

HM64YGB36100 Series

32M Synchronous Late Write Fast Static RAM
(1-Mword \times 36-bit)

REJ03C0271-0100
(Previous ADE-203-1374 (Z) Rev. 0.0)
Rev.1.00
Jun.27.2005

Description

The HM64YGB36100 is a synchronous fast static RAM organized as 1-Mword \times 36-bit. It has realized high speed access time by employing the most advanced CMOS process and high speed circuit designing technology. It is most appropriate for the application which requires high speed, high density memory and wide bit width configuration, such as cache and buffer memory in system. It is packaged in standard 119-bump BGA.

Note: All power supply and ground pins must be connected for proper operation of the device.

Features

- 2.5 V \pm 5% operation and 1.5 V (V_{DDQ})
- 32-Mbit density
- Synchronous register to register operation
- Internal self-timed late write
- Byte write control (4 byte write selects, one for each 9-bit)
- Optional $\times 18$ configuration
- HSTL compatible I/O
- Programmable impedance output drivers
- Differential HSTL clock inputs
- Asynchronous \overline{G} output control
- Asynchronous sleep mode
- FC-BGA 119pin package with SRAM JEDEC standard pinout
- Limited set of boundary scan JTAG IEEE 1149.1 compatible

Ordering Information

| Type No. | Organization | Access time | Cycle time | Package |
|-------------------|----------------|-------------|------------|--|
| HM64YGB36100BP-33 | 1M \times 36 | 1.6 ns | 3.3 ns | 119-bump 1.27 mm 14 mm \times 22 mm BGA PRBG0119DC-A (BP-119F) |

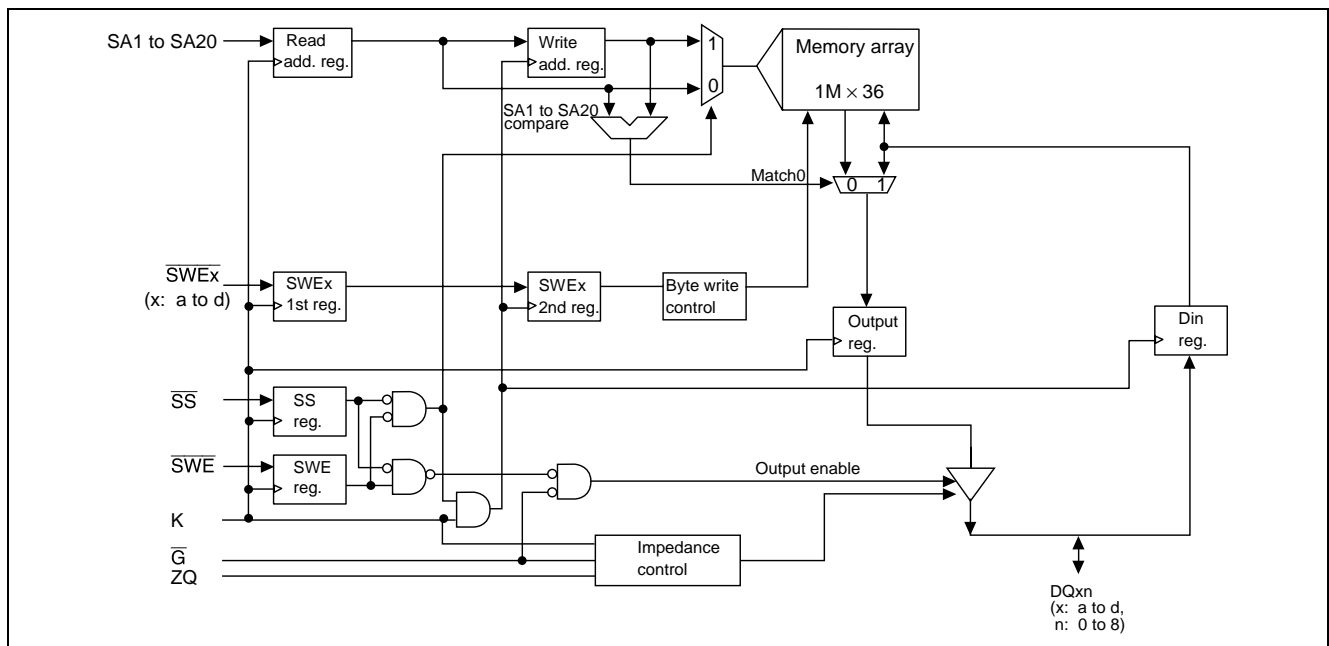
Note: HM: Hitachi Memory prefix, 64: External Cache SRAM, Y: $V_{DD} = 2.5$ V, G: Late Write SRAM, B: $V_{DDQ} = 1.5$ V

Pin Arrangement

| | 1 | 2 | 3 | 4 | 5 | 6 | 7 |
|---|------------------|-----------------|--------------------|-----------------|--------------------|-----------------|------------------|
| A | V _{DDQ} | SA14 | SA13 | NC | SA6 | SA7 | V _{DDQ} |
| B | NC | SA15 | SA12 | SA20 | SA5 | SA9 | NC |
| C | NC | SA16 | SA11 | V _{DD} | SA4 | SA8 | NC |
| D | DQc7 | DQc8 | V _{SS} | ZQ | V _{SS} | DQb8 | DQb7 |
| E | DQc5 | DQc6 | V _{SS} | \overline{SS} | V _{SS} | DQb6 | DQb5 |
| F | V _{DDQ} | DQc4 | V _{SS} | \overline{G} | V _{SS} | DQb4 | V _{DDQ} |
| G | DQc3 | DQc2 | \overline{SWEc} | NC | \overline{SWEb} | DQb2 | DQb3 |
| H | DQc1 | DQc0 | V _{SS} | NC | V _{SS} | DQb0 | DQb1 |
| J | V _{DDQ} | V _{DD} | V _{REF} | V _{DD} | V _{REF} | V _{DD} | V _{DDQ} |
| K | DQd1 | DQd0 | V _{SS} | K | V _{SS} | DQa0 | DQa1 |
| L | DQd3 | DQd2 | $\overline{SWE d}$ | \overline{K} | $\overline{SWE a}$ | DQa2 | DQa3 |
| M | V _{DDQ} | DQd4 | V _{SS} | SWE | V _{SS} | DQa4 | V _{DDQ} |
| N | DQd5 | DQd6 | V _{SS} | SA17 | V _{SS} | DQa6 | DQa5 |
| P | DQd7 | DQd8 | V _{SS} | SA19 | V _{SS} | DQa8 | DQa7 |
| R | NC | SA10 | M1 | V _{DD} | M2 | SA1 | NC |
| T | NC | NC | SA18 | SA3 | SA2 | NC | ZZ |
| U | V _{DDQ} | TMS | TDI | TCK | TDO | NC | V _{DDQ} |

(Top view)

Block Diagram



Pin Descriptions

| Name | I/O type | Descriptions | Notes |
|------------------|----------|---|------------------------|
| V _{DD} | Supply | Core power supply | |
| V _{SS} | Supply | Ground | |
| V _{DDQ} | Supply | Output power supply | |
| V _{REF} | Supply | Input reference, provides input reference voltage | |
| K | Input | Clock input, active high | |
| \bar{K} | Input | Clock input, active low | |
| \bar{SS} | Input | Synchronous chip select | |
| SWE | Input | Synchronous write enable | |
| SAn | Input | Synchronous address input | n: 1 to 20 |
| SWEx | Input | Synchronous byte write enables | x: a to d |
| \bar{G} | Input | Asynchronous output enable | |
| ZZ | Input | Power down mode select | |
| ZQ | Input | Output impedance control | 1 |
| DQxn | I/O | Synchronous data input/output | x: a to d n: 0 to 8 |
| M1, M2 | Input | Output protocol mode select | |
| TMS | Input | Boundary scan test mode select | |
| TCK | Input | Boundary scan test clock | |
| TDI | Input | Boundary scan test data input | |
| TDO | Output | Boundary scan test data output | |
| NC | — | No connection | |

| M1 | M2 | Protocol | Notes |
|-----------------|-----------------|--|-------|
| V _{SS} | V _{DD} | Synchronous register to register operation | 2 |

- Notes: 1. ZQ is to be connected to V_{SS} via a resistance R_Q where $175\ \Omega \leq R_Q \leq 300\ \Omega$. If ZQ = V_{DDQ} or open, output buffer impedance will be maximum.
2. Mode control input pins M1 and M2 are set at power-up and will not change the states during the SRAM operates.
This SRAM supports only single clock, pipelined read protocol.
Other settings are not applicable.
Mode control pin M2 can be set to V_{DDQ} instead of V_{DD}.

