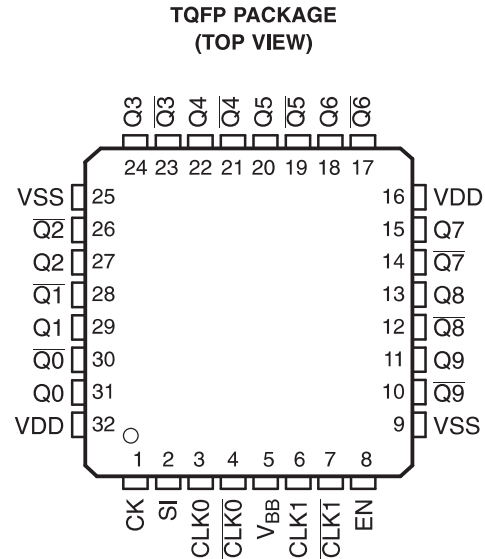


## PROGRAMMABLE LOW-VOLTAGE 1:10 LVDS CLOCK DRIVER

### FEATURES

- Low-Output Skew <30 ps (Typical) for Clock-Distribution Applications
- Distributes One Differential Clock Input to 10 LVDS Differential Clock Outputs
- $V_{CC}$  range 2.5 V  $\pm$ 5%
- Typical Signaling Rate Capability of Up to 1.1 GHz
- Configurable Register (SI/CK) Individually Enables Disables Outputs, Selectable CLK0, CLK0 or CLK1,  $\overline{\text{CLK1}}$  Inputs
- Full Rail-to-Rail Common-Mode Input Range
- Receiver Input Threshold  $\pm$ 100 mV
- Available in 32-Pin TQFP Package
- Fail-Safe I/O-Pins for  $V_{DD} = 0$  V (Power Down)



### DESCRIPTION

The CDCLVD110A clock driver distributes one pair of differential LVDS clock inputs (either CLK0 or CLK1) to 10 pairs of differential clock outputs (Q0–Q9) with minimum skew for clock distribution. The CDCLVD110A is specifically designed to drive 50- $\Omega$  transmission lines.

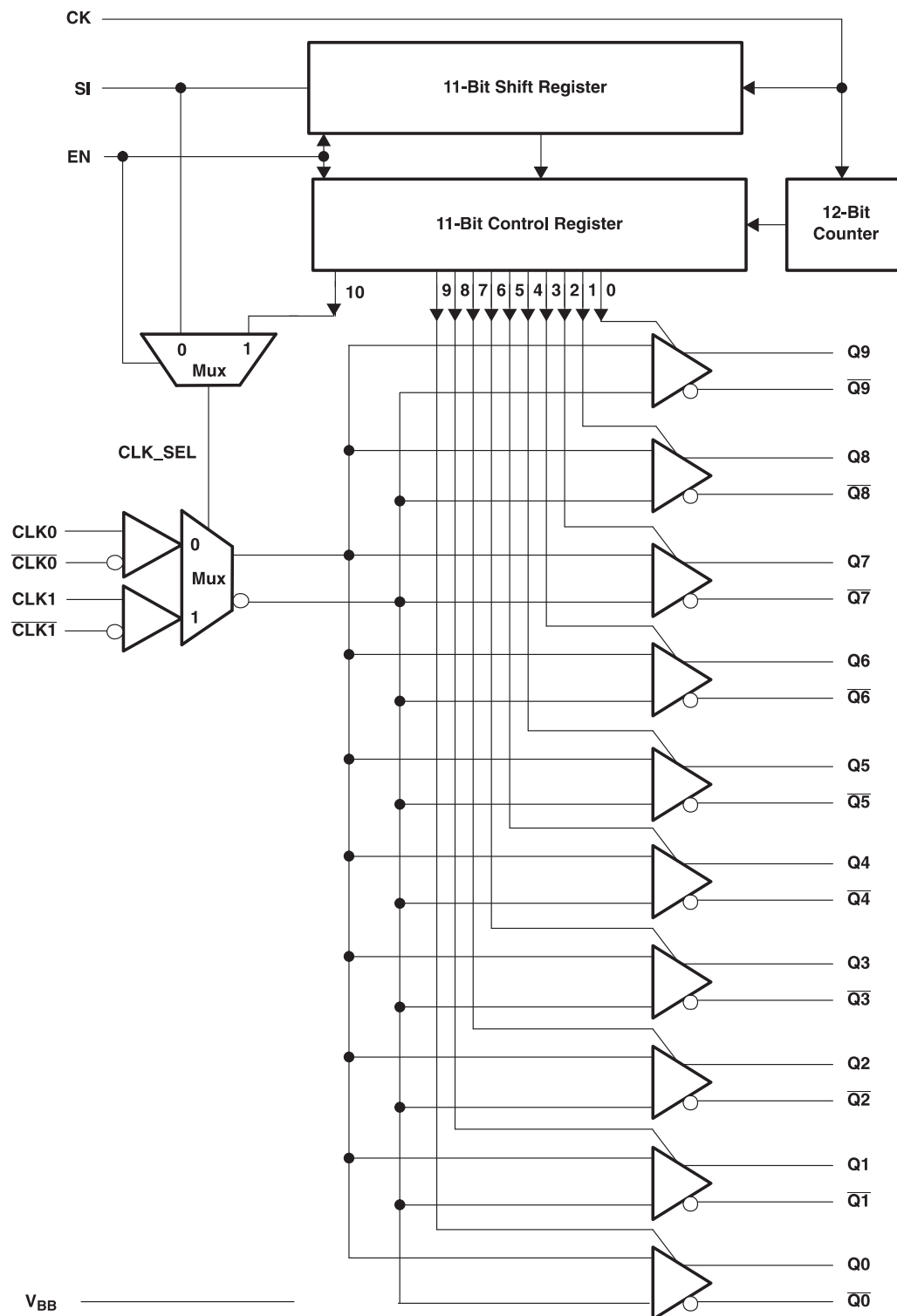
When the control enable is high ( $\text{EN} = 1$ ), the 10 differential outputs are programmable in that each output can be individually enabled/disabled (3-stated) according to the first 10 bits loaded into the shift register. Once the shift register is loaded, the last bit selects either CLK0 or CLK1 as the clock input. However, when  $\text{EN} = 0$ , the outputs are not programmable and all outputs are enabled.

