



Integrated
Circuit
Systems, Inc.

ICS9250-50

Frequency Generator & Integrated Buffers for PIII & Tualatin™

Recommended Application:

815B Solano B step style chipset

Output Features:

- 2 - CPUs @ 2.5V, up to 133MHz.
- 13 - SDRAM @ 3.3V, up to 133MHz.
- 3 - 3V66 @ 3.3V, 2x PCI MHz.
- 8 - PCI @ 3.3V
- 1 - 48MHz, @ 3.3V fixed
- 1 - 24/48MHz @ 3.3V
- 1 - REF @ 3.3V, 14.318MHz.
- 1 - IOAPIC @ 2.5V 16.67MHz.

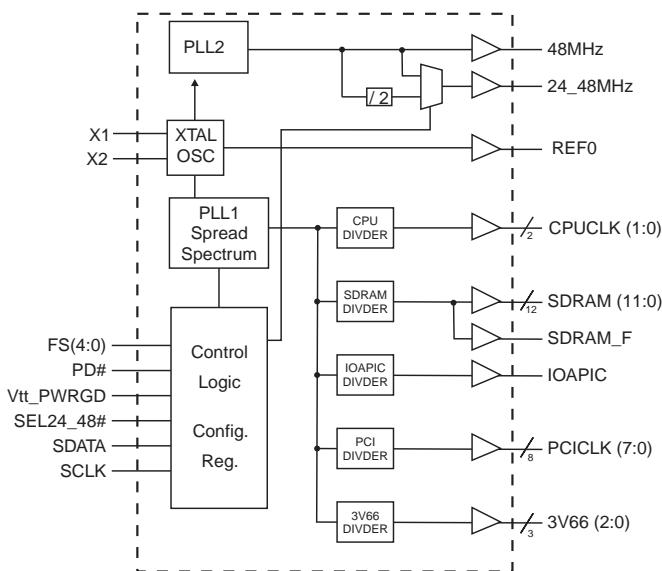
Features:

- Support PC133 SDRAM.
- Up to 133MHz frequency support
- Support power management through PD#
- Spread spectrum for EMI control ($\pm 0.25\%$ Center Spread or 0 to -0.5% down spread)
- Uses external 14.318MHz crystal
- FS pins for frequency select

Key Specifications:

- CPU Output Jitter: <250ps
- CPU Output Skew: <175ps
- PCI Output Skew: <500ps
- 3V66 Output Skew <175ps
- For group skew timing, please refer to the Group Timing Relationship Table.

Block Diagram



0594A—07/08/02

Pin Configuration

VDDA	1	56	REF0/FS4*
X1	2	55	VDDLAPIC
X2	3	54	IOAPIC
GND	4	53	VDDLCPU
GND3V66	5	52	CPUCLK0
3V66-0	6	51	CPUCLK1
3V66-1	7	50	GNDLCPU
3V66-2	8	49	GNDSDR
VDD3V66	9	48	SDRAM0
VDDPCI	10	47	SDRAM1
¹ *FS0/PCICLK0	11	46	SDRAM2
¹ *FS1/PCICLK1	12	45	VDDSDR
¹ *SEL24_48#/PCICLK2	13	44	SDRAM3
GNDPCI	14	43	SDRAM4
PCICLK3	15	42	SDRAM5
PCICLK4	16	41	GNDSDR
PCICLK5	17	40	SDRAM6
VDDPCI	18	39	SDRAM7
PCICLK6	19	38	SDRAM_F
PCICLK7	20	37	VDDSDR
GNDPCI	21	36	GND48
Vtt_PWRGD/PD#	22	35	24_48MHz/FS2*
SCLK	23	34	48MHz/FS3*
SDATA	24	33	VDD48
VDDSDR	25	32	VDDSDR
SDRAM11	26	31	SDRAM8
SDRAM10	27	30	SDRAM9
GNDSDR	28	29	GNDSDR

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56-Pin 300 mil SSOP

1. These pins will have 1.5 to 2X drive strength.
 * 120K ohm pull-up to VDD on indicated inputs.

Functionality

FS4	FS3	FS2	FS1	FS0	CPU	SDRAM	3V66	PCI
0	0	0	0	0	66.67	100.00	66.67	33.33
0	1	0	0	0	100.00	100.00	66.67	33.33
1	0	0	0	0	133.33	133.33	66.67	33.33
1	1	0	0	0	133.33	100.00	66.67	33.33

For other hardware/I²C selectable frequencies please refer to Byte 0 frequency select register.

Power Groups

- VDD48 = Fixed PLL power
 GND48 = Fixed PLL GND
 VDDA = Power for CPU PLL
 GNDA = GND for CPU PLL

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General Description

The **ICS9250-50** is a single chip clock solution for desktop designs using the 810/810E, Solano and Solano B- Step style chipset. It provides all necessary clock signals for such a system.

Spread spectrum may be enabled through I²C programming. Spread spectrum typically reduces system EMI by 8dB to 10dB. This simplifies EMI qualification without resorting to board design iterations or costly shielding. The ICS9250-50 employs a proprietary closed loop design, which tightly controls the percentage of spreading over process and temperature variations.

