

Adjustable Precision Shunt Regulator

TO-92



SOT-89



Pin Definition:

1. Reference
2. Anode
3. Cathode

SOT-23



Pin Definition:

1. Cathode
2. Reference
3. Anode

SOP-8



Pin Definition:

- | | |
|------------|--------------|
| 1. Cathode | 8. Reference |
| 2. Anode | 7. Anode |
| 3. Anode | 6. Anode |
| 4. N/C | 5. N/C |

General Description

TS2431 series integrated circuits are three-terminal programmable shunt regulator diodes. These monolithic IC voltage references operate as a low temperature coefficient zener which is programmable from V_{REF} to 36 volts with two external resistors. These devices exhibit a wide operating current range of 1.0 to 100mA with a typical dynamic impedance of 0.22Ω. The characteristics of these references make them excellent replacements for zener diodes in many applications such as digital voltmeters, power supplies, and op amp circuitry. The 2.5V reference makes it convenient to obtain a stable reference from 5.0V logic supplies, and since The TS2431 series operates as a shunt regulator, it can be used as either a positive or negative stage reference.

Features

- Precision Reference Voltage
TS2431 – 2.495V±2%
TS2431A – 2.495V±1%
TS2431B – 2.495V±0.5%
- Equivalent Full Range Temp. Coefficient: 50ppm/ °C
- Programmable Output Voltage up to 36V
- Fast Turn-On Response
- Sink Current Capability of 1~100mA
- Low Dynamic Output Impedance: 0.2Ω
- Low Output Noise

Ordering Information

Part No.	Package	Packing
TS2431xCT B0	TO-92	1Kpcs / Bulk
TS2431xCT A3	TO-92	2Kpcs / Ammo
TS2431xCX RF	SOT-23	3Kpcs / 7" Reel
TS2431xCY RM	SOT-89	1Kpcs / 7" Reel
TS2431xCS RL	SOP-8	2.5Kpcs / 13" Reel

Note: Where **xx** denotes voltage tolerance

Blank: ±2%

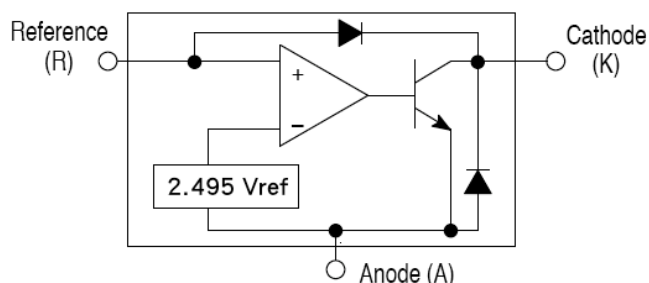
A: ±1%

B: ±0.5%

Application

- Voltage Monitor
- Delay Timmer
- Constant –Current Source/Sink
- High-Current Shunt Regulator
- Crow Bar
- Over-Voltage / Under-Voltage Protection

Block Diagram



Absolute Maximum Rating (Ta = 25°C unless otherwise noted)

Parameter	Symbol	Limit	Unit
Cathode Voltage (Note 1)	V_{KA}	37	V
Continuous Cathode Current Range	I_K	-100 ~ +150	mA
Reference Input Current Range	I_{REF}	-0.05 ~ +10	mA
Power Dissipation	TO-92	0.625	W
	SOT-23	0.30	
	SOT-89 / SOP-8	0.50	
Junction Temperature	T_J	+150	°C
Operating Temperature Range	T_{OPER}	0 ~ +70	°C
Storage Temperature Range	T_{STG}	-65 ~ +150	°C

Note 1: Voltage values are with respect to the anode terminal unless otherwise noted.

Recommend Operating Condition

Parameter	Symbol	Limit	Unit
Cathode Voltage (Note 1)	V_{KA}	Ref ~ 36	V
Continuous Cathode Current Range	I_K	1 ~ 100	mA

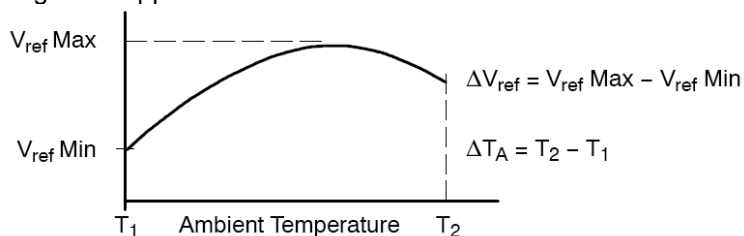
Recommend Operating Condition

Parameter	Symbol	Test Conditions	Min	Typ	Max	Unit
Reference voltage	V_{REF}	$V_{KA} = V_{REF}$, $I_K = 10\text{mA}$ (Figure 1) $T_a = 25^\circ\text{C}$	2.450	2.495	2.550	V
			2.475		2.525	
			2.487		2.513	
Deviation of reference input voltage	ΔV_{REF}	$V_{KA} = V_{REF}$, $I_K = 10\text{mA}$ (Figure 1) $T_a = \text{full range}$	--	3	12	mV
Radio of change in Vref to change in cathode Voltage	$\Delta V_{REF} / \Delta V_{KA}$	$I_{KA} = 10\text{mA}$, $V_{KA} = 10\text{V to } V_{REF}$ $V_{KA} = 36\text{V to } 10\text{V}$ (Figure 2)	--	-1.4 -1.0	-2.7 -2.0	mV/V
Reference Input current	I_{REF}	$R1=10\text{K}\Omega$, $R2=\infty$, $I_{KA} = 10\text{mA}$ $T_a = \text{full range}$ (Figure 2)	--	0.7	4.0	μA
Deviation of reference input current, over temp.	ΔI_{REF}	$R1=10\text{K}\Omega$, $R2=\infty$, $I_{KA} = 10\text{mA}$ $T_a = \text{full range}$ (Figure 2)	--	0.4	1.2	μA
Off-state Cathode Current	$I_{KA}(\text{off})$	$V_{REF} = 0\text{V}$ (Figure 3), $V_{KA} = 36\text{V}$	--	--	1.0	μA
Dynamic Output Impedance	$ Z_{KA} $	$f < 1\text{KHz}$, $V_{KA} = V_{REF}$ $I_{KA} = 1\text{mA to } 100\text{mA}$ (Figure 1)	--	0.22	0.5	Ω
Minimum operating cathode current	$I_{KA}(\text{min})$	$V_{KA} = V_{REF}$ (Figure 1)	--	0.4	0.6	mA

