

TLV5614

2.7-V TO 5.5-V 12-BIT 3- μ S QUADRUPLE DIGITAL-TO-ANALOG CONVERTERS WITH POWER DOWN

SLAS188 – SEPTEMBER 1998

- Four 12-Bit D/A Converters
- Programmable Settling Time of Either 3 μ s or 9 μ s Typ
- TMS320, (Q)SPI, and Microwire Compatible Serial Interface
- Internal Power-On Reset
- Low Power Consumption:
8 mW, Slow Mode – 5-V Supply
3.6 mW, Slow Mode – 3-V Supply
- Reference Input Buffer
- Voltage Output Range . . . 2 $\times$ the Reference Input Voltage
- Monotonic Over Temperature

- Dual 2.7-V to 5.5-V Supply (Separate Digital and Analog Supplies)
- Hardware Power Down (10 nA)
- Software Power Down (10 nA)
- Simultaneous Update

applications

- Battery Powered Test Instruments
- Digital Offset and Gain Adjustment
- Industrial Process Controls
- Machine and Motion Control Devices
- Communications
- Arbitrary Waveform Generation

description

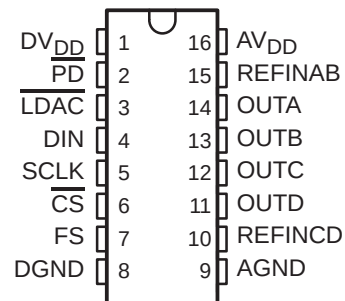
The TLV5614 is a quadruple 12-bit voltage output digital-to-analog converter (DAC) with a flexible 4-wire serial interface. The 4-wire serial interface allows glueless interface to TMS320, SPI, QSPI, and Microwire serial ports. The TLV5614 is programmed with a 16-bit serial word comprised of a DAC address, individual DAC control bits, and a 12-bit DAC value. The device has provision for two supplies: one digital supply for the serial interface (via pins DV_{DD} and DGND), and one for

the DACs, reference buffers, and output buffers (via pins AV_{DD} and AGND). Each supply is independent of the other, and can be any value between 2.7 V and 5.5 V. The dual supplies allow a typical application where the DAC will be controlled via a microprocessor operating on a 3 V supply (also used on pins DV_{DD} and DGND), with the DACs operating on a 5 V supply. Of course, the digital and analog supplies can be tied together.

The resistor string output voltage is buffered by a x2 gain rail-to-rail output buffer. The buffer features a Class AB output stage to improve stability and reduce settling time. A rail-to-rail output stage and a power-down mode makes it ideal for single voltage, battery based applications. The settling time of the DAC is programmable to allow the designer to optimize speed versus power dissipation. The settling time is chosen by the control bits within the 16-bit serial input string. A high-impedance buffer is integrated on the REFINAB and REFINCD terminals to reduce the need for a low source impedance drive to the terminal. REFINAB and REFINCD allow DACs A and B to have a different reference voltage than DACs C and D.

The TLV5614 is implemented with a CMOS process and is available in a 16-terminal SOIC package. The TLV5614C is characterized for operation from 0°C to 70°C. The TLV5614I is characterized for operation from –40°C to 85°C.

D OR PW PACKAGE
(TOP VIEW)



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**TEXAS
INSTRUMENTS**

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TLV5614

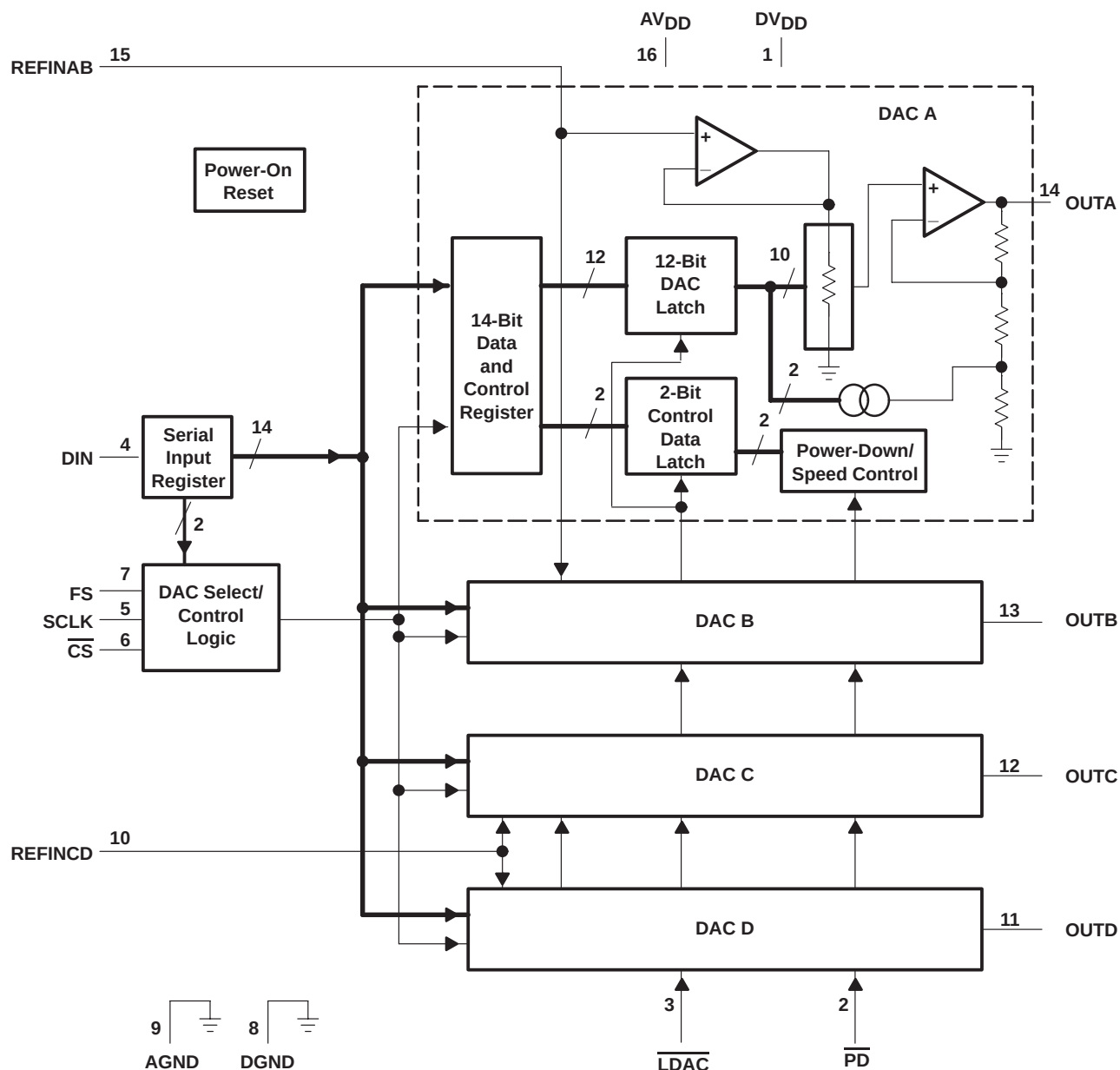
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AVAILABLE OPTIONS

T _A	PACKAGE	
	SOIC (D)	TSSOP (PW)
0°C to 70°C	TLV5614CD	TLV5614CPW
–40°C to 85°C	TLV5614ID	TLV5614IPW

functional block diagram



Terminal Functions

TERMINAL NAME	NO.	I/O	DESCRIPTION
AGND	9		Analog ground
AV _{DD}	16		Analog supply
$\overline{\text{CS}}$	6	I	Chip select. This terminal is active low.
DGND	8		Digital ground
DIN	4	I	Serial data input
DV _{DD}	1		Digital supply
FS	7	I	Frame sync input. The falling edge of the frame sync pulse indicates the start of a serial data frame shifted out to the TLV5614.
$\overline{\text{PD}}$	2	I	Power down pin. Powers down all DACs (overriding their individual power down settings), and all output stages. This terminal is active low.
$\overline{\text{LDAC}}$	3	I	Load DAC. When the $\overline{\text{LDAC}}$ signal is high, no DAC output updates occur when the input digital data is read into the serial interface. The DAC outputs are only updated when LDAC is low.
REFINAB	15	I	Voltage reference input for DACs A and B.
REFINCD	10	I	Voltage reference input for DACs C and D.
SCLK	5	I	Serial Clock input
OUTA	14	O	DACA output
OUTB	13	O	DACB output
OUTC	12	O	DACC output
OUTD	11	O	DACD output

absolute maximum ratings over operating free-air temperature range (unless otherwise noted)[†]

Supply voltage, (DV _{DD} , AV _{DD} to GND)	7 V
Supply voltage difference, (AV _{DD} to DV _{DD})	–2.8 V to 2.8 V
Digital input voltage range	–0.3 V to DV _{DD} + 0.3 V
Reference input voltage range	–0.3 V to AV _{DD} + 0.3 V
Operating free-air temperature range, T _A : TLV5614C	0°C to 70°C
TLV5614I	–40°C to 85°C
Storage temperature range, T _{stg}	–65°C to 150°C
Lead temperature 1,6 mm (1/16 inch) from case for 10 seconds	260°C

