



## K10 Sub-Family Data Sheet

Supports the following:

MK10N512VLK100, MK10N512VMB100

### Features

- Operating Characteristics
  - Voltage range: 1.71 to 3.6 V
  - Flash write voltage range: 1.71 to 3.6 V
  - Temperature range (ambient): -40 to 105°C
- Performance
  - Up to 100 MHz ARM Cortex-M4 core with DSP instructions delivering 1.25 Dhrystone MIPS per MHz
- Memories and memory interfaces
  - Up to 512 KB program flash memory on non-FlexMemory devices
  - Up to 128 KB RAM
  - Serial programming interface (EzPort)
  - FlexBus external bus interface
- Clocks
  - 1 to 32 MHz crystal oscillator
  - 32 kHz crystal oscillator
  - Multi-purpose clock generator
- System peripherals
  - 10 low-power modes to provide power optimization based on application requirements
  - Memory protection unit with multi-master protection
  - 16-channel DMA controller, supporting up to 64 request sources
  - External watchdog monitor
  - Software watchdog
  - Low-leakage wakeup unit
- Security and integrity modules
  - Hardware CRC module to support fast cyclic redundancy checks
  - Hardware random-number generator
  - 128-bit unique identification (ID) number per chip
- Human-machine interface
  - Low-power hardware touch sensor interface (TSI)
  - General-purpose input/output
- Analog modules
  - 16-bit SAR ADC with PGA (x64)
  - 12-bit DAC
  - Analog comparator (CMP) containing a 6-bit DAC and programmable reference input
  - Voltage reference
- Timers
  - Programmable delay block
  - Eight-channel motor control/general purpose/PWM timers
  - Two-channel quadrature decoder/general purpose timers
  - Periodic interrupt timers
  - 16-bit low-power timer
  - Carrier modulator transmitter
  - Real-time clock
- Communication interfaces
  - Controller Area Network (CAN) module
  - SPI modules
  - I2C modules
  - UART modules
  - Secure Digital host controller (SDHC)
  - I2S



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Preliminary

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Preliminary

# 1 Ordering parts

## 1.1 Determining valid orderable parts

Valid orderable part numbers are provided on the web. To determine the orderable part numbers for this device, go to [www.freescale.com](http://www.freescale.com) and perform a part number search for the following device numbers: PK10 and MK10.

## 2 Part identification

### 2.1 Description

Part numbers for the chip have fields that identify the specific part. You can use the values of these fields to determine the specific part you have received.

### 2.2 Format

Part numbers for this device have the following format:

Q K## M FFF T PP CCC N

### 2.3 Fields

This table lists the possible values for each field in the part number (not all combinations are valid):

| Field | Description          | Values                                                                                                                    |
|-------|----------------------|---------------------------------------------------------------------------------------------------------------------------|
| Q     | Qualification status | <ul style="list-style-type: none"><li>• M = Fully qualified, general market flow</li><li>• P = Prequalification</li></ul> |
| K##   | Kinetis family       | <ul style="list-style-type: none"><li>• K10</li></ul>                                                                     |
| M     | Flash memory type    | <ul style="list-style-type: none"><li>• N = Program flash only</li><li>• X = Program flash and FlexMemory</li></ul>       |

Table continues on the next page...

| Field | Description                 | Values                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            |
|-------|-----------------------------|-----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| FFF   | Program flash memory size   | <ul style="list-style-type: none"> <li>• 32 = 32 KB</li> <li>• 64 = 64 KB</li> <li>• 128 = 128 KB</li> <li>• 256 = 256 KB</li> <li>• 512 = 512 KB</li> <li>• 1M0 = 1 MB</li> </ul>                                                                                                                                                                                                                                                                                                                                                                                                |
| T     | Temperature range (°C)      | <ul style="list-style-type: none"> <li>• V = –40 to 105</li> </ul>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                |
| PP    | Package identifier          | <ul style="list-style-type: none"> <li>• FM = 32 QFN (5 mm x 5 mm)</li> <li>• FT = 48 QFN (7 mm x 7 mm)</li> <li>• LF = 48 LQFP (7 mm x 7 mm)</li> <li>• FX = 64 QFN (9 mm x 9 mm)</li> <li>• LH = 64 LQFP (10 mm x 10 mm)</li> <li>• LK = 80 LQFP (12 mm x 12 mm)</li> <li>• MB = 81 MAPBGA (8 mm x 8 mm)</li> <li>• LL = 100 LQFP (14 mm x 14 mm)</li> <li>• ML = 104 MAPBGA (8 mm x 8 mm)</li> <li>• LQ = 144 LQFP (20 mm x 20 mm)</li> <li>• MD = 144 MAPBGA (13 mm x 13 mm)</li> <li>• MF = 196 MAPBGA (15 mm x 15 mm)</li> <li>• MJ = 256 MAPBGA (17 mm x 17 mm)</li> </ul> |
| CCC   | Maximum CPU frequency (MHz) | <ul style="list-style-type: none"> <li>• 50 = 50 MHz</li> <li>• 72 = 72 MHz</li> <li>• 100 = 100 MHz</li> <li>• 120 = 120 MHz</li> <li>• 150 = 150 MHz</li> </ul>                                                                                                                                                                                                                                                                                                                                                                                                                 |
| N     | Packaging type              | <ul style="list-style-type: none"> <li>• R = Tape and reel</li> <li>• (Blank) = Trays</li> </ul>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  |

## 2.4 Example

This is an example part number:

MK10N512VMD100

## 3 Terminology and guidelines

### 3.1 Definition: Operating requirement

An *operating requirement* is a specified value or range of values for a technical characteristic that you must guarantee during operation to avoid incorrect operation and possibly decreasing the useful life of the chip.

### 3.1.1 Example

This is an example of an operating requirement, which you must meet for the accompanying operating behaviors to be guaranteed:

| Symbol          | Description               | Min. | Max. | Unit |
|-----------------|---------------------------|------|------|------|
| V <sub>DD</sub> | 1.0 V core supply voltage | 0.9  | 1.1  | V    |

## 3.2 Definition: Operating behavior

An *operating behavior* is a specified value or range of values for a technical characteristic that are guaranteed during operation if you meet the operating requirements and any other specified conditions.

### 3.2.1 Example

This is an example of an operating behavior, which is guaranteed if you meet the accompanying operating requirements:

| Symbol          | Description                              | Min. | Max. | Unit |
|-----------------|------------------------------------------|------|------|------|
| I <sub>WP</sub> | Digital I/O weak pullup/pulldown current | 10   | 130  | μA   |

## 3.3 Definition: Attribute

An *attribute* is a specified value or range of values for a technical characteristic that are guaranteed, regardless of whether you meet the operating requirements.

### 3.3.1 Example

This is an example of an attribute:

| Symbol | Description                     | Min. | Max. | Unit |
|--------|---------------------------------|------|------|------|
| CIN_D  | Input capacitance: digital pins | —    | 7    | pF   |

### 3.4 Definition: Rating

A *rating* is a minimum or maximum value of a technical characteristic that, if exceeded, may cause permanent chip failure:

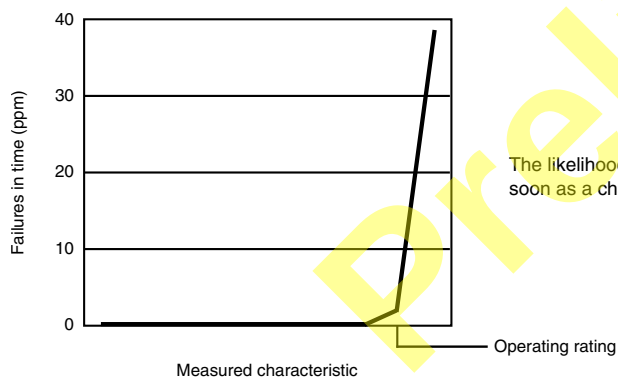
- *Operating ratings* apply during operation of the chip.
- *Handling ratings* apply when the chip is not powered.

#### 3.4.1 Example

This is an example of an operating rating:

| Symbol          | Description               | Min. | Max. | Unit |
|-----------------|---------------------------|------|------|------|
| V <sub>DD</sub> | 1.0 V core supply voltage | −0.3 | 1.2  | V    |

### 3.5 Result of exceeding a rating



The likelihood of permanent chip failure increases rapidly as soon as a characteristic begins to exceed one of its operating ratings.

## 3.6 Relationship between ratings and operating requirements

| Operating or handling rating (min.)                    |                                                                                                                             | Operating requirement (min.)                                                       |                                                                                                                             | Operating requirement (max.)                        |  | Operating or handling rating (max.)                    |  |
|--------------------------------------------------------|-----------------------------------------------------------------------------------------------------------------------------|------------------------------------------------------------------------------------|-----------------------------------------------------------------------------------------------------------------------------|-----------------------------------------------------|--|--------------------------------------------------------|--|
| <b>Fatal range</b><br><br>- Probable permanent failure | <b>Limited operating range</b><br><br>- No permanent failure<br>- Possible decreased life<br>- Possible incorrect operation | <b>Normal operating range</b><br><br>- No permanent failure<br>- Correct operation | <b>Limited operating range</b><br><br>- No permanent failure<br>- Possible decreased life<br>- Possible incorrect operation | <b>Handling range</b><br><br>- No permanent failure |  | <b>Fatal range</b><br><br>- Probable permanent failure |  |

## 3.7 Guidelines for ratings and operating requirements

Follow these guidelines for ratings and operating requirements:

- Never exceed any of the chip's ratings.
- During normal operation, don't exceed any of the chip's operating requirements.
- If you must exceed an operating requirement at times other than during normal operation (for example, during power sequencing), limit the duration as much as possible.

## 3.8 Definition: Typical value

A *typical value* is a specified value for a technical characteristic that:

- Lies within the range of values specified by the operating behavior
- Given the typical manufacturing process, is representative of that characteristic during operation when you meet the typical-value conditions or other specified conditions

Typical values are provided as design guidelines and are neither tested nor guaranteed.

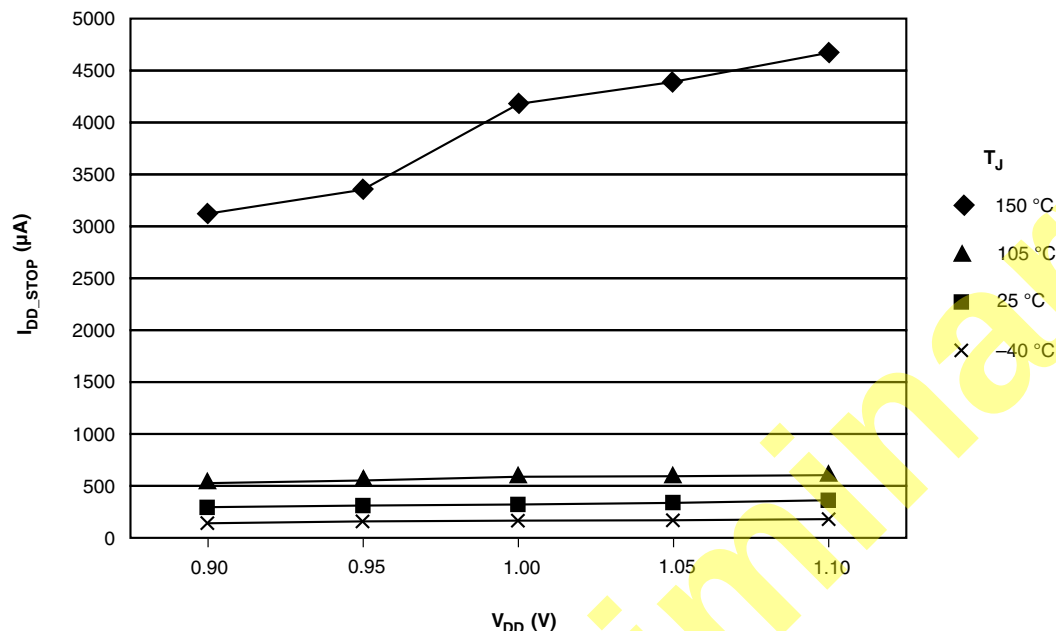
### 3.8.1 Example 1

This is an example of an operating behavior that includes a typical value:

| Symbol          | Description                              | Min. | Typ. | Max. | Unit |
|-----------------|------------------------------------------|------|------|------|------|
| I <sub>WP</sub> | Digital I/O weak pullup/pulldown current | 10   | 70   | 130  | μA   |

### 3.8.2 Example 2

This is an example of a chart that shows typical values for various voltage and temperature conditions:



## 3.9 Typical Value Conditions

Typical values assume you meet the following conditions (or other conditions as specified):

| Symbol          | Description          | Value | Unit |
|-----------------|----------------------|-------|------|
| T <sub>A</sub>  | Ambient temperature  | 25    | °C   |
| V <sub>DD</sub> | 3.3 V supply voltage | 3.3   | V    |

## 4 Ratings

## 4.1 Thermal handling ratings

| Symbol           | Description                   | Min. | Max. | Unit | Notes |
|------------------|-------------------------------|------|------|------|-------|
| T <sub>STG</sub> | Storage temperature           | −55  | 150  | °C   | 1     |
| T <sub>SDR</sub> | Solder temperature, lead-free | —    | 260  | °C   | 2     |
|                  | Solder temperature, leaded    | —    | 245  |      |       |

1. Determined according to JEDEC Standard JESD22-A103, *High Temperature Storage Life*.
2. Determined according to IPC/JEDEC Standard J-STD-020, *Moisture/Reflow Sensitivity Classification for Nonhermetic Solid State Surface Mount Devices*.

## 4.2 Moisture handling ratings

| Symbol | Description                | Min. | Max. | Unit | Notes |
|--------|----------------------------|------|------|------|-------|
| MSL    | Moisture sensitivity level | —    | 3    | —    | 1     |

1. Determined according to IPC/JEDEC Standard J-STD-020, *Moisture/Reflow Sensitivity Classification for Nonhermetic Solid State Surface Mount Devices*.

## 4.3 ESD handling ratings

| Symbol           | Description                                           | Min.  | Max.  | Unit | Notes |
|------------------|-------------------------------------------------------|-------|-------|------|-------|
| V <sub>HBM</sub> | Electrostatic discharge voltage, human body model     | −2000 | +2000 | V    | 1     |
| V <sub>CDM</sub> | Electrostatic discharge voltage, charged-device model | −500  | +500  | V    | 2     |
| I <sub>LAT</sub> | Latch-up current at ambient temperature of 85°C       | −100  | +100  | mA   |       |

1. Determined according to JEDEC Standard JESD22-A114, *Electrostatic Discharge (ESD) Sensitivity Testing Human Body Model (HBM)*.
2. Determined according to JEDEC Standard JESD22-C101, *Field-Induced Charged-Device Model Test Method for Electrostatic-Discharge-Withstand Thresholds of Microelectronic Components*.

## 4.4 Voltage and current operating ratings

| Symbol           | Description                                           | Min. | Max.                  | Unit |
|------------------|-------------------------------------------------------|------|-----------------------|------|
| V <sub>DD</sub>  | Digital supply voltage                                | −0.3 | 3.8                   | V    |
| I <sub>DD</sub>  | Digital supply current                                | —    | 185                   | mA   |
| V <sub>DIO</sub> | Digital input voltage (except RESET, EXTAL, and XTAL) | −0.3 | 5.5                   | V    |
| V <sub>AIO</sub> | Analog, RESET, EXTAL, and XTAL input voltage          | −0.3 | V <sub>DD</sub> + 0.3 | V    |

Table continues on the next page...

| Symbol       | Description                                                               | Min.           | Max.           | Unit |
|--------------|---------------------------------------------------------------------------|----------------|----------------|------|
| $I_D$        | Instantaneous maximum current single pin limit (applies to all port pins) | -25            | 25             | mA   |
| $V_{DDA}$    | Analog supply voltage                                                     | $V_{DD} - 0.3$ | $V_{DD} + 0.3$ | V    |
| $I_{DDA}$    | Analog supply current <sup>1</sup>                                        | TBD            | TBD            | mA   |
| $V_{BAT}$    | RTC battery supply voltage                                                | -0.3           | 3.8            | V    |
| $V_{RAM}$    | $V_{DD}$ voltage required to retain RAM                                   | 1.2            | —              | V    |
| $V_{RFVBAT}$ | $V_{BAT}$ voltage required to retain the VBAT register file               | TBD            | —              | V    |

1. The analog supply current is the sum of the active or disabled current for each of the analog modules on the device. See each module's specification for its supply current.

## 5 General

### 5.1 Nonswitching electrical specifications

#### 5.1.1 Voltage and Current Operating Requirements

Table 1. Voltage and current operating requirements

| Symbol             | Description                                                                                                                                                                                   | Min.                 | Max.                 | Unit | Notes |
|--------------------|-----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|----------------------|----------------------|------|-------|
| $V_{DD}$           | Supply voltage                                                                                                                                                                                | 1.71                 | 3.6                  | V    |       |
| $V_{DDA}$          | Analog supply voltage                                                                                                                                                                         | 1.71                 | 3.6                  | V    |       |
| $V_{DD} - V_{DDA}$ | $V_{DD}$ -to- $V_{DDA}$ differential voltage                                                                                                                                                  | -0.1                 | 0.1                  | V    |       |
| $V_{SS} - V_{SSA}$ | $V_{SS}$ -to- $V_{SSA}$ differential voltage                                                                                                                                                  | -0.1                 | 0.1                  | V    |       |
| $V_{IH}$           | Input high voltage <ul style="list-style-type: none"> <li><math>2.7\text{ V} \leq V_{DD} \leq 3.6\text{ V}</math></li> <li><math>1.7\text{ V} \leq V_{DD} \leq 2.7\text{ V}</math></li> </ul> | $0.7 \times V_{DD}$  | —                    | V    |       |
|                    |                                                                                                                                                                                               | $0.75 \times V_{DD}$ | —                    | V    |       |
| $V_{IL}$           | Input low voltage <ul style="list-style-type: none"> <li><math>2.7\text{ V} \leq V_{DD} \leq 3.6\text{ V}</math></li> <li><math>1.7\text{ V} \leq V_{DD} \leq 2.7\text{ V}</math></li> </ul>  | —                    | $0.35 \times V_{DD}$ | V    |       |
|                    |                                                                                                                                                                                               | —                    | $0.3 \times V_{DD}$  | V    |       |
| $V_{HYS}$          | Input hysteresis                                                                                                                                                                              | $0.06 \times V_{DD}$ | —                    | V    |       |

Table continues on the next page...

**Table 1. Voltage and current operating requirements (continued)**

| Symbol   | Description                                                               | Min. | Max. | Unit | Notes |
|----------|---------------------------------------------------------------------------|------|------|------|-------|
| $I_{IC}$ | DC injection current — single pin                                         |      |      |      | 1     |
|          |                                                                           | 0    | 2    | mA   |       |
|          | • $V_{IN} < V_{SS}$                                                       | 0    | -0.2 | mA   | 1     |
|          |                                                                           | 0    | -5   | mA   |       |
|          | DC injection current — total MCU limit, includes sum of all stressed pins |      |      |      | 1     |
|          |                                                                           | 0    | 25   | mA   |       |
|          | • $V_{IN} < V_{SS}$                                                       | 0    | -5   | mA   | 1     |
|          |                                                                           | 0    | -5   | mA   |       |

1. All functional non-supply pins are internally clamped to VSS and VDD. Input must be current limited to the value specified. To determine the value of the required current-limiting resistor, calculate resistance values for positive and negative clamp voltages, then use the larger of the two values. Power supply must maintain regulation within operating VDD range during instantaneous and operating maximum current conditions. If positive injection current ( $V_{IN} > V_{DD}$ ) is greater than  $I_{DD}$ , the injection current may flow out of VDD and could result in external power supply going out of regulation. Ensure external VDD load will shunt current greater than maximum injection current. This will be the greatest risk when the MCU is not consuming power. Examples are: if no system clock is present, or if clock rate is very low (which would reduce overall power consumption).

### 5.1.2 LVD and POR operating requirements

**Table 2. LVD and POR operating requirements**

| Symbol     | Description                                                 | Min. | Typ. | Max. | Unit | Notes |
|------------|-------------------------------------------------------------|------|------|------|------|-------|
| $V_{POR}$  | Falling VDD POR detect voltage                              | TBD  | 1.1  | TBD  | V    |       |
| $V_{LVDH}$ | Falling low-voltage detect threshold — high range (LVDV=01) | TBD  | 2.56 | TBD  | V    |       |
| $V_{LVW1}$ | Low-voltage warning thresholds — high range                 | TBD  | 2.70 | TBD  | V    | 1     |
| $V_{LVW2}$ |                                                             | TBD  | 2.80 | TBD  | V    |       |
| $V_{LVW3}$ |                                                             | TBD  | 2.90 | TBD  | V    |       |
| $V_{LVW4}$ |                                                             | TBD  | 3.00 | TBD  | V    |       |
| $V_{HYS}$  | Low-voltage inhibit reset/recover hysteresis — high range   |      | 60   |      | mV   |       |
| $V_{LVDL}$ | Falling low-voltage detect threshold — low range (LVDV=00)  | TBD  | TBD  | TBD  | V    |       |
| $V_{LVW1}$ | Low-voltage warning thresholds — low range                  | TBD  | 1.80 | TBD  | V    | 1     |
| $V_{LVW2}$ |                                                             | TBD  | 1.90 | TBD  | V    |       |
| $V_{LVW3}$ |                                                             | TBD  | 2.00 | TBD  | V    |       |
| $V_{LVW4}$ |                                                             | TBD  | 2.10 | TBD  | V    |       |

Table continues on the next page...