* The deviation parameters ΔV_{REF} and ΔI_{REF} are defined as difference between the maximum value and minimum value obtained over the full operating ambient temperature range that applied.

* The average temperature coefficient of the reference input voltage, αV_{REF} is defined as:

$$\alpha V_{REF} \left(\frac{\text{ppm}}{^\circ\text{C}} \right) = \frac{\left(\frac{\Delta V_{REF}}{V_{REF}} \right) \times 10^6}{\Delta T_A}$$



Where: $T_2 - T_1$ = full temperature change.

ΔV_{REF} can be positive or negative depending on whether the slope is positive or negative.

Example: Maximum $V_{REF} = 2.496\text{V}$ at 30°C , minimum $V_{REF} = 2.492\text{V}$ at 0°C , $V_{REF} = 2.495\text{V}$ at 25°C , $\Delta T = 70^\circ\text{C}$

$$\Delta V_{REF} = [4\text{mV} / 2495\text{mV}] \times 10^6 / 70^\circ\text{C} \approx 23\text{ppm}/^\circ\text{C}$$

Because minimum V_{REF} occurs at the lower temperature, the coefficient is positive.

* The dynamic impedance Z_{KA} is defined as:

$$|Z_{KA}| = \Delta V_{KA} / \Delta I_{KA}$$

* When the device operating with two external resistors, $R1$ and $R2$, (refer to Figure 2) the total dynamic impedance of the circuit is given by:

$$|Z_{KA}| = \Delta v / \Delta i \approx Z_{KA} \times (1 + R1 / R2)$$

Test Circuits

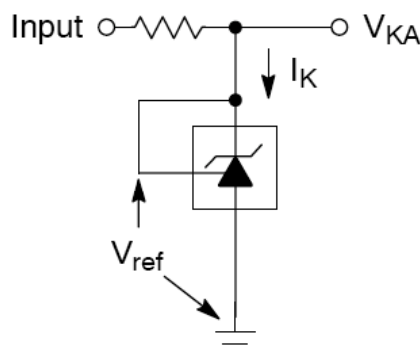


Figure 1: $V_{KA} = V_{REF}$

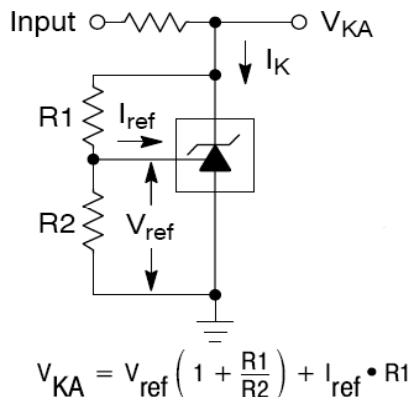


Figure 2: $V_{KA} > V_{REF}$

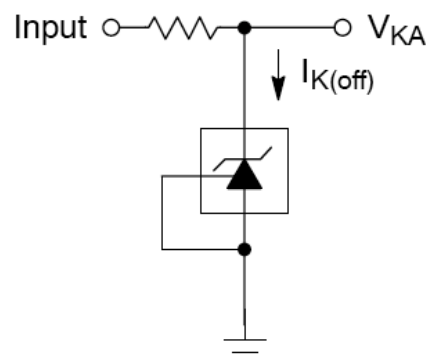


Figure 3: Off-State Current

Additional Information – Stability

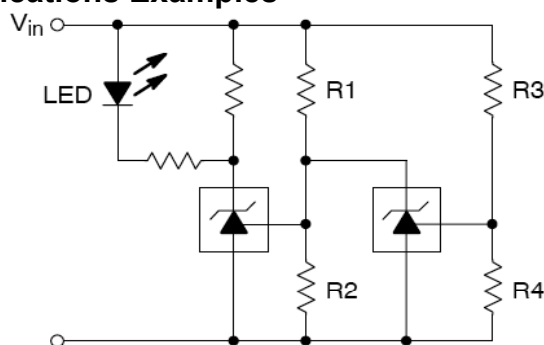
When The TS2431/2431A/2431B is used as a shunt regulator, there are two options for selection of C_L , are recommended for optional stability:

- A) No load capacitance across the device, decouple at the load.
- B) Large capacitance across the device, optional decoupling at the load.

The reason for this is that TS2431/2431A/2431B exhibits instability with capacitances in the range of 10nF to 1uF (approx.) at light cathode current up to 3mA (typ). The device is less stable the lower the cathode voltage has been set for. Therefore while the device will be perfectly stable operating at a cathode current of 10mA (approx.) with a 0.1uF capacitor across it, it will oscillate transiently during start up as the cathode current passes through the instability region. Select a very low capacitance, or alternatively a high capacitance (10uF) will avoid this issue altogether. Since the user will probably wish to have local decoupling at the load anyway, the most cost effective method is to use no capacitance at all directly across the device. PCB trace/via resistance and inductance prevent the local load decoupling from causing the oscillation during the transient start up phase.