Truth Table

| ZZ | SS | \bar{G} | SWE | SWEa | SWEb | SWEc | SWEd | K | \bar{K} | Operation | DQ (n) | DQ (n+1) |
|----|----|-----------|-----|------|------|------|------|-----|-----------|-----------------------|--------|--------------------------------------|
| H | × | × | × | × | × | × | × | × | × | Sleep mode | High-Z | High-Z |
| L | H | × | × | × | × | × | × | L-H | H-L | Dead (not selected) | × | High-Z |
| L | × | H | H | × | × | × | × | × | × | Dead (dummy read) | High-Z | × |
| L | L | L | H | × | × | × | × | L-H | H-L | Read | × | D _{OUT} (a, b, c, d) 0 to 8 |
| L | L | × | L | L | L | L | L | L-H | H-L | Write a, b, c, d byte | High-Z | D _{IN} (a, b, c, d) 0 to 8 |
| L | L | × | L | H | L | L | L | L-H | H-L | Write b, c, d byte | High-Z | D _{IN} (b, c, d) 0 to 8 |
| L | L | × | L | L | H | L | L | L-H | H-L | Write a, c, d byte | High-Z | D _{IN} (a, c, d) 0 to 8 |
| L | L | × | L | L | L | H | L | L-H | H-L | Write a, b, d byte | High-Z | D _{IN} (a, b, d) 0 to 8 |
| L | L | × | L | L | L | L | H | L-H | H-L | Write a, b, c byte | High-Z | D _{IN} (a, b, c) 0 to 8 |
| L | L | × | L | H | H | L | L | L-H | H-L | Write c, d byte | High-Z | D _{IN} (c, d) 0 to 8 |
| L | L | × | L | L | H | H | L | L-H | H-L | Write a, d byte | High-Z | D _{IN} (a, d) 0 to 8 |
| L | L | × | L | L | L | H | H | L-H | H-L | Write a, b byte | High-Z | D _{IN} (a, b) 0 to 8 |
| L | L | × | L | H | L | L | H | L-H | H-L | Write b, c byte | High-Z | D _{IN} (b, c) 0 to 8 |
| L | L | × | L | H | H | H | L | L-H | H-L | Write d byte | High-Z | D _{IN} (d) 0 to 8 |
| L | L | × | L | H | H | L | H | L-H | H-L | Write c byte | High-Z | D _{IN} (c) 0 to 8 |
| L | L | × | L | H | L | H | H | L-H | H-L | Write b byte | High-Z | D _{IN} (b) 0 to 8 |
| L | L | × | L | L | H | H | H | L-H | H-L | Write a byte | High-Z | D _{IN} (a) 0 to 8 |

Notes: 1. H: V_{IH}, L: V_{IL}, ×: V_{IH} or V_{IL}

2. SWE, SS, \bar{SWEa} to \bar{SWEd} and SA are sampled at the rising edge of K clock.

Programmable Impedance Output Drivers

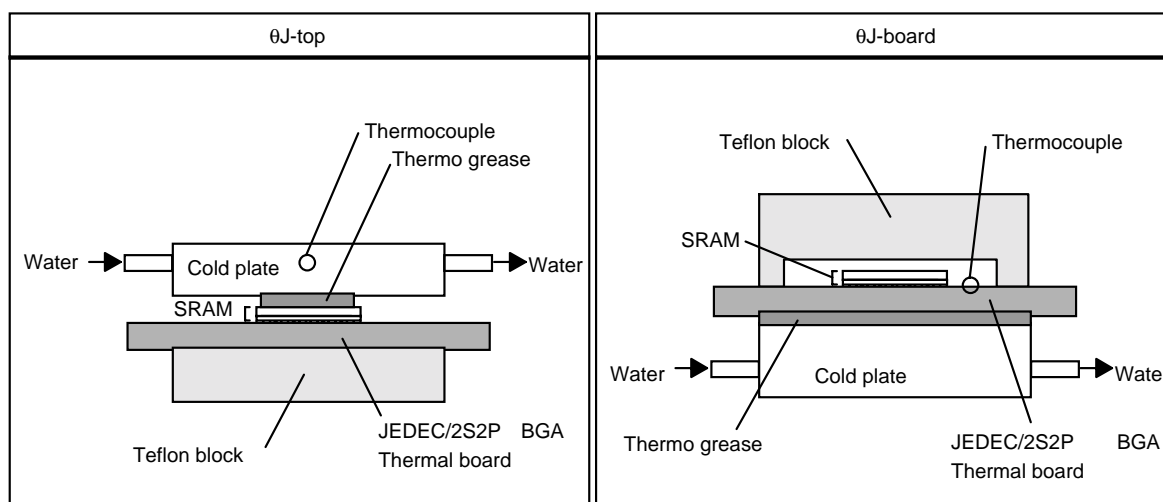
Output buffer impedance can be programmed by terminating the ZQ pin to V_{SS} through a precision resistor (R_Q). The value of R_Q is five times the output impedance desired. The allowable range of R_Q to guarantee impedance matching with a tolerance of 15% is 250 Ω typical. If the status of ZQ pin is open, output impedance is maximum value. Maximum impedance also occurs with ZQ connected to V_{DDQ} . The impedance update of the output driver occurs when the SRAM is in high-Z. Write and deselect operations will synchronously switch the SRAM into and out of high-Z, therefore will trigger an update. At power up, the output buffer is in high-Z. It will take 4,096 cycles for the impedance to be completely updated.

Absolute Maximum Ratings

| Parameter | Symbol | Rating | Unit | Notes |
|--|--------------------|-------------------------|------|-------|
| Input voltage on any pin | V_{IN} | -0.5 to $V_{DDQ} + 0.5$ | V | 1, 4 |
| Core supply voltage | V_{DD} | -0.5 to +3.13 | V | 1 |
| Output supply voltage | V_{DDQ} | -0.5 to +2.1 | V | 1, 4 |
| Operating temperature | T_{OPR} | 0 to +85 | °C | |
| Storage temperature | T_{STG} | -55 to +125 | °C | |
| Output short-circuit current | I_{OUT} | 25 | mA | |
| Latch up current | I_{LI} | 200 | mA | |
| Package junction to top thermal resistance | θ_{J-top} | 6.5 | °C/W | 5 |
| Package junction to board thermal resistance | $\theta_{J-board}$ | 12 | °C/W | 5 |

Notes: 1. All voltage is referenced to V_{SS} .