**Table 2. LVD and POR operating requirements (continued)**

| Symbol    | Description                                              | Min. | Typ. | Max. | Unit    | Notes |
|-----------|----------------------------------------------------------|------|------|------|---------|-------|
| $V_{HYS}$ | Low-voltage inhibit reset/recover hysteresis — low range |      | 40   |      | mV      |       |
| $V_{BG}$  | Bandgap voltage reference                                | TBD  | 1.00 | TBD  | V       |       |
| $t_{LPO}$ | Internal low power oscillator period<br>factory trimmed  | TBD  | 1000 | TBD  | $\mu$ s |       |

1. Rising thresholds are falling threshold +  $V_{HYS}$

### 5.1.3 Voltage and current operating behaviors

**Table 3. Voltage and current operating behaviors**

| Symbol                | Description                                                                | Min.           | Max. | Unit       | Notes |
|-----------------------|----------------------------------------------------------------------------|----------------|------|------------|-------|
| $V_{OH}$              | Output high voltage — high drive strength                                  |                |      |            |       |
|                       | • $2.7\text{ V} \leq V_{DD} \leq 3.6\text{ V}$ , $I_{OH} = -10\text{mA}$   | $V_{DD} - 0.5$ | —    | V          |       |
|                       | • $1.71\text{ V} \leq V_{DD} \leq 2.7\text{ V}$ , $I_{OH} = -3\text{mA}$   | $V_{DD} - 0.5$ | —    | V          |       |
|                       | Output high voltage — low drive strength                                   |                |      |            |       |
|                       | • $2.7\text{ V} \leq V_{DD} \leq 3.6\text{ V}$ , $I_{OH} = -2\text{mA}$    | $V_{DD} - 0.5$ | —    | V          |       |
|                       | • $1.71\text{ V} \leq V_{DD} \leq 2.7\text{ V}$ , $I_{OH} = -0.6\text{mA}$ | $V_{DD} - 0.5$ | —    | V          |       |
| $I_{OHT}$             | Output high current total for all ports                                    | —              | 100  | mA         |       |
| $V_{OL}$              | Output low voltage — high drive strength                                   |                |      |            |       |
|                       | • $2.7\text{ V} \leq V_{DD} \leq 3.6\text{ V}$ , $I_{OL} = 10\text{mA}$    | —              | 0.5  | V          |       |
|                       | • $1.71\text{ V} \leq V_{DD} \leq 2.7\text{ V}$ , $I_{OL} = 3\text{mA}$    | —              | 0.5  | V          |       |
|                       | Output low voltage — low drive strength                                    |                |      |            |       |
|                       | • $2.7\text{ V} \leq V_{DD} \leq 3.6\text{ V}$ , $I_{OL} = 2\text{mA}$     | —              | 0.5  | V          |       |
|                       | • $1.71\text{ V} \leq V_{DD} \leq 2.7\text{ V}$ , $I_{OL} = 0.6\text{mA}$  | —              | 0.5  | V          |       |
| $I_{OLT}$             | Output low current total for all ports                                     | —              | 100  | mA         |       |
| $I_{IN}$              | Input leakage current (per pin)                                            | —              | 1    | $\mu$ A    |       |
| $I_{OZ}$              | Hi-Z (off-state) leakage current (per pin)                                 | —              | 1    | $\mu$ A    |       |
| $R_{PU}$ and $R_{PD}$ | Internal weak pullup and pulldown resistors                                | 30             | 50   | k $\Omega$ | 1     |

1. Measured at  $V_{IL}$  max and  $V_{DD}$  min

## 5.1.4 Power mode transition operating behaviors

In the table below, all specifications except  $t_{POR}$ , assume the following clock configuration:

- CPU and system clocks = 100MHz
- Bus and FlexBus clocks = 50 MHz
- Flash clock = 25 MHz

**Table 4. Power mode transition operating behaviors**

| Symbol    | Description                                                                                                                                                      | Min. | Max.  | Unit    | Notes |
|-----------|------------------------------------------------------------------------------------------------------------------------------------------------------------------|------|-------|---------|-------|
| $t_{POR}$ | After a POR event, amount of time from the point $V_{DD}$ reaches 1.8V to execution of the first instruction across the operating temperature range of the chip. | —    | 300   | $\mu s$ | 1     |
|           | RUN → VLLS1 → RUN                                                                                                                                                |      |       |         |       |
|           | • RUN → VLLS1                                                                                                                                                    | —    | 4.1   | $\mu s$ |       |
|           | • VLLS1 → RUN                                                                                                                                                    | —    | 123.8 | $\mu s$ |       |
|           | RUN → VLLS2 → RUN                                                                                                                                                |      |       |         |       |
|           | • RUN → VLLS2                                                                                                                                                    | —    | 4.1   | $\mu s$ |       |
|           | • VLLS2 → RUN                                                                                                                                                    | —    | 49.3  | $\mu s$ |       |
|           | RUN → VLLS3 → RUN                                                                                                                                                |      |       |         |       |
|           | • RUN → VLLS3                                                                                                                                                    | —    | 4.1   | $\mu s$ |       |
|           | • VLLS3 → RUN                                                                                                                                                    | —    | 49.2  | $\mu s$ |       |
|           | RUN → LLS → RUN                                                                                                                                                  |      |       |         |       |
|           | • RUN → LLS                                                                                                                                                      | —    | 4.1   | $\mu s$ |       |
|           | • LLS → RUN                                                                                                                                                      | —    | 5.9   | $\mu s$ |       |
|           | RUN → STOP → RUN                                                                                                                                                 |      |       |         |       |
|           | • RUN → STOP                                                                                                                                                     | —    | 4.1   | $\mu s$ |       |
|           | • STOP → RUN                                                                                                                                                     | —    | 4.2   | $\mu s$ |       |
|           | RUN → VLPS → RUN                                                                                                                                                 |      |       |         |       |
|           | • RUN → VLPS                                                                                                                                                     | —    | 4.1   | $\mu s$ |       |
|           | • VLPS → RUN                                                                                                                                                     | —    | 5.8   | $\mu s$ |       |

1. Normal boot (FTFL\_OPT[LPBOOT]=1)

## 5.1.5 Power consumption operating behaviors

**Table 5. Power consumption operating behaviors**

| Symbol             | Description                                                                                                                                                                 | Min.   | Typ.     | Max.       | Unit     | Notes |
|--------------------|-----------------------------------------------------------------------------------------------------------------------------------------------------------------------------|--------|----------|------------|----------|-------|
| $I_{DD\_RUN}$      | Run mode current — all peripheral clocks disabled, code executing from flash <ul style="list-style-type: none"> <li>@ 1.8V</li> <li>@ 3.0V</li> </ul>                       | —<br>— | 40<br>42 | TBD<br>TBD | mA<br>mA | 1     |
| $I_{DD\_RUN}$      | Run mode current — all peripheral clocks enabled, code executing from flash <ul style="list-style-type: none"> <li>@ 1.8V</li> <li>@ 3.0V</li> </ul>                        | —<br>— | 55<br>56 | TBD<br>TBD | mA<br>mA | 2     |
| $I_{DD\_RUN\_MAX}$ | Run mode current — all peripheral clocks enabled and peripherals active, code executing from flash <ul style="list-style-type: none"> <li>@ 1.8V</li> <li>@ 3.0V</li> </ul> | —<br>— | 85<br>85 | TBD<br>TBD | mA<br>mA | 3     |
| $I_{DD\_WAIT}$     | Wait mode current at 3.0 V — all peripheral clocks disabled                                                                                                                 | —      | 15       | TBD        | mA       | 4     |
| $I_{DD\_STOP}$     | Stop mode current at 3.0 V                                                                                                                                                  | —      | 1.4      | TBD        | mA       |       |
| $I_{DD\_VLPR}$     | Very-low-power run mode current at 3.0 V — all peripheral clocks disabled                                                                                                   | —      | 1.25     | TBD        | mA       | 5     |
| $I_{DD\_VLPR}$     | Very-low-power run mode current at 3.0 V — all peripheral clocks enabled                                                                                                    | —      | TBD      | TBD        | mA       | 6     |
| $I_{DD\_VLPW}$     | Very-low-power wait mode current at 3.0 V                                                                                                                                   | —      | 1.05     | TBD        | mA       | 7     |
| $I_{DD\_VLPS}$     | Very-low-power stop mode current at 3.0 V                                                                                                                                   | —      | 30       | TBD        | μA       |       |
| $I_{DD\_LLS}$      | Low leakage stop mode current at 3.0 V                                                                                                                                      | —      | 12       | TBD        | μA       |       |
| $I_{DD\_VLLS3}$    | Very low-leakage stop mode 3 current at 3.0 V <ul style="list-style-type: none"> <li>128KB RAM devices</li> </ul>                                                           | —      | 8        | TBD        | μA       |       |
| $I_{DD\_VLLS2}$    | Very low-leakage stop mode 2 current at 3.0 V                                                                                                                               | —      | 4        | TBD        | μA       |       |
| $I_{DD\_VLLS1}$    | Very low-leakage stop mode 1 current at 3.0 V                                                                                                                               | —      | 2        | TBD        | μA       |       |
| $I_{DD\_VBAT}$     | Average current when CPU is not accessing RTC registers at 3.0 V                                                                                                            | —      | 550      | TBD        | nA       |       |

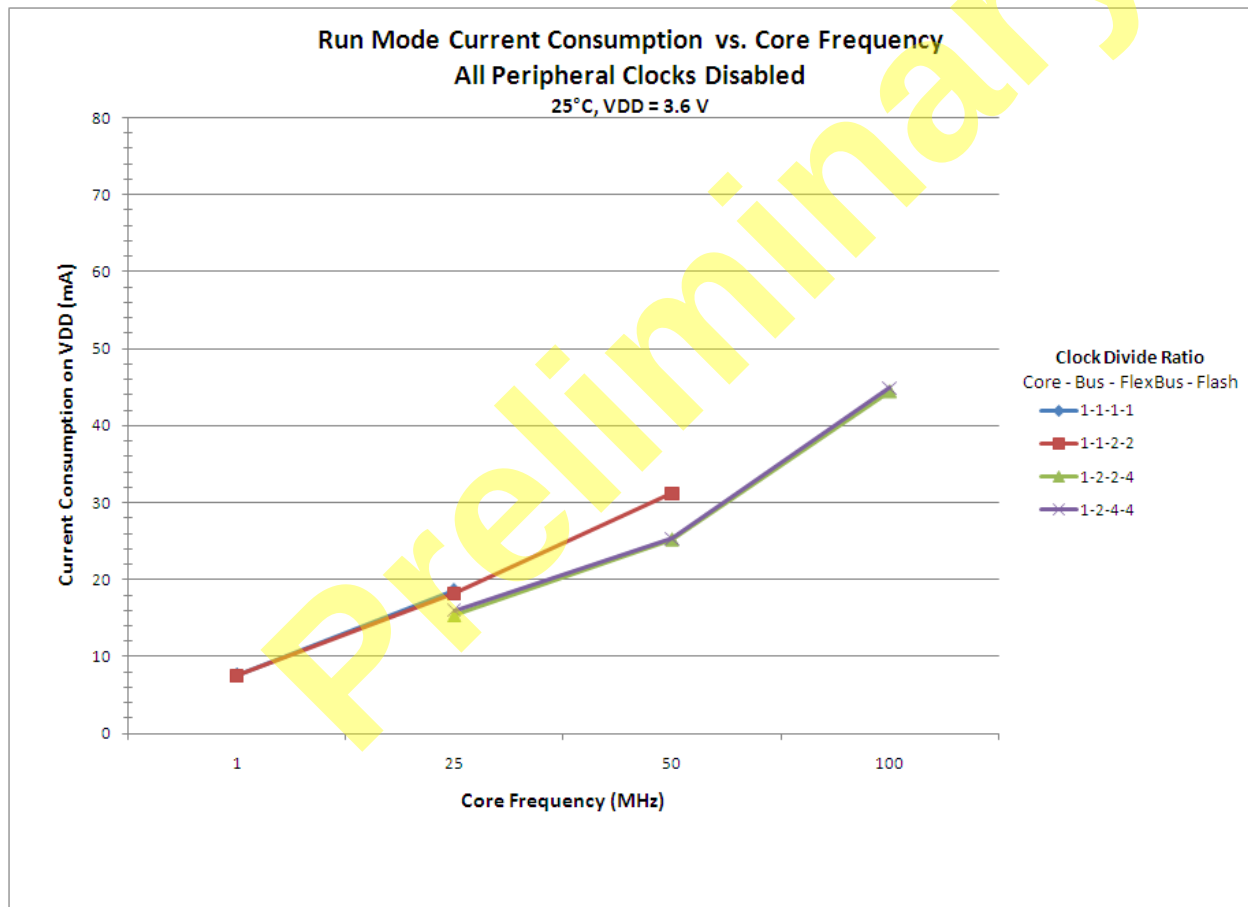
- 100MHz core and system clock, 50MHz bus and FlexBus clock, and 25MHz flash clock. MCG configured for FEI mode. All peripheral clocks disabled.
- 100MHz core and system clock, 50MHz bus and FlexBus clock, and 25MHz flash clock. MCG configured for FEI mode. All peripheral clocks enabled, but peripherals are not in active operation.
- 100MHz core and system clock, 50MHz bus and FlexBus clock, and 25MHz flash clock. MCG configured for FEI mode. All peripheral clocks enabled, and peripherals are in active operation.
- 25MHz core and system clock, 25MHz bus clock, and 12.5MHz FlexBus and flash clock. MCG configured for FEI mode.
- 2 MHz core, system, FlexBus, and bus clock and 1MHz flash clock. MCG configured for fast IRCLK mode. All peripheral clocks disabled. Code executing from flash.
- 2 MHz core, system, FlexBus, and bus clock and 1MHz flash clock. MCG configured for fast IRCLK mode. All peripheral clocks enabled but peripherals are not in active operation. Code executing from flash.

7. 2 MHz core, system, FlexBus, and bus clock and 1MHz flash clock. MCG configured for fast IRCLK mode. All peripheral clocks disabled.

### 5.1.5.1 Diagram: Typical IDD\_RUN operating behavior

The following data was measured under these conditions:

- MCG in FEI mode (39.0625 kHz IRC), except for 1 MHz core (FBE)
- All peripheral clocks disabled except FTFL
- LVD disabled
- No GPIOs toggled
- Code execution from flash



**Figure 1. Run mode supply current vs. core frequency — all peripheral clocks disabled**

The following data was measured under these conditions:

- MCG in FEI mode (39.0625 kHz IRC), except for 1 MHz core (FBE)
- All peripheral clocks enabled but peripherals are not in active operation
- LVD disabled
- No GPIOs toggled
- Code execution from flash



Figure 2. Run mode supply current vs. core frequency — all peripheral clocks enabled

## 5.1.6 EMC radiated emissions operating behaviors

Table 6. EMC radiated emissions operating behaviors

| Symbol                  | Description                        | Frequency band (MHz) | Typ. | Unit | Notes |
|-------------------------|------------------------------------|----------------------|------|------|-------|
| V <sub>RE1</sub>        | Radiated emissions voltage, band 1 | 0.15–50              | TBD  | dBμV | 1, 2  |
| V <sub>RE2</sub>        | Radiated emissions voltage, band 2 | 50–150               | TBD  |      |       |
| V <sub>RE3</sub>        | Radiated emissions voltage, band 3 | 150–500              | TBD  |      |       |
| V <sub>RE4</sub>        | Radiated emissions voltage, band 4 | 500–1000             | TBD  |      |       |
| V <sub>RE_IEC_SAE</sub> | IEC and SAE level                  | 0.15–1000            | TBD  | —    | 2, 3  |

1. Determined according to IEC Standard 61967-1, *Integrated Circuits - Measurement of Electromagnetic Emissions, 150 kHz to 1 GHz Part 1: General Conditions and Definitions*, IEC Standard 61967-2, *Integrated Circuits - Measurement of Electromagnetic Emissions, 150 kHz to 1 GHz Part 2: Measurement of Radiated Emissions—TEM Cell and Wideband TEM Cell Method*, and SAE Standard J1752-3, *Measurement of Radiated Emissions from Integrated Circuits—TEM/Wideband TEM (GTEM) Cell Method*.
2. V<sub>DD</sub> = 3 V, T<sub>A</sub> = 25 °C, f<sub>OSC</sub> = 16 MHz (crystal), f<sub>BUS</sub> = 20 MHz
3. Specified according to Annex D of IEC Standard 61967-2, *Measurement of Radiated Emissions—TEM Cell and Wideband TEM Cell Method*, and Appendix D of SAE Standard J1752-3, *Measurement of Radiated Emissions from Integrated Circuits—TEM/Wideband TEM (GTEM) Cell Method*.

### 5.1.7 Designing with radiated emissions in mind

1. To find application notes that provide guidance on designing your system to minimize interference from radiated emissions, go to [www.freescale.com](http://www.freescale.com) and perform a keyword search for “EMC design.”

### 5.1.8 Capacitance attributes

Table 7. Capacitance attributes

| Symbol            | Description                     | Min. | Max. | Unit |
|-------------------|---------------------------------|------|------|------|
| C <sub>IN_A</sub> | Input capacitance: analog pins  | —    | 7    | pF   |
| C <sub>IN_D</sub> | Input capacitance: digital pins | —    | 7    | pF   |

## 5.2 Switching electrical specifications

Table 8. Device clock specifications

| Symbol             | Description           | Min. | Max. | Unit | Notes |
|--------------------|-----------------------|------|------|------|-------|
| Normal run mode    |                       |      |      |      |       |
| f <sub>SYS</sub>   | System and core clock | —    | 100  | MHz  |       |
| f <sub>BUS</sub>   | Bus clock             | —    | 50   | MHz  |       |
| FB_CLK             | FlexBus clock         | —    | 50   | MHz  |       |
| f <sub>FLASH</sub> | Flash clock           | —    | 25   | MHz  |       |
| VLPR mode          |                       |      |      |      |       |
| f <sub>SYS</sub>   | System and core clock | —    | 2    | MHz  |       |
| f <sub>BUS</sub>   | Bus clock             | —    | 2    | MHz  |       |
| FB_CLK             | FlexBus clock         | —    | 2    | MHz  |       |
| f <sub>FLASH</sub> | Flash clock           | —    | 1    | MHz  |       |

## 5.3 Thermal specifications

## 5.3.1 Thermal operating requirements

Table 9. Thermal operating requirements

| Symbol | Description              | Min. | Max. | Unit |
|--------|--------------------------|------|------|------|
| $T_J$  | Die junction temperature | −40  | 125  | °C   |
| $T_A$  | Ambient temperature      | −40  | 105  | °C   |

## 5.3.2 Thermal attributes

| Board type        | Symbol           | Description                                                                                     | 81 MAPBGA | 80 LQFP | Unit | Notes |
|-------------------|------------------|-------------------------------------------------------------------------------------------------|-----------|---------|------|-------|
| Single-layer (1s) | $R_{\theta JA}$  | Thermal resistance, junction to ambient (natural convection)                                    | TBD       | TBD     | °C/W | 1     |
| Four-layer (2s2p) | $R_{\theta JA}$  | Thermal resistance, junction to ambient (natural convection)                                    | TBD       | TBD     | °C/W | 1     |
| Single-layer (1s) | $R_{\theta JMA}$ | Thermal resistance, junction to ambient (200 ft./min. air speed)                                | TBD       | TBD     | °C/W | 1     |
| Four-layer (2s2p) | $R_{\theta JMA}$ | Thermal resistance, junction to ambient (200 ft./min. air speed)                                | TBD       | TBD     | °C/W | 1     |
| —                 | $R_{\theta JB}$  | Thermal resistance, junction to board                                                           | TBD       | TBD     | °C/W | 2     |
| —                 | $R_{\theta JC}$  | Thermal resistance, junction to case                                                            | TBD       | TBD     | °C/W | 3     |
| —                 | $\Psi_{JT}$      | Thermal characterization parameter, junction to package top outside center (natural convection) | TBD       | TBD     | °C/W | 4     |

# 6 Peripheral operating requirements and behaviors

## 6.1 Core modules

1. Determined according to JEDEC Standard JESD51-2, *Integrated Circuits Thermal Test Method Environmental Conditions—Natural Convection (Still Air)*, or EIA/JEDEC Standard JESD51-6, *Integrated Circuit Thermal Test Method Environmental Conditions—Forced Convection (Moving Air)*.
2. Determined according to JEDEC Standard JESD51-8, *Integrated Circuit Thermal Test Method Environmental Conditions—Junction-to-Board*.
3. Determined according to Method 1012.1 of MIL-STD 883, *Test Method Standard, Microcircuits*, with the cold plate temperature used for the case temperature. The value includes the thermal resistance of the interface material between the top of the package and the cold plate.
4. Determined according to JEDEC Standard JESD51-2, *Integrated Circuits Thermal Test Method Environmental Conditions—Natural Convection (Still Air)*.

## 6.1.1 Debug trace timing specifications

Table 10. Debug trace operating behaviors

| Symbol    | Description              | Min.                | Max. | Unit |
|-----------|--------------------------|---------------------|------|------|
| $T_{cyc}$ | Clock period             | Frequency dependent |      | MHz  |
| $T_{wl}$  | Low pulse width          | 2                   | —    | ns   |
| $T_{wh}$  | High pulse width         | 2                   | —    | ns   |
| $T_r$     | Clock and data rise time | —                   | 3    | ns   |
| $T_f$     | Clock and data fall time | —                   | 3    | ns   |
| $T_s$     | Data setup               | 3                   | —    | ns   |
| $T_h$     | Data hold                | 2                   | —    | ns   |



Figure 3. TRACE\_CLKOUT specifications

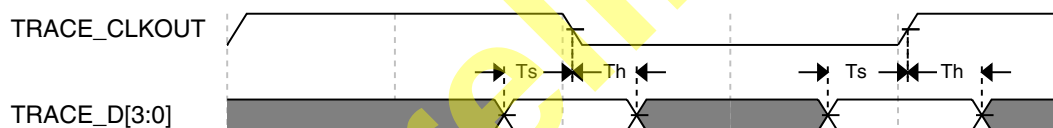


Figure 4. Trace data specifications

## 6.1.2 JTAG electricals

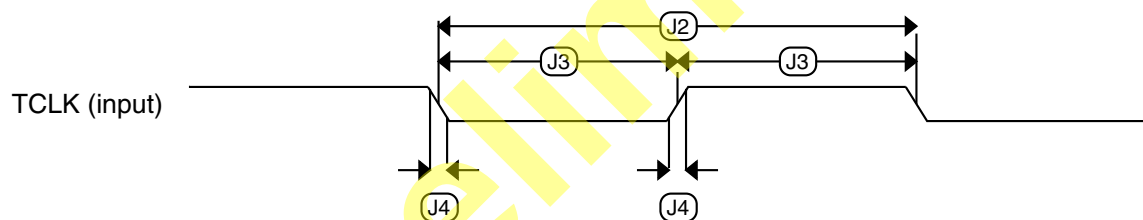
Table 11. JTAG electricals

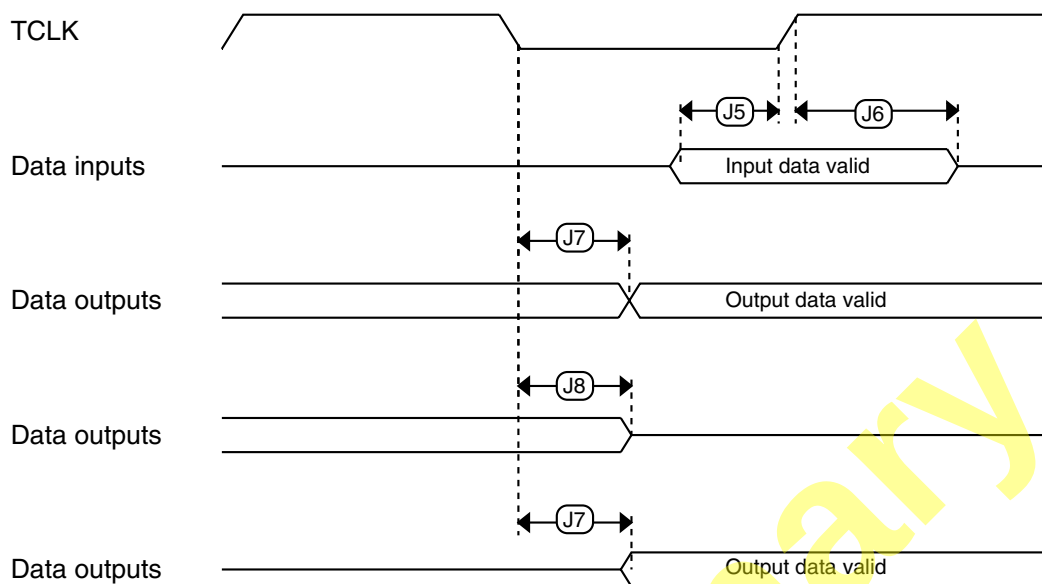
| Symbol | Description                                                                                                             | Min.   | Max.     | Unit |
|--------|-------------------------------------------------------------------------------------------------------------------------|--------|----------|------|
|        | Operating voltage                                                                                                       | 2.7    | 3.6      | V    |
| J1     | TCLK frequency of operation <ul style="list-style-type: none"> <li>JTAG and CJTAG</li> <li>Serial Wire Debug</li> </ul> | 0<br>0 | 25<br>50 | MHz  |
| J2     | TCLK cycle period                                                                                                       | 1/J1   | —        | ns   |

Table continues on the next page...

