read/write two-byte counts, the following precaution applies: A program must not transfer control between writing the first and second byte to another routine which also writes into that same Counter. Otherwise, the Counter will be loaded with an incorrect count.

Read Operations

It is often desirable to read the value of a Counter without disturbing the count in progress. This is easily done in the 82C54.

There are three possible methods for reading the Counters. The first is through the Read-Back command, which is explained later. The second is a simple read operation of the Counter, which is selected with the A1, A0 inputs. The only requirement is that the CLK input of the selected Counter must be inhibited by using either the GATE input or external logic. Otherwise, the count may be in process of changing when it is read, giving an undefined result.

Counter Latch Command

The other method for reading the Counters involves a special software command called the "Counter Latch Command". Like a Control Word, this command is written to the Control Word Register, which is selected when A1, A0 = 11. Also, like a Control Word, the SC0, SC1 bits select one of the three Counters, but two other bits, D5 and D4, distinguish this command from a Control Word.

A1, A0 = 11; $\overline{CS} = 0$; $\overline{RD} = 1$; $\overline{WR} = 0$

D7	D6	D5	D4	D3	D2	D1	D0
SC1	SC0	0	0	X	X	X	X

SC1, SC0 - specify counter to be latched

SC1	SC0	COUNTER
0	0	0
0	1	1
1	0	2
1	1	Read-Back Command

D5, D4 - 00 designates Counter Latch Command
X - Don't Care

NOTE: Don't Care bits (X) should be 0 to insure compatibility with future products.

FIGURE 7. COUNTER LATCH COMMAND FORMAT

The selected Counter's output latch (OL) latches the count when the Counter Latch Command is received. This count is held in the latch until it is read by the CPU (or until the

Counter is reprogrammed). The count is then unlatched automatically and the OL returns to "following" the counting element (CE). This allows reading the contents of the Counters "on the fly" without affecting counting in progress. Multiple Counter Latch Commands may be used to latch more than one Counter. Each latched Counter's OL holds its count until read. Counter Latch Commands do not affect the programmed Mode of the Counter in any way.

If a Counter is latched and then, some time later, latched again before the count is read, the second Counter Latch Command is ignored. The count read will be the count at the time the first Counter Latch Command was issued.

With either method, the count must be read according to the programmed format; specifically, if the Counter is programmed for two byte counts, two bytes must be read. The two bytes do not have to be read one right after the other; read or write or programming operations of other Counters may be inserted between them.

Another feature of the 82C54 is that reads and writes of the same Counter may be interleaved; for example, if the Counter is programmed for two byte counts, the following sequence is valid.

1. Read least significant byte.
2. Write new least significant byte.
3. Read most significant byte.
4. Write new most significant byte.

If a Counter is programmed to read or write two-byte counts, the following precaution applies: A program MUST NOT transfer control between reading the first and second byte to another routine which also reads from that same Counter. Otherwise, an incorrect count will be read.

Read-Back Command

The read-back command allows the user to check the count value, programmed Mode, and current state of the OUT pin and Null Count flag of the selected counter(s).

The command is written into the Control Word Register and has the format shown in Figure 8. The command applies to the counters selected by setting their corresponding bits D3, D2, D1 = 1.

A0, A1 = 11; $\overline{CS} = 0$; $\overline{RD} = 1$; $\overline{WR} = 0$

D7	D6	D5	D4	D3	D2	D1	D0
1	1	COUNT	STATUS	CNT 2	CNT 1	CNT 0	0

D5: 0 = Latch count of selected Counter(s)

D4: 0 = Latch status of selected Counter(s)

D3: 1 = Select Counter 2

D2: 1 = Select Counter 1

D1: 1 = Select Counter 0

D0: Reserved for future expansion; Must be 0

FIGURE 8. READ-BACK COMMAND FORMAT

DESIGN INFORMATION (Continued)

The information contained in this section has been developed through characterization by Harris Semiconductor and is for use as application and design information only. No guarantee is implied.

The read-back command may be used to latch multiple counter output latches (OL) by setting the COUNT bit D5 = 0 and selecting the desired counter(s). This single command is functionally equivalent to several counter latch commands, one for each counter latched. Each counter's latched count is held until it is read (or the counter is reprogrammed). That counter is automatically unlatched when read, but other counters remain latched until they are read. If multiple count read-back commands are issued to the same counter without reading the count, all but the first are ignored; i.e., the count which will be read is the count at the time the first read-back command was issued.

