## FEATURES

- 1-of-4 Bidirectional Translating Switches
- $I^{2} C$ Bus and SMBus Compatible
- Active-Low Reset Input
- Three Address Pins, Allowing up to Eight Devices on the $I^{2} C$ Bus
- Channel Selection Via $I^{2} C$ Bus
- Power Up With All Switch Channels Deselected
- Low R ${ }_{\text {ON }}$ Switches
- Allows Voltage-Level Translation Between 1.8-V, 2.5-V, 3.3-V, and 5-V Buses
- No Glitch on Power Up
- Supports Hot Insertion
- Low Standby Current
- Operating Power-Supply Voltage Range of 2.3 V to 5.5 V
- 5.5-V Tolerant Inputs
- 0 to $400-k H z$ Clock Frequency
- Latch-Up Performance Exceeds 100 mA Per JESD 78
- ESD Protection Exceeds JESD 22
- 2000-V Human-Body Model (A114-A)
- 200-V Machine Model (A115-A)
- 1000-V Charged-Device Model (C101)


## DESCRIPTION/ORDERING INFORMATION

The PCA9546A is a quad bidirectional translating switch controlled via the $I^{2} \mathrm{C}$ bus. The SCL/SDA upstream pair fans out to four downstream pairs, or channels. Any individual SCn/SDn channel or combination of channels can be selected, determined by the contents of the programmable control register.
An active-low reset ( $\overline{\mathrm{RESET}}$ ) input allows the PCA9546A to recover from a situation in which one of the downstream $I^{2} \mathrm{C}$ buses is stuck in a low state. Pulling RESET low resets the $\mathrm{I}^{2} \mathrm{C}$ state machine and causes all the channels to be deselected, as does the internal power-on reset function.

## ORDERING INFORMATION

| $\mathrm{T}_{\text {A }}$ | PACKAGE ${ }^{(1)(2)}$ |  | ORDERABLE PART NUMBER | TOP-SIDE MARKING |
| :---: | :---: | :---: | :---: | :---: |
| $-40^{\circ} \mathrm{C}$ to $85^{\circ} \mathrm{C}$ | QFN - RGV | Reel of 2500 | PCA9546ARGVR | PD546A |
|  | QFN - RGY | Reel of 1000 | PCA9546ARGYR | PD546A |
|  | SOIC - D | Tube of 40 | PCA9546AD | PCA9546A |
|  |  |  | PCA9546ADG4 |  |
|  |  | Reel of 2500 | PCA9546ADR |  |
|  |  |  | PCA9546ADRG4 |  |
|  |  | Reel of 250 | PCA9546ADT |  |
|  |  |  | PCA9546ADTG4 |  |
|  | SOIC - DW | Tube of 40 | PCA9546ADW | PCA9546A |
|  |  | Reel of 2000 | PCA9546ADWR |  |
|  |  | Reel of 250 | PCA9546ADWT | PREVIEW |
|  | TSSOP - PW | Tube of 90 | PCA9546APW | PD546A |
|  |  |  | PCA9546APWE4 |  |
|  |  | Reel of 2000 | PCA9546APWR |  |
|  |  |  | PCA9546APWRE4 |  |
|  |  | Reel of 250 | PCA9546APWT |  |
|  |  |  | PCA9546APWTE4 |  |
|  | TVSOP - DGV | Reel of 2000 | PCA9546ADGVR | PD546A |
|  |  | Reel of 250 | PCA9546ADGVT | PREVIEW |

(1) For the most current package and ordering information, see the Package Option Addendum at the end of this document, or see the TI website at www.ti.com
(2) Package drawings, thermal data, and symbolization are available at www.ti.com/packaging.

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## DESCRIPTION/ORDERING INFORMATION (CONTINUED)

The pass gates of the switches are constructed such that the $\mathrm{V}_{\mathrm{CC}}$ pin can be used to limit the maximum high voltage, which will be passed by the PCA9546A. This allows the use of different bus voltages on each pair, so that $1.8-\mathrm{V}, 2.5-\mathrm{V}$, or $3.3-\mathrm{V}$ parts can communicate with $5-\mathrm{V}$ parts without any additional protection. External pullup resistors pull the bus up to the desired voltage level for each channel. All I/O pins are $5.5-\mathrm{V}$ tolerant.


## TERMINAL FUNCTIONS

| NO. |  | NAME | DESCRIPTION |
| :---: | :---: | :---: | :---: |
| $\begin{aligned} & \text { D, DGV, DW, PW, } \\ & \text { AND RGY } \end{aligned}$ | RGV |  |  |
| 1 | 15 | A0 | Address input 0 . Connect directly to $\mathrm{V}_{C C}$ or ground. |
| 2 | 16 | A1 | Address input 1. Connect directly to $\mathrm{V}_{C C}$ or ground. |
| 3 | 1 | RESET | Active low reset input. Connect to $\mathrm{V}_{\text {CC }}$ through a pullup resistor, if not used. |
| 4 | 2 | SD0 | Serial data 0 . Connect to $\mathrm{V}_{C C}$ through a pullup resistor. |
| 5 | 3 | SC0 | Serial clock 0 . Connect to $\mathrm{V}_{\mathrm{CC}}$ through a pullup resistor. |
| 6 | 4 | SD1 | Serial data 1. Connect to $\mathrm{V}_{\mathrm{CC}}$ through a pullup resistor. |
| 7 | 5 | SC1 | Serial clock 1. Connect to $\mathrm{V}_{\mathrm{CC}}$ through a pullup resistor. |
| 8 | 6 | GND | Ground |
| 9 | 7 | SD2 | Serial data 2. Connect to $\mathrm{V}_{C C}$ through a pullup resistor. |
| 10 | 8 | SC2 | Serial clock 2. Connect to $\mathrm{V}_{C C}$ through a pullup resistor. |
| 11 | 9 | SD3 | Serial data 3. Connect to $\mathrm{V}_{\mathrm{CC}}$ through a pullup resistor. |
| 12 | 10 | SC3 | Serial clock 3. Connect to $\mathrm{V}_{\mathrm{CC}}$ through a pullup resistor. |
| 13 | 11 | A2 | Address input 2. Connect directly to $\mathrm{V}_{C C}$ or ground. |
| 14 | 12 | SCL | Serial clock line. Connect to $\mathrm{V}_{\mathrm{CC}}$ through a pullup resistor. |
| 15 | 13 | SDA | Serial data line. Connect to $\mathrm{V}_{\mathrm{CC}}$ through a pullup resistor. |
| 16 | 14 | $\mathrm{V}_{C C}$ | Supply power |