The CDCLVD110A has an improved startup circuit that minimizes enabling time in AC- and DC-coupled systems.

The CDCLVD110A is characterized for operation from  $-40^{\circ}\text{C}$  to  $85^{\circ}\text{C}$ .



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**FUNCTIONAL BLOCK DIAGRAM**

## TERMINAL FUNCTIONS

TERMINAL		I/O	DESCRIPTION
NAME	NO.		
CK	1	I	Control register input clock, features a 120-k. pullup resistor
SI	2	I	Control register serial input/CLK Select, features a 120-k. pulldown resistor
CLK0	3	I	True differential input, LVDS
$\overline{\text{CLK0}}$	4	I	Complementary differential input, LVDS
V <sub>BB</sub>	5	O	Reference voltage output
CLK1	6	I	True differential input, LVDS
$\overline{\text{CLK1}}$	7	I	Complementary differential input, LVDS
EN	8	I	Control enable (for programmability), features a 120-k. pulldown resistor, input
V <sub>SS</sub>	9, 25		Device ground
V <sub>DD</sub>	16, 32		Supply voltage
Q [9:0]	11, 13, 15, 18, 20, 22, 24, 27, 29, 31	O	Clock outputs, these outputs provide low-skew copies of CLKIN
$\overline{\text{Q}}[9:0]$	10, 12, 14, 17, 19, 21, 23, 26, 28, 30	O	Complementary clock outputs, these outputs provide low-skew copies of CLKIN

## ABSOLUTE MAXIMUM RATINGS<sup>(1)</sup>

	VALUE	UNIT
V <sub>DD</sub> Supply voltage	–0.3 to 2.8	V
V <sub>I</sub> Input voltage	–0.2 to (V <sub>DD</sub> + 0.2)	V
V <sub>O</sub> VI Output voltage	–0.2 to (V <sub>DD</sub> + 0.2)	V
Q <sub>n</sub> , $\overline{\text{Q}}_n$ , I <sub>OSD</sub> Driver short circuit current	Continuous	
Electrostatic discharge (HBM 1.5 k $\Omega$ , 100 pF), ESD	>2000	V

(1) Stresses beyond those listed under *absolute maximum ratings* may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated under *recommended operating conditions* is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