Serial programming I²C interface allows changing functions, stop clock programming and frequency selection.

Pin Configuration

PIN NUMBER	PIN NAME	TYPE	DESCRIPTION
1	VDDA	PWR	3.3V analog power supply for fixed PLL
9, 10, 18, 25, 32, 33, 37, 45	VDD	PWR	3.3V power supply
2	X1	IN	Crystal input, has internal load cap (33pF) and feedback resistor from X2
3	X2	OUT	Crystal output, nominally 14.318MHz. Has internal load cap (33pF)
4	GND _A	PWR	Analog Ground pin for 3.3V supply for fixed PLL
5, 14, 21, 28, 29, 36, 41, 49	GND	PWR	Ground pins for 3.3V supply
8, 7, 6	3V66 (2:0)	OUT	3.3V clock outputs for HUB @ 2X PCI frequency
11	PCICLK0	OUT	3.3V PCI clock outputs
	FS0	IN	Logic input frequency select bit. Input latched at power on.
12	PCICLK1	OUT	3.3V PCI clock outputs.
	FS1	IN	Logic input frequency select bit. Input latched at power on.
20, 19, 17, 16, 15	PCICLK (7:3)	OUT	3.3V PCI clock outputs.
13	PCICLK2	OUT	3.3V PCI clock output.
	SEL24_48#	IN	Input logic select. When logic "0" is selected pin 35 = 48MHz When logic "1" is selected pin 35 = 24MHz.
22	Vtt_PWRGD	IN	This pin acts as a dual function input pin for Vtt_PWRGD and PD# signal. When Vtt_PWRGD goes high the frequency select will be latched at power on thereafter the pin is an asynchronous active low power down pin.
	PD#	IN	Asynchronous active low input pin used to power down the device into a low power state. The internal clocks are disabled and the VCO and the crystal are stopped. The latency of the power down will not be greater than 3ms.
23	SCLK	IN	Clock input of I ² C serial input.
24	SDATA	IN	Data input for I ² C serial input.
34	48MHz	OUT	3.3V Fixed 48MHz clock output for USB.
	FS3	IN	Logic input frequency select bit. Input latched at power on.
35	FS2	IN	Logic input frequency select bit. Input latched at power on.
	24_48MHz	OUT	3.3V 24 or 48MHz output.
38	SDRAM_F	OUT	3.3V free running 100MHz SDRAM not affected by I ² C
48, 47, 46, 44, 43, 42, 40, 39, 31, 30, 27, 26	SDRAM (11:0)	OUT	3.3V output running 100MHz. All SDRAM outputs can be turned off through I ² C.
50	GNDL	PWR	Ground for 2.5V power supply for CPU & APIC.
51, 52	CPUCLK (1:0)	OUT	2.5V Host bus clock output. Output frequency derived from FS pins.
53, 55	VDDL	PWR	2.5V power supply for CPU, IOAPIC.
54	IOAPIC	OUT	2.5V clock outputs running at 16.67MHz.
56	FS4	IN	Logic input frequency select bit. Input latched at power on.
	REF0	OUT	3.3V, 14.318MHz reference clock output.

**Group Timing Relationship Table¹**

Group	CPU 66MHz SDRAM 100MHz		CPU 100MHz SDRAM 100MHz		CPU 133MHz SDRAM 100MHz		CPU 133MHz SDRAM 133MHz	
	Offset	Tolerance	Offset	Tolerance	Offset	Tolerance	Offset	Tolerance
CPU to SDRAM	2.5ns	500ps	5.0ns	500ps	0.0ns	500ps	3.75ns	500ps
CPU to 3V66	7.5ns	500ps	5.0ns	500ps	0.0ns	500ps	0.0ns	500ps
SDRAM to 3V66	0.0ns	500ps	0.0ns	500ps	0.0ns	500ps	3.75ns	500ps
3V66 to PCI	1.5-3.5ns	500ps	1.5-3.5ns	500ps	1.5-3.5ns	500ps	1.5 -3.5ns	500ps
PCI to PCI	0.0ns	1.0ns	0.0ns	1.0ns	0.0ns	1.0ns	0.0ns	1.0ns
USB & DOT	Asynch	N/A	Asynch	N/A	Asynch	N/A	Asynch	N/A

**Byte 0: Functionality and frequency select register (Default=0)
(1 = enable, 0 = disable)**

Bit	Description										PWD
Bit (2, 7:4)	Bit 2	Bit 7	Bit 6	Bit 5	Bit 4	CPUCLK MHz	SDRAM MHz	3V66 MHz	PCICLK	IOAPIC MHz	Spread Precentage 0 to -0.5% Down Spread 0 to -0.5% Down Spread 0 to -0.5% Down Spread 0 to -0.5% Down Spread
	FS4	FS3	FS2	FS1	FS0	66.67	100.01	66.67	33.34	16.67	
	0	0	0	0	0	100.00	100.00	66.67	33.33	16.67	
	0	1	0	0	0	133.33	133.33	66.67	33.33	16.67	
	1	0	0	0	0	133.33	100.00	66.67	33.33	16.67	
Bit 3	0-Frequency is selected by hardware select, latched inputs 1- Frequency is selected by Bit 2,7:4										0
Bit 1	0- Normal 1- Spread spectrum enable										1
Bit 0	0- Running 1- Tristate all outputs										0

Notes:

1. Default at power-up will be for latched logic inputs to define frequency, as displayed by Bit 3.
2. The I²C readback for Bit 2, 7:4 indicate the revision code.