A. Pin numbers shown are for the D, DGV, DW, PW and RGY packages.

## Device Address

Following a start condition, the bus master must output the address of the slave it is accessing. The address of the PCA9546A is shown in Figure 1. To conserve power, no internal pullup resistors are incorporated on the hardware-selectable address pins, and they must be pulled high or low.


Figure 1. PCA9546A Address
The last bit of the slave address defines the operation to be performed. When set to a logic 1, a read is selected, while a logic 0 selects a write operation.

## Control Register

Following the successful acknowledgment of the slave address, the bus master sends a byte to the PCA9546A, which is stored in the control register (see Figure 2). If multiple bytes are received by the PCA9546A, it will save the last byte received. This register can be written and read via the $I^{2} \mathrm{C}$ bus.


Figure 2. Control Register

## Control Register Definition

One or several SCn/SDn downstream pairs, or channels, are selected by the contents of the control register (see Table 11). This register is written after the PCA9546A has been addressed. The four LSBs of the control byte are used to determine which channel or channels are to be selected. When a channel is selected, the channel becomes active after a stop condition has been placed on the $I^{2} \mathrm{C}$ bus. This ensures that all $\mathrm{SCn} / \mathrm{SDn}$ lines are in a high state when the channel is made active, so that no false conditions are generated at the time of connection. A stop condition always must occur right after the acknowledge cycle.

Table 1. Control Register Write (Channel Selection), Control Register Read (Channel Status) ${ }^{(1)}$

| B7 | B6 | B5 | B4 | B3 | B2 | B1 | B0 | COMMAND |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| X | X | X | X | X | X | X | 0 | Channel 0 disabled |
|  |  |  |  |  |  |  | 1 | Channel 0 enabled |
| X | X | X | X | X | X | 0 | X | Channel 1 disabled |
|  |  |  |  |  |  | 1 |  | Channel 1 enabled |
| X | X | X | X | X | 0 | X | X | Channel 2 disabled |
|  |  |  |  |  | 1 |  |  | Channel 2 enabled |
| X | X | X | X | 0 | X | X | X | Channel 3 disabled |
|  |  |  |  | 1 |  |  |  | Channel 3 enabled |
| 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | No channel selected, power-up/reset default state |

(1) Several channels can be enabled at the same time. For example, $B 3=0, B 2=1, B 1=1, B 0=0$ means that channels 0 and 3 are disabled, and channels 1 and 2 are enabled. Care should be taken not to exceed the maximum bus capacity.

## RESET Input

The RESET input is an active-low signal that may be used to recover from a bus-fault condition. When this signal is asserted low for a minimum of $t_{\text {wL }}$, the PCA9446A resets its registers and $I^{2} C$ state machine and deselects all channels. The RESET input must be connected to $\mathrm{V}_{\mathrm{Cc}}$ through a pullup resistor.

## Power-On Reset

When power is applied to $\mathrm{V}_{\mathrm{CC}}$, an internal power-on reset holds the PCA9546A in a reset condition until $\mathrm{V}_{\mathrm{CC}}$ has reached $\mathrm{V}_{\text {POR }}$. At this point, the reset condition is released, and the PCA9546A registers and $I^{2} \mathrm{C}$ state machine are initialized to their default states, all zeroes, causing all the channels to be deselected. Thereafter, $\mathrm{V}_{\mathrm{CC}}$ must be lowered below 0.2 V to reset the device.

## Voltage Translation

The pass-gate transistors of the PCA9546A are constructed such that the $\mathrm{V}_{\mathrm{CC}}$ voltage can be used to limit the maximum voltage that will be passed from one $I^{2} \mathrm{C}$ bus to another.
Figure 3 shows the voltage characteristics of the pass-gate transistors (note that the graph was generated using the data specified in the electrical characteristics section of this data sheet). In order for the PCA9546A to act as a voltage translator, the $\mathrm{V}_{\text {pass }}$ voltage must be equal to or lower than the lowest bus voltage. For example, if the main bus is running at 5 V , and the downstream buses are 3.3 V and 2.7 V , then $\mathrm{V}_{\text {pass }}$ must be equal to or below 2.7 V to effectively clamp the downstream bus voltages. As shown in Figure 3, $\mathrm{V}_{\text {pass }}(\mathrm{max}$ ) is at 2.7 V when the PCA9546A supply voltage is 3.5 V or lower, so the PCA9546A supply voltage could be set to 3.3 V . Pullup resistors then can be used to bring the bus voltages to their appropriate levels (see Figure 12).


Figure 3. $\mathrm{V}_{\text {pass }}$ Voltage vs $\mathrm{V}_{\mathrm{cc}}$

## $1^{2} \mathrm{C}$ Interface

The $I^{2} \mathrm{C}$ bus is for two-way two-line communication between different ICs or modules. The two lines are a serial data line (SDA) and a serial clock line (SCL). Both lines must be connected to a positive supply via a pullup resistor when connected to the output stages of a device. Data transfer can be initiated only when the bus is not busy.
One data bit is transferred during each clock pulse. The data on the SDA line must remain stable during the high period of the clock pulse, as changes in the data line at this time are interpreted as control signals (see Figure 4).


