

# Dual Synchronous, Fixed Output 2.25MHz Step-Down DC/DC Regulator

## FEATURES

- **High Efficiency: Up to 95%**
- **1.8V at 800mA/1.575V at 400mA**
- **Very Low Quiescent Current: Only 40μA**
- **2.25MHz Constant Frequency Operation**
- **High Switch Current: 1.2A and 0.7A**
- **No Schottky Diodes Required**
- **V<sub>IN</sub>: 2.5V to 5.5V**
- **Current Mode Operation for Excellent Line and Load Transient Response**
- **Short-Circuit Protected**
- **Low Dropout Operation: 100% Duty Cycle**
- **Ultralow Shutdown Current: I<sub>Q</sub> < 1μA**
- **Small Thermally Enhanced 3mm × 3mm DFN Packages**

## APPLICATIONS

- PDAs/Palmtop PCs
- Digital Cameras
- Cellular Phones
- Portable Media Players
- PC Cards
- Wireless and DSL Modems

## DESCRIPTION

The LTC®3548-1 is a dual, fixed output, constant frequency, synchronous step-down DC/DC converter. Intended for low power applications, it operates from 2.5V to 5.5V input voltage range and has a constant 2.25MHz switching frequency, allowing the use of tiny, low cost capacitors and inductors with a profile ≤1mm. The output voltage for channel 1 is fixed at 1.8V and for channel 2 is fixed at 1.575V. Internal synchronous 0.35Ω, 1.2A/0.7A power switches provide high efficiency without the need for external Schottky diodes. Burst Mode® operation provides high efficiency at light loads.

To further maximize battery runtime, the P-channel MOSFETs are turned on continuously in dropout (100% duty cycle), and both channels draw a total quiescent current of only 40μA. In shutdown, the device draws <1μA.

The LTC3548-1 is available in both thin (0.75mm) and ultra-thin (0.55mm) 3mm × 3mm DFN packages.

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## TYPICAL APPLICATION

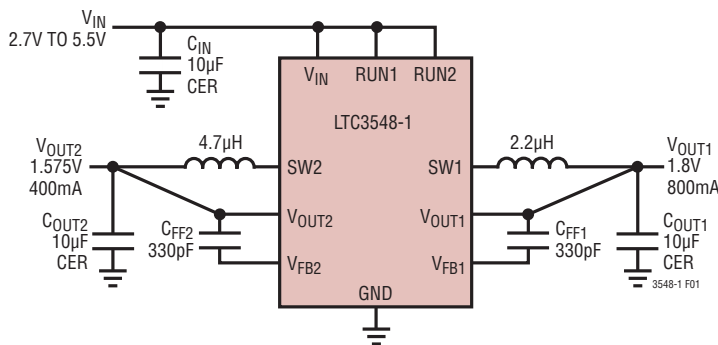
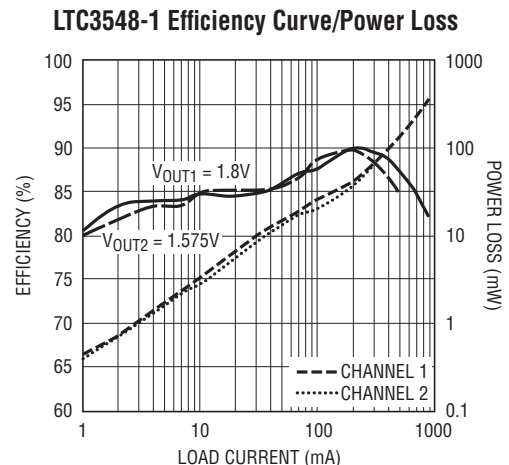


Figure 1. 1.8V/1.575V at 800mA/400mA Step-Down Regulators



35481 F01b

# LTC3548-1

## ABSOLUTE MAXIMUM RATINGS (Note 1)

|   |                          |                                     |               |                |
|---|--------------------------|-------------------------------------|---------------|----------------|
| $V_{IN}$ Voltages .....                           | –0.3V to 6V              | Ambient Operating Temperature Range | (Note 2)..... | –40°C to 85°C  |
| $V_{FB1}$ , $V_{FB2}$ , $V_{OUT1}$ , $V_{OUT2}$ , |                          | Junction Temperature (Note 5) ..... |               | 125°C          |
| RUN1, RUN2 Voltages .....                         | –0.3V to $V_{IN} + 0.3V$ | Storage Temperature Range.....      |               | –65°C to 125°C |
| SW1, SW2 Voltage.....                             | –0.3V to $V_{IN} + 0.3V$ |                                     |               |                |

## PIN CONFIGURATION

|   |  |
|---|--|
| <p>TOP VIEW</p> <p>DD PACKAGE<br/>10-LEAD (3mm × 3mm) PLASTIC DFN</p> <p><math>T_{JMAX} = 125^{\circ}C</math>, <math>\theta_{JA} = 40^{\circ}C/W</math>, <math>\theta_{JC} = 3^{\circ}C/W</math><br/>EXPOSED PAD (PIN 11) IS GND, MUST BE SOLDERED TO PCB GND<br/>(SOLDERED TO A 4-LAYER BOARD)</p> | <p>TOP VIEW</p> <p>KD PACKAGE<br/>10-LEAD (3mm × 3mm) PLASTIC UTDFN</p> <p><math>T_{JMAX} = 125^{\circ}C</math>, <math>\theta_{JA} = 43^{\circ}C/W</math>, <math>\theta_{JC} = 10^{\circ}C/W</math><br/>EXPOSED PAD (PIN 11) IS GND, MUST BE SOLDERED TO PCB GND<br/>(SOLDERED TO A 4-LAYER BOARD)</p> |
|---|--|

## ORDER INFORMATION

| LEAD FREE FINISH | TAPE AND REEL      | PART MARKING | PACKAGE DESCRIPTION               | TEMPERATURE RANGE |
|------------------|--------------------|--------------|-----------------------------------|-------------------|
| LTC3548EDD-1#PBF | LTC3548EDD-1#TRPBF | LBZC         | 10-Lead (3mm × 3mm) Plastic DFN   | –40°C to 85°C     |
| LTC3548EKD-1#PBF | LTC3548EKD-1#TRPBF | CXVT         | 10-Lead (3mm × 3mm) Plastic UTDFN | –40°C to 85°C     |

Consult LTC Marketing for parts specified with wider operating temperature ranges.

Consult LTC Marketing for information on non-standard lead based finish parts.

For more information on lead free part marking, go to: <http://www.linear.com/leadfree/>

For more information on tape and reel specifications, go to: <http://www.linear.com/tapeandreel/>

## ELECTRICAL CHARACTERISTICS

The ● denotes the specifications which apply over the full operating temperature range, otherwise specifications are at  $T_A = 25^\circ\text{C}$ .  $V_{IN} = 3.6\text{V}$ , unless otherwise specified. (Note 2)