[†] Stresses beyond those listed under “absolute maximum ratings” may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated under “recommended operating conditions” is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

recommended operating conditions

		MIN	NOM	MAX	UNIT
Supply voltage, AV_{DD} , DV_{DD}	5-V supply	4.5	5	5.5	V
	3-V supply	2.7	3	3.3	
High-level digital input, V_{IH}	$DV_{DD} = 2.7\text{ V to }5.5\text{ V}$	2			V
Low-level digital input, V_{IL}	$DV_{DD} = 2.7\text{ V to }5.5\text{ V}$			0.8	V
Reference voltage, V_{Ref} to REFINAB, REFINCD terminal	5-V supply, See Note 1	0	2.048	$V_{DD}-1.5$	V
	3-V supply, See Note 1	0	1.024	$V_{DD}-1.5$	
Load resistance, R_L		2	10		k Ω
Load capacitance, C_L				100	pF
Serial clock rate, SCLK				20	MHz
Operating free-air temperature	TLV5614C	0		70	$^{\circ}\text{C}$
	TLV5614I	-40		85	

NOTE 1: Voltages greater than $AV_{DD}/2$ will cause output saturation for large DAC codes.

electrical characteristics over recommended operating free-air temperature range, supply voltages, and reference voltages (unless otherwise noted)

static DAC specifications

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
Resolution			12			bits
Integral nonlinearity (INL), end point adjusted		See Note 2		± 1.5	± 4	LSB
Differential nonlinearity (DNL)		See Note 3		± 0.5	± 1	LSB
EZS	Zero scale error (offset error at zero scale)	See Note 4			± 12	mV
	Zero scale error temperature coefficient	See Note 5		10		ppm/ $^{\circ}\text{C}$
EG	Gain error	See Note 6			± 0.6	% of FS voltage
	Gain error temperature coefficient	See Note 7		10		ppm/ $^{\circ}\text{C}$
PSRR	Power supply rejection ratio	Zero scale	See Notes 8 and 9		-80	dB
		Full scale			-80	dB

- NOTES: 2. The relative accuracy or integral nonlinearity (INL) sometimes referred to as linearity error, is the maximum deviation of the output from the line between zero and full scale excluding the effects of zero code and full-scale errors.
3. The differential nonlinearity (DNL) sometimes referred to as differential error, is the difference between the measured and ideal 1 LSB amplitude change of any two adjacent codes. Monotonic means the output voltage changes in the same direction (or remains constant) as a change in the digital input code.
4. Zero-scale error is the deviation from zero voltage output when the digital input code is zero.
5. Zero-scale-error temperature coefficient is given by: $E_{ZS} \text{ TC} = [E_{ZS}(T_{\max}) - E_{ZS}(T_{\min})]/V_{\text{ref}} \times 10^6/(T_{\max} - T_{\min})$.
6. Gain error is the deviation from the ideal output ($2 V_{\text{ref}} - 1 \text{ LSB}$) with an output load of 10 k Ω excluding the effects of the zero-error.
7. Gain temperature coefficient is given by: $E_G \text{ TC} = [E_G(T_{\max}) - E_G(T_{\min})]/V_{\text{ref}} \times 10^6/(T_{\max} - T_{\min})$.
8. Zero-scale-error rejection ratio (EZS-RR) is measured by varying the AV_{DD} from $5 \pm 0.5\text{ V}$ and $3 \pm 0.5\text{ V}$ dc, and measuring the proportion of this signal imposed on the zero-code output voltage.
9. Full-scale rejection ratio (EG-RR) is measured by varying the AV_{DD} from $5 \pm 0.5\text{ V}$ and $3 \pm 0.5\text{ V}$ dc and measuring the proportion of this signal imposed on the full-scale output voltage after subtracting the zero scale change.

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electrical characteristics over recommended operating free-air temperature range, supply voltages, and reference voltages (unless otherwise noted) (continued)

individual DAC output specifications

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
V_O Voltage output range	$R_L = 10\text{ k}\Omega$	0		$AV_{DD}-0.4$	V
Output load regulation accuracy	$R_L = 2\text{ k}\Omega$ vs $10\text{ k}\Omega$		0.1	0.25	% of FS voltage

reference inputs (REFINAB, REFINCD)

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
V_I Input voltage range	See Note 10	0		$AV_{DD}-1.5$	V
R_I Input resistance			10		M Ω
C_I Input capacitance			5		pF
Reference feed through	REFIN = 1 V_{pp} at 1 kHz + 1.024 V dc (see Note 11)		-75		dB
Reference input bandwidth	REFIN = 0.2 V_{pp} + 1.024 V dc large signal	Slow	0.5		MHz
		Fast	1		

NOTES: 10. Reference input voltages greater than $V_{DD}/2$ will cause output saturation for large DAC codes.

11. Reference feedthrough is measured at the DAC output with an input code = 000 hex and a V_{ref} (REFINAB or REFINCD) input = $1.024\text{ Vdc} + 1\text{ V}_{pp}$ at 1 kHz.

digital inputs ($\overline{DIN}$, $\overline{CS}$, $\overline{LDAC}$, $\overline{PD}$)

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
I_{IH} High-level digital input current	$V_I = V_{DD}$			± 1	μA
I_{IL} Low-level digital input current	$V_I = 0\text{ V}$			± 1	μA
C_I Input capacitance			3		pF

power supply

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
I_{DD} Power supply current	5-V supply, No load, Clock running, All inputs 0 V or V_{DD}	Slow	1.6	2.4	mA
		Fast	3.8	5.6	
	3-V supply, No load, Clock running, All inputs 0 V or DV_{DD}	Slow	1.2	1.8	mA
		Fast	3.2	4.8	
Power down supply current (see Figure 12)			10		nA



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electrical characteristics over recommended operating free-air temperature range, supply voltages, and reference voltages (unless otherwise noted) (continued)

analog output dynamic performance

PARAMETER		TEST CONDITIONS		MIN	TYP	MAX	UNIT
SR	Output slew rate	C _L = 100 pF, R _L = 10 kΩ, V _O = 10% to 90%, V _{ref} = 2.048 V, 1024 V	Fast	5			V/μs
			Slow	1			V/μs
t _s	Output settling time	To ± 0.5 LSB, C _L = 100 pF, R _L = 10 kΩ, See Notes 12 and 14	Fast	3	5.5		μs
			Slow	9	20		
t _{s(c)}	Output settling time, code to code	To ± 0.5 LSB, C _L = 100 pF, R _L = 10 kΩ, See Note 15	Fast	1			μs
			Slow	2			
Glitch energy		Code transition from 7FF to 800		10			nV-sec
SNR	Signal-to-noise ratio	Sinewave generated by DAC, Reference voltage = 1.024 at 3 V and 2.048 at 5 V, f _s = 400 KSPS, f _{OUT} = 1.1 kHz sinewave, C _L = 100 pF, R _L = 10 kΩ, BW = 20 kHz		74			dB
S/(N+D)	Signal to noise + distortion			66			
THD	Total harmonic Distortion			–68			
SFDR	Spurious free dynamic range			70			

NOTES: 12. Settling time is the time for the output signal to remain within $\pm 0.5\text{ LSB}$ of the final measured value for a digital input code change of FFF hex to 080 hex for 080 hex to FFF hex.

13. Settling time is the time for the output signal to remain within $\pm 0.5\text{ LSB}$ of the final measured value for a digital input code change of one count.

14. Limits are ensured by design and characterization, but are not production tested.

electrical characteristics over recommended operating free-air temperature range, supply voltages, and reference voltages (unless otherwise noted) (continued)

digital input timing requirements

	MIN	NOM	MAX	UNIT
$t_{su}(\overline{CS}-FS)$ Setup time, $\overline{CS}$ low before $FS\downarrow$	10			ns
$t_{su}(FS-CK)$ Setup time, FS low before first negative SCLK edge	8			ns
$t_{su}(C16-FS)$ Setup time, sixteenth negative edge after FS low on which bit D0 is sampled before rising edge of FS	10			ns
$t_{su}(C16-CS)$ Setup time, sixteenth positive SCLK edge (first positive after D0 is sampled) before $\overline{CS}$ rising edge. If FS is used instead of the sixteenth positive edge to update the DAC, then the setup time is between the FS rising edge and $\overline{CS}$ rising edge.	10			ns
t_{wH} Pulse duration, SCLK high	25			ns
t_{wL} Pulse duration, SCLK low	25			ns
$t_{su}(D)$ Setup time, data ready before SCLK falling edge	8			ns
$t_h(D)$ Hold time, data held valid after SCLK falling edge	5			ns
$t_{wH}(FS)$ Pulse duration, FS high	20			ns