The read-back command may also be used to latch status information of selected counter(s) by setting STATUS bit D4 = 0. Status must be latched to be read; status of a counter is accessed by a read from that counter.

The counter status format is shown in Figure 9. Bits D5 through D0 contain the counter's programmed Mode exactly as written in the last Mode Control Word. OUTPUT bit D7 contains the current state of the OUT pin. This allows the user to monitor the counter's output via software, possibly eliminating some hardware from a system.

D7	D6	D5	D4	D3	D2	D1	D0
OUTPUT	NULL COUNT	RW1	RW0	M2	M1	M0	BCD

D7 1 = Out pin is 1

0 = Out pin is 0

D6 1 = Null count

0 = Count available for reading

D5-D0 = Counter programmed mode (See Figure 5)

FIGURE 9. STATUS BYTE

NULL COUNT bit D6 indicates when the last count written to the counter register (CR) has been loaded into the counting element (CE). The exact time this happens depends on the Mode of the counter and is described in the Mode

Definitions, but until the counter is loaded into the counting element (CE), it can't be read from the counter. If the count is latched or read before this time, the count value will not reflect the new count just written. The operation of Null Count is shown in Figure 10.

THIS ACTION:

CAUSES:

- A. Write to the control word register: (1) Null Count = 1
- B. Write to the count register (CR): (2) Null Count = 1
- C. New count is loaded into CE (CR - CE) Null Count = 0

- (1) Only the counter specified by the control word will have its null count set to 1. Null count bits of other counters are unaffected.
- (2) If the counter is programmed for two-byte counts (least significant byte then most significant byte) null count goes to 1 when the second byte is written.

FIGURE 10. NULL COUNT OPERATION

If multiple status latch operations of the counter(s) are performed without reading the status, all but the first are ignored; i.e., the status that will be read is the status of the counter at the time the first status read-back command was issued.

Both count and status of the selected counter(s) may be latched simultaneously by setting both COUNT and STATUS bits D5, D4 = 0. This is functionally the same as issuing two separate read-back commands at once, and the above discussions apply here also. Specifically, if multiple count and/or status read-back commands are issued to the same counter(s) without any intervening reads, all but the first are ignored. This is illustrated in Figure 11. If both count and status of a counter are latched, the first read operation of that counter will return latched status, regardless of which was latched first. The next one or two reads (depending on whether the counter is programmed for one or two type counts) return latched count. Subsequent reads return unlatched count.

COMMAND								DESCRIPTION	RESULT
D7	D6	D5	D4	D3	D2	D1	D0		
1	1	0	0	0	0	1	0	Read Back Count and Status of Counter 0	Count and Status Latched for Counter 0
1	1	1	0	0	1	0	0	Read-Back Status of Counter 1	Status Latched for Counter 1
1	1	1	0	1	1	0	0	Read-Back Status of Counters 2, 1	Status Latched for Counter 2, But Not Counter 1
1	1	0	1	1	0	0	0	Read-Back Count of Counter 2	Count Latched for Counter 2
1	1	0	0	0	1	0	0	Read-Back Count and Status of Counter 1	Count Latched for Counter 1 But Not Status
1	1	1	0	0	0	1	0	Read-Back Status of Counter 1	Command Ignored, Status Already Latched for Counter 1

FIGURE 11. READ-BACK COMMAND EXAMPLE

DESIGN INFORMATION (Continued)

The information contained in this section has been developed through characterization by Harris Semiconductor and is for use as application and design information only. No guarantee is implied.

CS	RD	WR	A1	A0	
0	1	0	0	0	Write into Counter 0
0	1	0	0	1	Write into Counter 1
0	1	0	1	0	Write into Counter 2
0	1	0	1	1	Write Control Word
0	0	1	0	0	Read from Counter 0
0	0	1	0	1	Read from Counter 1
0	0	1	1	0	Read from Counter 2
0	0	1	1	1	No-Operation (Three-State)
1	X	X	X	X	No-Operation (Three-State)
0	1	1	X	X	No-Operation (Three-State)

FIGURE 12. READ/WRITE OPERATIONS SUMMARY

Mode Definitions

The following are defined for use in describing the operation of the 82C54.

CLK PULSE:

A rising edge, then a falling edge, in that order, of a Counter's CLK input.

TRIGGER:

A rising edge of a Counter's Gate input.