Note: if the TS2431/2431A/2431B is located right at the load, so the load decoupling capacitor is directly across it, then this capacitor will have to be $\leq 1\text{nF}$ or $\geq 10\mu\text{F}$.

Applications Examples

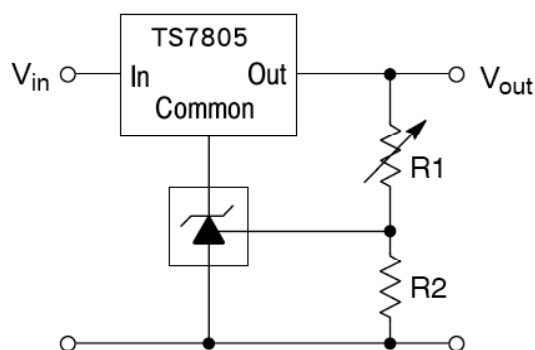


L.E.D. indicator is 'ON' when V_{in} is between the upper and lower limits,

$$\text{Lower limit} = \left(1 + \frac{R1}{R2} \right) V_{ref}$$

$$\text{Upper limit} = \left(1 + \frac{R3}{R4} \right) V_{ref}$$

Figure 4: Voltage Monitor



$$V_{out} = \left(1 + \frac{R1}{R2} \right) V_{ref}$$

$$V_{out(min)} = V_{ref} + 5.0 \text{ V}$$

Figure 5: Output Control for Three Terminal Fixed Regulator

Applications Examples (Continue)

