## FEATURES

## 8 ADCs integrated into 1 package

93.5 mW ADC power per channel at 50 MSPS

SNR $=\mathbf{7 3 ~ d B}$ (to Nyquist)
Excellent linearity
DNL $= \pm 0.4$ LSB (typical)
INL = $\pm 1.5$ LSB (typical)
Serial LVDS (ANSI-644, default)
Low power reduced signal option, IEEE 1596.3 similar
Data and frame clock outputs
325 MHz , full power analog bandwidth
2 V p-p input voltage range
1.8 V supply operation

## Serial port control

Full-chip and individual-channel power-down modes
Flexible bit orientation
Built-in and custom digital test pattern generation
Programmable clock and data alignment
Programmable output resolution
Standby mode

## APPLICATIONS

Medical imaging and nondestructive ultrasound Portable ultrasound and digital beam forming systems
Quadrature radio receivers
Diversity radio receivers

## Tape drives

Optical networking
Test equipment

## GENERAL DESCRIPTION

The AD9252 is an octal, 14-bit, 50 MSPS analog-to-digital converter (ADC) with an on-chip sample-and-hold circuit that is designed for low cost, low power, small size, and ease of use. The product operates at a conversion rate of up to 50 MSPS and is optimized for outstanding dynamic performance and low power in applications where a small package size is critical.
The ADC requires a single 1.8 V power supply and LVPECL-/ CMOS-/LVDS-compatible sample rate clock for full performance operation. No external reference or driver components are required for many applications.

The ADC automatically multiplies the sample rate clock for the appropriate LVDS serial data rate. A data clock (DCO) for capturing data on the output and a frame clock (FCO) for signaling a new output byte are provided. Individual channel power-down is supported and typically consumes less than 2 mW when all channels are disabled.

## Rev. 0

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The ADC contains several features designed to maximize flexibility and minimize system cost, such as programmable clock and data alignment and programmable digital test pattern generation. The available digital test patterns include built-in deterministic and pseudorandom patterns, along with custom userdefined test patterns entered via the serial port interface (SPI ${ }^{\circ}$ ).

The AD9252 is available in a Pb -free, 64 -lead LFCSP package. It is specified over the industrial temperature range of $-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$.

## PRODUCT HIGHLIGHTS

1. Small Footprint. Eight ADCs are contained in a small, spacesaving package; low power of $93.5 \mathrm{~mW} /$ channel at 50 MSPS.
2. Ease of Use. A data clock output (DCO) operates up to 300 MHz and supports double data rate operation (DDR).
3. User Flexibility. Serial port interface (SPI) control offers a wide range of flexible features to meet specific system requirements.
4. Pin-Compatible Family. This includes the AD9212 (10-bit), and AD9222 (12-bit).
[^0]
## AD9252

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## REVISION HISTORY

10/06—Revision 0: Initial Version

## AD9252

## SPECIFICATIONS

$\mathrm{AVDD}=1.8 \mathrm{~V}, \mathrm{DRVDD}=1.8 \mathrm{~V}, 2 \mathrm{~V}$ p-p differential input, 1.0 V internal reference, $\mathrm{AIN}=-0.5 \mathrm{dBFS}$, unless otherwise noted.
Table 1.


[^1]
## AD9252

## AC SPECIFICATIONS

$\mathrm{AVDD}=1.8 \mathrm{~V}, \mathrm{DRVDD}=1.8 \mathrm{~V}, 2 \mathrm{~V}$ p-p differential input, 1.0 V internal reference, $\mathrm{AIN}=-0.5 \mathrm{dBFS}$, unless otherwise noted.
Table 2.

| Parameter ${ }^{1}$ |  | Temperature | AD9252-50 |  |  | Unit |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  | Min | Typ | Max |  |
| SIGNAL-TO-NOISE RATIO (SNR) | $\mathrm{fin}_{\text {I }}=2.4 \mathrm{MHz}$ | Full | 71 | 73.2 |  | dB |
|  | $\mathrm{fiN}^{\text {}}=19.7 \mathrm{MHz}$ | Full |  | 73 |  | dB |
|  | $\mathrm{fiN}_{\mathrm{i}}=35 \mathrm{MHz}$ | Full |  | 72.7 |  | dB |
|  | $\mathrm{f}_{\mathrm{iN}}=70 \mathrm{MHz}$ | Full |  | 71 |  | dB |
| SIGNAL-TO-NOISE AND DISTORTION RATIO (SINAD) | $\mathrm{fiN}=2.4 \mathrm{MHz}$ | Full | 70.2 | 72.5 |  | dB |
|  | $\mathrm{fiN}^{\mathrm{N}}=19.7 \mathrm{MHz}$ | Full |  | 72.2 |  | dB |
|  | $\mathrm{fiN}_{\text {I }}=35 \mathrm{MHz}$ | Full |  | 72 |  | dB |
|  | $\mathrm{fiN}_{\mathrm{I}}=70 \mathrm{MHz}$ | Full |  | 70.5 |  | dB |
| EFFECTIVE NUMBER OF BITS (ENOB) | $\mathrm{fin}^{\text {= }}$ 2.4 MHz | Full | 11.5 | 11.87 |  | Bits |
|  | $\mathrm{fiN}^{\text {( }}$ = 19.7 MHz | Full |  | 11.84 |  | Bits |
|  | $\mathrm{fiN}_{\text {I }}=35 \mathrm{MHz}$ | Full |  | 11.79 |  | Bits |
|  | $\mathrm{fiN}_{\mathrm{IN}}=70 \mathrm{MHz}$ | Full |  | 11.5 |  | Bits |
| SPURIOUS-FREE DYNAMIC RANGE (SFDR) | $\mathrm{fin}^{\text {}}=2.4 \mathrm{MHz}$ | Full | 73 | 85 |  | dBc |
|  | $\mathrm{fiN}_{\text {I }}=19.7 \mathrm{MHz}$ | Full |  | 84 |  | dBc |
|  | $\mathrm{fiN}^{\prime}=35 \mathrm{MHz}$ | Full |  | 83 |  | dBc |
|  | $\mathrm{fiN}^{\prime}=70 \mathrm{MHz}$ | Full |  | 79 |  | dBc |
| WORST HARMONIC (Second or Third) | $\mathrm{fiN}_{\text {I }}=2.4 \mathrm{MHz}$ | Full |  | -85 | -73 | dBc |
|  | $\mathrm{fiN}^{\text {I }}=19.7 \mathrm{MHz}$ | Full |  | -84 |  | dBc |
|  | $\mathrm{fiN}_{\text {I }}=35 \mathrm{MHz}$ | Full |  | -83 |  | dBc |
|  | $\mathrm{fiN}_{\text {I }}=70 \mathrm{MHz}$ | Full |  | -79 |  | dBc |
| WORST OTHER (Excluding Second or Third) | $\mathrm{fin}^{\text {}}=2.4 \mathrm{MHz}$ | Full |  | -90 | -80 | dBc |
|  | $\mathrm{fin}^{\prime}=19.7 \mathrm{MHz}$ | Full |  | -90 |  | dBc |
|  | $\mathrm{fiN}_{\mathrm{I}}=35 \mathrm{MHz}$ | Full |  | -90 |  | dBc |
|  | $\mathrm{fiN}_{\mathrm{IN}}=70 \mathrm{MHz}$ | Full |  | -89 |  | dBc |
| TWO-TONE INTERMODULATION DISTORTION (IMD)— AIN1 AND AIN2 $=-7.0 \mathrm{dBFS}$ | $\begin{aligned} & \mathrm{f}_{\mathrm{IN} 1}=15 \mathrm{MHz}, \\ & \mathrm{f}_{\mathrm{IN} 2}=16 \mathrm{MHz} \end{aligned}$ |  |  | 80.0 |  |  |
|  | $\begin{aligned} & f_{\mathrm{IN}_{1}=70 \mathrm{MHz},} \mathrm{f}_{\mathrm{IN} 2}=71 \mathrm{MHz} \end{aligned}$ | $25^{\circ} \mathrm{C}$ |  | 80.0 |  | dBc |

[^2]
## DIGITAL SPECIFICATIONS

$\operatorname{AVDD}=1.8 \mathrm{~V}, \mathrm{DRVDD}=1.8 \mathrm{~V}, 2 \mathrm{~V}$ p-p differential input, 1.0 V internal reference, $\mathrm{AIN}=-0.5 \mathrm{dBFS}$, unless otherwise noted.
Table 3.

| Parameter ${ }^{1}$ | Temperature | AD9252-50 |  |  | Unit |
| :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | Min | Typ | Max |  |
| CLOCK INPUTS (CLK+, CLK-) |  |  |  |  |  |
| Logic Compliance |  | CMOS/LVDS/LVPECL |  |  |  |
| Differential Input Voltage ${ }^{2}$ | Full | 250 |  |  | mV p-p |
| Input Common-Mode Voltage | Full |  | 1.2 |  | V |
| Input Resistance (Differential) | $25^{\circ} \mathrm{C}$ |  | 20 |  | $\mathrm{k} \Omega$ |
| Input Capacitance | $25^{\circ} \mathrm{C}$ |  | 1.5 |  | pF |
| LOGIC INPUTS (PDWN, SCLK/DTP) |  |  |  |  |  |
| Logic 1 Voltage | Full | 1.2 | 3.6 |  | V |
| Logic 0 Voltage | Full |  | 0.3 |  | V |
| Input Resistance | $25^{\circ} \mathrm{C}$ |  | 30 |  | $\mathrm{k} \Omega$ |
| Input Capacitance | $25^{\circ} \mathrm{C}$ |  | 0.5 |  | pF |
| LOGIC INPUT (CSB) |  |  |  |  |  |
| Logic 1 Voltage | Full | 1.2 |  | 3.6 | V |
| Logic 0 Voltage | Full |  |  | 0.3 | V |
| Input Resistance | $25^{\circ} \mathrm{C}$ |  | 70 |  | $\mathrm{k} \Omega$ |
| Input Capacitance | $25^{\circ} \mathrm{C}$ |  | 0.5 |  | pF |
| LOGIC INPUT (SDIO/ODM) |  |  |  |  |  |
| Logic 1 Voltage | Full | 1.2 |  | DRVDD + 0.3 | V |
| Logic 0 Voltage | Full | 0 |  | 0.3 | V |
| Input Resistance | $25^{\circ} \mathrm{C}$ | 30 |  |  | $\mathrm{k} \Omega$ |
| Input Capacitance | $25^{\circ} \mathrm{C}$ | 2 |  |  | pF |
| LOGIC OUTPUT (SDIO/ODM) ${ }^{3}$ |  |  |  |  |  |
| Logic 1 Voltage ( $\mathrm{l}_{\text {OH }}=800 \mu \mathrm{~A}$ ) | Full | 1.79 |  |  | V |
| Logic 0 Voltage ( $\mathrm{loL}=50 \mu \mathrm{~A}$ ) | Full |  |  | 0.05 | V |
| DIGITAL OUTPUTS (D+, D-), (ANSI-644) |  |  |  |  | $\begin{aligned} & \mathrm{mV} \\ & \mathrm{~V} \end{aligned}$ |
| Logic Compliance |  |  | LVDS |  |  |
| Differential Output Voltage (Vod) | Full | 247 |  | 454 |  |
| Output Offset Voltage (Vos) | Full | 1.125 |  | 1.375 |  |
| Output Coding (Default) |  | Offset binary |  |  |  |
| DIGITAL OUTPUTS (D+, D-), (Low Power, Reduced Signal Option) |  |  |  |  |  |
| Logic Compliance |  |  | LVDS |  |  |
| Differential Output Voltage (Vod) | Full | 150 |  | 250 | mV |
| Output Offset Voltage (Vos) | Full | 1.10 |  | 1.30 | V |
| Output Coding (Default) |  |  |  | binary |  |

[^3]
## AD9252

## SWITCHING SPECIFICATIONS

AVDD $=1.8 \mathrm{~V}, \mathrm{DRVDD}=1.8 \mathrm{~V}, 2 \mathrm{~V}$ p-p differential input, 1.0 V internal reference, $\mathrm{AIN}=-0.5 \mathrm{dBFS}$, unless otherwise noted.
Table 4.