Figure 4. Bit Transfer
Both data and clock lines remain high when the bus is not busy. A high-to-low transition of the data line while the clock is high is defined as the start condition (S). A low-to-high transition of the data line while the clock is high is defined as the stop condition $(\mathrm{P})$ (see Figure 5).


Figure 5. Definition of Start and Stop Conditions
A device generating a message is a transmitter; a device receiving is the receiver. The device that controls the message is the master, and the devices that are controlled by the master are the slaves (see Figure 6).


Figure 6. System Configuration
The number of data bytes transferred between the start and the stop conditions from transmitter to receiver is not limited. Each byte of eight bits is followed by one acknowledge (ACK) bit. The transmitter must release the SDA line before the receiver can send an ACK bit.

When a slave receiver is addressed, it must generate an ACK after the reception of each byte. Also, a master must generate an ACK after the reception of each byte that has been clocked out of the slave transmitter. The device that acknowledges must pull down the SDA line during the ACK clock pulse so that the SDA line is stable low during the high pulse of the ACK-related clock period (see Figure 7). Setup and hold times must be taken into account.


Figure 7. Acknowledgment on the $I^{2} C$ Bus
Data is transmitted to the PCA9546A control register using the write mode shown in Figure 8.


Start Condition
R/W ACK From Slave
ACK From Slave Stop Condition
Figure 8. Write Control Register
Data is read from the PCA9546A control register using the read mode shown in Figure 9.


Figure 9. Read Control Register

## Absolute Maximum Ratings ${ }^{(1)}$

over operating free-air temperature range (unless otherwise noted)

|  |  |  | MIN | MAX | UNIT |
| :---: | :---: | :---: | :---: | :---: | :---: |
| $\mathrm{V}_{\mathrm{CC}}$ | Supply voltage range |  | -0.5 | 7 | V |
| $\mathrm{V}_{1}$ | Input voltage range ${ }^{(2)}$ |  | -0.5 | 7 | V |
| $I_{1}$ | Input current |  |  | $\pm 20$ | mA |
| $\mathrm{I}_{0}$ | Output current |  |  | $\pm 25$ | mA |
| Continuous current through V CC |  |  |  | $\pm 100$ | mA |
| Continuous current through GND |  |  |  | $\pm 100$ | mA |
| $\theta_{\mathrm{JA}} \quad$ Package thermal impedance ${ }^{(3)}$ |  | D package |  | 73 | ${ }^{\circ} \mathrm{C} / \mathrm{W}$ |
|  |  | DGV package |  | 120 |  |
|  |  | DW package |  | 57 |  |
|  |  | PW package |  | 108 |  |
|  |  | RGV package |  | 51.38 |  |
|  |  | RGY package |  | 50 |  |
| $\mathrm{P}_{\text {tot }}$ | Total power dissipation |  |  | 400 | mW |
| $\mathrm{T}_{\text {stg }}$ | Storage temperature range |  | -65 | 150 | ${ }^{\circ} \mathrm{C}$ |
| $\mathrm{T}_{\mathrm{A}}$ | Operating free-air temperature range |  | -40 | 85 | ${ }^{\circ} \mathrm{C}$ |

(1) Stresses beyond those listed under "absolute maximum ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated under "recommended operating conditions" is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.
(2) The input negative-voltage and output voltage ratings may be exceeded if the input and output current ratings are observed.
(3) The package thermal impedance is calculated in accordance with JESD 51-7.

Recommended Operating Conditions ${ }^{(1)}$

|  |  |  | MIN | MAX | UNIT |
| :---: | :---: | :---: | :---: | :---: | :---: |
| $\mathrm{V}_{\mathrm{CC}}$ | Supply voltage |  | 2.3 | 5.5 | V |
|  |  | SCL, SDA | $0.7 \times \mathrm{V}_{\text {CC }}$ | 6 | V |
| $\mathrm{V}_{\mathrm{IH}}$ | Hign-level input voltage | A2-A0, RESET | $0.7 \times \mathrm{V}_{\mathrm{CC}}$ | $\mathrm{V}_{C C}+0.5$ |  |
|  |  | SCL, SDA | -0.5 | $0.3 \times \mathrm{V}_{\text {CC }}$ | V |
| VIL | Low-level input voltage | A2-A0, RESET | -0.5 | $0.3 \times \mathrm{V}_{\mathrm{CC}}$ |  |
| $\mathrm{T}_{\mathrm{A}}$ | Operating free-air tempe |  | -40 | 85 | ${ }^{\circ} \mathrm{C}$ |

(1) All unused inputs of the device must be held at $\mathrm{V}_{\mathrm{CC}}$ or GND to ensure proper device operation. Refer to the TI application report, Implications of Slow or Floating CMOS Inputs, literature number SCBA004.

## Electrical Characteristics

over recommended operating free-air temperature range (unless otherwise noted)

