

PAW3504 PURE USB OPTICAL MOUSE SINGLE CHIP

General Description

The PAW3504 is a CMOS process optical mouse sensor single chip with USB interface that serves as a non-mechanical motion estimation engine for implementing a computer mouse.

Feat	tures	Key Specification	
	USB interface	Dames Complex	Wide operating supply range
	Single power supply	Power Supply	4.25V ~ 5.5V
	Optical motion estimation technology	Interface	USB
	Complete 2-D motion sensor		
	Accurate motion estimation over a wide range of	Optical Lens	1:1
	surfaces	System Clock	24.000 MHz
	High speed motion detection up to 28 inches/sec		
	Power saving mode during times of no	Speed	28 inches/sec
	movement	Acceleration	20g
	Supports three buttons (R, M, L) and three axes		3)
	(X, Y, Z) output	Resolution	800 CPI
	Z-axis support mechanical input (Z/2)	Frame Rate	3000 frames/sec
	Reduce jiggle happen		10mA @Mouse moving (Normal)
- 1	USB spec.		5mA @Mouse not moving (Sleep)
>	Complete Universal Serial Bus specs V1.1		480uA @USB suspend (Suspend)
>	compatibility Complete USB HID specs V1.11 compatibility	Package	Shrunk DIP14

Ordering Information

serial interface engine

Part Number	CPI
PAW3504DLY	800

> Integrated USB transceiver and 1.5Mbps USB

1. Pin Configuration

1.1 Pin Description

Pin#	Name	Туре	Definition
1	OSCIN	IN	Oscillator input, connected to resonator or resistor
2	BL	IN	Button left key input, normal pull-high (50k), press connect to low
3	LED	OUT	LED control
4	VDDQ	BYPASS	I/O voltage reference
5	VSS	GND	Chip ground
6	VDD5V	PWR	Chip power VDD, 5.0V
7	VDDA	BYPASS	Analog voltage reference
8	D+	I/O	USB D+
9	D-	I/O	USB D-
10	BR	IN	Button right key input, normal pull-high (50k), press connect to low
11	BM	IN	Button middle key input, normal pull-high (50k), press connect to low
12	Z2	IN	Z axis, support mechanical scroller input
13	Z1	IN	Z axis, support mechanical scroller input
14	OSCOUT	OUT	Oscillator output, connected to resonator

1.2 Pin Assignment

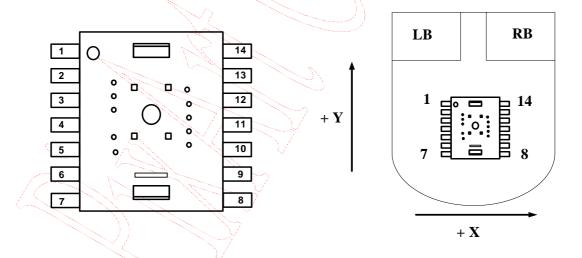


Figure 1. Top View Pinout

Figure 2. Top View of Mouse

2. Block Diagram and Operation

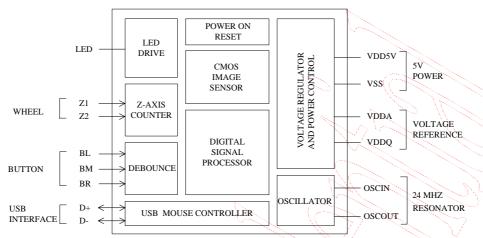


Figure 3. Block Diagram

The PAW3504 supports X, Y, Z three axes, and L, R, M three buttons under USB mode. It is a CMOS process optical mouse sensor single chip with USB interface that serves as a non-mechanical motion estimation engine for implementing a computer mouse.

The PAW3504 is in a 14-pin optical package and comes with the resolution of 800 counts per inch (CPI) and the rate of motion up to 28 inches per second. It includes USB interface so that no mouse controller is needed to interface through USB. The PAW3504 can receive command and echo status or data format, both complete Universal Serial Bus® spec V1.1 and USB HID spec V1.11 compatibility. It is also a cost effective solution to support USB Mouse.