| Parameter ${ }^{1}$ | Temp | AD9252-50 |  |  | Unit |
| :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | Min | Typ | Max |  |
| CLOCK ${ }^{2}$ |  |  |  |  |  |
| Maximum Clock Rate | Full | 50 |  |  | MSPS |
| Minimum Clock Rate | Full |  |  | 10 | MSPS |
| Clock Pulse Width High (teH) | Full |  | 10.0 |  | ns |
| Clock Pulse Width Low ( $\mathrm{teL}^{\text {L }}$ ) | Full |  | 10.0 |  | ns |
| OUTPUT PARAMETERS ${ }^{2,3}$ |  |  |  |  |  |
| Propagation Delay (tpd) | Full | 1.5 | 2.3 | 3.1 | ns |
| Rise Time ( $\mathrm{t}_{\mathrm{R}}$ ) (20\% to 80\%) | Full |  | 300 |  | ps |
| Fall Time ( $\mathrm{t}_{\mathrm{F}}$ ) (20\% to 80\%) | Full |  | 300 |  | ps |
| FCO Propagation Delay ( $\mathrm{t}_{\text {Fco }}$ ) | Full | 1.5 | 2.3 | 3.1 | ns |
| DCO Propagation Delay (tcpD ${ }^{4}$ | Full |  | $\begin{aligned} & \mathrm{t}_{\text {FCo }}+ \\ & \left(\mathrm{t}_{\text {SAMPLE }}\right. \text { ) } \end{aligned}$ |  | ns |
| DCO to Data Delay (tdate $)^{4}$ | Full | $\left(\mathrm{tsAMPLE}^{\text {/ } 28) ~}-300\right.$ | ( $\mathrm{tsAMPLE}^{\text {/ }}$ /28) | $\left(\mathrm{t}_{\text {SAMPLE }} / 28\right)+300$ | ps |
| DCO to FCO Delay (trRame $)^{4}$ | Full | $\left(\mathrm{t}_{\text {SAMPLE }} / 28\right)-300$ | ( $\mathrm{t}_{\text {SAMPLE }} / 28$ ) | $\left(\mathrm{t}_{\text {SAMPLE }} / 28\right)+300$ | ps |
| Data to Data Skew <br> (tdata-max - tdata-min) | Full |  | $\pm 50$ | $\pm 200$ | ps |
| Wake-Up Time (Standby) | $25^{\circ} \mathrm{C}$ |  | 600 |  | ns |
| Wake-Up Time (Power-Down) | $25^{\circ} \mathrm{C}$ |  | $375$ |  | $\mu \mathrm{s}$ |
| Pipeline Latency | Full |  | 8 |  | CLK cycles |
| APERTURE |  |  |  |  |  |
| Aperture Delay ( $\mathrm{t}_{\mathrm{A}}$ ) | $25^{\circ} \mathrm{C}$ |  | 750 |  | ps |
| Aperture Uncertainty (Jitter) | $25^{\circ} \mathrm{C}$ |  | $<1$ |  | ps rms |
| Out-of-Range Recovery Time | $25^{\circ} \mathrm{C}$ |  | 1 |  | CLK cycles |

[^4]TIMING DIAGRAMS


Figure 2. 14-Bit Data Serial Stream (Default)


Figure 3. 12-Bit Data Serial Stream


Figure 4. 14-Bit Data Serial Stream, LSB First

## ABSOLUTE MAXIMUM RATINGS

Table 5.

| Parameter | With Respect To | Rating |
| :---: | :---: | :---: |
| ELECTRICAL |  |  |
| AVDD | AGND | -0.3 V to +2.0 V |
| DRVDD | DRGND | -0.3 V to +2.0 V |
| AGND | DRGND | -0.3 V to +0.3 V |
| AVDD | DRVDD | -2.0 V to +2.0 V |
| Digital Outputs $\begin{aligned} & \text { (D+, D-, DCO+, } \\ & \text { DCO-, FCO+, FCO-) } \end{aligned}$ | DRGND | -0.3 V to +2.0 V |
| CLK+, CLK- | AGND | -0.3 V to +3.9 V |
| VIN+, VIN- | AGND | -0.3 V to +2.0 V |
| SDIO/ODM | AGND | -0.3 V to +2.0 V |
| PDWN, SCLK/DTP, CSB | AGND | -0.3 V to +3.9 V |
| REFT, REFB, RBIAS | AGND | -0.3 V to +2.0 V |
| VREF, SENSE | AGND | -0.3 V to +2.0 V |
| ENVIRONMENTAL |  |  |
| Operating Temperature Range (Ambient) |  | $-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$ |
| Maximum Junction Temperature |  | $150^{\circ} \mathrm{C}$ |
| Lead Temperature (Soldering, 10 sec ) |  | $300^{\circ} \mathrm{C}$ |
| Storage Temperature Range (Ambient) |  | $-65^{\circ} \mathrm{C}$ to $+150^{\circ} \mathrm{C}$ |

Stresses above those listed under Absolute Maximum Ratings may cause permanent damage to the device. This is a stress rating only; functional operation of the device at these or any other conditions above those indicated in the operational section of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

## THERMAL IMPEDANCE

Table 6.

| Air Flow Velocity (m/s) | $\theta_{\text {JA }}{ }^{1}$ | $\theta_{\text {נв }}$ | $\theta_{\text {Jc }}$ |
| :---: | :---: | :---: | :---: |
| 0.0 | $17.7^{\circ} \mathrm{C} / \mathrm{W}$ |  |  |
| 1.0 | $15.5^{\circ} \mathrm{C} / \mathrm{W}$ | $8.7^{\circ} \mathrm{C} / \mathrm{W}$ | $0.6^{\circ} \mathrm{C} / \mathrm{W}$ |
| 2.5 | $13.9^{\circ} \mathrm{C} / \mathrm{W}$ |  |  |

## ESD CAUTION

|  | ESD (electrostatic discharge) sensitive device. <br> Charged devices and circuit boards can discharge <br> without detection. Although this product features <br> patented or proprietary protection circuitry, damage <br> may occur on devices subjected to high energy ESD. <br> Therefore, proper ESD precautions should be taken to <br> avoid performance degradation or loss of functionality. |
| :--- | :--- |

## PIN CONFIGURATION AND FUNCTION DESCRIPTIONS



Figure 5. 64-Lead LFCSP Top View

Table 7. Pin Function Descriptions

| Pin No. | Mnemonic | Description |
| :---: | :---: | :---: |
| 0 | AGND | Analog Ground (Exposed Paddle) |
| $\begin{aligned} & 1,4,7,8,11, \\ & 12,37,42,45, \\ & 48,51,59,62 \end{aligned}$ | AVDD | 1.8V Analog Supply |
| 13, 36 | DRGND | Digital Output Driver Ground |
| 14,35 | DRVDD | 1.8 V Digital Output Driver Supply |
| 2 | VIN+G | ADC G Analog Input-True |
| 3 | VIN-G | ADC G Analog Input-Complement |
| 5 | VIN-H | ADC H Analog Input-Complement |
| 6 | $\mathrm{VIN}+\mathrm{H}$ | ADC H Analog Input-True |
| 9 | CLK- | Input Clock-Complement |
| 10 | CLK+ | Input Clock-True |
| 15 | D-H | ADC H Digital Output-Complement |
| 16 | D+H | ADC H True Digital Output-True |
| 17 | D-G | ADC G Digital Output-Complement |
| 18 | D+G | ADC G True Digital Output-True |
| 19 | D-F | ADC F Digital Output-Complement |
| 20 | D+F | ADC F True Digital Output-True |
| 21 | D-E | ADC E Digital Output-Complement |
| 22 | D+E | ADC E True Digital Output-True |
| 23 | DCO- | Data Clock Digital Output-Complement |
| 24 | DCO+ | Data Clock Digital Output-True |
| 25 | FCO- | Frame Clock Digital Output-Complement |
| 26 | FCO+ | Frame Clock Digital Output-True |
| 27 | D-D | ADC D Digital Output-Complement |
| 28 | D+D | ADC D True Digital Output-True |
| 29 | D-C | ADC C Digital Output-Complement |
| 30 | D+C | ADC C True Digital Output-True |
| 31 | D-B | ADC B Digital Output-Complement |
| 32 | D+B | ADC B True Digital Output-True |


| Pin No. | Mnemonic | Description |
| :--- | :--- | :--- |
| 33 | D-A | ADC A Digital Output—Complement |
| 34 | D+A | ADC A True Digital Output—True |
| 38 | SCLK/DTP | Serial Clock/Digital Test Pattern |
| 39 | SDIO/ODM | Serial Data Input-Output/Output Driver Mode |
| 40 | CSB | Chip Select Bar |
| 41 | PDWN | Power Down |
| 43 | VIN+A | ADC A Analog Input—True |
| 44 | VIN-A | ADC A Analog Input—Complement |
| 46 | VIN-B | ADC B Analog Input—Complement |
| 47 | VIN+B | ADC B Analog Input—True |
| 49 | VIN+C | ADC C Analog Input—True |
| 50 | VIN-C | ADC C Analog Input—Complement |
| 52 | VIN-D | ADC D Analog Input—Complement |
| 53 | VIN+D | ADC D Analog Input—True |
| 54 | RBIAS | External Resistor to Set the Internal ADC Core Bias Current |
| 55 | SENSE | Reference Mode Selection |
| 56 | VREF | Voltage Reference Input/Output |
| 57 | REFB | Differential Reference (Negative) |
| 58 | REFT | Differential Reference (Positive) |
| 60 | VIN+E | ADC E Analog Input—True |
| 61 | VIN-E | ADC E Analog Input—Complement |
| 63 | VIN-F | ADC F Analog Input—Complement |
| 64 | VIN+F | ADC F Analog Input-True |

## AD9252

## EQUIVALENT CIRCUITS



Figure 6. Equivalent Analog Input Circuit


Figure 9. Equivalent Digital Output Circuit


Figure 10. Equivalent SCLK/DTP or PDWN Input Circuit


Figure 11. Equivalent RBIAS Circuit



Figure 14. Equivalent VREF Circuit


Figure 13. Equivalent SENSE Circuit

## AD9252

## TYPICAL PERFORMANCE CHARACTERISTICS



Figure 15. Single-Tone 32k FFT with $f_{I N}=2.3 \mathrm{MHz}, f_{\text {SAMPLE }}=50 \mathrm{MSPS}$


Figure 16. Single-Tone 32k FFT with $f_{I N}=35 \mathrm{MHz}, f_{\text {SAMPLE }}=50 \mathrm{MSPS}$


Figure 17. Single-Tone 32k FFT with $f_{I N}=70 \mathrm{MHz}, f_{\text {SAMPLE }}=50 \mathrm{MSPS}$


Figure 18. Single-Tone 32k FFT with $f_{I N}=120 \mathrm{MHz}, f_{\text {SAMPLE }}=50 \mathrm{MSPS}$


Figure 19. SNR/SFDR vs. $f_{\text {SAMPLE, }} f_{I N}=10.3 \mathrm{MHz}, f_{S A M P L E}=50 \mathrm{MSPS}$


Figure 20. SNR/SFDR vs. $f_{S A M P L E}, f_{I N}=19.7 \mathrm{MHz}, f_{S A M P L E}=50 \mathrm{MSPS}$


Figure 21. SNR/SFDR vs. Analog Input Level, $f_{I N}=10.3 \mathrm{MHz}, f_{\text {SAMPLE }}=50 \mathrm{MSPS}$


Figure 22. SNR/SFDR vs. Analog Input Level, $f_{I N}=19.7 \mathrm{MHz}, f_{\text {SAMPLE }}=50 \mathrm{MSPS}$


Figure 23. Two-Tone 32k FFT with $f_{I_{1} 1}=15 \mathrm{MHz}$ and $f_{I N 2}=16 \mathrm{MHz}, f_{\text {SAMPLE }}=50 \mathrm{MSPS}$


Figure 24. Two-Tone 32k FFT with $f_{I N 1}=70 \mathrm{MHz}$ and $f_{I N 2}=71 \mathrm{MHz}, f_{\text {SAMPLE }}=50 \mathrm{MSPS}$