## RECOMMENDED OPERATING CONDITIONS

	MIN	NOM	MAX	UNIT
V <sub>DD</sub> Supply voltage	2.375	2.5	2.625	V
V <sub>IC</sub> Receiver common-mode input voltage	0.5 V <sub>ID</sub>		V <sub>DD</sub> – 0.5 V <sub>ID</sub>	V
T <sub>A</sub> Operating free-air temperature	–40		85	°C

**ELECTRICAL CHARACTERISTICS**

over recommended operating free-air temperature range (unless otherwise noted)

PARAMETER			TEST CONDITIONS	MIN	TYP	MAX	UNIT
DRIVER							
V <sub>OD</sub>	Differential output voltage		R <sub>L</sub> = 100Ω	250	450	600	mV
ΔV <sub>OD</sub>	V <sub>OD</sub> magnitude change					50	mV
V <sub>OS</sub>	Offset voltage		– 40°C to 85 °C	0.95	1.2	1.45	V
ΔV <sub>OS</sub>	V <sub>OS</sub> magnitude change					350	mV
I <sub>OS</sub>	Output short circuit current		V <sub>O</sub> = 0 V			–20	mA
			V <sub>OD</sub>   = 0 V			20	
V <sub>BB</sub>	Reference output voltage		V <sub>DD</sub> = 2.5 V, I <sub>BB</sub> = –100 μA	1.15	1.25	1.35	V
C <sub>O</sub>	Output capacitance		V <sub>O</sub> = V <sub>DD</sub> or GND		3		pF
RECEIVER							
V <sub>IDH</sub>	Input threshold high					100	mV
V <sub>IDL</sub>	Input threshold low			–100			mV
V <sub>ID</sub>	Input differential voltage			200			mV
I <sub>IH</sub>	Input current, CLK0/CLK0, CLK1/CLK1		V <sub>I</sub> = V <sub>DD</sub>	–5		5	μA
I <sub>IL</sub>			V <sub>I</sub> = 0 V				
C <sub>I</sub>	Input capacitance		V <sub>I</sub> = V <sub>DD</sub> or GND		3		pF
SUPPLY CURRENT							
I <sub>DD</sub>	Supply current	Full loaded	All outputs enabled and loaded, R <sub>L</sub> = 100 Ω, f = 100 MHz	100		110	mA
			All outputs enabled and loaded, R <sub>L</sub> = 100 Ω, f = 800 MHz	150		160	
		No load	Outputs enabled, no output load, f = 0 Hz		35		
I <sub>DDZ</sub>		3-State	All outputs 3-state by control logic, f = 0 Hz			35	

**LVDS — SWITCHING CHARACTERISTICS**over recommended operating free-air temperature range,  $V_{DD} = 2.5\text{ V} \pm 5\%$ 

PARAMETER		FROM (INPUT)	TO (OUTPUT)	MIN	TYP	MAX	UNIT
$t_{PLH}$	Propagation delay low-to-high	CLK0, CLK0, CLK1, CLK1	$Q_n, \overline{Q_n}$		2	3	ns
$t_{PHL}$	Propagation delay high-to-low	CLK0, CLK0, CLK1, CLK1	$Q_n, \overline{Q_n}$		2	3	ns
$t_{duty}$	Duty cycle	CLK0, CLK0, CLK1, CLK1	$Q_n, \overline{Q_n}$	45%		55%	
$t_{sk(o)}$	Output skew		Any $Q_n, \overline{Q_n}$		30		ps
$t_{sk(p)}$	Pulse skew		Any $Q_n, \overline{Q_n}$			50	ps
$t_{sk(pp)}$	Part-to-part skew		Any $Q_n, \overline{Q_n}$			600	ps
$t_r$	Output rise time, 20% to 80%, $R_L = 100\Omega$ , $C_L = 5\text{ pF}$		Any $Q_n, \overline{Q_n}$			350	ps
$t_f$	Output fall time, 20% to 80%, $R_L = 100\Omega$ , $C_L = 5\text{ pF}$		Any $Q_n, \overline{Q_n}$			350	ps
$f_{clk}$	Max input frequency	CLK0, CLK0, CLK1, CLK1	Any $Q_n, \overline{Q_n}$	900	1100		MHz