PARAMETER MEASUREMENT INFORMATION

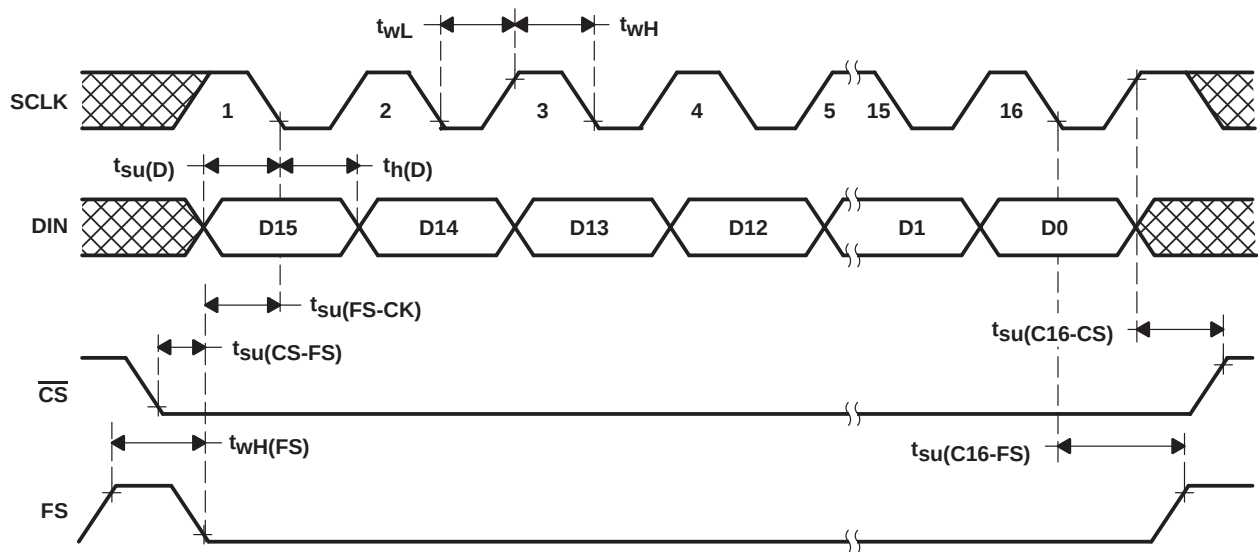


Figure 1. Timing Diagram

TYPICAL CHARACTERISTICS

LOAD REGULATION

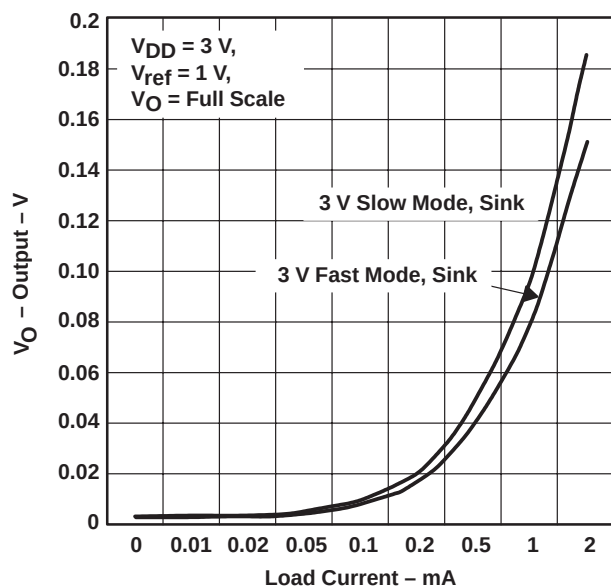


Figure 2

LOAD REGULATION

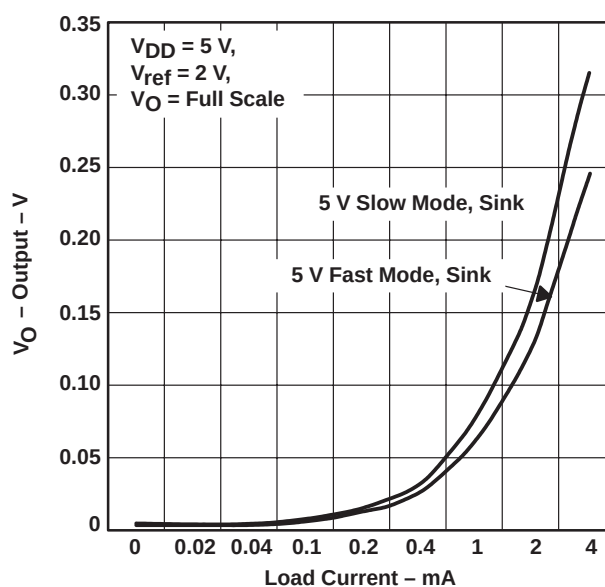


Figure 3

LOAD REGULATION

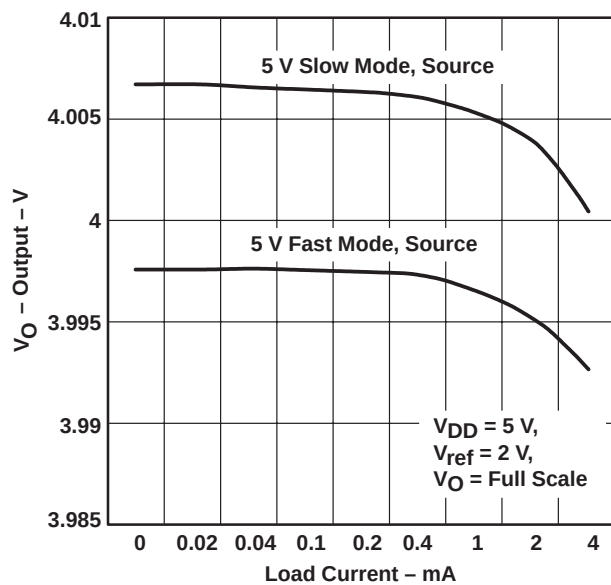


Figure 4

LOAD REGULATION

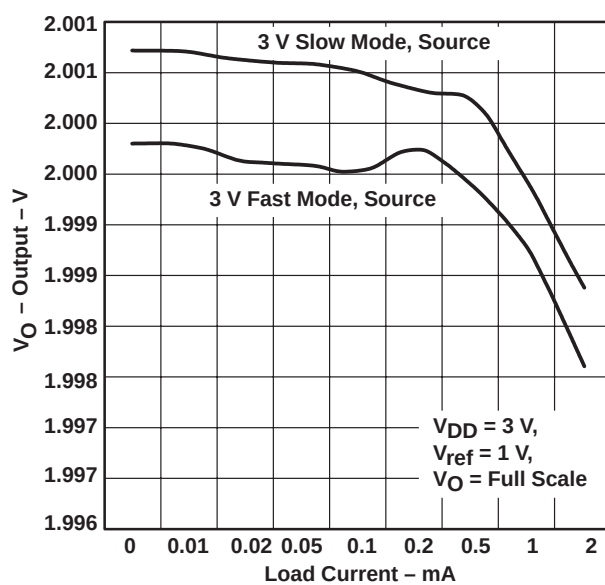
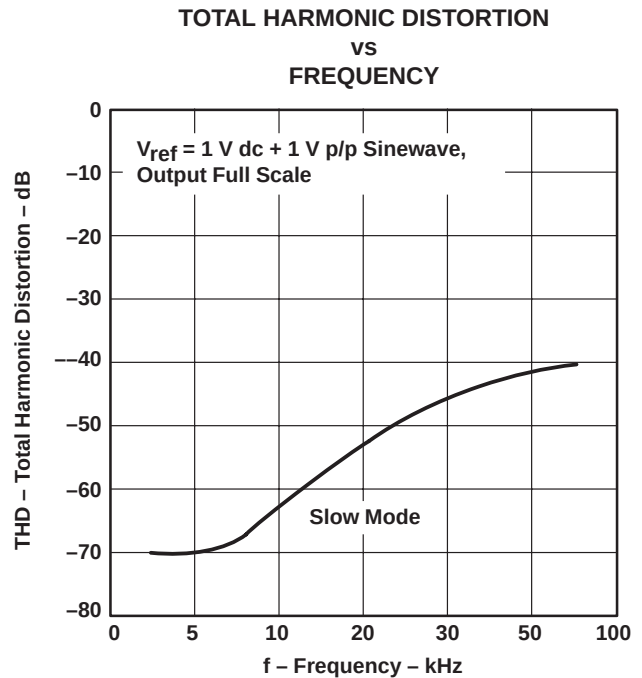
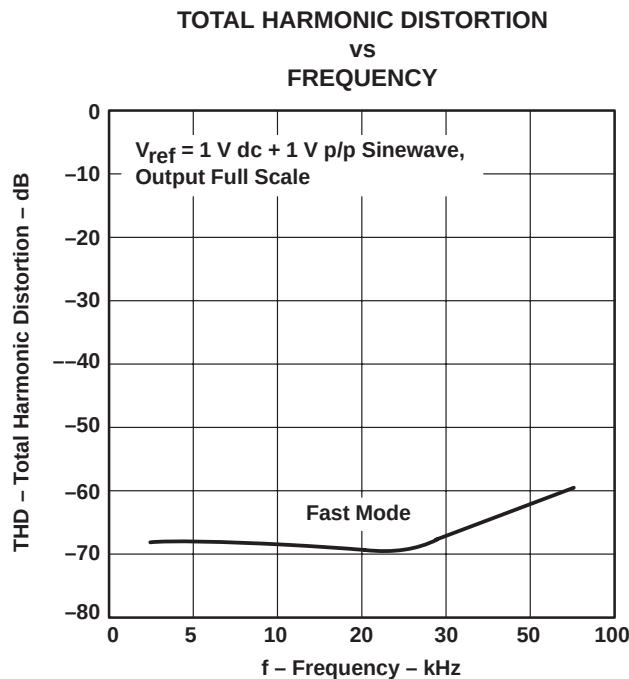
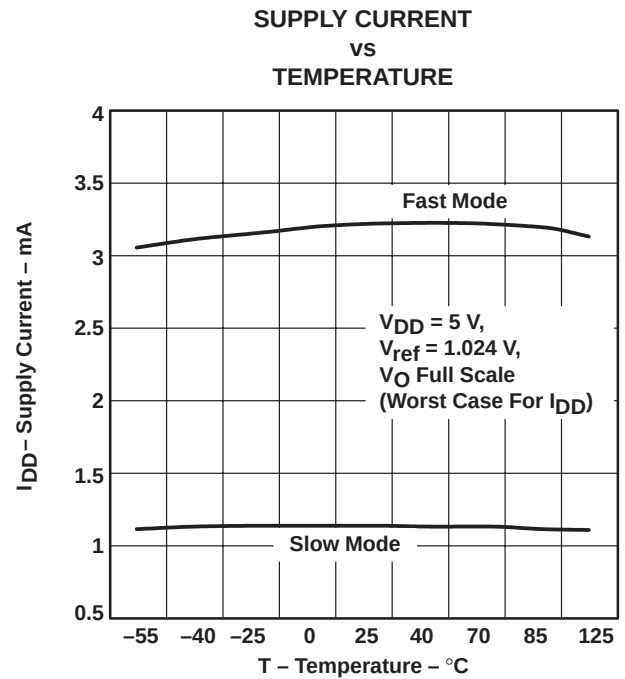
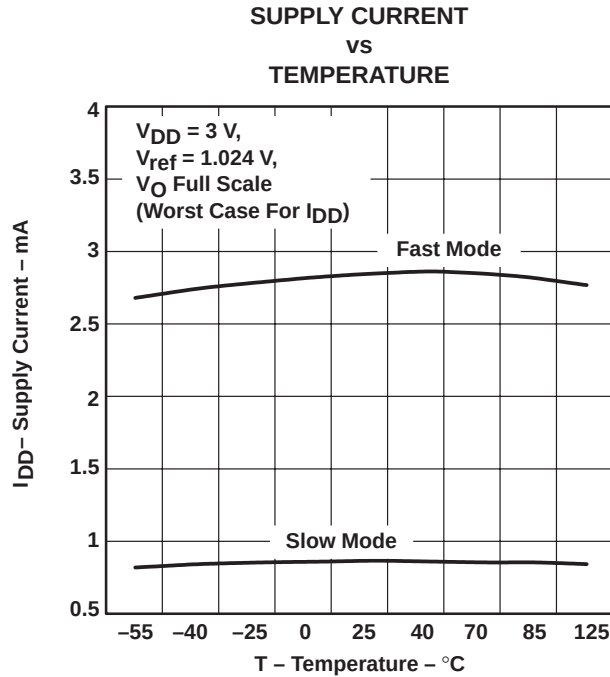