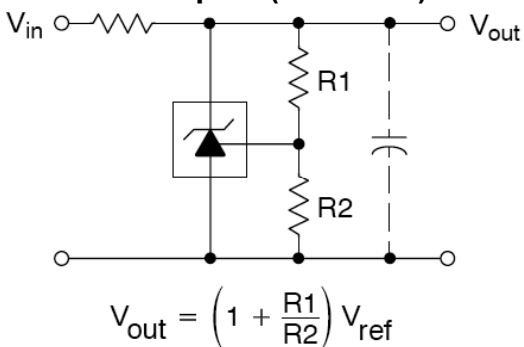


Figure 6: Shunt Regulator

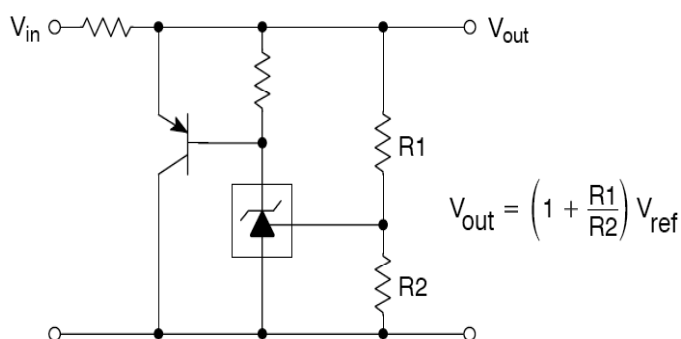


Figure 7: High Current Shunt Regulator

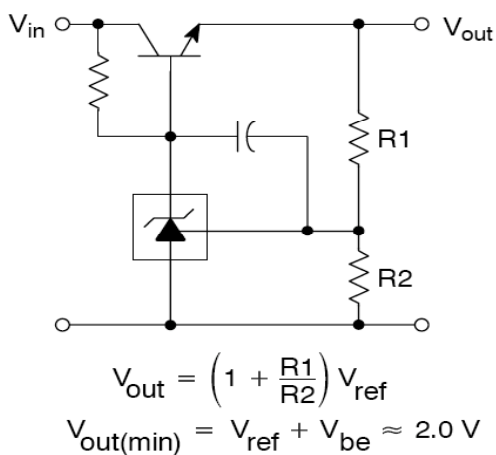


Figure 8: Series Pass Regulator

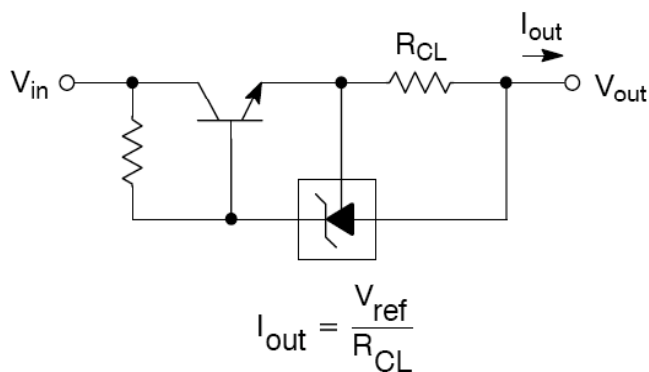


Figure 9: Constant Current Source

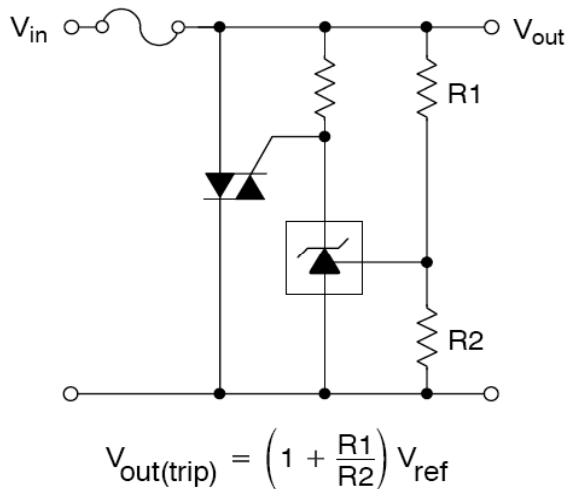


Figure 10: TRIAC Crowbar

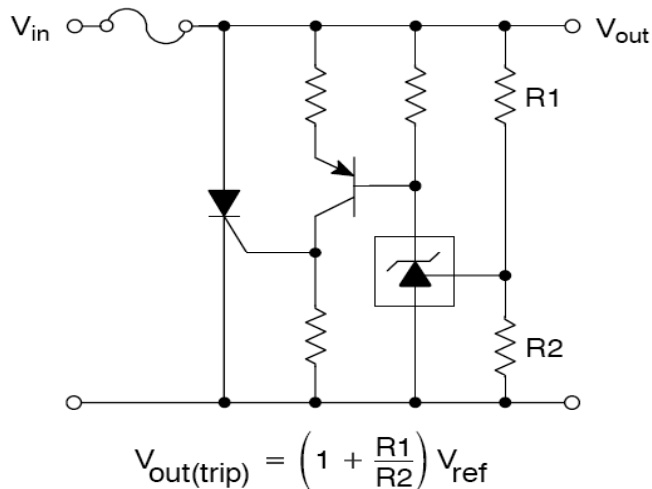


Figure 11: SCR Crowbar

Applications Examples (Continue)

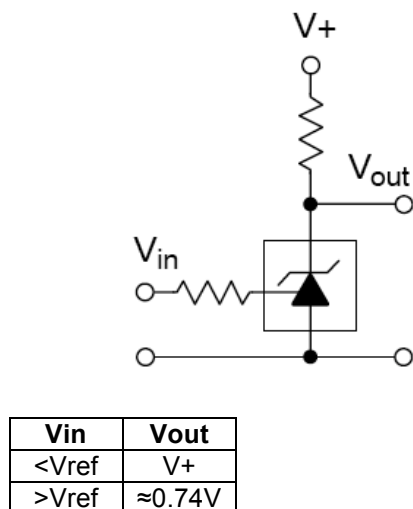


Figure 12: Single-Supply Comparator with Temperature-Compensated Threshold

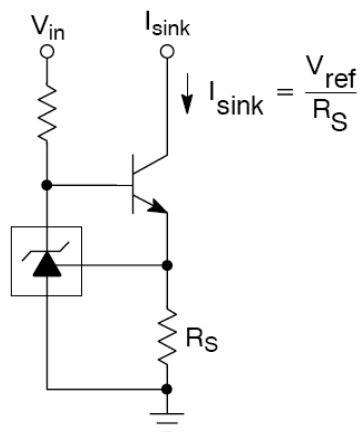


Figure 13: Constant Current Sink

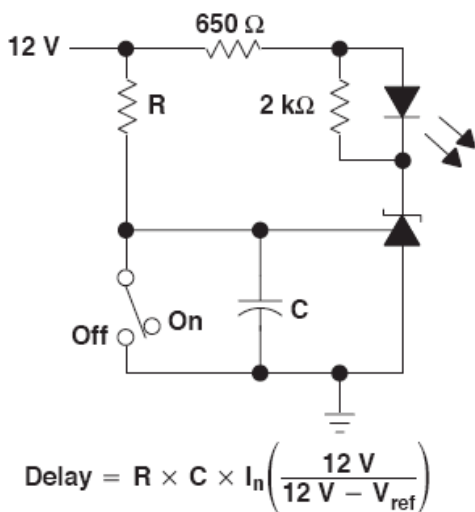


Figure 14: Delay Timer

Typical Performance Characteristics

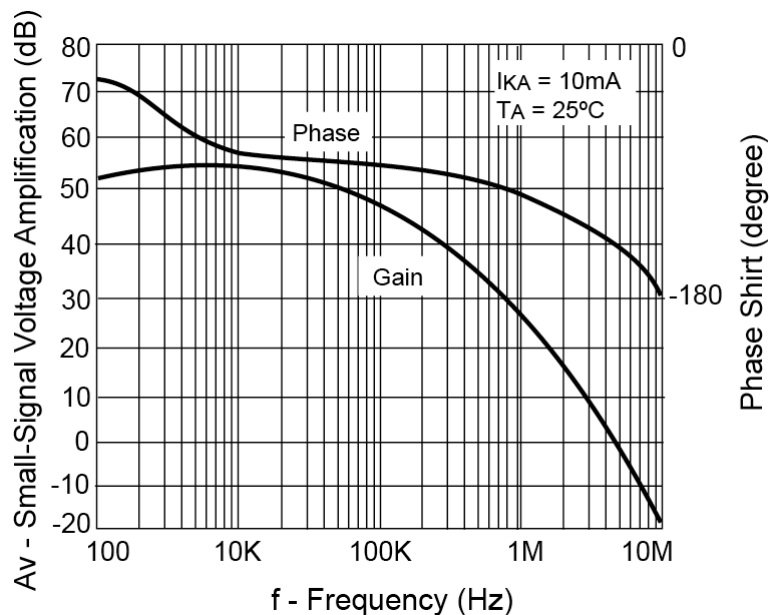
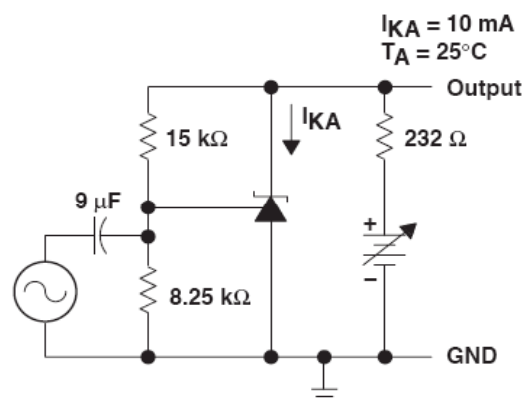