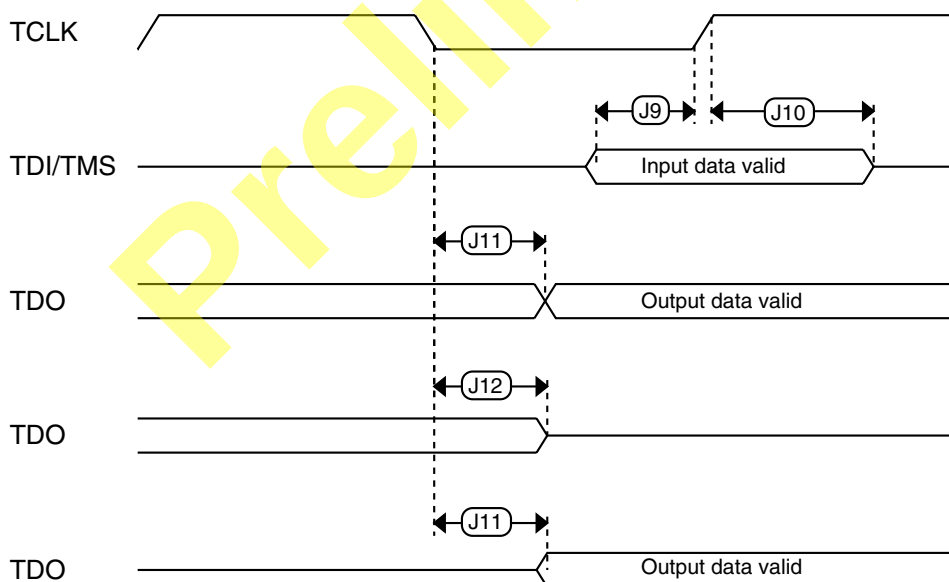
**Table 11. JTAG electricals (continued)**

| Symbol | Description                                                                                                        | Min.     | Max.   | Unit |
|--------|--------------------------------------------------------------------------------------------------------------------|----------|--------|------|
| J3     | TCLK clock pulse width <ul style="list-style-type: none"> <li>JTAG and CJTAG</li> <li>Serial Wire Debug</li> </ul> | 20<br>10 | —<br>— | ns   |
| J4     | TCLK rise and fall times                                                                                           | —        | 3      | ns   |
| J5     | Boundary scan input data setup time to TCLK rise                                                                   | 20       | —      | ns   |
| J6     | Boundary scan input data hold time after TCLK rise                                                                 | 0        | —      | ns   |
| J7     | TCLK low to boundary scan output data valid                                                                        | —        | 30     | ns   |
| J8     | TCLK low to boundary scan output high-Z                                                                            | —        | 30     | ns   |
| J9     | TMS, TDI input data setup time to TCLK rise                                                                        | 16       | —      | ns   |
| J10    | TMS, TDI input data hold time after TCLK rise                                                                      | 1        | —      | ns   |
| J11    | TCLK low to TDO data valid                                                                                         | —        | 4      | ns   |
| J12    | TCLK low to TDO high-Z                                                                                             | —        | 4      | ns   |
| J13    | $\overline{\text{TRST}}$ assert time                                                                               | 100      | —      | ns   |
| J14    | $\overline{\text{TRST}}$ setup time (negation) to TCLK high                                                        | 8        | —      | ns   |

**Figure 5. Test clock input timing**



**Figure 6. Boundary scan (JTAG) timing**



**Figure 7. Test Access Port timing**

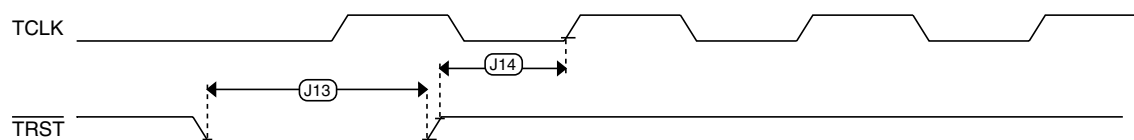


Figure 8. TRST timing

## 6.2 System modules

There are no specifications necessary for the device's system modules.

## 6.3 Clock modules

### 6.3.1 MCG Specifications

Table 12. MCG specifications

| Symbol                          | Description                                                                                            | Min.  | Typ.           | Max.    | Unit               | Notes |
|---------------------------------|--------------------------------------------------------------------------------------------------------|-------|----------------|---------|--------------------|-------|
| $f_{\text{ints\_ft}}$           | Internal reference frequency (slow clock) — factory trimmed at nominal VDD and 25°C                    | —     | 32.768         | —       | kHz                |       |
| $f_{\text{ints\_t}}$            | Internal reference frequency (slow clock) — user trimmed                                               | 31.25 | —              | 39.0625 | kHz                |       |
| $t_{\text{irefst}}$             | Internal reference (slow clock) startup time                                                           | —     | TBD            | 4       | μs                 |       |
| $\Delta f_{\text{dco\_res\_t}}$ | Resolution of trimmed DCO output frequency at fixed voltage and temperature — using SCTRIM and SCFTRIM | —     | ± 0.1          | ± 0.3   | % $f_{\text{dco}}$ |       |
| $\Delta f_{\text{dco\_res\_t}}$ | Resolution of trimmed DCO output frequency at fixed voltage and temperature — using SCTRIM only        | —     | ± 0.2          | ± 0.5   | % $f_{\text{dco}}$ |       |
| $\Delta f_{\text{dco\_t}}$      | Total deviation of trimmed DCO output frequency over voltage and temperature                           | —     | + 0.5<br>- 1.0 | ± 3.5   | % $f_{\text{dco}}$ |       |
| $\Delta f_{\text{dco\_t}}$      | Total deviation of trimmed DCO output frequency over fixed voltage and temperature range of 0–70°C     | —     | ± 0.5          | ± TBD   | % $f_{\text{dco}}$ |       |
| $f_{\text{intf\_ft}}$           | Internal reference frequency (fast clock) — factory trimmed at nominal VDD and 25°C                    | 3.875 | 4              | 4.125   | MHz                |       |
| $f_{\text{intf\_t}}$            | Internal reference frequency (fast clock) — user trimmed                                               | 3     | —              | 5       | MHz                |       |

Table continues on the next page...

Table 12. MCG specifications (continued)

| Symbol                       | Description                                                      | Min.                                                  | Typ. | Max.                                 | Unit | Notes |      |
|------------------------------|------------------------------------------------------------------|-------------------------------------------------------|------|--------------------------------------|------|-------|------|
| t <sub>irefstf</sub>         | Internal reference startup time (fast clock)                     | —                                                     | TBD  | TBD                                  | μs   |       |      |
| f <sub>loc_low</sub>         | Loss of external clock minimum frequency — RANGE = 00            | (3/5) x f <sub>ints_t</sub>                           | —    | —                                    | kHz  |       |      |
| f <sub>loc_high</sub>        | Loss of external clock minimum frequency — RANGE = 01, 10, or 11 | (16/5) x f <sub>ints_t</sub>                          | —    | —                                    | kHz  |       |      |
| FLL                          |                                                                  |                                                       |      |                                      |      |       |      |
| f <sub>dco_t</sub>           | DCO output frequency range — user trimmed and DMX32=0            | Low range (DRS=00)<br>640 × f <sub>ints_t</sub>       | 20   | 20.97                                | 25   | MHz   | 1, 2 |
|                              |                                                                  | Mid range (DRS=01)<br>1280 × f <sub>ints_t</sub>      | 40   | 41.94                                | 50   | MHz   |      |
|                              |                                                                  | Mid-high range (DRS=10)<br>1920 × f <sub>ints_t</sub> | 60   | 62.91                                | 75   | MHz   |      |
|                              |                                                                  | High range (DRS=11)<br>2560 × f <sub>ints_t</sub>     | 80   | 83.89                                | 100  | MHz   |      |
| f <sub>dco_t</sub> DMX32 = 2 | DCO output frequency range — reference = 32,768Hz and DMX32=1    | Low range (DRS=00)<br>732 × f <sub>ints_t</sub>       | —    | 23.99                                | —    | MHz   | 3    |
|                              |                                                                  | Mid range (DRS=01)<br>1464 × f <sub>ints_t</sub>      | —    | 47.97                                | —    | MHz   |      |
|                              |                                                                  | Mid-high range (DRS=10)<br>2197 × f <sub>ints_t</sub> | —    | 71.99                                | —    | MHz   |      |
|                              |                                                                  | High range (DRS=11)<br>2929 × f <sub>ints_t</sub>     | —    | 95.98                                | —    | MHz   |      |
| J <sub>cyc_fll</sub>         | FLL period jitter                                                | —                                                     | TBD  | TBD                                  | ps   | 4     |      |
| J <sub>acc_fll</sub>         | FLL accumulated jitter of DCO output over a 1μs time window      | —                                                     | TBD  | TBD                                  | ps   |       |      |
| t <sub>fll_acquire</sub>     | FLL target frequency acquisition time                            | —                                                     | —    | 1                                    | ms   | 5     |      |
| PLL                          |                                                                  |                                                       |      |                                      |      |       |      |
| f <sub>vco</sub>             | VCO operating frequency                                          | 48.0                                                  | —    | 100                                  | MHz  |       |      |
| f <sub>pll_ref</sub>         | PLL reference frequency range                                    | 2.0                                                   | —    | 4.0                                  | MHz  |       |      |
| J <sub>cyc_pll</sub>         | PLL period jitter                                                | —                                                     | 400  | —                                    | ps   | 6, 7  |      |
| J <sub>acc_pll</sub>         | PLL accumulated jitter over 1μs window                           | —                                                     | TBD  | —                                    | ps   | 6, 7  |      |
| D <sub>lock</sub>            | Lock entry frequency tolerance                                   | ± 1.49                                                | —    | ± 2.98                               | %    |       |      |
| D <sub>unl</sub>             | Lock exit frequency tolerance                                    | ± 4.47                                                | —    | ± 5.97                               | %    |       |      |
| t <sub>pll_lock</sub>        | Lock detector detection time                                     | —                                                     | —    | 0.15 + 1075(1/f <sub>pll_ref</sub> ) | ms   | 8     |      |

1. The resulting system clock frequencies should not exceed their maximum specified values.

2. This specification includes the 2% precision of the internal reference frequency (slow clock).
3. The resulting clock frequency must not exceed the maximum specified clock frequency of the device.
4. This specification was obtained at TBD frequency.
5. This specification applies to any time the FLL reference source or reference divider is changed, trim value is changed, DMX32 bit is changed, DRS bits are changed, or changing from FLL disabled (BLPE, BLPI) to FLL enabled (FEI, FEE, FBE, FBI). If a crystal/resonator is being used as the reference, this specification assumes it is already running.
6. This specification was obtained using a Freescale developed PCB. PLL jitter is dependent on the noise characteristics of each PCB and results will vary.
7. This specification was obtained at internal frequency of TBD.
8. This specification applies to any time the PLL VCO divider or reference divider is changed, or changing from PLL disabled (BLPE, BLPI) to PLL enabled (PBE, PEE). If a crystal/resonator is being used as the reference, this specification assumes it is already running.

## 6.3.2 Oscillator Electrical Characteristics

This section provides the electrical characteristics of the module.

### 6.3.2.1 Oscillator DC Electrical Specifications

**Table 13. Oscillator DC electrical specifications, ( $V_{SSOSC} = 0\text{ V}_{DC}$ ) ( $T_A = T_L$  to  $T_H$ )**

| Symbol        | Description                                                                                                                                                                                         | Min. | Typ. | Max. | Unit | Notes |
|---------------|-----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|------|------|------|------|-------|
| $V_{DD33OSC}$ | 3.3 V supply voltage                                                                                                                                                                                | 1.71 | —    | 3.6  | V    |       |
| $I_{DDOSC}$   | Supply current — low-power mode <ul style="list-style-type: none"> <li>• 32 kHz</li> <li>• 1 MHz</li> <li>• 4 MHz</li> <li>• 8 MHz</li> <li>• 16 MHz</li> <li>• 24 MHz</li> <li>• 32 MHz</li> </ul> | —    | 500  | —    | nA   | 1     |
|               |                                                                                                                                                                                                     | —    | 100  | —    | μA   |       |
|               |                                                                                                                                                                                                     | —    | 200  | —    | μA   |       |
|               |                                                                                                                                                                                                     | —    | 300  | —    | μA   |       |
|               |                                                                                                                                                                                                     | —    | 700  | —    | μA   |       |
|               |                                                                                                                                                                                                     | —    | 1.2  | —    | mA   |       |
|               |                                                                                                                                                                                                     | —    | 1.5  | —    | mA   |       |
| $I_{DDOSC}$   | Supply current — high gain mode <ul style="list-style-type: none"> <li>• 32 kHz</li> <li>• 1 MHz</li> <li>• 4 MHz</li> <li>• 8 MHz</li> <li>• 16 MHz</li> <li>• 24 MHz</li> <li>• 32 MHz</li> </ul> | —    | 25   | —    | μA   | 1     |
|               |                                                                                                                                                                                                     | —    | 200  | —    | μA   |       |
|               |                                                                                                                                                                                                     | —    | 400  | —    | μA   |       |
|               |                                                                                                                                                                                                     | —    | 800  | —    | μA   |       |
|               |                                                                                                                                                                                                     | —    | 1.5  | —    | mA   |       |
|               |                                                                                                                                                                                                     | —    | 3    | —    | mA   |       |
|               |                                                                                                                                                                                                     | —    | 4    | —    | mA   |       |
| $C_x$         | EXTAL load capacitance                                                                                                                                                                              | —    | —    | —    |      | 2, 3  |
| $C_y$         | XTAL load capacitance                                                                                                                                                                               | —    | —    | —    |      | 2, 3  |

Table continues on the next page...

**Table 13. Oscillator DC electrical specifications, ( $V_{SSOSC} = 0 V_{DC}$ ) ( $T_A = T_L$  to  $T_H$ ) (continued)**

| Symbol   | Description                                                                              | Min.                      | Typ.          | Max. | Unit       | Notes |
|----------|------------------------------------------------------------------------------------------|---------------------------|---------------|------|------------|-------|
| $R_F$    | Feedback resistor — low-frequency, low-power mode                                        | —                         | —             | —    | M $\Omega$ | 2, 3  |
|          | Feedback resistor — low-frequency, high-gain mode                                        | —                         | 10            | —    | M $\Omega$ |       |
|          | Feedback resistor — high-frequency, low-power mode (1 – 8 MHz, 8 – 32 MHz)               | —                         | —             | —    | M $\Omega$ |       |
|          | Feedback resistor — high-frequency, high-gain mode (1 – 8 MHz, 8 – 32 MHz)               | —                         | 1             | —    | M $\Omega$ |       |
| $R_S$    | Series resistor — low-frequency, low-power mode                                          | —                         | —             | —    | k $\Omega$ |       |
|          | Series resistor — low-frequency, high-gain mode                                          | —                         | 200           | —    | k $\Omega$ |       |
|          | Series resistor — high-frequency, low-power mode                                         | —                         | —             | —    | k $\Omega$ |       |
|          | Series resistor — high-frequency, high-gain mode                                         |                           |               |      |            |       |
|          | • 1 MHz resonator                                                                        | —                         | 6.6           | —    | k $\Omega$ |       |
|          | • 2 MHz resonator                                                                        | —                         | 3.3           | —    | k $\Omega$ |       |
|          | • 4 MHz resonator                                                                        | —                         | 0             | —    | k $\Omega$ |       |
|          | • 8 MHz resonator                                                                        | —                         | 0             | —    | k $\Omega$ |       |
|          | • 16 MHz resonator                                                                       | —                         | 0             | —    | k $\Omega$ |       |
|          | • 20 MHz resonator                                                                       | —                         | 0             | —    | k $\Omega$ |       |
|          | • 32 MHz resonator                                                                       | —                         | 0             | —    | k $\Omega$ |       |
| $V_{pp}$ | Peak-to-peak amplitude of oscillation (oscillator mode) — low-frequency, low-power mode  | —                         | 0.6           | —    | V          |       |
|          | Peak-to-peak amplitude of oscillation (oscillator mode) — low-frequency, high-gain mode  | $0.75 \times V_{DD33OSC}$ | $V_{DD33OSC}$ | —    | V          |       |
|          | Peak-to-peak amplitude of oscillation (oscillator mode) — high-frequency, low-power mode | —                         | 0.6           | —    | V          |       |
|          | Peak-to-peak amplitude of oscillation (oscillator mode) — high-frequency, high-gain mode | $0.75 \times V_{DD33OSC}$ | $V_{DD33OSC}$ | —    | V          |       |

- $V_{DD33OSC}=3.3$  V, Temperature =27 °C, Cx/Cy=20 pF
- See crystal or resonator manufacturer's recommendation
- $R_F$  and  $C_X, C_Y$  are integrated in low-frequency, low-power mode and must not be attached externally

### 6.3.2.2 Oscillator frequency specifications

**Table 14. Oscillator frequency specifications, ( $V_{DD33OSC} = V_{DD33OSC} (min)$  to  $V_{DD33OSC} (max)$ ,  $T_A = T_L$  to  $T_H$ )**

| Symbol           | Description                                                                  | Min. | Typ. | Max. | Unit | Notes   |
|------------------|------------------------------------------------------------------------------|------|------|------|------|---------|
| $f_{osc\_lo}$    | Oscillator crystal or resonator frequency — low frequency mode               | 32   | —    | 40   | kHz  |         |
| $f_{osc\_hi\_1}$ | Oscillator crystal or resonator frequency — high frequency mode (low range)  | 1    | —    | 8    | MHz  |         |
| $f_{osc\_hi\_2}$ | Oscillator crystal or resonator frequency — high frequency mode (high range) | 8    | —    | 32   | MHz  |         |
| $t_{dc\_extal}$  | Input clock duty cycle (external clock mode)                                 | 40   | 50   | 60   | %    |         |
| $t_{cst}$        | Crystal start-up time — 32 kHz low-frequency, low-power mode                 | —    | TBD  | —    | ms   | 1, 2, 3 |
|                  | Crystal start-up time — 32 kHz low-frequency, high-gain mode                 | —    | 800  | —    | ms   |         |
|                  | Crystal start-up time — 8 MHz high-frequency, low-power mode                 | —    | 4    | —    | ms   |         |
|                  | Crystal start-up time — 8 MHz high-frequency, high-gain mode                 | —    | 3    | —    | ms   |         |

1. This parameter is characterized before qualification rather than 100% tested.
2. Proper PC board layout procedures must be followed to achieve specifications.
3. Crystal start up time is defined as the time between the oscillator being enabled and the OSCINIT bit in the MCG\_S register being set.

### 6.3.3 32kHz Oscillator Electrical Characteristics

This section describes the module electrical characteristics.

#### 6.3.3.1 32kHz Oscillator DC Electrical Specifications

**Table 15. 32kHz Oscillator Module DC Electrical Specifications ( $V_{SSOSC} = 0 V_{DC}$ ) ( $T_A = T_L$  to  $T_H$ )**

| Symbol     | Description                                   | Min. | Typ. | Max. | Unit |
|------------|-----------------------------------------------|------|------|------|------|
| $V_{BAT}$  | Supply voltage                                | 1.71 | —    | 3.6  | V    |
| $R_F$      | Internal feedback resistor                    | —    | 100  | —    | MΩ   |
| $C_{para}$ | Parasitical capacitance of EXTAL32 and XTAL32 | —    | 2.5  | —    | pF   |
| $C_{load}$ | Internal load capacitance (programmable)      | —    | 15   | —    | pF   |
| $V_{pp}$   | Peak-to-peak amplitude of oscillation         | —    | 0.6  | —    | V    |

### 6.3.3.2 32kHz Oscillator Frequency Specifications

**Table 16. 32kHz oscillator frequency specifications ( $V_{DD33OSC} = V_{DD33OSC}(\min)$  to  $V_{DD33OSC}(\max)$ ,  $T_A = T_L$  to  $T_H$ )**

| Symbol        | Description           | Min. | Typ. | Max. | Unit | Notes |
|---------------|-----------------------|------|------|------|------|-------|
| $f_{osc\_lo}$ | Oscillator crystal    | —    | 32   | —    | kHz  |       |
| $t_{start}$   | Crystal start-up time | —    | 1000 | —    | ms   | 1, 2  |

1. This parameter is characterized before qualification rather than 100% tested.
2. Proper PC board layout procedures must be followed to achieve specifications.

## 6.4 Memories and memory interfaces

### 6.4.1 Flash (FTFL) Electrical Characteristics

This section describes the electrical characteristics of the FTFL module.