## CONTROL REGISTER CHARACTERISTICS

over recommended operating free-air temperature range,  $V_{DD} = 2.5\text{ V} \pm 5\%$  (unless otherwise noted)

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
$f_{MAX}$	Maximum frequency of shift register		100	150		MHz
$t_{SU}$	Setup time, clock to SI				2	ns
$t_h$	Hold time, clock to SI				1.5	ns
$t_{removal}$	Removal time, enable to clock				1.5	ns
$t_{startup}$	Startup time after disable through SI				1.0	$\mu s$
$t_w$	Clock pulse width, minimum		3			ns
$V_{IH}$	Logic input high	$V_{DD} = 2.5\text{ V}$	2			V
$V_{IL}$	Logic input low	$V_{DD} = 2.5\text{ V}$			0.8	V
$I_{IH}$	Input current, CK pin	$V_I = V_{DD}$	-5		5	$\mu A$
	Input current, SI and EN pins		10		-30	
$I_{IL}$	Input current, CK pin	$V_I = GND$	-10		30	$\mu A$
	Input current, SI and EN pins		-5		5	

## SPECIFICATION OF CONTROL REGISTER

The CDCLVD110A has an 11-bit, serial-in shift register and an 11-bit control register. The control Register enables/disables each output clock, and selects either CLK0 or CLK1 as the input clock. The CDCLVD110A has two modes of operation:

### Programmable Mode (EN=1)

The shift register uses a serial input (SI) and a clock input (CK). Once the shift register is loaded with 11 clock pulses, the 12th clock pulse loads the control register. The first bit (bit 0) on SI enables the Q9-Q0 output pair, and the 10th bit (bit 9) enables the Q0-Q0 pair. The 11th bit (bit 10) on SI selects either CLK0 or CLK1 as the input clock; a bit value of 0 selects CLK0, whereas a bit value of 1 selects CLK1. To restart the control register configuration, a reset of the state machine must be done with a clock pulse on CK (shift register clock input) and EN set to low. The control register can be configured only once after each reset.

### Standard Mode (EN=0)

In this mode, the CDCLVD110A is not programmable and all the clock outputs are enabled. The clock input (CLK0 or CLK1) is selected with the SI pin, as is shown in the table entitled control register.

STATE-MACHINE INPUTS			
EN	SI	CK	OUTPUT
L	L	X	All outputs enabled, CLK0 selected, control register disabled, default state
L	H	X	All outputs enabled, CLK1 selected, control register disabled
H	L	↑	First stage stores L, other stage stores data of previous stage
H	H		First stage stores H, other stage stores data of previous stage
L	X		Reset of state machine, shift and control registers

CONTROL REGISTER		
BIT 10	BITS [0-9]	Q <sub>N</sub> [0-9]
L	H	CLK0
H	H	CLK1
X	L	Outputs disabled

SERIAL INPUT (SI) SEQUENCE										
BIT 10	BIT 9	BIT 8	BIT 7	BIT 6	BIT 5	BIT 4	BIT 3	BIT 2	BIT 1	BIT 0
CLK_SEL	Q0	Q1	Q2	Q3	Q4	Q5	Q6	Q7	Q8	Q9

TRUTH TABLE FOR CONTROL LOGIC									
CK	EN	SI	CLK0	CLK0	CLK1	CLK1	Q(0-9)	Q(0-9)	
L	L	L	L	H	X	X	L	H	
L	L	L	H	L	X	X	H	L	
L	L	L	Open	Open	X	X	L	H	
L	L	H	X	X	L	H	L	H	
L	L	H	X	X	H	L	H	L	
L	L	H	X	X	Open	Open	L	H	
All outputs enabled			X = Don't care						

## APPLICATION INFORMATION

### Fall-Safe Information

For  $V_{DD} = 0$  V (power-down mode) the CDCLVD110A has fail-safe input and output pins. In power-on mode, fail-safe biasing at input pins can be accomplished with a 10-k $\Omega$  pullup resistor from CLK0/CLK1 to VDD and a 10-k $\Omega$  pulldown resistor from  $\overline{\text{CLK0/CLK1}}$  to GND.