Figure 14: Small-Signal Voltage Gain and Phase Shift vs. Frequency



Test Circuit for Voltage Amplification

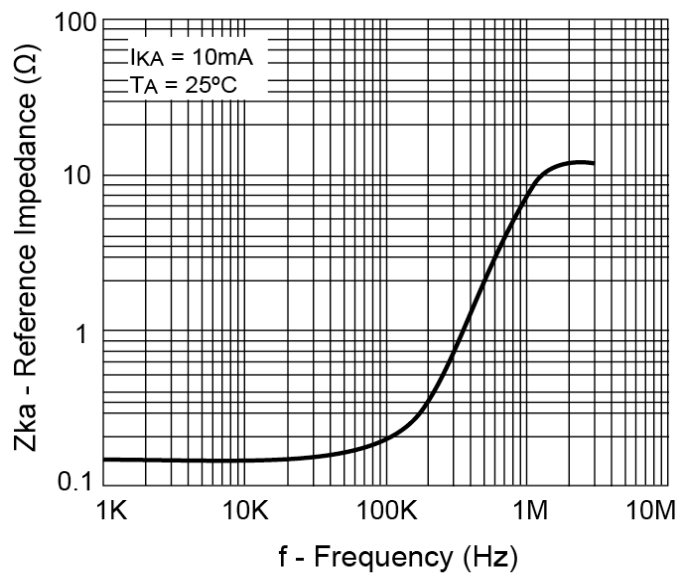
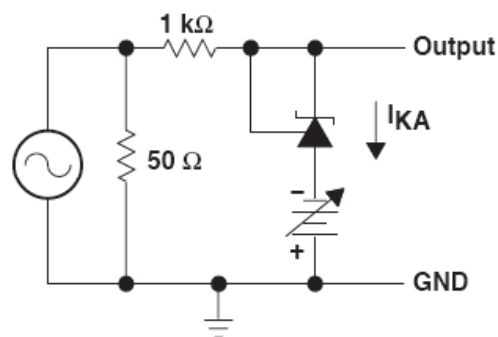
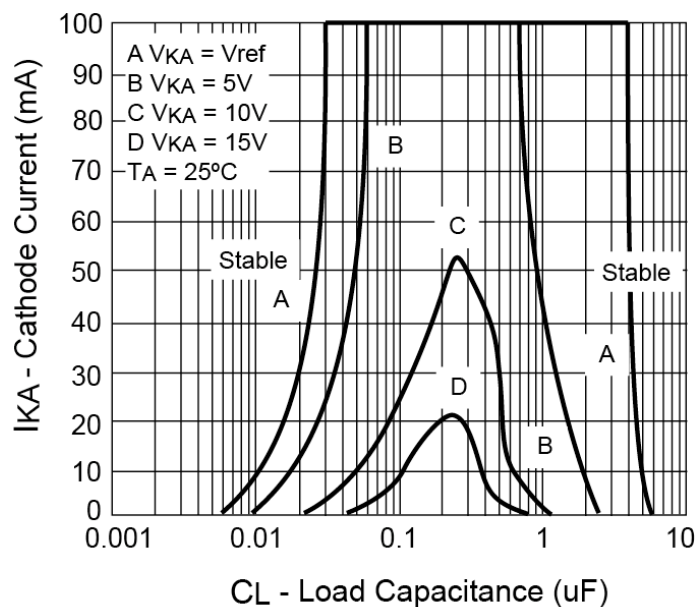


Figure 15: Reference Impedance vs. Frequency

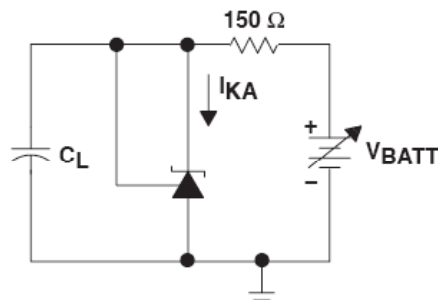


Test Circuit for Reference Impedance

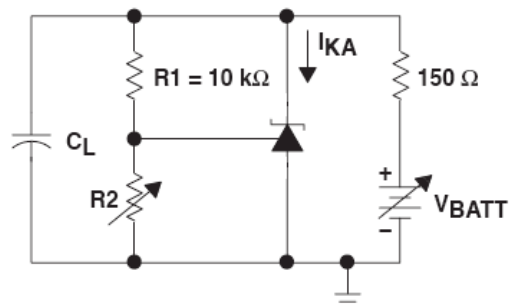
Typical Performance Characteristics (Continue)



The areas under the curves represent conditions that may cause the device to oscillate. For curves B, C, and D, R_2 and V_+ were adjusted to establish the initial V_{KA} and I_{KA} conditions with $C_L=0$. V_{BATT} and C_L then were adjusted to determine the ranges of stability.

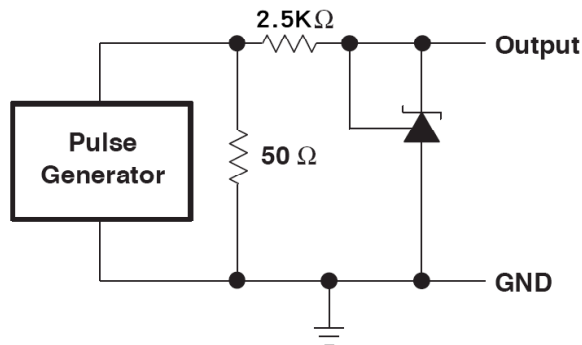
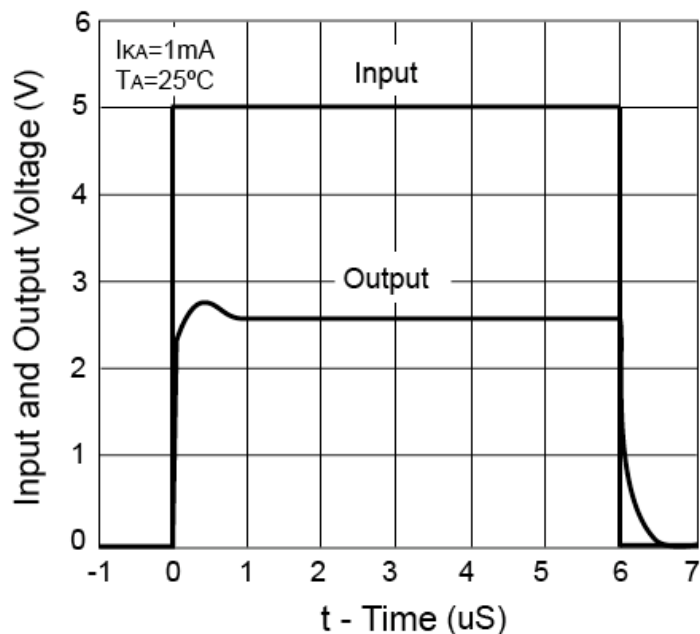