COUNTER LOADING:

The transfer of a count from the CR to the CE (See "Functional Description")

Mode 0: Interrupt on Terminal Count

Mode 0 is typically used for event counting. After the Control Word is written, OUT is initially low, and will remain low until the Counter reaches zero. OUT then goes high and remains high until a new count or a new Mode 0 Control Word is written to the Counter.

GATE = 1 enables counting; GATE = 0 disables counting. GATE has no effect on OUT.

After the Control Word and initial count are written to a Counter, the initial count will be loaded on the next CLK pulse. This CLK pulse does not decrement the count, so for an initial count of N, OUT does not go high until N + 1 CLK pulses after the initial count is written.

If a new count is written to the Counter it will be loaded on the next CLK pulse and counting will continue from the new count. If a two-byte count is written, the following happens:

- (1) Writing the first byte disables counting. Out is set low immediately (no clock pulse required).
- (2) Writing the second byte allows the new count to be loaded on next CLK pulse.

This allows the counting sequence to be synchronized by software. Again OUT does not go high until N + 1 CLK pulses after the new count of N is written.

If an initial count is written while GATE = 0, it will still be loaded on the next CLK pulse. When GATE goes high, OUT will go high N CLK pulses later; no CLK pulse is needed to load the counter as this has already been done.

Mode 1: Hardware Retriggerable One-Shot

OUT will be initially high. OUT will go low on the CLK pulse following a trigger to begin the one-shot pulse, and will remain low until the Counter reaches zero. OUT will then go high and remain high until the CLK pulse after the next trigger.

After writing the Control Word and initial count, the Counter is armed. A trigger results in loading the Counter and setting OUT low on the next CLK pulse, thus starting the one-shot pulse N CLK cycles in duration. The one-shot is retriggerable, hence OUT will remain low for N CLK pulses after any trigger. The one-shot pulse can be repeated without rewriting the same count into the counter. GATE has no effect on OUT.

If a new count is written to the Counter during a one-shot pulse, the current one-shot is not affected unless the Counter is retriggered. In that case, the Counter is loaded with the new count and the one-shot pulse continues until the new count expires.

Mode 2: Rate Generator

This Mode functions like a divide-by-N counter. It is typically used to generate a Real Time Clock interrupt. OUT will initially be high. When the initial count has decremented to 1, OUT goes low for one CLK pulse. OUT then goes high again, the Counter reloads the initial count and the process is repeated. Mode 2 is periodic; the same sequence is repeated indefinitely. For an initial count of N, the sequence repeats every N CLK cycles.

GATE = 1 enables counting; GATE = 0 disables counting. If GATE goes low during an output pulse, OUT is set high immediately. A trigger reloads the Counter with the initial count on the next CLK pulse; OUT goes low N CLK pulses after the trigger. Thus the GATE input can be used to synchronize the Counter.

After writing a Control Word and initial count, the Counter will be loaded on the next CLK pulse. OUT goes low N CLK pulses after the initial count is written. This allows the Counter to be synchronized by software also.

Writing a new count while counting does not affect the current counting sequence. If a trigger is received after writing a new count but before the end of the current period, the Counter will be loaded with the new count on the next CLK pulse and counting will continue from the new count. Otherwise, the new count will be loaded at the end of the current counting cycle.

DESIGN INFORMATION (Continued)

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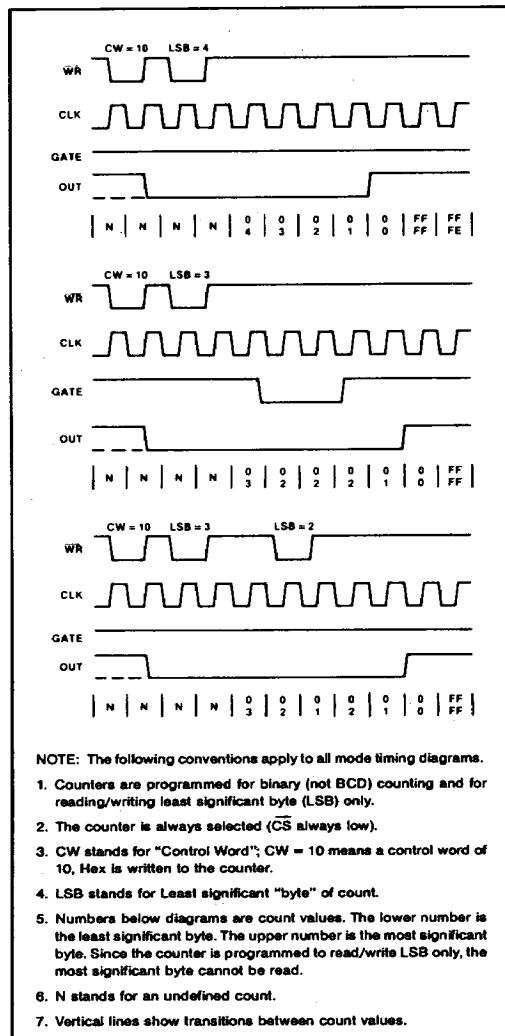