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Byte 1: Control Register
(1 = enable, 0 = disable)

Bit	Pin#	PWD	Description
Bit 7	-	X	FS3#
Bit 6	-	X	FS0#
Bit 5	-	X	FS2#
Bit 4	35	0	24_48MHz #
Bit 3	-	1	(Reserved)
Bit 2	34	1	48MHz
Bit 1	-	1	(Reserved)
Bit 0	38	1	SDRAM_F

Byte 2: Control Register
(1 = enable, 0 = disable)

Bit	Pin#	PWD	Description
Bit 7	39	1	SDRAM7
Bit 6	40	1	SDRAM6
Bit 5	42	1	SDRAM5
Bit 4	43	1	SDRAM4
Bit 3	44	1	SDRAM3
Bit 2	46	1	SDRAM2
Bit 1	47	1	SDRAM1
Bit 0	48	1	SDRAM0

Byte 3: Control Register
(1 = enable, 0 = disable)

Bit	Pin#	PWD	Description
Bit 7	20	1	PCICLK7
Bit 6	19	1	PCICLK6
Bit 5	17	1	PCICLK5
Bit 4	16	1	PCICLK4
Bit 3	15	1	PCICLK3
Bit 2	13	1	PCICLK2
Bit 1	12	1	PCICLK1
Bit 0	11	1	PCICLK0

Byte 4: Control Register
(1 = enable, 0 = disable)

Bit	Pin#	PWD	Description
Bit 7	8	1	3V66_2
Bit 6	6	1	3V66_0
Bit 5	7	1	3V66_1
Bit 4	-	X	FS4#
Bit 3	54	1	IOAPIC
Bit 2	-	X	FS1#
Bit 1	51	1	CPUCLK1
Bit 0	52	1	CPUCLK0

Byte 5: Control Register
(1 = enable, 0 = disable)

Bit	Pin#	PWD	Description
Bit 7	-	1	(Reserved)
Bit 6	-	1	(Reserved)
Bit 5	-	1	(Reserved)
Bit 4	-	X	24_48MHz#
Bit 3	26	1	SDRAM11
Bit 2	27	1	SDRAM10
Bit 1	30	1	SDRAM9
Bit 0	31	1	SDRAM8

Byte 6: Peripheral , Active/Inactive Register
(1 = enable, 0 = disable)

Bit	Pin#	PWD	Description
Bit7	-	0	Reserved (Note)
Bit6	-	0	Reserved (Note)
Bit5	-	0	Reserved (Note)
Bit4	-	0	Reserved (Note)
Bit3	-	0	Reserved (Note)
Bit2	-	1	Reserved (Note)
Bit1	-	1	Reserved (Note)
Bit0	-	0	Reserved (Note)

Note: Don't write into this register, writing into this register can cause malfunction

Notes:

1. Inactive means outputs are held LOW and are disabled from switching. These outputs are designed to be configured at power-on and are not expected to be configured during the normal modes of operation.
2. PWD = Power on Default



Absolute Maximum Ratings

Core Supply Voltage	4.6 V
I/O Supply Voltage	3.6V
Logic Inputs	GND -0.5 V to V _{DD} +0.5 V
Ambient Operating Temperature	0°C to +70°C
Storage Temperature.....	-65°C to +150°C
Case Temperature	115°C

Stresses above those listed under *Absolute Maximum Ratings* may cause permanent damage to the device. These ratings are stress specifications only and functional operation of the device at these or any other conditions above those listed in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect product reliability.