Figure 25. SNR/SFDR vs. $f_{I N}, f_{S A M P L E}=50$ MSPS


Figure 26. SINAD/SFDR vs. Temperature, $f_{I N}=19.7 \mathrm{MHz}, f_{S A M P L E}=50 \mathrm{MSPS}$


Figure 27. $I N L, f_{I N}=2.3 \mathrm{MHz}, f_{\text {SAMPLE }}=50 \mathrm{MSPS}$


Figure 28. $D N L, f_{I N}=2.3 \mathrm{MHz}, f_{\text {SAMPLE }}=50 \mathrm{MSPS}$


Figure 29. $C M R$ v vs. Frequency, $f_{S A M P L E}=50$ MSPS


Figure 30. Input-Referred Noise Histogram, $f_{\text {SAMPLE }}=50 \mathrm{MSPS}$


Figure 31. Noise Power Ratio (NPR), $f_{\text {SAMPLE }}=50$ MSPS


Figure 32. Full Power Bandwidth vs. Frequency, $f_{S A M P L E}=50 \mathrm{MSPS}$

## THEORY OF OPERATION

The AD9252 architecture consists of a pipelined ADC that is divided into three sections: a 4-bit first stage followed by eight 1.5-bit stages and a final 3-bit flash. Each stage provides sufficient overlap to correct for flash errors in the preceding stages. The quantized outputs from each stage are combined into a final 14-bit result in the digital correction logic. The pipelined architecture permits the first stage to operate on a new input sample while the remaining stages operate on preceding samples. Sampling occurs on the rising edge of the clock.
Each stage of the pipeline, excluding the last, consists of a low resolution flash ADC connected to a switched-capacitor DAC and interstage residue amplifier (MDAC). The residue amplifier magnifies the difference between the reconstructed DAC output and the flash input for the next stage in the pipeline. One bit of redundancy is used in each stage to facilitate digital correction of flash errors. The last stage simply consists of a flash ADC.
The output staging block aligns the data, carries out the error correction, and passes the data to the output buffers. The data is then serialized and aligned to the frame and output clock.

## ANALOG INPUT CONSIDERATIONS

The analog input to the AD9252 is a differential switched-capacitor circuit designed for processing differential input signals. The input can support a wide common-mode range and maintain excellent performance. An input common-mode voltage of midsupply minimizes signal-dependent errors and provides optimum performance.


Figure 33. Switched-Capacitor Input Circuit
The clock signal alternately switches the input circuit between sample mode and hold mode (see Figure 33). When the input circuit is switched into sample mode, the signal source must be capable of charging the sample capacitors and settling within one-half of a clock cycle. A small resistor in series with each input can help reduce the peak transient current injected from the output stage of the driving source. In addition, low-Q inductors or ferrite beads can be placed on each leg of the input to reduce the high differential capacitance seen at the analog inputs, thus
realizing the maximum bandwidth of the ADC. Such use of low-Q inductors or ferrite beads is required when driving the converter front end at high IF frequencies. Either a shunt capacitor or two single-ended capacitors can be placed on the inputs to provide a matching passive network. This ultimately creates a low-pass filter at the input to limit any unwanted broadband noise. See the AN-742 Application Note, the AN-827 Application Note, and the Analog Dialogue article "Transformer-Coupled Front-End for Wideband A/D Converters" for more information on this subject. In general, the precise values depend on the application.
The analog inputs of the AD9252 are not internally dc-biased. In ac-coupled applications, the user must provide this bias externally. Setting the device so that $V_{C M}=A V D D / 2$ is recommended for optimum performance, but the device can function over a wider range with reasonable performance, as shown in Figure 34 and Figure 35.


Figure 34. SNR/SFDR vs. Common-Mode Voltage, $f_{I N}=2.3 \mathrm{MHz}, f_{\text {SAMPLE }}=50 \mathrm{MSPS}$


Figure 35. SNR/SFDR vs. Common-Mode Voltage,
$f_{\text {IN }}=35 \mathrm{MHz}, f_{\text {SAMPLE }}=50 \mathrm{MSPS}$

## AD9252

For best dynamic performance, the source impedances driving VIN+ and VIN - should be matched such that common-mode settling errors are symmetrical. These errors are reduced by the common-mode rejection of the ADC. An internal reference buffer creates the positive and negative reference voltages, REFT and REFB, respectively, that define the span of the ADC core. The output common mode of the reference buffer is set to midsupply, and the REFT and REFB voltages and span are defined as

$$
\begin{aligned}
& R E F T=1 / 2(A V D D+V R E F) \\
& R E F B=1 / 2(A V D D-V R E F) \\
& S p a n=2 \times(R E F T-R E F B)=2 \times V R E F
\end{aligned}
$$

It can be seen from these equations that the REFT and REFB voltages are symmetrical about the midsupply voltage and, by definition, the input span is twice the value of the VREF voltage.

Maximum SNR performance is always achieved by setting the ADC to the largest span in a differential configuration. In the case of the AD9252, the largest input span available is 2 V p-p.

## Differential Input Configurations

There are several ways in which to drive the AD9252 either actively or passively. In either case, the optimum performance is achieved by driving the analog input differentially. One example is by using the AD8334 differential driver. It provides excellent performance and a flexible interface to the ADC (see Figure 39) for baseband applications. This configuration is common for medical ultrasound systems.

However, the noise performance of most amplifiers is not adequate to achieve the true performance of the AD9252. For applications where SNR is a key parameter, differential transformer coupling is the recommended input configuration. Two examples are shown in Figure 36 and Figure 37.
In any configuration, the value of the shunt capacitor, $C$, is dependent on the input frequency and may need to be reduced or removed.


Figure 36. Differential Transformer-Coupled Configuration for Baseband Applications


Figure 37. Differential Transformer-Coupled Configuration for IF Applications

## Single-Ended Input Configuration

A single-ended input may provide adequate performance in cost-sensitive applications. In this configuration, SFDR and distortion performance degrade due to the large input commonmode swing. If the application requires a single-ended input configuration, ensure that the source impedances on each input are well matched in order to achieve the best possible performance. A full-scale input of 2 V p-p can still be applied to the ADC's VIN+ pin while the VIN- pin is terminated. Figure 38 details a typical single-ended input configuration.


Figure 38. Single-Ended Input Configuration


Figure 39. Differential Input Configuration Using the AD8334

## CLOCK INPUT CONSIDERATIONS

For optimum performance, the AD9252 sample clock inputs (CLK+ and CLK-) should be clocked with a differential signal. This signal is typically ac-coupled into the CLK+ and CLK- pins via a transformer or capacitors. These pins are biased internally and require no additional bias.

Figure 40 shows one preferred method for clocking the AD9252. The low jitter clock source is converted from single-ended to differential using an RF transformer. The back-to-back Schottky diodes across the secondary transformer limit clock excursions into the AD9252 to approximately 0.8 V p-p differential. This helps prevent the large voltage swings of the clock from feeding through to other portions of the AD9252 and preserves the fast rise and fall times of the signal, which are critical to low jitter performance.


Figure 40. Transformer-Coupled Differential Clock
If a low jitter clock is available, another option is to ac-couple a differential PECL signal to the sample clock input pins as shown in Figure 41. The AD9510/AD9511/AD9512/AD9513/AD9514/ AD9515 family of clock drivers offers excellent jitter performance.


Figure 41. Differential PECL Sample Clock


Figure 42. Differential LVDS Sample Clock

In some applications, it is acceptable to drive the sample clock inputs with a single-ended CMOS signal. In such applications, CLK+ should be directly driven from a CMOS gate, and the CLK- pin should be bypassed to ground with a $0.1 \mu \mathrm{~F}$ capacitor in parallel with a $39 \mathrm{k} \Omega$ resistor (see Figure 43). Although the CLK+ input circuit supply is AVDD ( 1.8 V ), this input is designed to withstand input voltages up to 3.3 V , making the selection of the drive logic voltage very flexible.


Figure 43. Single-Ended 1.8 V CMOS Sample Clock


Figure 44. Single-Ended 3.3 V CMOS Sample Clock

## Clock Duty Cycle Considerations

Typical high speed ADCs use both clock edges to generate a variety of internal timing signals. As a result, these ADCs may be sensitive to clock duty cycle. Commonly, a $5 \%$ tolerance is required on the clock duty cycle to maintain dynamic performance characteristics. The AD9252 contains a duty cycle stabilizer (DCS) that retimes the nonsampling edge, providing an internal clock signal with a nominal $50 \%$ duty cycle. This allows a wide range of clock input duty cycles without affecting the performance of the AD9252. When the DCS is on, noise and distortion performance are nearly flat for a wide range of duty cycles. However, some applications may require the DCS function to be off. If so, keep in mind that the dynamic range performance can be affected when operated in this mode. See the Memory Map section for more details on using this feature.

The duty cycle stabilizer uses a delay-locked loop (DLL) to create the nonsampling edge. As a result, any changes to the sampling frequency require approximately eight clock cycles to allow the DLL to acquire and lock to the new rate.

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## Clock Jitter Considerations

High speed, high resolution ADCs are sensitive to the quality of the clock input. The degradation in SNR at a given input frequency $\left(\mathrm{f}_{\mathrm{A}}\right)$ due only to aperture jitter $\left(\mathrm{t}_{\mathrm{J}}\right)$ can be calculated by

$$
\text { SNR degradation }=20 \times \log 10\left[1 / 2 \times \pi \times f_{A} \times t_{]}\right]
$$

In this equation, the rms aperture jitter represents the root mean square of all jitter sources, including the clock input, analog input signal, and ADC aperture jitter specifications. IF undersampling applications are particularly sensitive to jitter (see Figure 45).
The clock input should be treated as an analog signal in cases where aperture jitter may affect the dynamic range of the AD9252. Power supplies for clock drivers should be separated from the ADC output driver supplies to avoid modulating the clock signal with digital noise. Low jitter, crystal-controlled oscillators make the best clock sources. If the clock is generated from another type of source (by gating, dividing, or other methods), it should be retimed by the original clock at the last step.

Refer to the AN-501 Application Note and the AN-756 Application Note for more in-depth information about jitter performance as it relates to ADCs (visit www.analog.com).


Figure 45. Ideal SNR vs. Input Frequency and Jitter

## Power Dissipation and Power-Down Mode

As shown in Figure 46, the power dissipated by the AD9252 is proportional to its sample rate. The digital power dissipation does not vary much because it is determined primarily by the DRVDD supply and bias current of the LVDS output drivers.


Figure 46. Supply Current vs. $f_{\text {SAMPLE }}$ for $f_{I N}=10.3 \mathrm{MHz}, f_{\text {SAMPLE }}=50 \mathrm{MSPS}$

By asserting the PDWN pin high, the AD9252 is placed in power-down mode. In this state, the ADC typically dissipates 11 mW . During power-down, the LVDS output drivers are placed in a high impedance state. The AD9252 returns to normal operating mode when the PDWN pin is pulled low. This pin is both 1.8 V and 3.3 V tolerant.

In power-down mode, low power dissipation is achieved by shutting down the reference, reference buffer, PLL, and biasing networks. The decoupling capacitors on REFT and REFB are discharged when entering power-down mode and must be recharged when returning to normal operation. As a result, the wake-up time is related to the time spent in the power-down mode; shorter cycles result in proportionally shorter wake-up times. With the recommended $0.1 \mu \mathrm{~F}$ and $4.7 \mu \mathrm{~F}$ decoupling capacitors on REFT and REFB, it takes approximately 1 sec to fully discharge the reference buffer decoupling capacitors and $375 \mu$ s to restore full operation.
There are a number of other power-down options available when using the SPI port interface. The user can individually power down each channel or put the entire device into standby mode. This allows the user to keep the internal PLL powered when fast wake-up times ( $\sim 600 \mathrm{~ns}$ ) are required. See the Memory Map section for more details on using these features.

## Digital Outputs and Timing

The AD9252 differential outputs conform to the ANSI-644 LVDS standard on default power-up. This can be changed to a low power, reduced signal option similar to the IEEE 1596.3 standard using the SDIO/ODM pin or via the SPI. This LVDS standard can further reduce the overall power dissipation of the device by approximately 36 mW . See the SDIO/ODM Pin section or Table 15 in the Memory Map section for more information. The LVDS driver current is derived on-chip and sets the output current at each output equal to a nominal 3.5 mA . A $100 \Omega$ differential termination resistor placed at the LVDS receiver inputs results in a nominal 350 mV swing at the receiver.