Figure 5

TYPICAL CHARACTERISTICS



TYPICAL CHARACTERISTICS

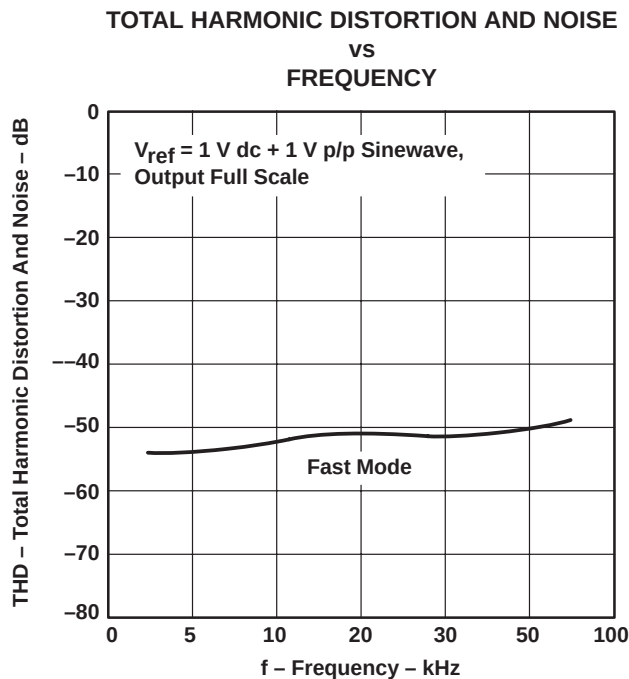


Figure 10

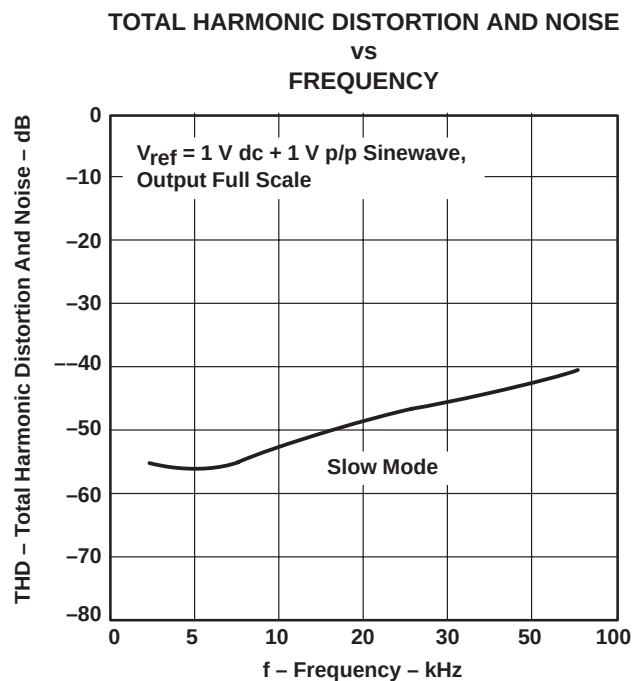


Figure 11

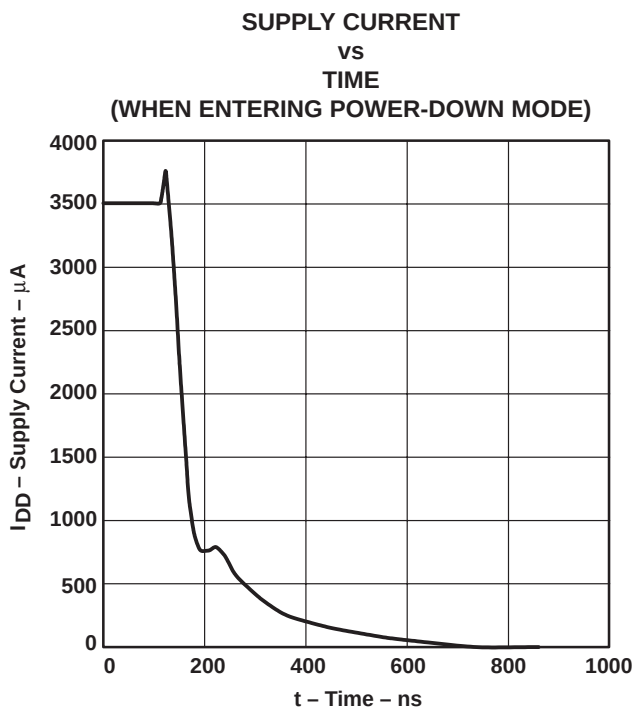


Figure 12

TYPICAL CHARACTERISTICS

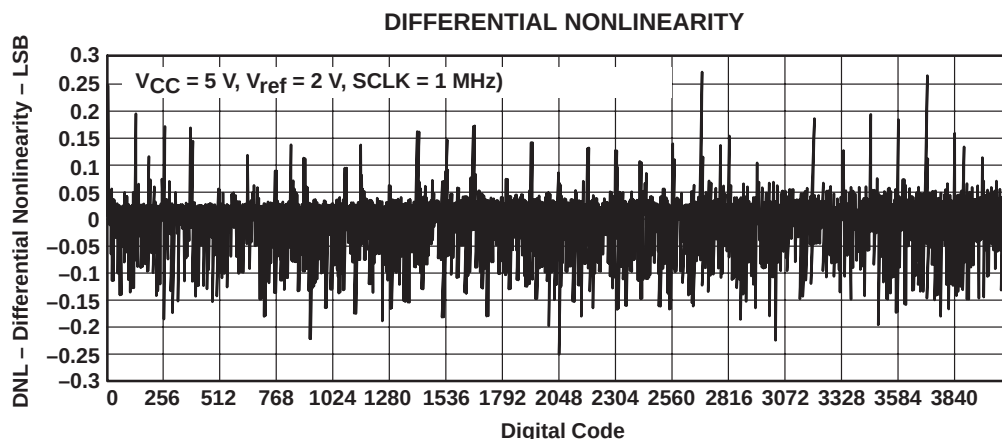


Figure 13

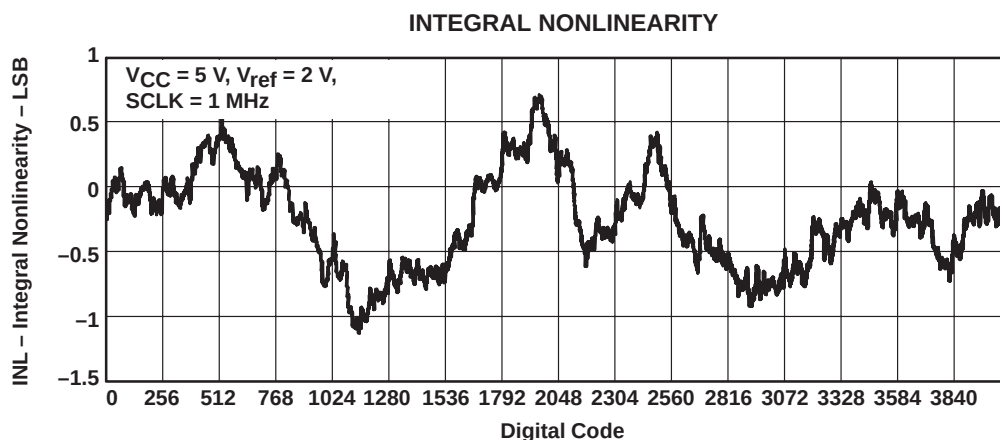


Figure 14

APPLICATION INFORMATION

general function

The TLV5614 is a 12-bit single supply DAC based on a resistor string architecture. The device consists of a serial interface, speed and power down control logic, a reference input buffer, a resistor string, and a rail-to-rail output buffer.

The output voltage (full scale determined by external reference) is given by:

$$2 \text{ REF } \frac{\text{CODE}}{0x1000} \text{ [V]}$$

Where REF is the reference voltage and CODE is the digital input value within the range of 0x000 to 0xFFF. A power-on reset initially resets the internal latches to a defined state (all bits zero).

serial interface

Explanation of data transfer: First, the device has to be enabled with $\overline{\text{CS}}$ set to low. Then, a falling edge of FS starts shifting the data bit-per-bit (starting with the MSB) to the internal register on the falling edges of SCLK. After 16 bits have been transferred or FS rises, the content of the shift register is moved to the DAC latch which updates the voltage output to the new level.

The serial interface of the TLV5614 can be used in two basic modes:

- four wire (with chip select)
- three wire (without chip select)

Using chip select (four wire mode), it is possible to have more than one device connected to the serial port of the data source (DSP or microcontroller). The interface is compatible with the TMS320 family. Figure 15 shows an example with two TLV5614s connected directly to a TMS320 DSP.

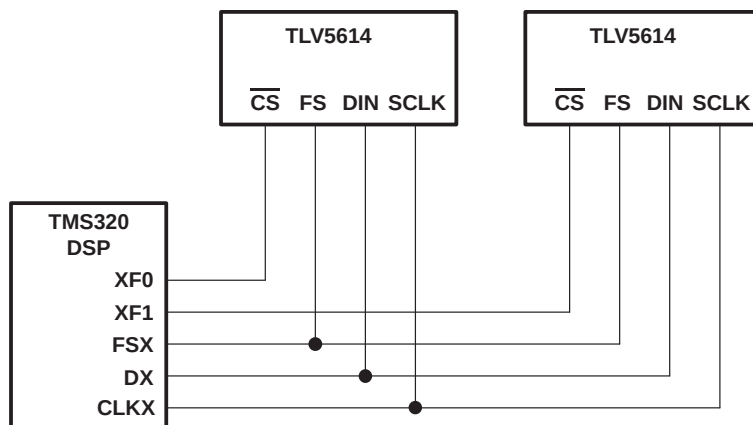


Figure 15. TMS320 Interface

APPLICATION INFORMATION

serial interface (continued)

If there is no need to have more than one device on the serial bus, then $\overline{\text{CS}}$ can be tied low. Figure 16 shows an example of how to connect the TLV5614 to a TMS320, SPI, or Microwire port using only three pins.

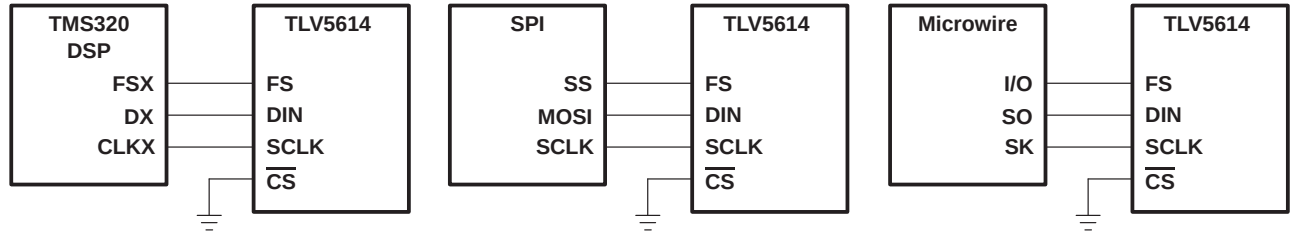


Figure 16. Three-Wire Interface

Notes on SPI and Microwire: Before the controller starts the data transfer, the software has to generate a falling edge on the I/O pin connected to FS. If the word width is 8 bits (SPI and Microwire), two write operations must be performed to program the TLV5614. After the write operation(s), the DAC output is updated automatically on the sixteenth positive clock edge.

serial clock frequency and update rate