Electrical Characteristics - Input / Supply / Common Output Parameters

T_A = 0 - 70°C; Supply Voltage V_{DD} = 3.3 V +/-5%, V_{DDL} = 2.5 V +/-5% (unless otherwise stated)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
Input High Voltage (Latched Inputs)	V _{IH}	V _{DD} <= 2.5 V	0.9	0.75	V _{DD} + 0.3	V
		V _{DD} = 3.15 - 3.45 V	1.15	0.85		
Input Low Voltage (Latched Inputs)	V _{IL}	V _{DD} <= 2.5 V	V _{SS} - 0.3	0.72	0.60	V
		V _{DD} = 3.15 - 3.45 V		0.82	0.65	
Input High Voltage (Real-Time Inputs)	V _{IH}	V _{DD} <= 2.5 V	1.4	1.05	V _{DD} + 0.3	V
		V _{DD} = 3.15 - 3.45 V	2	1.45		
Input Low Voltage (Real Time Inputs)	V _{IL}	V _{DD} <= 2.5 V	V _{SS} - 0.3	0.95	0.60	V
		V _{DD} = 3.15 - 3.45 V		1.35	0.80	
V _{DD} 3.3 Supply Power ²	I _{RAMP}	V _{DD} = 0 to 2.0 V	50			μs
Input High Current	I _{IH}	V _{IN} = V _{DD}	-5		5	mA
Input Low Current	I _{IL1}	V _{IN} = 0 V; Inputs with no pull-up resistors	-5			mA
Input Low Current	I _{IL2}	V _{IN} = 0 V; Inputs with pull-up resistors	-200			mA
Operating Supply Current	I _{DD3.3OP}	Cl = max cap loads; Select @ 66MHz		350	400	mA
	I _{DDL2.5OP}	Cl = max cap loads; Select @ 66MHz		13	20	
Power Down Current	I _{DD3.3PD}	Cl = 0 pF; With Input to Vdd or Gnd		275	600	μA
Input frequency	F _i	V _{DD} = 3.3 V		14.32		MHz
Pin Inductance	L _{pin}				7	nH
Input Capacitance ¹	C _{IN}	Logic Inputs			5	pF
	C _{out}	Output pin capacitance			6	pF
	C _{INX}	X1 & X2 pins	27		45	pF
Transition Time ¹	T _{Trans}	To 1st crossing of target Freq.			3	ms
Settling Time ¹	T _S	From 1st crossing to 1% target Freq.			3	ms
Clk Stabilization ¹	T _{Stab}	From V _{DD} = 3.3 V to 1% target Freq.			3	ms
Delay ¹	T _{PZH} , T _{PZL}	output enable delay(all outputs)	1		10	ns
	T _{PHZ} , T _{PLZ}	output disable delay(all outputs)	1		10	ns

¹Guaranteed by design, not 100% tested in production.

²When 2.5V and PD# pins are high before or simultaneous with V_{DD}3.3 reaching 2V.

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Electrical Characteristics - CPU

$T_A = 0 - 70^\circ\text{C}$; $V_{DD} = 2.5 \text{ V } +/- 5\%$; $C_L = 10-20 \text{ pF}$ (unless otherwise specified)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
Output Impedance ¹	R_{DSP2B}	$V_O = V_{DD}^*(0.5)$	13.5		45	Ω
Output Impedance ¹	R_{DSN2B}	$V_O = V_{DD}^*(0.5)$	13.5		45	Ω
Output High Voltage	V_{OH2B}	$I_{OH} = -1 \text{ mA}$	2			V
Output Low Voltage	V_{OL2B}	$I_{OL} = 1 \text{ mA}$			0.4	V
Output High Current	I_{OH2B}	$V_{OH} @ MIN = 1.0 \text{ V}$	-27			mA
		$V_{OH} @ MAX = 2.375 \text{ V}$			-27	
Output Low Current	I_{OL2B}	$V_{OL} @ MIN = 1.2 \text{ V}$	27			mA
		$V_{OL} @ MAX = 0.3 \text{ V}$			30	
Rise Time ¹	t_{r2B}	$V_{OL} = 0.4 \text{ V}$, $V_{OH} = 2.0 \text{ V}$	0.4	0.8	1.6	ns
Fall Time ¹	t_{f2B}	$V_{OH} = 2.0 \text{ V}$, $V_{OL} = 0.4 \text{ V}$	0.4	0.9	1.6	ns
Duty Cycle ¹	d_{t2B}	$V_T = 1.25 \text{ V}$, 66, 100 MHz	45	51	55	%
Skew window ¹	t_{sk2B}	$V_T = 1.25 \text{ V}$		98	175	ps
Jitter, Cycle-to-cycle ¹	$t_{j_{cyc-cyc2B}}$	$V_T = 1.25 \text{ V}$		115	250	ps

¹Guaranteed by design, not 100% tested in production.

Electrical Characteristics - 3V66

$T_A = 0 - 70^\circ\text{C}$; $V_{DD} = 3.3 \text{ V } +/- 5\%$; $C_L = 10-20 \text{ pF}$ (unless otherwise specified)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
Output Impedance	R_{DSP1}^1	$V_O = V_{DD}^*(0.5)$	12	17	55	Ω
Output Impedance	R_{DSN1}^1	$V_O = V_{DD}^*(0.5)$	12	18	55	Ω
Output High Voltage	V_{OH1}	$I_{OH} = -1 \text{ mA}$	2.4			V
Output Low Voltage	V_{OL1}	$I_{OL} = 1 \text{ mA}$			0.55	V
Output High Current	I_{OH1}	$V_{OH} @ MIN = 1.0 \text{ V}$	-33	-108		mA
		$V_{OH} @ MAX = 3.135 \text{ V}$		-9	-33	
Output Low Current	I_{OL1}	$V_{OL} @ MIN = 1.95 \text{ V}$	30	95		mA
		$V_{OL} @ MAX = 0.4 \text{ V}$		29	38	
Rise Time ¹	t_{r1}	$V_{OL} = 0.4 \text{ V}$, $V_{OH} = 2.4 \text{ V}$	0.4	1	1.6	ns
Fall Time ¹	t_{f1}	$V_{OH} = 2.4 \text{ V}$, $V_{OL} = 0.4 \text{ V}$	0.4	1	1.6	ns
Duty Cycle ¹	d_{t1}	$V_T = 1.5 \text{ V}$	45	50	55	%
Skew window ¹	t_{sk1}	$V_T = 1.5 \text{ V}$		75	175	ps
Jitter, Cycle-to-cycle ¹	$t_{j_{cyc-cyc1}}$	$V_T = 1.5 \text{ V}$		155	500	ps

¹Guaranteed by design, not 100% tested in production.