The AD9252 LVDS outputs facilitate interfacing with LVDS receivers in custom ASICs and FPGAs that have LVDS capability for superior switching performance in noisy environments. Single point-to-point net topologies are recommended with a
$100 \Omega$ termination resistor placed as close to the receiver as possible. No far-end receiver termination and poor differential trace routing may result in timing errors. It is recommended that the trace length is no longer than 24 inches and that the differential output traces are kept close together and at equal lengths. An example of the FCO and data stream with proper trace length and position can be found in Figure 47.


Figure 47. LVDS Output Timing Example in ANSI Mode (Default)
An example of the LVDS output using the ANSI standard (default) data eye and a time interval error (TIE) jitter histogram with trace lengths less than 24 inches on regular FR-4 material is shown in Figure 48 . Figure 49 shows an example of when the trace lengths exceed 24 inches on regular FR-4 material. Notice that the TIE jitter histogram reflects the decrease of the data eye opening as the edge deviates from the ideal position. It is up to the user to determine if the waveforms meet the timing budget of the design when the trace lengths exceed 24 inches. Additional SPI options allow the user to further increase the internal termination (increasing the current) of all eight outputs in order to drive longer trace lengths (see Figure 50). Even though this produces sharper rise and fall times on the data edges and is less prone to bit errors, the power dissipation of the DRVDD supply increases when this option is used. Also notice in Figure 50 that the histogram has improved.
In cases that require increased driver strength to the DCO and FCO outputs because of load mismatch, Register 15 allows the user to increase the drive strength by $2 \times$. To do this, set the appropriate bit in Register 5. Note that this feature cannot be used with Bit 4 and Bit 5 in Register 15. Bit 4 and Bit 5 will take precedence over this feature. See the Memory Map section for more details.



Figure 48. Data Eye for LVDS Outputs in ANSI Mode with Trace Lengths Less than 24 Inches on Standard FR-4



Figure 49. Data Eye for LVDS Outputs in ANSI Mode with Trace Lengths Greater than 24 Inches on Standard FR-4

 Figure 50. Data Eye for LVDS Outputs in ANSI Mode with $100 \Omega$ Termination on and Trace Lengths Greater than 24 Inches on Standard FR-4

The format of the output data is offset binary by default. An example of the output coding format can be found in Table 8. If it is desired to change the output data format to twos complement, see the Memory Map section.

Table 8. Digital Output Coding

| Code | (VIN+) - (VIN-), Input <br> Span $=\mathbf{2}$ V p-p (V) | Digital Output Offset Binary <br> (D13 ... D0) |
| :--- | :--- | :--- |
| 16383 | +1.00 | 11111111111111 |
| 8192 | 0.00 | 10000000000000 |
| 8191 | -0.000122 | 01111111111111 |
| 0 | -1.00 | 00000000000000 |

Data from each ADC is serialized and provided on a separate channel. The data rate for each serial stream is equal to 14 bits times the sample clock rate, with a maximum of 700 Mbps ( 14 bits $\times 50 \mathrm{MSPS}=700 \mathrm{Mbps}$ ). The lowest typical conversion rate is 10 MSPS. However, if lower sample rates are required for a specific application, the PLL can be set up for encode rates lower than 10 MSPS via the SPI. This allows encode rates as low as 5 MSPS. See the Memory Map section to enable this feature.

Two output clocks are provided to assist in capturing data from the AD9252. The DCO is used to clock the output data and is equal to seven times the sampling clock (CLK) rate. Data is clocked out of the AD9252 and must be captured on the rising and falling edges of the DCO that supports double data rate
(DDR) capturing. The frame clock out (FCO) is used to signal the start of a new output byte and is equal to the sampling clock rate. See the timing diagram shown in Figure 2 for more information.

Table 9. Flex Output Test Modes

| Output Test <br> Mode Bit <br> Sequence | Pattern Name | Digital Output Word 1 | Digital Output Word 2 | Subject to Data Format Select |
| :---: | :---: | :---: | :---: | :---: |
| 0000 | Off (default) | N/A | N/A | N/A |
| 0001 | Midscale short | $\begin{aligned} & 10000000 \text { (8-bit) } \\ & 1000000000 \text { (10-bit) } \\ & 100000000000 \text { (12-bit) } \\ & 10000000000000 \text { (14-bit) } \end{aligned}$ | Same | Yes |
| 0010 | +Full-scale short | 11111111 (8-bit) <br> 1111111111 (10-bit) <br> 111111111111 (12-bit) <br> 11111111111111 (14-bit) | Same | Yes |
| 0011 | -Full-scale short | $\begin{aligned} & 00000000 \text { (8-bit) } \\ & 0000000000 \text { (10-bit) } \\ & 000000000000 \text { (12-bit) } \\ & 00000000000000 \text { (14-bit) } \end{aligned}$ | Same | Yes |
| 0100 | Checker board | $\begin{aligned} & 10101010 \text { (8-bit) } \\ & 1010101010 \text { (10-bit) } \\ & 101010101010 \text { (12-bit) } \\ & 10101010101010 \text { (14-bit) } \end{aligned}$ | 01010101 (8-bit) <br> 0101010101 (10-bit) <br> 010101010101 (12-bit) <br> 01010101010101 (14-bit) | No |
| 0101 | PN sequence long ${ }^{1}$ | N/A | N/A | Yes |
| 0110 | PN sequence short ${ }^{1}$ | N/A | N/A | Yes |
| 0111 | One/zero word toggle | $\begin{aligned} & 11111111 \text { (8-bit) } \\ & 1111111111 \text { (10-bit) } \\ & 111111111111 \text { (12-bit) } \\ & 11111111111111 \text { (14-bit) } \end{aligned}$ | $\begin{aligned} & 00000000 \text { (8-bit) } \\ & 0000000000 \text { (10-bit) } \\ & 000000000000 \text { (12-bit) } \\ & 00000000000000 \text { (14-bit) } \end{aligned}$ | No |
| 1000 | User input | Register 0x19 to Register 0x1A | Register 0x1B to Register 0x1C | No |
| 1001 | One/zero bit toggle | $\begin{aligned} & 10101010 \text { (8-bit) } \\ & 1010101010 \text { (10-bit) } \\ & 101010101010 \text { (12-bit) } \\ & 10101010101010 \text { (14-bit) } \end{aligned}$ | N/A | No |
| 1010 | $1 \times$ sync | $\begin{aligned} & 00001111 \text { (8-bit) } \\ & 0000011111 \text { (10-bit) } \\ & 000000111111 \text { (12-bit) } \\ & 00000001111111 \text { (14-bit) } \end{aligned}$ | N/A | No |
| 1011 | One bit high | $\begin{aligned} & 10000000 \text { (8-bit) } \\ & 1000000000 \text { (10-bit) } \\ & 100000000000 \text { (12-bit) } \\ & 10000000000000 \text { (14-bit) } \end{aligned}$ | N/A | No |
| 1100 | Mixed frequency | $\begin{aligned} & 10100011 \text { (8-bit) } \\ & 1001100011 \text { (10-bit) } \\ & 101000110011 \text { (12-bit) } \\ & 10100001100111 \text { (14-bit) } \end{aligned}$ | N/A | No |

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When using the serial port interface (SPI), the DCO phase can be adjusted in $60^{\circ}$ increments relative to the data edge. This enables the user to refine system timing margins if required. The default DCO timing, as shown in Figure 2, is $90^{\circ}$ relative to the output data edge.

An 8-, 10-, and 12-bit serial stream can also be initiated from the SPI. This allows the user to implement and test compatibility to lower resolution systems. When changing the resolution to an $8-, 10-$, or 12 -bit serial stream, the data stream is shortened. See Figure 3 for a 12-bit example.
When using the SPI, all of the data outputs can also be inverted from their nominal state. This is not to be confused with inverting the serial stream to an LSB-first mode. In default mode, as shown in Figure 2, the MSB is represented first in the data output serial stream. However, this can be inverted so that the LSB is represented first in the data output serial stream (see Figure 4).

There are 12 digital output test pattern options available that can be initiated through the SPI. This is a useful feature when validating receiver capture and timing. Refer to Table 9 for the output bit sequencing options available. Some test patterns have two serial sequential words and can be alternated in various ways, depending on the test pattern chosen. It should be noted that some patterns may not adhere to the data format select option. In addition, customer user patterns can be assigned in the $0 \mathrm{x} 19,0 \mathrm{x} 1 \mathrm{~A}, 0 \mathrm{x} 1 \mathrm{~B}$, and 0 x 1 C register addresses. All test mode options can support 8 - to 14 -bit word lengths in order to verify data capture to the receiver.

Please consult the Memory Map section for information on how to change these additional digital output timing features through the serial port interface or SPI.

## SDIO/ODM Pin

For applications that do not require SPI mode operation, the SDIO/ODM pin can enable a low power, reduced signal option similar to the IEEE 1596.3 reduced range link output standard if this pin and the CSB pin are tied to AVDD during device powerup. This option should only be used when the digital output trace lengths are less than 2 inches from the LVDS receiver. The FCO, DCO, and outputs function normally, but the LVDS signal swing of all channels is reduced from 350 mV p-p to 200 mV p-p. This output mode allows the user to further lower the power on the DRVDD supply. For applications where this pin is not used, it should be tied low. In this case, the device pin can be left open, and the $30 \mathrm{k} \Omega$ internal pull-down resistor pulls this pin low. This pin is only 1.8 V tolerant. If applications require this pin to be driven from a 3.3 V logic level, insert a $1 \mathrm{k} \Omega$ resistor in series with this pin to limit the current.

Table 10. Output Driver Mode Pin Settings

| Selected ODM | ODM Voltage | Resulting <br> Output Standard | Resulting <br> FCO and DCO |
| :--- | :--- | :--- | :--- |
| Normal <br> Operation | $10 \mathrm{k} \Omega$ to AGND | ANSI-644 <br> (default) | ANSI-644 <br> (default) |
| ODM | AVDD | Low power, <br> reduced signal <br> option | Low power, <br> reduced <br> signal <br> option |

## SCLK/DTP Pin

For applications that do not require SPI mode operation, the serial clock/digital test pattern (SCLK/DTP) pin can enable a single digital test pattern if this pin and the CSB pin are held high during device power-up. When the DTP is tied to AVDD, all the ADC channel outputs shift out the following pattern: 1000000000 0000. The FCO and DCO outputs still work as usual while all channels shift out the repeatable test pattern. This pattern allows the user to perform timing alignment adjustments among the FCO, DCO, and output data. For normal operation, this pin should be tied to AGND through a $10 \mathrm{k} \Omega$ resistor. This pin is both 1.8 V and 3.3 V tolerant.

Table 11. Digital Test Pattern Pin Settings

| Selected DTP | DTP Voltage | Resulting <br> D+ and D- | Resulting <br> FCO and DCO |
| :--- | :--- | :--- | :--- |
| Normal | $10 \mathrm{k} \Omega$ to AGND | Normal <br> operation <br> Operation | 1000000000 <br> DTP |
|  | AVDD | 0000 | Normal operation |
|  |  |  |  |

Additional and custom test patterns can also be observed when commanded from the SPI port. Consult the Memory Map section to choose from the different options available.

## CSB Pin

The chip select bar (CSB) pin should be tied to AVDD for applications that do not require SPI mode operation. By tying CSB high, all SCLK and SDIO information is ignored. This pin is both 1.8 V and 3.3 V tolerant.

## RBIAS Pin

To set the internal core bias current of the ADC, place a resistor (nominally equal to $10.0 \mathrm{k} \Omega$ ) to ground at the RBIAS pin. The resistor current is derived on-chip and sets the ADC's AVDD current to a nominal 360 mA at 50 MSPS. Therefore, it is imperative that at least a $1 \%$ tolerance on this resistor be used to achieve consistent performance. If SFDR performance is not as critical as power, simply adjust the ADC core current to achieve a lower power. Figure 51 and Figure 52 show the relationship between the dynamic range and power as the RBIAS resistance is changed. Nominally, a $10.0 \mathrm{k} \Omega$ value is used, as indicated by the dashed line.