| PARAMETER |  |  | TEST CONDITIONS |  | $\mathrm{V}_{\mathrm{Cc}}$ | MIN | TYP ${ }^{(1)}$ | MAX | $\begin{gathered} \hline \text { UNIT } \\ \hline \mathrm{V} \\ \hline \end{gathered}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $\mathrm{V}_{\mathrm{POR}}$ | Power-on reset voltage ${ }^{(2)}$ |  | No load, | $\mathrm{V}_{\mathrm{I}}=\mathrm{V}_{\mathrm{CC}}$ or GND | $\mathrm{V}_{\mathrm{POR}}$ |  | 1.6 | 2.1 |  |
| $V_{\text {pass }}$ | Switch output voltage |  | $\mathrm{V}_{\text {SWin }}=\mathrm{V}_{\mathrm{CC}}$, | $\mathrm{Is}_{\text {Sout }}=-100 \mu \mathrm{~A}$ | 5 V |  | 3.6 |  | V |
|  |  |  | 4.5 V to 5.5 V |  | 2.6 |  | 4.5 |  |
|  |  |  | 3.3 V |  |  | 1.9 |  |  |
|  |  |  | 3 V to 3.6 V |  | 1.6 |  | 2.8 |  |
|  |  |  | 2.5 V |  |  | 1.5 |  |  |
|  |  |  | 2.3 V to 2.7 V |  | 1.1 |  | 2 |  |
| $\mathrm{l}_{\mathrm{OL}}$ | SCL, SDA |  |  | $\mathrm{V}_{\mathrm{OL}}=0.4 \mathrm{~V}$ |  | 2.3 V to 5.5 V | 3 | 7 |  | mA |
|  |  |  | $\mathrm{V}_{\mathrm{OL}}=0.6 \mathrm{~V}$ | 6 | 10 |  |  |  |  |
| 1 | SCL, SDA |  |  | $\mathrm{V}_{\mathrm{I}}=\mathrm{V}_{\mathrm{CC}} \text { or } \mathrm{GND}$ |  | 2.3 V to 5.5 V |  |  | $\pm 1$ | $\mu \mathrm{A}$ |
|  | SC3-SC0, SD3-SD0 |  |  |  |  |  |  | $\pm 1$ |  |  |
|  | A2-A0 |  |  |  |  |  |  | $\pm 1$ |  |  |
|  | RESET |  |  |  |  |  |  | $\pm 1$ |  |  |
| Icc | Operating mode | $\mathrm{f}_{\mathrm{SCL}}=100 \mathrm{kHz}$ | $\mathrm{V}_{\mathrm{I}}=\mathrm{V}_{\text {CC }}$ or GND, | $\mathrm{I}_{0}=0$ | 5.5 V |  |  | 3 | 12 | $\mu \mathrm{A}$ |
|  |  |  |  |  | 3.6 V |  |  | 3 | 11 |  |
|  |  |  |  |  | 2.7 V |  |  | 3 | 10 |  |
|  | Standby mode | Low inputs | $\mathrm{V}_{\mathrm{l}}=\mathrm{GND}$, | $\mathrm{l}_{0}=0$ | 5.5 V |  | 0.3 | 1 |  |  |
|  |  |  |  |  | 3.6 V |  | 0.1 | 1 |  |  |
|  |  |  |  |  | 2.7 V |  | 0.1 | 1 |  |  |
|  |  | High inputs | $\mathrm{V}_{1}=\mathrm{V}_{\mathrm{CC}}$, | $\mathrm{I}_{0}=0$ | 5.5 V |  | 0.3 | 1 |  |  |
|  |  |  |  |  | 3.6 V |  | 0.1 | 1 |  |  |
|  |  |  |  |  | 2.7 V |  | 0.1 | 1 |  |  |
| $\Delta \mathrm{l}_{\text {cc }}$ | Supply-current change | SCL, SDA | SCL or SDA input at 0.6 V , Other inputs at $\mathrm{V}_{\mathrm{CC}}$ or GND |  |  |  | 8 | 15 | $\mu \mathrm{A}$ |  |
|  |  |  | SCL or SDA input at $\mathrm{V}_{\mathrm{CC}}-0.6 \mathrm{~V}$, Other inputs at $\mathrm{V}_{\mathrm{CC}}$ or GND |  | 2.3 V to 5.5 V |  | 8 | 15 |  |  |
| $\mathrm{C}_{i}$ | A2-A0 |  | $\mathrm{V}_{\mathrm{I}}=\mathrm{V}_{\mathrm{CC}}$ or GND |  | 2.3 V to 5.5 V |  | 4.5 | 6 | pF |  |
|  | RESET |  |  |  |  | 4.5 | 5.5 |  |  |
| $\mathrm{C}_{\mathrm{io}(\mathrm{OFF})}{ }^{(3)}$ | SCL, SDA |  | $\mathrm{V}_{\mathrm{I}}=\mathrm{V}_{\mathrm{CC}}$ or GND, | Switch OFF |  | 2.3 V to 5.5 V |  | 15 | 19 | pF |
|  | SC3-SC0, SD3-SD0 |  |  |  |  |  | 6 | 8 |  |  |
| $\mathrm{R}_{\mathrm{ON}}$ | Switch on-state resistance |  | $\mathrm{V}_{\mathrm{O}}=0.4 \mathrm{~V}$, | $\mathrm{I}_{\mathrm{O}}=15 \mathrm{~mA}$ | 4.5 V to 5.5 V | 4 | 9 | 16 | $\Omega$ |  |
|  |  |  | 3 V to 3.6 V |  | 5 | 11 | 20 |  |  |
|  |  |  | $\mathrm{V}_{\mathrm{O}}=0.4 \mathrm{~V}$, | $\mathrm{I}_{0}=10 \mathrm{~mA}$ | 2.3 V to 2.7 V | 7 | 16 | 45 |  |  |

(1) All typical values are at nominal supply voltage ( $2.5-\mathrm{V}, 3.3-\mathrm{V}$, or $5-\mathrm{V} \mathrm{V}_{\mathrm{CC}}$ ), $\mathrm{T}_{\mathrm{A}}=25^{\circ} \mathrm{C}$.
(2) The power-on reset circuit resets the $I^{2} \mathrm{C}$ bus logic with $\mathrm{V}_{C C}<\mathrm{V}_{P O R}$. $\mathrm{V}_{C C}$ must be lowered to 0.2 V to reset the device.
(3) $\mathrm{C}_{\mathrm{io}(\mathrm{ON})}$ depends on internal capacitance and external capacitance added to the SCn lines when channels(s) are ON .