FIGURE 13. MODE 0

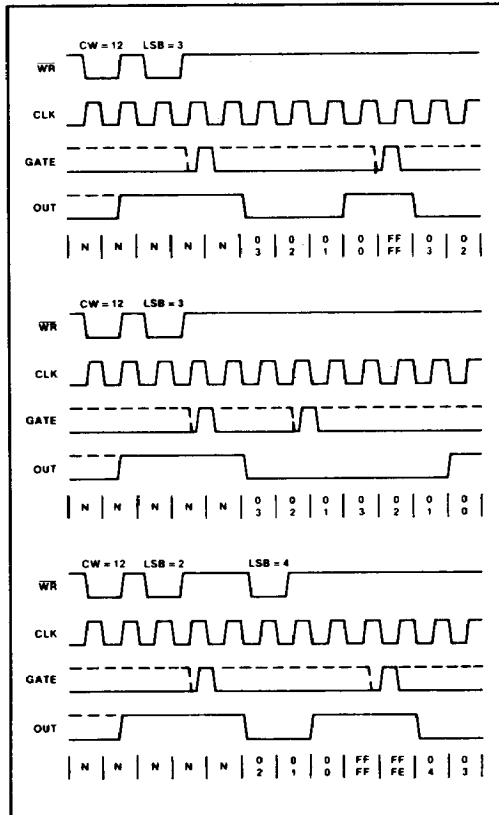


FIGURE 14. MODE 1

DESIGN INFORMATION (Continued)

The information contained in this section has been developed through characterization by Harris Semiconductor and is for use as application and design information only. No guarantee is implied.

Mode 3: Square Wave Mode

Mode 3 is typically used for Baud rate generation. Mode 3 is similar to Mode 2 except for the duty cycle of OUT. OUT will initially be high. When half the initial count has expired, OUT goes low for the remainder of the count. Mode 3 is periodic; the sequence above is repeated indefinitely. An initial count of N results in a square wave with a period of N CLK cycles.

GATE = 1 enables counting; GATE = 0 disables counting. If GATE goes low while OUT is low, OUT is set high immediately; no CLK pulse is required. A trigger reloads the Counter with the initial count on the next CLK pulse. Thus the GATE input can be used to synchronize the Counter.

After writing a Control Word and initial count, the Counter will be loaded on the next CLK pulse. This allows the Counter to be synchronized by software also.

Writing a new count while counting does not affect the current counting sequence. If a trigger is received after writing a new count but before the end of the current half-cycle of the square wave, the Counter will be loaded with the new count on the next CLK pulse and counting will continue from the new count. Otherwise, the new count will be loaded at the end of the current half-cycle.

Mode 3 is Implemented as Follows:

EVEN COUNTS: OUT is initially high. The initial count is loaded on one CLK pulse and then is decremented by two on succeeding CLK pulses. When the count expires, OUT changes value and the Counter is reloaded with the initial count. The above process is repeated indefinitely.