Figure 51. SNR/SFDR vs. RBIAS


Figure 52. IAVDD vs. RBIAS

## Voltage Reference

A stable and accurate 0.5 V voltage reference is built into the AD9252. This is gained up by a factor of 2 internally, setting $\mathrm{V}_{\text {ReF }}$ to 1.0 V , which results in a full-scale differential input span of 2 V p-p. The $\mathrm{V}_{\text {ref }}$ is set internally by default; however, the VREF pin can be driven externally with a 1.0 V reference to achieve more accuracy.
When applying the decoupling capacitors to the VREF, REFT, and REFB pins, use ceramic low ESR capacitors. These capacitors should be close to the ADC pins and on the same layer of the PCB as the AD9252. The recommended capacitor values and configurations for the AD9252 reference pin can be found in Figure 53.

Table 12. Reference Settings

| Selected <br> Mode | SENSE <br> Voltage | Resulting <br> VREF (V) | Resulting <br> Differential <br> Span (V p-p) |
| :--- | :--- | :--- | :--- |
| External <br> Reference <br> Internal, <br> $2 \mathrm{~V} \mathrm{p-p} \mathrm{FSR}$ AGDD | N/A | $2 \times$ external <br> reference <br> 2.0 |  |

## Internal Reference Operation

A comparator within the AD9252 detects the potential at the SENSE pin and configures the reference. If SENSE is grounded, the reference amplifier switch is connected to the internal resistor divider (see Figure 53), setting VREF to 1 V .

The REFT and REFB pins establish their input span of the ADC core from the reference configuration. The analog input fullscale range of the ADC equals twice the voltage at the reference pin for either an internal or an external reference configuration.

If the reference of the AD9252 is used to drive multiple converters to improve gain matching, the loading of the reference by the other converters must be considered. Figure 55 depicts how the internal reference voltage is affected by loading.


Figure 53. Internal Reference Configuration


1OPTIONAL.

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## External Reference Operation

The use of an external reference may be necessary to enhance the gain accuracy of the ADC or improve thermal drift characteristics. Figure 56 shows the typical drift characteristics of the internal reference in 1 V mode.

When the SENSE pin is tied to AVDD, the internal reference is disabled, allowing the use of an external reference. The external reference is loaded with an equivalent $6 \mathrm{k} \Omega$ load. An internal reference buffer generates the positive and negative full-scale references, REFT and REFB, for the ADC core. Therefore, the external reference must be limited to a nominal of 1.0 V .



Figure 56. Typical V ${ }_{\text {REF }}$ Drift

## SERIAL PORT INTERFACE (SPI)

The AD9252 serial port interface allows the user to configure the converter for specific functions or operations through a structured register space provided inside the ADC. This gives the user added flexibility and customization depending on the application. Addresses are accessed via the serial port and can be written to or read from via the port. Memory is organized into bytes that can be further divided down into fields, as documented in the Memory Map section. Detailed operational information can be found in the Analog Devices, Inc., user manual Interfacing to High Speed ADCs via SPI.

There are three pins that define the serial port interface, or SPI, to this particular ADC. They are the SCLK, SDIO, and CSB pins. The SCLK (serial clock) is used to synchronize the read and write data presented to the ADC. The SDIO (serial data input/output) is a dual-purpose pin that allows data to be sent to and read from the internal ADC memory map registers. The CSB (chip select bar) is an active low control that enables or disables the read and write cycles (see Table 13).

Table 13. Serial Port Pins

| Pin | Function |
| :--- | :--- |
| SCLK | Serial Clock. The serial shift clock in. SCLK is used to <br> synchronize serial interface reads and writes. <br> SDIO |
| Serial Data Input/Output. A dual-purpose pin. The <br> typical role for this pin is an input or output, depending <br> on the instruction sent and the relative position in the <br> timing frame. <br> Chip Select Bar (Active Low). This control gates the read <br> and write cycles. |  |

The falling edge of the CSB in conjunction with the rising edge of the SCLK determines the start of the framing sequence. During an instruction phase, a 16-bit instruction is transmitted, followed by one or more data bytes, which is determined by Bit Fields W0 and W1. An example of the serial timing and its definitions can be found in Figure 58 and Table 14. In normal operation, CSB is used to signal to the device that SPI commands are to be received and processed. When CSB is brought low, the device processes SCLK and SDIO to process instructions. Normally, CSB remains low until the communication cycle is complete. However, if connected to a slow device, CSB can be brought high between bytes, allowing older microcontrollers enough time to transfer data into shift registers. CSB can be stalled when transferring one, two, or three bytes of data. When W0 and W1 are set to 11 , the device enters streaming mode and continues to process data, either reading or writing, until the CSB is taken high to end the communication cycle. This allows complete memory transfers without having to provide additional instructions. Regardless of the mode, if CSB is taken high in the middle of any byte transfer, the SPI state machine is reset and the device waits for a new instruction.

In addition to the operation modes, the SPI port can be configured to operate in different manners. For applications that do not require a control port, the CSB line can be tied and held high. This places the remainder of the SPI pins in their secondary mode as defined in the Serial Port Interface (SPI) section. CSB can also be tied low to enable 2-wire mode. When CSB is tied low, SCLK and SDIO are the only pins required for communication. Although the device is synchronized during power-up, caution must be exercised when using this mode to ensure that the serial port remains synchronized with the CSB line. When operating in 2 -wire mode, it is recommended to use a 1-, 2-, or 3-byte transfer exclusively. Without an active CSB line, streaming mode can be entered but not exited.

In addition to word length, the instruction phase determines if the serial frame is a read or write operation, allowing the serial port to be used to both program the chip and read the contents of the on-chip memory. If the instruction is a readback operation, performing a readback causes the serial data input/output (SDIO) pin to change direction from an input to an output at the appropriate point in the serial frame.

Data can be sent in MSB- or LSB-first mode. MSB-first mode is the default at power-up and can be changed by adjusting the configuration register. For more information about this and other features, see the user manual Interfacing to High Speed ADCs via SPI.

## HARDWARE INTERFACE

The pins described in Table 13 compose the physical interface between the user's programming device and the serial port of the AD9252. The SCLK and CSB pins function as inputs when using the SPI interface. The SDIO pin is bidirectional, functioning as an input during write phases and as an output during readback.
If multiple SDIO pins share a common connection, care should be taken to ensure that proper $\mathrm{V}_{\mathrm{OH}}$ levels are met. Assuming the same load as the AD9252, Figure 57 shows the number of SDIO pins that can be connected together and the resulting $\mathrm{V}_{\mathrm{OH}}$ level.


Figure 57. SDIO Pin Loading

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This interface is flexible enough to be controlled by either serial PROMS or PIC mirocontrollers. This provides the user an alternative method, other than a full SPI controller, to program the ADC (see the AN-812 Application Note).
If the user chooses not to use the SPI interface, these pins serve a dual function and are associated with secondary functions when the CSB is strapped to AVDD during device power-up. See the Theory of Operation section for details on which pinstrappable functions are supported on the SPI pins.


Table 14. Serial Timing Definitions

| Parameter | Timing (minimum, ns) | Description |
| :---: | :---: | :---: |
| $\mathrm{t}_{\text {DS }}$ | 5 | Set-up time between the data and the rising edge of SCLK |
| toh | 2 | Hold time between the data and the rising edge of SCLK |
| tcık | 40 | Period of the clock |
| ts | 5 | Set-up time between CSB and SCLK |
| $\mathrm{tH}_{\mathrm{H}}$ | 2 | Hold time between CSB and SCLK |
| $\mathrm{tHI}_{\text {I }}$ | 16 | Minimum period that SCLK should be in a logic high state |
| $\mathrm{t}_{\mathrm{o}}$ | 16 | Minimum period that SCLK should be in a logic low state |
| ten_sdoo | 1 | Minimum time for the SDIO pin to switch from an input to an output relative to the SCLK falling edge (not shown in Figure 58) |
| $t_{\text {DII_SDIO }}$ | 5 | Minimum time for the SDIO pin to switch from an output to an input relative to the SCLK rising edge (not shown in Figure 58) |

## MEMORY MAP

## READING THE MEMORY MAP TABLE

Each row in the memory map table has eight address locations. The memory map is roughly divided into three sections: chip configuration register map (Address $0 \times 00$ to Address $0 \times 02$ ), device index and transfer register map (Address 0x05 and Address 0xFF), and program register map (Address 0x08 to Address 0x25).
The left-hand column of the memory map indicates the register address number in hexadecimal. The default value of this address is shown in hexadecimal in the right-hand column. The Bit 7 (MSB) column is the start of the default hexadecimal value given. For example, Hexadecimal Address 0x09, Clock, has a hexadecimal default value of $0 \times 01$. This means Bit $7=0$, Bit $6=0$, Bit $5=0$, Bit $4=0$, Bit $3=0$, Bit $2=0$, Bit $1=0$, and Bit $0=1$, or 00000001 in binary. This setting is the default for the duty cycle stabilizer in the on condition. By writing a 0 to Bit 6 at this address, the duty cycle stabilizer turns off. For more information on this and other functions, consult the user manual Interfacing to High Speed ADCs via SPI.

## RESERVED LOCATIONS

Undefined memory locations should not be written to except when writing the default values suggested in this data sheet. Addresses that have values marked as 0 should be considered reserved and have a 0 written into their registers during power-up.

## DEFAULT VALUES

Coming out of reset, critical registers are preloaded with default values. These values are indicated in Table 15, where an X refers to an undefined feature.

## LOGIC LEVELS

An explanation of various registers follows: "Bit is set" is synonymous with "bit is set to Logic 1" or "writing Logic 1 for the bit." Similarly, "clear a bit" is synonymous with "bit is set to Logic 0" or "writing Logic 0 for the bit."

## AD9252

Table 15. Memory Map Register

| Addr. <br> (Hex) | Parameter Name | $\begin{aligned} & \text { Bit } 7 \\ & \text { (MSB) } \end{aligned}$ | Bit 6 | Bit 5 | Bit 4 | Bit 3 | Bit 2 | Bit 1 | $\begin{aligned} & \text { Bit } 0 \\ & \text { (LSB) } \end{aligned}$ | Default Value (Hex) | Default Notes/ Comments |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Chip Configuration Registers |  |  |  |  |  |  |  |  |  |  |  |
| 00 | chip_port_config | 0 | $\begin{aligned} & \text { LSB first } \\ & 1=\text { on } \\ & 0=\text { off } \\ & \text { (default) } \end{aligned}$ | Soft reset $1=\text { on }$ $0=\text { off }$ <br> (default) | 1 | 1 | Soft reset $1=\text { on }$ $0=\text { off }$ <br> (default) | $\begin{aligned} & \text { LSB first } \\ & 1=\text { on } \\ & 0=\text { off } \\ & \text { (default) } \end{aligned}$ | 0 | 0x18 | The nibbles should be mirrored so that LSB- or MSB-first mode registers correctly regardless of shift mode. |
| 01 | chip_id | 8-bit Chip ID Bits 7:0 (AD9252 = 0x09), (default) |  |  |  |  |  |  |  | Read only | Default is unique chip ID, different for each device. This is a readonly register. |
| 02 | chip_grade | X | Child ID 6:4 (identify device variants of Chip ID) $011=50$ MSPS |  |  | X | X | X | X | Read only | Child ID used to differentiate graded devices. |
| Device Index and Transfer Registers |  |  |  |  |  |  |  |  |  |  |  |
| 04 | device_index_2 | X | X | X | X | Data <br> Channel <br> H <br> 1 = on <br> (default) $0=\text { off }$ | Data <br> Channel <br> G <br> 1 = on <br> (default) $0=\text { off }$ | Data <br> Channel <br> F <br> 1 = on <br> (default) $0=\mathrm{off}$ | Data <br> Channel <br> E <br> 1 = on <br> (default) $0=\text { off }$ | 0x0F | Bits are set to determine which on-chip device receives the next write command. |
| 05 | device_index_1 | X | X | Clock Channel DCO $1=$ on 0 = off (default) | Clock Channel FCO $1=$ on $0=$ off (default) | Data Channel D 1 = on (default) 0 = off | Data <br> Channel <br> C <br> $1=$ on <br> (default) $0=\mathrm{off}$ | Data Channel B 1 = on (default) 0 = off | Data Channel A 1 = on (default) $0=$ off | 0x0F | Bits are set to determine which on-chip device receives the next write command. |
| FF | device_update | X | X | X | X | X | X | X | SW <br> transfer $\begin{aligned} & 1=\text { on } \\ & 0=\text { off } \end{aligned}$ <br> (default) | 0x00 | Synchronously transfers data from the master shift register to the slave. |
| ADC Functions |  |  |  |  |  |  |  |  |  |  |  |
| 08 | modes | X | X | X | X | X | Internal power-down mode 000 = chip run (default) <br> 001 = full power-down <br> $010=$ standby <br> $011=$ reset |  |  | 0x00 | Determines various generic modes of chip operation. |
| 09 | clock | X | X | X | X | X | X | X | Duty cycle stabilizer 1 = on (default) 0 = off | 0x01 | Turns the internal duty cycle stabilizer on and off. |
| 0D | test_io | User test mode $00=$ off (default) <br> $01=$ on, single alternate <br> $10=$ on, single once <br> 11 = on, alternate once |  | Reset PN long gen $\begin{aligned} & 1=\text { on } \\ & 0=\text { off } \end{aligned}$ <br> (default) | Reset <br> PN short gen $1=$ on 0 = off (default) | Output test mode-see Table 9 in the Digital Outputs and Timing section $0000=$ off (default) <br> 0001 = midscale short <br> $0010=+$ FS short <br> $0011=-$ FS short <br> $0100=$ checker board output <br> $0101=$ PN 23 sequence <br> $0110=$ PN 9 <br> 0111 = one/zero word toggle <br> $1000=$ user input <br> $1001=$ one/zero bit toggle <br> $1010=1 \times$ sync <br> $1011=$ one bit high <br> $1100=$ mixed bit frequency <br> (format determined by output_mode) |  |  |  | 0x00 | When set, the test data is placed on the output pins in place of normal data. |