- Permanent device damage may occur if absolute maximum ratings are exceeded. Functional operation should be restricted the operation conditions. Exposure to higher voltages than recommended voltages for extended periods of time could affect device reliability.
- These CMOS memory circuits have been designed to meet the DC and AC specifications shown in the tables after thermal equilibrium has been established.
- The following supply voltage application sequence is recommended: V_{SS} , V_{DD} , V_{DDQ} , V_{REF} then V_{IN} . Remember, according to the absolute maximum ratings table, V_{DDQ} is not to exceed 2.1 V, whatever the instantaneous value of V_{DDQ} .
- See figure below.



Note: The following DC and AC specifications shown in the tables, this device is tested under the minimum transverse air flow exceeding 500 linear feet per minute.

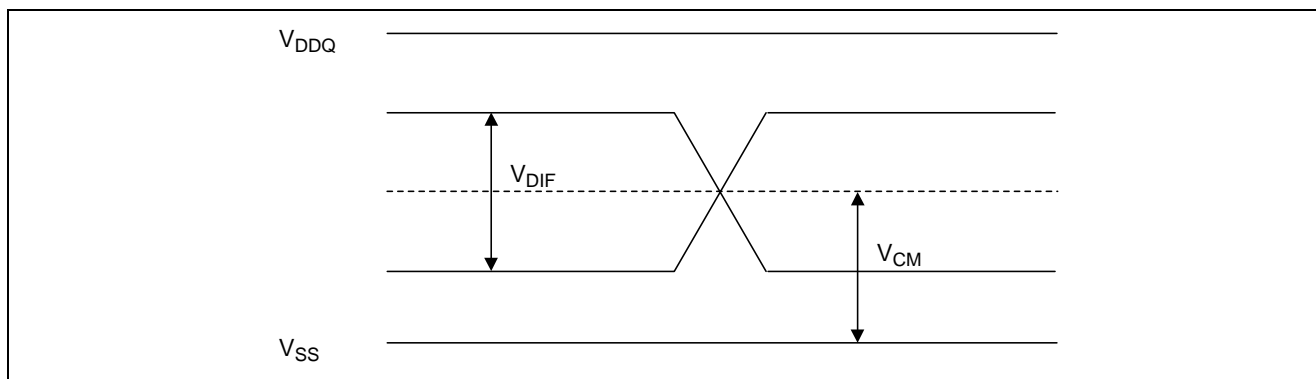
Recommended DC Operating Conditions

(Ta = 0 to +85°C)

| Parameter | Symbol | Min | Typ | Max | Unit | Notes |
|------------------------------|-----------|------------------|------|------------------|------|-------|
| Power supply voltage: core | V_{DD} | 2.38 | 2.50 | 2.63 | V | |
| Power supply voltage: I/O | V_{DDQ} | 1.40 | 1.50 | 1.60 | V | |
| Input reference voltage: I/O | V_{REF} | 0.60 | 0.75 | 0.90 | V | 1 |
| Input high voltage | V_{IH} | $V_{REF} + 0.10$ | — | $V_{DDQ} + 0.30$ | V | 4 |
| Input low voltage | V_{IL} | -0.30 | — | $V_{REF} - 0.10$ | V | 4 |
| Clock differential voltage | V_{DIF} | 0.10 | — | $V_{DDQ} + 0.30$ | V | 2, 3 |
| Clock common mode voltage | V_{CM} | 0.60 | — | 0.90 | V | 3 |

- Notes:
1. Peak to peak AC component superimposed on V_{REF} may not exceed 5% of V_{REF} .
 2. Minimum differential input voltage required for differential input clock operation.
 3. See figure below.
 4. $V_{REF} = 0.75$ V (typ).

Differential Voltage / Common Mode Voltage



DC Characteristics

(Ta = 0 to +85°C, V_{DD} = 2.5 V ± 5%)

| Parameter | Symbol | Min | Max | Unit | Notes |
|---|-------------------|-----|-----|------|-------|
| Input leakage current | I _{LI} | — | 2 | μA | 1 |
| Output leakage current | I _{LO} | — | 5 | μA | 2 |
| Standby current | I _{SBZZ} | — | 150 | mA | 3 |
| V _{DD} operating current, excluding output drivers | I _{DD} | — | 550 | mA | 4 |
| Quiescent active power supply current | I _{DD2} | — | 200 | mA | 5 |
| Maximum power dissipation, including output drivers | P | — | 2.3 | W | 6 |

| Parameter | Symbol | Min | Typ | Max | Unit | Notes |
|---------------------------|-----------------|--|-----|--|------|--------|
| Output low voltage | V _{OL} | V _{SS} | — | V _{SS} + 0.4 | V | 7 |
| Output high voltage | V _{OH} | V _{DDQ} - 0.4 | — | V _{DDQ} | V | 8 |
| ZQ pin connect resistance | RQ | — | 250 | — | Ω | |
| Output "Low" current | I _{OL} | (V _{DDQ} /2) / {(RQ/5) - 15%} | | (V _{DDQ} /2) / {(RQ/5) + 15%} | mA | 9, 11 |
| Output "High" current | I _{OH} | (V _{DDQ} /2) / {(RQ/5) + 15%} | | (V _{DDQ} /2) / {(RQ/5) - 15%} | mA | 10, 11 |

- Notes:
1. $0 \leq V_{IN} \leq V_{DDQ}$ for all input pins (except V_{REF}, ZQ, M1, M2 pin)
 2. $0 \leq V_{OUT} \leq V_{DDQ}$, DQ in high-Z
 3. All inputs (except clock) are held at either V_{IH} or V_{IL}, ZZ is held at V_{IH}, I_{OUT} = 0 mA. Specification is guaranteed at +75°C junction temperature.
 4. I_{OUT} = 0 mA, read 50% / write 50%, V_{DD} = V_{DD} max, frequency = min. cycle
 5. I_{OUT} = 0 mA, read 50% / write 50%, V_{DD} = V_{DD} max, frequency = 3 MHz
 6. Output drives a 12 pF load and switches every cycle. This parameter should be used by the SRAM designer to determine electrical and package requirements for the SRAM device.
 7. RQ = 250 Ω, I_{OL} = 6.8 mA
 8. RQ = 250 Ω, I_{OH} = -6.8 mA
 9. Measured at V_{OL} = 1/2 V_{DDQ}
 10. Measured at V_{OH} = 1/2 V_{DDQ}
 11. The total external capacitance of ZQ pin must be less than 7.5 pF.

AC Characteristics

(Ta = 0 to +85°C, V_{DD} = 2.5 V ± 5%)

Single Differential Clock Register-Register Mode

| Parameter | Symbol | HM64YGB36100BP | | Unit | Notes |
|---|--------------------|----------------|------|------|---------|
| | | -33 | | | |
| | | Min | Max | | |
| CK clock cycle time | t _{KHKH} | 3.3 | — | ns | |
| CK clock high width | t _{KHKL} | 1.3 | — | ns | |
| CK clock low width | t _{KLKH} | 1.3 | — | ns | |
| Address setup time | t _{AVKH} | 0.3 | — | ns | 2 |
| Data setup time | t _{DVKH} | 0.3 | — | ns | 2 |
| Address hold time | t _{KHAX} | 0.6 | — | ns | |
| Data hold time | t _{KHDX} | 0.6 | — | ns | |
| Clock high to output valid | t _{KHQV} | — | 1.6 | ns | 1 |
| Clock high to output hold | t _{KHQX} | 0.65 | — | ns | 1, 6 |
| Clock high to output low-Z (\overline{SS} control) | t _{KHQX2} | 0.65 | — | ns | 1, 4, 6 |
| Clock high to output high-Z | t _{KHQZ} | 0.65 | 2.0 | ns | 1, 3, 6 |
| Output enable low to output low-Z | t _{GLQX} | 0.1 | — | ns | 1, 4, 6 |
| Output enable low to output valid | t _{GLQV} | — | 2.0 | ns | 1, 4 |
| Output enable high to output high-Z | t _{GHQZ} | — | 2.0 | ns | 1, 3 |
| Sleep mode recovery time | t _{ZZR} | 20.0 | — | ns | 5 |
| Sleep mode enable time | t _{ZZE} | — | 15.0 | ns | 1, 3, 5 |

Notes: 1. See figure in "AC Test Conditions".