WITH RESET FUNCTION
SCPS148E-OCTOBER 2005-REVISED JANUARY 2008

## $I^{2} \mathrm{C}$ Interface Timing Requirements

over recommended operating free-air temperature range (unless otherwise noted) (see Figure 10)

|  |  |  | STANDARD MODE $1^{2} \mathrm{C}$ BUS | FAST MODE $I^{2} \mathrm{C}$ BUS | UNIT |
| :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  | MIN MAX | MIN MAX |  |
| $\mathrm{f}_{\text {scl }}$ | $\mathrm{I}^{2} \mathrm{C}$ clock frequency |  | 0100 | $0 \quad 400$ | kHz |
| $\mathrm{t}_{\text {sch }}$ | $1^{2} \mathrm{C}$ clock high time |  | 4 | 0.6 | $\mu \mathrm{s}$ |
| $\mathrm{t}_{\text {scl }}$ | $1^{2} \mathrm{C}$ clock low time |  | 4.7 | 1.3 | $\mu \mathrm{s}$ |
| $\mathrm{t}_{\text {sp }}$ | $1^{2} \mathrm{C}$ spike time |  | 50 | 50 | ns |
| $\mathrm{t}_{\text {sds }}$ | $1^{2} \mathrm{C}$ serial-data setup time |  | 250 | 100 | ns |
| $\mathrm{t}_{\text {sah }}$ | $1^{2} \mathrm{C}$ serial-data hold time |  | $0^{(1)}$ | $0^{(1)}$ | $\mu \mathrm{s}$ |
| $\mathrm{t}_{\text {icr }}$ | $1^{2} \mathrm{C}$ input rise time |  | 1000 | $20+0.1 \mathrm{C}_{\mathrm{b}}{ }^{(2)} \quad 300$ | ns |
| $\mathrm{t}_{\text {cff }}$ | $1^{2} \mathrm{C}$ input fall time |  | 300 | $20+0.1 \mathrm{C}_{\mathrm{b}}{ }^{(2)} \quad 300$ | ns |
| $\mathrm{t}_{\text {ocf }}$ | $1^{2} \mathrm{C}$ output fall time | $10-\mathrm{pF}$ to $400-\mathrm{pF}$ bus | 300 | $20+0.1 \mathrm{C}_{\mathrm{b}}{ }^{(2)} \quad 300$ | ns |
| $\mathrm{t}_{\text {buf }}$ | $I^{2} \mathrm{C}$ bus free time between stop and | start | 4.7 | 1.3 | $\mu \mathrm{S}$ |
| $\mathrm{t}_{\text {sts }}$ | $1^{2} \mathrm{C}$ start or repeated start conditio | setup | 4.7 | 0.6 | $\mu \mathrm{s}$ |
| $\mathrm{t}_{\text {sth }}$ | $\mathrm{I}^{2} \mathrm{C}$ start or repeated start conditio | hold | 4 | 0.6 | $\mu \mathrm{s}$ |
| $\mathrm{t}_{\text {sps }}$ | $1^{2} \mathrm{C}$ stop condition setup |  | 4 | 0.6 | $\mu \mathrm{s}$ |
| $\mathrm{t}_{\mathrm{vdL}}$ (Data) | Valid-data time (high to low) ${ }^{(3)}$ | SCL low to SDA output low valid | 1 | 1 | $\mu \mathrm{S}$ |
| $\mathrm{tvaH}_{\text {(Data) }}$ | Valid-data time (low to high) ${ }^{(3)}$ | SCL low to SDA output high valid | 0.6 | 0.6 | $\mu \mathrm{S}$ |
| $\mathrm{t}_{\mathrm{v}}($ (ack) | Valid-data time of ACK condition | ACK signal from SCL low to SDA output low | 1 | 1 | $\mu \mathrm{S}$ |
| $\mathrm{C}_{\mathrm{b}}$ | $1^{2} \mathrm{C}$ bus capacitive load |  | 400 | 400 | pF |

(1) A device internally must provide a hold time of at least 300 ns for the SDA signal (referred to the $\mathrm{V}_{\mathrm{IH}}$ min of the SCL signal), in order to bridge the undefined region of the falling edge of SCL.
(2) $\mathrm{C}_{\mathrm{b}}=$ total bus capacitance of one bus line in pF
(3) Data taken using a $1-\mathrm{k} \Omega$ pullup resistor and $50-\mathrm{pF}$ load (see Figure 10)

## Switching Characteristics

over recommended operating free-air temperature range, $\mathrm{C}_{\mathrm{L}} \leq 100 \mathrm{pF}$ (unless otherwise noted) (see Figure 10)

| PARAMETER |  |  | FROM (INPUT) | TO (OUTPUT) | MIN MAX | UNIT |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $\mathrm{tpd}{ }^{(1)}$ | Propagation delay time | $\mathrm{R}_{\mathrm{ON}}=20 \Omega, \mathrm{C}_{\mathrm{L}}=15 \mathrm{pF}$ | SDA or SCL | SDn or SCn | 0.3 | ns |
|  |  | $\mathrm{R}_{\mathrm{ON}}=20 \Omega, \mathrm{C}_{\mathrm{L}}=50 \mathrm{pF}$ |  |  | 1 |  |

(1) The propagation delay is the calculated RC time constant of the typical ON-state resistance of the switch and the specified load capacitance, when driven by an ideal voltage source (zero output impedance).

## Interrupt and Reset Timing Requirements

over recommended operating free-air temperature range (unless otherwise noted)

| PARAMETER |  | MIN | MAX | UNIT |
| :---: | :---: | :---: | :---: | :---: |
| $\mathrm{t}_{\text {WL }}$ | Pulse duration, $\overline{\text { RESET }}$ low | 6 |  | ns |
| $\mathrm{trst}^{(1)}$ | $\overline{\text { RESET }}$ time (SDA clear) |  | 500 | ns |
| $\mathrm{t}_{\text {REC(STA) }}$ | Recovery time from RESET to start | 0 |  | ns |

(1) $t_{r s t}$ is the propagation delay measured from the time the RESET pin is first asserted low to the time the SDA pin is asserted high, signaling a stop condition. It must be a minimum of $t_{W L}$.