3. Specifications

3.1 Absolute Maximum Ratings

Exposure to absolute maximum rating may affect device reliability.

Symbol	Parameter	Min.	Max.	Unit	Notes
T _{STG}	Storage Temperature	-40	85	°C	
TA	Operating Temperature	-15	55	°C	
	Lead Solder Temp		260	°C	For 10 seconds, 1.6 mm below seating plane.
ESD			2	kV	All pins, human body model MIL 883 Method 3015
V_{DC}	DC Supply Voltage	-0.5	5.5	V	
V	DC Input Voltage	-0.5	5.5	V	Z1, Z2
V_{IN}	DC input voltage	-0.5	4.0	V	BL, BR, BM

3.2 Recommend Operating Condition

Symbol	Parameter	Min.	Typ.	Max.	Unit	Notes
T_A	Operating Temperature	0	1	40	°C	S .
V_{DD}	Power Supply Voltage	4.25	5.0	5.5	V	
V_N	Supply Noise			100	mV	Peak to peak within 0 - 80 MHz
Z	Distance from Lens Reference Plane to Surface	2.3	2.4	2.5	mm	Refer to Figure 4.
R	Resolution	400	800	1	CPI	
A	Acceleration	$\langle \gamma \rangle$		20)) g	
F_{CLK}	Clock Frequency		24	The same of the sa	MHz	
FR	Frame Rate		3000		frames/sec	
S	Speed	0	20	28	inches/sec	28 inches/sec @400CPI 20 inches/sec @800CPI

3.3 AC Electrical Characteristics

Electrical characteristics over recommended operating conditions. Typical values at 25 °C, $V_{DD} = 5.0 \text{ V}$, $F_{CLK} = 24 \text{ MHz}$

Symbol	Parameters	Min.	Тур.	Max.	Unit	Notes
Tb	Mouse Button Debounce Time	-	10.24	-	ms	
Tz	Mouse Z Debounce Time	-	1.024	-	ms	

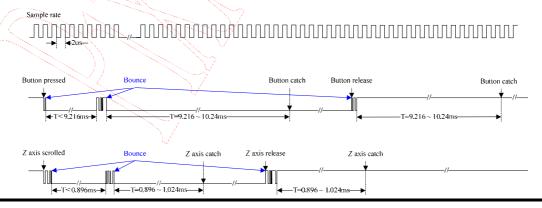
3.4 DC Electrical Characteristics

Electrical characteristics over recommended operating conditions. Typical values at 25 °C, V_{DD} =5.0 V, F_{CLK} =24 MHz.

Symbol	Parameter	Min.	Тур.	Max.	Unit	Notes
Type: U	SB Mouse PWR					
I_{DD}	Supply Current Mouse moving (Normal)	1	10	1	mA	
I_{DD}	Supply Current Mouse not moving (Sleep)	I	5	1	mA	
I_{DD}	Supply Current USB suspend current	I	ı	480	uA	
Type: B	L, BM, BR			r.		
R_{PH}	Internal Pull Up Resistance	-	50	P.	Kohm	
V_{IH}	Input High Voltage	2.0	-	-	V	
$V_{\rm IL}$	Input Low Voltage	-	N. O.	0.8	V	NV
Type: Z	1, Z 2		10		1	
R_{PD}	Internal Pull Down Resistance	-	50	Z /	Kohm	
V_{IH}	Input High Voltage	2.0	-	$=$ $\frac{1}{2}$ $\frac{1}{2}$	V	
V_{IL}	Input Low Voltage	-	-	0.8	V	
Type: U	SB DP, DN			NA		V
R_{PH}	Internal Pull Up Resistance (USB Spec 5%)	-20%	1.5	+20%	Kohm	
Type: O	SCIN					
V_{IH}	Input High Voltage	2.1	-	17.	V	When driving from an external source
V_{IL}	Input Low Voltage	-	-	0.5	V	When driving from an external source
Type: V	DDQ				M	
VDDQ	I/O Voltage Reference	-	3.3	_	V	

3.5 Button and Z-Wheel Debounce Timing

Buttons and Z wheel of PAW3504DLY include detect and debounce function which are hardware implement. When press button input signals need keeping low level up to 9.216ms. Button function just can catch data otherwise debounce function will judge it is bounce issue. When scroll Z wheel input signals need keeping turning level up to 0.896ms. Z wheel function just can catch data otherwise debounce function will judge it is bounce issue. And the hardware sample rate is 2us so if bounce time is less than 2us the debounce function will ignore it. Following the below specifications Buttons and Z wheel will work normally.