| SYMBOL                 | PARAMETER  | CONDITIONS  |   | MIN            | TYP              | MAX            | UNITS          |
|------------------------|--|---|---|----------------|------------------|----------------|----------------|
| V <sub>IN</sub>        | Operating Voltage Range  |   | ● | 2.5            |                  | 5.5            | V              |
| V <sub>OUT1</sub>      | Output Voltage   | 0°C ≤ T <sub>A</sub> ≤ 85°C (Note 3)<br>−40°C ≤ T <sub>A</sub> ≤ 85°C (Note 3)  | ● | 1.764<br>1.755 | 1.8<br>1.8       | 1.836<br>1.836 | V<br>V         |
| V <sub>OUT2</sub>      | Output Voltage   | 0°C ≤ T <sub>A</sub> ≤ 85°C (Note 3)<br>−40°C ≤ T <sub>A</sub> ≤ 85°C (Note 3)  | ● | 1.544<br>1.536 | 1.575<br>1.575   | 1.607<br>1.607 | V<br>V         |
| ΔV <sub>LINE REG</sub> | Reference Voltage Line Regulation  | V <sub>IN</sub> = 2.5V to 5.5V (Note 3)   |   |                | 0.3              | 0.5            | %/V            |
| ΔV <sub>LOAD REG</sub> | Output Voltage Load Regulation   | (Note 3)  |   |                | 0.5              |                | %              |
| I <sub>S</sub>         | Input DC Supply Current<br>Active Mode<br>Sleep Mode<br>Shutdown           | V <sub>OUT1</sub> = 1.5V, V <sub>OUT2</sub> = 1.3V<br>V <sub>OUT1</sub> = 1.9V, V <sub>OUT2</sub> = 1.65V<br>RUN = 0V, V <sub>IN</sub> = 5.5V |   |                | 700<br>40<br>0.1 | 950<br>60<br>1 | μA<br>μA<br>μA |
| f <sub>OSC</sub>       | Oscillator Frequency   | V <sub>OUT1</sub> = 1.8V, V <sub>OUT2</sub> = 1.575V  | ● | 1.8            | 2.25             | 2.7            | MHz            |
| I <sub>LIM</sub>       | Peak Switch Current Limit Channel 1<br>Peak Switch Current Limit Channel 2 | V <sub>IN</sub> = 3V, Duty Cycle <35%<br>V <sub>IN</sub> = 3V, Duty Cycle <35%  |   | 0.95<br>0.6    | 1.2<br>0.7       | 1.6<br>0.9     | A<br>A         |
| R <sub>DS(ON)</sub>    | Top Switch On-Resistance<br>Bottom Switch On-Resistance                    | (Note 6)<br>(Note 6)  |   |                | 0.35<br>0.30     | 0.45<br>0.45   | Ω<br>Ω         |
| I <sub>SW(LKG)</sub>   | Switch Leakage Current   | V <sub>IN</sub> = 5V, V <sub>RUN</sub> = 0V, V <sub>OUT1</sub> = V <sub>OUT2</sub> = 0  |   |                | 0.01             | 1              | μA             |
| V <sub>RUN</sub>       | RUN Threshold  |   | ● | 0.3            | 1                | 1.5            | V              |
| I <sub>RUN</sub>       | RUN Leakage Current  |   | ● |                | 0.01             | 1              | μA             |

**Note 1:** Stresses beyond those listed under Absolute Maximum Ratings may cause permanent damage to the device. Exposure to any Absolute Maximum Rating condition for extended periods may affect device reliability and lifetime.

**Note 2:** The LTC3548-1 is guaranteed to meet specified performance from  $0^\circ\text{C}$  to  $85^\circ\text{C}$ . Specifications over the  $-40^\circ\text{C}$  and  $85^\circ\text{C}$  operating temperature range are assured by design, characterization and correlation with statistical process controls.

**Note 3:** The LTC3548-1 is tested in a proprietary test mode that connects the output of the error amplifier to an outside servo-loop.

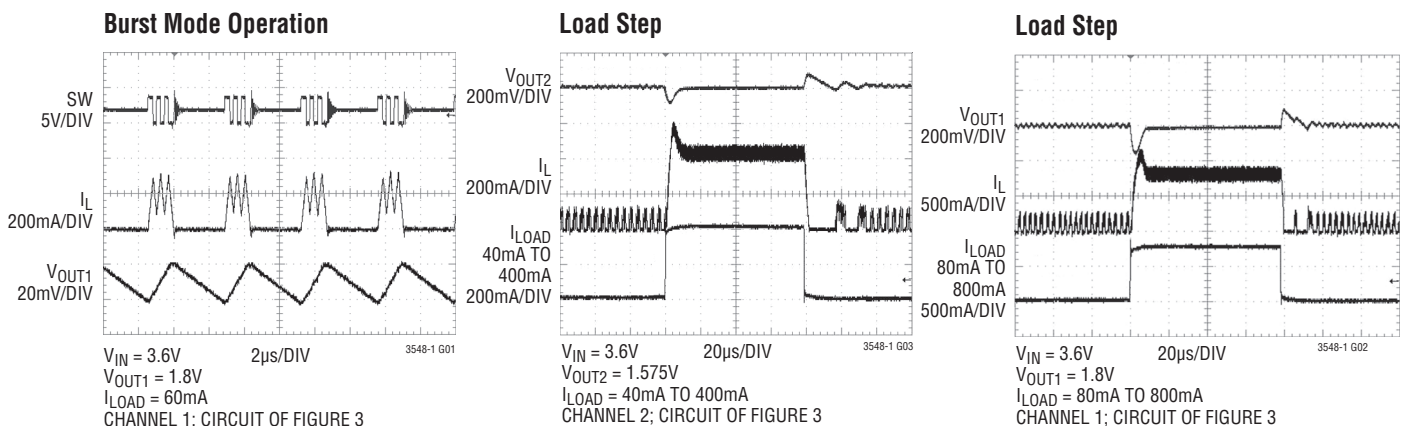
**Note 4:** Dynamic supply current is higher due to the internal gate charge being delivered at the switching frequency.

**Note 5:**  $T_J$  is calculated from the ambient  $T_A$  and power dissipation  $P_D$  according to the following formula:  $T_J = T_A + (P_D \cdot \theta_{JA})$ .

**Note 6:** The DFN switch on-resistance is guaranteed by correlation to wafer level measurements.

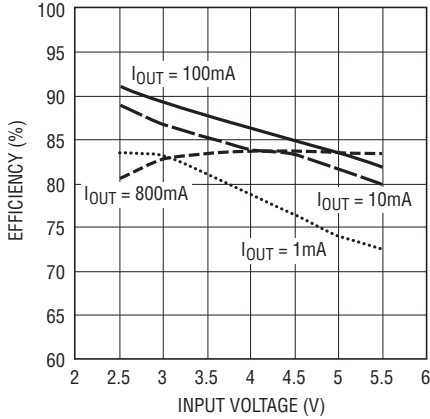
## TYPICAL PERFORMANCE CHARACTERISTICS

$T_A = 25^\circ\text{C}$  unless otherwise specified.



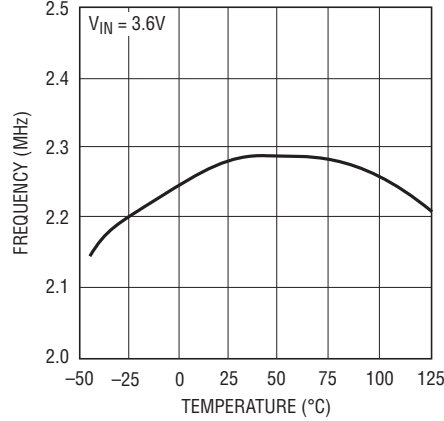
## TYPICAL PERFORMANCE CHARACTERISTICS $T_A = 25^\circ\text{C}$ unless otherwise specified.