2. Parameters may be guaranteed by design, i.e., without tester guardband.

3. Transitions are measured ±50 mV of output high impedance from output low impedance.

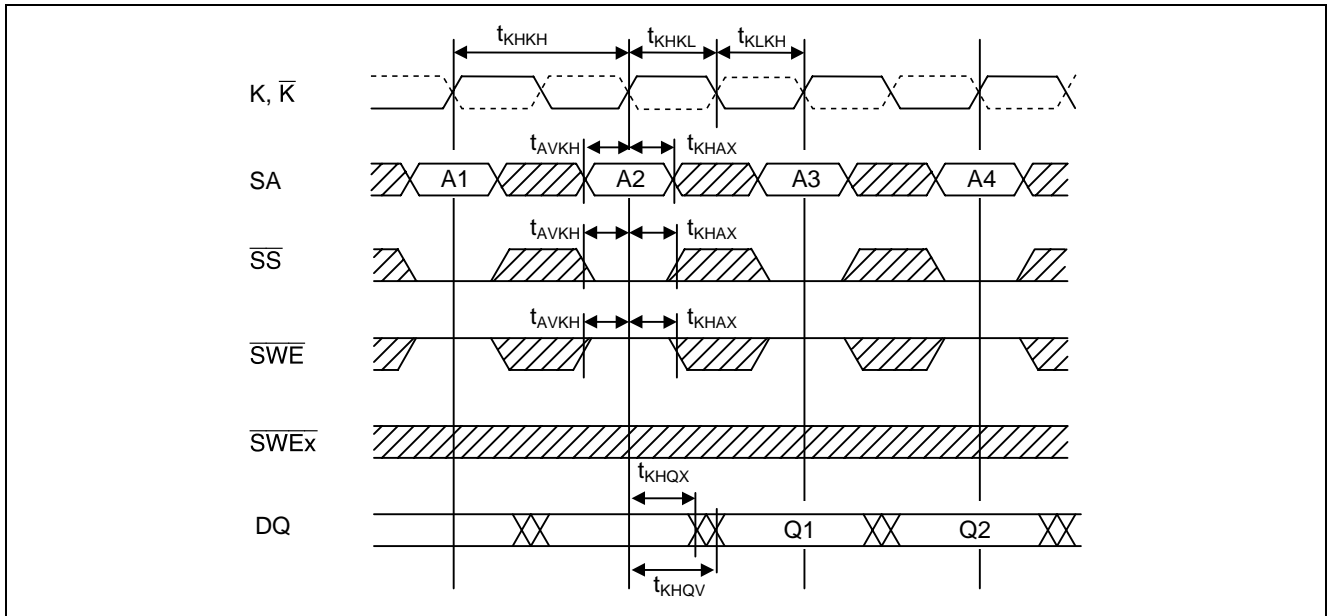
4. Transitions are measured ±50 mV from steady state voltage.

5. When ZZ is switching, clock input K must be at the same logic level for the reliable operation.

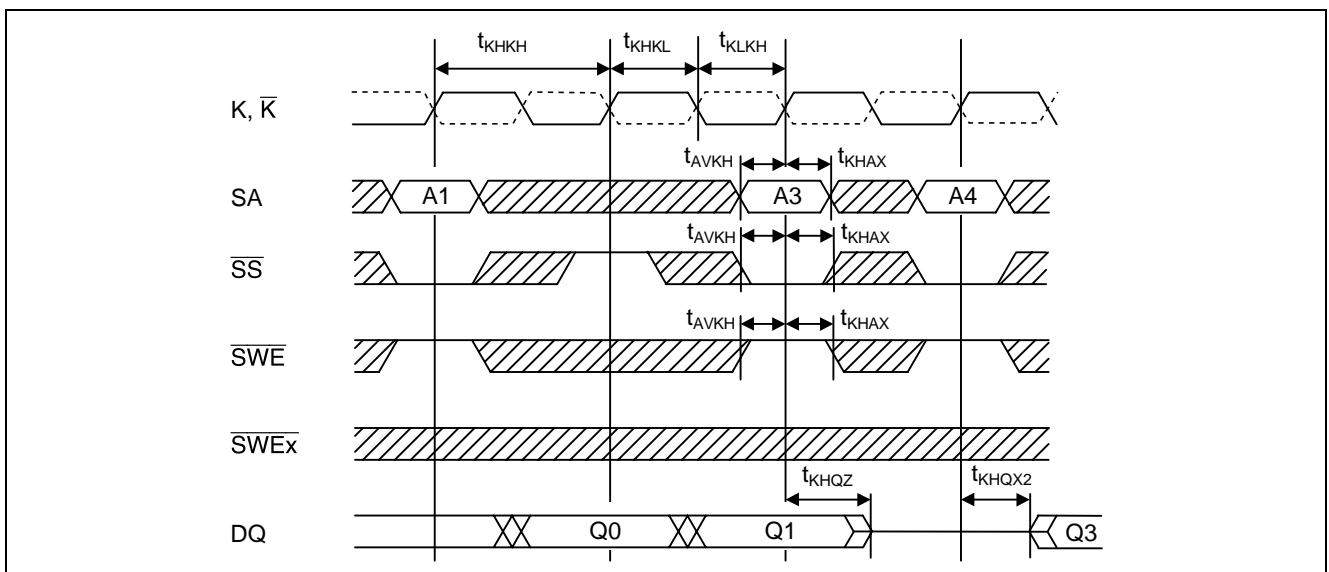
6. Minimum value is verified by design and tested without guardband.