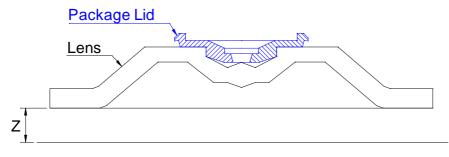


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4. Z and 2D/3D Assembly



OBJECT SURFACE

Figure 4. Distance from Lens Reference Plane to Surface

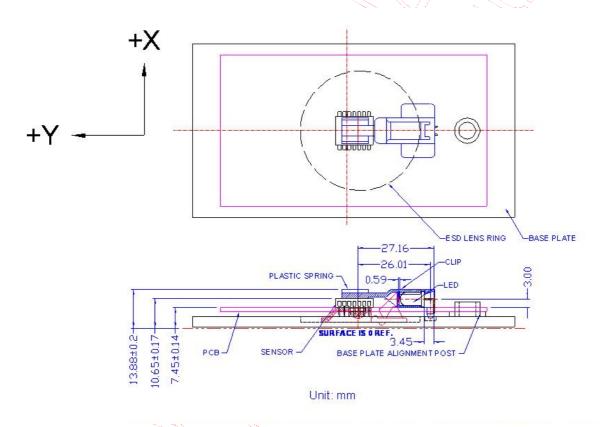
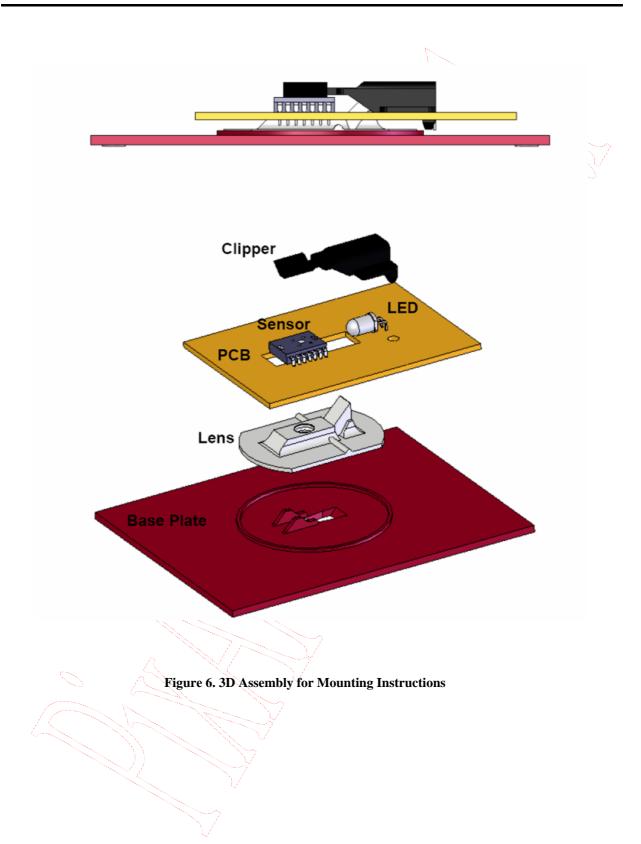


Figure 5. 2D Assembly

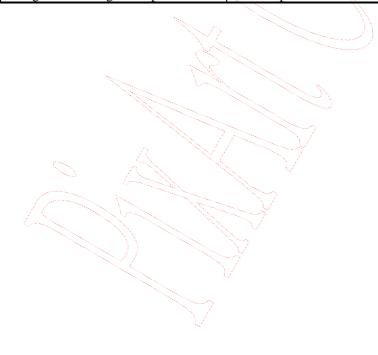


5. USB Interface

5.1 USB Command Set Description (USB Descriptor)

The USB HOST detects USB mouse device plug-in and assigns a new unique address to the USB mouse device, then asking USB mouse device for information about the device description, configuration description, and assigning a configuration value for USB mouse device during enumeration period. After enumeration, the USB mouse device is able to transfer motion and button value to the USB host.