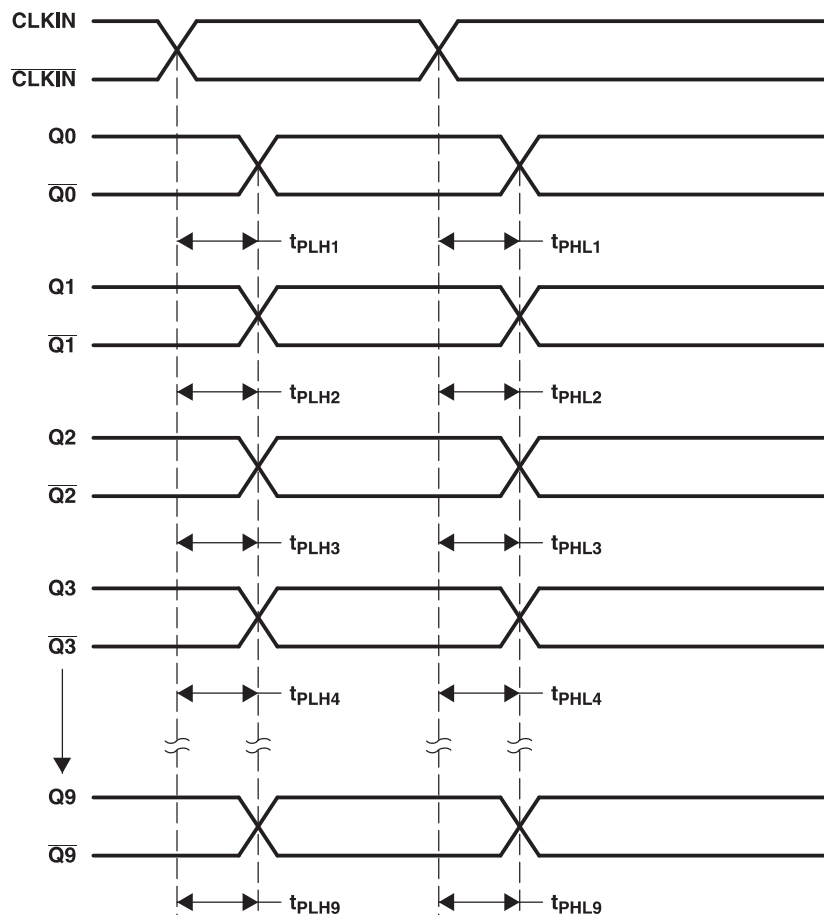
### LVDS Receiver Input Termination

The LVDS receiver inputs require 100- $\Omega$  termination resistors placed as close as possible across the input pins.

### Control Inputs Termination

No external termination is required. The CK control input has an internal 120-k $\Omega$  pullup resistor, while the SI– and EN–control inputs each have an internal 120-k $\Omega$  pulldown resistor. If the control pins are left open per the default, all outputs are enabled, CLK0,  $\overline{\text{CLK0}}$  is selected, and the control register is disabled.

## PARAMETER MEASUREMENT INFORMATION



- A. Output skew,  $t_{\text{sk(o)}}$ , is calculated as the greater of:
  - The difference between the fastest and the slowest  $t_{\text{PLH}n}$  ( $n = 1, 2, \dots, 10$ )
  - The difference between the fastest and the slowest  $t_{\text{PHL}n}$  ( $n = 1, 2, \dots, 10$ )
- B. Part-to-part skew,  $t_{\text{sk(pp)}}$ , is calculated as the greater of:
  - The difference between the fastest and the slowest  $t_{\text{PLH}n}$  ( $n = 1, 2, \dots, 10$ ) across multiple devices
  - The difference between the fastest and the slowest  $t_{\text{PHL}n}$  ( $n = 1, 2, \dots, 10$ ) across multiple devices
- C. Pulse skew,  $t_{\text{sk(p)}}$ , is calculated as the magnitude of the absolute time difference between the high-to-low ( $t_{\text{PHL}}$ ) and the low-to-high ( $t_{\text{PLH}}$ ) propagation delays when a single switching input causes one or more outputs to switch,  $t_{\text{sk(p)}} = |t_{\text{PHL}} - t_{\text{PLH}}|$ . Pulse skew is sometimes referred to as pulse-width distortion or duty-cycle skew.