The maximum serial clock frequency is given by:

$$f_{\text{SCLKmax}} = \frac{1}{t_{\text{WH(min)}} + t_{\text{WL(min)}}} = 20 \text{ MHz}$$

The maximum update rate is:

$$f_{\text{UPDATEmax}} = \frac{1}{16 (t_{\text{WH(min)}} + t_{\text{WL(min)}})} = 1.25 \text{ MHz}$$

Note that the maximum update rate is a theoretical value for the serial interface since the settling time of the TLV5614 has to be considered also.

data format

The 16-bit data word for the TLV5614 consists of two parts:

- Control bits (D15 . . . D12)
- New DAC value (D11 . . . D0)

D15	D14	D13	D12	D11	D10	D9	D8	D7	D6	D5	D4	D3	D2	D1	D0
A1	A0	PWR	SPD	New DAC value (12 bits)											

X: don't care

SPD: Speed control bit. 1 → fast mode 0 → slow mode

PWR: Power control bit. 1 → power down 0 → normal operation

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APPLICATION INFORMATION

In power down mode, all amplifiers within the TLV5614 are disabled. A particular DAC (A, B, C, D) of the TLV5614 is selected by A1 and A0 within the input word.

A1	A0	DAC
0	0	A
0	1	B
1	0	C
1	1	D

TLV5614 interfaced to TMS320C203 DSP

hardware interfacing

Figure 17 shows an example of how to connect the TLV5614 to a TMS320C203 DSP. The serial port is configured in burst mode, with FSX generated by the TMS320C203 to provide the frame sync (FS) input to the TLV5614. Data is transmitted on the DX line, with the serial clock input on the CLKX line. The general-purpose input/output port bits IO0 and IO1 are used to generate the chip select ($\overline{\text{CS}}$) and DAC latch update ($\overline{\text{LDAC}}$) inputs to the TLV5614. The active low power down ($\overline{\text{PD}}$) is pulled high all the time to ensure the DACs are enabled.

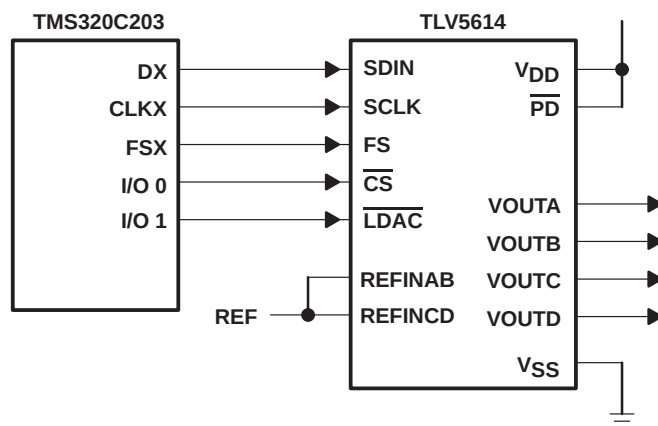


Figure 17. TLV5614 Interfaced with TMS320C203

software

The application example outputs a differential in-phase (sine) signal between the VOUTA and VOUTB pins, and its quadrature (cosine) signal as the differential signal between VOUTC and VOUTD.

The on-chip timer is used to generate interrupts at a fixed frequency. The related interrupt service routine pulses $\overline{\text{LDAC}}$ low to update all 4 DACs simultaneously, then fetches and writes the next sample to all 4 DACs. The samples are stored in a look-up table, which describes two full periods of a sine wave.

The synchronous serial port of the DSP is used in burst mode. In this mode, the processor generates an FS pulse preceding the MSB of every data word. If multiple, contiguous words are transmitted, a violation of the $\text{tsu}(\text{C16}-\text{FS})$ timing requirement will occur. To avoid this, the program waits until the transmission of the previous word has been completed.