| Addr. <br> (Hex) | Parameter Name | Bit 7 <br> (MSB) | Bit 6 | Bit 5 | Bit 4 | Bit 3 | Bit 2 | Bit 1 | $\begin{aligned} & \text { Bit } 0 \\ & \text { (LSB) } \end{aligned}$ | Default Value (Hex) | Default Notes/ Comments |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 14 | output_mode | X | $0=\operatorname{LVDS}$ <br> ANSI <br> (default) 1 = LVDS low power, (IEEE 1596.3 similar) | X | X | X | Output invert 1 = on $0=$ off (default) | $00=\text { offse }$ <br> (default) <br> $01=$ twos <br> complem | binary | 0x00 | Configures the outputs and the format of the data. |
| 15 | output_adjust | X | X | $\begin{aligned} & \begin{array}{l} \text { Outpu } \\ \text { termir } \end{array} \\ & 00=n \\ & 01=2 \\ & 10=1 \\ & 11=1 \end{aligned}$ | er default) | X | X | X | DCO and FCO <br> $2 \times$ drive strength $1=\mathrm{on}$ $0=\text { off }$ <br> (default) | 0x00 | Determines LVDS or other output properties. Primarily functions to set the LVDS span and common-mode levels in place of an external resistor. |
| 16 | output_phase | X | X | X | X | 0011 = ou <br> (0000 thr <br> (Default: <br> $0000=0^{\circ}$ <br> $0001=60$ <br> $0010=12$ <br> $0011=18$ <br> $0100=24$ <br> $0101=30$ <br> $0110=36$ <br> $0111=42$ <br> $1000=48$ <br> $1001=54$ <br> $1010=60$ <br> 1011 to 1 | put clock p ugh 1010) $80^{\circ}$ relative elative to relative to $0^{\circ}$ relative to $0^{\circ}$ relative t <br> $0^{\circ}$ relative to <br> $0^{\circ}$ relative to <br> $0^{\circ}$ relative t <br> $0^{\circ}$ relative to <br> $0^{\circ}$ relative to <br> $0^{\circ}$ relative to <br> $0^{\circ}$ relative to <br> $11=660^{\circ} \mathrm{r}$ | ase adjust <br> o DATA ed TA edge DATA edge DATA edge DATA edg DATA edg DATA edg DATA edg DATA edge DATA edge DATA edge DATA edge ative to DA | A edge | 0x03 | On devices that utilize global clock divide, determines which phase of the divider output is used to supply the output clock. Internal latching is unaffected. |
| 19 | user_patt1_Isb | B7 | B6 | B5 | B4 | B3 | B2 | B1 | B0 | 0x00 | User-defined pattern, 1 LSB. |
| 1A | user_patt1_msb | B15 | B14 | B13 | B12 | B11 | B10 | B9 | B8 | 0x00 | User-defined pattern, 1 MSB. |
| 1B | user_patt2_Isb | B7 | B6 | B5 | B4 | B3 | B2 | B1 | B0 | 0x00 | User-defined pattern, 2 LSB. |
| 1C | user_patt2_msb | B15 | B14 | B13 | B12 | B11 | B10 | B9 | B8 | 0x00 | User-defined pattern, 2 MSB. |
| 21 | serial_control | $\begin{aligned} & \text { LSB first } \\ & 1=\text { on } \\ & 0=\text { off } \\ & \text { (default) } \end{aligned}$ | X | X | X | $<10$ <br> MSPS, <br> low encode <br> rate <br> mode <br> 1 = on <br> $0=$ off <br> (default) | $000=14$ <br> stream) $\begin{aligned} & 001=8 \mathrm{bi} \\ & 010=10 \\ & 011=12 \\ & 100=14 \end{aligned}$ | s (default, | normal bit | 0x00 | Serial stream control. Default causes MSB first and the native bit stream (global). |
| 22 | serial_ch_stat | X | X | X | X | X | X | Channel output reset $1=\text { on }$ $0=\text { off }$ (default) | Channel powerdown 1 = on 0 = off (default) | 0x00 | Used to power down individual sections of a converter (local). |

## Power and Ground Recommendations

When connecting power to the AD9252, it is recommended that two separate 1.8 V supplies be used: one for analog (AVDD) and one for digital (DRVDD). If only one supply is available, it should be routed to the AVDD first and then tapped off and isolated with a ferrite bead or a filter choke preceded by decoupling capacitors for the DRVDD. The user can employ several different decoupling capacitors to cover both high and low frequencies. These should be located close to the point of entry at the PC board level and close to the parts with minimal trace length.
A single PC board ground plane should be sufficient when using the AD9252. With proper decoupling and smart partitioning of the PC board's analog, digital, and clock sections, optimum performance is easily achieved.

## Exposed Paddle Thermal Heat Slug Recommendations

It is required that the exposed paddle on the underside of the ADC is connected to analog ground (AGND) to achieve the best electrical and thermal performance of the AD9252. An exposed continuous copper plane on the PCB should mate to the AD9252 exposed paddle, Pin 0 . The copper plane should have several vias to achieve the lowest possible resistive thermal path for heat dissipation to flow through the bottom of the PCB. These vias should be solder filled or plugged.
To maximize the coverage and adhesion between the ADC and PCB, partition the continuous copper plane by overlaying a silkscreen on the PCB into several uniform sections. This provides several tie points between the two during the reflow process. Using one continuous plane with no partitions only guarantees one tie point between the ADC and PCB. See Figure 59 for a PCB layout example. For detailed information on packaging and the PCB layout of chip scale packages, see the AN-772 Application Note, A Design and Manufacturing Guide for the Lead Frame Chip Scale Package (LFCSP), at www.analog.com.


Figure 59. Typical PCB Layout

## EVALUATION BOARD

The AD9252 evaluation board provides all of the support circuitry required to operate the ADC in its various modes and configurations. The converter can be driven differentially through a transformer (default) or through the AD8334 driver. The ADC can also be driven in a single-ended fashion. Separate power pins are provided to isolate the DUT from the AD8334 drive circuitry. Each input configuration can be selected by proper connection of various jumpers (see Figure 62 to Figure 66). Figure 60 shows the typical bench characterization setup used to evaluate the ac performance of the AD9252. It is critical that the signal sources used for the analog input and clock have very low phase noise ( $<1 \mathrm{ps} \mathrm{rms} \mathrm{jitter)} \mathrm{to} \mathrm{realize} \mathrm{the} \mathrm{optimum} \mathrm{performance} \mathrm{of} \mathrm{the}$ converter. Proper filtering of the analog input signal to remove harmonics and lower the integrated or broadband noise at the input is also necessary to achieve the specified noise performance.

See Figure 62 to Figure 72 for the complete schematics and layout diagrams that demonstrate the routing and grounding techniques that should be applied at the system level.

## POWER SUPPLIES

This evaluation board comes with a wall-mountable switching power supply that provides a $6 \mathrm{~V}, 2$ A maximum output. Simply connect the supply to the rated 100 V ac to 240 V ac wall outlet at 47 Hz to 63 Hz . The other end is a 2.1 mm inner diameter jack that connects to the PCB at P701. Once on the PC board, the 6 V supply is fused and conditioned before connecting to three low dropout linear regulators that supply the proper bias to each of the various sections on the board.

When operating the evaluation board in a nondefault condition, L701 to L704 can be removed to disconnect the switching power supply. This enables the user to bias each section of the board individually. Use P702 to connect a different supply for each section. At least one 1.8 V supply is needed with a 1 A current
capability for AVDD_DUT and DRVDD_DUT; however, it is recommended that separate supplies be used for both analog and digital. To operate the evaluation board using the VGA option, a separate 5.0 V analog supply is needed. The 5.0 V supply, or AVDD_5 V, should have a 1 A current capability. To operate the evaluation board using the SPI and alternate clock options, a separate 3.3 V analog supply is needed in addition to the other supplies. The 3.3 V supply, or AVDD_3.3 V, should have a 1 A current capability as well.

## INPUT SIGNALS

When connecting the clock and analog source, use clean signal generators with low phase noise, such as Rohde \& Schwarz SMHU or HP8644 signal generators or the equivalent. Use a 1 m , shielded, RG-58, $50 \Omega$ coaxial cable for making connections to the evaluation board. Enter the desired frequency and amplitude from the ADC specifications tables. Typically, most Analog Devices evaluation boards can accept $\sim 2.8 \mathrm{~V}$ p-p or 13 dBm sine wave input for the clock. When connecting the analog input source, it is recommended to use a multipole, narrow-band, band-pass filter with $50 \Omega$ terminations. Analog Devices uses TTE, Allen Avionics, and K\&L types of band-pass filters. The filter should be connected directly to the evaluation board if possible.

## OUTPUT SIGNALS

The default setup uses the HSC-ADC-FPGA high speed deserialization board to deserialize the digital output data and convert it to parallel CMOS. These two channels interface directly with the Analog Devices standard dual-channel FIFO data capture board (HSC-ADC-EVALB-DC). Two of the eight channels can then be evaluated at the same time. For more information on channel settings on these boards and their optional settings, visit www.analog.com/FIFO.


Figure 60. Evaluation Board Connection

## AD9252

## DEFAULT OPERATION AND JUMPER SELECTION SETTINGS

The following is a list of the default and optional settings or modes allowed on the AD9252 Rev. A evaluation board.

- POWER: Connect the switching power supply that is supplied in the evaluation kit between a rated 100 V ac to 240 V ac wall outlet at 47 Hz to 63 Hz and P701.
- AIN: The evaluation board is set up for a transformercoupled analog input with optimum $50 \Omega$ impedance matching out to 150 MHz (see Figure 61). For more bandwidth response, the differential capacitor across the analog inputs can be changed or removed. The common mode of the analog inputs is developed from the center tap of the transformer or AVDD_DUT/2.


