

Tri Axis Gyroscope & Accelerometer

Preliminary Technical Data

ADIS16350

FEATURES

Tri-axis gyroscope

+320 degrees/second measurement range

14-bit resolution

Tri-axis accelerometer

±10g measurement range

14-bit resolution

350Hz Bandwidth

Factory calibrated sensitivity and bias

Digitally controlled sensitivity and bias

Digitally controlled sample rate

Digitally controlled filtering

Programmable condition monitoring, alarms

Auxiliary digital I/O

Digitally activated self-test

Programmable power management

Embedded Temperature Sensor

SPI®-compatible serial interface

Auxiliary 12-bit ADC input and DAC output

Single-supply operation: +4.75V to +5.25 V

2000 g powered shock survivability

APPLICATIONS

Guidance and control
Platform control and stabilization
Motion control and analysis
Inertial Measurement Units
General Navigation
Image stabilization
Robotics

GENERAL DESCRIPTION

The ADIS16350 *i*Sensor[™] provides complete tri axis inertial sensing (both angular and linear motion) in a compact module fully ready for system integration. With Analog Devices' iMEMS[™] sensor technology at its core, the ADIS16350 includes embedded processing for sensor calibration and tuning. An SPI interface allows for simple system interface and programming.

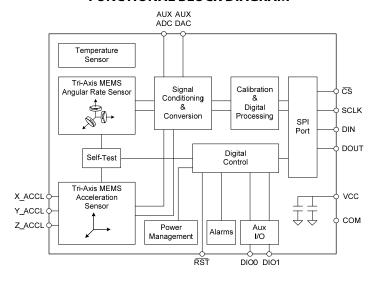
The SPI port provides access to the following embedded sensors: X, Y, and Z axis angular rate; X, Y, and Z axis linear acceleration; Internal Temperature; Power Supply; and an Auxiliary analog input. The inertial sensors are precision aligned across axis, and are calibrated for offset and sensitivity.

System interfacing is simplified with the following additional programmable features:

- In-system Bias Auto Calibration
- Digital Filtering and Sample Rate
- Self Test
- Power Management
- Condition Monitoring
- Auxiliary Digital I/O

The ultra compact module measures 22.7mmx23.2mmx22.9mm, plus mounting extensions.

FUNCTIONAL BLOCK DIAGRAM



REVISION HISTORY

9/06—Revision PSD1: Initial Version

SPECIFICATIONS

 $T_{A} = -40^{\circ}\text{C to } + 85^{\circ}\text{C}, \text{ $V_{CC} = 5.0 V$, Angular Rate} = 0^{\circ}\text{/s}, \text{ Dynamic Range } 320^{\circ}\text{/sec}, \\ \underline{+}1\text{g}, \text{ unless otherwise noted.}$

Table 1.

| Parameter Conditions | | Min | Тур | Max | Unit |
|------------------------------------|---|---------|---------------|-------------|---------|
| GYRO SENSITIVITY | ' Each axis | | | | |
| Dynamic Range | Full-scale range over specifications range | ±320 | | | °/s |
| Initial | 25°C, Dynamic range = <u>+</u> 320°/sec 0.07233 0.0732 | | 0.07326 | 0.07400 | °/s/LSB |
| | 25°C, Dynamic range = ±160°/sec | 0.03663 | | °/s/LSB | |
| | 25°C, Dynamic range = $\pm 80^{\circ}$ /sec | | 0.01832 | | °/s/LSB |
| Sensitivity Drift over Temp | -20°C to 75°C | | <u>+</u> 500 | | ppm/°C |
| Axis Non-orthogonality | 25°C, difference from 90 degrees ideal | | TBD | | degree |
| Axis Misalignment | 25°C, relative to base-plate & guide pins | | TBD | | degree |
| Non-Linearity | Best fit straight line | | <u>+</u> 0.1 | | % of FS |
| GYRO BIAS | | | | | |
| In Run Bias Stability | 25°C, 1 σ | | 0.016 | | °/s |
| Turn on – Turn on Bias Stability | 25°C, 1 σ | | 0.035 | | °/s |
| Angular Random Walk | 25°C | | 3.6 | | °/√hr |
| Zero Rate Bias Drift over Temp | -20°C to 75°C | | <u>+</u> 0.06 | | °/s/°C |
| g Sensitivity | Any Axis | | 0.2 | | °/s/g |
| Voltage Sensitivity | $V_{cc} = 4.75 \text{ V to } 5.25 \text{ V}$ | | 1.0 | | °/s /V |
| GYRO NOISE PERFORMANCE | | | | | |
| Output Noise | At 25°C, ±320 °/s Dynamic range, no filtering | TBD | | °/s rms | |
| | At 25°C, ±160 °/s Dynamic range, minimum 4 tap filter setting | TBD | | °/s rms | |
| | At 25°C, <u>+</u> 80°/s Dynamic range, minimum 16 tap filter setting | TBD | | °/s rms | |
| Rate Noise Density | At 25°C, f= 25Hz, no average | 0.05 | | °/s/√Hz rms | |
| GYRO FREQUENCY RESPONSE | | | | | |
| Sensor Bandwidth | | 350 | | Hz | |
| Sensor Resonant Frequency | | 14 | | kHz | |
| Turn-on Time | Power on from Sleep Mode to <u>+</u> 2°/s of final, no averaging, min sample period | TBD | | ms | |
| GYRO SELF-TEST STATE | | | | | |
| Change for positive stimulus | Relative to nominal output | 439 | 721 | 1092 | LSB |
| Change for negative stimulus | Relative to nominal output | -439 | -721 | -1092 | LSB |
| ACCELEROMETER SENSITIVITY | Each axis | | | | |
| Dynamic Range | | ±10 | | | g |
| Initial | @25°C | TBD | TBD 2.78 TBD | | mg/LSB |
| Sensitivity Drift Over Temperature | | TBD | | ppm/°C | |
| Axis Non-orthogonality | 25°C, difference from 90 degrees ideal | TBD | | degree | |
| Axis Misalignment | 25°C, relative to base-plate & guide pins | TBD | | degree | |
| Nonlinearity | Best Fit Straight Line | ±0.2 | | % of FS | |
| ACCELEROMETER BIAS | | | | | |
| 0g Offset | @25°C | TBD | | TBD | mg |
| 0g Offset Over Temperature | - | | TBD | | mg/°C |
| Axis Non-orthogonality | 25°C, difference from 90 degrees ideal | | TBD | | degree |
| Axis Misalignment | 25°C, relative to base-plate & guide pins | | TBD | | degree |