APPLICATION INFORMATION

```

;-----
; Processor:  TMS320C203 running at 40 MHz
;
; Description:
;
; This program generates a differential in-phase (sine) on (OUTA-OUTB) and it's
; quadrature (cosine) as a differential signal on (OUTC-OUTD).
;
; The DAC codes for the signal samples are stored as a table of 64 12-bit values,
; describing 2 periods of a sine function. A rolling pointer is used to address the
; table location in the first period of this waveform, from which the DAC A samples
; are read. The samples for the other 3 DACs are read at an offset to this rolling
; pointer:
;
;   DAC      Function      Offset from rolling pointer
;   A        sine          0
;   B        inverse sine  16
;   C        cosine        8
;   D        inverse cosine24
;
; The on-chip timer is used to generate interrupts at a fixed rate. The interrupt
; service routine first pulses LDAC low to update all DACs simultaneously
; with the values which were written to them in the previous interrupt. Then all
; 4 DAC values are fetched and written out through the synchronous serial interface
; Finally, the rolling pointer is incremented to address the next sample, ready for
; the next interrupt.
;
; © 1998, Texas Instruments Inc.
;-----

```

----- I/O and memory mapped regs -----

```

;-----
; .include "regs.asm"
;-----

```

```

;-----
; jump vectors
;-----

```

```

; .ps      0h
; b        start
; b        int1
; b        int23
; b        timer_isr;
;-----

```

----- variables -----

```

temp      .equ    0060h
r_ptr     .equ    0061h
iosr_stat .equ    0062h
DACA_ptr  .equ    0063h
DACB_ptr  .equ    0064h
DACC_ptr  .equ    0065h
DACd_ptr  .equ    0066h
;-----

```

----- constants -----

```

; DAC control bits to be OR'ed onto data
; all fast mode

```

```

DACA_control .equ    01000h
DACB_control .equ    05000h
DACC_control .equ    09000h
DACd_control .equ    0d000h
;-----

```

----- tables -----

```

; .ds      02000h
;-----

```

```

sinevals

```

```

; .word    00800h
; .word    0097Ch
; .word    00AE9h
; .word    00C3Ah
; .word    00D61h
; .word    00E53h
; .word    00F07h
; .word    00F76h
; .word    00F9Ch
; .word    00F76h
; .word    00F07h
; .word    00E53h

```

APPLICATION INFORMATION

.word 00D61h
.word 00C3Ah
.word 00AE9h
.word 0097Ch
.word 00800h
.word 00684h
.word 00517h
.word 003C6h
.word 0029Fh
.word 001ADh
.word 000F9h
.word 0008Ah
.word 00064h
.word 0008Ah
.word 000F9h
.word 001ADh
.word 0029Fh
.word 003C6h
.word 00517h
.word 00684h
.word 00800h
.word 0097Ch
.word 00AE9h
.word 00C3Ah
.word 00D61h
.word 00E53h
.word 00F07h
.word 00F76h
.word 00F9Ch
.word 00F76h
.word 00F07h
.word 00E53h
.word 00D61h
.word 00C3Ah
.word 00AE9h
.word 0097Ch
.word 00800h
.word 00684h
.word 00517h
.word 003C6h
.word 0029Fh
.word 001ADh
.word 000F9h
.word 0008Ah
.word 00064h
.word 0008Ah
.word 000F9h
.word 001ADh
.word 0029Fh
.word 003C6h
.word 00517h
.word 00684h

APPLICATION INFORMATION

```

;-----
; Main Program
;-----
        .ps      1000h
        .entry
start
;-----
; disable interrupts
;-----
        setc     INTM      ; disable maskable interrupts
        splk     #0ffffh, IFR; clear all interrupts
        splk     #0004h, IMR; timer interrupts unmasked
;-----
; set up the timer
; timer period set by values in PRD and TDDR
; period = (CLKOUT1 period) x (1+PRD) x (1+TDDR)
; examples for TMS320C203 with 40MHz main clock
; Timer rate      TDDR   PRD
; 80 kHz          9      24 (18h)
; 50 kHz          9      39 (27h)
;-----
prd_val.equ      0018h
tcr_val.equ      0029h
        splk     #0000h, temp; clear timer
        out      temp, TIM
        splk     #prd_val, temp; set PRD
        out      temp, PRD
        splk     #tcr_val, temp; set TDDR, and TRB=1 for auto-reload
        out      temp, TCR
;-----
; Configure I00/1 as outputs to be :
; I00 CS - and set high
; I01 LDAC - and set high
;-----
        in       temp, ASPCR; configure as output
        lacl     temp
        or       #0003h
        saccl    temp
        out      temp, ASPCR
        in       temp, IOSR; set them high
        lacl     temp
        or       #0003h
        saccl    temp
        out      temp, IOSR
;-----
; set up serial port for
; SSPCR.TXM=1      Transmit mode - generate FSX
; SSPCR.MCM=1      Clock mode - internal clock source
; SSPCR.FSM=1      Burst mode
;-----
        splk     #0000Eh, temp
        out      temp, SSPCR; reset transmitter
        splk     #0002Eh, temp
        out      temp, SSPCR
;-----
; reset the rolling pointer
;-----
        lacl     #000h
        saccl    r_ptr
;-----
; enable interrupts
;-----
        clrc     INTM      ; enable maskable interrupts
;-----
; loop forever!
;-----

```

APPLICATION INFORMATION

```

next   idle           ;wait for interrupt
      b       next
;-----
; all else fails stop here
;-----
done   b       done   ;hang there
;-----
; Interrupt Service Routines
;-----
int1   ret           ; do nothing and return
int23  ret           ; do nothing and return
timer_isr:
  in    iosr_stat, IOSR; store IOSR value into variable space
  lacl  iosr_stat     ; load acc with iosr status
  and   #0FFFDh       ; reset IO1 - LDAC low
  sac1  temp          ;
  out   temp, IOSR    ;
  or    #0002h        ; set IO1 - LDAC high
  sac1  temp          ;
  out   temp, IOSR    ;
  and   #0FFFEh       ; reset IO0 - CS low
  sac1  temp          ;
  out   temp, IOSR    ;
  lacl  r_ptr         ; load rolling pointer to accumulator
  add   #sinevals     ; add pointer to table start
  sac1  DACa_ptr       ; to get a pointer for next DAC a sample
  add   #08h          ; add 8 to get to DAC C pointer
  sac1  DACc_ptr       ;
  add   #08h          ; add 8 to get to DAC B pointer
  sac1  DACb_ptr       ;
  add   #08h          ; add 8 to get to DAC D pointer
  sac1  DACd_ptr       ;
  mar   *,ar0         ; set ar0 as current AR

; DAC A
  lar   ar0, DACa_ptr ; ar0 points to DAC a sample
  lacl  *             ; get DAC a sample into accumulator
  or    #DACa_control ; OR in DAC A control bits
  sac1  temp          ;
  out   temp, SDTR    ; send data
;-----
; We must wait for transmission to complete before writing next word to the SDTR.;
; TLV5614/04 interface does not allow the use of burst mode with the full packet; rate, as
; we need a CLKX -ve edge to clock in last bit before FS goes high again;; to allow SPI
; compatibility.
;-----
  rpt   #016h        ; wait long enough for this configuration
  nop                   ; of MCLK/CLKOUT1 rate

; DAC B
  lar   ar0, dacb_ptr ; ar0 points to DAC a sample
  lacl  *             ; get DAC a sample into accumulator
  or    #DACb_control ; OR in DAC B control bits
  sac1  temp          ;
  out   temp, SDTR    ; send data
  rpt   #016h        ; wait long enough for this configuration
  nop                   ; of MCLK/CLKOUT1 rate

; DAC C
  lar   ar0, dacc_ptr ; ar0 points to dac a sample
  lacl  *             ; get DAC a sample into accumulator
  or    #DACc_control ; OR in DAC C control bits
  sac1  temp          ;
  out   temp, SDTR    ; send data
  rpt   #016h        ; wait long enough for this configuration
  nop                   ; of MCLK/CLKOUT1 rate

```

APPLICATION INFORMATION

```

; DAC D
  lar      ar0, dacd_ptr; ar0 points to DAC a sample
  lacl     *          ; get DAC a sample into accumulator
  or       #dacd_control; OR in DAC D control bits
  saccl    temp
  out      temp, SDTR  ; send data

  lacl     r_ptr       ; load rolling pointer to accumulator
  add      #1h         ; increment rolling pointer
  and      #001Fh      ; count 0-31 then wrap back round
  saccl    r_ptr       ; store rolling pointer
  rpt      #016h       ; wait long enough for this configuration
  nop      ; of MCLK/CLKOUT1 rate

; now take CS high again
  lacl     iosr_stat   ; load acc with iosr status
  or       #0001h     ; set IO0 - CS high
  saccl    temp
  out      temp, IOSR
  clrc     intm        ; re-enable interrupts
  ret      ; return from interrupt
.end

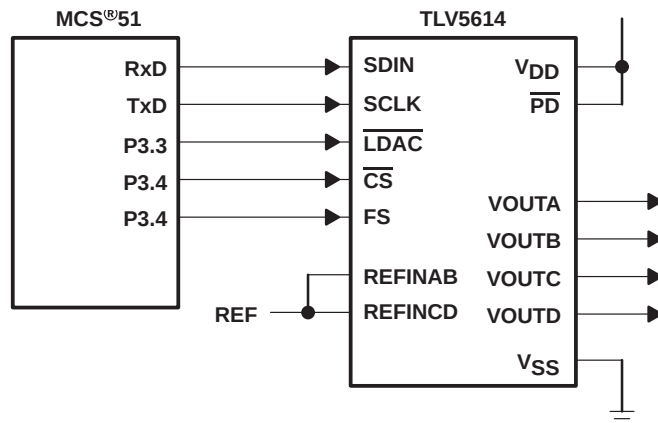
```

APPLICATION INFORMATION

TLV5614 interfaced to MCS[®]51 microcontroller

hardware interfacing

Figure 18 shows an example of how to connect the TLV5614 to an MCS[®]51 Microcontroller. The serial DAC input data and external control signals are sent via I/O Port 3 of the controller. The serial data is sent on the RxD line, with the serial clock output on the TxD line. Port 3 bits 3, 4, and 5 are configured as outputs to provide the DAC latch update ($\overline{\text{LDAC}}$), chip select ($\overline{\text{CS}}$) and frame sync (FS) signals for the TLV5614. The active low power down pin ($\overline{\text{PD}}$) of the TLV5614 is pulled high to ensure that the DACs are enabled.