Efficiency vs Input Voltage



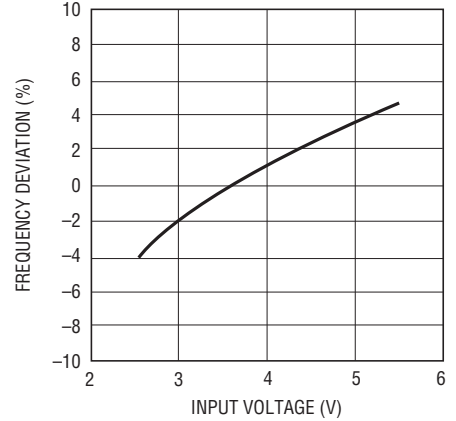
3548-1 G04

Oscillator Frequency vs Temperature



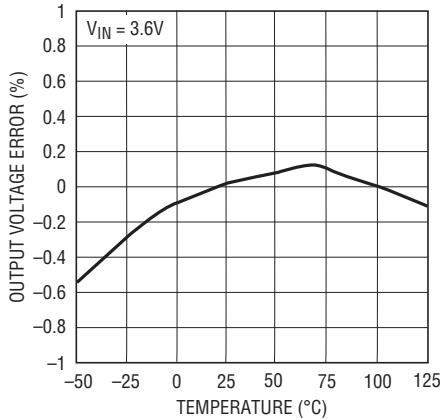
3548-1 G05

Oscillator Frequency vs Input Voltage



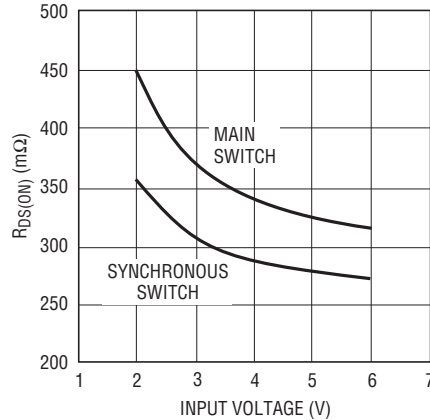
3548-1 G06

Output Voltage Error vs Temperature



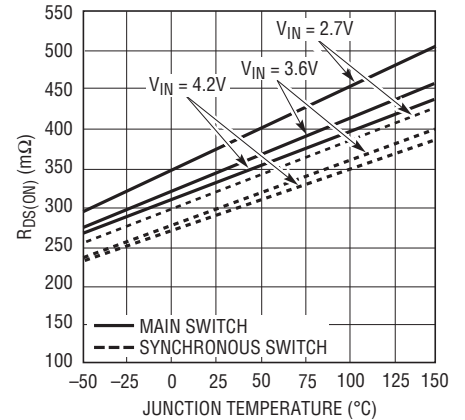
3548-1 G07

$R_{DS(ON)}$  vs Input Voltage



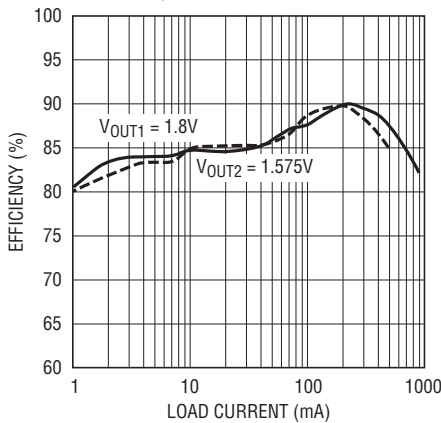
3548-1 G08

$R_{DS(ON)}$  vs Junction Temperature



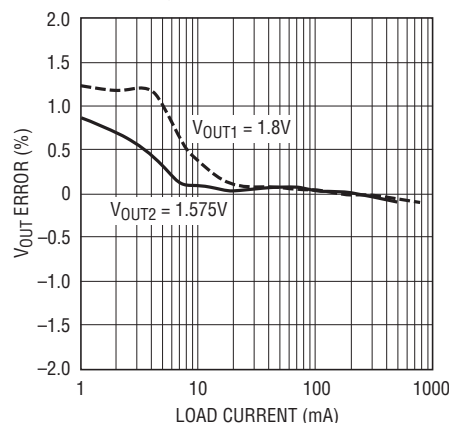
3548-1 G09

Efficiency vs Load Current



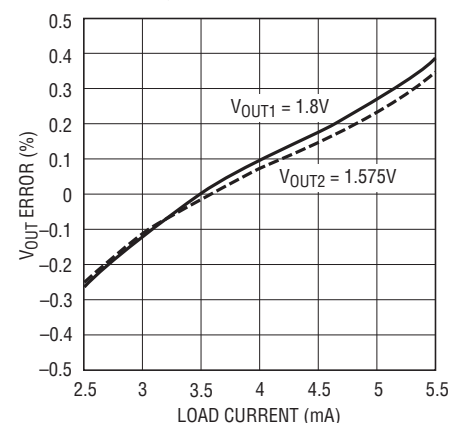
3548-1 G11

Load Regulation



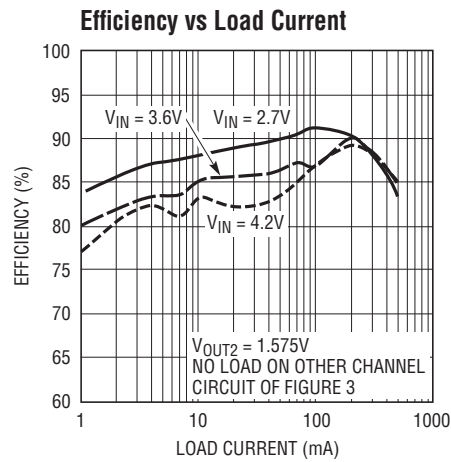
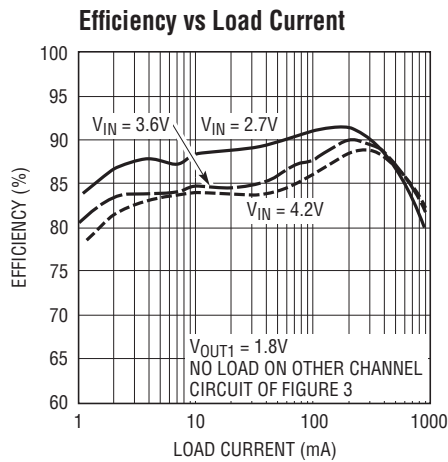
3548-1 G12

Line Regulation



3548-1 G15

## TYPICAL PERFORMANCE CHARACTERISTICS $T_A = 25^\circ\text{C}$ unless otherwise specified.



## PIN FUNCTIONS

**V<sub>FB1</sub> (Pin 1):** Output Feedback for Channel 1. Receives the feedback voltage from internal resistive divider across the output. Normal voltage for this pin is 0.6V.

**V<sub>OUT1</sub> (Pin 2):** Output Voltage Feedback Pin for Channel 1. An internal resistive divider divides the output voltage down for comparison to the internal reference voltage.

**V<sub>IN</sub> (Pin 3):** Input Power Supply. Must be closely decoupled to GND.

**SW1 (Pin 4):** Regulator 1 Switch Node Connection to the Inductor. This pin swings from V<sub>IN</sub> to GND.

**GND (Pin 5):** Ground. Connect to the (–) terminal of C<sub>OUT</sub> and (–) terminal of C<sub>IN</sub> (see Figure 4).

**RUN2 (Pin 6):** Regulator 2 Enable. Forcing this pin to V<sub>IN</sub> enables regulator 2, while forcing it to GND causes regulator 2 to shut down. This pin must be driven; do not float.