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Table 2. (Continued)

| Parameter | Conditions | Min | Тур | Max | Unit |
|---|---|--------|----------|------|-------------|
| ACCELEROMETER NOISE PERFORMANCE | | | | | |
| Output Noise | @25°C, no filtering | | TBD | | LSB rms |
| Noise Density | @25°C, no filtering | | 0.072 | | LSB/√Hz rms |
| ACCELEROMETER FREQUENCY RESPONSE | | | | | |
| Sensor Bandwidth | | | 350 | | Hz |
| Sensor Resonant Frequency | | | 10 | | kHz |
| ACCELEROMETER SELF-TEST STATE | | | | | |
| Output Change When Active | @25°C | 44 | 80 | 120 | LSB |
| TEMPERATURE SENSOR | | | | | |
| Output at 25°C | | | 1278 | | LSB |
| Scale Factor | | | -2.13 | | LSB/°C |
| ADC INPUT | | | | | |
| Resolution | | | 12 | | Bits |
| Integral Nonlinearity | | | ±2 | | LSB |
| Differential Nonlinearity | | | ±1 | | LSB |
| Offset Error | | | ±4 | | LSB |
| Gain Error | | | ±2 | | LSB |
| Input Range | | 0 | | 2.5 | V |
| Input Capacitance | During acquisition | | 20 | | pF |
| DAC OUTPUT | 5 kΩ/100 pF to GND | + | | | le. |
| Resolution | С 123 100 p. 10 0112 | | 12 | | Bits |
| Relative Accuracy | For Code 101 to Code 4095 | | 4 | | LSB |
| Differential Nonlinearity | | | 1 | | LSB |
| Offset Error | | | ±5 | | mV |
| Gain Error | | | ±0.5 | | % |
| Output Range | | | 0 to 2.5 | | V |
| Output Impedance | | | 2 | | Ω |
| Output Settling Time | | | 10 | | μs |
| LOGIC INPUTS | | + | | | ļ. |
| Input High Voltage, V _{INH} | | 2.0 | | | V |
| Input Low Voltage, V _{INL} | | | | 0.8 | V |
| pac 2011 Foliage, Fine | For –CS signal when used to wake up from SLEEP mode | | | 0.55 | V |
| Logic 1 Input Current, I _{INH} | V _{IH} = 3.3 V | | ±0.2 | ±10 | μΑ |
| Logic 0 Input Current, I _{INL} | $V_{IL} = 0 V$ | | -40 | -60 | μΑ |
| Input Capacitance, C _{IN} | | | 10 | | pF |
| DIGITAL OUTPUTS | | | | | <u> </u> |
| Output High Voltage, V _{он} | I _{SOURCE} = 1.6 mA | 2.4 | | | V |
| Output Low Voltage, Vol | $I_{SINK} = 1.6 \text{ mA}$ | | | 0.4 | V |
| SLEEP TIMER | | | | | |
| Timeout Period ¹ | | 0.5 | | 128 | Sec |
| FLASH MEMORY | | | | | 1 |
| | | | | | |
| Endurance ² | | 20,000 | | | Cycles |