PARAMETER MEASUREMENT INFORMATION

${ }^{2}{ }^{2} \mathrm{C}$ PORT LOAD CONFIGURATION


| BYTE | DESCRIPTION |
| :---: | :---: |
| 1 | ${ }^{2} \mathrm{C}$ address $+\mathrm{R} / \overline{\mathrm{W}}$ |
| 2 | Control register data |



VOLTAGE WAVEFORMS
A. $\quad C_{L}$ includes probe and jig capacitance.
B. All input pulses are supplied by generators having the following characteristics: $\mathrm{PRR} \leq 10 \mathrm{MHz}, \mathrm{Z}_{\mathrm{O}}=50 \Omega$, $\mathrm{t}_{\mathrm{r}} / \mathrm{t}_{\mathrm{f}} \leq 30 \mathrm{~ns}$.
C. The outputs are measured one at a time, with one transition per measurement.

Figure 10. ${ }^{2}$ C Interface Load Circuit, Byte Descriptions, and Voltage Waveforms

PARAMETER MEASUREMENT INFORMATION (continued)


Figure 11. Reset Timing

## APPLICATION INFORMATION

Figure 12 shows an application in which the PCA9546A can be used.

A. Pin numbers shown are for the D, DGV, DW, PW, and RGY packages.

Figure 12. Typical Application

## PACKAGING INFORMATION

| Orderable Device | Status ${ }^{(1)}$ | Package Type | Package Drawing | Pins | Package Qty | $\text { Eco Plan }{ }^{(2)}$ | Lead/Ball Finish | MSL Peak Temp ${ }^{(3)}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| PCA9546AD | ACTIVE | SOIC | D | 16 | 40 | Green (RoHS \& no $\mathrm{Sb} / \mathrm{Br}$ ) | CU NIPDAU | Level-1-260C-UNLIM |
| PCA9546ADG4 | ACTIVE | SOIC | D | 16 | 40 | Green (RoHS \& no $\mathrm{Sb} / \mathrm{Br}$ ) | CU NIPDAU | Level-1-260C-UNLIM |
| PCA9546ADGVR | ACTIVE | TVSOP | DGV | 16 | 2000 | Green (RoHS \& no $\mathrm{Sb} / \mathrm{Br}$ ) | CU NIPDAU | Level-1-260C-UNLIM |
| PCA9546ADGVRG4 | ACTIVE | TVSOP | DGV | 16 | 2000 | Green (RoHS \& no $\mathrm{Sb} / \mathrm{Br}$ ) | CU NIPDAU | Level-1-260C-UNLIM |
| PCA9546ADR | ACTIVE | SOIC | D | 16 | 2500 | Green (RoHS \& no $\mathrm{Sb} / \mathrm{Br}$ ) | CU NIPDAU | Level-1-260C-UNLIM |
| PCA9546ADRG4 | ACTIVE | SOIC | D | 16 | 2500 | Green (RoHS \& no $\mathrm{Sb} / \mathrm{Br}$ ) | CU NIPDAU | Level-1-260C-UNLIM |
| PCA9546ADT | ACTIVE | SOIC | D | 16 | 250 | Green (RoHS \& no $\mathrm{Sb} / \mathrm{Br}$ ) | CU NIPDAU | Level-1-260C-UNLIM |
| PCA9546ADTG4 | ACTIVE | SOIC | D | 16 | 250 | Green (RoHS \& no $\mathrm{Sb} / \mathrm{Br}$ ) | CU NIPDAU | Level-1-260C-UNLIM |
| PCA9546ADW | ACTIVE | SOIC | DW | 16 | 40 | Green (RoHS \& no $\mathrm{Sb} / \mathrm{Br}$ ) | CU NIPDAU | Level-1-260C-UNLIM |
| PCA9546ADWG4 | ACTIVE | SOIC | DW | 16 | 40 | Green (RoHS \& no $\mathrm{Sb} / \mathrm{Br}$ ) | CU NIPDAU | Level-1-260C-UNLIM |
| PCA9546ADWR | ACTIVE | SOIC | DW | 16 | 2000 | Green (RoHS \& no $\mathrm{Sb} / \mathrm{Br}$ ) | CU NIPDAU | Level-1-260C-UNLIM |
| PCA9546ADWRG4 | ACTIVE | SOIC | DW | 16 | 2000 | Green (RoHS \& no $\mathrm{Sb} / \mathrm{Br}$ ) | CU NIPDAU | Level-1-260C-UNLIM |
| PCA9546APW | ACTIVE | TSSOP | PW | 16 | 90 | Green (RoHS \& no Sb/Br) | CU NIPDAU | Level-1-260C-UNLIM |
| PCA9546APWE4 | ACTIVE | TSSOP | PW | 16 | 90 | Green (RoHS \& no $\mathrm{Sb} / \mathrm{Br}$ ) | CU NIPDAU | Level-1-260C-UNLIM |
| PCA9546APWG4 | ACTIVE | TSSOP | PW | 16 | 90 | Green (RoHS \& no $\mathrm{Sb} / \mathrm{Br}$ ) | CU NIPDAU | Level-1-260C-UNLIM |
| PCA9546APWR | ACTIVE | TSSOP | PW | 16 | 2000 | Green (RoHS \& no Sb/Br) | CU NIPDAU | Level-1-260C-UNLIM |
| PCA9546APWRE4 | ACTIVE | TSSOP | PW | 16 | 2000 | Green (RoHS \& no $\mathrm{Sb} / \mathrm{Br}$ ) | CU NIPDAU | Level-1-260C-UNLIM |
| PCA9546APWRG4 | ACTIVE | TSSOP | PW | 16 | 2000 | Green (RoHS \& no $\mathrm{Sb} / \mathrm{Br}$ ) | CU NIPDAU | Level-1-260C-UNLIM |
| PCA9546APWT | ACTIVE | TSSOP | PW | 16 | 250 | Green (RoHS \& no $\mathrm{Sb} / \mathrm{Br}$ ) | CU NIPDAU | Level-1-260C-UNLIM |
| PCA9546APWTE4 | ACTIVE | TSSOP | PW | 16 | 250 | Green (RoHS \& no $\mathrm{Sb} / \mathrm{Br}$ ) | CU NIPDAU | Level-1-260C-UNLIM |
| PCA9546APWTG4 | ACTIVE | TSSOP | PW | 16 | 250 | Green (RoHS \& no $\mathrm{Sb} / \mathrm{Br}$ ) | CU NIPDAU | Level-1-260C-UNLIM |
| PCA9546ARGVR | ACTIVE | VQFN | RGV | 16 | 2500 | Green (RoHS \& no $\mathrm{Sb} / \mathrm{Br}$ ) | CU NIPDAU | Level-2-260C-1 YEAR |
| PCA9546ARGVRG4 | ACTIVE | VQFN | RGV | 16 | 2500 | Green (RoHS \& no Sb/Br) | CU NIPDAU | Level-2-260C-1 YEAR |
| PCA9546ARGYR | ACTIVE | VQFN | RGY | 16 | 3000 | Green (RoHS \& no $\mathrm{Sb} / \mathrm{Br}$ ) | CU NIPDAU | Level-2-260C-1 YEAR |
| PCA9546ARGYRG4 | ACTIVE | VQFN | RGY | 16 | 3000 | Green (RoHS \& no $\mathrm{Sb} / \mathrm{Br}$ ) | CU NIPDAU | Level-2-260C-1 YEAR |