Figure 18. TLV5614 Interfaced with MCS[®]51

software

The example is the same as for the TMS320C203 in this datasheet, but adapted for a MCS[®]51 controller. It generates a differential in-phase (sine) signal between the VOUTA and VOUTB pins, and its quadrature (cosine) signal as the differential signal between VOUTC and VOUTD.

The on-chip timer is used to generate interrupts at a fixed frequency. The related interrupt service routine pulses $\overline{\text{LDAC}}$ low to update all 4 DACs simultaneously, then fetches and writes the next sample to all 4 DACs. The samples are stored as a look-up table, which describes one full period of a sine wave.

The serial port of the controller is used in Mode 0, which transmits 8 bits of data on RxD, accompanied by a synchronous clock on TxD. Two writes concatenated together are required to write a complete word to the TLV5614. The $\overline{\text{CS}}$ and FS signals are provided in the required fashion through control of IO port 3, which has bit addressable outputs.

APPLICATION INFORMATION

```

-----
; Processor: 80C51
;
; Description:
;
; This program generates a differential in-phase
; (sine) on (OUTA-OUTB) ; and it's quadrature (cosine)
; as a differential signal on (OUTC-OUTD).
;
; © 1998, Texas Instruments Inc.
-----
NAME    GENIQ
MAIN    SEGMENT      CODE
ISR     SEGMENT      CODE
SINTBL  SEGMENT      CODE
VAR1    SEGMENT      DATA
STACK   SEGMENT      IDATA
-----
; Code start at address 0, jump to start
;
; CSEG AT 0
; LJMP start ; Execution starts at address 0 on power-up.
-----
; Code in the timer0 interrupt vector
;
; CSEG AT 0BH
; LJMP timer0isr ; Jump vector for timer 0 interrupt is 000Bh
-----
; Global variables need space allocated
;
; RSEG VAR1
temp_ptr: DS 1
rolling_ptr: DS 1
;
-----
; Interrupt service routine for timer 0 interrupts
;
; RSEG ISR
timer0isr:
  PUSH PSW
  PUSH ACC
  CLR INT1 ; pulse LDAC low
  SETB INT1 ; to latch all 4 previous values at the same time
              ; 1st thing done in timer isr => fixed period
  CLR T0 ; set CS low

  ; The signal to be output on each DAC is a sine function.
  ; One cycle of a sine wave is held in a table @ sinevals
  ; as 32 samples of msb, lsb pairs (64 bytes).
  ; We have ; one pointer which rolls round this table, rolling_ptr,
  ; incrementing by 2 bytes (1 sample) on each interrupt (at the end of
  ; this routine).

  ; The DAC samples are read at an offset to this rolling pointer:
  ; DAC Function Offset from rolling_ptr
  ; A sine 0
  ; B inverse sine 32
  ; C cosine 16
  ; D inverse cosine 48
  MOV DPTR,#sinevals; set DPTR to the start of the table
              ; of sine signal values
  MOV R7,rolling_ptr; R7 holds the pointer
              ; into the sine table

  MOV A,R7 ; get DAC A msb
  MOVC A,@A+DPTR ; msb of DAC A is in the ACC

```

2.7-V TO 5.5-V 12-BIT 3- μ S QUADRUPLE DIGITAL-TO-ANALOG CONVERTERS WITH POWER DOWN

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APPLICATION INFORMATION

```

CLR    T1                ; transmit it - set FS low
MOV    SBUF,A            ; send it out the serial port

INC    R7                ; increment the pointer in R7
MOV    A,R7              ; to get the next byte from the table
MOVC   A,@A+DPTR         ; which is the lsb of this sample, now in ACC
A_MSB_TX:
JNB    TI,A_MSB_TX       ; wait for transmit to complete
CLR    TI                ; clear for new transmit
MOV    SBUF,A            ; and send out the lsb of DAC A

; DAC C next
; DAC C codes should be taken from 16 bytes (8 samples) further on
; in the sine table - this gives a cosine function
MOV    A,R7              ; pointer in R7
ADD    A,#0FH            ; add 15 - already done one INC
ANL    A,#03FH           ; wrap back round to 0 if > 64
MOV    R7,A              ; pointer back in R7

MOVC   A,@A+DPTR         ; get DAC C msb from the table
ORL    A,#01H            ; set control bits to DAC C address
A_LSB_TX:
JNB    TI,A_LSB_TX       ; wait for DAC A lsb transmit to complete
SETB   T1                ; toggle FS
CLR    T1
CLR    TI                ; clear for new transmit
MOV    SBUF,A            ; and send out the msb of DAC C
INC    R7                ; increment the pointer in R7
MOV    A,R7              ; to get the next byte from the table
MOVC   A,@A+DPTR         ; which is the lsb of this sample, now in ACC
C_MSB_TX:
JNB    TI,C_MSB_TX       ; wait for transmit to complete
CLR    TI                ; clear for new transmit
MOV    SBUF,A            ; and send out the lsb of DAC C

; DAC B next
; DAC B codes should be taken from 16 bytes (8 samples) further on
; in the sine table - this gives an inverted sine function
MOV    A,R7              ; pointer in R7
ADD    A,#0FH            ; add 15 - already done one INC
ANL    A,#03FH           ; wrap back round to 0 if > 64
MOV    R7,A              ; pointer back in R7

MOVC   A,@A+DPTR         ; get DAC B msb from the table
ORL    A,#02H            ; set control bits to DAC B address
C_LSB_TX:
JNB    TI,C_LSB_TX       ; wait for DAC C lsb transmit to complete
SETB   T1                ; toggle FS
CLR    T1
CLR    TI                ; clear for new transmit
MOV    SBUF,A            ; and send out the msb of DAC B

; get DAC B LSB
INC    R7                ; increment the pointer in R7
MOV    A,R7              ; to get the next byte from the table
MOVC   A,@A+DPTR         ; which is the lsb of this sample, now in ACC
B_MSB_TX:
JNB    TI,B_MSB_TX       ; wait for transmit to complete
CLR    TI                ; clear for new transmit
MOV    SBUF,A            ; and send out the lsb of DAC B

; DAC D next
; DAC D codes should be taken from 16 bytes (8 samples) further on
; in the sine table - this gives an inverted cosine function

```

APPLICATION INFORMATION

```

MOV    A,R7          ; pointer in R7
ADD    A,#0FH        ; add 15 - already done one INC
ANL    A,#03FH       ; wrap back round to 0 if > 64
MOV    R7,A          ; pointer back in R7
MOVC   A,@A+DPTR     ; get DAC D msb from the table
ORL    A,#03H        ; set control bits to DAC D address

B_LSB_TX:
JNB    TI,B_LSB_TX   ; wait for DAC B lsb transmit to complete
SETB   T1            ; toggle FS
CLR    T1
CLR    TI ; clear for new transmit
MOV    SBUF,A        ; and send out the msb of DAC D

INC    R7            ; increment the pointer in R7
MOV    A,R7          ; to get the next byte from the table
MOVC   A,@A+DPTR     ; which is the lsb of this sample, now in ACC
D_MSB_TX:
JNB    TI,D_MSB_TX   ; wait for transmit to complete
CLR    TI            ; clear for new transmit
MOV    SBUF,A        ; and send out the lsb of DAC D

; increment the rolling pointer to point to the next sample
; ready for the next interrupt
MOV    A,rolling_ptr
ADD    A,#02H        ; add 2 to the rolling pointer
ANL    A,#03FH       ; wrap back round to 0 if > 64
MOV    rolling_ptr,A ; store in memory again
D_LSB_TX:
JNB    TI,D_LSB_TX   ; wait for DAC D lsb transmit to complete
CLR    TI            ; clear for next transmit
SETB   T1            ; FS high
SETB   T0            ; CS high
POP    ACC
POP    PSW
RETI

;-----
; Stack needs definition
;-----
RSEG   STACK
DS     10h           ; 16 Byte Stack!
;-----
; Main program code
;-----
RSEG   MAIN
start:
MOV    SP,#STACK-1   ; first set Stack Pointer
CLRA
MOV    SCON,A        ; set serial port 0 to mode 0
MOV    TMOD,#02H     ; set timer 0 to mode 2 - auto-reload
MOV    TH0,#038H     ; set TH0 for 5kHs interrupts
SETB   INT1          ; set LDAC = 1
SETB   T1            ; set FS = 1
SETB   T0            ; set CS = 1
SETB   ET0           ; enable timer 0 interrupts
SETB   EA            ; enable all interrupts
MOV    rolling_ptr,A ; set rolling pointer to 0
SETB   TR0           ; start timer 0
always:
SJMP   always        ; while(1) !
RET

;-----
; Table of 32 sine wave samples used as DAC data
;-----
RSEG   SINTBL