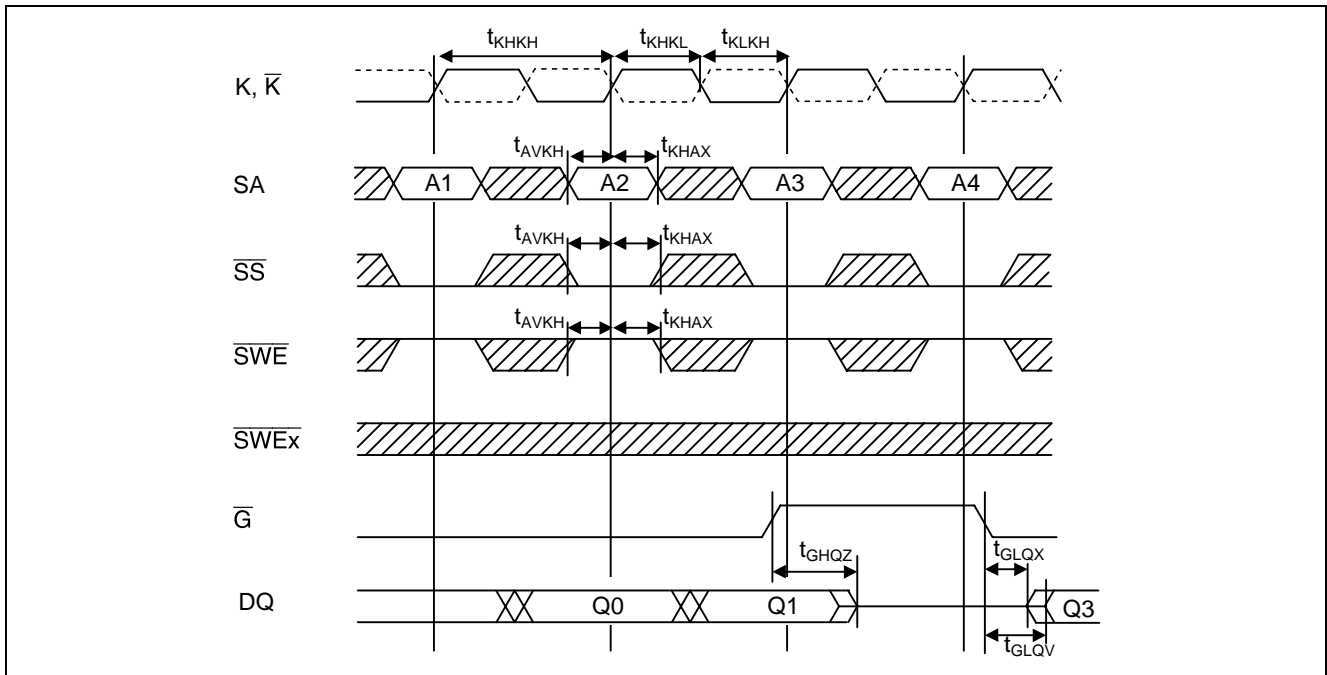
Timing Waveforms

Read Cycle-1



Read Cycle-2 (\bar{SS} Controlled)

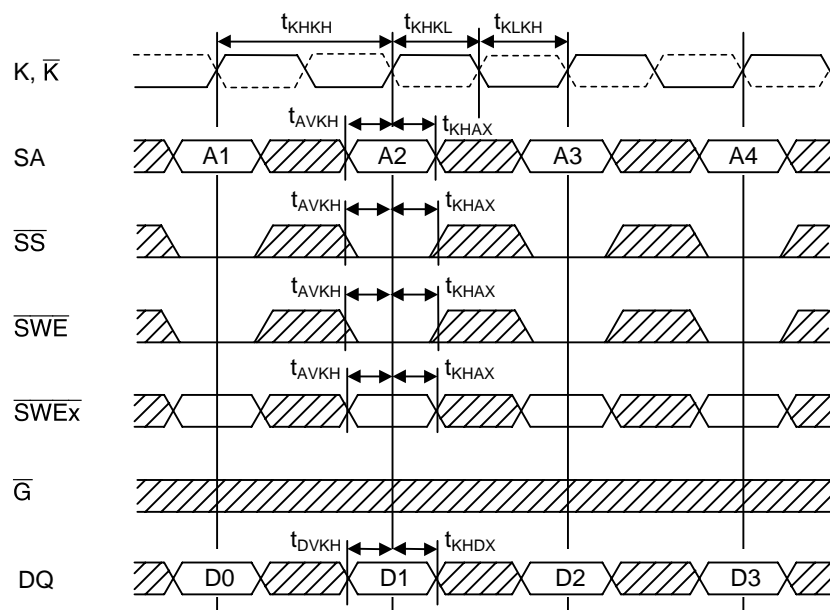


Read Cycle-3 (\overline{G} Controlled)

Read operation

During read cycle, the address is registered during the first rising clock edge, the internal array is read between this first edge and second edge, and data is captured in the output register.

Write Cycle

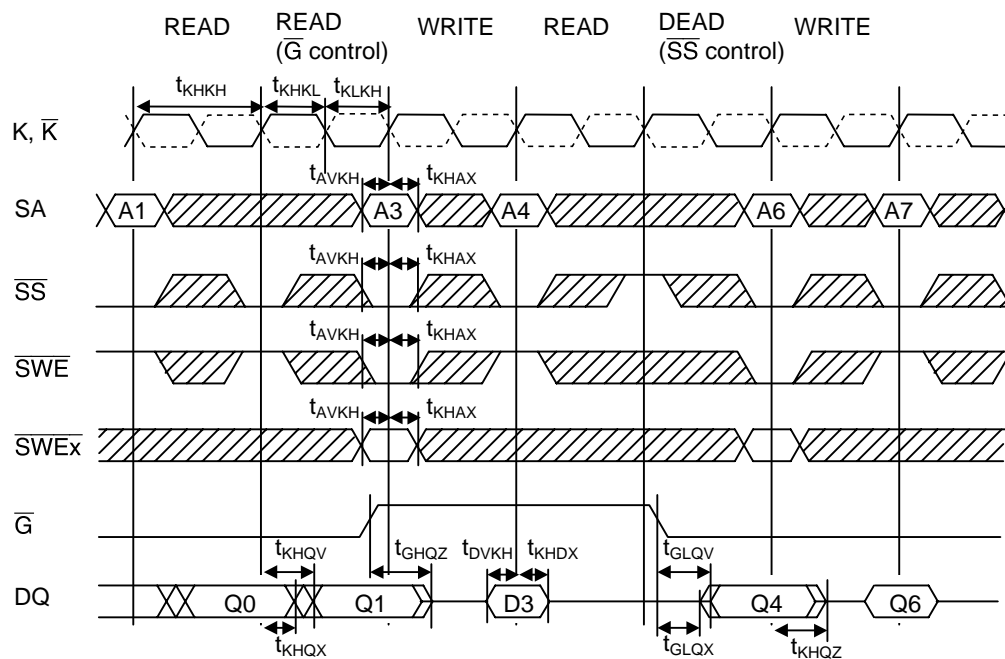


Notes: ZZ = V_{IL} , x: a to d

Write operation

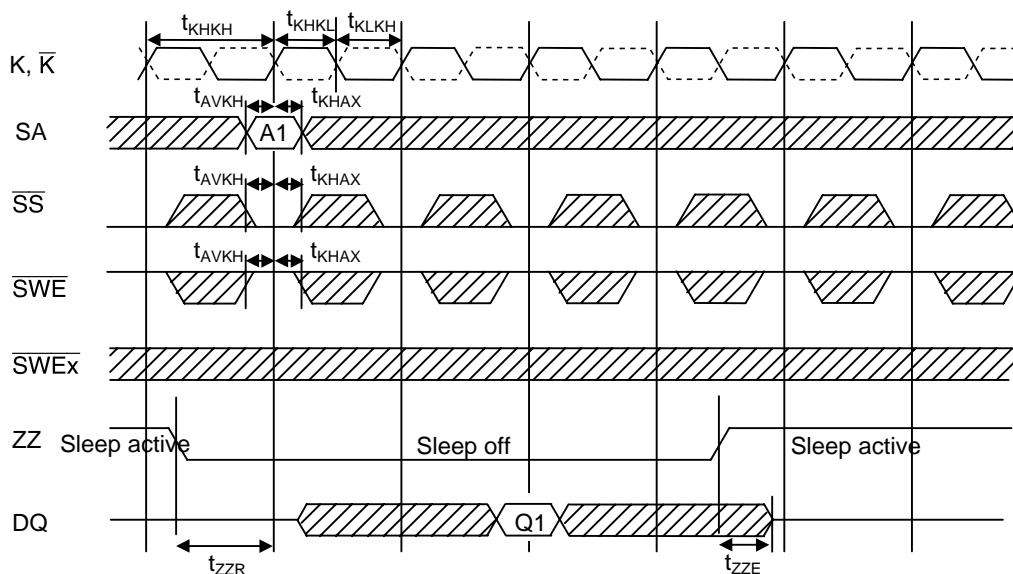
During write cycle, the write data follows the write address by one cycle. All N bits of address are presented during the same cycle. Any subsequent read to this address should get the latest data. Because in the actual implementation the data will be written into the SRAM array only after the next write address is received, a one-entry buffer is needed to hold the write data and to allow bypassing of data from the write buffer to the output if there is a read of the same address.