${ }^{(1)}$ The marketing status values are defined as follows:
ACTIVE: Product device recommended for new designs.
LIFEBUY: TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.
NRND: Not recommended for new designs. Device is in production to support existing customers, but Tl does not recommend using this part in a new design.
PREVIEW: Device has been announced but is not in production. Samples may or may not be available.
OBSOLETE: TI has discontinued the production of the device.
${ }^{(2)}$ Eco Plan - The planned eco-friendly classification: Pb-Free (RoHS), Pb-Free (RoHS Exempt), or Green (RoHS \& no Sb/Br) - please check http://www.ti.com/productcontent for the latest availability information and additional product content details.
TBD: The $\mathrm{Pb}-\mathrm{Free} / \mathrm{Green}$ conversion plan has not been defined.
Pb-Free (RoHS): TI's terms "Lead-Free" or "Pb-Free" mean semiconductor products that are compatible with the current RoHS requirements for all 6 substances, including the requirement that lead not exceed $0.1 \%$ by weight in homogeneous materials. Where designed to be soldered at high temperatures, TI Pb-Free products are suitable for use in specified lead-free processes.
Pb -Free (RoHS Exempt): This component has a RoHS exemption for either 1) lead-based flip-chip solder bumps used between the die and package, or 2) lead-based die adhesive used between the die and leadframe. The component is otherwise considered Pb-Free (RoHS compatible) as defined above.
Green (RoHS \& no Sb/Br): TI defines "Green" to mean Pb-Free (RoHS compatible), and free of Bromine (Br) and Antimony (Sb) based flame retardants ( Br or Sb do not exceed $0.1 \%$ by weight in homogeneous material)
${ }^{(3)}$ MSL, Peak Temp. -- The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

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## TAPE AND REEL INFORMATION



QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE

*All dimensions are nominal

| Device | Package <br> Type | Package <br> Drawing | Pins | SPQ | Reel <br> Diameter <br> $(\mathbf{m m})$ | Reel <br> Width <br> $\mathbf{W 1}(\mathbf{m m})$ | A0 <br> $(\mathbf{m m})$ | $\mathbf{B 0} \mathbf{( m )}$ <br> $(\mathbf{m m})$ | K0 <br> $(\mathbf{m m})$ | P1 <br> $(\mathbf{m m})$ | $\mathbf{W}$ <br> $(\mathbf{m m})$ | Pin1 <br> Quadrant |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| PCA9546ADGVR | TVSOP | DGV | 16 | 2000 | 330.0 | 12.4 | 6.8 | 4.0 | 1.6 | 8.0 | 12.0 | Q1 |
| PCA9546ADR | SOIC | D | 16 | 2500 | 330.0 | 16.4 | 6.5 | 10.3 | 2.1 | 8.0 | 16.0 | Q1 |
| PCA9546ADWR | SOIC | DW | 16 | 2000 | 330.0 | 16.4 | 10.75 | 10.7 | 2.7 | 12.0 | 16.0 | Q1 |
| PCA9546APWR | TSSOP | PW | 16 | 2000 | 330.0 | 12.4 | 6.9 | 5.6 | 1.6 | 8.0 | 12.0 | Q1 |
| PCA9546ARGVR | VQFN | RGV | 16 | 2500 | 330.0 | 12.4 | 4.25 | 4.25 | 1.15 | 8.0 | 12.0 | Q2 |
| PCA9546ARGYR | VQFN | RGY | 16 | 3000 | 330.0 | 12.4 | 3.8 | 4.3 | 1.5 | 8.0 | 12.0 | Q1 |


*All dimensions are nominal

| Device | Package Type | Package Drawing | Pins | SPQ | Length (mm) | Width (mm) | Height (mm) |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| PCA9546ADGVR | TVSOP | DGV | 16 | 2000 | 346.0 | 346.0 | 29.0 |
| PCA9546ADR | SOIC | D | 16 | 2500 | 333.2 | 345.9 | 28.6 |
| PCA9546ADWR | SOIC | DW | 16 | 2000 | 346.0 | 346.0 | 33.0 |
| PCA9546APWR | TSSOP | PW | 16 | 2000 | 346.0 | 346.0 | 29.0 |
| PCA9546ARGVR | VQFN | RGV | 16 | 2500 | 346.0 | 346.0 | 29.0 |
| PCA9546ARGYR | VQFN | RGY | 16 | 3000 | 346.0 | 346.0 | 29.0 |

D (R-PDSO-G16) PLASTIC SMALL-OUTLINE PACKAGE


NOTES: A. All linear dimensions are in inches (millimeters).
B. This drawing is subject to change without notice.