Test Circuit for Curve A



Test Circuit for Curve B, C and D

Figure 16: Stability Boundary Condition



Test Circuit for Pulse Response, $I_k=1mA$

Figure 17: Pulse Response

Electrical Characteristics

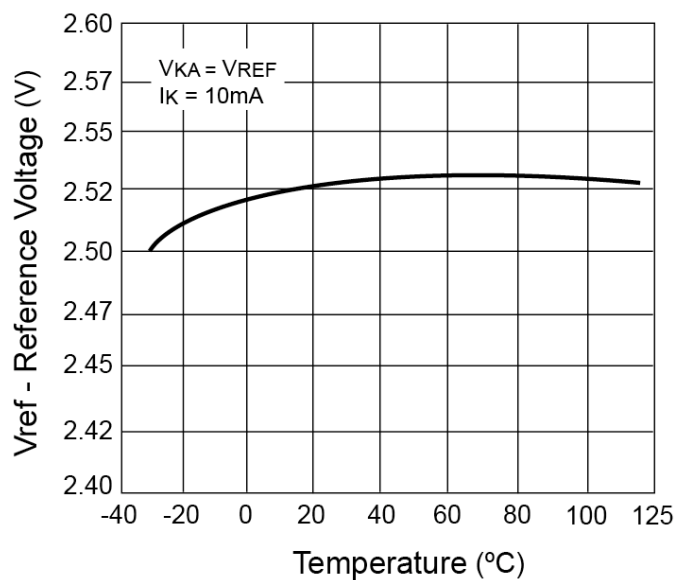


Figure 18: Reference Voltage vs. Temperature

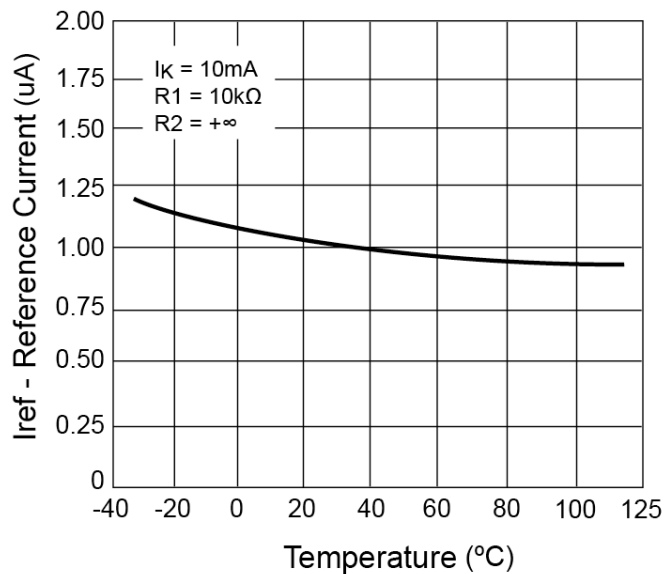


Figure 19: Reference Current vs. Temperature

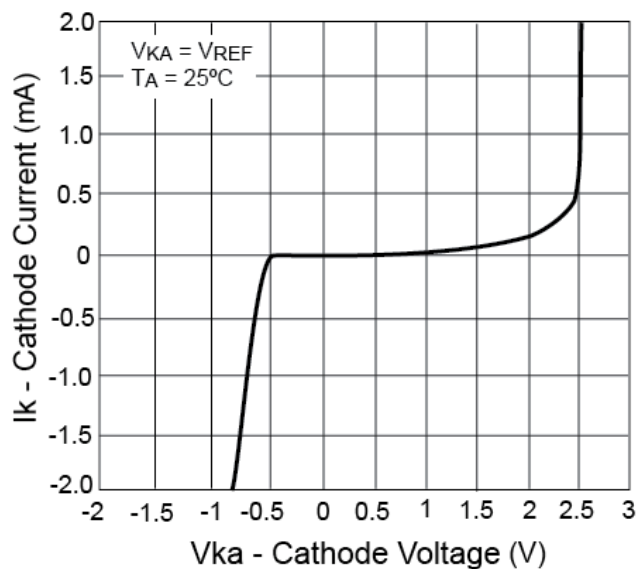
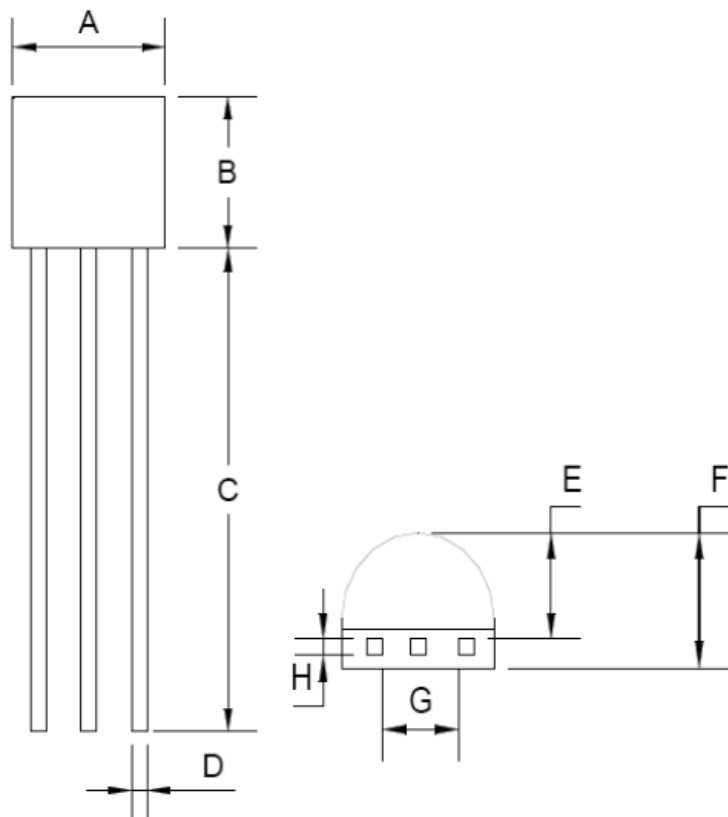


