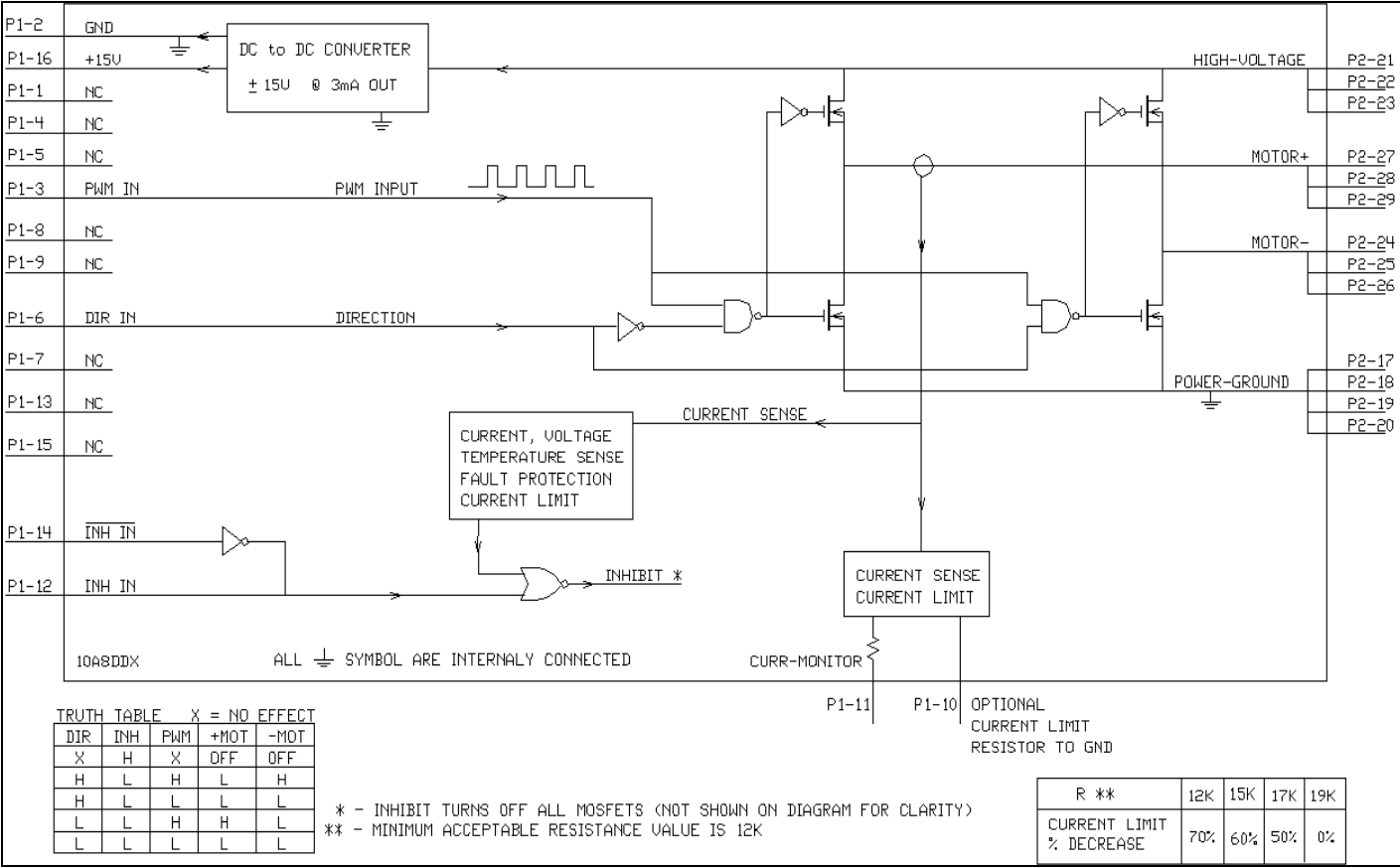
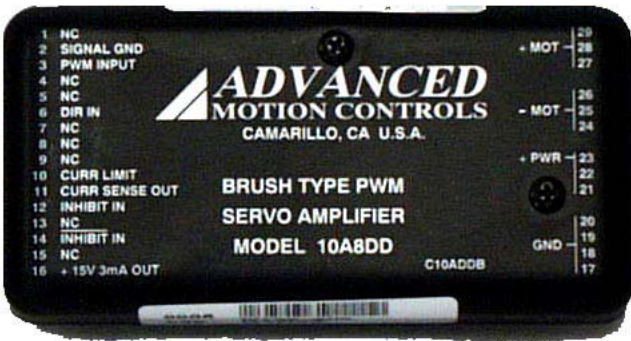