**SW2 (Pin 7):** Regulator 2 Switch Node Connection to the Inductor. This pin swings from V<sub>IN</sub> to GND.

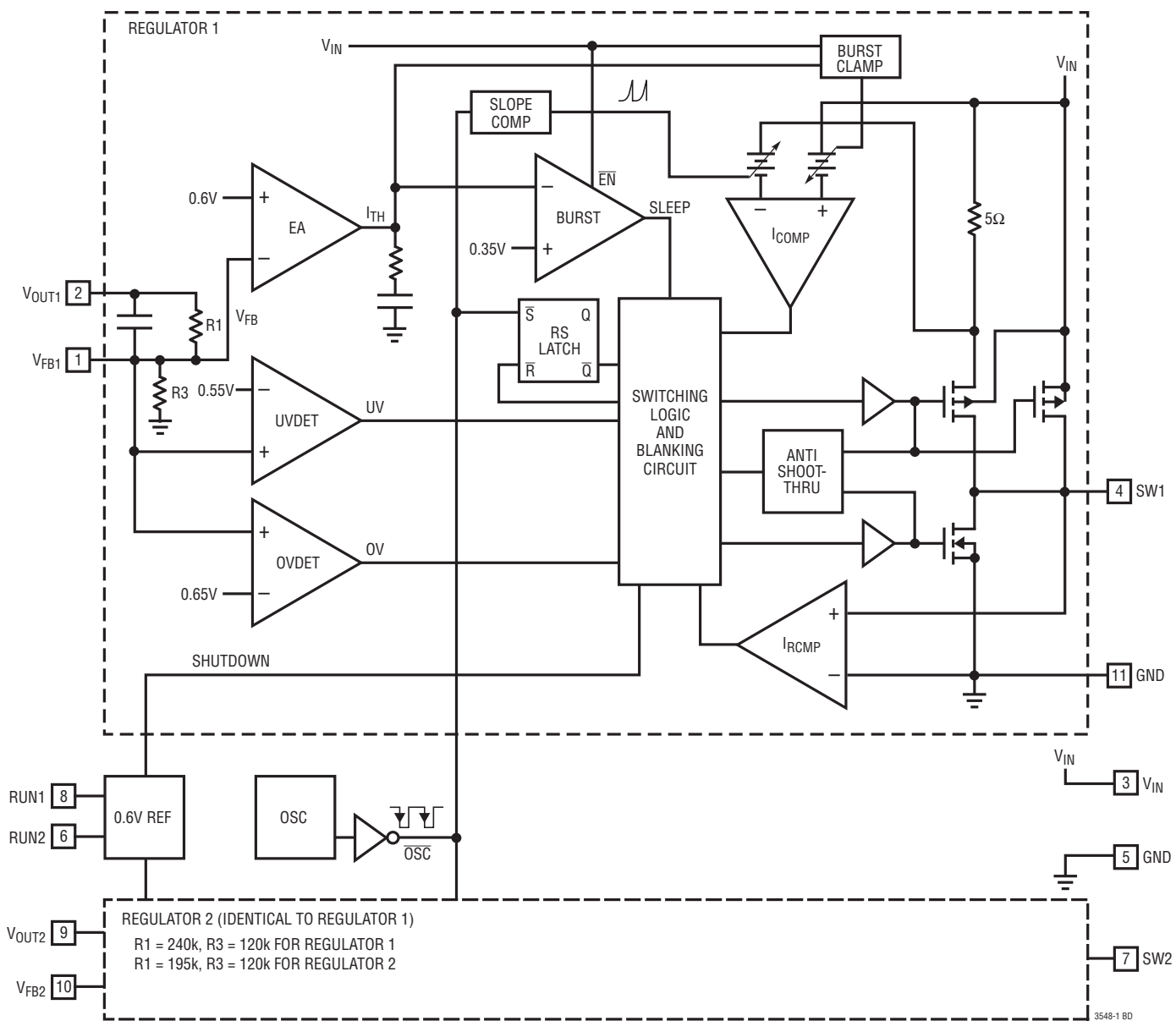
**RUN1 (Pin 8):** Regulator 1 Enable. Forcing this pin to V<sub>IN</sub> enables regulator 1, while forcing it to GND causes regulator 1 to shut down. This pin must be driven; do not float.

**V<sub>OUT2</sub> (Pin 9):** Output Voltage Feedback Pin for Channel 2. An internal resistive divider divides the output voltage down for comparison to the internal reference voltage.

**V<sub>FB2</sub> (Pin 10):** Output Feedback for Channel 2. Receives the feedback voltage from internal resistive divider across the output. Normal voltage for this pin is 0.6V.

**Exposed Pad (GND) (Pin 11):** Ground. Connect to the (–) terminal of C<sub>OUT</sub>, and (–) terminal of C<sub>IN</sub>. Must be connected to electrical ground on PCB (see Figure 4).

BLOCK DIAGRAM



3548-1 BD

## OPERATION

The LTC3548-1 uses a constant frequency, current mode architecture. The operating frequency is set at 2.25MHz. Both channels share the same clock and run in-phase.

The output voltage is set by an internal divider. An error amplifier compares the divided output voltage with a reference voltage of 0.6V and adjusts the peak inductor current accordingly.

### Main Control Loop

During normal operation, the top power switch (P-channel MOSFET) is turned on at the beginning of a clock cycle when the  $V_{OUT}$  voltage is below the regulated voltage. The current flows into the inductor and the load increases until current limit is reached. The switch turns off and energy stored in the inductor flows through the bottom switch (N-channel MOSFET) into the load until the next clock cycle.

The peak inductor current is controlled by the internally compensated  $I_{TH}$  voltage, which is the output of the error amplifier. This amplifier compares the feedback voltage  $V_{FB}$  to the 0.6V reference (see Block Diagram). When the load current increases, the  $V_{FB}$  voltage decreases slightly below the reference. This decrease causes the error amplifier to increase the  $I_{TH}$  voltage until the average inductor current matches the new load current.

The main control loop is shut down by pulling the RUN pin to ground.

### Low Current Operation

When the load is relatively light, the LTC3548-1 automatically switches into Burst Mode operation, in which the PMOS switch operates intermittently based on load demand with a fixed peak inductor current. By running cycles periodically, the switching losses which are dominated by the gate charge losses of the power MOSFETs are minimized. The main control loop is interrupted when the output voltage reaches the desired regulated value. A voltage comparator trips when  $I_{TH}$  is below 0.35V, shutting off the switch and reducing the power. The output capacitor and the inductor supply the power to the load until  $I_{TH}$  exceeds 0.65V, turning on the switch and the main control loop which starts another cycle.

### Dropout Operation

When the input supply voltage decreases toward the output voltage, the duty cycle increases to 100% which is the dropout condition. In dropout, the PMOS switch is turned on continuously with the output voltage being equal to the input voltage minus the voltage drops across the internal p-channel MOSFET and the inductor.

An important design consideration is that the  $R_{DS(ON)}$  of the P-channel switch increases with decreasing input supply voltage (see Typical Performance Characteristics). Therefore, the user should calculate the power dissipation when the LTC3548-1 is used at 100% duty cycle with low input voltage (see Thermal Considerations in the Applications Information section).

### Low Supply Operation

To prevent unstable operation, the LTC3548-1 incorporates an undervoltage lockout circuit which shuts down the part when the input voltage drops below about 1.65V.



## APPLICATIONS INFORMATION

A general LTC3548-1 application circuit is shown in Figure 2. External component selection is driven by the load requirement, and begins with the selection of the inductor L. Once the inductor is chosen,  $C_{IN}$  and  $C_{OUT}$  can be selected.

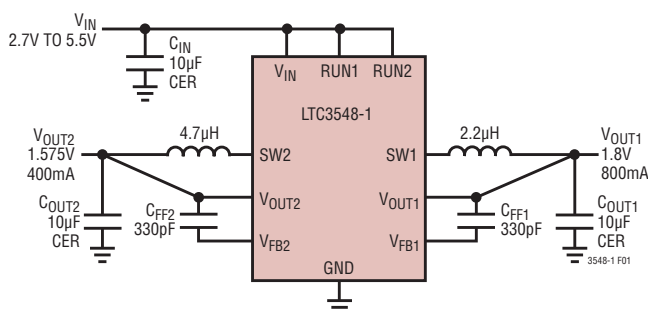


Figure 2. LTC3548-1 General Schematic

### Inductor Selection

Although the inductor does not influence the operating frequency, the inductor value has a direct effect on ripple current. The inductor ripple current  $\Delta I_L$  decreases with higher inductance and increases with higher  $V_{IN}$  or  $V_{OUT}$ :

$$\Delta I_L = \frac{V_{OUT}}{f_0 \cdot L} \cdot \left( 1 - \frac{V_{OUT}}{V_{IN}} \right)$$

Accepting larger values of  $\Delta I_L$  allows the use of low inductances, but results in higher output voltage ripple, greater core losses, and lower output current capability.