Electrical Characteristics - IOAPIC

$T_A = 0 - 70^\circ\text{C}$; $V_{DD} = 2.5 \text{ V } +/- 5\%$; $C_L = 10-20 \text{ pF}$ (unless otherwise specified)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
Output Impedance ¹	R_{DSP4B}	$V_O = V_{DD}^*(0.5)$	9	21.5	30	Ω
Output Impedance ¹	R_{DSN4B}	$V_O = V_{DD}^*(0.5)$	9	23	30	Ω
Output High Voltage	V_{OH4B}	$I_{OH} = -1 \text{ mA}$	2			V
Output Low Voltage	V_{OL4B}	$I_{OL} = 1 \text{ mA}$			0.4	V
Output High Current	I_{OH4B}	$V_{OH} @ MIN = 1.0 \text{ V}$	-27	-68		mA
		$V_{OH} @ MAX = 2.375 \text{ V}$		-9	-27	
Output Low Current	I_{OL4B}	$V_{OL} @ MIN = 1.2 \text{ V}$	27	54		mA
		$V_{OL} @ MAX = 0.3 \text{ V}$		11	30	
Rise Time ¹	t_{r4B}	$V_{OL} = 0.4 \text{ V}, V_{OH} = 2.0 \text{ V}$	0.4	1.2	1.6	ns
Fall Time ¹	t_{f4B}	$V_{OH} = 2.0 \text{ V}, V_{OL} = 0.4 \text{ V}$	0.4	1.3	1.6	ns
Duty Cycle ¹	d_{t4B}	$V_T = 1.25 \text{ V}$	45	50.6	55	%
Jitter, Cycle-to-cycle ¹	$t_{j_{cyc-cyc4B}}$	$V_T = 1.25 \text{ V}$		210	500	ps

¹Guaranteed by design, not 100% tested in production.

Electrical Characteristics - SDRAM

$T_A = 0 - 70^\circ\text{C}$; $V_{DD} = 3.3 \text{ V } +/- 5\%$; $C_L = 20-30 \text{ pF}$ (unless otherwise specified)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
Output Impedance ¹	R_{DSP3}	$V_O = V_{DD}^*(0.5)$	10	14	24	Ω
Output Impedance ¹	R_{DSN3}	$V_O = V_{DD}^*(0.5)$	10	18	24	Ω
Output High Voltage	V_{OH3}	$I_{OH} = -1 \text{ mA}$	2.4			V
Output Low Voltage	V_{OL3}	$I_{OL} = 1 \text{ mA}$			0.4	V
Output High Current	I_{OH3}	$V_{OH} @ MIN = 2.0 \text{ V}$	-54	-92		mA
		$V_{OH} @ MAX = 3.135 \text{ V}$		-16	-46	
Output Low Current	I_{OL3}	$V_{OL} @ MIN = 1.0 \text{ V}$	54	68		mA
		$V_{OL} @ MAX = 0.4 \text{ V}$		29	53	
Rise Time ¹	t_{r3}	$V_{OL} = 0.4 \text{ V}, V_{OH} = 2.4 \text{ V}$	0.4	1	1.6	ns
Fall Time ¹	t_{f3}	$V_{OH} = 2.4 \text{ V}, V_{OL} = 0.4 \text{ V}$	0.4	1.5	1.6	ns
Duty Cycle ¹	d_{t3}	$V_T = 1.5 \text{ V}$	45	52.5	55	%
Skew window ¹	t_{sk3}	$V_T = 1.5 \text{ V}$		58	250	ps
Jitter, Cycle-to-cycle ¹	$t_{j_{cyc-cyc3}}$	$V_T = 1.5 \text{ V}, 66, 100 \text{ MHz}$		170	250	ps

¹Guaranteed by design, not 100% tested in production.

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Electrical Characteristics - PCI

$T_A = 0 - 70^\circ\text{C}$; $V_{DD} = 3.3 \text{ V} +/- 5\%$; $C_L = 10-30 \text{ pF}$ (unless otherwise specified)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
Output Impedance ¹	R_{DSP1}	$V_O = V_{DD}^*(0.5)$	12	14	55	Ω
Output Impedance ¹	R_{DSN1}	$V_O = V_{DD}^*(0.5)$	12	18	55	Ω
Output High Voltage	V_{OH1}	$I_{OH} = -1 \text{ mA}$	2.4			V
Output Low Voltage	V_{OL1}	$I_{OL} = 1 \text{ mA}$			0.55	V
Output High Current	I_{OH1}	$V_{OH} @ \text{MIN} = 1.0 \text{ V}$	-33	-106		mA
		$V_{OH} @ \text{MAX} = 3.135 \text{ V}$		-14	-33	
Output Low Current	I_{OL1}	$V_{OL} @ \text{MIN} = 1.95 \text{ V}$	30	94		mA
		$V_{OL} @ \text{MAX} = 0.4 \text{ V}$		29	38	
Rise Time ¹	t_{r1}	$V_{OL} = 0.4 \text{ V}, V_{OH} = 2.4 \text{ V}$	0.5	1.5	2	ns
Fall Time ¹	t_{f1}	$V_{OH} = 2.4 \text{ V}, V_{OL} = 0.4 \text{ V}$	0.5	1.6	2	ns
Duty Cycle ¹	d_{t1}	$V_T = 1.5 \text{ V}$	45	51.9	55	%
Skew window ¹	t_{sk1}	$V_T = 1.5 \text{ V}$		328	500	ps
Jitter, Cycle-to-cycle ¹	$t_{j\text{cyc-cyc1}}$	$V_T = 1.5 \text{ V}$		170	500	ps