#### 6.4.1.1 Flash Timing Parameters — Program and Erase

The following characteristics represent the amount of time the internal charge pumps are active and do not include command overhead.

**Table 17. NVM program/erase timing characteristics**

| Symbol         | Description                        | Min. | Typ. | Max. | Unit    | Notes |
|----------------|------------------------------------|------|------|------|---------|-------|
| $t_{hvpgm4}$   | Longword Program high-voltage time | —    | 20   | TBD  | $\mu s$ |       |
| $t_{hversscr}$ | Sector Erase high-voltage time     | —    | 20   | 100  | ms      | 1     |
| $t_{hversblk}$ | Erase Block high-voltage time      | —    | 160  | 800  | ms      | 1     |

1. Maximum time based on expectations at cycling end-of-life.

#### 6.4.1.2 Flash Timing Parameters — Commands

**Table 18. Flash command timing characteristics**

| Symbol         | Description                                        | Min. | Typ. | Max. | Unit    | Notes |
|----------------|----------------------------------------------------|------|------|------|---------|-------|
| $t_{rd1blk}$   | Read 1s Block execution time                       | —    | —    | 1.4  | ms      |       |
| $t_{rd1sec2k}$ | Read 1s Section execution time (2 KB flash sector) | —    | —    | 40   | $\mu s$ |       |
| $t_{pgmchk}$   | Program Check execution time                       | —    | —    | 35   | $\mu s$ |       |

Table continues on the next page...

**Table 18. Flash command timing characteristics (continued)**

| Symbol         | Description                                        | Min. | Typ. | Max. | Unit    | Notes |
|----------------|----------------------------------------------------|------|------|------|---------|-------|
| $t_{rdsrc}$    | Read Resource execution time                       | —    | —    | 35   | $\mu s$ | 1     |
| $t_{pgm4}$     | Program Longword execution time                    | —    | 50   | TBD  | $\mu s$ |       |
| $t_{ersblk}$   | Erase Flash Block execution time                   | —    | 160  | 800  | ms      | 2     |
| $t_{ersscr}$   | Erase Flash Sector execution time                  | —    | 20   | 100  | ms      | 2     |
| $t_{pgmsec2k}$ | Program Section execution time (2 KB flash sector) | —    | TBD  | TBD  | ms      |       |
| $t_{rd1all}$   | Read 1s All Blocks execution time                  | —    | —    | 2.8  | ms      |       |
| $t_{rdonce}$   | Read Once execution time                           | —    | —    | 35   | $\mu s$ | 1     |
| $t_{pgmonce}$  | Program Once execution time                        | —    | 50   | TBD  | $\mu s$ |       |
| $t_{ersall}$   | Erase All Blocks execution time                    | —    | 320  | 1600 | ms      | 2     |
| $t_{vfykey}$   | Verify Backdoor Access Key execution time          | —    | —    | 35   | $\mu s$ | 1     |

1. Assumes 25MHz flash clock frequency.
2. Maximum times for erase parameters based on expectations at cycling end-of-life.

### 6.4.1.3 Flash (FTFL) Current and Power Parameters

**Table 19. Flash (FTFL) current and power parameters**

| Symbol        | Description                                     | Typ. | Unit |
|---------------|-------------------------------------------------|------|------|
| $I_{DD\_PGM}$ | Worst case programming current in program flash | 10   | mA   |

### 6.4.1.4 Reliability Characteristics

**Table 20. NVM reliability characteristics**

| Symbol           | Description                            | Min. | Typ. <sup>1</sup> | Max. | Unit   | Notes |
|------------------|----------------------------------------|------|-------------------|------|--------|-------|
| Program Flash    |                                        |      |                   |      |        |       |
| $t_{nvmretp10k}$ | Data retention after up to 10 K cycles | 5    | TBD               | —    | years  | 2     |
| $t_{nvmretp1k}$  | Data retention after up to 1 K cycles  | 10   | TBD               | —    | years  | 2     |
| $t_{nvmretp100}$ | Data retention after up to 100 cycles  | 15   | TBD               | —    | years  | 2     |
| $n_{nvmcycp}$    | Cycling endurance                      | 10 K | TBD               | —    | cycles | 3     |

1. Typical data retention values are based on intrinsic capability of the technology measured at high temperature derated to 25°C. For additional information on how Freescale defines typical data retention, please refer to Engineering Bulletin EB618.
2. Data retention is based on  $T_{javg} = 55^{\circ}C$  (temperature profile over the lifetime of the application).
3. Cycling endurance represents number of program/erase cycles at  $-40^{\circ}C \leq T_j \leq 125^{\circ}C$

## 6.4.2 EzPort Switching Specifications

Table 21. EzPort switching specifications

| Num  | Description                                                                        | Min.                          | Max.        | Unit |
|------|------------------------------------------------------------------------------------|-------------------------------|-------------|------|
|      | Operating voltage                                                                  | 2.7                           | 3.6         | V    |
| EP1  | EZP_CK frequency of operation (all commands except READ)                           | —                             | $f_{SYS}/2$ | MHz  |
| EP1a | EZP_CK frequency of operation (READ command)                                       | —                             | $f_{SYS}/8$ | MHz  |
| EP2  | $\overline{\text{EZP\_CS}}$ negation to next $\overline{\text{EZP\_CS}}$ assertion | $2 \times t_{\text{EZP\_CK}}$ | —           | ns   |
| EP3  | $\overline{\text{EZP\_CS}}$ input valid to EZP_CK high (setup)                     | 5                             | —           | ns   |
| EP4  | EZP_CK high to $\overline{\text{EZP\_CS}}$ input invalid (hold)                    | 5                             | —           | ns   |
| EP5  | EZP_D input valid to EZP_CK high (setup)                                           | 2                             | —           | ns   |
| EP6  | EZP_CK high to EZP_D input invalid (hold)                                          | 5                             | —           | ns   |
| EP7  | EZP_CK low to EZP_Q output valid (setup)                                           | —                             | 12          | ns   |
| EP8  | EZP_CK low to EZP_Q output invalid (hold)                                          | 0                             | —           | ns   |
| EP9  | $\overline{\text{EZP\_CS}}$ negation to EZP_Q tri-state                            | —                             | 12          | ns   |

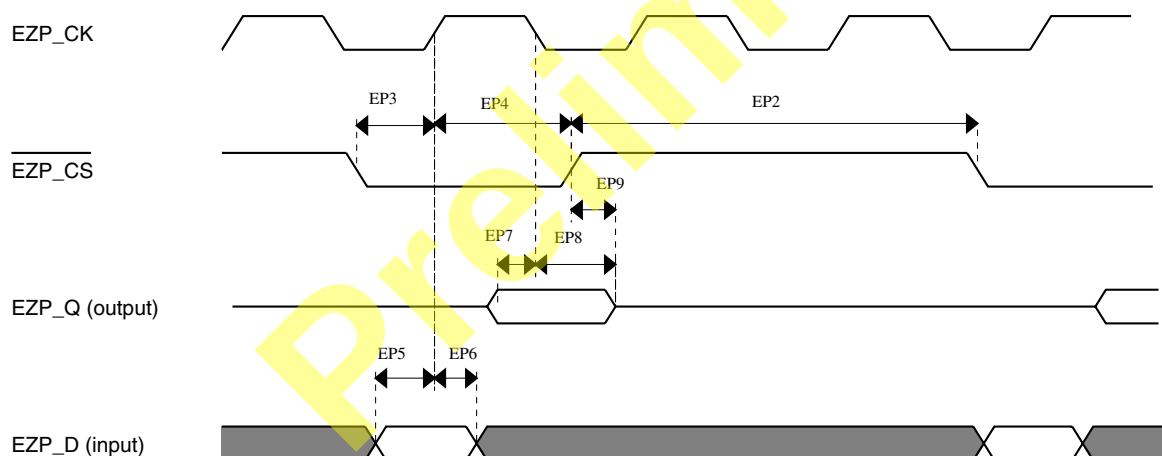


Figure 9. EzPort Timing Diagram

## 6.4.3 Flexbus Switching Specifications

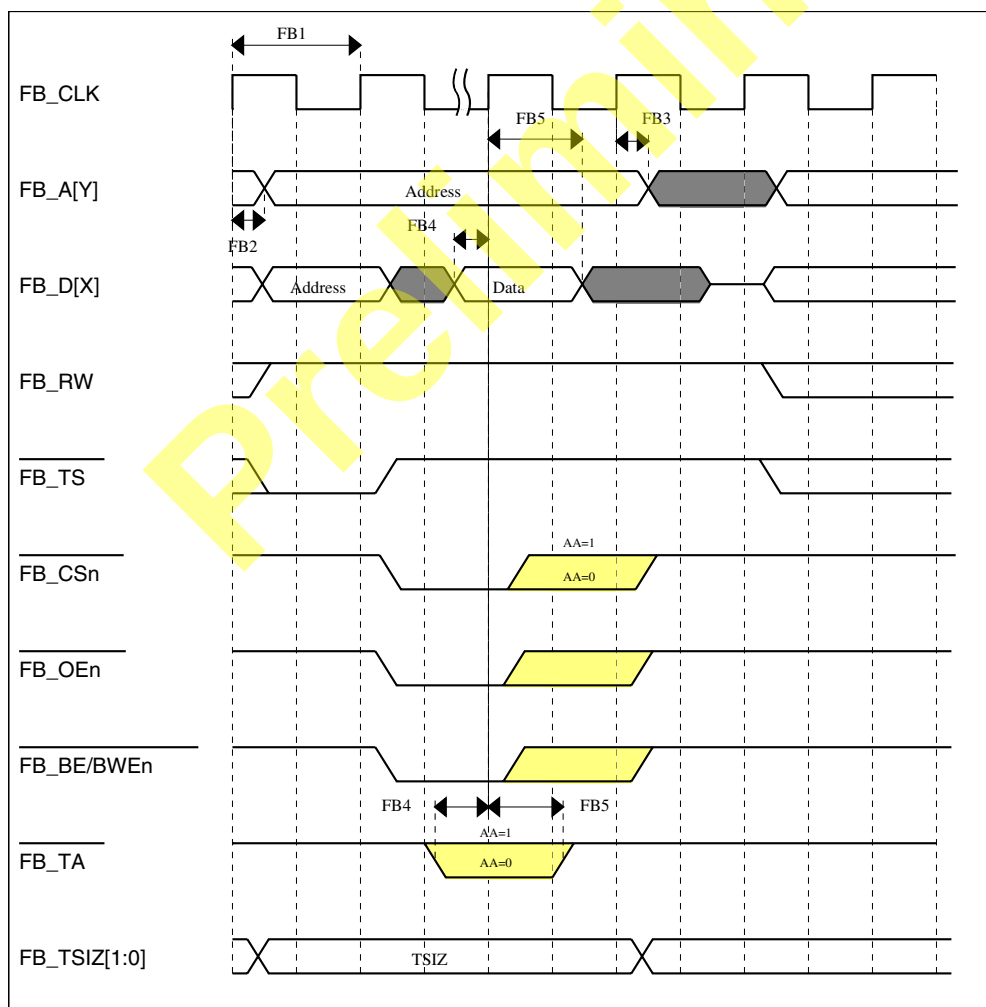
All processor bus timings are synchronous; input setup/hold and output delay are given in respect to the rising edge of a reference clock, FB\_CLK. The FB\_CLK frequency may be the same as the internal system bus frequency or an integer divider of that frequency.

The following timing numbers indicate when data is latched or driven onto the external bus, relative to the Flexbus output clock (FB\_CLK). All other timing relationships can be derived from these values.

**Table 22. Flexbus switching specifications**

| Num | Description                                     | Min. | Max. | Unit | Notes |
|-----|-------------------------------------------------|------|------|------|-------|
|     | Operating voltage                               | 2.7  | 3.6  | V    |       |
|     | Frequency of operation                          | —    | 50   | Mhz  |       |
| FB1 | Clock period                                    | 20   | —    | ns   |       |
| FB2 | Address, data, and control output valid         | TBD  | 11.5 | ns   | 1     |
| FB3 | Address, data, and control output hold          | 0    | —    | ns   | 1     |
| FB4 | Data and $\overline{\text{FB\_TA}}$ input setup | 8.5  | —    | ns   | 2     |
| FB5 | Data and $\overline{\text{FB\_TA}}$ input hold  | 0.5  | —    | ns   | 2     |

1. Specification is valid for all FB\_AD[31:0], FB\_BE/BWEn, FB\_CS $\overline{n}$ , FB\_OE, FB\_R/W, FB\_TBST, FB\_TSI[1:0], and FB\_TS.
2. Specification is valid for all FB\_AD[31:0] and FB\_TA.



**Figure 10. FlexBus read timing diagram**

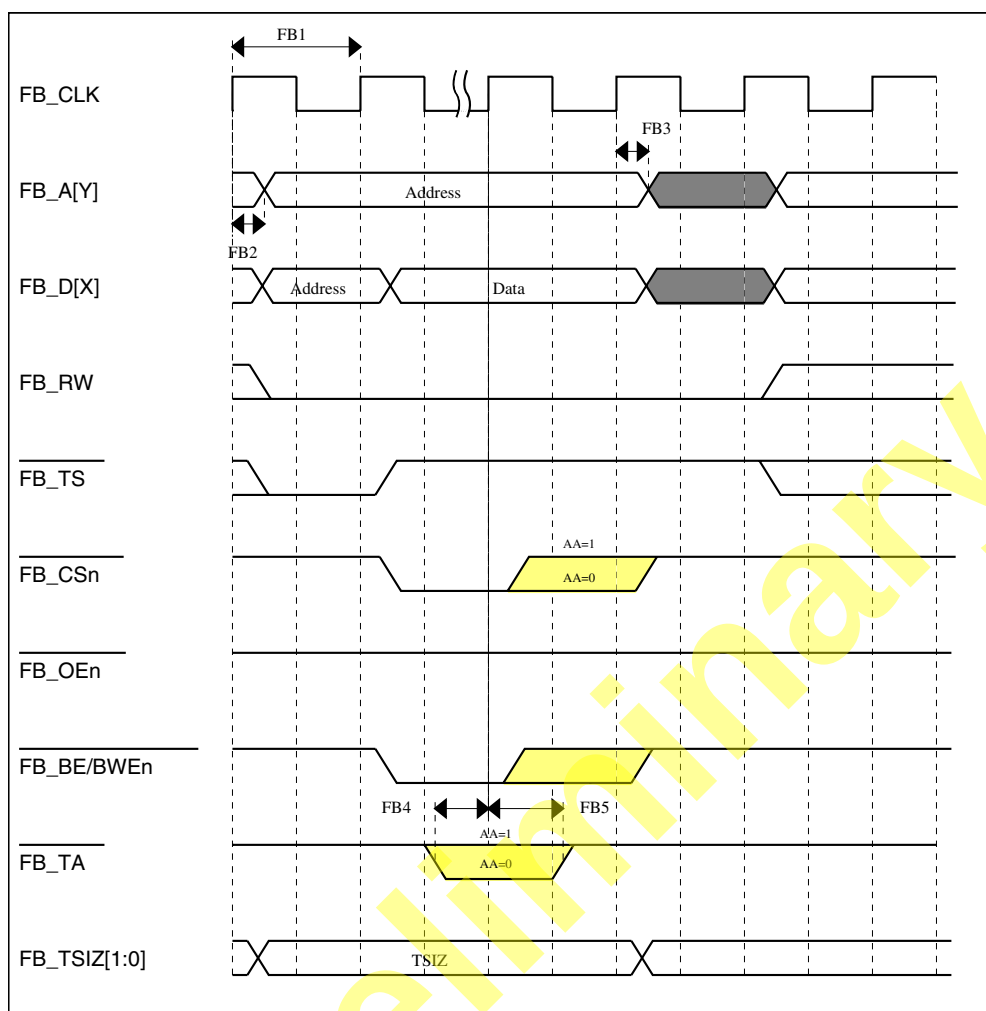


Figure 11. FlexBus write timing diagram

## 6.5 Security and integrity modules

There are no specifications necessary for the device's security and integrity modules.

## 6.6 Analog

### 6.6.1 ADC electrical specifications

The 16-bit accuracy specifications listed in [Table 23](#) and [Table 24](#) are achievable on the differential pins (ADCx\_DP0, ADCx\_DM0, ADC, ADCx\_DP1, ADCx\_DM1, ADCx\_DP3, and ADCx\_DM3). The ADCx\_DP2 and ADCx\_DM2 ADC inputs are used

as the PGA inputs and are not direct device pins. Accuracy specifications for these pins are defined in [Table 25](#) and [Table 26](#). All other ADC channels meet the 13-bit differential/12-bit single-ended accuracy specifications.

### 6.6.1.1 16-bit ADC operating conditions

**Table 23. 16-bit ADC operating conditions**

| Symbol           | Description                | Conditions                                                                                | Min.       | Typ. <sup>1</sup> | Max.       | Unit       | Notes |
|------------------|----------------------------|-------------------------------------------------------------------------------------------|------------|-------------------|------------|------------|-------|
| $V_{DDA}$        | Supply voltage             | Absolute                                                                                  | 1.71       | —                 | 3.6        | V          |       |
| $\Delta V_{DDA}$ | Supply voltage             | Delta to $V_{DD}$ ( $V_{DD} - V_{DDA}$ )                                                  | -100       | 0                 | +100       | mV         | 2     |
| $\Delta V_{SSA}$ | Ground voltage             | Delta to $V_{SS}$ ( $V_{SS} - V_{SSA}$ )                                                  | -100       | 0                 | +100       | mV         | 2     |
| $V_{REFH}$       | ADC reference voltage high |                                                                                           | 1.13       | $V_{DDA}$         | $V_{DDA}$  | V          |       |
| $V_{REFL}$       | Reference voltage low      |                                                                                           | $V_{SSA}$  | $V_{SSA}$         | $V_{SSA}$  | V          |       |
| $V_{ADIN}$       | Input voltage              |                                                                                           | $V_{REFL}$ | —                 | $V_{REFH}$ | V          |       |
| $C_{ADIN}$       | Input capacitance          | <ul style="list-style-type: none"> <li>16 bit modes</li> <li>8/10/12 bit modes</li> </ul> | —          | 8<br>4            | 10<br>5    | pF         |       |
| $R_{ADIN}$       | Input resistance           |                                                                                           | —          | 2                 | 5          | k $\Omega$ |       |

Table continues on the next page...

**Table 23. 16-bit ADC operating conditions (continued)**

| Symbol            | Description                    | Conditions                   | Min. | Typ. <sup>1</sup> | Max. | Unit | Notes                               |
|-------------------|--------------------------------|------------------------------|------|-------------------|------|------|-------------------------------------|
| R <sub>AS</sub>   | Analog source resistance       | 16 bit modes                 |      |                   |      |      | External to MCU<br>Assumes ADLSMP=0 |
|                   |                                | • f <sub>ADCK</sub> > 8MHz   | —    | —                 | 0.5  | kΩ   |                                     |
|                   |                                | • f <sub>ADCK</sub> = 4–8MHz | —    | —                 | 1    | kΩ   |                                     |
|                   |                                | • f <sub>ADCK</sub> < 4MHz   | —    | —                 | 2    | kΩ   |                                     |
|                   |                                | 13/12 bit modes              |      |                   |      |      |                                     |
|                   |                                | • f <sub>ADCK</sub> > 16MHz  | —    | —                 | 0.5  | kΩ   |                                     |
|                   |                                | • f <sub>ADCK</sub> > 8MHz   | —    | —                 | 1    | kΩ   |                                     |
|                   |                                | • f <sub>ADCK</sub> = 4–8MHz | —    | —                 | 2    | kΩ   |                                     |
|                   |                                | • f <sub>ADCK</sub> < 4MHz   | —    | —                 | 5    | kΩ   |                                     |
|                   |                                | 11/10 bit modes              |      |                   |      |      |                                     |
|                   |                                | • f <sub>ADCK</sub> > 8MHz   | —    | —                 | 2    | kΩ   |                                     |
|                   |                                | • f <sub>ADCK</sub> = 4–8MHz | —    | —                 | 5    | kΩ   |                                     |
|                   |                                | • f <sub>ADCK</sub> < 4MHz   | —    | —                 | 10   | kΩ   |                                     |
| f <sub>ADCK</sub> | ADC conversion clock frequency | 9/8 bit modes                |      |                   |      |      |                                     |
|                   |                                | • f <sub>ADCK</sub> > 8MHz   | —    | —                 | 5    | kΩ   |                                     |
|                   |                                | • f <sub>ADCK</sub> < 8MHz   | —    | —                 | 10   | kΩ   |                                     |
|                   |                                | ADLPC=0, ADHSC=1             |      |                   |      |      |                                     |
|                   |                                | • 16 bit modes               | 1.0  | —                 | TBD  | MHz  |                                     |
|                   |                                | • ≤13 bit modes              | 1.0  | —                 | TBD  | MHz  |                                     |
|                   |                                | ADLPC=0, ADHSC=0             |      |                   |      |      |                                     |
|                   |                                | • 16 bit modes               | 1.0  | —                 | 8.0  | MHz  |                                     |
|                   |                                | • ≤13 bit modes              | 1.0  | —                 | 12.0 | MHz  |                                     |
|                   |                                | ADLPC=1, ADHSC=1             |      |                   |      |      |                                     |
|                   |                                | • 16 bit modes               | 1.0  | —                 | 5.0  | MHz  |                                     |
|                   |                                | • ≤13 bit modes              | 1.0  | —                 | 8.0  | MHz  |                                     |
|                   |                                | ADLPC=1, ADHSC=0             |      |                   |      |      |                                     |
|                   |                                | • 16 bit modes               | 1.0  | —                 | 2.5  | MHz  |                                     |
|                   |                                | • ≤13 bit modes              | 1.0  | —                 | 5.0  | MHz  |                                     |

1. Typical values assume V<sub>DDA</sub> = 3.0 V, Temp = 25°C, f<sub>ADCK</sub> = 1.0 MHz unless otherwise stated. Typical values are for reference only and are not tested in production.