A reasonable starting point for setting ripple current is  $\Delta I_L = 0.3 \cdot I_{OUT(MAX)}$ , where  $I_{OUT(MAX)}$  is 0.8A for channel 1 and 400mA for channel 2. The largest ripple current  $\Delta I_L$  occurs at the maximum input voltage. To guarantee that the ripple current stays below a specified maximum, the inductor value should be chosen according to the following equation:

$$L = \frac{V_{OUT}}{f_0 \cdot \Delta I_L} \cdot \left( 1 - \frac{V_{OUT}}{V_{IN(MAX)}} \right)$$

The inductor value will also have an effect on Burst Mode operation. The transition from low current operation begins when the peak inductor current falls below a level set by the burst clamp. Lower inductor values result in

higher ripple current which causes this to occur at lower load currents. This causes a dip in efficiency in the upper range of low current operation. In Burst Mode operation, lower inductance values will cause the burst frequency to increase.

### Inductor Core Selection

Different core materials and shapes will change the size/current and price/current relationship of an inductor. Toroid or shielded pot cores in ferrite or permalloy materials are small and don't radiate much energy, but generally cost more than powdered iron core inductors with similar electrical characteristics. The choice of which style inductor to use often depends more on the price vs size requirements and any radiated field/EMI requirements than on what the LTC3548-1 requires to operate. Table 1 shows some typical surface mount inductors that work well in LTC3548-1 applications.

Table 1. Representative Surface Mount Inductors

| PART NUMBER      | VALUE (µH) | DCR (Ω MAX) | MAX DC CURRENT (A) | SIZE W × L × H (mm <sup>3</sup> ) |
|------------------|------------|-------------|--------------------|-----------------------------------|
| Sumida CDRH3D16  | 2.2        | 0.075       | 1.20               | 3.8 × 3.8 × 1.8                   |
|                  | 3.3        | 0.110       | 1.10               |                                   |
|                  | 4.7        | 0.162       | 0.90               |                                   |
| Sumida CMD4D06   | 2.2        | 0.089       | 0.95               | 4.1 × 3.2 × 0.8                   |
|                  | 4.7        | 0.166       | 0.75               |                                   |
| Sumida CMD4D11   | 2.2        | 0.116       | 0.950              | 4.4 × 5.8 × 1.2                   |
|                  | 3.3        | 0.174       | 0.770              |                                   |
| Murata LQH32CN   | 1.0        | 0.060       | 1.00               | 2.5 × 3.2 × 2.0                   |
|                  | 2.2        | 0.097       | 0.79               |                                   |
| Toko D312F       | 2.2        | 0.060       | 1.08               | 2.5 × 3.2 × 2.0                   |
|                  | 3.3        | 0.260       | 0.92               |                                   |
| Panasonic ELT5KT | 3.3        | 0.17        | 1.00               | 4.5 × 5.4 × 1.2                   |
|                  | 4.7        | 0.20        | 0.95               |                                   |

### Input Capacitor ( $C_{IN}$ ) Selection

In continuous mode, the input current of the converter is a square wave with a duty cycle of approximately  $V_{OUT}/V_{IN}$ . To prevent large voltage transients, a low equivalent series resistance (ESR) input capacitor sized for the maximum RMS current must be used. The maximum RMS capacitor current is given by:

$$I_{RMS} \approx I_{MAX} \frac{\sqrt{V_{OUT}(V_{IN} - V_{OUT})}}{V_{IN}}$$



## APPLICATIONS INFORMATION

where the maximum average output current  $I_{MAX}$  equals the peak current minus half the peak-to-peak ripple current,  $I_{MAX} = I_{LIM} - \Delta I_L/2$ .

This formula has a maximum at  $V_{IN} = 2V_{OUT}$ , where  $I_{RMS} = I_{OUT}/2$ . This simple worst-case is commonly used to design because even significant deviations do not offer much relief. Note that capacitor manufacturer's ripple current ratings are often based on only 2000 hours lifetime. This makes it advisable to further derate the capacitor, or choose a capacitor rated at a higher temperature than required. Several capacitors may also be paralleled to meet the size or height requirements of the design. An additional 0.1 $\mu$ F to 1 $\mu$ F ceramic capacitor is also recommended on  $V_{IN}$  for high frequency decoupling, when not using an all ceramic capacitor solution.

### Output Capacitor ( $C_{OUT}$ ) Selection

The selection of  $C_{OUT}$  is driven by the required ESR to minimize voltage ripple and load step transients. Typically, once the ESR requirement is satisfied, the capacitance is adequate for filtering. The output ripple ( $\Delta V_{OUT}$ ) is determined by:

$$\Delta V_{OUT} \approx \Delta I_L \left( \text{ESR} + \frac{1}{8f_0 C_{OUT}} \right)$$

where  $f_0$  = operating frequency,  $C_{OUT}$  = output capacitance and  $\Delta I_L$  = ripple current in the inductor. The output ripple is highest at maximum input voltage since  $\Delta I_L$  increases with input voltage. With  $\Delta I_L = 0.3 \cdot I_{OUT(MAX)}$  the output ripple will be less than 100mV at maximum  $V_{IN}$  and  $f_0 = 2.25\text{MHz}$  with:

$$\text{ESR}_{C_{OUT}} < 150\text{m}\Omega$$

Once the ESR requirements for  $C_{OUT}$  have been met, the RMS current rating generally far exceeds the  $I_{RIPPLE(P-P)}$  requirement, except for an all ceramic solution.

In surface mount applications, multiple capacitors may have to be paralleled to meet the capacitance, ESR or RMS current handling requirement of the application. Aluminum electrolytic, special polymer, ceramic and dry tantalum capacitors are all available in surface mount packages. The OS-CON semiconductor dielectric capacitor available from Sanyo has the lowest ESR(size) product

of any aluminum electrolytic at a somewhat higher price. Special polymer capacitors, such as Sanyo POSCAP, Panasonic Special Polymer (SP), and Kemet A700, offer very low ESR, but have a lower capacitance density than other types. Tantalum capacitors have the highest capacitance density, but they have a larger ESR and it is critical that the capacitors are surge tested for use in switching power supplies. An excellent choice is the AVX TPS series of surface mount tantalums, available in case heights ranging from 2mm to 4mm. Aluminum electrolytic capacitors have a significantly larger ESR, and are often used in extremely cost-sensitive applications provided that consideration is given to ripple current ratings and long term reliability. Ceramic capacitors have the lowest ESR and cost, but also have the lowest capacitance density, a high voltage and temperature coefficient, and exhibit audible piezoelectric effects. In addition, the high Q of ceramic capacitors along with trace inductance can lead to significant ringing.

In most cases, 0.1 $\mu$ F to 1 $\mu$ F of ceramic capacitors should also be placed close to the LTC3548-1 in parallel with the main capacitors for high frequency decoupling.

### Ceramic Input and Output Capacitors

Higher value, lower cost ceramic capacitors are now becoming available in smaller case sizes. These are tempting for switching regulator use because of their very low ESR. Unfortunately, the ESR is so low that it can cause loop stability problems. Solid tantalum capacitor ESR generates a loop "zero" at 5kHz to 50kHz that is instrumental in giving acceptable loop phase margin. Ceramic capacitors remain capacitive to beyond 300kHz and usually resonate with their ESL before ESR becomes effective. Also, ceramic caps are prone to temperature effects which requires the designer to check loop stability over the operating temperature range. To minimize their large temperature and voltage coefficients, only X5R or X7R ceramic capacitors should be used. A good selection of ceramic capacitors is available from Taiyo Yuden, AVX, Kemet, TDK, and Murata.