Figure 61. Evaluation Board Full Power Bandwidth

- VREF: VREF is set to 1.0 V by tying the SENSE pin to ground, R317. This causes the ADC to operate in 2.0 V p-p full-scale range. A separate external reference option using the ADR510 or ADR520 is also included on the evaluation board. Simply populate R312 and R313 and remove C307. Proper use of the VREF options is noted in the Voltage Reference section.
- RBIAS: RBIAS has a default setting of $10 \mathrm{k} \Omega$ (R301) to ground and is used to set the ADC core bias current. To further lower the core power (excluding the LVDS driver supply), simply change the resistor setting. However, performance of the ADC will degrade depending on the resistor chosen. See RBIAS section for more information.
- CLOCK: The default clock input circuitry is derived from a simple transformer-coupled circuit using a high bandwidth 1:1 impedance ratio transformer (T401) that adds a very low amount of jitter to the clock path. The clock input is
$50 \Omega$ terminated and ac-coupled to handle single-ended sine wave types of inputs. The transformer converts the single-ended input to a differential signal that is clipped before entering the ADC clock inputs.

A differential LVPECL clock can also be used to clock the ADC input using the AD9515 (U401). Simply populate R406 and R407 with $0 \Omega$ resistors and remove R215 and R216 to disconnect the default clock path inputs. In addition, populate C205 and C206 with a $0.1 \mu \mathrm{~F}$ capacitor and remove C409 and C410 to disconnect the default clock path outputs. The AD9515 has many pin-strappable options that are set to a default working condition. Consult the AD9515 data sheet for more information about these and other options.
If using an oscillator, two oscillator footprint options are also available (OSC401) to check the ADC performance. J401 gives the user flexibility in using the enable pin, which is common on most oscillators.

- PDWN: To enable the power-down feature, simply short J301 to the on position (AVDD) on the PDWN pin.
- SCLK/DTP: To enable a digital test pattern on the digital outputs of the ADC, use J304. If J304 is tied to AVDD during device power-up, Test Pattern 10000000000000 will be enabled. See the SCLK/DTP Pin section for details.
- SDIO/ODM: To enable the low power, reduced signal option similar to the IEEE 1595.3 reduced range link LVDS output standard, use J303. If J303 is tied to AVDD during device power-up, it enables the LVDS outputs in a low power, reduced signal option from the default ANSI standard. This option changes the signal swing from 350 mV p-p to 200 mV p-p, which reduces the power of the DRVDD supply. See the SDIO/ODM Pin section for more details.
- CSB: To enable the SPI information on the SDIO and SCLK pins that is to be processed, simply tie J302 low in the always enable mode. To ignore the SDIO and SCLK information, tie J302 to AVDD.
- Non-SPI Mode: For users who wish to operate the DUT without using SPI, simply remove Jumpers J302, J303, and J304. This disconnects the CSB, SCLK/DTP, and SDIO/OMD pins from the control bus, allowing the DUT to operate in its simplest mode. Each of these pins has internal termination and will float to its respective level.
- $\mathrm{D}+, \mathrm{D}-$ : If an alternative data capture method to the setup described in Figure 62 is used, optional receiver terminations, R318, R320 to R328, can be installed next to the high speed backplane connector.


## AD9252

## ALTERNATIVE ANALOG INPUT DRIVE CONFIGURATION

The following is a brief description of the alternative analog input drive configuration using the AD8334 dual VGA. If this particular drive option is in use, some components may need to be populated, in which case all the necessary components are listed in Table 16. For more details on the AD8334 dual VGA, including how it works and its optional pin settings, consult the AD8334 data sheet.
To configure the analog input to drive the VGA instead of the default transformer option, the following components need to be removed and/or changed.

- Remove R102, R115, R128, R141, R202, R218, R234, R252, T101, T102, T103, T104, T201, T202, T203, and T204 in the default analog input path.
- Populate R101, R114, R127, R140, R201, R217, R233, and R251 with $0 \Omega$ resistors in the analog input path.
- Populate R106, R107, R119, R120, R132, R133, R144, R145, R206, R207, R223, R224, R239, R240, R257, and R258 with $10 \mathrm{k} \Omega$ resistors to provide an input common-mode level to the analog input.
- Populate R105, R113, R118, R124, R131, R137, R151, and R160, R205, R213, R221, R222, R239, R240, R255, and R256 with $0 \Omega$ resistors in the analog input path.
Currently, L505 to L520 and L605 to L620 are populated with $0 \Omega$ resistors to allow signal connection. This area allows the user to design a filter if additional requirements are necessary.


Figure 62. Evaluation Board Schematic, DUT Analog Inputs


Figure 63. Evaluation Board Schematic, DUTAnalog Inputs (Continued)


Figure 64. Evaluation Board Schematic, DUT, VREF, and Digital Output Interface


Figure 65. Evaluation Board Schematic, Clock Circuitry


Figure 66. Evaluation Board Schematic, Optional DUT Analog Input Drive


Figure 67. Evaluation Board Schematic, Optional DUT Analog Input Drive (Continued)


Figure 68. Evaluation Board Schematic, Power Supply Inputs and SPI Interface Circuitry


Figure 69. Evaluation Board Layout, Primary Side


Figure 70. Evaluation Board Layout, Ground Plane


Figure 71. Evaluation Board Layout, Power Plane


Figure 72. Evaluation Board Layout, Secondary Side (Mirrored Image)

Table 16. Evaluation Board Bill of Materials (BOM) ${ }^{1}$


## AD9252

| Item | Qty per Board | REFDES | Device | Package | Value | Manufacturer | Manufacturer Part Number |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 8 | 8 | $\begin{aligned} & \text { C503, C514, C520, } \\ & \text { C526, C603, C614, } \\ & \text { C620, C626 } \end{aligned}$ | Capacitor | 402 | $\begin{aligned} & 22 \mathrm{pF}, \text { ceramic, NPO, } \\ & 5 \% \text { tol, } 50 \mathrm{~V} \end{aligned}$ | Murata | GRM1555C1H220JZ01D |
| 9 | 1 | C704 | Capacitor | 1206 | $10 \mu \mathrm{~F}$, tantalum, $16 \mathrm{~V}, 20 \%$ tol | Rohm | TCA1C106M8R |
| 10 | 9 | $\begin{aligned} & \text { C307, C714, C715, } \\ & \text { C716, C717, C719, } \\ & \text { C720, C721, C722 } \end{aligned}$ | Capacitor | 603 | $1 \mu \mathrm{~F}$, ceramic, X5R, 6.3 V, 10\% tol | Murata | GRM188R61C105KA93D |
| 11 | 16 | C540, C541, C544, <br> C545, C548, C549, <br> C552, C553, C640, <br> C641, C644, C645, C648, C649, C652, C653 | Capacitor | 805 | $0.1 \mu \mathrm{~F}$, ceramic, X7R, $50 \mathrm{~V}, 10 \%$ tol | Murata | GRM21BR71H104KA01L |
| 12 | 4 | C705, C707, C709, C711 | Capacitor | 603 | $10 \mu \mathrm{~F}$, ceramic, X5R, $6.3 \mathrm{~V}, 20 \%$ tol | Murata | GRM188R60J106ME47D |
| 13 | 1 | CR401 | Diode | SOT-23 | $30 \mathrm{~V}, 20 \mathrm{~mA}$, dual Schottky | Agilent Technologies | HSMS-2812-TR1G |
| 14 | 2 | CR701, CR702 | LED | 603 | Green, 4V, 5 m candela | Panasonic | LNJ314G8TRA |
| 15 | 1 | D702 | Diode | $\begin{aligned} & \text { DO- } \\ & 214 \mathrm{AB} \end{aligned}$ | $3 \mathrm{~A}, 30 \mathrm{~V}, \mathrm{SMC}$ | Micro Commercial Co. | SK33-TP |
| 16 | 1 | D701 | Diode | $\begin{aligned} & \text { DO- } \\ & 214 \mathrm{AA} \end{aligned}$ | $5 \mathrm{~A}, 50 \mathrm{~V}, \mathrm{SMC}$ | Micro Commercial Co. | S2A-TP |
| 17 | 1 | F701 | Fuse | 1210 | 6.0 V, 2.2 A trip-current resettable fuse | Tyco/Raychem | NANOSMDC110F-2 |
| 18 | 1 | FER701 | Choke coil | 2020 | $10 \mu \mathrm{H}, 5 \mathrm{~A}, 50 \mathrm{~V}, 190 \Omega$ <br> @ 100 MHz | Murata | DLW5BSN191SQ2L |
| 19 | 24 | FB101, FB102, FB103, FB104, FB105, FB106, FB107, FB108, FB109, FB110, FB111, FB112, FB201, FB202, FB203, FB204, FB205, FB206, FB207, FB208, FB209, FB210, FB211, FB212 | Ferrite bead | 603 | $10 \Omega$, test frequency 100 MHz , 25\% tol, 500 mA | Murata | BLM18BA100SN1D |
| 20 | 4 | $\begin{aligned} & \text { JP501, JP502, } \\ & \text { JP601, JP602 } \end{aligned}$ | Connector | 2-pin | 100 mil header jumper, 2-pin | Samtec | TSW-102-07-G-S |
| 21 | 6 | $\begin{aligned} & \text { J301, J302, J303, } \\ & \text { J304, J401, J701 } \end{aligned}$ | Connector | 3-pin | 100 mil header jumper, 3-pin | Samtec | TSW-103-07-G-S |
| 23 | 1 | J702 | Connector | 10-pin | 100 mil header, male, $2 \times 5$ double row straight | Samtec | TSW-105-08-G-D |
| 24 | 8 | L701, L702, L703, L704, L705, L706, L707, L708 | Ferrite bead | 1210 | $\begin{aligned} & 10 \mu \mathrm{H}, \text { bead core } 3.2 \times \\ & 2.5 \times 1.6 \mathrm{SMD}, 2 \mathrm{~A} \end{aligned}$ | Murata | BLM31PG500SN1L |
| 25 | 8 | L501, L502, L503, L504, L601, L602, L603, L604 | Inductor | 402 | 120 nH , test freq $100 \mathrm{MHz}, 5 \%$ tol, 150 mA | Murata | LQG15HNR12J02D |


| Item | Qty per Board | REFDES | Device | Package | Value | Manufacturer | Manufacturer Part Number |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 26 | 32 | L505, L506, L507, L508, L509, L510, L511, L512, L513, L514, L515, L516, L517, L518, L519, L520, L605, L606, L607, L608, L609, L610, L611, L612, L613, L614, L615, L616, L617, L618, L619, L620 | Resistor | 805 | $0 \Omega, 1 / 8 \mathrm{~W}, 5 \%$ tol | NIC <br> Components Corp. | NRC04ZOTRF |
| 27 | 1 | OSC401 | Oscillator | SMT | Clock oscillator, $50.00 \mathrm{MHz}, 3.3 \mathrm{~V}$, $\pm 5 \%$ duty cycle | Valphey Fisher | VFAC3H-L-50MHz |
| 28 | 9 | P101, P103, P105, P107, P201, P203, P205, P207, P401 | Connector | SMA | Side-mount SMA for 0.063" board thickness | Johnson Components | 142-0701-851 |
| 29 | 1 | P301 | Connector | HEADER | 1469169-1, right angle 2-pair, 25 mm , header assembly | Tyco | 6469169-1 |
| 30 | 1 | P701 | Connector | $\begin{aligned} & 0.1 ", \\ & \text { PCMT } \end{aligned}$ | RAPC722, power supply connector | Switchcraft | RAPC722X |
| 31 | 21 | R301, R307, R401, R402, R410, R413, R504, R505, R511, R512, R523, R524, R604, R605, R611, R612, R623, R624, R711, R714, R715 | Resistor | 402 | $\begin{aligned} & 10 \mathrm{k} \Omega, 1 / 16 \mathrm{~W}, \\ & 5 \% \mathrm{tol} \end{aligned}$ | NIC Components Corp. | NRC04J103TRF |
| 32 | 18 | R103, R117, R129, R142, R203, R219, R235, R253, R317, R405, R415, R416, R417, R418, R706, R707, R708, R709 | Resistor | 402 | $\begin{aligned} & 0 \Omega, 1 / 16 \mathrm{~W}, \\ & 5 \% \text { tol } \end{aligned}$ | NIC Components Corp. | NRC04ZOTRF |
| 33 | 8 | R102, R115, R128, R141, R202, R218, R234, R252 | Resistor | 402 | $\begin{aligned} & 64.9 \Omega, 1 / 16 \mathrm{~W}, \\ & 1 \% \mathrm{tol} \end{aligned}$ | NIC <br> Components Corp. | NRC04F64R9TRF |
| 34 | 8 | R104, R116, R130, <br> R143, R204, R220, R236, R254 | Resistor | 603 | $\begin{aligned} & 0 \Omega, 1 / 10 \mathrm{~W}, \\ & 5 \% \text { tol } \end{aligned}$ | NIC Components Corp. | NRC06ZOTRF |
| 35 | 28 | R109, R111, R112, R123, R125, R126, R135, R138, R139, R148, R149, R150, R211, R212, R214, R228, R231, R232, R246, R249, R250, R262, R265, R266, R319, R710, R712, R713 | Resistor | 402 | $\begin{aligned} & 1 \mathrm{k} \Omega, 1 / 16 \mathrm{~W}, \\ & 1 \% \text { tol } \end{aligned}$ | NIC <br> Components Corp. | NRC04F1001TRF |
| 36 | 16 | R108, R110, R121, R122, R134, R136, R146, R147, R209, R210, R226, R227, R242, R245, R260, R261 | Resistor | 402 | $\begin{aligned} & 33 \Omega, 1 / 16 \mathrm{~W}, \\ & 5 \% \mathrm{tol} \end{aligned}$ | NIC <br> Components Corp. | NRC04J330TRF |