Figure 1. Waveforms for Calculation of  $t_{\text{sk(o)}}$  and  $t_{\text{sk(pp)}}$



PARAMETER MEASUREMENT INFORMATION (continued)

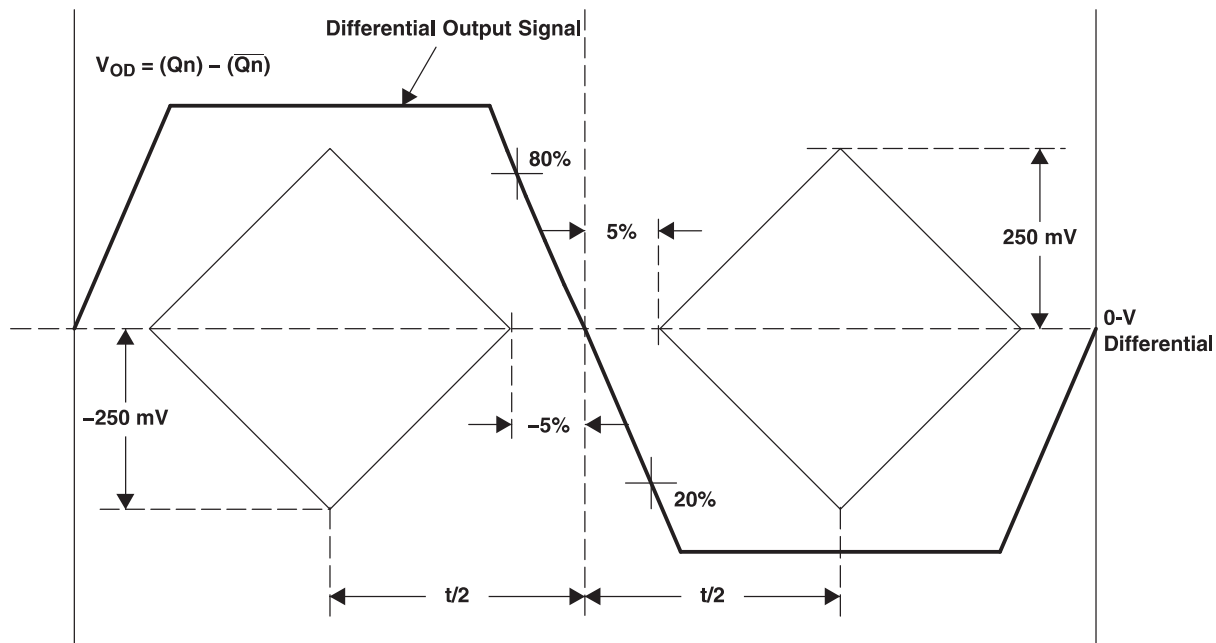


Figure 2. Test Criteria for  $f_{clk}$ , Duty Cycle,  $t_r$ ,  $t_f$ ,  $V_{OD}$

## PACKAGING INFORMATION

Orderable Device	Status <sup>(1)</sup>	Package Type	Package Drawing	Pins	Package Qty	Eco Plan <sup>(2)</sup>	Lead/Ball Finish	MSL Peak Temp <sup>(3)</sup>
CDCLVD110AVF	ACTIVE	LQFP	VF	32	250	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-1-260C-UNLIM
CDCLVD110AVFG4	ACTIVE	LQFP	VF	32	250	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-1-260C-UNLIM
CDCLVD110AVFR	ACTIVE	LQFP	VF	32	1000	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-1-260C-UNLIM
CDCLVD110AVFRG4	ACTIVE	LQFP	VF	32	1000	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-1-260C-UNLIM

<sup>(1)</sup> The marketing status values are defined as follows:

**ACTIVE:** Product device recommended for new designs.

**LIFEBUY:** TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

**NRND:** Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

**PREVIEW:** Device has been announced but is not in production. Samples may or may not be available.

**OBSOLETE:** TI has discontinued the production of the device.

<sup>(2)</sup> Eco Plan - The planned eco-friendly classification: Pb-Free (RoHS), Pb-Free (RoHS Exempt), or Green (RoHS & no Sb/Br) - please check <http://www.ti.com/productcontent> for the latest availability information and additional product content details.

**TBD:** The Pb-Free/Green conversion plan has not been defined.

**Pb-Free (RoHS):** TI's terms "Lead-Free" or "Pb-Free" mean semiconductor products that are compatible with the current RoHS requirements for all 6 substances, including the requirement that lead not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, TI Pb-Free products are suitable for use in specified lead-free processes.