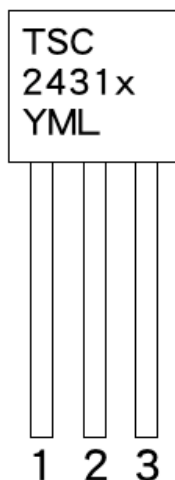
Figure 20: Cathode Current vs. Cathode Voltage

TO-92 Mechanical Drawing



TO-92 DIMENSION				
DIM	MILLIMETERS		INCHES	
	MIN	MAX	MIN	MAX
A	4.30	4.70	0.169	0.185
B	4.30	4.70	0.169	0.185
C	14.30(typ)		0.563(typ)	
D	0.43	0.49	0.017	0.019
E	2.19	2.81	0.086	0.111
F	3.30	3.70	0.130	0.146
G	2.42	2.66	0.095	0.105
H	0.37	0.43	0.015	0.017

Marking Diagram



X = Tolerance Code

(**A** = $\pm 1\%$, **B** = $\pm 0.5\%$, **Blank** = $\pm 2\%$,)

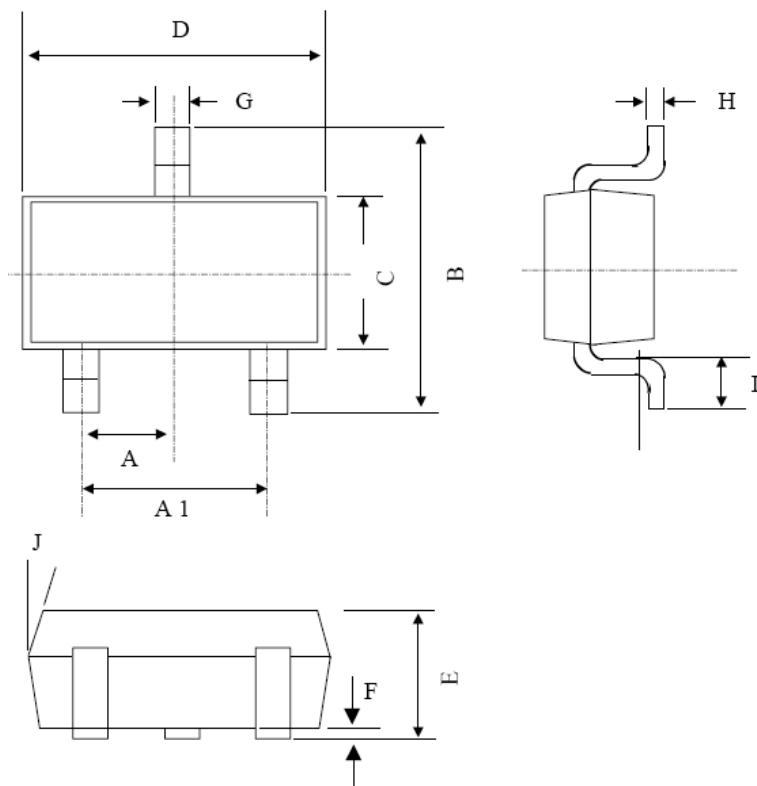
Y = Year Code

M = Month Code

(**A**=Jan, **B**=Feb, **C**=Mar, **D**=Apr, **E**=May, **F**=Jun, **G**=Jul, **H**=Aug, **I**=Sep, **J**=Oct, **K**=Nov, **L**=Dec)

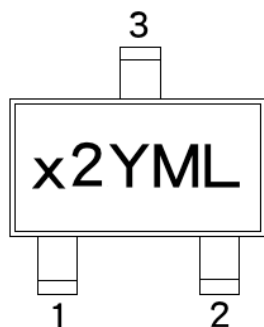
L = Lot Code

SOT-23 Mechanical Drawing



DIM	MILLIMETERS		INCHES	
	MIN	MAX	MIN	MAX.
A	0.95 BSC		0.037 BSC	
A1	1.9 BSC		0.074 BSC	
B	2.60	3.00	0.102	0.118
C	1.40	1.70	0.055	0.067
D	2.80	3.10	0.110	0.122
E	1.00	1.30	0.039	0.051
F	0.00	0.10	0.000	0.004
G	0.35	0.50	0.014	0.020
H	0.10	0.20	0.004	0.008
I	0.30	0.60	0.012	0.024
J	5°	10°	5°	10°

Marking Diagram



X = Tolerance Code

(**A** = ±1%, **B** = ±0.5%, **C** = ±2%,)