SERIES 10A-DD PWM BRUSH TYPE SERVO AMPLIFIERS
Model: 10A8DD

FEATURES:

- Surface-mount technology
- Small size, low cost, ease of use
- Adjustable current limit
- Four quadrant regenerative operation
- Agency Approvals:



ADVANCED MOTION CONTROLS
3805 Calle Tecate, Camarillo, CA 93012 Tel: (805) 389-1935, Fax: (805) 389-1165

DESCRIPTION: The 10A8DD PWM servo amplifier is designed to drive brush type DC motors. The PWM frequency is determined by the PWM input signal. The 10A8DD is fully protected against over-voltage, over-current, over-heating and short circuits across motor, ground and power leads. This model interfaces with digital controllers that have a digital PWM output. It can also be used as a stand-alone system. The 10A8DD amplifier requires only a single unregulated DC power supply as all logic and control voltages are generated internally. PWM input determines the output duty cycle. "Direction In" determines which side of the "H bridge" output is switching. The current limit can be reduced by an external resistor. The voltage at the current monitor pin P1-11 is proportional to the actual motor current.

SPECIFICATIONS:

	MODEL
POWER STAGE SPECIFICATIONS	10A8DD
DC SUPPLY VOLTAGE	20 - 80 V
PEAK CURRENT	± 10 A
MAXIMUM CONTINUOUS CURRENT	± 6 A
MINIMUM LOAD INDUCTANCE*	150 μ H
SWITCHING FREQUENCY	5-20 kHz $\pm 15\%$
HEATSINK (base) TEMPERATURE RANGE	0° to + 65° C, disables if > +65° C
POWER DISSIPATION AT CONTINUOUS CURRENT	40 W
OVER-VOLTAGE SHUT-DOWN (self reset)	85 V

MECHANICAL SPECIFICATIONS	
SIGNAL CONNECTOR	Molex connectors
SIZE	4.00 x 2.00 x 0.60 inches 101.6 x 50.8 x 15.2 mm
WEIGHT	5.1 oz 0.143 kg

* "Pancake" and "basket-wound" motors require external inductors.

PIN FUNCTIONS:

CONNECTOR	PIN	NAME	DESCRIPTION / NOTES	I/O
P1	1	NC		
	2	SIGNAL GND	Reference ground	GND
	3	PWM / IN	2.5 - 15 V, Pulse Width Modulated Digital Input	I
	4	NC		
	5	NC		
	6	DIRECTION	2.5 - 15 V, Direction Input	I
	7	NC		
	8	NC		
	9	NC		
	10	CURRENT LIMIT	Can be used to reduce the factory preset maximum current limit.	I
	11	CURRENT MONITOR	This signal is proportional to the actual current in the motor leads. Scaling is 1V = 2A.	O
	12	INHIBIT	Turns off all mosfets of the "H" bridge drive when high.	I
	13	NC		
	14	INHIBIT	Turns off all mosfets of the "H" bridge drive when low.	I
	15	NC		
	16	15 V @ 3 mA	For customer use	O
	17-20	POWER GND	Power Ground, Common to P1-2	GND
	21-23	+ HIGH VTG	DC Power Input	I
	24-26	- MOTOR	Negative Motor Output	O
	27-29	+ MOTOR	Positive Motor Output	O