¹Guaranteed by design, not 100% tested in production.

Electrical Characteristics - REF, 24.48MHz

$T_A = 0 - 70^\circ\text{C}$; $V_{DD} = 3.3 \text{ V} +/- 5\%$; $C_L = 10-20 \text{ pF}$ (unless otherwise specified)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
Output Impedance ¹	R_{DSP5}	$V_O = V_{DD}^*(0.5)$	12	17	55	Ω
Output Impedance ¹	R_{DSN5}	$V_O = V_{DD}^*(0.5)$	12	18	55	Ω
Output High Voltage	V_{OH15}	$I_{OH} = -1 \text{ mA}$	2.4			V
Output Low Voltage	V_{OL5}	$I_{OL} = 1 \text{ mA}$			0.55	V
Output High Current	I_{OH5}	$V_{OH} @ \text{MIN} = 1.0 \text{ V}$	-33	-108		mA
		$V_{OH} @ \text{MAX} = 3.135 \text{ V}$		-9	-33	
Output Low Current	I_{OL5}	$V_{OL} @ \text{MIN} = 1.95 \text{ V}$	30	95		mA
		$V_{OL} @ \text{MAX} = 0.4 \text{ V}$		29	38	
Rise Time ¹	t_{r5}	$V_{OL} = 0.4 \text{ V}, V_{OH} = 2.4 \text{ V}$	0.4	1.2	4	ns
Fall Time ¹	t_{f5}	$V_{OH} = 2.4 \text{ V}, V_{OL} = 0.4 \text{ V}$	0.4	1.2	4	ns
Duty Cycle ¹	d_{t5}	$V_T = 1.5 \text{ V}$	45	52	55	%
Jitter, Cycle-to-cycle ¹	$t_{j\text{cyc-cyc5}}$	$V_T = 1.5 \text{ V}$, Fixed clocks		310	500	ps
Jitter, Cycle-to-cycle ¹	$t_{j\text{cyc-cyc5}}$	$V_T = 1.5 \text{ V}$, Ref clocks		720	1000	ps

¹Guaranteed by design, not 100% tested in production.



General I²C serial interface information

The information in this section assumes familiarity with I²C programming.
For more information, contact ICS for an I²C programming application note.

How to Write:

- Controller (host) sends a start bit.
- Controller (host) sends the write address D2_(H)
- ICS clock will *acknowledge*
- Controller (host) sends a dummy command code
- ICS clock will *acknowledge*
- Controller (host) sends a dummy byte count
- ICS clock will *acknowledge*
- Controller (host) starts sending first byte (Byte 0) through byte 5
- ICS clock will *acknowledge* each byte *one at a time*.
- Controller (host) sends a Stop bit

How to Write:	
Controller (Host)	ICS (Slave/Receiver)
Start Bit	
Address D2 _(H)	
	ACK
Dummy Command Code	
	ACK
Dummy Byte Count	
	ACK
Byte 0	
	ACK
Byte 1	
	ACK
Byte 2	
	ACK
Byte 3	
	ACK
Byte 4	
	ACK
Byte 5	
	ACK
Stop Bit	

How to Read:

- Controller (host) will send start bit.
- Controller (host) sends the read address D3_(H)
- ICS clock will *acknowledge*
- ICS clock will send the *byte count*
- Controller (host) acknowledges
- ICS clock sends first byte (*Byte 0*) through *byte 5*
- Controller (host) will need to acknowledge each byte
- Controller (host) will send a stop bit

How to Read:	
Controller (Host)	ICS (Slave/Receiver)
Start Bit	
Address D3 _(H)	
	ACK
	Byte Count
	ACK
	Byte 0
	ACK
	Byte 1
	ACK
	Byte 2
	ACK
	Byte 3
	ACK
	Byte 4
	ACK
	Byte 5
	ACK
Stop Bit	

Notes:

1. The ICS clock generator is a slave/receiver, I²C component. It can read back the data stored in the latches for verification. **Read-Back will support Intel PIIX4 "Block-Read" protocol.**
2. The data transfer rate supported by this clock generator is 100K bits/sec or less (standard mode)
3. The input is operating at 3.3V logic levels.
4. The data byte format is 8 bit bytes.
5. To simplify the clock generator I²C interface, the protocol is set to use only "**Block-Writes**" from the controller. The bytes must be accessed in sequential order from lowest to highest byte with the ability to stop after any complete byte has been transferred. The Command code and Byte count shown above must be sent, but the data is ignored for those two bytes. The data is loaded until a Stop sequence is issued.
6. At power-on, all registers are set to a default condition, as shown.