```

APPLICATION INFORMATION

sinevals:

```
DW 01000H
DW 0903EH
DW 05097H
DW 0305CH
DW 0B086H
DW 070CAH
DW 0F0E0H
DW 0F06EH
DW 0F039H
DW 0F06EH
DW 0F0E0H
DW 070CAH
DW 0B086H
DW 0305CH
DW 05097H
DW 0903EH
DW 01000H
DW 06021H
DW 0A0E8H
DW 0C063H
DW 040F9H
DW 080B5H
DW 0009FH
DW 00051H
DW 00026H
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DW 0009FH
DW 080B5H
DW 040F9H
DW 0C063H
DW 0A0E8H
DW 06021H
```

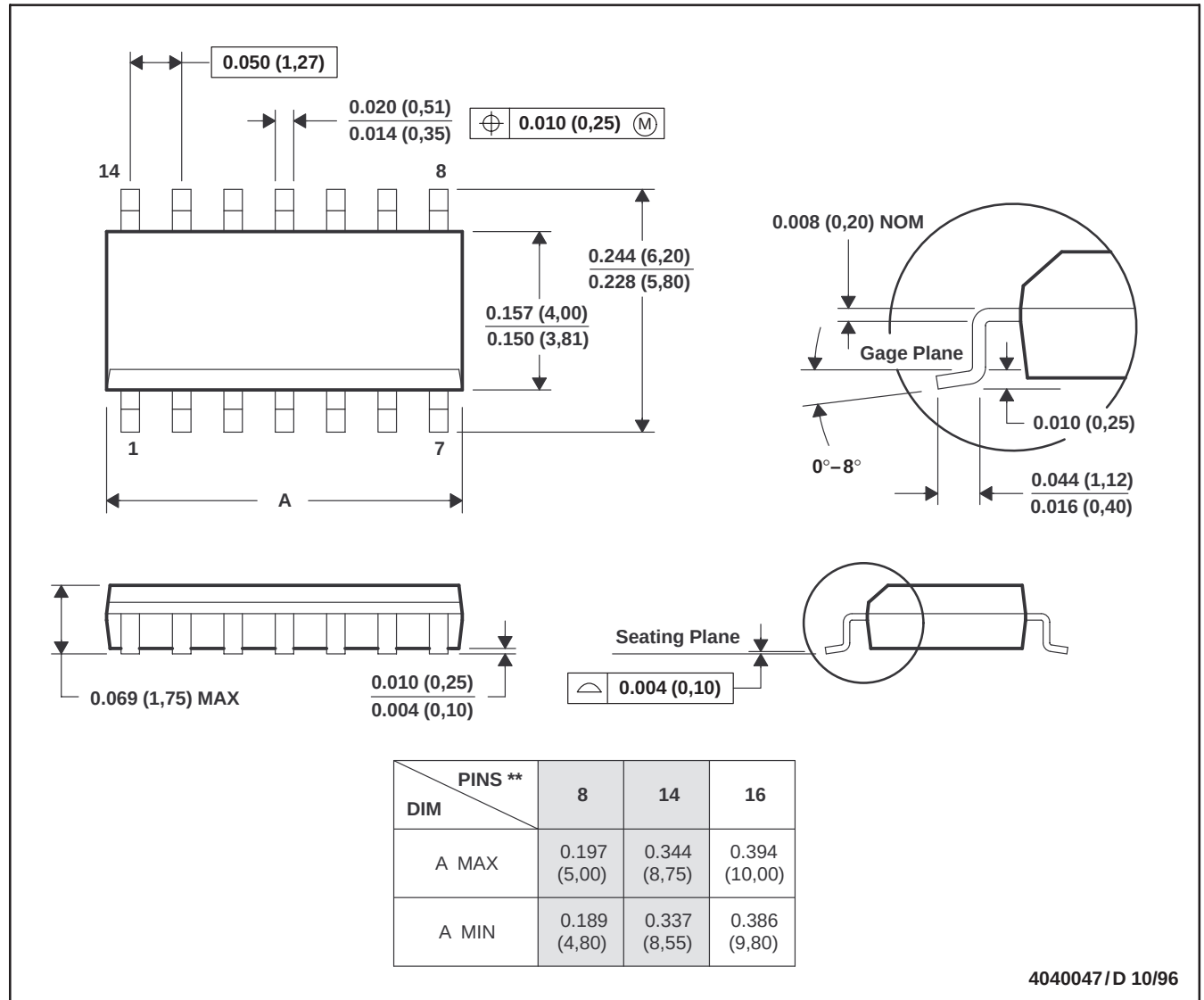
END

MECHANICAL DATA

D (R-PDSO-G**)

PLASTIC SMALL-OUTLINE PACKAGE

14 PIN SHOWN



- NOTES: A. All linear dimensions are in inches (millimeters).
B. This drawing is subject to change without notice.
C. Body dimensions do not include mold flash or protrusion, not to exceed 0.006 (0,15).
D. Falls within JEDEC MS-012

TLV5614
2.7-V TO 5.5-V 12-BIT 3- μ S QUADRUPLE DIGITAL-TO-ANALOG CONVERTERS
WITH POWER DOWN

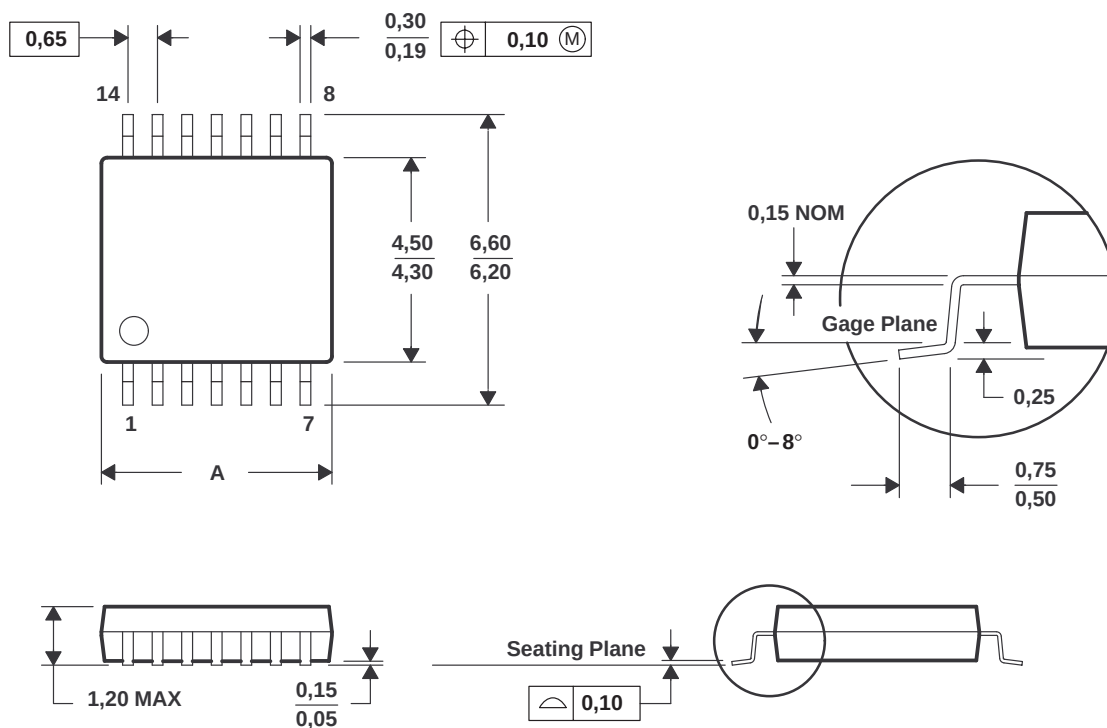
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MECHANICAL DATA

PW (R-PDSO-G)**

PLASTIC SMALL-OUTLINE PACKAGE

14 PIN SHOWN



PINS **	8	14	16	20	24	28
DIM						
A MAX	3,10	5,10	5,10	6,60	7,90	9,80
A MIN	2,90	4,90	4,90	6,40	7,70	9,60

4040064/E 08/96

- NOTES: A. All linear dimensions are in millimeters.
 B. This drawing is subject to change without notice.
 C. Body dimensions do not include mold flash or protrusion not to exceed 0,15.
 D. Falls within JEDEC MO-153

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