Descriptor Type	Byte	Byte	Byte	Byte	Byte	Byte	Byte	Byte
	12	01	10	01	/00	.00	00	08
Device Descriptor (18 bytes)	3A	09	10	25	V00	01	01	02
	00	01			and the same of th			
Configuration Descriptor (0 hytes)	09	02	22	00	-01	01	04	A0
Configuration Descriptor (9 bytes)	32			6	27		5	
Interface Descriptor (0 bytes)	09	04	00	00	01	03	01	02
Interface Descriptor (9 bytes)	00	V-		1//	77		\overline{X}	
Human Interface Device Descriptor	09	21	10	01	/ 00	01	22	3E
(9 bytes)	00	\mathcal{Q}	((1// 1	1	
Endpoint Descriptor (7 bytes)	07	05	81	03	04	-00	0A	
	05	01	09	02	A1	01	05	09
	19	01	/ 29	03	15	00	25	01
	95	03 ?	75	01	81	02	95	01
Human Interface Device Report	75	05	81	03	05	01	09	01
Descriptor (62 bytes, 3D3B)	A1	00	09	30	09	31	15	81
	25	7F	75	08	95	02	81	06
	C0	-09	38	15	81	25	7F	75
	08	95	01	81	706	C0		
Language String Descriptor (4 bytes)	04	03	09	04	Y			
Manufacture String Descriptor	PIXART							
Product String Descriptor	USB OPTICAL MOUSE							
Configuration String Descriptor	HID-cor	npliant M	IOUSE					



5.2 USB Data Report Format

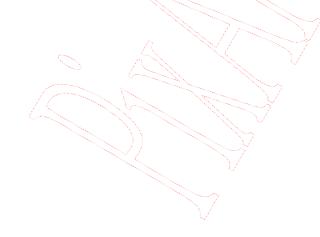
The USB report has two data formats, depending on boot or report protocol is selected. One kind of data format is the boot protocol used in legacy environment as 5.2.1. The other kind of data format is USB report protocol format which includes Z-wheel movement data in the fourth byte as 5.2.2. The Z-wheel is moved forward the fourth byte data is 01H, the Z-wheel is moved backward the fourth byte data is FFH, and the Z-wheel is idle the fourth byte data is 00H.

5.2.1 USB Boot Protocol for Legacy Operation

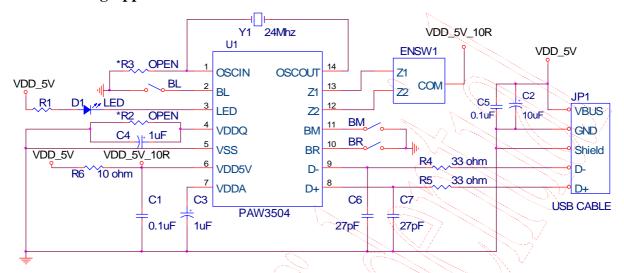
Byte	Bit	Symbol	Description
	0	BL	1 = Left button pressed
1	1	BR	1 = Right button pressed
1	2	BM	1 = Middle button pressed
	3 ~ 7	NC	Reserved
2	0 - 7	X0 ~ X7	X data (D0 - D7). A positive value indicates motion to the right; a negative value
	0 - 7	A0 ~ A7	indicates motion to the left. Bit $0 = LSB$.
3	0 - 7	Y0 ~ Y7	Y data (D0 - D7). A positive value indicates device motion upward; a negative
3	0 - 7	10~17	value indicates motion downward, Bit 0 = LSB.