2. DC potential difference.

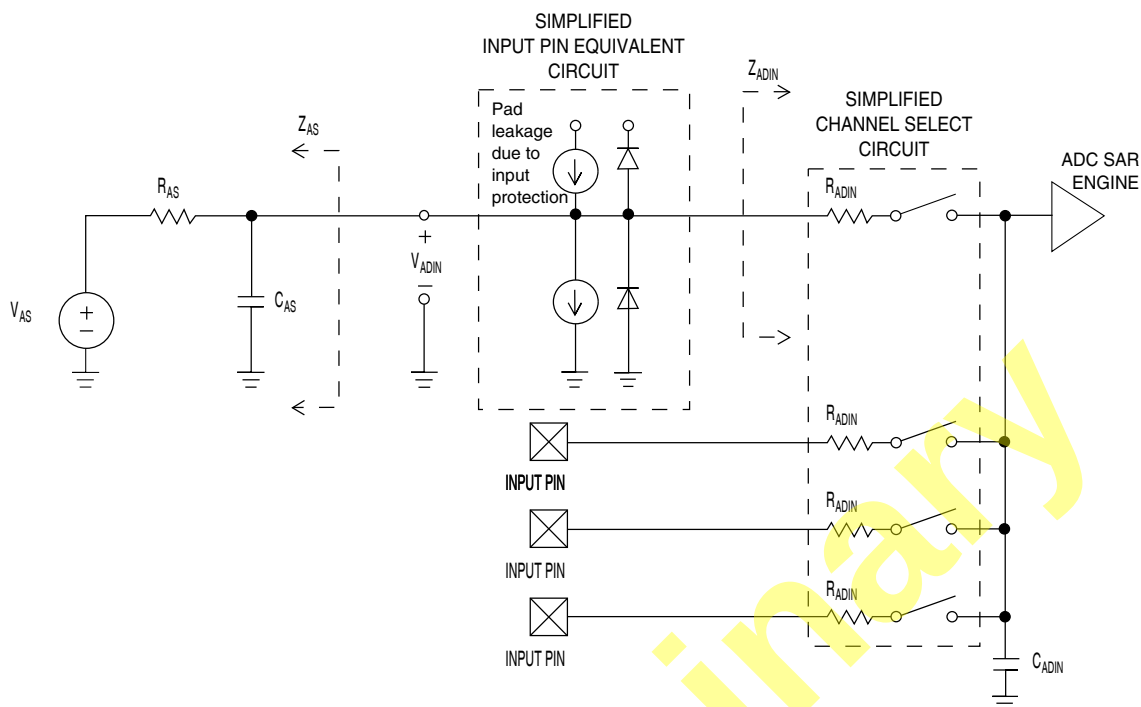


Figure 12. ADC input impedance equivalency diagram

### 6.6.1.2 16-bit ADC electrical characteristics

Table 24. 16-bit ADC characteristics ( $V_{REFH} = V_{DDA}$ ,  $V_{REFL} = V_{SSA}$ )

| Symbol             | Description                   | Conditions <sup>1</sup>                                                                                                                             | Min. | Typ. <sup>2</sup> | Max. | Unit | Notes                                     |
|--------------------|-------------------------------|-----------------------------------------------------------------------------------------------------------------------------------------------------|------|-------------------|------|------|-------------------------------------------|
| I <sub>DDA</sub>   | Supply current                | <ul style="list-style-type: none"><li>• ADLPC=1, ADHSC=0</li><li>• ADLPC=1, ADHSC=1</li><li>• ADLPC=0, ADHSC=0</li><li>• ADLPC=0, ADHSC=1</li></ul> | —    | 215               | —    | μA   | ADLSMP=0<br>ADCO=1                        |
|                    | Supply current                | <ul style="list-style-type: none"><li>• Stop, reset, module off</li></ul>                                                                           | —    | 0.01              | 0.8  | μA   |                                           |
| f <sub>ADACK</sub> | ADC asynchronous clock source | <ul style="list-style-type: none"><li>• ADLPC=1, ADHSC=0</li></ul>                                                                                  | TBD  | 2.4               | TBD  | MHz  | t <sub>ADACK</sub> = 1/f <sub>ADACK</sub> |
|                    |                               | <ul style="list-style-type: none"><li>• ADLPC=1, ADHSC=1</li></ul>                                                                                  | TBD  | 4.0               | TBD  | MHz  |                                           |
|                    |                               | <ul style="list-style-type: none"><li>• ADLPC=0, ADHSC=0</li></ul>                                                                                  | TBD  | 5.2               | TBD  | MHz  |                                           |
|                    |                               | <ul style="list-style-type: none"><li>• ADLPC=0, ADHSC=1</li></ul>                                                                                  | TBD  | 6.2               | TBD  | MHz  |                                           |
|                    | Sample Time                   | See Reference Manual chapter for sample times                                                                                                       |      |                   |      |      |                                           |
|                    | Conversion Time               | See Reference Manual chapter for conversion times                                                                                                   |      |                   |      |      |                                           |

Table continues on the next page...

**Table 24. 16-bit ADC characteristics ( $V_{REFH} = V_{DDA}$ ,  $V_{REFL} = V_{SSA}$ ) (continued)**

| Symbol          | Description                | Conditions <sup>1</sup>                                                                                                                                                                                                                                                                        | Min. | Typ. <sup>2</sup> | Max. | Unit             | Notes                                          |
|-----------------|----------------------------|------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|------|-------------------|------|------------------|------------------------------------------------|
| TUE             | Total unadjusted error     | <ul style="list-style-type: none"> <li>• 16 bit differential</li> <li>• 16 bit single-ended</li> <li>• 13 bit differential</li> <li>• 12 bit single-ended</li> <li>• 11 bit differential</li> <li>• 10 bit single-ended</li> <li>• 9 bit differential</li> <li>• 8 bit single-ended</li> </ul> | —    | ±14.0             | ±TBD | LSB <sup>3</sup> | Max hardware averaging (AVGE = %1, AVGS = %11) |
| DNL             | Differential non-linearity | <ul style="list-style-type: none"> <li>• 16 bit differential</li> <li>• 16 bit single-ended</li> <li>• 13 bit differential</li> <li>• 12 bit single-ended</li> <li>• 11 bit differential</li> <li>• 10 bit single-ended</li> <li>• 9 bit differential</li> <li>• 8 bit single-ended</li> </ul> | —    | ±2.5              | ±TBD | LSB <sup>3</sup> | Max hardware averaging (AVGE = %1, AVGS = %11) |
| INL             | Integral non-linearity     | <ul style="list-style-type: none"> <li>• 16 bit differential</li> <li>• 16 bit single-ended</li> <li>• 13 bit differential</li> <li>• 12 bit single-ended</li> <li>• 11 bit differential</li> <li>• 10 bit single-ended</li> <li>• 9 bit differential</li> <li>• 8 bit single-ended</li> </ul> | —    | -6 to +2.5        | —    | LSB <sup>3</sup> | Max averaging                                  |
| E <sub>zs</sub> | Zero-scale error           | <ul style="list-style-type: none"> <li>• 16 bit differential</li> <li>• 16 bit single-ended</li> <li>• 13 bit differential</li> <li>• 12 bit single-ended</li> <li>• 11 bit differential</li> <li>• 10 bit single-ended</li> <li>• 9 bit differential</li> <li>• 8 bit single-ended</li> </ul> | —    | ±4.0              | —    | LSB <sup>3</sup> | $V_{ADIN} = V_{SSA}$                           |

Table continues on the next page...

**Table 24. 16-bit ADC characteristics ( $V_{REFH} = V_{DDA}$ ,  $V_{REFL} = V_{SSA}$ ) (continued)**

| Symbol   | Description                     | Conditions <sup>1</sup>                                                                                                                                                                                                                                                                       | Min.                             | Typ. <sup>2</sup> | Max. | Unit             | Notes                |
|----------|---------------------------------|-----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|----------------------------------|-------------------|------|------------------|----------------------|
| $E_{FS}$ | Full-scale error                | <ul style="list-style-type: none"> <li>16 bit differential</li> <li>16 bit single-ended</li> <li>13 bit differential</li> <li>12 bit single-ended</li> <li>11 bit differential</li> <li>10 bit single-ended</li> <li>9 bit differential</li> <li>8 bit single-ended</li> </ul>                | —                                | 0 to +10          | —    | LSB <sup>3</sup> | $V_{ADIN} = V_{DDA}$ |
| $E_Q$    | Quantization error              | <ul style="list-style-type: none"> <li>16 bit modes</li> <li>≤13 bit modes</li> </ul>                                                                                                                                                                                                         | —                                | -1 to 0           | —    | LSB <sup>3</sup> |                      |
| ENOB     | Effective number of bits        | 16 bit differential mode <ul style="list-style-type: none"> <li>Avg=32</li> <li>Avg=16</li> <li>Avg=8</li> <li>Avg=4</li> <li>Avg=1</li> </ul> 16 bit single-ended mode <ul style="list-style-type: none"> <li>Avg=32</li> <li>Avg=16</li> <li>Avg=8</li> <li>Avg=4</li> <li>Avg=1</li> </ul> | TBD                              | 13.6              | TBD  | bits             | 4                    |
|          |                                 |                                                                                                                                                                                                                                                                                               | TBD                              | TBD               | TBD  | bits             |                      |
|          |                                 |                                                                                                                                                                                                                                                                                               | TBD                              | 14.1              | TBD  | bits             |                      |
|          |                                 |                                                                                                                                                                                                                                                                                               | TBD                              | TBD               | TBD  | bits             |                      |
|          |                                 |                                                                                                                                                                                                                                                                                               | TBD                              | 13.2              | TBD  | bits             |                      |
|          |                                 |                                                                                                                                                                                                                                                                                               | TBD                              | TBD               | TBD  | bits             |                      |
|          |                                 |                                                                                                                                                                                                                                                                                               | TBD                              | TBD               | TBD  | bits             |                      |
|          |                                 |                                                                                                                                                                                                                                                                                               | TBD                              | TBD               | TBD  | bits             |                      |
|          |                                 |                                                                                                                                                                                                                                                                                               | TBD                              | TBD               | TBD  | bits             |                      |
| SINAD    | Signal-to-noise plus distortion | See ENOB                                                                                                                                                                                                                                                                                      | $6.02 \times \text{ENOB} + 1.76$ |                   |      | dB               |                      |
| THD      | Total harmonic distortion       | 16 bit differential mode                                                                                                                                                                                                                                                                      | —                                | -94               | TBD  | dB               | 4                    |
|          |                                 | <ul style="list-style-type: none"> <li>Avg=32</li> </ul>                                                                                                                                                                                                                                      | —                                | TBD               | TBD  | dB               |                      |
|          |                                 | 16 bit single-ended mode                                                                                                                                                                                                                                                                      | —                                | TBD               | TBD  | dB               |                      |
|          |                                 | <ul style="list-style-type: none"> <li>Avg=32</li> </ul>                                                                                                                                                                                                                                      | TBD                              | 95                | —    | dB               | 4                    |
|          |                                 | 16 bit single-ended mode                                                                                                                                                                                                                                                                      | TBD                              | TBD               | —    | dB               |                      |
|          |                                 | <ul style="list-style-type: none"> <li>Avg=32</li> </ul>                                                                                                                                                                                                                                      | TBD                              | TBD               | —    | dB               |                      |

Table continues on the next page...

**Table 24. 16-bit ADC characteristics ( $V_{REFH} = V_{DDA}$ ,  $V_{REFL} = V_{SSA}$ ) (continued)**

| Symbol       | Description         | Conditions <sup>1</sup>                                                                | Min.                   | Typ. <sup>2</sup> | Max. | Unit  | Notes                                                                                        |
|--------------|---------------------|----------------------------------------------------------------------------------------|------------------------|-------------------|------|-------|----------------------------------------------------------------------------------------------|
| $E_{IL}$     | Input leakage error |                                                                                        | $I_{in} \times R_{AS}$ |                   |      | mV    | $I_{in}$ = leakage current<br><br>(refer to the MCU's voltage and current operating ratings) |
|              | Temp sensor slope   | <ul style="list-style-type: none"> <li>–40°C to 25°C</li> <li>25°C to 105°C</li> </ul> | —                      | TBD               | —    | mV/°C |                                                                                              |
| $V_{TEMP25}$ | Temp sensor voltage | 25°C                                                                                   | —                      | TBD               | —    | mV    |                                                                                              |

1. All accuracy numbers assume the ADC is calibrated with  $V_{REFH} = V_{DDA}$
2. Typical values assume  $V_{DDA} = 3.0$  V, Temp = 25°C,  $f_{ADCK} = 2.0$  MHz unless otherwise stated. Typical values are for reference only and are not tested in production.
3. 1 LSB =  $(V_{REFH} - V_{REFL})/2^N$
4. Input data is 1 kHz sine wave.

### 6.6.1.3 16-bit ADC with PGA operating conditions

**Table 25. 16-bit ADC with PGA operating conditions**

| Symbol       | Description                  | Conditions        | Min.      | Typ. <sup>1</sup> | Max.      | Unit | Notes      |
|--------------|------------------------------|-------------------|-----------|-------------------|-----------|------|------------|
| $V_{DDA}$    | Supply voltage               | Absolute          | 1.71      | —                 | 3.6       | V    |            |
| $V_{REFPGA}$ | PGA ref voltage              |                   | VREFOUT   | VREFOUT           | VREFOUT   | V    | 2, 3       |
| $V_{ADIN}$   | Input voltage                |                   | $V_{SSA}$ | —                 | $V_{DDA}$ | V    |            |
| $R_{PGA}$    | Input impedance              | Gain = 1, 2, 4, 8 | TBD       | 64                | TBD       | kΩ   |            |
|              |                              | Gain = 16, 32     | TBD       | 32                | TBD       |      |            |
|              |                              | Gain = 64         | TBD       | 16                | TBD       |      |            |
| $R_{PGAD}$   | Differential input impedance | Gain = 1, 2, 4, 8 | TBD       | 128               | TBD       | kΩ   | IN+ to IN- |
|              |                              | Gain = 16, 32     | TBD       | 64                | TBD       |      |            |
|              |                              | Gain = 64         | TBD       | 32                | TBD       |      |            |
| $R_{AS}$     | Analog source resistance     | Gain = 16, 32     | —         | 100               | —         | Ω    | 4          |
| $T_S$        | ADC sampling time            | Gain = 64         | 1.25      | —                 | —         | μs   | 5          |

1. Typical values assume  $V_{DDA} = 3.0$  V, Temp = 25°C,  $f_{ADCK} = 6$  MHz unless otherwise stated. Typical values are for reference only and are not tested in production.
2. ADC must be configured to use the internal voltage reference (VREFOUT)
3. PGA reference connected to the VREFOUT pin. If the user wishes to drive VREFOUT with a voltage other than the output of the VREF module, the VREF module must be disabled.

4. The analog source resistance ( $R_{AS}$ ), external to MCU, should be kept as minimum as possible. Increased  $R_{AS}$  causes drop in PGA gain without affecting other performances. This is not dependent on ADC clock frequency.
5. The minimum sampling time is dependent on input signal frequency and ADC mode of operation. A minimum of  $1.25\mu s$  time should be allowed for  $F_{in}=4$  kHz at 16-bit differential mode. Recommended ADC setting is: ADLSMP=1, ADLSTS=2 at 8 MHz ADC clock. The ADLSTS bits can be adjusted for different ADC clock frequency

### 6.6.1.4 16-bit ADC with PGA characteristics

**Table 26. 16-bit ADC with PGA characteristics**

| Symbol                | Description                    | Conditions                                                                                                                                               | Min.                                          | Typ. <sup>1</sup>                          | Max.                                          | Unit                                   | Notes                                                 |
|-----------------------|--------------------------------|----------------------------------------------------------------------------------------------------------------------------------------------------------|-----------------------------------------------|--------------------------------------------|-----------------------------------------------|----------------------------------------|-------------------------------------------------------|
| $I_{DDA\_PGA}$        | Supply current                 |                                                                                                                                                          | TBD                                           | 590                                        | TBD                                           | $\mu A$                                |                                                       |
| $I_{LKG}$             | Leakage current                | PGA disabled                                                                                                                                             | —                                             | < 1                                        | TBD                                           | $\mu A$                                |                                                       |
| G                     | Gain <sup>2</sup>              | <ul style="list-style-type: none"> <li>PGAG=0</li> <li>PGAG=1</li> <li>PGAG=2</li> <li>PGAG=3</li> <li>PGAG=4</li> <li>PGAG=5</li> <li>PGAG=6</li> </ul> | TBD<br>TBD<br>TBD<br>TBD<br>TBD<br>TBD<br>TBD | 1<br>2<br>3.9<br>TBD<br>TBD<br>29.9<br>TBD | TBD<br>TBD<br>TBD<br>TBD<br>TBD<br>TBD<br>TBD | dB<br>dB<br>dB<br>dB<br>dB<br>dB<br>dB | $R_{AS} < 100\Omega$                                  |
| $G_A$                 | Gain error                     |                                                                                                                                                          | —                                             | —                                          | $\pm 0.5$                                     | dB                                     | $R_{AS} < 100\Omega$                                  |
| BW                    | Input signal band-width        | <ul style="list-style-type: none"> <li>16-bit modes</li> <li>&lt; 16-bit modes</li> </ul>                                                                | —<br>—                                        | —<br>—                                     | 4<br>40                                       | kHz<br>kHz                             |                                                       |
| PSRR                  | Power supply rejection ration  | Gain=1                                                                                                                                                   | TBD                                           | TBD                                        | —                                             | dB                                     | $V_{DDA} = 3V \pm 100mV$ ,<br>$f_{VDDA} = 50Hz, 60Hz$ |
| CMRR                  | Common mode rejection ratio    | <ul style="list-style-type: none"> <li>Gain=1</li> <li>Gain=64</li> </ul>                                                                                | TBD<br>TBD                                    | TBD<br>TBD                                 | —<br>—                                        | dB<br>dB                               | $V_{CM} = 500mV_{pp}$ ,<br>$f_{VCM} = 50Hz, 100Hz$    |
| $V_{OFS}$             | Input offset voltage           |                                                                                                                                                          | —                                             | 0.2                                        | TBD                                           | mV                                     | Gain=1, ADC Averaging=32                              |
| $T_{GSW}$             | Gain switching settling time   |                                                                                                                                                          | —                                             | TBD                                        | 10                                            | $\mu s$                                | 3                                                     |
| dG/dT                 | Gain drift over temperature    | <ul style="list-style-type: none"> <li>Gain=1</li> <li>Gain=64</li> </ul>                                                                                | —<br>—                                        | TBD<br>TBD                                 | TBD<br>TBD                                    | ppm/°C<br>ppm/°C                       | 0 to 50°C                                             |
| dV <sub>OFS</sub> /dT | Offset drift over temperature  | Gain=1                                                                                                                                                   | —                                             | TBD                                        | TBD                                           | ppm/°C                                 | 0 to 50°C, ADC Averaging=32                           |
| dG/dV <sub>DDA</sub>  | Gain drift over supply voltage | <ul style="list-style-type: none"> <li>Gain=1</li> <li>Gain=64</li> </ul>                                                                                | —<br>—                                        | TBD<br>TBD                                 | TBD<br>TBD                                    | %/V<br>%/V                             | $V_{DDA}$ from 1.71 to 3.6V                           |

Table continues on the next page...

**Table 26. 16-bit ADC with PGA characteristics (continued)**

| Symbol        | Description                             | Conditions                                                                | Min.                                                        | Typ. <sup>1</sup> | Max. | Unit | Notes                                                                                    |
|---------------|-----------------------------------------|---------------------------------------------------------------------------|-------------------------------------------------------------|-------------------|------|------|------------------------------------------------------------------------------------------|
| $E_{IL}$      | Input leakage error                     | All modes                                                                 | $I_{in} \times R_{AS}$                                      |                   |      | mV   | $I_{in}$ = leakage current<br>(refer to the MCU's voltage and current operating ratings) |
| $V_{PP,DIFF}$ | Maximum differential input signal swing |                                                                           | $[(V_{REFPGA} \times 2.33) - 0.2] / (2 \times \text{Gain})$ |                   |      | V    | 4                                                                                        |
| SNR           | Signal-to-noise ratio                   | <ul style="list-style-type: none"> <li>Gain=1</li> <li>Gain=64</li> </ul> | TBD                                                         | 8.3               | —    | dB   | Average=32                                                                               |
|               |                                         |                                                                           | TBD                                                         | 57.7              | —    | dB   |                                                                                          |
| THD           | Total harmonic distortion               | <ul style="list-style-type: none"> <li>Gain=1</li> <li>Gain=64</li> </ul> | TBD                                                         | 87.3              | —    | dB   | Average=32,<br>$f_{in}=100\text{Hz}$                                                     |
|               |                                         |                                                                           | TBD                                                         | 85.3              | —    | dB   |                                                                                          |
| SFDR          | Spurious free dynamic range             | <ul style="list-style-type: none"> <li>Gain=1</li> <li>Gain=64</li> </ul> | TBD                                                         | 92.42             | —    | dB   | Average=32,<br>$f_{in}=100\text{Hz}$                                                     |
|               |                                         |                                                                           | TBD                                                         | 92.54             | —    | dB   |                                                                                          |
| ENOB          | Effective number of bits                | • Gain=1, Average=4                                                       | TBD                                                         | 12.3              | —    | bits |                                                                                          |
|               |                                         | • Gain=1, Average=8                                                       | TBD                                                         | 12.7              | —    | bits |                                                                                          |
|               |                                         | • Gain=64, Average=4                                                      | TBD                                                         | 8.4               | —    | bits |                                                                                          |
|               |                                         | • Gain=64, Average=8                                                      | TBD                                                         | 8.7               | —    | bits |                                                                                          |
|               |                                         | • Gain=1, Average=32                                                      | TBD                                                         | 13.4              | —    | bits |                                                                                          |
|               |                                         | • Gain=2, Average=32                                                      | TBD                                                         | 13.1              | —    | bits |                                                                                          |
|               |                                         | • Gain=4, Average=32                                                      | TBD                                                         | 12.6              | —    | bits |                                                                                          |
|               |                                         | • Gain=8, Average=32                                                      | TBD                                                         | 11.8              | —    | bits |                                                                                          |
|               |                                         | • Gain=16, Average=32                                                     | TBD                                                         | 11.1              | —    | bits |                                                                                          |
|               |                                         | • Gain=32, Average=32                                                     | TBD                                                         | 10.2              | —    | bits |                                                                                          |
|               |                                         | • Gain=64, Average=32                                                     | TBD                                                         | 9.3               | —    | bits |                                                                                          |
| SINAD         | Signal-to-noise plus distortion ratio   | See ENOB                                                                  | $6.02 \times \text{ENOB} + 1.76$                            |                   |      | dB   |                                                                                          |

1. Typical values assume  $V_{DDA} = 3.0\text{V}$ ,  $\text{Temp} = 25^\circ\text{C}$ ,  $f_{ADCK} = 6\text{MHz}$  unless otherwise stated.