Table 3. (Continued)

| rable 3. (Continued) | | | | | |
|---|---------------------|------|--------|------|-----|
| CONVERSION RATE | | | | | |
| Minimum Conversion Time | | | 0.9766 | | ms |
| Maximum Conversion Time | | | 1.937 | | Sec |
| Maximum Throughput Rate | | | 1024 | | SPS |
| Minimum Throughput Rate | | | 0.516 | | SPS |
| POWER SUPPLY | | | | | |
| Operating Voltage Range V _{CC} | | 4.75 | 5.0 | 5.25 | V |
| Power Supply Current | Normal mode at 25°C | | 48 | | mA |
| | Fast mode at 25°C | | 77 | | mA |
| | Sleep mode at 25°C | | 500 | | μΑ |

¹ Guaranteed by design ² Endurance is qualified as per JEDEC Standard 22 Method A117 and measured at –40°C, +25°C, +85°C, and +125°C. ³ Retention lifetime equivalent at junction temperature (T_.) 55°C as per JEDEC Standard 22 Method A117. Retention lifetime decreases with junction temperature.

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TIMING SPECIFICATIONS

 $T_A = +25$ °C, VCC = +5.0 V, angular rate = 0°/sec, unless otherwise noted.

Table 4.

| Parameter | Description | Min ¹ | Тур | Max | Unit |
|-----------------------|---|------------------|-----|------|------|
| f _{SCLK} | Fast mode, SMPL_TIME \leq 0x07 ($f_S \geq$ 256 Hz) | 0.01 | | 2.5 | MHz |
| | Normal mode, SMPL_TIME \geq 0x08 (f _S \leq 228 Hz) | 0.01 | | 1.0 | MHz |
| t _{DATARATE} | Chip select period, fast mode, SMPL_TIME \leq 0x07 (f _S \geq 256 Hz) | 40 | | | μs |
| | Chip select period, normal mode, SMPL_TIME \geq 0x08 (f _s \leq 228 Hz) | 100 | | | μs |
| tcs | Chip select to clock edge | 48.8 | | | ns |
| t _{DAV} | Data output valid after SCLK falling edge ² | | | 100 | ns |
| t _{DSU} | Data input setup time before SCLK rising edge | 24.4 | | | ns |
| t _{DHD} | Data input hold time after SCLK rising edge | 48.8 | | | ns |
| t _{DF} | Data output fall time | | 5 | 12.5 | ns |
| t _{DR} | Data output rise time | | 5 | 12.5 | ns |
| tsfs | CS high after SCLK edge ³ | 5 | | | ns |

¹ Guaranteed by design, not production tested.

TIMING DIAGRAMS

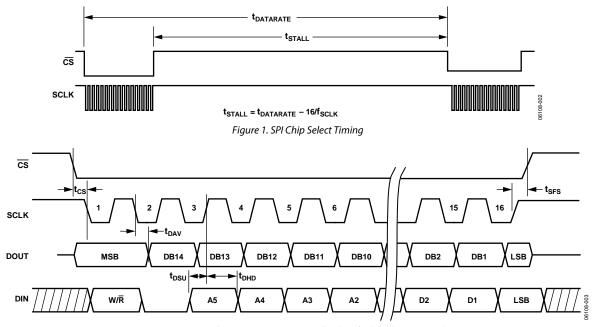


Figure 2. SPI Timing, Utilizing SPI Settings Typically Identified as Phase = 1, Polarity = 1

² The MSB presents an exception to this parameter. The MSB clocks out on the falling edge of CS. The rest of the DOUT bits are clocked after the falling edge of SCLK and are governed by this specification.

³ This parameter may need to be expanded to allow for proper capture of the LSB. After CS goes high, the DOUT line goes into a high impedance state.

ABSOLUTE MAXIMUM RATINGS

Table 5

| Table 3. | |
|-------------------------------------|-----------------------|
| Parameter | Rating |
| Acceleration (Any Axis, Unpowered) | 2000 g |
| Acceleration (Any Axis, Powered) | 2000 <i>g</i> |
| VDD to COM | −0.3 V to +7.0 V |
| Digital Input/Output Voltage to COM | −0.3 V to +5.5 V |
| Analog Inputs to COM | -0.3 V to VCC + 0.3 V |
| Operating Temperature Range | −40°C to +105°C |
| Storage Temperature Range | −65°C to +150°C¹ |

 $^{^1}$ Extended exposure to temperatures outside of the specified temperature range of -40°C to +85°C can adversely affect the accuracy of the factory calibration. For best accuracy, store the parts within the specified operating range of -40°C to +85°C.