5.2.2 USB Report Protocol

Byte	Bit	Symbol	Description
	0	BL	1 = Left button pressed
	1	BR	1 = Right button pressed
1	2	BM	1 = Middle button pressed
1	3	B4	Reserved
	4	B5	Reserved
	5 ~ 7	NC	Reserved
2.	0 - 7	X0 ~ X7	X data (D0 - D7). A positive value indicates motion to the right; a negative value
	0 - 7	A0 ~ A7	indicates motion to the left. Bit $0 = LSB$.
3	0 - 7	Y0 ~ Y7	Y data (D0 - D7). A positive value indicates device motion upward; a negative
3	0 - 7	10~17	value indicates motion downward. Bit 0 = LSB.
			Z-wheel motion data (D0 - D7). A positive value indicates device motion
4	0 - 7	7 Z0 ~ Z7	downward; a negative value indicates motion upward. The Z0 - Z7 limit value is
		THE STATE OF	\pm 7. Bit $0 = LSB$.



6. Referencing Application Circuit



Note:

- 1. *R2 is left for PAN3401 with PS/2 interface
- 2. *R3 is left for PAN3502 RC Oscillator
- 3. R4,R5,C6,C7 are for EMCimmunity
- 4. USB cable connector JP1 is suggested to has the pin sequence like this: VBUS, GND, Shield, D-, D+

Figure 7. Application Circuit for PAW3504

6.2 PCB Layout Guideline

The following guidelines apply to component placement and routing on the PCB. That will get an optimum EMC solution and tracking performance.

6.2.1 Key Components Placement Rules

- 1. Place resonator (Y1) near SENSOR pin1 and pin 14.
- 2. Place bulk capacitor (C2) and bypass (C5) near the USB CABLE.
- 3. Place C1 and C3 near SENSOR pin 6 and pin 7.
- 4. The C6/C7 and R4/R5 should be placed as close to the USB CABLE.

6.2.2 Routing Rules

- 1. Caps for pins 4, 6, 7 trace length must be less than 5 mm.
- 2. The trace length of OSCOUT, OSCIN must be less than 10 mm.
- 3. Other general rules refer file"PAW3504DLY PCB Layout Guide"

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6.3 Recommended Value for R1

Radiometric intensity of LED

Bin limits (mW/Sr at 20mA)

LED Bin Grade	Min	Тур	Max	Unit 🥎	
N	14.7	-	17.7	mW/Sr	
P	17.7	-	21.2	mW/Sr	
Q	21.2	-	25.4	mW/Sr	

Note: Tolerance for each bin will be \pm 15%

R1 value (ohm), $V_{DD} = 5.0V$

LED Bin Grade	Min	Тур	Max	Unit
N	56.2	100	2	ohm
P	56.2	100	6	ohm
Q	56.2	100	-	ohm



7. Package Information

7.1 Package Outline Drawing 0 13.208 0.520 10.16 0.400 3.20 0.126 <u>1.02</u> 0.040 <u>1.42</u> 0.056 5.08 0.200 0.254 0.010 0.457 0.018 14.22 +/- 0.2 0.560 +/-0.0079 7.874 0.310 5.334 0.210 4.064 0.160 6.604 0.260 5.080 0.200 NOTES: 1. All dimensions in MM/INCH. All dimensions tolerance: +/- 0.10mm Maxmumflash: +0.2mm 10 **\$** \frac{5.6}{0.220}

Figure 8. Package Outline Drawing

7.2 Recommended PCB Mechanical Cutouts and Spacing

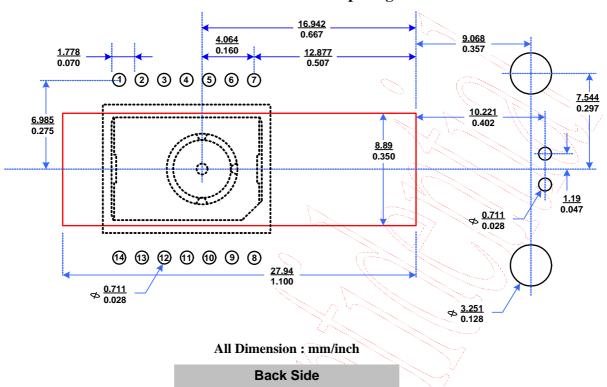


Figure 9. Recommended PCB Mechanical Cutouts and Spacing

8. Update History

Version	Update	Date
V1.0	Creation, Preliminary 1 st version	06/09/2008

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