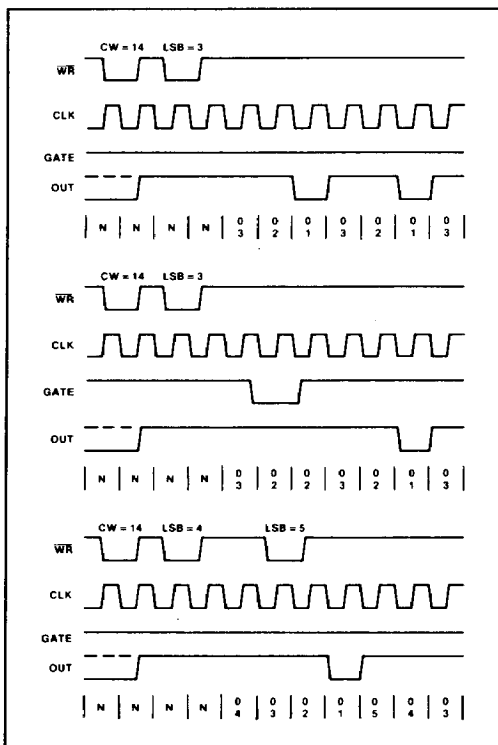


FIGURE 15. MODE 2

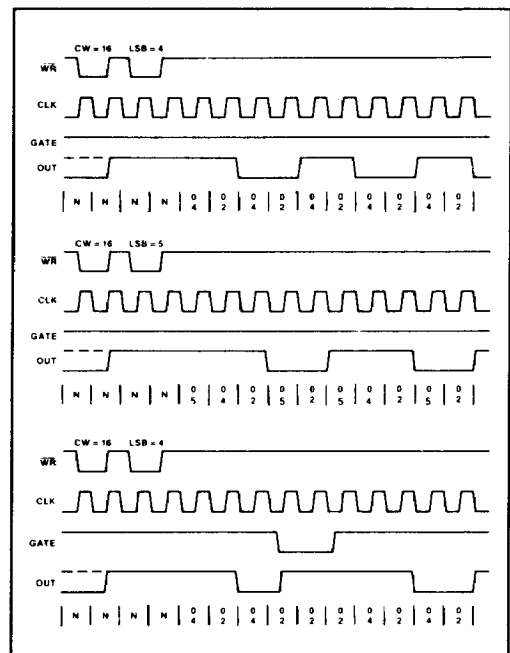


FIGURE 16. MODE 3

DESIGN INFORMATION (Continued)

The information contained in this section has been developed through characterization by Harris Semiconductor and is for use as application and design information only. No guarantee is implied.

ODD COUNTS: OUT is initially high. The initial count is loaded on one CLK pulse, decremented by one on the next CLK pulse, and then decremented by two on succeeding CLK pulses. When the count expires, OUT goes low and the Counter is reloaded with the initial count. The count is decremented by three for one CLK pulse, and then by two on succeeding CLK pulses. When the count expires, OUT goes high again and the Counter is reloaded with the initial count. The above process is repeated indefinitely. So for odd counts, OUT will be high for $(N + 1)/2$ counts and low for $(N - 1)/2$ counts.

Mode 4: Software Triggered Mode

OUT will be initially high. When the initial count expires, OUT will go low for one CLK pulse then go high again. The counting sequence is "Triggered" by writing the initial count.

GATE = 1 enables counting; GATE = 0 disables counting. GATE has no effect on OUT.

After writing a Control Word and initial count, the Counter will be loaded on the next CLK pulse. This CLK pulse does not decrement the count, so for an initial count of N, OUT does not strobe low until $N + 1$ CLK pulses after the initial count is written.

If a new count is written during counting, it will be loaded on the next CLK pulse and counting will continue from the new count. If a two-byte count is written, the following happens:

- (1) Writing the first byte has no effect on counting.
- (2) Writing the second byte allows the new count to be loaded on the next CLK pulse.

This allows the sequence to be "retriggered" by software. OUT strobes low $N + 1$ CLK pulses after the new count of N is written.

Mode 5: Hardware Triggered Strobe (Retriggerable)

OUT will initially be high. Counting is triggered by a rising edge of GATE. When the initial count has expired, OUT will go low for one CLK pulse and then go high again.