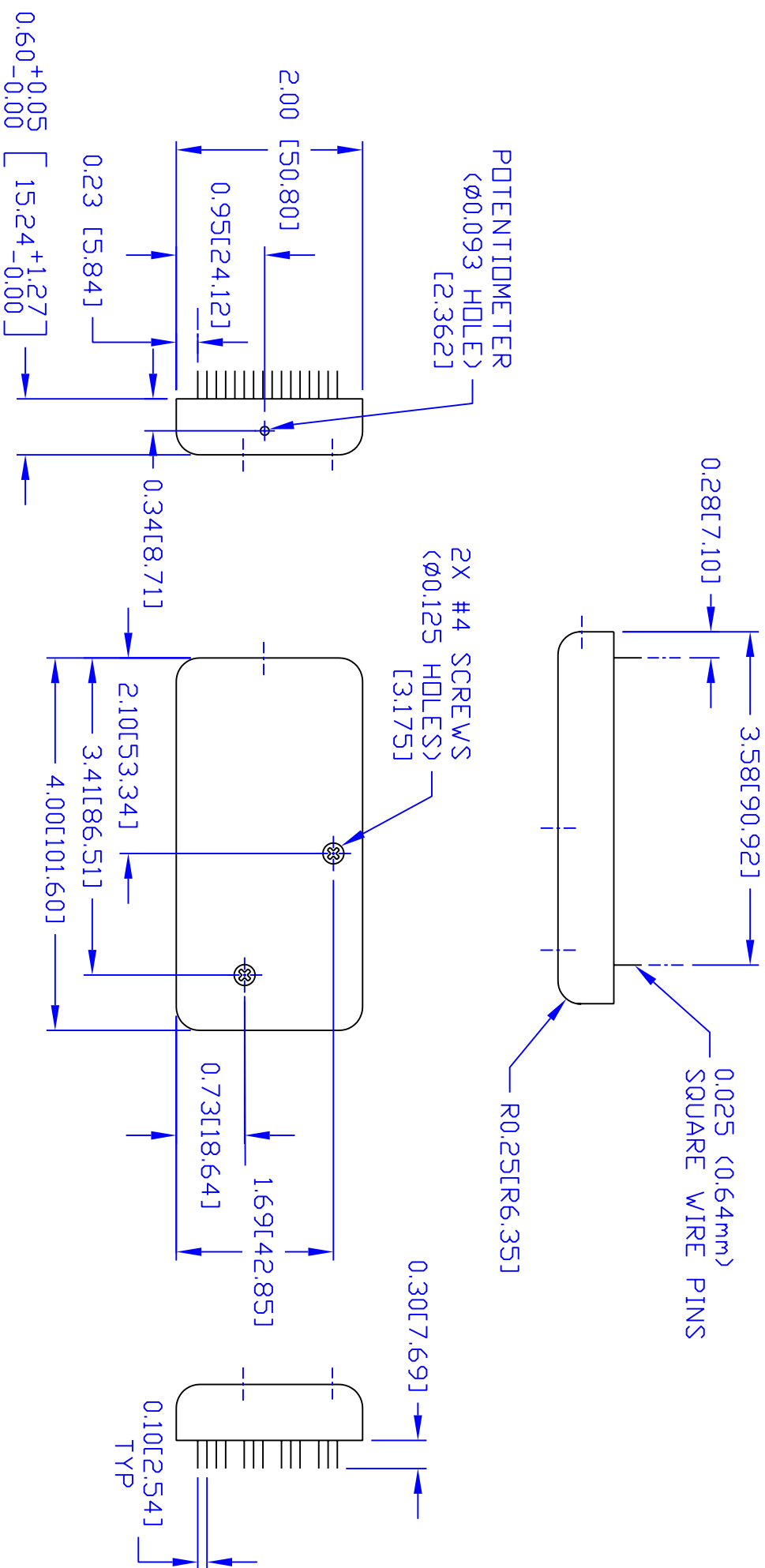
10A8DD Series

ORDERING INFORMATION:

Model: 10A8DDX

X indicates current revision letter.

MOUNTING DIMENSIONS: See page F-5.



MODEL 10A8, 10A8DD

NOTE: DIMENSIONS IN [] ARE IN MM.

		C	ADDED TOL. TO DIM. 0.60		11/19/03	RB
		B	UPDATE ADDRESS ON DWG FORMAT		02/12/02	RB
		A	UPDATE DWG FORMAT		08/22/96	RB
		REV	DESCRIPTION		DATE	BY
		UNLESS OTHERWISE SPECIFIED: DIMENSIONS ARE IN INCHES TOLERANCES .XX ± .010 .XXX ± .005 DO NOT SCALE DRAWING				
		DRAWN BY: AIDA DATE: 06/03/93				
		CHECK BY: DATE:				
		DESIGN APPROVED: DATE:				
10A8DD SERIES 10A SERIES USED ON		SIZE B SCALE: NONE		DWG. NO. M10A		REV C
		TITLE MOUNTING DIMENSIONS 10A SERIES				
		ADVANCED MOTION CONTROLS • PWM SERVO AMPLIFIERS • 3805 Calle Tecate, Camarillo, CA 93012				