## AD9252

| Item | Qty per Board | REFDES | Device | Package | Value | Manufacturer | Manufacturer Part Number |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 37 | 8 | $\begin{aligned} & \text { R161, R162, R163, } \\ & \text { R164, R208, R225, } \\ & \text { R241, R259 } \end{aligned}$ | Resistor | 402 | $\begin{aligned} & 499 \Omega, 1 / 16 \mathrm{~W}, \\ & 1 \% \text { tol } \end{aligned}$ | NIC Components Corp. | NRC04F4990TRF |
| 38 | 3 | R303, R305, R306 | Resistor | 402 | $100 \mathrm{k} \Omega, 1 / 16 \mathrm{~W},$ $1 \%$ tol | NIC Components Corp. | NRC04F1003TRF |
| 39 | 1 | R414 | Resistor | 402 | $\begin{aligned} & 4.12 \mathrm{k} \Omega, 1 / 16 \mathrm{~W}, \\ & 1 \% \text { tol } \end{aligned}$ | NIC Components Corp. | NRC04F4121TRF |
| 40 | 1 | R404 | Resistor | 402 | $49.9 \Omega, 1 / 16 \mathrm{~W}$, $0.5 \%$ tol | Susumu | RR0510R-49R9-D |
| 41 | 1 | R309 | Resistor | 402 | $\begin{aligned} & 4.99 \mathrm{k} \Omega, 1 / 16 \mathrm{~W} \text {, } \\ & 5 \% \text { tol } \end{aligned}$ | NIC Components Corp. | NRC04F4991TRF |
| 42 | 5 | $\begin{aligned} & \text { R310, R501, R535, } \\ & \text { R601, R634 } \end{aligned}$ | Potentiometer | 3-lead | $10 \mathrm{k} \Omega$, Cermet trimmer potentiometer, 18 turn top adjust, 10\%, 1/2 W | $\begin{aligned} & \text { COPAL } \\ & \text { ELECTRONICS } \end{aligned}$ | CT94EW103 |
| 43 | 1 | R308 | Resistor | 402 | $\begin{aligned} & 470 \mathrm{k} \Omega, 1 / 16 \mathrm{~W}, \\ & 5 \% \text { tol } \end{aligned}$ | NIC Components Corp. | NRC04J474TRF |
| 44 | 4 | $\begin{aligned} & \text { R502, R536, R602, } \\ & \text { R635 } \end{aligned}$ | Resistor | 402 | $\begin{aligned} & 39 \mathrm{k} \Omega, 1 / 16 \mathrm{~W}, \\ & 5 \% \mathrm{tol} \end{aligned}$ | NIC Components Corp. | NRC04J393TRF |
| 45 | 16 | R513, R514, R518, R519, R525, R526, R530, R531, R613, R614, R618, R619, R625, R626, R630, R631 | Resistor | 402 | $\begin{aligned} & 187 \Omega, 1 / 16 \mathrm{~W}, \\ & 1 \% \text { tol } \end{aligned}$ | NIC Components Corp. | NRC04F1870TRF |
| 46 | 8 | $\begin{aligned} & \text { R515, R520, R527, } \\ & \text { R532, R615, R620, } \\ & \text { R627, R632 } \end{aligned}$ | Resistor | 402 | $\begin{aligned} & 374 \Omega, 1 / 16 \mathrm{~W}, \\ & 1 \% \text { tol } \end{aligned}$ | NIC Components Corp. | NRC04F3740TRF |
| 47 | 8 | $\begin{aligned} & \text { R503, R507, R508, } \\ & \text { R509, R603, R607, } \\ & \text { R608, R609 } \end{aligned}$ | Resistor | 402 | $\begin{aligned} & 274 \Omega, 1 / 16 \mathrm{~W}, \\ & 1 \% \text { tol } \end{aligned}$ | NIC Components Corp. | NRC04F2740TRF |
| 48 | 11 | $\begin{aligned} & \text { R425, R427, R429, } \\ & \text { R431, R433, R435, } \\ & \text { R436, R439, R441, } \\ & \text { R443, R445 } \end{aligned}$ | Resistor | 201 | $\begin{aligned} & 0 \Omega, 1 / 20 \mathrm{~W}, \\ & 5 \% \text { tol } \end{aligned}$ | NIC Components Corp. | NRC02ZOTRF |
| 49 | 1 | R701 | Resistor | 402 | $\begin{aligned} & 4.7 \mathrm{k} \Omega, 1 / 16 \mathrm{~W}, \\ & 1 \% \text { tol } \end{aligned}$ | NIC Components Corp. | NRC04J472TRF |
| 50 | 1 | R702 | Resistor | 402 | $\begin{aligned} & 261 \Omega, 1 / 16 \mathrm{~W}, \\ & 1 \% \text { tol } \end{aligned}$ | NIC Components Corp. | NRC04F2610TRF |
| 51 | 1 | R716 | Resistor | 603 | $\begin{aligned} & 261 \Omega, 1 / 16 \mathrm{~W}, \\ & 1 \% \text { tol } \end{aligned}$ | NIC Components Corp. | NRC06F261OTRF |
| 52 | 2 | R420, R421 | Resistor | 402 | $\begin{aligned} & 240 \Omega, 1 / 16 \mathrm{~W}, \\ & 5 \% \text { tol } \end{aligned}$ | NIC Components Corp. | NRC04J241TRF |
| 53 | 2 | R422, R423 | Resistor | 402 | $\begin{aligned} & 100 \Omega, 1 / 16 \mathrm{~W}, \\ & 1 \% \text { tol } \end{aligned}$ | NIC Components Corp. | NRC04F1000TRF |
| 54 | 1 | S701 | Switch | SMD | LIGHT TOUCH, 100GE, 5 mm | Panasonic | EVQ-PLDA15 |


| Item | $\begin{array}{\|l\|} \hline \text { Qty } \\ \text { per } \\ \text { Board } \\ \hline \end{array}$ | REFDES | Device | Package | Value | Manufacturer | Manufacturer <br> Part Number |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 55 | 9 | $\begin{aligned} & \hline \text { T101, T102, T103, } \\ & \text { T104, T201, T202, } \\ & \text { T203, T204, T401 } \end{aligned}$ | Transformer | CD542 | ADT1-1WT+, 1:1 impedance ratio transformer | Mini-Circuits | ADT1-1WT+ |
| 56 | 2 | U704, U707 | IC | SOT-223 | ADP33339AKC-1.8-RL, 1.5 A, 1.8 V LDO regulator | Analog Devices | ADP3339AKCZ-1.8-RL |
| 57 | 2 | U501, U601 | IC | CP-64-3 | AD8334ACPZ-REEL, ultralow noise precision dual VGA | Analog Devices | AD8334ACPZ-REEL |
| 58 | 1 | U706 | IC | SOT-223 | ADP33339AKC-5-RL7 | Analog Devices | ADP3339AKCZ-5-RL7 |
| 59 | 1 | U705 | IC | SOT-223 | ADP33339AKC-3.3-RL | Analog Devices | ADP3339AKCZ-3.3-RL |
| 60 | 1 | U301 | IC | CP-64-3 | AD9252BCPZ-50, octal, 14-bit, 50 MSPS serial LVDS 1.8V ADC | Analog Devices | AD9252BCPZ-50 |
| 61 | 1 | U302 | IC | SOT-23 | ADR510ARTZ, 1.0 V , precision low noise shunt voltage reference | Analog Devices | ADR510ARTZ |
| 62 | 1 | U401 | IC | $\begin{aligned} & \text { LFCSP } \\ & \text { CP-32-2 } \end{aligned}$ | AD9515BCPZ, 1.6 GHz clock distribution IC | Analog Devices | AD9515BCPZ |
| 63 | 1 | U702 | IC | SC70, <br> MAA06A | NC7WZ07P6X_NL, UHS dual buffer | Fairchild | NC7WZ07P6X_NL |
| 64 | 1 | U703 | IC | SC70, MAA06A | NC7WZ16P6X_NL, UHS dual buffer | Fairchild | NC7WZ16P6X_NL |
| 65 | 1 | U701 | IC | 8-SOIC | Flash prog mem 1kx14, RAM size $64 \times 8$, 20 MHz speed, PIC12F controller series | Microchip | PIC12F629-I/SNG |

[^6]
## AD9252

## OUTLINE DIMENSIONS



ORDERING GUIDE

| Model | Temperature Range | Package Description | Package Option |
| :--- | :--- | :--- | :--- |
| AD9252BCPZ-50 | $-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$ | 64-Lead Lead Frame Chip Scale Package [LFCSP_VQ] | CP-64-3 |
| AD9252BCPZRL7-50 | $-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$ | 64-Lead Lead Frame Chip Scale Package [LFCSP_VQ] Tape and Reel | CP-64-3 |
| AD9252-50EBZ $^{1}$ |  | Evaluation Board |  |

${ }^{1} \mathrm{Z}=\mathrm{Pb}$-free part.


[^0]:    One Technology Way, P.O. Box 9106, Norwood, MA 02062-9106, U.S.A.
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    www.analog.com
    Fax: 781.461.3113
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[^1]:    ${ }^{1}$ See the AN-835 Application Note, Understanding High Speed ADC Testing and Evaluation, for a complete set of definitions and how these tests were completed.
    ${ }^{2}$ Can be controlled via SPI.
    ${ }^{3}$ Overrange condition is specific with 6 dB of the full-scale input range.

[^2]:    ${ }^{1}$ See the AN-835 Application Note, Understanding High Speed ADC Testing and Evaluation, for a complete set of definitions and how these tests were completed.

[^3]:    ${ }^{1}$ See the AN-835 Application Note, Understanding High Speed ADC Testing and Evaluation, for a complete set of definitions and how these tests were completed.
    ${ }^{2}$ This is specified for LVDS and LVPECL only.
    ${ }^{3}$ This is specified for 13 SDIO pins sharing the same connection.

[^4]:    ${ }^{1}$ See the AN-835 Application Note, Understanding High Speed ADC Testing and Evaluation, for a complete set of definitions and how these tests were completed.
    ${ }^{2}$ Can be adjusted via the SPI interface.
    ${ }^{3}$ Measurements were made using a part soldered to FR4 material.
    ${ }^{4} \mathrm{t}_{\text {SAMPLE }} / 28$ is based on the number of bits divided by 2 because the delays are based on half duty cycles.

[^5]:    ${ }^{1}$ PN, or pseudorandom number, sequence is determined by the number of bits in the shift register. The long sequence is 23 bits and the short sequence is 9 bits. How the sequence is generated and utilized is described in the ITU O .150 standard. In general, the polynomial, X23 $+\mathrm{X} 18+1$ (long) and X9 $+\mathrm{X} 5+1$ (short), defines the pseudorandom sequence.

[^6]:    ${ }^{1}$ This BOM is RoHS compliant.