Read-Write Cycle



Notes: $ZZ = V_{IL}$, x: a to d

ZZ Control



Notes: $\bar{G} = V_{IL}$, x: a to d

When ZZ is switching, clock input K must be at the same logic level for the reliable operation.

Input Capacitance

($V_{DD} = 2.5\text{ V}$, $V_{DDQ} = 1.5\text{ V}$, $T_a = +25^\circ\text{C}$, $f = 1\text{ MHz}$)

| Parameter | Symbol | Min | Max | Unit | Pin name | Notes |
|-------------------------|-----------|-----|-----|------|--|---------|
| Input capacitance | C_{IN} | — | 4 | pF | $\overline{SA_n}$, \overline{SS} , \overline{SWE} , \overline{SWEx} | 1, 3 |
| Clock input capacitance | C_{CLK} | — | 5 | pF | \overline{K} , \overline{K} | 1, 2, 3 |
| I/O capacitance | C_{IO} | — | 5 | pF | \overline{DQxn} | 1, 3 |

Notes: 1. This parameter is sampled and not 100% tested.

2. Exclude \overline{G}

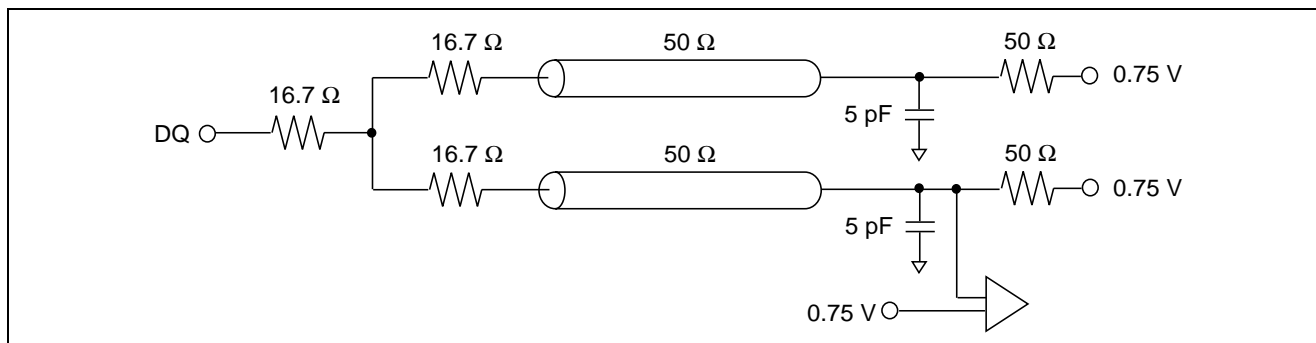
3. Connect pins to GND, except V_{DD} , V_{DDQ} , and the measured pin.

AC Test Conditions

| Parameter | Symbol | Conditions | Unit | Note |
|--|---------------------|--------------------------|------|------|
| Input and output timing reference levels | V_{REF} | 0.75 | V | |
| Input signal amplitude | V_{IL} , V_{IH} | 0.25 to 1.25 | V | |
| Input rise / fall time | t_r , t_f | 0.5 (10% to 90%) | ns | |
| Clock input timing reference level | | Differential cross point | | |
| V_{DIF} to clock | | 0.75 | V | |
| V_{CM} to clock | | 0.75 | V | |
| Output loading conditions | | See figure below | | |

Note: Parameters are tested with $R_Q = 250\ \Omega$ and $V_{DDQ} = 1.5\text{ V}$.

Output Loading Conditions



Boundary Scan Test Access Port Operations

Overview

In order to perform the interconnect testing of the modules that include this SRAM, the serial boundary scan test access port (TAP) is designed to operate in a manner consistent with IEEE Standard 1149.1 - 1990. But does not implement all of the functions required for 1149.1 compliance. The HM64YGB series contains a TAP controller. Instruction register, boundary scans register, bypass register and ID register.

Test Access Port Pins

| Symbol I/O | Name |
|------------|------------------|
| TCK | Test clock |
| TMS | Test mode select |
| TDI | Test data in |
| TDO | Test data out |

Note: This device does not have a TRST (TAP Reset) pin. TRST is optional in IEEE 1149.1.
 To disable the TAP, TCK must be connected to V_{SS} . TDO should be left unconnected.
 To test boundary scan, the ZZ pin needs to be kept below $V_{REF} - 0.4$ V.

TAP DC Operating Characteristics

($T_a = 0$ to $+85^{\circ}\text{C}$)

| Parameter | Symbol | Min | Max | Notes |
|-------------------------------------|----------|-------------------|-------------------|-------|
| Boundary scan input high voltage | V_{IH} | 1.4 V | 3.6 V | |
| Boundary scan input low voltage | V_{IL} | -0.3 V | 0.8 V | |
| Boundary scan input leakage current | I_{LI} | -10 μA | +10 μA | 1 |
| Boundary scan output low voltage | V_{OL} | — | 0.2 V | 2 |
| Boundary scan output high voltage | V_{OH} | 2.1 V | — | 3 |

Notes: 1. $0 \leq V_{IN} \leq 3.6$ V for all logic input pin
 2. $I_{OL} = 2$ mA at $V_{DD} = 2.5$ V.
 3. $I_{OH} = -2$ mA at $V_{DD} = 2.5$ V.

TAP AC Operating Characteristics

(Ta = 0 to +85°C)

| Parameter | Symbol | Min | Max | Unit | Note |
|-----------------------------|-------------------|-----|-----|------|------|
| Test clock cycle time | t _{THTH} | 67 | — | ns | |
| Test clock high pulse width | t _{HTL} | 30 | — | ns | |
| Test clock low pulse width | t _{TLTH} | 30 | — | ns | |
| Test mode select setup | t _{MVTH} | 10 | — | ns | |
| Test mode select hold | t _{HMX} | 10 | — | ns | |
| Capture setup | t _{CS} | 10 | — | ns | 1 |
| Capture hold | t _{CH} | 10 | — | ns | 1 |
| TDI valid to TCK high | t _{DVTH} | 10 | — | ns | |
| TCK high to TDI don't care | t _{THDX} | 10 | — | ns | |
| TCK low to TDO unknown | t _{TLQX} | 0 | — | ns | |
| TCK low to TDO valid | t _{TLQV} | — | 20 | ns | |

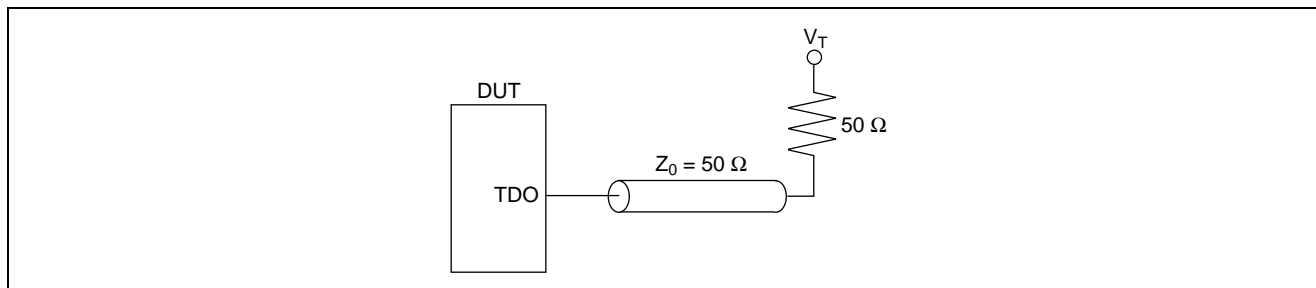
Note: 1. t_{CS} + t_{CH} defines the minimum pause in RAM I/O pad transitions to assure pad data capture.