Stresses above those listed under Absolute Maximum Ratings may cause permanent damage to the device. This is a stress rating only; functional operation of the device at these or any other conditions above those indicated in the operational section of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

Table 6. Package Characteristics

| Package Type | θ _{JA} | θις | Device Weight |
|--------------|-----------------|-----|---------------|
| TBD | TBD | TBD | TBD |

ESD CAUTION

ESD (electrostatic discharge) sensitive device. Electrostatic charges as high as 4000 V readily accumulate on the human body and test equipment and can discharge without detection. Although this product features proprietary ESD protection circuitry, permanent damage may occur on devices subjected to high energy electrostatic discharges. Therefore, proper ESD precautions are recommended to avoid performance degradation or loss of functionality.



PIN CONFIGURATION AND FUNCTION DESCRIPTIONS

| 1 | 0 | 0 | 2 |
|----|---|---|----|
| 3 | 0 | 0 | 4 |
| 5 | 0 | 0 | 6 |
| 7 | 0 | 0 | 8 |
| 9 | 0 | 0 | 10 |
| 11 | 0 | 0 | 12 |
| 13 | 0 | 0 | 14 |
| 15 | 0 | 0 | 16 |
| 17 | 0 | 0 | 18 |
| 19 | 0 | 0 | 20 |
| 21 | 0 | 0 | 22 |
| 23 | 0 | 0 | 24 |
| | | | |

Figure 3. Pin Configuration, Bottom, Pin View

Table 7. Pin Function Descriptions

| Pin No. | Mnemonic | Type ¹ | Description |
|---------|----------|-------------------|---|
| 1 | DNC | | Do not connect |
| 2 | DNC | | Do not connect |
| 3 | SCLK | 1 | SPI, Serial clock |
| 4 | DOUT | 0 | SPI, Data output |
| 5 | DIN | 1 | SPI, Data input |
| 6 | ~CS | 1 | SPI, Chip Select |
| 7 | DIO0 | I/O | Digital I/O |
| 8 | ~RST | 1 | Reset |
| 9 | DIO1 | I/O | Digital I/O |
| 10 | VCC | S | Power supply |
| 11 | VCC | S | Power supply |
| 12 | VCC | S | Power supply |
| 13 | GND | S | Power ground |
| 14 | GND | S | Power ground |
| 15 | GND | S | Power ground |
| 16 | DNC | N/A | Do not connect |
| 17 | DNC | N/A | Do not connect |
| 18 | DNC | N/A | Do not connect |
| 19 | DNC | N/A | Do not connect |
| 20 | AUX_DAC | 0 | Auxiliary, 12-bit digital-to-analog converter output |
| 21 | AUX_ADC | 1 | Auxiliary, 12-bit, analog-to-digital converter in put |
| 22 | Y_ACCL | 0 | Y-Axis acceleration |
| 23 | X_ACCL | 0 | X-Axis acceleration |
| 24 | Z_ACCL | 0 | Z-Axis acceleration |

 $^{^{1}}$ S = supply, O = output, I = input.

OUTLINE DIMENSIONS

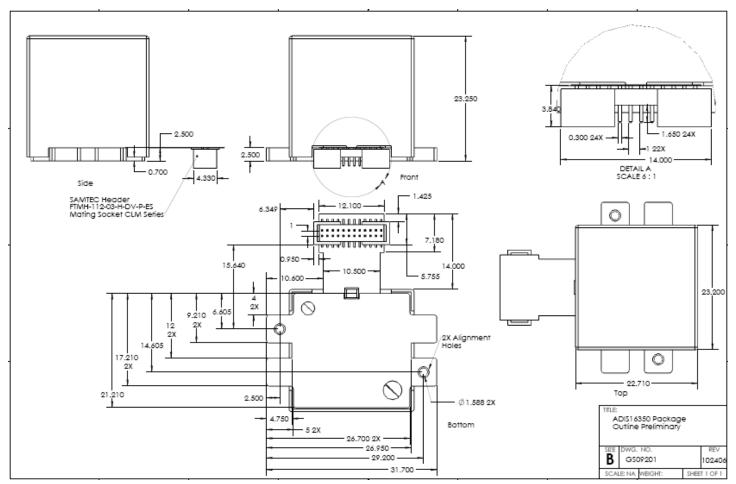


Figure 4.
Dimensions shown in millimeters

ORDERING GUIDE

| Model | Temperature Range | Package Description | Package Option |
|----------------|-------------------|---------------------|----------------|
| ADIS16350AML | -40°C to +85°C | | |
| ADIS16350/PCBZ | | | |

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NOTES