2.  $\text{Gain} = 2^{\text{PGAGx}}$

3. When the PGA gain is changed, it takes some time to settle the output for the ADC to work properly. During a gain switching, a few ADC outputs should be discarded (minimum two data samples, may be more depending on ADC sampling rate and time of the switching).

4. Limit the input signal swing so that the PGA does not saturate during operation. Input signal swing is dependent on the PGA reference voltage and gain setting.

## 6.6.2 CMP and 6-bit DAC electrical specifications

**Table 27. Comparator and 6-bit DAC electrical specifications**

| Symbol      | Description                                                                    | Min.           | Typ. | Max.     | Unit             |
|-------------|--------------------------------------------------------------------------------|----------------|------|----------|------------------|
| $V_{DD}$    | Supply voltage                                                                 | 1.71           | —    | 3.6      | V                |
| $I_{DDHS}$  | Supply current, High-speed mode (EN=1, PMODE=1, $V_{DDA} \geq V_{LVI\_trip}$ ) | —              | —    | 200      | $\mu$ A          |
| $I_{DLS}$   | Supply current, low-speed mode (EN=1, PMODE=0)                                 | —              | —    | 20       | $\mu$ A          |
| $I_{DDOFF}$ | Supply current, OFF Mode (EN=0,)                                               | —              | —    | 100      | nA               |
| $V_{AIN}$   | Analog input voltage                                                           | $V_{SS} - 0.3$ | —    | $V_{DD}$ | V                |
| $V_{AIO}$   | Analog input offset voltage                                                    | —              | —    | 20       | mV               |
| $V_H$       | Analog comparator hysteresis                                                   | —              | 5    | —        | mV               |
|             |                                                                                | —              | 10   | —        | mV               |
|             |                                                                                | —              | 20   | —        | mV               |
|             |                                                                                | —              | 30   | —        | mV               |
| $V_{CMPOH}$ | Output high                                                                    | $V_{DD} - 0.5$ | —    | —        | V                |
| $V_{CMPOI}$ | Output low                                                                     | —              | —    | 0.5      | V                |
| $t_{DHS}$   | Propagation delay, high-speed mode (EN=1, PMODE=1)                             | 20             | 50   | 120      | ns               |
| $t_{DLS}$   | Propagation delay, low-speed mode (EN=1, PMODE=1)                              | 120            | 250  | 420      | ns               |
|             | Analog comparator initialization delay                                         | —              | —    | TBD      | ns               |
| $I_{DAC6b}$ | 6-bit DAC current adder (enabled)                                              | —              | —    | 8        | $\mu$ A          |
| INL         | 6-bit DAC integral non-linearity                                               | -0.5           | —    | 0.5      | LSB <sup>1</sup> |
| DNL         | 6-bit DAC differential non-linearity                                           | -0.3           | —    | 0.3      | LSB              |

1. 1 LSB =  $V_{reference}/64$

## 6.6.3 12-bit DAC electrical characteristics

### 6.6.3.1 12-bit DAC operating requirements

**Table 28. 12-bit DAC operating requirements**

| Symbol     | Description       | Min. | Max. | Unit | Notes |
|------------|-------------------|------|------|------|-------|
| $V_{DDA}$  | Supply voltage    | 1.71 | 3.6  | V    |       |
| $V_{DACR}$ | Reference voltage | 1.15 | 3.6  | V    | 1     |
| $T_A$      | Temperature       | -40  | 105  | °C   |       |

Table continues on the next page...

**Table 28. 12-bit DAC operating requirements (continued)**

| Symbol | Description             | Min. | Max. | Unit | Notes |
|--------|-------------------------|------|------|------|-------|
| $C_L$  | Output load capacitance | —    | 100  | pF   | 2     |
| $I_L$  | Output load current     | —    | 1    | mA   |       |

1. The DAC reference can be selected to be VDDA or the voltage output of the VREF module (VREFO)
2. A small load capacitance (47 pF) can improve the bandwidth performance of the DAC

### 6.6.3.2 12-bit DAC operating behaviors

**Table 29. 12-bit DAC operating behaviors**

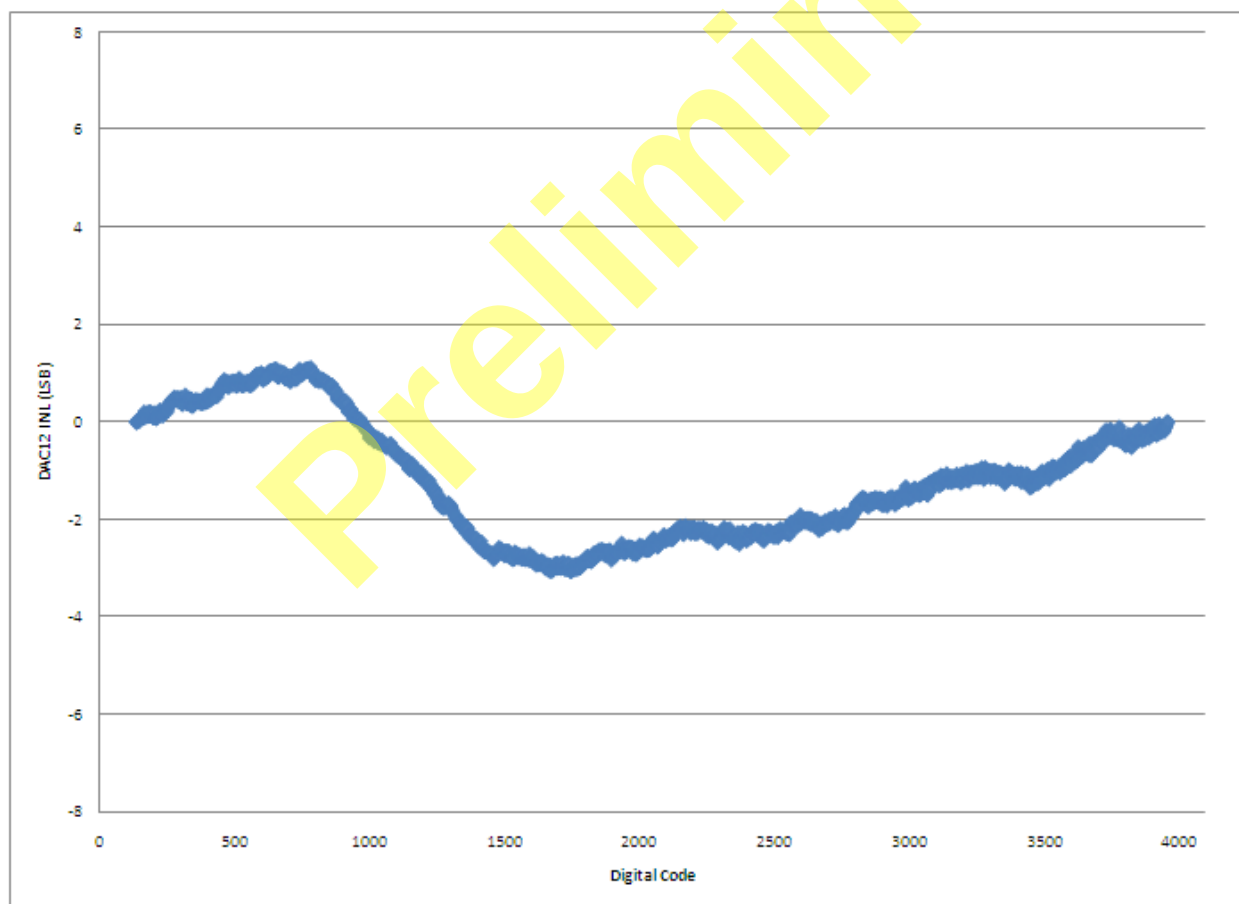
| Symbol           | Description                                                                 | Min.               | Typ. | Max.       | Unit         | Notes |
|------------------|-----------------------------------------------------------------------------|--------------------|------|------------|--------------|-------|
| n                | Resolution                                                                  | 12                 | —    | 12         | b            |       |
| $I_{DDA\_DACLP}$ | Supply current — low-power mode                                             | —                  | —    | 150        | $\mu A$      |       |
| $I_{DDA\_DACHP}$ | Supply current — high-speed mode                                            | —                  | —    | 700        | $\mu A$      |       |
| $t_{DACLP}$      | Full-scale settling time (0x080 to 0xF7F) — low-power mode                  | —                  | 100  | 200        | $\mu s$      | 1     |
| $t_{DACHP}$      | Full-scale settling time (0x080 to 0xF7F) — high-power mode                 | —                  | 15   | 30         | $\mu s$      | 1     |
| $t_{CCDACLP}$    | Code-to-code settling time (0xBF8 to 0xC08) — low-power mode                | —                  | —    | 5          | $\mu s$      | 1     |
| $t_{CCDACHP}$    | Code-to-code settling time (0xBF8 to 0xC08) — high-speed mode               | 1                  | TBD  | —          | $\mu s$      | 1     |
| $V_{dacoutl}$    | DAC output voltage range low — high-speed mode, no load, DAC set to 0x000   | 0                  | 100  | —          | mV           |       |
| $V_{dacouth}$    | DAC output voltage range high — high-speed mode, no load, DAC set to 0xFFFF | $V_{DACR}$<br>–100 | —    | $V_{DACR}$ | mV           |       |
| INL              | Integral non-linearity error — high speed mode                              | $\pm 3$            | —    | $\pm 8$    | LSB          | 2     |
| DNL              | Differential non-linearity error — $V_{DACR} > 2 V$                         | $\pm 0.5$          | —    | $\pm 1$    | LSB          | 3     |
| DNL              | Differential non-linearity error — $V_{DACR} = VREFO$ (1.15 V)              | $\pm 0.5$          | —    | $\pm 1$    | LSB          | 4     |
| $V_{OFFSET}$     | Offset error                                                                | $\pm 0.4$          | —    | $\pm 0.8$  | %FSR         | 5     |
| $E_G$            | Gain error                                                                  | $\pm 0.1$          | —    | $\pm 0.6$  | %FSR         | 5     |
| PSRR             | Power supply rejection ratio, $V_{DDA} \geq 2.4 V$                          | 60                 |      | 90         | dB           |       |
| $T_{CO}$         | Temperature coefficient offset voltage                                      | —                  | TBD  | —          | $\mu V/C$    |       |
| $T_{GE}$         | Temperature coefficient gain error                                          | —                  | TBD  | —          | ppm of FSR/C |       |
| $A_C$            | Offset aging coefficient                                                    | —                  | —    | TBD        | $\mu V/yr$   |       |
| $R_{op}$         | Output resistance load = 3 k $\Omega$                                       | —                  | —    | 250        | $\Omega$     |       |

Table continues on the next page...

**Table 29. 12-bit DAC operating behaviors (continued)**

| Symbol | Description                                                                                                                                   | Min.        | Typ.        | Max.   | Unit | Notes |
|--------|-----------------------------------------------------------------------------------------------------------------------------------------------|-------------|-------------|--------|------|-------|
| SR     | Slew rate -80h→ F7Fh→ 80h <ul style="list-style-type: none"> <li>High power (SP<sub>HP</sub>)</li> <li>Low power (SP<sub>LP</sub>)</li> </ul> | 1.2<br>0.05 | 1.7<br>0.12 | —<br>— | V/μs |       |
| CT     | Channel to channel cross talk                                                                                                                 | —           | —           | -80    | dB   |       |
| BW     | 3dB bandwidth <ul style="list-style-type: none"> <li>High power (SP<sub>HP</sub>)</li> <li>Low power (SP<sub>LP</sub>)</li> </ul>             | 550<br>40   | —<br>—      | —<br>— | kHz  |       |

1. Settling within  $\pm 1$  LSB
2. The INL is measured for 0+100mV to VD<sub>ACR</sub>-100 mV
3. The DNL is measured for 0+100 mV to V<sub>DACR</sub>-100 mV
4. The DNL is measured for 0+100mV to V<sub>DACR</sub>-100 mV with V<sub>DDA</sub> > 2.4V
5. Calculated by a best fit curve from V<sub>SS</sub>+100 mV to V<sub>REF</sub>-100 mV

**Figure 13. Typical INL error vs. digital code**

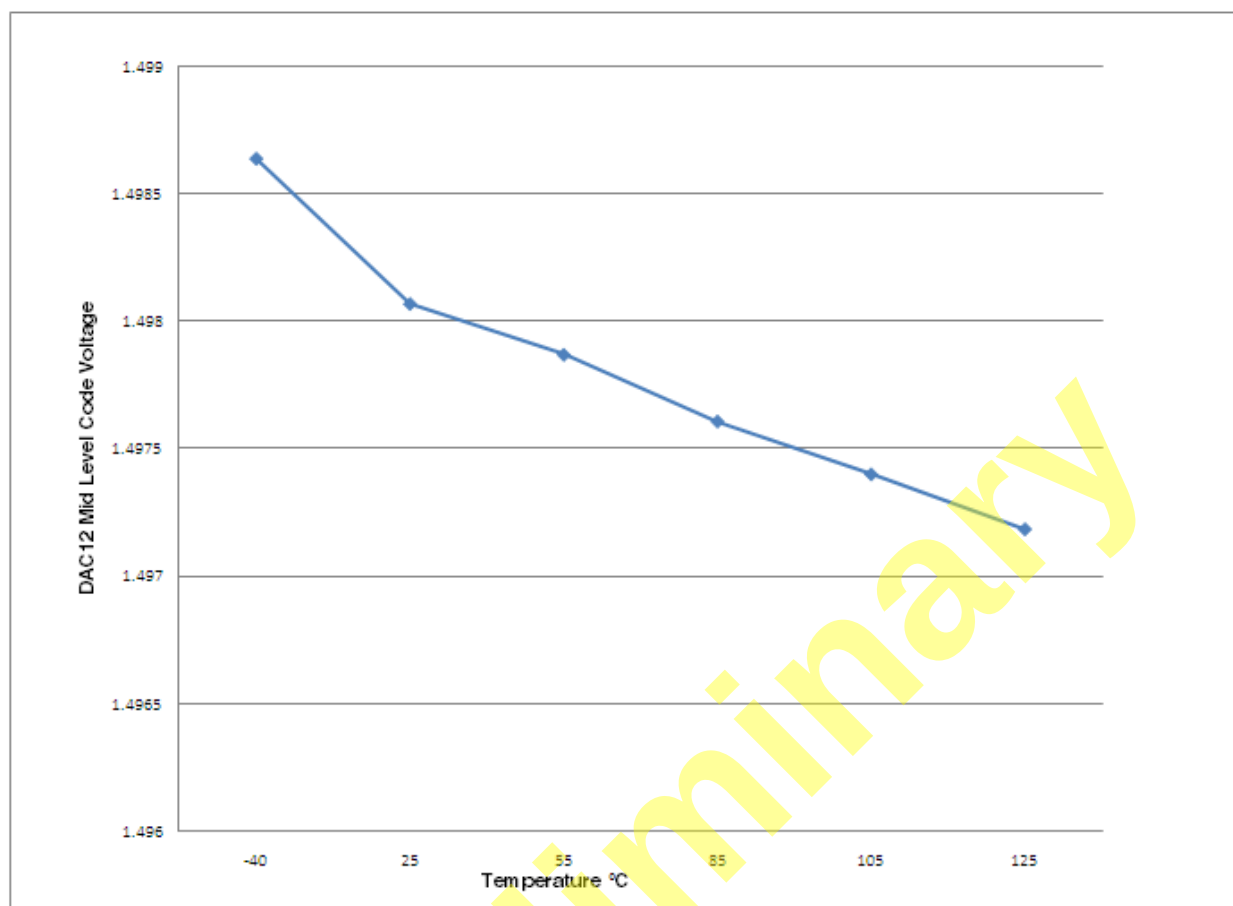


Figure 14. Offset at half scale vs. temperature

## 6.6.4 Voltage Reference Electrical Specifications

Table 30. VREF full-range operating requirements

| Symbol    | Description             | Min. | Max. | Unit | Notes |
|-----------|-------------------------|------|------|------|-------|
| $V_{DDA}$ | Supply voltage          | 1.71 | 3.6  | V    |       |
| $T_A$     | Temperature             | -40  | 105  | °C   |       |
| $C_L$     | Output load capacitance | —    | 100  | nF   |       |

Table 31. VREF full-range operating behaviors

| Symbol      | Description                                                                | Min. | Typ. | Max. | Unit | Notes         |
|-------------|----------------------------------------------------------------------------|------|------|------|------|---------------|
| $V_{out}$   | Voltage reference output with factory trim                                 | TBD  | 1.2  | TBD  | V    |               |
| $V_{out}$   | Voltage reference output without factory trim                              | 1.15 | —    | 1.24 | V    |               |
| $V_{drift}$ | Temperature drift ( $V_{max} - V_{min}$ across the full temperature range) | —    | —    | 7    | mV   | See Figure 15 |

Table continues on the next page...

**Table 31. VREF full-range operating behaviors (continued)**

| Symbol     | Description                                             | Min. | Typ. | Max. | Unit     | Notes |
|------------|---------------------------------------------------------|------|------|------|----------|-------|
| $T_c$      | Temperature coefficient                                 | —    | —    | TBD  | ppm/°C   |       |
| $A_c$      | Aging coefficient                                       | —    | —    | TBD  | ppm/year |       |
| $I_{off}$  | Powered down current (off mode, VREFEN = 0, VRSTEN = 0) | —    | —    | 0.10 | μA       |       |
| $I_{bg}$   | Bandgap only (MODE_LV = 00) current                     | —    | TBD  | 75   | μA       |       |
| $I_{tr}$   | Tight-regulation buffer (MODE_LV = 10) current          | —    | —    | 1.1  | mA       |       |
|            | Load regulation (MODE_LV = 10) current                  | —    | —    | 100  | μV/mA    |       |
| $T_{stup}$ | Buffer startup time                                     | 100  | —    | TBD  | μs       |       |
| DC         | Line regulation (power supply rejection)                | —    | —    | TBD  | mV       |       |
|            |                                                         | −60  | —    | TBD  | dB       |       |

**Table 32. VREF limited-range operating requirements**

| Symbol | Description | Min. | Max. | Unit | Notes |
|--------|-------------|------|------|------|-------|
| $T_A$  | Temperature | 0    | 50   | °C   |       |

**Table 33. VREF limited-range operating behaviors**

| Symbol    | Description                                | Min. | Max. | Unit | Notes |
|-----------|--------------------------------------------|------|------|------|-------|
| $V_{out}$ | Voltage reference output with factory trim | TBD  | TBD  | μA   |       |

TBD

**Figure 15. Typical output vs. temperature**

TBD

**Figure 16. Typical output vs. VDD**

## 6.7 Timers

See [General Switching Specifications](#).

## 6.8 Communication interfaces

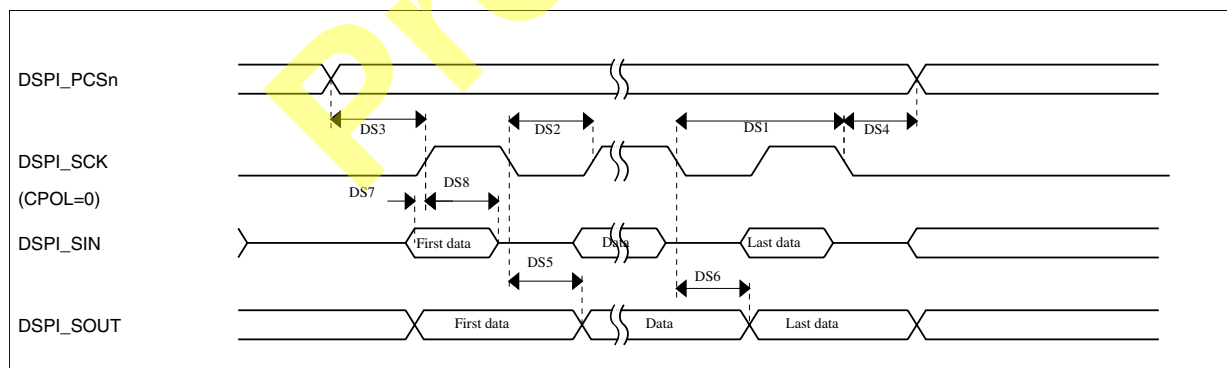
## 6.8.1 DSPI Switching Specifications for Low-speed Operation

The DMA Serial Peripheral Interface (DSPI) provides a synchronous serial bus with master and slave operations. Many of the transfer attributes are programmable. The tables below provides DSPI timing characteristics for classic SPI timing modes. Refer to the DSPI chapter of the Reference Manual for information on the modified transfer formats used for communicating with slower peripheral devices.

**Table 34. Master Mode DSPI Timing (Low-speed mode)**

| Num | Description                        | Min.                       | Max.                     | Unit | Notes |
|-----|------------------------------------|----------------------------|--------------------------|------|-------|
|     | Operating voltage                  | 1.71                       | 3.6                      | V    | 1     |
|     | Frequency of operation             | —                          | 12.5                     | MHz  |       |
| DS1 | DSPI_SCK output cycle time         | $4 \times t_{\text{BCLK}}$ | —                        | ns   |       |
| DS2 | DSPI_SCK output high/low time      | $(t_{\text{SCK}}/2) - 4$   | $(t_{\text{SCK}}/2) + 4$ | ns   |       |
| DS3 | DSPI_PCSn to DSPI_SCK output valid | $(t_{\text{SCK}}/2) - 4$   | —                        | ns   |       |
| DS4 | DSPI_SCK to DSPI_PCSn output hold  | $(t_{\text{SCK}}/2) - 4$   | —                        | ns   |       |
| DS5 | DSPI_SCK to DSPI_SOUT valid        | —                          | 10                       | ns   |       |
| DS6 | DSPI_SCK to DSPI_SOUT invalid      | -2                         | —                        | ns   |       |
| DS7 | DSPI_SIN to DSPI_SCK input setup   | 15                         | —                        | ns   |       |
| DS8 | DSPI_SCK to DSPI_SIN input hold    | 0                          | —                        | ns   |       |

1. The DSPI module can operate across the entire operating voltage for the processor, but to run across the full voltage range the maximum frequency of operation is reduced.