Shared Pin Operation - Input/Output Pins

The I/O pins designated by (input/output) serve as dual signal functions to the device. During initial power-up, they act as input pins. The logic level (voltage) that is present on these pins at this time is read and stored into a 5-bit internal data latch. At the end of Power-On reset, (see AC characteristics for timing values), the device changes the mode of operations for these pins to an output function. In this mode the pins produce the specified buffered clocks to external loads.

To program (load) the internal configuration register for these pins, a resistor is connected to either the VDD (logic 1) power supply or the GND (logic 0) voltage potential. A 10 Kilohm (10K) resistor is used to provide both the solid CMOS programming voltage needed during the power-up programming period and to provide an insignificant load on the output clock during the subsequent operating period.

Figure 1 shows a means of implementing this function when a switch or 2 pin header is used. With no jumper installed the pin will be pulled high. With the jumper in place the pin will be pulled low. If programmability is not necessary, than only a single resistor is necessary. The programming resistors should be located close to the series termination resistor to minimize the current loop area. It is more important to locate the series termination resistor close to the driver than the programming resistor.

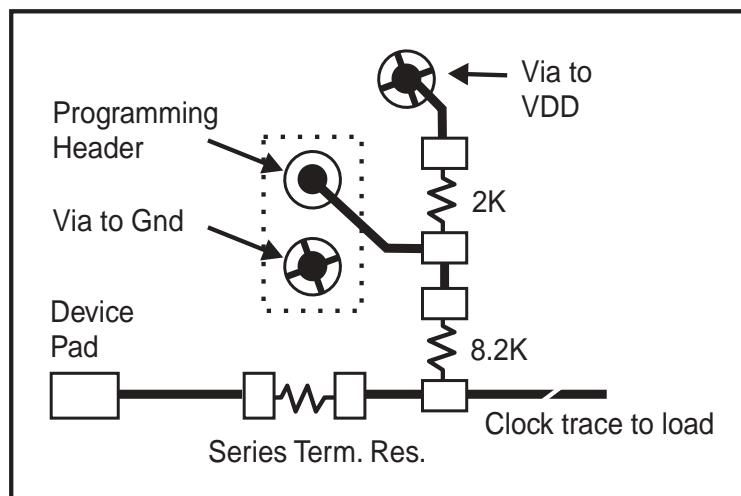
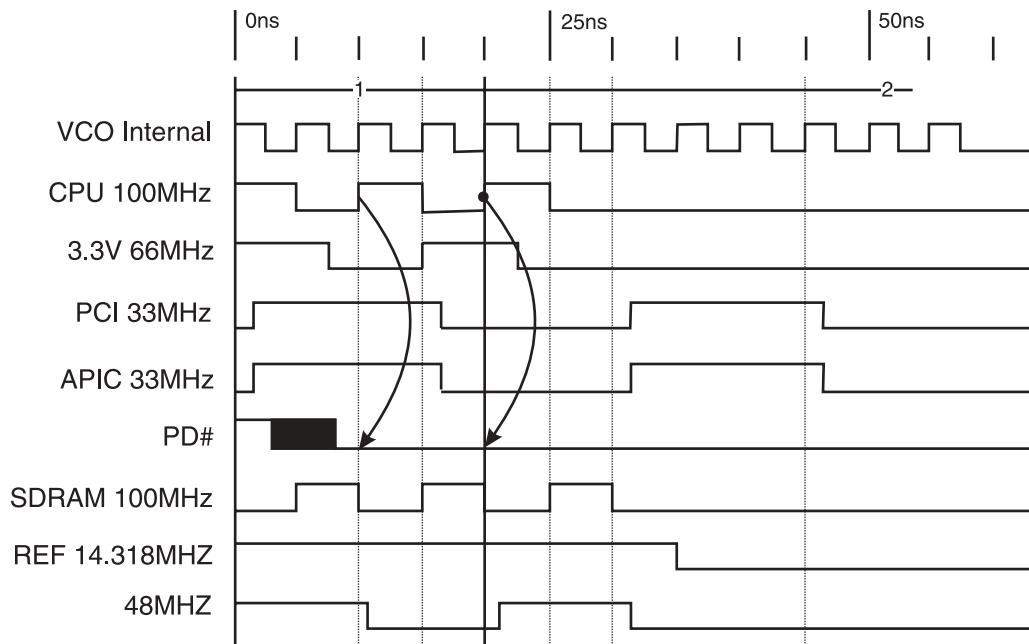