C Body length does not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not exceed $.006(0,15)$ per end.
(D) Body width does not include interlead flash. Interlead flash shall not exceed $.017(0,43)$ per side.
E. Reference JEDEC MS-012 variation AC.


THERMAL PAD MECHANICAL DATA
RGY (R-PVQFN-N16) PLASTIC QUAD FLATPACK NO-LEAD

THERMAL INFORMATION
This package incorporates an exposed thermal pad that is designed to be attached directly to an external heatsink. The thermal pad must be soldered directly to the printed circuit board (PCB). After soldering, the PCB can be used as a heatsink. In addition, through the use of thermal vias, the thermal pad can be attached directly to the appropriate copper plane shown in the electrical schematic for the device, or alternatively, can be attached to a special heatsink structure designed into the PCB. This design optimizes the heat transfer from the integrated circuit (IC).

For information on the Quad Flatpack No-Lead (QFN) package and its advantages, refer to Application Report, QFN/SON PCB Attachment, Texas Instruments Literature No. SLUA271. This document is available at www.ti.com.

The exposed thermal pad dimensions for this package are shown in the following illustration.


Bottom View

NOTE: All linear dimensions are in millimeters

Exposed Thermal Pad Dimensions


NOTES: A. All linear dimensions are in millimeters.
B. This drawing is subject to change without notice.
C. Publication IPC-7351 is recommended for alternate designs.
D. This package is designed to be soldered to a thermal pad on the board. Refer to Application Note, Quad Flat-Pack QFN/SON PCB Attachment, Texas Instruments Literature No. SLUA271, and also the Product Data Sheets for specific thermal information, via requirements, and recommended board layout. These documents are available at www.ti.com <http: //www.ti.com>.
E. Laser cutting apertures with trapezoidal walls and also rounding corners will offer better paste release. Customers should contact their board assembly site for stencil design recommendations. Refer to IPC 7525 for stencil design considerations.
F. Customers should contact their board fabrication site for minimum solder mask web tolerances between signal pads.


NOTES: A. All linear dimensions are in millimeters. Dimensioning and tolerancing per ASME Y14.5M-1994.
B. This drawing is subject to change without notice.
C. Quad Flatpack, No-leads (QFN) package configuration.

D The package thermal pad must be soldered to the board for thermal and mechanical performance. See the Product Data Sheet for details regarding the exposed thermal pad dimensions.
E. Falls within JEDEC MO-220.

THERMAL PAD MECHANICAL DATA
RGV (S-PVQFN-N16) PLASTIC QUAD FLATPACK NO-LEAD

## THERMAL INFORMATION

This package incorporates an exposed thermal pad that is designed to be attached directly to an external heatsink. The thermal pad must be soldered directly to the printed circuit board (PCB). After soldering, the PCB can be used as a heatsink. In addition, through the use of thermal vias, the thermal pad can be attached directly to the appropriate copper plane shown in the electrical schematic for the device, or alternatively, can be attached to a special heatsink structure designed into the PCB. This design optimizes the heat transfer from the integrated circuit (IC).
For information on the Quad Flatpack No-Lead (QFN) package and its advantages, refer to Application Report, QFN/SON PCB Attachment, Texas Instruments Literature No. SLUA271. This document is available at www.ti.com.

The exposed thermal pad dimensions for this package are shown in the following illustration.


Bottom View
NOTE: All linear dimensions are in millimeters

Exposed Thermal Pad Dimensions

RGV (S-PVQFN-N16)


NOTES: A. All linear dimensions are in millimeters.
B. This drawing is subject to change without notice.
C. Publication IPC-7351 is recommended for alternate designs.
D. This package is designed to be soldered to a thermal pad on the board. Refer to Application Note, QFN Packages, Texas Instruments Literature No. SLUA271, and also the Product Data Sheets for specific thermal information, via requirements, and recommended board layout. These documents are available at www.ti.com <http: //www.ti.com>.
E. Laser cutting apertures with trapezoidal walls and also rounding corners will offer better paste release. Customers should contact their board assembly site for stencil design recommendations. Refer to IPC 7525 for stencil design considerations.
F. Customers should contact their board fabrication site for solder mask tolerances.

DW (R-PDSO-G16)

## PLASTIC SMALL-OUTLINE PACKAGE



NOTES: A. All linear dimensions are in inches (millimeters).
B. This drawing is subject to change without notice.
C. Body dimensions do not include mold flash or protrusion not to exceed $0.006(0,15)$.
D. Falls within JEDEC MS-013 variation AA.


| PIMS $^{* *}$ | $\mathbf{8}$ | $\mathbf{1 4}$ | $\mathbf{1 6}$ | $\mathbf{2 0}$ | $\mathbf{2 4}$ | $\mathbf{2 8}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| A MAX | 3,10 | 5,10 | 5,10 | 6,60 | 7,90 | 9,80 |
| A MIN | 2,90 | 4,90 | 4,90 | 6,40 | 7,70 | 9,60 |

NOTES: A. All linear dimensions are in millimeters.
B. This drawing is subject to change without notice.
C. Body dimensions do not include mold flash or protrusion not to exceed 0,15 .
D. Falls within JEDEC MO-153

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