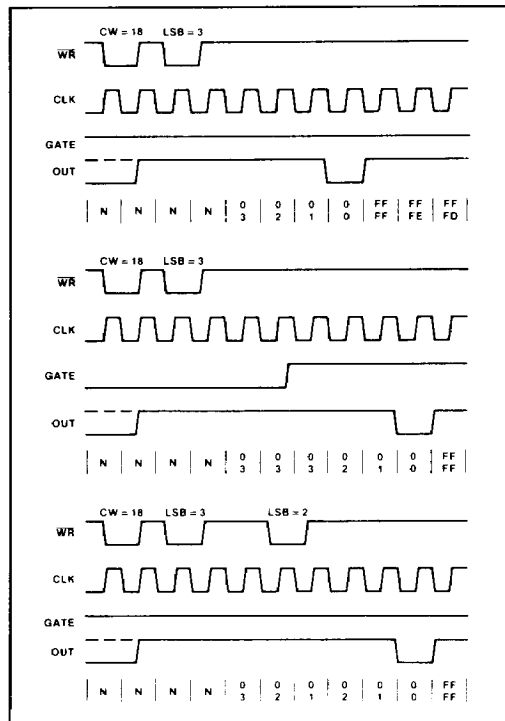


FIGURE 17. MODE 4

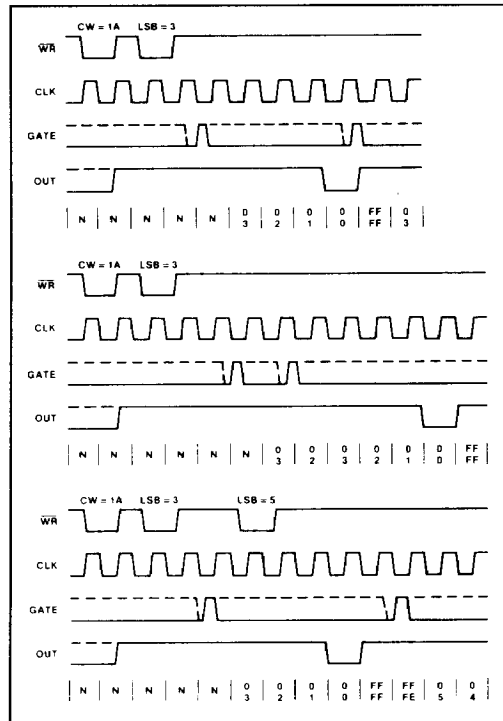


FIGURE 18. MODE 5

DESIGN INFORMATION (Continued)

The information contained in this section has been developed through characterization by Harris Semiconductor and is for use as application and design information only. No guarantee is implied.

After writing the Control Word and initial count, the counter will not be loaded until the CLK pulse after a trigger. This CLK pulse does not decrement the count, so for an initial count of N, OUT does not strobe low until N + 1 CLK pulses after any trigger.

A trigger results in the Counter being loaded with the initial count on the next CLK pulse. The counting sequence is triggerable. OUT will not strobe low for N + 1 CLK pulses after any trigger. GATE has no effect on OUT.

If a new count is written during counting, the current counting sequence will not be affected. If a trigger occurs after the new count is written but before the current count expires, the Counter will be loaded with the new count on the next CLK pulse and counting will continue from there.

Operation Common to All Modes

Programming

When a Control Word is written to a Counter, all Control Logic is immediately reset and OUT goes to a known initial state; no CLK pulses are required for this.

Gate

The GATE input is always sampled on the rising edge of CLK. In Modes 0, 2, 3 and 4 the GATE input is level sensitive, and logic level is sampled on the rising edge of CLK. In modes 1, 2, 3 and 5 the GATE input is rising-edge sensitive. In these Modes, a rising edge of Gate (trigger) sets an edge-sensitive flip-flop in the Counter. This flip-flop is then sampled on the next rising edge of CLK. The flip-flop is reset immediately after it is sampled. In this way, a trigger will be detected no matter when it occurs – a high logic level does not have to be maintained until the next rising edge of CLK. Note that in Modes 2 and 3, the GATE input is both edge- and level-sensitive.

Counter

New counts are loaded and Counters are decremented on the falling edge of CLK.

The largest possible initial count is 0; this is equivalent to 2^{16} for binary counting and 10^4 for BCD counting.

The counter does not stop when it reaches zero. In Modes 0, 1, 4 and 5 the Counter "wraps around" to the highest count, either FFFF hex for binary counting or 9999 for BCD

counting, and continues counting. Modes 2 and 3 are periodic; the Counter reloads itself with the initial count and continues counting from there.

SIGNAL STATUS MODES	LOW OR GOING LOW	ISING	HIGH
0	Disables counting	–	Enables counting
1	–	1) Initiates counting 2) Resets output after next clock	–
2	1) Disables counting 2) Sets output immediately high	Initiates counting	Enables counting
3	1) Disables counting 2) Sets output immediately high	Initiates counting	Enables counting
4	1) Disables counting	–	Enables counting
5	–	Initiates counting	–

FIGURE 19. GATE PIN OPERATIONS SUMMARY

MODE	MIN COUNT	MAX COUNT
0	1	0
1	1	0
2	2	0
3	2	0
4	1	0
5	1	0

NOTE: 0 is equivalent to 2^{16} for binary counting and 10^4 for BCD counting.

FIGURE 20. MINIMUM AND MAXIMUM INITIAL COUNTS