Great care must be taken when using only ceramic input and output capacitors. When a ceramic capacitor is used at the input and the power is being supplied through long wires, such as from a wall adapter, a load step at the output

## APPLICATIONS INFORMATION

can induce ringing at the  $V_{IN}$  pin. At best, this ringing can couple to the output and be mistaken as loop instability. At worst, the ringing at the input can be large enough to damage the part.

Since the ESR of a ceramic capacitor is so low, the input and output capacitor must instead fulfill a charge storage requirement. During a load step, the output capacitor must instantaneously supply the current to support the load until the feedback loop raises the switch current enough to support the load. The time required for the feedback loop to respond is dependent on the compensation and the output capacitor size. Typically, 3-4 cycles are required to respond to a load step, but only in the first cycle does the output drop linearly. The output droop,  $V_{DROOP}$ , is usually about 2-3 times the linear drop of the first cycle. Thus, a good place to start is with the output capacitor size of approximately:

$$C_{OUT} \approx 2.5 \frac{\Delta I_{OUT}}{f_o \cdot V_{DROOP}}$$

More capacitance may be required depending on the duty cycle and load step requirements.

In most applications, the input capacitor is merely required to supply high frequency bypassing, since the impedance to the supply is very low. A 10 $\mu$ F ceramic capacitor is usually enough for these conditions.

### Checking Transient Response

The regulator loop response can be checked by looking at the load transient response. Switching regulators take several cycles to respond to a step in load current. When a load step occurs,  $V_{OUT}$  immediately shifts by an amount equal to  $\Delta I_{LOAD} \cdot ESR$ , where ESR is the effective series resistance of  $C_{OUT}$ .  $\Delta I_{LOAD}$  also begins to charge or discharge  $C_{OUT}$ , generating a feedback error signal used by the regulator to return  $V_{OUT}$  to its steady-state value. During this recovery time,  $V_{OUT}$  can be monitored for overshoot or ringing that would indicate a stability problem.

The initial output voltage step may not be within the bandwidth of the feedback loop, so the standard second-order overshoot/DC ratio cannot be used to determine phase

margin. In addition, a feed-forward capacitor,  $C_{FF}$ , is added externally to improve the high frequency response. Capacitor  $C_{FF}$  provides phase lead by creating a high frequency zero with  $R1$ , which improves the phase margin.

The output voltage settling behavior is related to the stability of the closed-loop system and will demonstrate the actual overall supply performance. For a detailed explanation of optimizing the compensation components, including a review of control loop theory, refer to Application Note 76.

In some applications, a more severe transient can be caused by switching loads with large (>1 $\mu$ F) load input capacitors. The discharged load input capacitors are effectively put in parallel with  $C_{OUT}$ , causing a rapid drop in  $V_{OUT}$ . No regulator can deliver enough current to prevent this problem, if the switch connecting the load has low resistance and is driven quickly. The solution is to limit the turn-on speed of the load switch driver. A Hot Swap™ controller is designed specifically for this purpose and usually incorporates current limiting, short-circuit protection, and soft-starting.

### Efficiency Considerations

The percent efficiency of a switching regulator is equal to the output power divided by the input power times 100%. It is often useful to analyze individual losses to determine what is limiting the efficiency and which change would produce the most improvement. Percent efficiency can be expressed as:

$$\% \text{ Efficiency} = 100\% - (L1 + L2 + L3 + \dots)$$

where  $L1$ ,  $L2$ , etc. are the individual losses as a percentage of input power.

Although all dissipative elements in the circuit produce losses, four main sources usually account for most of the losses in LTC3548-1 circuits: 1)  $V_{IN}$  quiescent current, 2) switching losses, 3)  $I^2R$  losses, 4) other losses.

- 1) The  $V_{IN}$  current is the DC supply current given in the Electrical Characteristics which excludes MOSFET driver and control currents.  $V_{IN}$  current results in a small (<0.1%) loss that increases with  $V_{IN}$ , even at no load.

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## APPLICATIONS INFORMATION

- 2) The switching current is the sum of the MOSFET driver and control currents. The MOSFET driver current results from switching the gate capacitance of the power MOSFETs. Each time a MOSFET gate is switched from low to high to low again, a packet of charge  $dQ$  moves from  $V_{IN}$  to ground. The resulting  $dQ/dt$  is a current out of  $V_{IN}$  that is typically much larger than the DC bias current. In continuous mode,  $I_{GATECHG} = f_O(Q_T + Q_B)$ , where  $Q_T$  and  $Q_B$  are the gate charges of the internal top and bottom MOSFET switches. The gate charge losses are proportional to  $V_{IN}$  and thus their effects will be more pronounced at higher supply voltages.
- 3)  $I^2R$  losses are calculated from the DC resistances of the internal switches,  $R_{SW}$ , and external inductor,  $R_L$ . In continuous mode, the average output current flows through inductor  $L$ , but is “chopped” between the internal top and bottom switches. Thus, the series resistance looking into the SW pin is a function of both top and bottom MOSFET  $R_{DS(ON)}$  and the duty cycle ( $D$ ) as follows:

$$R_{SW} = (R_{DS(ON)TOP})(D) + (R_{DS(ON)BOT})(1 - D)$$

The  $R_{DS(ON)}$  for both the top and bottom MOSFETs can be obtained from the Typical Performance Characteristics curves. Thus, to obtain  $I^2R$  losses:

$$I^2R \text{ losses} = I_{OUT}^2(R_{SW} + R_L)$$

- 4) Other “hidden” losses such as copper trace and internal battery resistances can account for additional efficiency degradations in portable systems. It is very important to include these “system” level losses in the design of a system. The internal battery and fuse resistance losses can be minimized by making sure that  $C_{IN}$  has adequate charge storage and very low ESR at the switching frequency. Other losses including diode conduction losses during dead-time and inductor core losses generally account for less than 2% total additional loss.

### Thermal Considerations

In a majority of applications, the LTC3548-1 does not dissipate much heat due to its high efficiency. However, in applications where the LTC3548-1 is running at high ambient temperature with low supply voltage and high

duty cycles, such as in dropout, the heat dissipated may exceed the maximum junction temperature of the part. If the junction temperature reaches approximately 150°C, both power switches will turn off and the SW node will become high impedance.

To prevent the LTC3548-1 from exceeding the maximum junction temperature, the user will need to do some thermal analysis. The goal of the thermal analysis is to determine whether the power dissipated exceeds the maximum junction temperature of the part. The temperature rise is given by:

$$T_{RISE} = P_D \cdot \theta_{JA}$$

where  $P_D$  is the power dissipated by the regulator and  $\theta_{JA}$  is the thermal resistance from the junction of the die to the ambient temperature.

The junction temperature,  $T_J$ , is given by:

$$T_J = T_{RISE} + T_{AMBIENT}$$

As an example, consider the case when the LTC3548-1 is at an input voltage of 2.7V with a load current of 400mA and 800mA and an ambient temperature of 70°C. From the Typical Performance Characteristics graph of Switch Resistance, the  $R_{DS(ON)}$  resistance of the main switch is 0.425Ω. Therefore, power dissipated by each channel is:

$$P_D = I^2 \cdot R_{DS(ON)} = 272\text{mW and } 68\text{mW}$$

The DFN package junction-to-ambient thermal resistance,  $\theta_{JA}$ , is 40°C/W. Therefore, the junction temperature of the regulator operating in a 70°C ambient temperature is approximately:

$$T_J = (0.272 + 0.068) \cdot 40 + 70 = 83.6^\circ\text{C}$$

which is below the absolute maximum junction temperature of 125°C.

### Design Example

As a design example, consider using the LTC3548-1 in an portable application with a Li-Ion battery. The battery provides a  $V_{IN}$  = 2.8V to 4.2V. The load requires a maximum of 800mA in active mode and 2mA in standby mode. The output voltage is  $V_{OUT}$  = 1.8V.