TAP AC Test Conditions

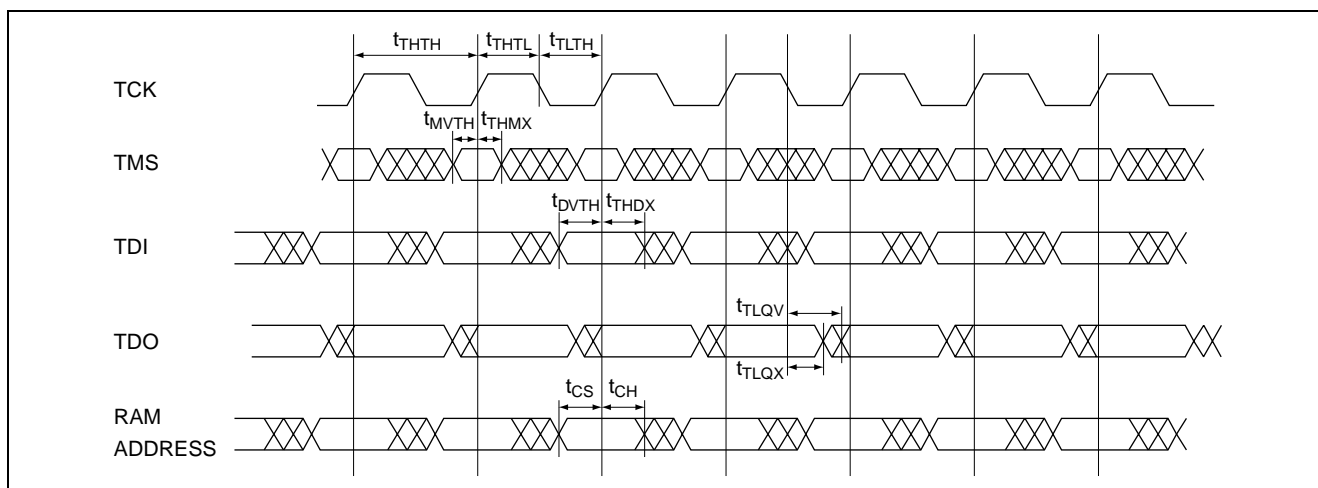
(V_{DD} = 2.5 V)

| | |
|--|-----------------------------|
| Temperature | 0°C ≤ Ta ≤ +85°C |
| Input timing measurement reference level | 1.1 V |
| Input pulse levels | 0 to 2.5 V |
| Input rise/fall time | 1.5 ns typical (10% to 90%) |
| Output timing measurement reference level | 1.25 V |
| Test load termination supply voltage (V _T) | 1.25 V |
| Output load | See figure below |

Boundary Scan AC Test Load



TAP Controller Timing Diagram



Test Access Port Registers

| Register name | Length | Symbol | Note |
|------------------------|---------|-----------|------|
| Instruction register | 3 bits | IR [2:0] | |
| Bypass register | 1 bit | BP | |
| ID register | 32 bits | ID [31:0] | |
| Boundary scan register | 70 bits | BS [70:1] | |

TAP Controller Instruction Set

| IR2 | IR1 | IR0 | Instruction | Operation |
|-----|-----|-----|-------------|---|
| 0 | 0 | 0 | SAMPLE-Z | Tristate all data drivers and capture the pad value |
| 0 | 0 | 1 | IDCODE | |
| 0 | 1 | 0 | SAMPLE-Z | Tristate all data drivers and capture the pad value |
| 0 | 1 | 1 | BYPASS | |
| 1 | 0 | 0 | SAMPLE | |
| 1 | 0 | 1 | BYPASS | |
| 1 | 1 | 0 | PRIVATE | Do not use. They are reserved for vendor use only |
| 1 | 1 | 1 | BYPASS | |

Note: This device does not perform EXTEST, INTEST or the preload portion of the PRELOAD command in IEEE 1149.1.

Boundary Scan Order (HM64YGB36100)

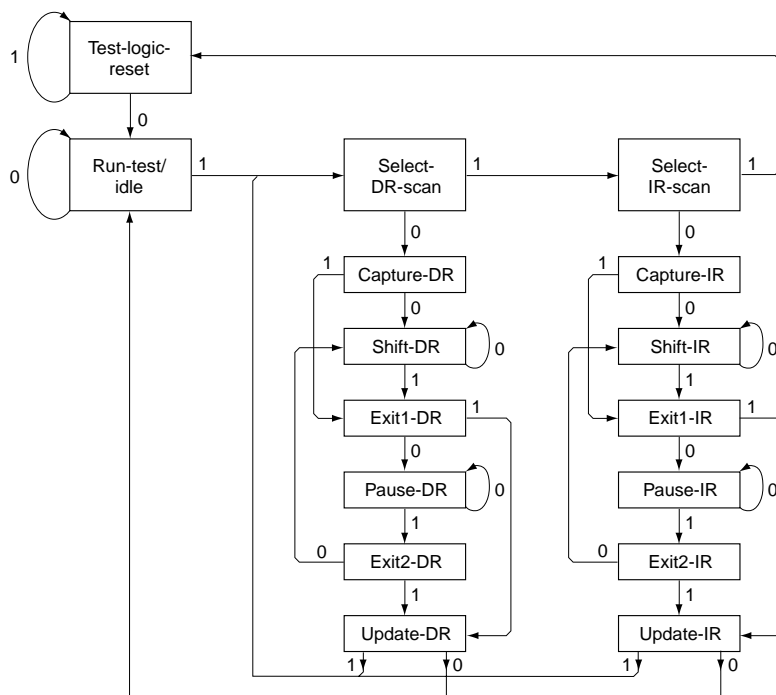
| Bit # | Bump ID | Signal name | Bit # | Bump ID | Signal name |
|-------|---------|--------------------------|-------|---------|--------------------------|
| 1 | 5R | M2 | 36 | 3B | SA12 |
| 2 | 4P | SA19 | 37 | 2B | SA15 |
| 3 | 4T | SA3 | 38 | 3A | SA13 |
| 4 | 6R | SA1 | 39 | 3C | SA11 |
| 5 | 5T | SA2 | 40 | 2C | SA16 |
| 6 | 7T | ZZ | 41 | 2A | SA14 |
| 7 | 6P | DQa8 | 42 | 2D | DQc8 |
| 8 | 7P | DQa7 | 43 | 1D | DQc7 |
| 9 | 6N | DQa6 | 44 | 2E | DQc6 |
| 10 | 7N | DQa5 | 45 | 1E | DQc5 |
| 11 | 6M | DQa4 | 46 | 2F | DQc4 |
| 12 | 6L | DQa2 | 47 | 2G | DQc2 |
| 13 | 7L | DQa3 | 48 | 1G | DQc3 |
| 14 | 6K | DQa0 | 49 | 2H | DQc0 |
| 15 | 7K | DQa1 | 50 | 1H | DQc1 |
| 16 | 5L | $\overline{\text{SWEa}}$ | 51 | 3G | $\overline{\text{SWEc}}$ |
| 17 | 4L | $\overline{\text{K}}$ | 52 | 4D | ZQ |
| 18 | 4K | K | 53 | 4E | SS |
| 19 | 4F | $\overline{\text{G}}$ | 54 | 4B | SA20 |
| 20 | 5G | $\overline{\text{SWEb}}$ | 55 | 4H | NC |
| 21 | 7H | DQb1 | 56 | 4M | $\overline{\text{SWE}}$ |
| 22 | 6H | DQb0 | 57 | 3L | $\overline{\text{SWEd}}$ |
| 23 | 7G | DQb3 | 58 | 1K | DQd1 |
| 24 | 6G | DQb2 | 59 | 2K | DQd0 |
| 25 | 6F | DQb4 | 60 | 1L | DQd3 |
| 26 | 7E | DQb5 | 61 | 2L | DQd2 |
| 27 | 6E | DQb6 | 62 | 2M | DQd4 |
| 28 | 7D | DQb7 | 63 | 1N | DQd5 |
| 29 | 6D | DQb8 | 64 | 2N | DQd6 |
| 30 | 6A | SA7 | 65 | 1P | DQd7 |
| 31 | 6C | SA8 | 66 | 2P | DQd8 |
| 32 | 5C | SA4 | 67 | 3T | SA18 |
| 33 | 5A | SA6 | 68 | 2R | SA10 |
| 34 | 6B | SA9 | 69 | 4N | SA17 |
| 35 | 5B | SA5 | 70 | 3R | M1 |