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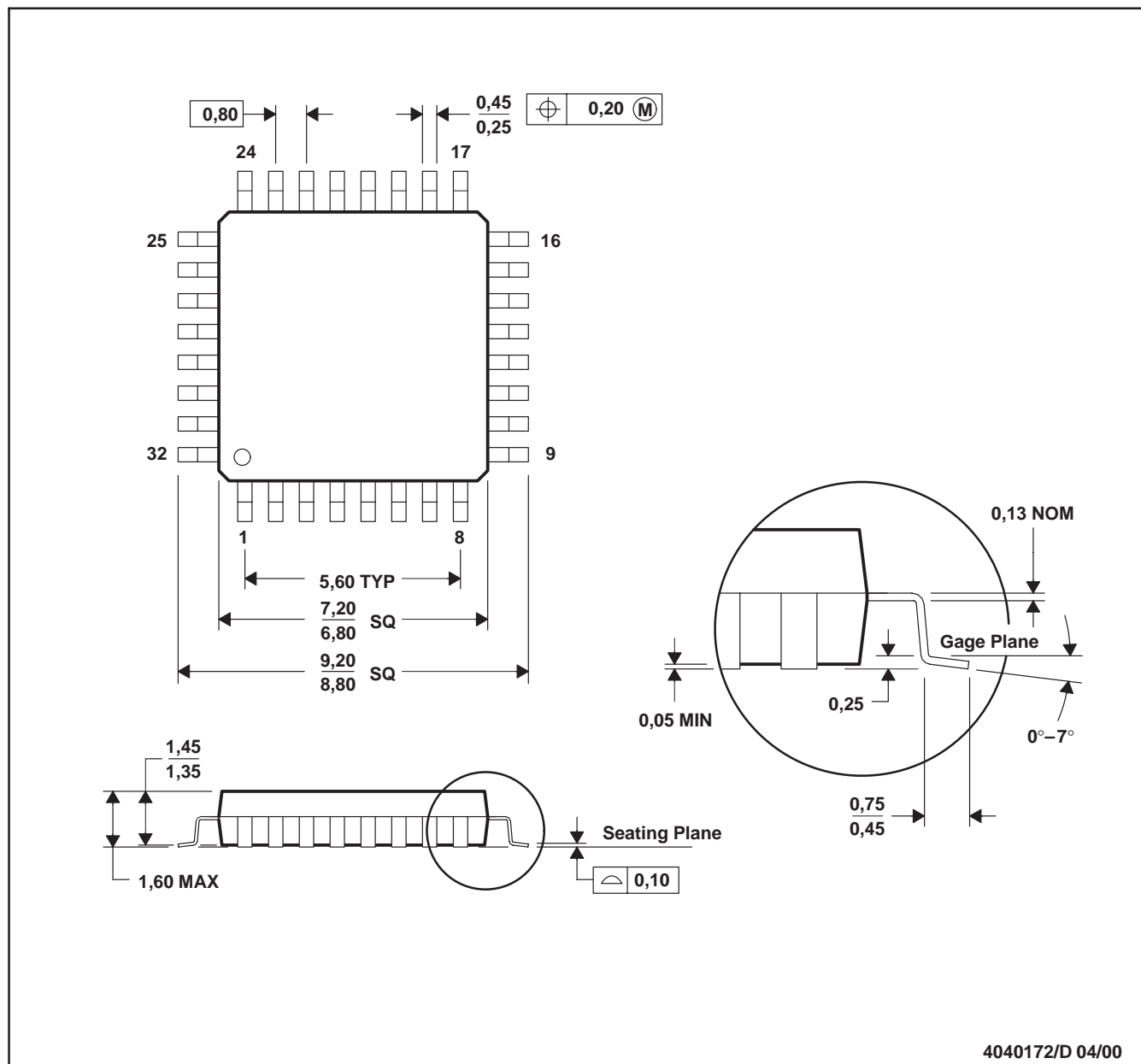
<sup>(3)</sup> MSL, Peak Temp. -- The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

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## VF (S-PQFP-G32)

## PLASTIC QUAD FLATPACK



- NOTES: A. All linear dimensions are in millimeters.  
 B. This drawing is subject to change without notice.

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