## APPLICATIONS INFORMATION

First, calculate the inductor value for about 30% ripple current at maximum  $V_{IN}$ :

$$L = \frac{1.8V}{2.25MHz \cdot 240mA} \cdot \left(1 - \frac{1.8V}{4.2V}\right) = 1.9\mu H$$

Choosing a vendor's closest inductor value of  $2.2\mu H$ , results in a maximum ripple current of:

$$\Delta I_L = \frac{1.8V}{2.25MHz \cdot 2.2\mu} \cdot \left(1 - \frac{1.8V}{4.2V}\right) = 207mA$$

For cost reasons, a ceramic capacitor will be used.  $C_{OUT}$  selection is then based on load step droop instead of ESR requirements. For a 5% output droop:

$$C_{OUT} \approx 1.8 \frac{800mA}{2.25MHz \cdot (5\% \cdot 1.8V)} = 7.1\mu F$$

A good standard value is  $10\mu F$ . Since the output impedance of a Li-Ion battery is very low,  $C_{IN}$  is typically  $10\mu F$ .

Figure 3 shows the complete schematic for this design example.

## Board Layout Considerations

When laying out the printed circuit board, the following checklist should be used to ensure proper operation of the LTC3548-1. These items are also illustrated graphically in the layout diagram of Figure 4. Check the following in your layout:

1. Does the capacitor  $C_{IN}$  connect to the power  $V_{IN}$  (Pin 3) and GND (exposed pad) as close as possible? This capacitor provides the AC current to the internal power MOSFETs and their drivers.
2. The feedback lines from  $V_{OUT}$  should be routed away from noisy traces such as the SW line and its trace should be minimized.
3. Are the  $C_{OUT}$  and L1 closely connected? The (-) plate of  $C_{OUT}$  returns current to GND and the (-) plate of  $C_{IN}$ .
4. Keep sensitive components away from the SW pins. The input capacitor  $C_{IN}$  should be routed away from the SW traces and the inductors.
5. A ground plane is preferred, but if not available, keep the signal and power grounds segregated with small signal components returning to the GND pin at one point and should not share the high current path of  $C_{IN}$  or  $C_{OUT}$ .
6. Flood all unused areas on all layers with copper. Flooding with copper will reduce the temperature rise of power components. These copper areas should be connected to  $V_{IN}$  or GND.

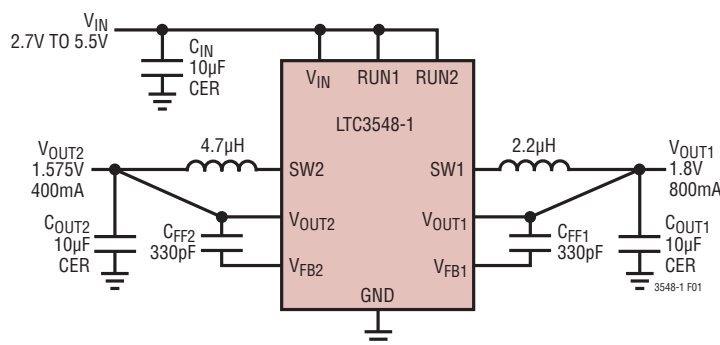
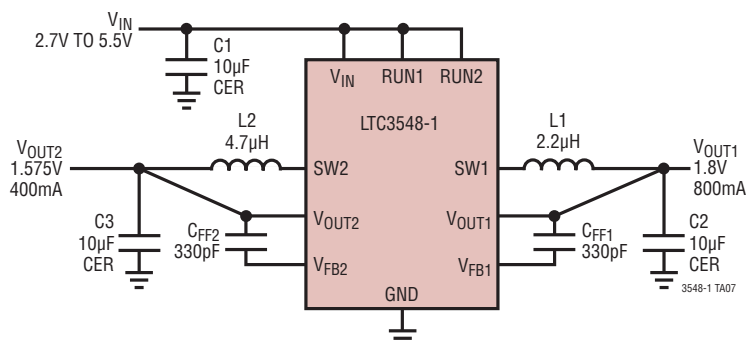


Figure 3. LTC3548-1 Typical Application

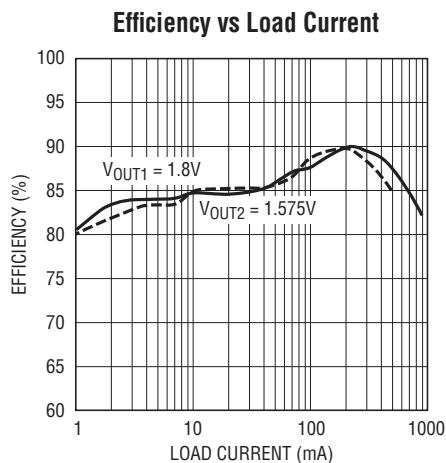


## TYPICAL APPLICATIONS

## 1mm Profile Core and I/O Supplies



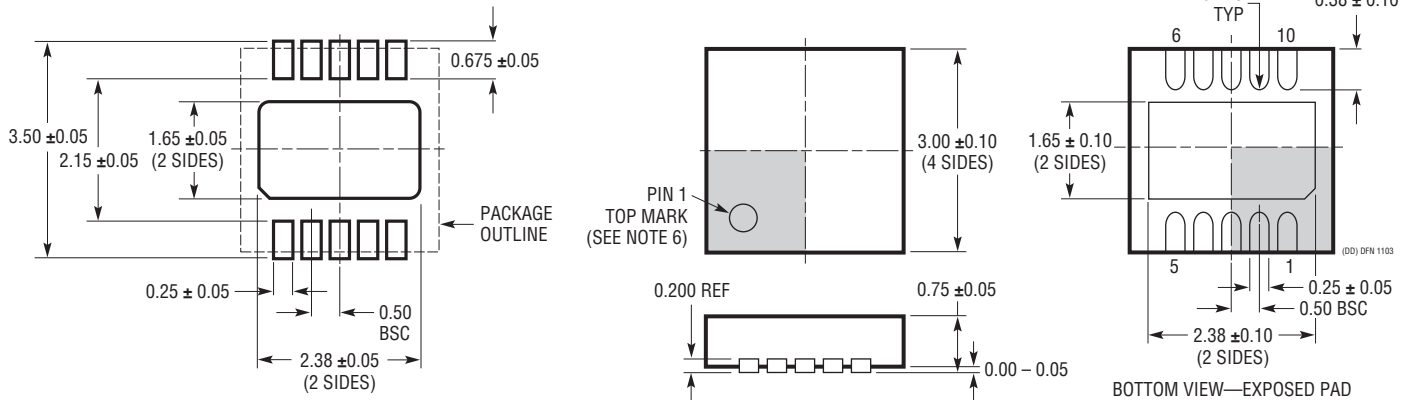
C1, C2: MURATA GRM219R60J106KE19  
 C3: MURATA GRM219R60J475KE19  
 L1: COILTRONICS LPO3310-222MX  
 L2: COILTRONICS LPO3310-472MX  
 \*IF C1 IS GREATER THAN 3" FROM POWER SOURCE,  
 ADDITIONAL CAPACITANCE MAY BE REQUIRED.