**Figure 17. DSPI Classic SPI Timing — Master Mode**

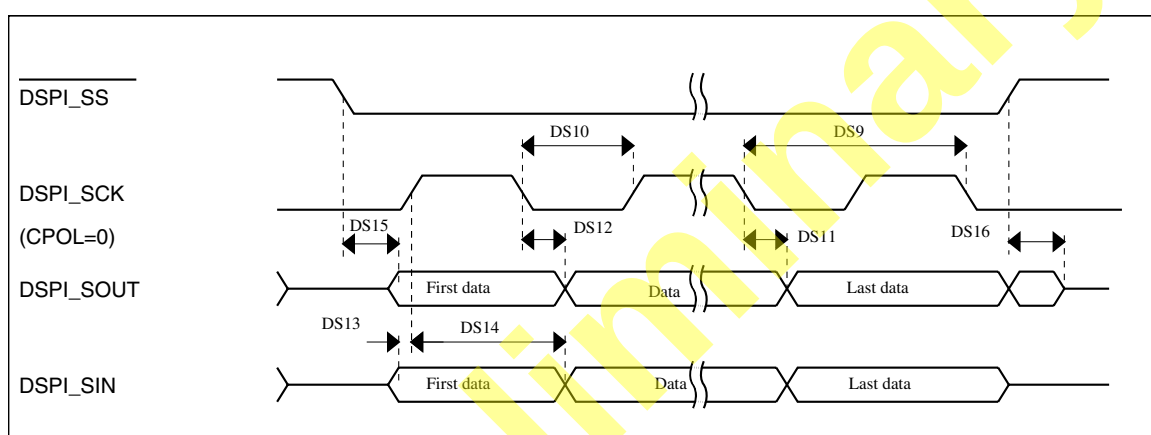
**Table 35. Slave Mode DSPI Timing (Low-speed Mode)**

| Num | Description            | Min. | Max. | Unit |
|-----|------------------------|------|------|------|
|     | Operating voltage      | 1.71 | 3.6  | V    |
|     | Frequency of operation | —    | 6.25 | MHz  |

Table continues on the next page...

**Table 35. Slave Mode DSPI Timing (Low-speed Mode) (continued)**

| Num  | Description                                                   | Min.                | Max.              | Unit    |
|------|---------------------------------------------------------------|---------------------|-------------------|---------|
| DS9  | DSPI_SCK input cycle time                                     | $8 \times t_{BCLK}$ | —                 | ns      |
| DS10 | DSPI_SCK input high/low time                                  | $(t_{SCK}/2) - 4$   | $(t_{SCK}/2) + 4$ | ns      |
| DS11 | DSPI_SCK to DSPI_SOUT valid                                   | —                   | 20                | ns      |
| DS12 | DSPI_SCK to DSPI_SOUT invalid                                 | 0                   | —                 | ns      |
| DS13 | DSPI_SIN to DSPI_SCK input setup                              | 5                   | —                 | ns      |
| DS14 | DSPI_SCK to DSPI_SIN input hold                               | 15                  | —                 | ns      |
| DS15 | $\overline{\text{DSPI\_SS}}$ active to DSPI_SOUT driven       | —                   | 15                | ns </td |
| DS16 | $\overline{\text{DSPI\_SS}}$ inactive to DSPI_SOUT not driven | —                   | 15                | ns      |

**Figure 18. DSPI Classic SPI Timing — Slave Mode**

## 6.8.2 DSPI Switching Specifications (High-speed mode)

The DMA Serial Peripheral Interface (DSPI) provides a synchronous serial bus with master and slave operations. Many of the transfer attributes are programmable. The tables below provide DSPI timing characteristics for classic SPI timing modes. Refer to the DSPI chapter of the Reference Manual for information on the modified transfer formats used for communicating with slower peripheral devices.

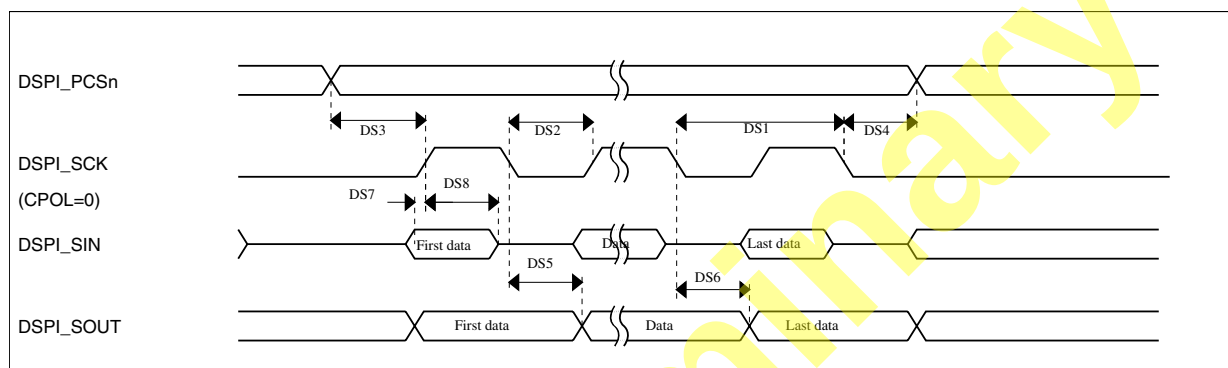
**Table 36. Master Mode DSPI Timing (High-speed mode)**

| Num | Description                   | Min.                | Max.              | Unit |
|-----|-------------------------------|---------------------|-------------------|------|
|     | Operating voltage             | 2.7                 | 3.6               | V    |
|     | Frequency of operation        | —                   | 25                | MHz  |
| DS1 | DSPI_SCK output cycle time    | $2 \times t_{BCLK}$ | —                 | ns   |
| DS2 | DSPI_SCK output high/low time | $(t_{SCK}/2) - 2$   | $(t_{SCK}/2) + 2$ | ns   |

Table continues on the next page...

**Table 36. Master Mode DSPI Timing (High-speed mode) (continued)**

| Num | Description                        | Min.                     | Max. | Unit |
|-----|------------------------------------|--------------------------|------|------|
| DS3 | DSPI_PCSn to DSPI_SCK output valid | $(t_{\text{SCK}}/2) - 2$ | —    | ns   |
| DS4 | DSPI_SCK to DSPI_PCSn output hold  | $(t_{\text{SCK}}/2) - 2$ | —    | ns   |
| DS5 | DSPI_SCK to DSPI_SOUT valid        | —                        | 8.5  | ns   |
| DS6 | DSPI_SCK to DSPI_SOUT invalid      | -2                       | —    | ns   |
| DS7 | DSPI_SIN to DSPI_SCK input setup   | TBD                      | —    | ns   |
| DS8 | DSPI_SCK to DSPI_SIN input hold    | 0                        | —    | ns   |

**Figure 19. DSPI Classic SPI Timing — Master Mode****Table 37. Slave Mode DSPI Timing (High-speed mode)**

| Num  | Description                              | Min.                       | Max.                     | Unit |
|------|------------------------------------------|----------------------------|--------------------------|------|
|      | Operating voltage                        | 2.7                        | 3.6                      | V    |
|      | Frequency of operation                   |                            | 12.5                     | MHz  |
| DS9  | DSPI_SCK input cycle time                | $4 \times t_{\text{BCLK}}$ | —                        | ns   |
| DS10 | DSPI_SCK input high/low time             | $(t_{\text{SCK}}/2) - 2$   | $(t_{\text{SCK}}/2) + 2$ | ns   |
| DS11 | DSPI_SCK to DSPI_SOUT valid              | —                          | TBD                      | ns   |
| DS12 | DSPI_SCK to DSPI_SOUT invalid            | 0                          | —                        | ns   |
| DS13 | DSPI_SIN to DSPI_SCK input setup         | 2                          | —                        | ns   |
| DS14 | DSPI_SCK to DSPI_SIN input hold          | 7                          | —                        | ns   |
| DS15 | DSPI_SS active to DSPI_SOUT driven       | —                          | 14                       | ns   |
| DS16 | DSPI_SS inactive to DSPI_SOUT not driven | —                          | 14                       | ns   |

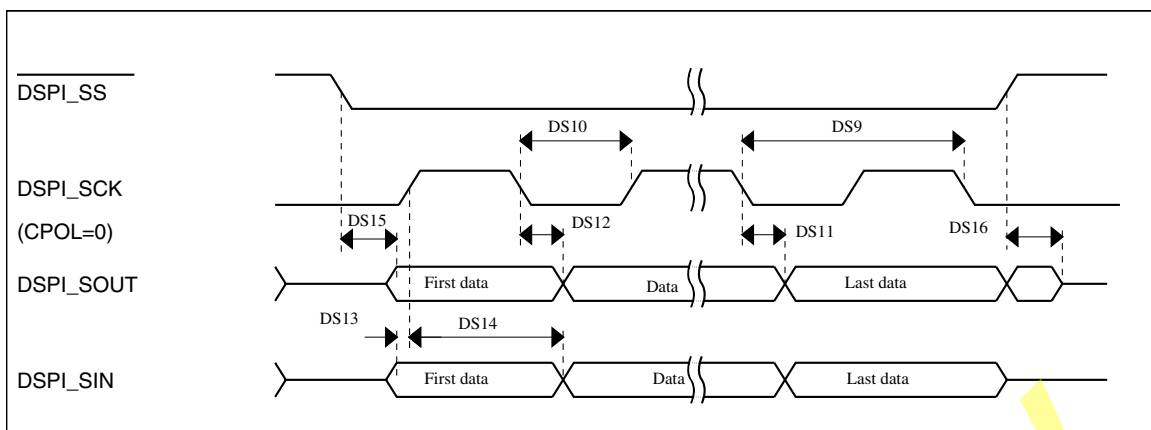


Figure 20. DSPI Classic SPI Timing — Slave Mode

### 6.8.3 SDHC Specifications

The following timing specs are defined at the chip I/O pin and must be translated appropriately to arrive at timing specs/constraints for the physical interface.

Table 38. SDHC switching specifications

| Num                                                                         | Symbol           | Description                           | Min. | Max. | Unit |
|-----------------------------------------------------------------------------|------------------|---------------------------------------|------|------|------|
| <b>Card input clock</b>                                                     |                  |                                       |      |      |      |
| SD1                                                                         | fpp              | Clock frequency (low speed)           | 0    | 400  | kHz  |
|                                                                             | fpp              | Clock frequency (SD/SDIO full speed)  | 0    | 25   | MHz  |
|                                                                             | fpp              | Clock frequency (MMC full speed)      | 0    | 20   | MHz  |
|                                                                             | f <sub>OD</sub>  | Clock frequency (identification mode) | 0    | 400  | kHz  |
| SD2                                                                         | t <sub>WL</sub>  | Clock low time                        | 7    | —    | ns   |
| SD3                                                                         | t <sub>WH</sub>  | Clock high time                       | 7    | —    | ns   |
| SD4                                                                         | t <sub>TLH</sub> | Clock rise time                       | —    | 3    | ns   |
| SD5                                                                         | t <sub>THL</sub> | Clock fall time                       | —    | 3    | ns   |
| <b>SDHC output / card inputs SDHC_CMD, SDHC_DAT (reference to SDHC_CLK)</b> |                  |                                       |      |      |      |
| SD6                                                                         | t <sub>OD</sub>  | SDHC output delay (output valid)      | -5   | 6.5  | ns   |
| <b>SDHC input / card inputs SDHC_CMD, SDHC_DAT (reference to SDHC_CLK)</b>  |                  |                                       |      |      |      |
| SD7                                                                         | t <sub>THL</sub> | SDHC input setup time                 | 5    | —    | ns   |
| SD8                                                                         | t <sub>THL</sub> | SDHC input hold time                  | 0    | —    | ns   |

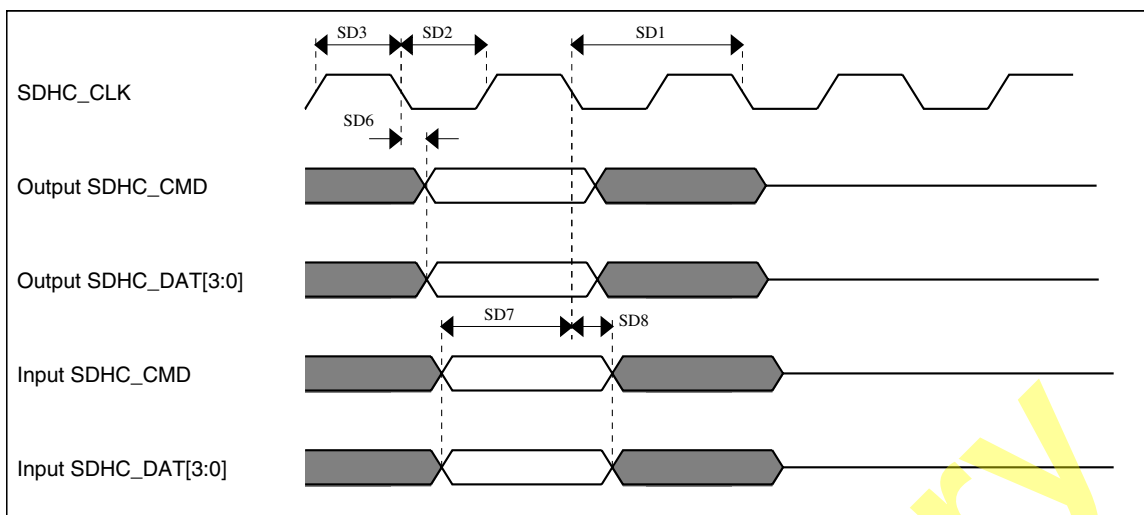


Figure 21. SDHC timing

### 6.8.4 I<sup>2</sup>S Switching Specifications

This section provides the AC timings for the I<sup>2</sup>S in master (clocks driven) and slave modes (clocks input). All timings are given for non-inverted serial clock polarity (TCR[TSCKP] = 0, RCR[RSCKP] = 0) and a non-inverted frame sync (TCR[TFSI] = 0, RCR[RFSI] = 0). If the polarity of the clock and/or the frame sync have been inverted, all the timings remain valid by inverting the clock signal (I2S\_BCLK) and/or the frame sync (I2S\_FS) shown in the figures below.

Table 39. I<sup>2</sup>S master mode timing

| Num | Description                                | Min.                 | Max. | Unit        |
|-----|--------------------------------------------|----------------------|------|-------------|
|     | Operating voltage                          | 2.7                  | 3.6  | V           |
| S1  | I2S_MCLK cycle time                        | 2 x t <sub>sys</sub> |      | ns          |
| S2  | I2S_MCLK pulse width high/low              | 45%                  | 55%  | MCLK period |
| S3  | I2S_BCLK cycle time                        | 5 x t <sub>sys</sub> | —    | ns          |
| S4  | I2S_BCLK pulse width high/low              | 45%                  | 55%  | BCLK period |
| S5  | I2S_BCLK to I2S_FS output valid            | —                    | 15   | ns          |
| S6  | I2S_BCLK to I2S_FS output invalid          | -2.5                 | —    | ns          |
| S7  | I2S_BCLK to I2S_TXD valid                  | —                    | 15   | ns          |
| S8  | I2S_BCLK to I2S_TXD invalid                | -3                   | —    | ns          |
| S9  | I2S_RXD/I2S_FS input setup before I2S_BCLK | 20                   | —    | ns          |
| S10 | I2S_RXD/I2S_FS input hold after I2S_BCLK   | 0                    | —    | ns          |

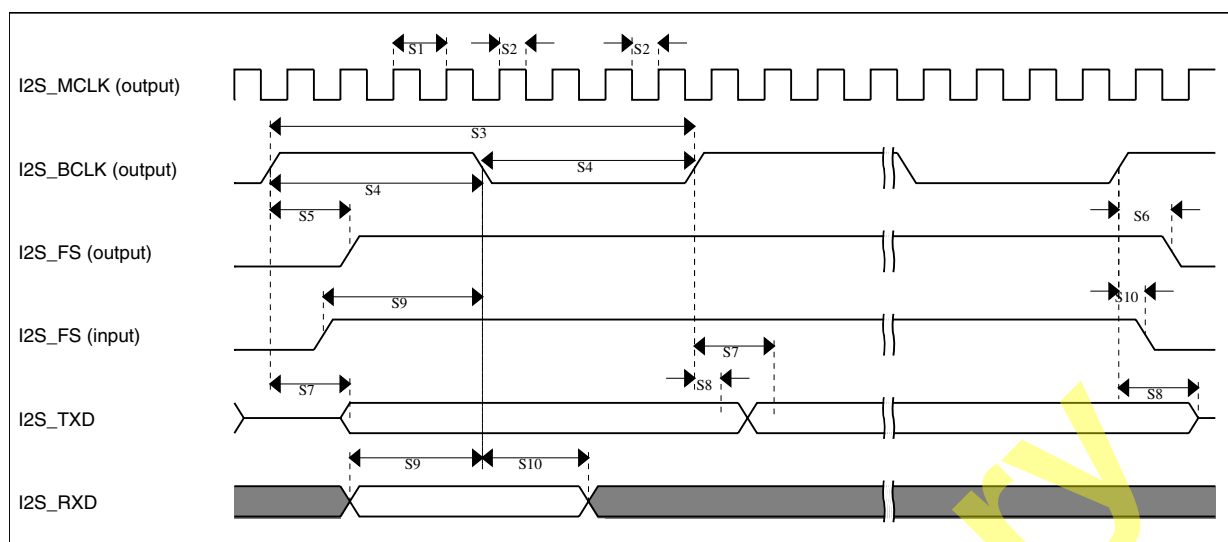


Figure 22. I²S timing — master mode

Table 40. I²S slave mode timing

| Num | Description                               | Min.               | Max. | Unit        |
|-----|-------------------------------------------|--------------------|------|-------------|
|     | Operating voltage                         | 2.7                | 3.6  | V           |
| S11 | I2S_BCLK cycle time (input)               | $8 \times t_{SYS}$ | —    | ns          |
| S12 | I2S_BCLK pulse width high/low (input)     | 45%                | 55%  | MCLK period |
| S13 | I2S_FS input setup before I2S_BCLK        | 10                 | —    | ns          |
| S14 | I2S_FS input hold after I2S_BCLK          | 3                  | —    | ns          |
| S15 | I2S_BCLK to I2S_TXD/I2S_FS output valid   | —                  | 20   | ns          |
| S16 | I2S_BCLK to I2S_TXD/I2S_FS output invalid | 0                  | —    | ns          |
| S17 | I2S_RXD setup before I2S_BCLK             | 10                 | —    | ns          |
| S18 | I2S_RXD hold after I2S_BCLK               | 2                  | —    | ns          |

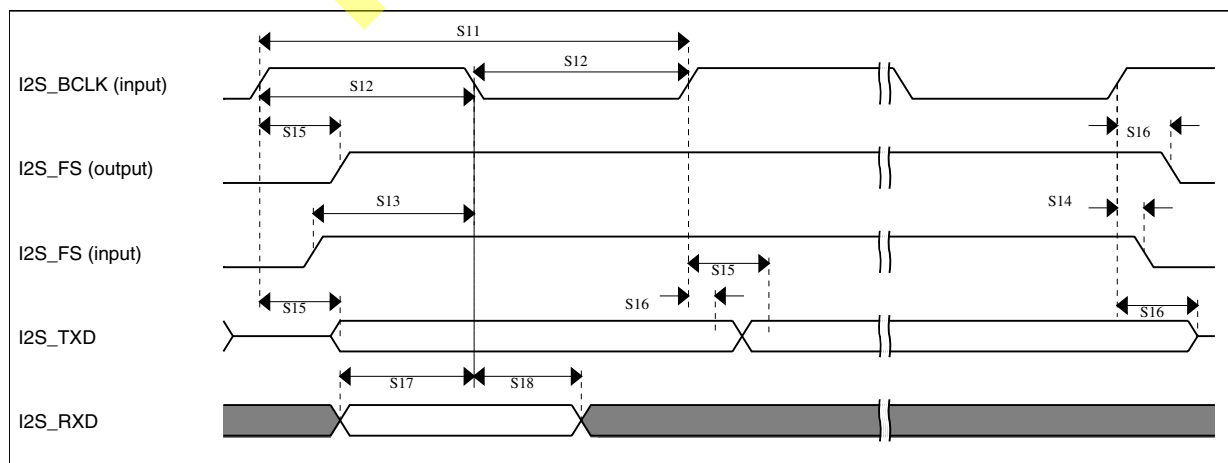


Figure 23. I²S timing — slave modes

## 6.9 Human-machine interfaces (HMI)

### 6.9.1 General Switching Specifications

These general purpose specifications apply to all signals configured for GPIO, SCI, FlexCAN, CMT, and I<sup>2</sup>C signals.

**Table 41. General switching specifications**

| Symbol | Description                                                                                                 | Min. | Max. | Unit             | Notes |
|--------|-------------------------------------------------------------------------------------------------------------|------|------|------------------|-------|
|        | GPIO pin interrupt pulse width (digital glitch filter disabled) — Synchronous path                          | 1.5  | —    | Bus clock cycles | 1     |
|        | GPIO pin interrupt pulse width (digital glitch filter disabled, analog filter enabled) — Asynchronous path  | 100  | —    | ns               | 2     |
|        | GPIO pin interrupt pulse width (digital glitch filter disabled, analog filter disabled) — Asynchronous path | 16   | —    | ns               | 2     |
|        | External reset pulse width (digital glitch filter disabled)                                                 | TBD  | —    |                  |       |
|        | Mode select (EZP_CS) hold time after reset deassertion                                                      | 2    | —    | Bus clock cycles |       |
|        | Port rise and fall time (high drive strength)                                                               |      |      |                  | 3     |
|        | • Slew disabled                                                                                             | —    | 12   | ns               |       |
|        | • Slew enabled                                                                                              | —    | 36   | ns               |       |
|        | Port rise and fall time (low drive strength)                                                                |      |      |                  | 4     |
|        | • Slew disabled                                                                                             | —    | 32   | ns               |       |
|        | • Slew enabled                                                                                              | —    | 36   | ns               |       |

1. The greater synchronous and asynchronous timing must be met.
2. This is the shortest pulse that is guaranteed to be recognized.
3. 75pF load
4. 15pF load

### 6.9.2 TSI Electrical Specifications

**Table 42. Touch Sensing Input module specifications**

| Symbol              | Description                        | Min. | Typ. | Max. | Unit | Notes |
|---------------------|------------------------------------|------|------|------|------|-------|
| V <sub>DDTSI</sub>  | Operating voltage                  | 1.71 | —    | 3.6  | V    |       |
| C <sub>ELE</sub>    | Target electrode capacitance range | 1    | 20   | 500  | pF   | 1     |
| f <sub>REFmax</sub> | Reference oscillator frequency     | —    | 5.5  | TBD  | MHz  |       |

Table continues on the next page...