- Notes:
1. Bit#1 is the first scan bit to exit the chip.
 2. The NC pads listed in this table are indeed no connects, but are represented in the boundary scan register by a "Place Holder". Place holder registers are internally connected to V_{SS} .
 3. In boundary scan mode, differential input K and $\overline{\text{K}}$ are referenced to each other and must be at the opposite logic levels for the reliable operation.
 4. ZZ must remain V_{IL} during boundary scan.
 5. In boundary scan mode, ZQ must be driven to V_{DDQ} or V_{SS} supply rail to ensure consistent results.
 6. M1 and M2 must be driven to V_{DD} , V_{DDQ} or V_{SS} supply rail to ensure consistent results.

ID Register

| Part | Revision number (31:28) | Device density and configuration (27:18) | Vendor definition (17:12) | Vendor JEDEC code (11:1) | Start bit (0) |
|--------------|-------------------------|--|---------------------------|--------------------------|---------------|
| HM64YGB36100 | 0000 | 0100000100 | xxxxxx | 00000000111 | 1 |

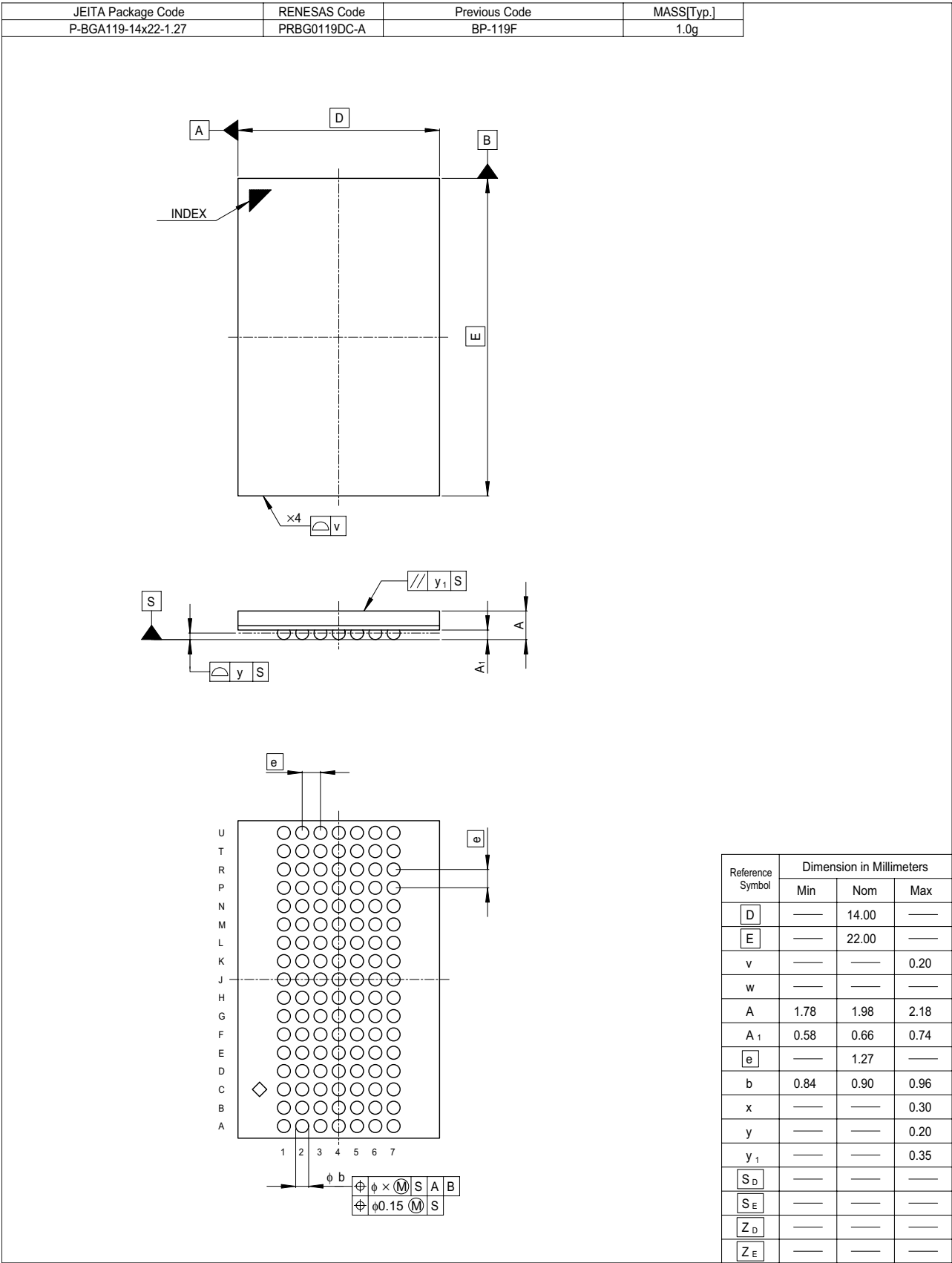
TAP Controller State Diagram



Note: The value adjacent to each state transition in this figure represents the signal present at TMS at the time of a rising edge at TCK.
No matter what the original state of the controller, it will enter Test-logic-reset when TMS is held high for at least five rising edges of TCK.

Package Dimensions

HM64YGB36100BP Series (PRBG0119DC-A / Previous Code: BP-119F)



| | |
|-------------------------|---------------------------------------|
| Revision History | HM64YGB36100 Series Data Sheet |
|-------------------------|---------------------------------------|

| Rev. | Date | Description | |
|------|---------------|-------------|--|
| | | Page | Summary |
| 0.0 | Dec. 5, 2002 | — | Initial issue |
| 1.00 | Jun. 27, 2005 | — | Change format issued by Renesas Technology Corp. |
| | | 1 | Ordering Information |
| | | | Addition of Renesas package codes |
| | | 5 | Change of |
| | | | Programmable Impedance |
| | | | Output Drivers |
| | | 19 | Package Dimensions |
| | | | Addition of Renesas package codes |
| | | | Changed to Renesas formats |

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