3548-1 G11

## PACKAGE DESCRIPTION

### DD Package 10-Lead Plastic DFN (3mm × 3mm) (Reference LTC DWG # 05-08-1699)

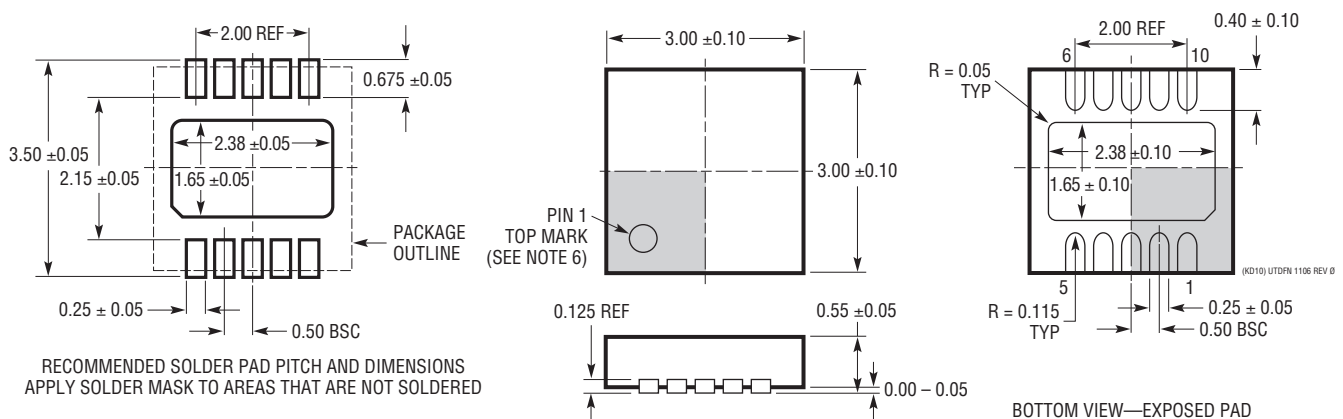


#### RECOMMENDED SOLDER PAD PITCH AND DIMENSIONS

##### NOTE:

1. DRAWING TO BE MADE A JEDEC PACKAGE OUTLINE M0-229 VARIATION OF (WEED-2). CHECK THE LTC WEBSITE DATA SHEET FOR CURRENT STATUS OF VARIATION ASSIGNMENT
2. DRAWING NOT TO SCALE
3. ALL DIMENSIONS ARE IN MILLIMETERS
4. DIMENSIONS OF EXPOSED PAD ON BOTTOM OF PACKAGE DO NOT INCLUDE MOLD FLASH. MOLD FLASH, IF PRESENT, SHALL NOT EXCEED 0.15mm ON ANY SIDE
5. EXPOSED PAD SHALL BE SOLDER PLATED
6. SHADED AREA IS ONLY A REFERENCE FOR PIN 1 LOCATION ON THE TOP AND BOTTOM OF PACKAGE

### KD Package 10-Lead Plastic UTDFN (3mm × 3mm) (Reference LTC DWG # 05-08-1739 Rev 0)



RECOMMENDED SOLDER PAD PITCH AND DIMENSIONS  
APPLY SOLDER MASK TO AREAS THAT ARE NOT SOLDERED

##### NOTE:

1. DRAWING TO BE MADE A JEDEC PACKAGE OUTLINE VARIATION OF (TBI).
2. DRAWING NOT TO SCALE
3. ALL DIMENSIONS ARE IN MILLIMETERS
4. DIMENSIONS OF EXPOSED PAD ON BOTTOM OF PACKAGE DO NOT INCLUDE MOLD FLASH. MOLD FLASH, IF PRESENT, SHALL NOT EXCEED 0.15mm ON ANY SIDE
5. EXPOSED PAD AND TIE BARS SHALL BE SOLDER PLATED
6. SHADED AREA IS ONLY A REFERENCE FOR PIN 1 LOCATION ON THE TOP AND BOTTOM OF PACKAGE



## RELATED PARTS

| PART NUMBER      | DESCRIPTION   | COMMENTS   |
|------------------|---|--|
| LTC1878          | 600mA ( $I_{OUT}$ ), 550kHz, Synchronous Step-Down DC/DC Converter                        | 95% Efficiency, $V_{IN}$ : 2.7V to 6V, $V_{OUT(MIN)} = 0.8V$ , $I_Q = 10\mu A$ , $I_{SD} < 1\mu A$ , MSOP-8 Package          |
| LT1940           | Dual Output 1.4A( $I_{OUT}$ ), Constant 1.1MHz, High Efficiency Step-Down DC/DC Converter | $V_{IN}$ : 3V to 25V, $V_{OUT(MIN)} = 1.2V$ , $I_Q = 2.5mA$ , $I_{SD} = < 1\mu A$ , TSSOP-16E Package                        |
| LTC3252          | Dual 250mA ( $I_{OUT}$ ), 1MHz, Spread Spectrum Inductorless Step-Down DC/DC Converter    | 88% Efficiency, $V_{IN}$ : 2.7V to 5.5V, $V_{OUT(MIN)} = 0.9V$ to 1.6V, $I_Q = 60\mu A$ , $I_{SD} < 1\mu A$ , DFN-12 Package |
| LTC3405/LTC3405A | 300mA ( $I_{OUT}$ ), 1.5MHz, Synchronous Step-Down DC/DC Converters                       | 96% Efficiency, $V_{IN}$ : 2.5V to 5.5V, $V_{OUT(MIN)} = 0.8V$ , $I_Q = 20\mu A$ , $I_{SD} < 1\mu A$ , ThinSOT Package       |
| LTC3406/LTC3406B | 600mA ( $I_{OUT}$ ), 1.5MHz, Synchronous Step-Down DC/DC Converters                       | 96% Efficiency, $V_{IN}$ : 2.5V to 5.5V, $V_{OUT(MIN)} = 0.6V$ , $I_Q = 20\mu A$ , $I_{SD} < 1\mu A$ , ThinSOT Package       |
| LT3407/LT3407-2  | 600mA/1.5MHz, 800mA/2.25MHz Dual Synchronous Step-Down DC/DC Converter                    | 96% Efficiency, $V_{IN}$ : 2.5V to 5.5V, $V_{OUT(MIN)} = 0.6V$ , $I_Q = 40\mu A$ , $I_{SD} < 1\mu A$ , MSE, DFN Package      |
| LTC3410/LTC3410B | 300mA, 2.25MHz Synchronous Step-Down DC/DC Converters                                     | 95% Efficiency, $V_{IN}$ : 2.5V to 5.5V, $V_{OUT(MIN)} = 0.8V$ , $I_Q = 26\mu A$ , $I_{SD} < 1\mu A$ , SC70 Package          |
| LTC3411          | 1.25A ( $I_{OUT}$ ), 4MHz, Synchronous Step Down DC/DC Converter                          | 95% Efficiency, $V_{IN}$ : 2.5V to 5.5V, $V_{OUT(MIN)} = 0.8V$ , $I_Q = 60\mu A$ , $I_{SD} < 1\mu A$ , MSOP-10 Package       |
| LTC3412          | 2.5A ( $I_{OUT}$ ), 4MHz, Synchronous Step Down DC/DC Converter                           | 95% Efficiency, $V_{IN}$ : 2.5V to 5.5V, $V_{OUT(MIN)} = 0.8V$ , $I_Q = 60\mu A$ , $I_{SD} < 1\mu A$ , TSSOP-16E Package     |
| LTC3414          | 4A ( $I_{OUT}$ ), 4MHz, Synchronous Step Down DC/DC Converter                             | 95% Efficiency, $V_{IN}$ : 2.25V to 5.5V, $V_{OUT(MIN)} = 0.8V$ , $I_Q = 64\mu A$ , $I_{SD} < 1\mu A$ , TSSOP-28E Package    |
| LTC3440          | 600mA ( $I_{OUT}$ ), 2MHz, Synchronous Buck-Boost DC/DC Converter                         | 95% Efficiency, $V_{IN}$ : 2.5V to 5.5V, $V_{OUT(MIN)} = 2.5V$ , $I_Q = 25\mu A$ , $I_{SD} < 1\mu A$ , MSOP-10 Package       |
| LTC3548          | 400mA/800mA ( $I_{OUT}$ ), 2.25MHz, Dual Synchronous Step-Down DC/DC Converter            | 95% Efficiency, $V_{IN}$ : 2.5V to 5.5V, $V_{OUT(MIN)} = 0.6V$ , $I_Q = 40\mu A$ , $I_{SD} < 1\mu A$ , MSE, DFN-10 Packages  |