2 = Device Code

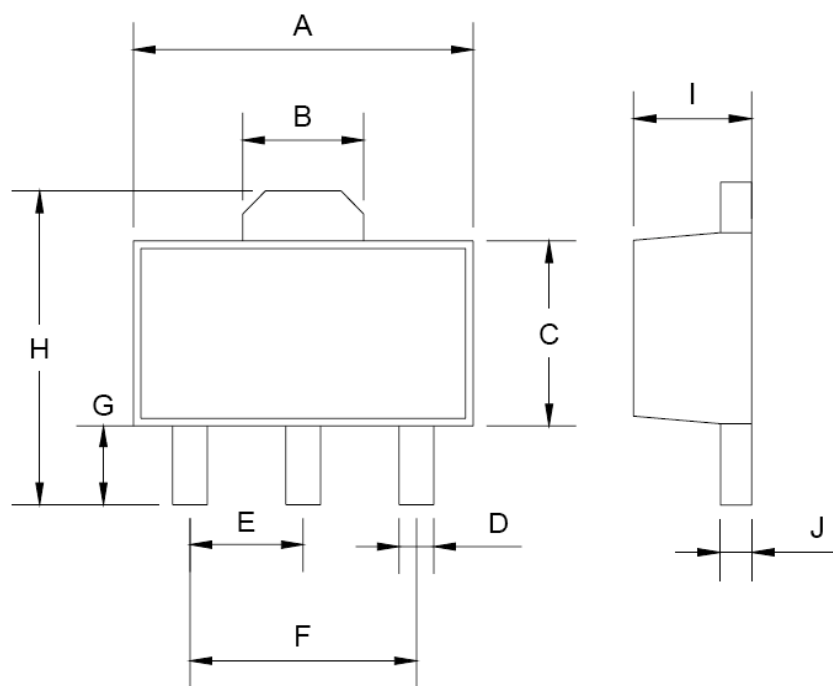
Y = Year Code

M = Month Code

(**A**=Jan, **B**=Feb, **C**=Mar, **D**=Apr, **E**=May, **F**=Jun, **G**=Jul, **H**=Aug, **I**=Sep, **J**=Oct, **K**=Nov, **L**=Dec)

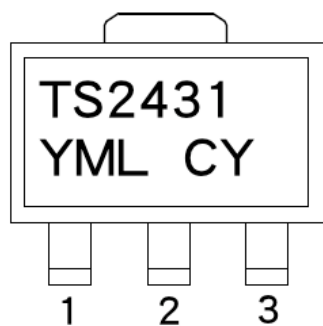
L = Lot Code

SOT-89 Mechanical Drawing



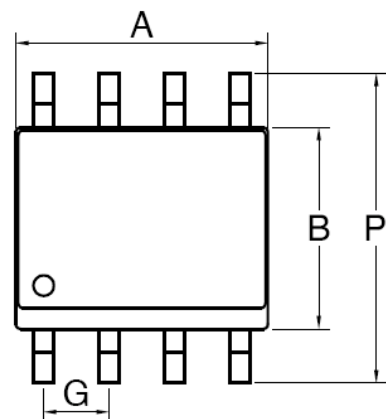
SOT-89 DIMENSION				
DIM	MILLIMETERS		INCHES	
	MIN	MAX	MIN	MAX
A	4.40	4.60	0.173	0.181
B	1.50	1.7	0.059	0.070
C	2.30	2.60	0.090	0.102
D	0.40	0.52	0.016	0.020
E	1.50	1.50	0.059	0.059
F	3.00	3.00	0.118	0.118
G	0.89	1.20	0.035	0.047
H	4.05	4.25	0.159	0.167
I	1.4	1.6	0.055	0.068
J	0.35	0.44	0.014	0.017

Marking Diagram

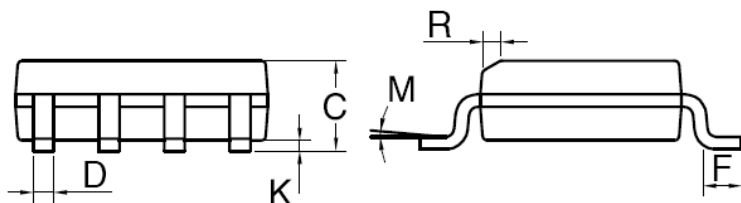


- Y** = Year Code
- M** = Month Code
(A=Jan, B=Feb, C=Mar, D=Apl, E=May, F=Jun, G=Jul, H=Aug, I=Sep, J=Oct, K=Nov, L=Dec)
- L** = Lot Code
- CY** = Package Code

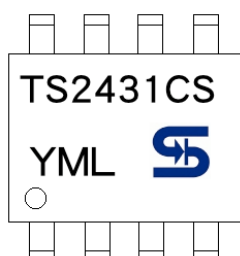
SOP-8 Mechanical Drawing



DIM	SOP-8 DIMENSION			
	MILLIMETERS		INCHES	
	MIN	MAX	MIN	MAX.
A	4.80	5.00	0.189	0.196
B	3.80	4.00	0.150	0.157
C	1.35	1.75	0.054	0.068
D	0.35	0.49	0.014	0.019
F	0.40	1.25	0.016	0.049
G	1.27BSC		0.05BSC	
K	0.10	0.25	0.004	0.009
M	0°	7°	0°	7°
P	5.80	6.20	0.229	0.244
R	0.25	0.50	0.010	0.019



Marking Diagram



- Y** = Year Code
M = Month Code
 (A=Jan, B=Feb, C=Mar, D=Apl, E=May, F=Jun, G=Jul, H=Aug, I=Sep, J=Oct, K=Nov, L=Dec)
L = Lot Code

TS2431

Adjustable Precision Shunt Regulator

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