**Table 42. Touch Sensing Input module specifications (continued)**

| Symbol                | Description                                      | Min.  | Typ.  | Max. | Unit          | Notes |
|-----------------------|--------------------------------------------------|-------|-------|------|---------------|-------|
| $f_{\text{ELEmax}}$   | Electrode oscillator frequency                   | —     | 0.5   | TBD  | MHz           |       |
| $C_{\text{REF}}$      | Internal reference capacitor                     | TBD   | 1     | TBD  | pF            |       |
| $V_{\text{DELTA}}$    | Oscillator delta voltage                         | TBD   | 600   | TBD  | mV            |       |
| $I_{\text{REF}}$      | Reference oscillator current source base current | TBD   | 1     | TBD  | $\mu\text{A}$ | 2     |
| $I_{\text{ELE}}$      | Electrode oscillator current source base current | TBD   | 1     | TBD  | $\mu\text{A}$ | 3     |
| Pres5                 | Electrode capacitance measurement precision      | —     | TBD   | TBD  | %             | 4     |
| Pres20                | Electrode capacitance measurement precision      | —     | TBD   | TBD  | %             | 5     |
| Pres100               | Electrode capacitance measurement precision      | —     | TBD   | TBD  | %             | 6     |
| Max-Sens20            | Max sensitivity @ 20pF electrode                 | 0.15  | 0.326 | 600  | fF            | 7     |
| MaxSens               | Maximum sensitivity                              | 0.006 | 0.326 | 24   | fF            | 8     |
| Res                   | Resolution                                       | —     | —     | 16   | bits          |       |
| $T_{\text{Con20}}$    | Response time @ 20pF                             | —     | 30    | —    | $\mu\text{s}$ | 9     |
| $I_{\text{TSL\_RUN}}$ | Current added in run mode                        | —     | TBD   | —    | $\mu\text{A}$ |       |
| $I_{\text{TSL\_LP}}$  | Low power mode current adder                     | —     | 1     | TBD  | $\mu\text{A}$ |       |

1. The TSI module is functional with capacitance values outside of this range. However, optimal performance is not guaranteed.
2. The programmable current source value is generated by multiplying the SCANC[REFCHRG] value and the base current
3. The programmable current source value is generated by multiplying the SCANC[EXTCHRG] value and the base current
4. Measured with a 5pF electrode, reference oscillator frequency of 10MHz, PS = 128, NCSC = 8; lext = 16
5. Measured with a 20pF electrode, reference oscillator frequency of 10MHz, PS = 128, NCSC = 2; lext = 16
6. Measured with a 20pF electrode, reference oscillator frequency of 10MHz, PS = 16, NCSC = 3; lext = 16
7. 6.2ms scan time
8. 1pF electrode capacitance with 4.96ms scan time
9. Time that takes to do one complete measurement of the electrode. Sensitivity resolution of 0.0133pF

## 7 Dimensions

### 7.1 Obtaining package dimensions

Package dimensions are provided in package drawings.

To find a package drawing, go to [www.freescale.com](http://www.freescale.com) and perform a keyword search for the drawing's document number:

| If you want the drawing for this package | Then use this document number |
|------------------------------------------|-------------------------------|
| 80-pin LQFP                              | 98ASS23174W                   |
| 81-pin MAPBGA                            | 98ASH98051A                   |

## 8 Pinout

### 8.1 K10 Signal Multiplexing and Pin Assignments

The following table shows the signals available on each pin and the locations of these pins on the devices supported by this document. The Port Control Module is responsible for selecting which ALT functionality is available on each pin.

| 80 QFP | Default                           | ALT0                              | ALT1  | ALT2      | ALT3        | ALT4       | ALT5 | ALT6       | ALT7 | EzPort |
|--------|-----------------------------------|-----------------------------------|-------|-----------|-------------|------------|------|------------|------|--------|
| 1      | ADC1_SE4a                         | ADC1_SE4a                         | PTE0  | SPI1_PCS1 | UART1_TX    | SDHC0_D1   |      | I2C1_SDA   |      |        |
| 2      | ADC1_SE5a                         | ADC1_SE5a                         | PTE1  | SPI1_SOUT | UART1_RX    | SDHC0_D0   |      | I2C1_SCL   |      |        |
| 3      | ADC1_SE6a                         | ADC1_SE6a                         | PTE2  | SPI1_SCK  | UART1_CTS_b | SDHC0_DCLK |      |            |      |        |
| 4      | ADC1_SE7a                         | ADC1_SE7a                         | PTE3  | SPI1_SIN  | UART1_RTS_b | SDHC0_CMD  |      |            |      |        |
| 5      | DISABLED                          |                                   | PTE4  | SPI1_PCS0 | UART3_TX    | SDHC0_D3   |      |            |      |        |
| 6      | DISABLED                          |                                   | PTE5  | SPI1_PCS2 | UART3_RX    | SDHC0_D2   |      |            |      |        |
| 7      | VDD                               | VDD                               |       |           |             |            |      |            |      |        |
| 8      | VSS                               | VSS                               |       |           |             |            |      |            |      |        |
| 9      | ADC0_SE4a                         | ADC0_SE4a                         | PTE16 | SPI0_PCS0 | UART2_TX    | FTM_CLKIN0 |      | FTM0_FLT3  |      |        |
| 10     | ADC0_SE5a                         | ADC0_SE5a                         | PTE17 | SPI0_SCK  | UART2_RX    | FTM_CLKIN1 |      | LPT00_ALT3 |      |        |
| 11     | ADC0_SE6a                         | ADC0_SE6a                         | PTE18 | SPI0_SOUT | UART2_CTS_b | I2C0_SDA   |      |            |      |        |
| 12     | ADC0_SE7a                         | ADC0_SE7a                         | PTE19 | SPI0_SIN  | UART2_RTS_b | I2C0_SCL   |      |            |      |        |
| 13     | PGA0_DP/<br>ADC0_DP0/<br>ADC1_DP3 | PGA0_DP/<br>ADC0_DP0/<br>ADC1_DP3 |       |           |             |            |      |            |      |        |
| 14     | PGA0_DM/<br>ADC0_DM0/<br>ADC1_DM3 | PGA0_DM/<br>ADC0_DM0/<br>ADC1_DM3 |       |           |             |            |      |            |      |        |
| 15     | PGA1_DP/<br>ADC1_DP0/<br>ADC0_DP3 | PGA1_DP/<br>ADC1_DP0/<br>ADC0_DP3 |       |           |             |            |      |            |      |        |
| 16     | PGA1_DM/<br>ADC1_DM0/<br>ADC0_DM3 | PGA1_DM/<br>ADC1_DM0/<br>ADC0_DM3 |       |           |             |            |      |            |      |        |
| 17     | VDDA                              | VDDA                              |       |           |             |            |      |            |      |        |
| 18     | VREFH                             | VREFH                             |       |           |             |            |      |            |      |        |
| 19     | VREFL                             | VREFL                             |       |           |             |            |      |            |      |        |
| 20     | VSSA                              | VSSA                              |       |           |             |            |      |            |      |        |
| 21     | VREF_OUT                          | VREF_OUT                          |       |           |             |            |      |            |      |        |
| 22     | DAC0_OUT                          | DAC0_OUT                          |       |           |             |            |      |            |      |        |

| 80 QFP | Default                            | ALT0                               | ALT1  | ALT2            | ALT3            | ALT4       | ALT5     | ALT6            | ALT7                   | EzPort   |
|--------|------------------------------------|------------------------------------|-------|-----------------|-----------------|------------|----------|-----------------|------------------------|----------|
| 23     | XTAL32                             | XTAL32                             |       |                 |                 |            |          |                 |                        |          |
| 24     | EXTAL32                            | EXTAL32                            |       |                 |                 |            |          |                 |                        |          |
| 25     | VBAT                               | VBAT                               |       |                 |                 |            |          |                 |                        |          |
| 26     | JTAG_TCLK/<br>SWD_CLK/<br>EZP_CLK  | TSI0_CH1                           | PTA0  | UART0_CTS_<br>b | FTM0_CH5        |            |          |                 | JTAG_TCLK/<br>SWD_CLK  | EZP_CLK  |
| 27     | JTAG_TDI/<br>EZP_DI                | TSI0_CH2                           | PTA1  | UART0_RX        | FTM0_CH6        |            |          |                 | JTAG_TDI               | EZP_DI   |
| 28     | JTAG_TDO/<br>TRACE_SWO/<br>EZP_DO  | TSI0_CH3                           | PTA2  | UART0_TX        | FTM0_CH7        |            |          |                 | JTAG_TDO/<br>TRACE_SWO | EZP_DO   |
| 29     | JTAG_TMS/<br>SWD_DIO               | TSI0_CH4                           | PTA3  | UART0_RTS_<br>b | FTM0_CH0        |            |          |                 | JTAG_TMS/<br>SWD_DIO   |          |
| 30     | NMI_b/<br>EZP_CS_b                 | TSI0_CH5                           | PTA4  |                 | FTM0_CH1        |            |          |                 | NMI_b                  | EZP_CS_b |
| 31     | JTAG_TRST                          |                                    | PTA5  |                 | FTM0_CH2        |            | CMP2_OUT | I2S0_RX_BCLK    | JTAG_TRST              |          |
| 32     | CMP2_IN0                           | CMP2_IN0                           | PTA12 | CAN0_TX         | FTM1_CH0        |            |          | I2S0_TXD        | FTM1_QD_PH<br>A        |          |
| 33     | CMP2_IN1                           | CMP2_IN1                           | PTA13 | CAN0_RX         | FTM1_CH1        |            |          | I2S0_TX_FS      | FTM1_QD_PH<br>B        |          |
| 34     | DISABLED                           |                                    | PTA14 | SPI0_PCS0       | UART0_TX        |            |          | I2S0_TX_BCLK    |                        |          |
| 35     | DISABLED                           |                                    | PTA15 | SPI0_SCK        | UART0_RX        |            |          | I2S0_RXD        |                        |          |
| 36     | DISABLED                           |                                    | PTA16 | SPI0_SOUT       | UART0_CTS_<br>b |            |          | I2S0_RX_FS      |                        |          |
| 37     | ADC1_SE17                          | ADC1_SE17                          | PTA17 | SPI0_SIN        | UART0_RTS_<br>b |            |          | I2S0_MCLK       | I2S0_CLKIN             |          |
| 38     | VDD                                | VDD                                |       |                 |                 |            |          |                 |                        |          |
| 39     | VSS                                | VSS                                |       |                 |                 |            |          |                 |                        |          |
| 40     | EXTAL                              | EXTAL                              | PTA18 |                 | FTM0_FLT2       | FTM_CLKIN0 |          |                 |                        |          |
| 41     | XTAL                               | XTAL                               | PTA19 |                 | FTM1_FLT0       | FTM_CLKIN1 |          | LPT0_ALT1       |                        |          |
| 42     | RESET_b                            | RESET_b                            |       |                 |                 |            |          |                 |                        |          |
| 43     | ADC0_SE8/<br>ADC1_SE8/<br>TSI0_CH0 | ADC0_SE8/<br>ADC1_SE8/<br>TSI0_CH0 | PTB0  | I2C0_SCL        | FTM1_CH0        |            |          | FTM1_QD_PH<br>A |                        |          |
| 44     | ADC0_SE9/<br>ADC1_SE9/<br>TSI0_CH6 | ADC0_SE9/<br>ADC1_SE9/<br>TSI0_CH6 | PTB1  | I2C0_SDA        | FTM1_CH1        |            |          | FTM1_QD_PH<br>B |                        |          |
| 45     | ADC0_SE12/<br>TSI0_CH7             | ADC0_SE12/<br>TSI0_CH7             | PTB2  | I2C0_SCL        | UART0_RTS_<br>b |            |          | FTM0_FLT3       |                        |          |
| 46     | ADC0_SE13/<br>TSI0_CH8             | ADC0_SE13/<br>TSI0_CH8             | PTB3  | I2C0_SDA        | UART0_CTS_<br>b |            |          | FTM0_FLT0       |                        |          |
| 47     | ADC1_SE14                          | ADC1_SE14                          | PTB10 | SPI1_PCS0       | UART3_RX        |            | FB_AD19  | FTM0_FLT1       |                        |          |
| 48     | ADC1_SE15                          | ADC1_SE15                          | PTB11 | SPI1_SCK        | UART3_TX        |            | FB_AD18  | FTM0_FLT2       |                        |          |
| 49     | VSS                                | VSS                                |       |                 |                 |            |          |                 |                        |          |
| 50     | VDD                                | VDD                                |       |                 |                 |            |          |                 |                        |          |

## Pinout

| 80 QFP | Default                      | ALT0                         | ALT1  | ALT2      | ALT3        | ALT4         | ALT5                                               | ALT6        | ALT7 | EzPort |
|--------|------------------------------|------------------------------|-------|-----------|-------------|--------------|----------------------------------------------------|-------------|------|--------|
| 51     | TSI0_CH9                     | TSI0_CH9                     | PTB16 | SPI1_SOUT | UART0_RX    |              | FB_AD17                                            | EWM_IN      |      |        |
| 52     | TSI0_CH10                    | TSI0_CH10                    | PTB17 | SPI1_SIN  | UART0_TX    |              | FB_AD16                                            | EWM_OUT_b   |      |        |
| 53     | TSI0_CH11                    | TSI0_CH11                    | PTB18 | CAN0_TX   | FTM2_CH0    | I2S0_TX_BCLK | FB_AD15                                            | FTM2_QD_PHA |      |        |
| 54     | TSI0_CH12                    | TSI0_CH12                    | PTB19 | CAN0_RX   | FTM2_CH1    | I2S0_TX_FS   | FB_OE_b                                            | FTM2_QD_PHB |      |        |
| 55     | ADC0_SE14/TSI0_CH13          | ADC0_SE14/TSI0_CH13          | PTC0  | SPI0_PCS4 | PDB0_EXTRG  | I2S0_TXD     | FB_AD14                                            |             |      |        |
| 56     | ADC0_SE15/TSI0_CH14          | ADC0_SE15/TSI0_CH14          | PTC1  | SPI0_PCS3 | UART1_RTS_b | FTM0_CH0     | FB_AD13                                            |             |      |        |
| 57     | ADC0_SE4b/CMP1_IN0/TSI0_CH15 | ADC0_SE4b/CMP1_IN0/TSI0_CH15 | PTC2  | SPI0_PCS2 | UART1_CTS_b | FTM0_CH1     | FB_AD12                                            |             |      |        |
| 58     | CMP1_IN1                     | CMP1_IN1                     | PTC3  | SPI0_PCS1 | UART1_RX    | FTM0_CH2     | FB_CLKOUT                                          |             |      |        |
| 59     | VSS                          | VSS                          |       |           |             |              |                                                    |             |      |        |
| 60     | VDD                          | VDD                          |       |           |             |              |                                                    |             |      |        |
| 61     | DISABLED                     |                              | PTC4  | SPI0_PCS0 | UART1_TX    | FTM0_CH3     | FB_AD11                                            | CMP1_OUT    |      |        |
| 62     | DISABLED                     |                              | PTC5  | SPI0_SCK  |             | LPT0_ALT2    | FB_AD10                                            | CMP0_OUT    |      |        |
| 63     | CMP0_IN0                     | CMP0_IN0                     | PTC6  | SPI0_SOUT | PDB0_EXTRG  |              | FB_AD9                                             |             |      |        |
| 64     | CMP0_IN1                     | CMP0_IN1                     | PTC7  | SPI0_SIN  |             |              | FB_AD8                                             |             |      |        |
| 65     | ADC1_SE4b/CMP0_IN2           | ADC1_SE4b/CMP0_IN2           | PTC8  |           | I2S0_MCLK   | I2S0_CLKIN   | FB_AD7                                             |             |      |        |
| 66     | ADC1_SE5b/CMP0_IN3           | ADC1_SE5b/CMP0_IN3           | PTC9  |           |             | I2S0_RX_BCLK | FB_AD6                                             | FTM2_FLT0   |      |        |
| 67     | ADC1_SE6b/CMP0_IN4           | ADC1_SE6b/CMP0_IN4           | PTC10 | I2C1_SCL  |             | I2S0_RX_FS   | FB_AD5                                             |             |      |        |
| 68     | ADC1_SE7b                    | ADC1_SE7b                    | PTC11 | I2C1_SDA  |             | I2S0_RXD     | FB_RW_b                                            |             |      |        |
| 69     | VSS                          | VSS                          |       |           |             |              |                                                    |             |      |        |
| 70     | VDD                          | VDD                          |       |           |             |              |                                                    |             |      |        |
| 71     | DISABLED                     |                              | PTC16 | CAN1_RX   | UART3_RX    |              | FB_CS5_b/<br>FB_TSI21/<br>FB_BE23_16_<br>BLS15_8_b |             |      |        |
| 72     | DISABLED                     |                              | PTC17 | CAN1_TX   | UART3_TX    |              | FB_CS4_b/<br>FB_TSI20/<br>FB_BE31_24_<br>BLS7_0_b  |             |      |        |
| 73     | DISABLED                     |                              | PTD0  | SPI0_PCS0 | UART2_RTS_b |              | FB_ALE/<br>FB_CS1_b/<br>FB_TS_b                    |             |      |        |
| 74     | ADC0_SE5b                    | ADC0_SE5b                    | PTD1  | SPI0_SCK  | UART2_CTS_b |              | FB_CS0_b                                           |             |      |        |
| 75     | DISABLED                     |                              | PTD2  | SPI0_SOUT | UART2_RX    |              | FB_AD4                                             |             |      |        |
| 76     | DISABLED                     |                              | PTD3  | SPI0_SIN  | UART2_TX    |              | FB_AD3                                             |             |      |        |
| 77     | DISABLED                     |                              | PTD4  | SPI0_PCS1 | UART0_RTS_b | FTM0_CH4     | FB_AD2                                             | EWM_IN      |      |        |

| 80 QFP | Default   | ALT0      | ALT1 | ALT2      | ALT3        | ALT4     | ALT5   | ALT6      | ALT7 | EzPort |
|--------|-----------|-----------|------|-----------|-------------|----------|--------|-----------|------|--------|
| 78     | ADC0_SE6b | ADC0_SE6b | PTD5 | SPI0_PCS2 | UART0_CTS_b | FTM0_CH5 | FB_AD1 | EWM_OUT_b |      |        |
| 79     | ADC0_SE7b | ADC0_SE7b | PTD6 | SPI0_PCS3 | UART0_RX    | FTM0_CH6 | FB_AD0 | FTM0_FLT0 |      |        |
| 80     | DISABLED  |           | PTD7 | CMT_IRO   | UART0_TX    | FTM0_CH7 |        | FTM0_FLT1 |      |        |

## 8.2 K10 Pinouts

The below figure shows the pinout diagram for the devices supported by this document. Many signals may be multiplexed onto a single pin. To determine what signals can be used on which pin, see the previous section.

Preliminary

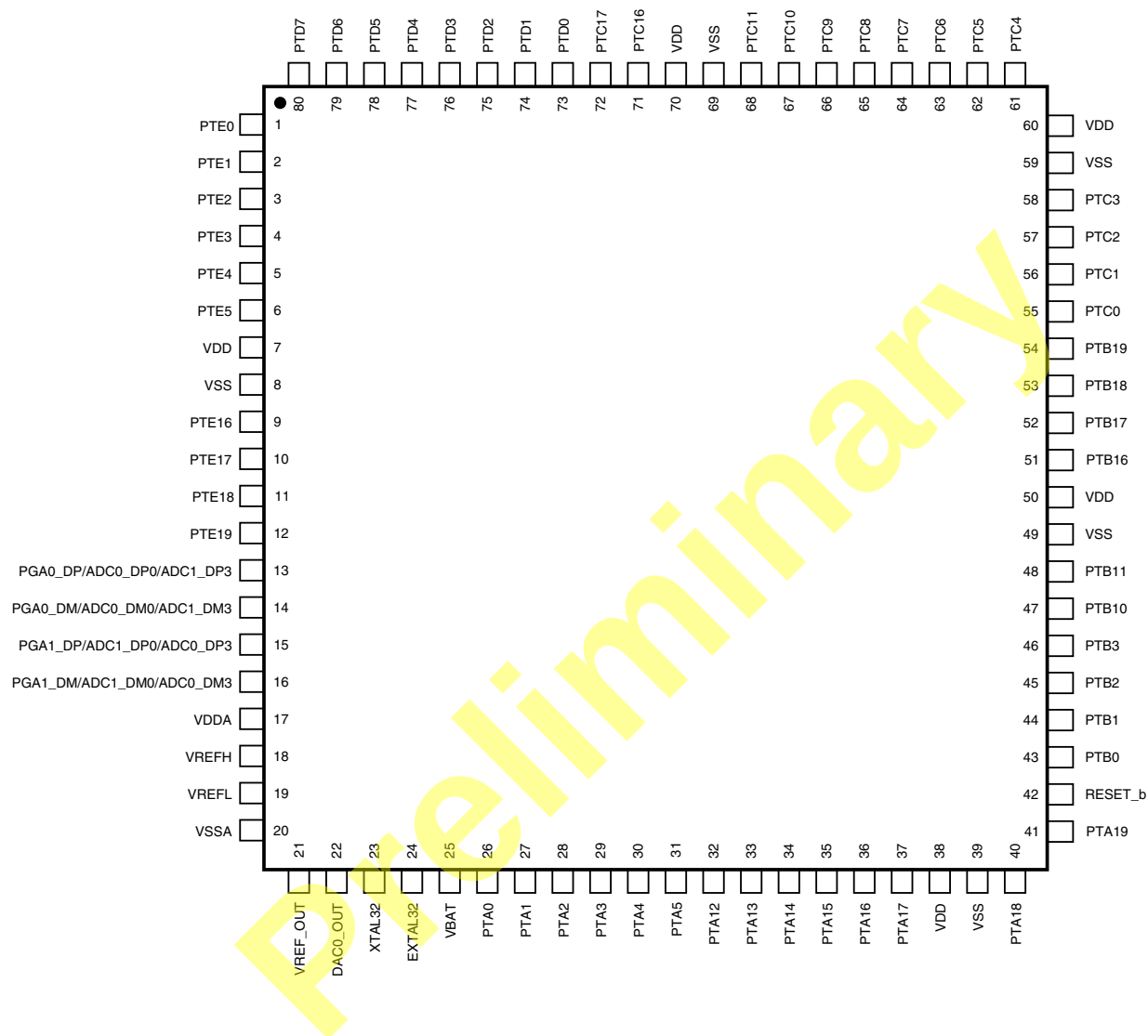


Figure 24. K10 80 LQFP Pinout Diagram

## 9 Revision History

The following table provides a revision history for this document.

**Table 43. Revision History**

| Rev. No. | Date    | Substantial Changes     |
|----------|---------|-------------------------|
| 1        | 11/2010 | Initial public revision |

Preliminary

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