Fig. 1

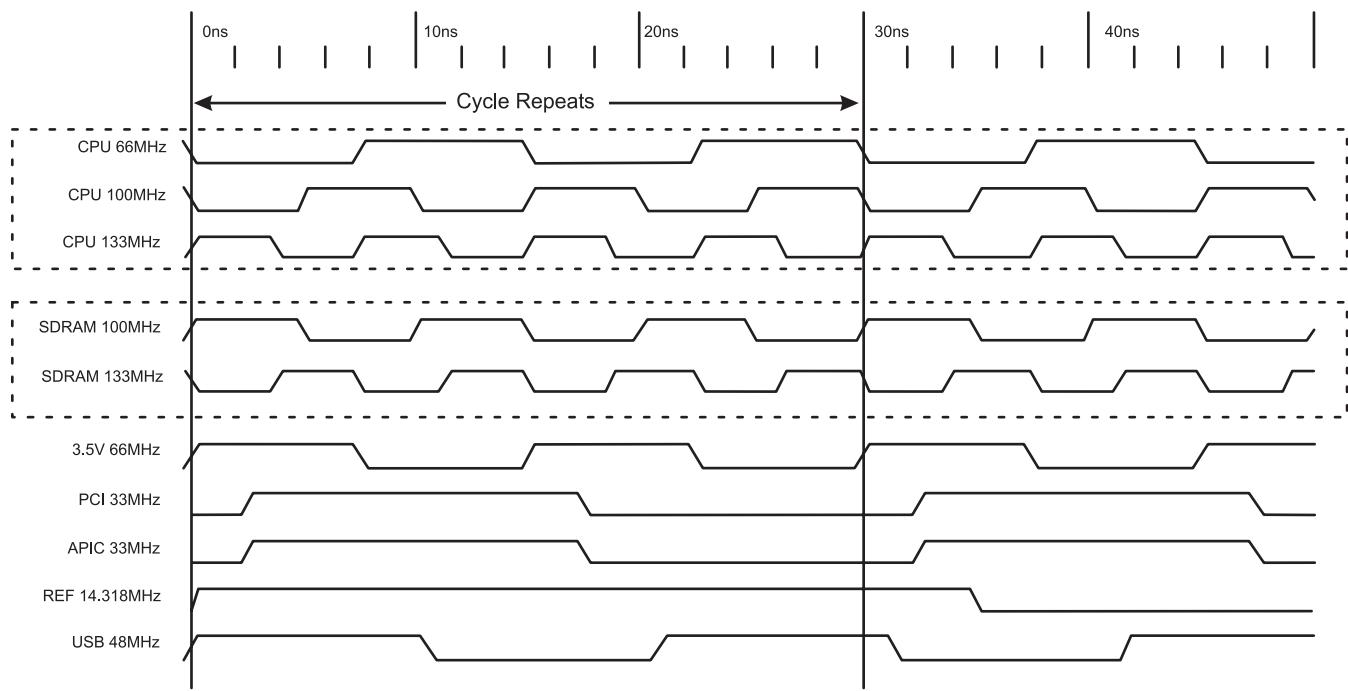


Power Down Waveform

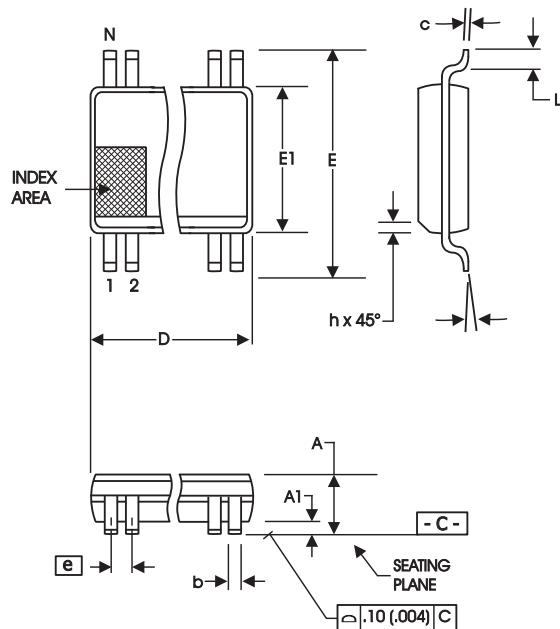


Note

1. After PD# is sampled active (Low) for 2 consecutive rising edges of CPUCLKs, all the output clocks are driven Low on their next High to Low transition.
2. Power-up latency <3ms.
3. Waveform shown for 100MHz



Group Offset Waveforms



SYMBOL	In Millimeters COMMON DIMENSIONS		In Inches COMMON DIMENSIONS	
	MIN	MAX	MIN	MAX
A	2.41	2.80	.095	.110
A1	0.20	0.40	.008	.016
b	0.20	0.34	.008	.0135
c	0.13	0.25	.005	.010
D	SEE VARIATIONS	SEE VARIATIONS	SEE VARIATIONS	SEE VARIATIONS
E	10.03	10.68	.395	.420
E1	7.40	7.60	.291	.299
e	0.635 BASIC		0.025 BASIC	
h	0.38	0.64	.015	.025
L	0.50	1.02	.020	.040
N	SEE VARIATIONS	SEE VARIATIONS	SEE VARIATIONS	SEE VARIATIONS
α	0°	8°	0°	8°

VARIATIONS

N	D mm.		D (inch)	
	MIN	MAX	MIN	MAX
56	18.31	18.55	.720	.730

Reference Doc.: JEDEC Publication 95, M O-118

10-0034

Ordering Information

ICS9250yF-50-T

Example:

